

Query Embeddings for KGs

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Graph Neural Networks and Applications



- 1 Knowledge Graphs Recap
- 2 KG Completion
- 3 Embedding Logical Queries to KGs

Knowledge Graphs Recap

Main idea

- Knowledge as graphs (linked data)
- Nodes as entities
- Labels as attributes
- Edges as relation types (heterogeneous network)

Applications

- Analytic representation of data
- Interpretable decision making
- Reasoning & QA
- Edges as relation types (heterogeneous network)

RDF representation

- $r(s,p,o)$ = subject–predicate–object relation
- ABox representing data
- TBox representing rules (ontologies)
- `rdfs:domain`, `rdfs:range`, `rdf:type`, `rdfs:subClassOf`, `rdfs:subPropertyOf`
- `owl:inverseOf`, `owl:TransitiveProperty`, `owl:FunctionalProperty`

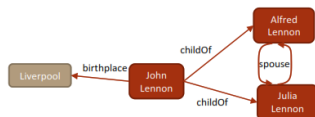
Knowledge Extraction vs. KG Construction

Problem	KE	KG
Who are entities?	NER & Coreference	Entity Linking
What are the attributes?	NER	Classification
How are they connected?	Relation extraction	Link Prediction

Table: Difference in view on knowledge mining

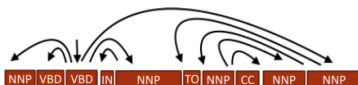
Knowledge Extraction

- Entity resolution, Entity linking, Relation Extraction (corpora)
- Coreference resolution (document)
- Dependency parsing, part of speech tagging, NER (sentence)



Lennon.. the Pool Mrs. Lennon.. his father
John Lennon... .. his mother .. he Alfred

Person Location Person Person
John was born in Liverpool, to Julia and Alfred Lennon.

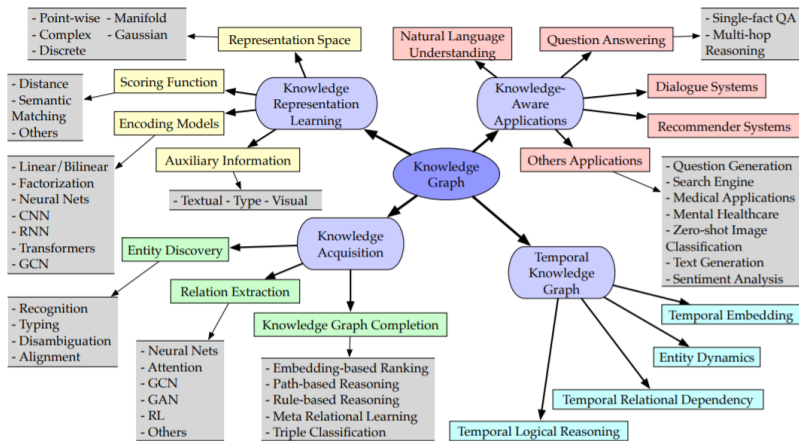


John was born in Liverpool, to Julia and Alfred Lennon.

from <https://kgtutorial.github.io/>, 2018

A Survey on Knowledge Graphs: Representation, Acquisition and Applications

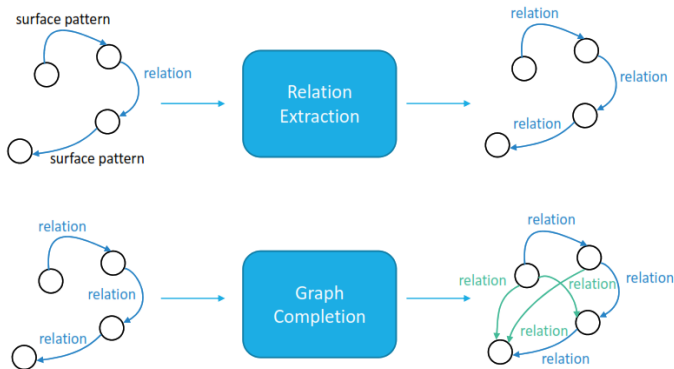
• Taxonomy of research and applications



Knowledge Graph Completion

Relation Extraction and KG Completion

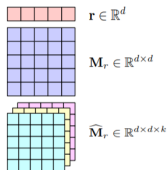
- Similar Pairs of Entities refer to similar relations (not identical)
- Similar Relations refer to paraphrases or implications
- Logical rules \rightarrow Embedding space



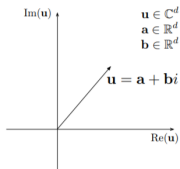
from <https://kgtutorial.github.io/>, 2018

Entity and relation representations

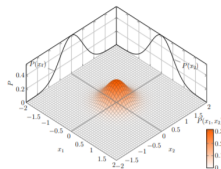
- Different embedding spaces
- Different relation properties to capture



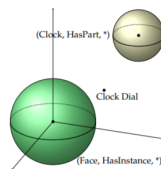
(a) Point-wise space.



