Around 1010 milli per round

Count = 100, encoderCount = 82317

Count = 100, encoderCount = 82316

Count = 100, encoderCount = 82315

Count = 100, encoderCount = 82316

Avg = 823.16

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

Around 500 milli per round

Count = 100, encoderCount = 82315

Count = 100, encoderCount = 82320

Count = 100, encoderCount = 82326

Count = 100, encoderCount = 82339

Count = 100, encoderCount = 82358

Count = 100, encoderCount = 82342

Avg = 823.333

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

Around 400 milli per round

Count = 100, encoderCount = 83557

Count = 100, encoderCount = 82506

Count = 100, encoderCount = 82318

Count = 100, encoderCount = 82317

Count = 100, encoderCount = 82320

Avg =

\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*

Around 400 milli per round

Count = 1000, encoderCount = 824872

Count = 1000, encoderCount = 825470

Avg =

Avg of avgs = 824.424

<https://electronicshobbyists.com/controlling-dc-motors-arduino-arduino-l298n-tutorial/>

<https://howtomechatronics.com/tutorials/arduino/arduino-dc-motor-control-tutorial-l298n-pwm-h-bridge/>