$$Q_{i}(x|\alpha,b) = b x^{\alpha-i-b\alpha}$$

Q,6,x70

The mean is coladated first

$$\int_{0}^{\infty} \lambda \frac{1}{\Gamma(\alpha)} b^{\alpha} \lambda^{\alpha-1} e^{\alpha} F(-\lambda b) d\lambda = \frac{b^{\alpha}}{\Gamma(\alpha)} \int_{0}^{\infty} \lambda^{\alpha} e^{\alpha} F(-\lambda b) d\lambda$$

$$= \frac{b^{\alpha}}{\Gamma(\alpha)} \int_{0}^{\infty} (\frac{b^{\alpha}}{b})^{\alpha} e^{\alpha} F(-\lambda b) d\lambda$$

$$= \frac{1}{\Gamma(\alpha)} \int_{0}^{\infty} (\frac{b^{\alpha}}{b})^{\alpha} e^{\alpha} F(-\lambda b) d\lambda$$

To colubate E(13):

$$\int_{0}^{\infty} \int_{1}^{2} \int_{0}^{\infty} \int_{0$$

According to var[1]= E[1] - E[1] = alatil - [w] = ax

In order to First the mode of a game distribution, the maximum of the PDF

should be calcolated, then it is neccessary to calculate the derivative respect

d | 1 6 x 1 x = exp(-6x)| = [(x-1)-61.7 f(x)] = x = xp(-2x)

1ts maximum is at 12 x-1 so gamme distribution had node at Gam (21x,b) = 2-1

Knowing that XX"=I

$$\begin{pmatrix} A & B \\ c & D \end{pmatrix} \begin{pmatrix} M & -MBD^{-1} \\ -D^{*}CM & D^{*}+D^{*}CMBD^{-1} \end{pmatrix} = \begin{pmatrix} I & O \\ O & I \end{pmatrix}$$

AM-BO'(M => M (A-BO'E)=I

CM+D'(MD=0

- CMBD O+DD + DD CMBD = I

$$Q_3. R = \begin{pmatrix} \Lambda + A^T L A & -A^T L \\ -LA & L \end{pmatrix}$$

by the property in the previous question.

$$\begin{pmatrix} AB \\ CP \end{pmatrix} = \begin{pmatrix} M & -MBD^{-1} \\ -DCM & D^{-1}+D^{-1}CMBD^{-1} \end{pmatrix}$$

$$M = (\Lambda + A^{T} L A - (A^{T} L L^{-1} L A))^{-1}$$

$$= \Lambda + A^{T} L A - (-A^{T} - L A)^{-1}$$

$$= \Lambda^{-1}$$

$$R^{-1} = \begin{pmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{pmatrix}$$

$$M_{11} = \Lambda^{-1}$$
 $M_{12} = -\Lambda^{-1} - \Lambda^{-1} 2 L^{-1} = \Lambda^{-1} A^{T}$
 $M_{21} = (-L^{-1})(-2A)(\Lambda^{-1}) = \Lambda \Lambda^{-1}$
 $M_{22} = (-L^{-1})(-2A)(\Lambda^{-1}) = \Lambda^{-1}$

Then
$$COV |Z| = R^{-1} - |\Lambda^{-1}| \Lambda^{-1} A^{T}$$

$$|A\Lambda^{-1}| L^{-1}A\Lambda^{-1} A^{T}$$

$$M_{Y/X} = E[X] + E[Z]$$
 $E_{Y/X} = Cov[X] + cov[Z] = E_{Z}$
= $X + M_{Z}$

by comparing
$$P(X) = N((X|M), \Lambda^{-1})$$

$$P(Y|X) = \mathcal{N}(Y|AX+b,L')$$

 $P(Y) = \mathcal{N}(Y+AM+b, L'+AN^AT)$

In this qualition it is necessary to write the joint distribution p(x,y) and the combined it to obtain marginal distribution A(y)

the coodratic form of p(xy) in exponential form is:

terns with x are:

while integrating overx, it is possible to see that the first term disspapered into a constant, then the rangining terms should be extracted

= 1 4 TC2-1A (A+ATLA) ATL] 4+4 T([2-LA(A+ATLA ATL) HLA(A+ATLA) 1/A)

by using the inverse of 47, the coraniance matrix can be obtained by:

By using wooddory inversion formula:

(x+420) = x"-x"y(2"+0x"y)"0x"

x"=L, Y=A, 7= 1, v=AT

coefficient y most be equal to E(y) (Lov(y))