(b) Complex vector space.



(c) Gaussian distribution.

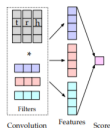


(d) Manifold space.

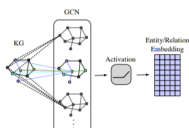
from Yu et al., 2021

Entity and relation encoding

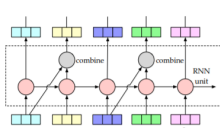
- CNN uses dense layer and convolution operation
- GCN encodes knowledge graphs
- RSN encodes entity-relation sequences and with masking relations discriminatively
- Transformer-based CoKE encodes triples as sequences with masked entities



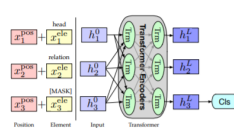
(a) CNN.



(b) GCN.



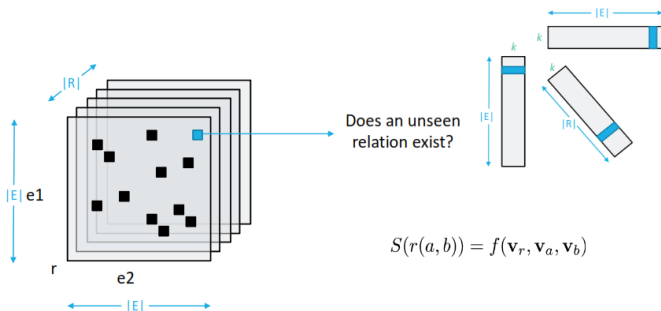
(c) RSN.



(d) Transformer.

from Yu et al., 2021

Tensor Formulation of KG



from <https://kgtutorial.github.io/>, 2018

KG Completion

CANDECOMP/PARAFAC-Decomposition

$$S(r(a, b)) = \sum_k R_{r,k} \cdot e_{a,k} \cdot e_{b,k}$$

Tucker2 and RESCAL Decompositions

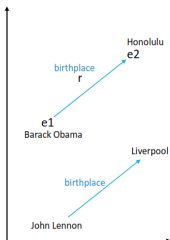
$$S(r(a, b)) = (\mathbf{R}_r \times \mathbf{e}_a) \times \mathbf{e}_b$$

Model E

$$S(r(a, b)) = \mathbf{R}_{r,1} \cdot \mathbf{e}_a + \mathbf{R}_{r,2} \cdot \mathbf{e}_b$$

Holographic Embeddings

$$S(r(a, b)) = \mathbf{R}_r \times (\mathbf{e}_a \star \mathbf{e}_b)$$



TransE

$$S(r(a, b)) = -\|\mathbf{e}_a + \mathbf{R}_r - \mathbf{e}_b\|_2^2$$

TransH

$$S(r(a, b)) = -\|\mathbf{e}_a^\perp + \mathbf{R}_r - \mathbf{e}_b^\perp\|_2^2$$
$$\mathbf{e}_a^\perp = \mathbf{e}_a - \mathbf{w}_r^T \mathbf{e}_a \mathbf{w}_r$$

TransR

$$S(r(a, b)) = -\|\mathbf{e}_a \mathbf{M}_r + \mathbf{R}_r - \mathbf{e}_b \mathbf{M}_r\|_2^2$$

