Assignment 7: SML Playground

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1 Problem 1

1.1 Substitution Application

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• \omega(s):
                                               \omega(h(g(x,y,c),x))
                                               h(\omega(\langle g(x,y,c),x\rangle))
                                               h(\omega(g(x,y,c)),\omega(x))
                                               h(g(\omega(\langle x, y, c \rangle)), h(a, b))
                                               h(g(\omega(x),\omega(y),\omega(c)),h(a,b))
                                               h(g(h(a,b),g(c,f(c),b),c),h(a,b))
• \omega(t):
                                               \omega(g(y, h(y, x), a))
                                               g(\omega(\langle x, h(y, x), a \rangle))
                                               g(\omega(x), \omega(h(y,x)), \omega(a))
                                               g(h(a,b),h(\omega(\langle y,x\rangle)),a)
                                               g(h(a,b),h(\omega(y),\omega(x)),a)
                                               g(h(a,b), h(g(c, f(c), b), h(a, b)), a)
\bullet \tau(s):
                                                       \tau(h(g(x,y,c),x))
                                                       h(\tau(\langle g(x,y,c),x\rangle))
                                                       h(\tau(g(x,y,c)),\tau(x))
                                                       h(g(\tau(\langle x, y, c \rangle)), a)
                                                       h(g(\tau(x), \tau(y), \tau(c)), a)
                                                       h(g(a, h(b, c), b), a)
• \tau(t):
                                                     \tau(g(y, h(y, x), a))
                                                     g(\tau(\langle y, h(y, x), a \rangle))
                                                     g(\tau(y), \tau(h(y,x)), \tau(a))
                                                     g(h(b,c),h(\tau(\langle y,x\rangle)),a)
                                                     g(h(b,c),h(\tau(y),\tau(x)),a)
                                                     g(h(b,c),h(h(b,c),a),a)
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1.2 Commutativity Proof

No, substitution isn't commutative. The coutner-example is the following:

We have $\omega(t) = g(h(a,b), h(g(c,f(c),b), h(a,b)), a)$ and $\tau(t) = g(h(b,c), h(h(b,c),a), a)$ so $\tau(\omega(t))$:

$$\begin{aligned} &\tau(g(h(a,b),h(g(c,f(c),b),h(a,b)),a)) \\ &g(h(\tau(a),\tau(b)),h(g(\tau(c),f(\tau(c))),\tau(b)),h(\tau(a),\tau(b)),\tau(a)) \\ &g(h(a,b),h(g(b,f(b)),a),a) \end{aligned}$$

Now $\omega \tau(t)$:

$$\omega(g(h(b,c),h(h(b,c),a),a))$$

$$g(h(\omega(b),\omega(c)),h(h(\omega(b),\omega(c)),\omega(a)),\omega(a))$$

$$g(h(b,c),h(h(b,c),a),a)$$

We can see that $g(h(b,c),h(h(b,c),a),a) \neq g(h(a,b),h(g(b,f(b)),a),a)$ thus $\tau(\omega(t)) \neq \omega(\tau(t))$.