E (4) (1"+ ANAT) = ([1-LA(N+A"LA)"A"] b + LA(N+A"LA)" / M)

€ (9)-12"+AN" ATX ((2-1A(n+ATLA)"ATL) & + LA(n+ATLA)" /M)

E[Y= (2"+AN" AT) ([L"+AN"AT) "b+LA (N+ATZA)" AA)

E(4) = (2+(2-1+A)-1)2A (1+A-2A)-1/4)

by using wed bury invesion method:

(\(\L^{+}A^{\ta}\)^{-1} = M^{-}N'A^{\ta}(2^{\ta} + A N'A^{\ta})^{-1}AA^{\ta}\)

\(\E\{\gamma}\) = \(\Bar{L}^{-} + A N'A^{\ta}) \(\Delta A N' A^{\ta}\) \(\L^{-} + A N'A^{\ta})^{-1}AA^{\ta}\)

\(= \Bar{L}^{-1} + A N'A^{\ta} + A N^{-1} \((\L^{-} + A N'A^{\ta})^{\ta} + A N'A^{\ta})^{\ta}AA^{\ta}\)

\(= \Bar{L}^{-1} + A N'A^{\ta} + A N'^{-1} + A N'A^{\ta}A^{\ta}\)

\(= \Bar{L}^{-1} + A N'' + A N'A^{\ta} + A N'' A N' A N' A N' A N' A N' A N''

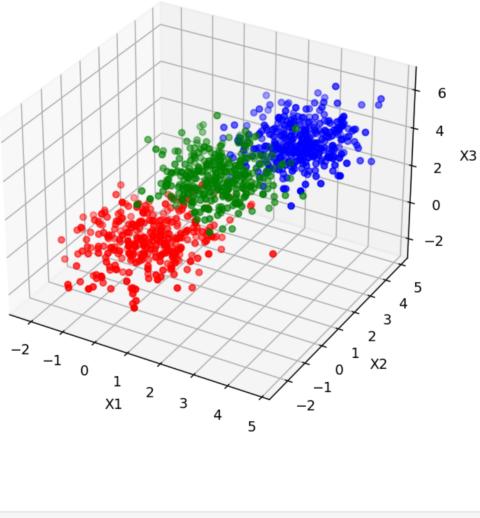
\(= \Bar{L}^{\ta} + A N'' \)

\(= \Bar{L}^{\ta} + A N'' \)

\(= \A M + B)

