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About Project

Project ID

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Description

Feline Utility Rovers

Files

Images Source

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Report

Jan 21, 2017

257640



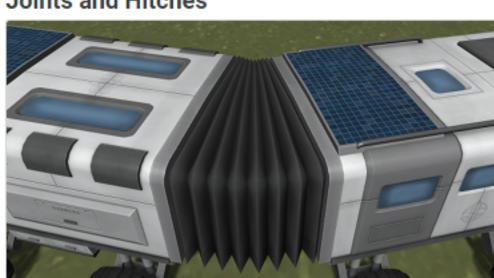


Kerbetrotter Ltd. is happy to announce its newest creation from the *Feline Utility Rover* series: The Lynx Rover.

A medium sized versatile rover that is capable to operate independently in the harshest environments. It is mainly designed to operate on other planets, but also in the outback of Kerbin. Depending on your configuration it can contain crew cabins, a laboratory or even bellowed joints to be more flexible in difficult terrain.

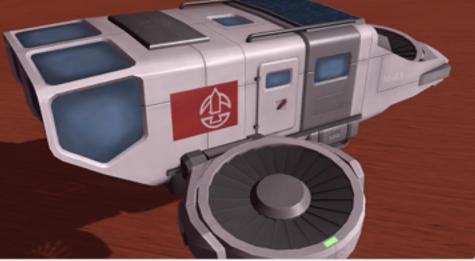
Features

Joints and Hitches

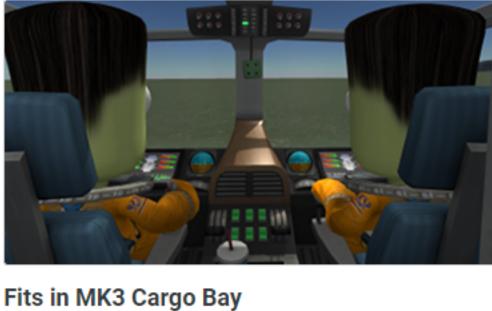




Hover Engines

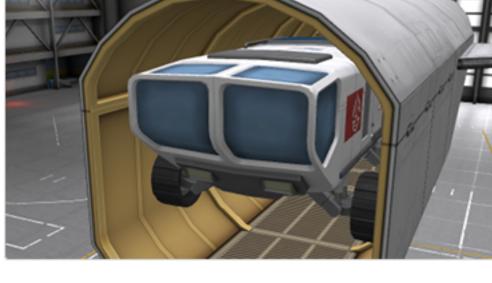


IVAs in all crewed parts



Custom Wheels





Configurable Containers



Instructions For instructions on how to use the hitches and joints, please take a look at the **KPSedia** entry of *Feline Utility Rovers*

Languages Español by bice

Русский by Tirathangil 中国语文 by <u>ssd21345</u>, <u>vosskftw</u> and <u>Levin845</u> Português (do Brasil) by FellipeC Deutsch by Nils277 Italiano by Simog

Looking for help:

If anyone is interested to translate FUR into Japanese or French, please let me know! You can find all the texts that need translation here: <u>Texts</u>. (1968 Words)

Important: Please contact me before you start with the translation. It already happend more than once that multiple persons worked on a translation for the

same texts and therefore their efforts were in vain.

Supported Mods Life Support:

TAC-LS, USI-LS, Snacks!, Kerbalism, IFI Life Support

Gameplay: KIS, KeepFit, RemoteTech, Connected Living Space, Pathfinder, Realfuels

Visual: JSI Advanced Transparend Pods, Raster Prop Monitor, ASET Props

Supports resources from:

OSE Workshop, Extraplanetary Launchpads, MKS, Deepfreeze, Near Future Propulsion, Near Future Electrical

Changelog

For instructions on how to use the hitches and joints, please take a look at the **KSPedia** entry of Feline Utility Rovers.

Instructions

The hitches and joints are locked by default when you first launch your vessel. You have to click "Unlock" in them right-click menu to unlock them.

The Hover Engines can be controlled with the controls for the Wheels to accelerate and steer. Lateral movement and height changes can be made with the controls for RCS. Please also visit the KSPedia for more information.

If you have any questions regarding this mod, please ask in the **Forum Thread**. If you encounter a bug with Kerbal Planetary Base Systems, please follow these instructions to report it in the Forum Thread.

Support and Bug reports

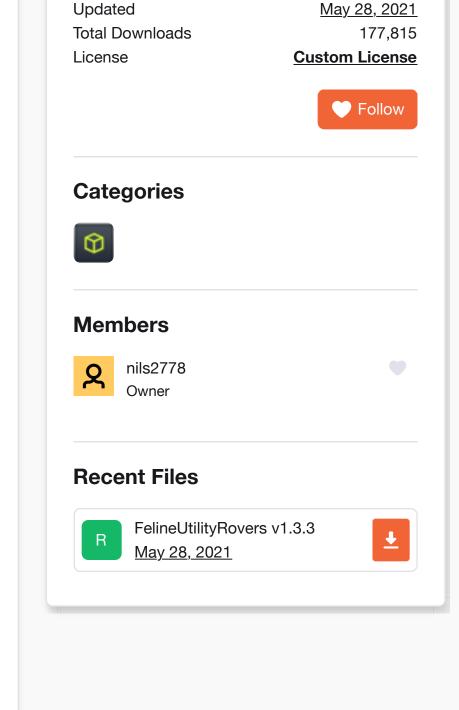
Most important: I need the LOG FILE. Otherwise i won't be able to help!

Also thanks to **Snjo** for the *Firespitter* mod. The Fuel switch is based on the one from Firespitter.

Thanks

Last but not least thanks to **Rafael Acevedo** for testing and suggestions during the development.

<u>sirkut</u> and <u>Ziw</u> for *Infernal Robotics*, which was used as reference/learning source for the functionality of the hitch.





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