L. B. B. L. den S. Co.

```
Question 2.6
         # Loading of relevant libraries
         import numpy as np
         import matplotlib
         import matplotlib.pyplot as plt
         from mpl toolkits.mplot3d import Axes3D
         import seaborn as sns
         N = 1000
         np.random.seed(4)
         Pw0 = Pw1 = Pw2 = 1/3 # class a priori probabilities are equal
         m0 = np.array([0, 0, 0])
         m1 = np.array([1, 2, 2])
         m2 = np.array([3, 3, 4])
         S1 = np.array([[0.8, 0.2, 0.1],
                       [0.2,0.8,0.2],
                       [0.1,0.2,0.8]])
         S2 = np.array([[0.6, 0.01, 0.01],
                       [0.01,0.8,0.01],
                        [0.01,0.01,0.6]])
         S3 = np.array([[0.6, 0.1, 0.1],
                       [0.1, 0.6, 0.1],
                       [0.1, 0.1, 0.6]
         ## training set
         Xtr w0 = np.random.multivariate normal(m0, S1, 333) # vectors for class 0
         ytr w0 = 0*np.ones((333, 1))
                                                            # labels for class 0
         Xtr_w1 = np.random.multivariate_normal(m1, S2, 333) # vectors for class_1
                                                            # labels for class 1
         ytr w1 = 1*np.ones((333, 1))
         Xtr_w2 = np.random.multivariate_normal(m2, S3, 333) # vectors for class_2
         ytr w2 = 2*np.ones((333, 1))
                                                             # labels for class 2
         # collection in a single set for data and labels
         Xtr = np.concatenate((Xtr_w0, Xtr_w1, Xtr_w2), axis = 0)
         ytr = np.concatenate((ytr_w0, ytr_w1, ytr_w2), axis = 0)
         ## test set
         Xte w0 = np.random.multivariate normal(m0, S1, 333) # vectors for class 0
         yte w0 = 0*np.ones((333, 1))
                                                               # labels for class 0
         Xte w1 = np.random.multivariate normal(m1, S2, 333) # vectors for class 1
                                                               # labels for class 1
         yte w1 = 1*np.ones((333, 1))
         Xte w2 = np.random.multivariate normal(m2, S3, 333) # vectors for class 2
         yte w2 = 2*np.ones((333, 1))
                                                               # labels for class 2
         # collection in a single set for data and labels
         Xte = np.concatenate((Xte w0, Xte w1, Xte w2), axis = 0)
         yte = np.concatenate((yte_w0, yte_w1, yte_w2), axis = 0)
In [4]:
         # data ploting
         %matplotlib notebook
         fig = plt.figure(figsize = (6,6))
         ax = fig.add_subplot(projection = "3d")
         ax.scatter(Xtr_w0[:,0], Xtr_w0[:,1], Xtr_w0[:,2], marker = "o", color = "r", label = "Class 0")
         ax.scatter(Xtr_w1[:,0], Xtr_w1[:,1], Xtr_w1[:,2], marker = "o", color = "g", label = "Class 1")
         ax.scatter(Xtr_w2[:,0], Xtr_w2[:,1], Xtr_w2[:,2], marker = "o", color = "b", label = "Class 2")
         ax.set xlabel('X1')
         ax.set_ylabel('X2')
         ax.set_zlabel('X3')
         plt.show()
```



```
# question -1 : Calculation of ML estimates
m0 hat = (1.0/(N/3))*np.sum(Xtr w0, axis = 0)
S0_{hat} = (1.0/(N/3))*np.dot((Xtr_w0-m0_hat).T,(Xtr_w0-m0_hat))
m1 hat = (1.0/(N/3))*np.sum(Xtr w1, axis = 0)
S1_hat = (1.0/(N/3))*np.dot((Xtr_w1-m1_hat).T,(Xtr_w1-m1_hat))
m2_hat = (1.0/(N/3))*np.sum(Xtr_w2, axis = 0)
S2_hat = (1.0/(N/3))*np.dot((Xtr_w2-m2_hat).T,(Xtr_w2-m2_hat))
S_{hat} = (1.0/3.0)*(S0_{hat} + S1_{hat} + S2_{hat})
# Question - 2
# Mahalanobis distance calculation on the test set from the estimate mean of each class
inv_S = np.linalg.inv(S_hat)
dm_0 = np.sqrt(np.sum(np.dot((Xte-m0_hat), inv_S)*(Xte-m0_hat), axis = 1))
dm_1 = np.sqrt(np.sum(np.dot((Xte-ml_hat), inv_S)*(Xte-ml_hat), axis = 1))
dm_2 = np.sqrt(np.sum(np.dot((Xte-m2_hat), inv_S)*(Xte-m2_hat), axis = 1))
# Classification based on the calculated euclidean distances
dm_matrix = np.stack((dm_0, dm_1, dm_2), axis = 1)
Mahal_result = np.argmin(dm_matrix, axis = 1)
#Question - 3
def multivariate_normal_pdf_v2(x, mean, sigma):
   1 = x.shape[1]
   det_S = np.linalg.det(sigma)
   norm const = 1.0/((2.0*np.pi)**(1/2.0)*np.sqrt(det S))
   inv S = np.linalg.inv(sigma)
   a1 = np.sum(np.dot(x-mean, inv S)*(x-mean), axis = 1)
   return norm const*np.exp(-0.5*a1)
baydis_x1 = Pw0*multivariate_normal_pdf_v2(Xte, m0_hat,S_hat)
baydis_x2 = Pw1*multivariate_normal_pdf_v2(Xte, m1_hat,S_hat)
baydis_x3 = Pw2*multivariate_normal_pdf_v2(Xte, m2_hat,S_hat)
de matrix = np.stack((baydis_x1, baydis_x2, baydis_x3), axis = 1)
Bayes_result = np.argmax(de_matrix, axis = 1)
# Question - 4
# To compute the error probability the classification results are compare with the reference matrix
#error bayesian clasifier
error_bayesian = 1-np.sum(Bayes_result == yte.flatten())/N
#error mahalanobis
error mahalanobis = 1-np.sum(Mahal result == yte.flatten())/N
#print(error_bayesian)
```

it is possible to observe that the error using both methods is the same due to the same probability that each class have

print(error_bayesian)

#print(error euclidean)

print(error_mahalanobis)

0.0590000000000005
0.0590000000000005