from <https://kgtutorial.github.io/>, 2018

Scoring models II

Category	Model	Ent. embed.	Rel. embed.	Scoring Function $f_r(h, t)$
Polar coordinate	HAKE [19]	$\mathbf{h}_m, \mathbf{t}_m \in \mathbb{R}^k$	$\mathbf{r}_m \in \mathbb{R}_+^k$	$-\ \mathbf{h}_m \circ \mathbf{r}_m - \mathbf{t}_m\ _2 - \lambda \ \sin((\mathbf{h}_p + \mathbf{r}_p - \mathbf{t}_p)/2)\ _1$
		$\mathbf{h}_p, \mathbf{t}_p \in [0, 2\pi)^k$	$\mathbf{r}_p, \in [0, 2\pi)^k$	
Complex vector	ComplEx [23]	$\mathbf{h}, \mathbf{t} \in \mathbb{C}^d$	$\mathbf{r} \in \mathbb{C}^d$	$\text{Re}(\langle \mathbf{r}, \mathbf{h}, \tilde{\mathbf{t}} \rangle) = \text{Re}\left(\sum_{k=1}^K r_k \mathbf{h}_k \tilde{\mathbf{t}}_k\right)$
	RotatE [24]	$\mathbf{h}, \mathbf{t} \in \mathbb{C}^d$	$\mathbf{r} \in \mathbb{C}^d$	$\ \mathbf{h} \circ \mathbf{r} - \mathbf{t}\ $
	QuatE [25]	$\mathbf{h}, \mathbf{t} \in \mathbb{H}^d$	$\mathbf{r} \in \mathbb{H}^d$	$\mathbf{h} \otimes \frac{1}{\ \mathbf{r}\ } \cdot \mathbf{t}$
Manifold & Group	ManifoldE [28]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\ \mathcal{M}(h, r, t) - D_r^2\ ^2$
	TorusE [15]	$[\mathbf{h}], [\mathbf{t}] \in \mathbb{T}^n$	$[\mathbf{r}] \in \mathbb{T}^n$	$\min_{(x,y) \in ([\mathbf{h}] + [\mathbf{r}]) \times [\mathbf{t}]} \ x - y\ _1$
	DihEdral [31]	$\mathbf{h}^{(l)}, \mathbf{t}^{(l)} \in \mathbb{R}^2$	$\mathbf{R}^{(l)} \in \mathbb{D}_K$	$\sum_{l=1}^L \mathbf{h}^{(l)\top} \mathbf{R}^{(l)} \mathbf{t}^{(l)}$
	MuRP [29]	$\mathbf{h}, \mathbf{t} \in \mathbb{B}_c^d, b_h, b_t \in \mathbb{R}$	$\mathbf{r} \in \mathbb{B}_c^d$	$-d_{\mathcal{G}}(\exp_{\mathcal{G}}(\mathbf{R} \log_{\mathcal{G}}(\mathbf{h})), \mathbf{t} \oplus_{\mathcal{G}} \mathbf{r})^2 + b_h + b_t$
	AttH [30]	$\mathbf{h}, \mathbf{t} \in \mathbb{B}_c^d, b_h, b_t \in \mathbb{R}$	$\mathbf{r} \in \mathbb{B}_c^d$	$-d_{\mathcal{G}}^{\text{rot}}\left(\text{Att}\left(\mathbf{q}_{\text{Rot}}^H, \mathbf{q}_{\text{Ref}}^H; \mathbf{a}_r\right) \oplus_{\mathcal{G}} \mathbf{r}_r^H, \mathbf{e}_t^H\right)^2 + b_h + b_t$
Gaussian	KG2E [26]	$\mathbf{h} \sim \mathcal{N}(\boldsymbol{\mu}_h, \boldsymbol{\Sigma}_h)$	$\mathbf{r} \sim \mathcal{N}(\boldsymbol{\mu}_r, \boldsymbol{\Sigma}_r)$	$\int_{x \in \mathbb{R}^{k_e}} \mathcal{N}(x; \boldsymbol{\mu}_r, \boldsymbol{\Sigma}_r) \log \frac{\mathcal{N}(x; \boldsymbol{\mu}_e, \boldsymbol{\Sigma}_e)}{\mathcal{N}(x; \boldsymbol{\mu}_r, \boldsymbol{\Sigma}_r)} dx$
		$\mathbf{t} \sim \mathcal{N}(\boldsymbol{\mu}_t, \boldsymbol{\Sigma}_t)$		$\log \int_{x \in \mathbb{R}^{k_e}} \mathcal{N}(x; \boldsymbol{\mu}_e, \boldsymbol{\Sigma}_e) \mathcal{N}(x; \boldsymbol{\mu}_r, \boldsymbol{\Sigma}_r) dx$
	TransG [27]	$\mathbf{h} \sim \mathcal{N}(\boldsymbol{\mu}_h, \sigma_h^2 \mathbf{I})$ $\mathbf{t} \sim \mathcal{N}(\boldsymbol{\mu}_t, \boldsymbol{\Sigma}_t)$ $\boldsymbol{\Sigma}_h, \boldsymbol{\Sigma}_t \in \mathbb{R}^{d \times d}$	$\boldsymbol{\mu}_r \in \mathbb{R}^d, \boldsymbol{\Sigma}_r \in \mathbb{R}^{d \times d}$ $\boldsymbol{\mu}_r^i \sim \mathcal{N}(\boldsymbol{\mu}_i - \boldsymbol{\mu}_h, (\sigma_h^2 + \sigma_t^2) \mathbf{I})$ $\mathbf{r} = \sum_i \pi_r^i \boldsymbol{\mu}_r^i \in \mathbb{R}^d$	$\sum_i \pi_r^i \exp\left(-\frac{\ \boldsymbol{\mu}_h + \boldsymbol{\mu}_r^i - \boldsymbol{\mu}_t\ _2^2}{\sigma_h^2 + \sigma_t^2}\right)$
Translational Distance	TransE [16]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$-\ \mathbf{h} + \mathbf{r} - \mathbf{t}\ _{1/2}$
	TransR [17]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^k, \mathbf{M}_r \in \mathbb{R}^{k \times d}$	$-\ \mathbf{M}_r \mathbf{h} + \mathbf{r} - \mathbf{M}_r \mathbf{t}\ _2^2$
	TransH [20]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r}, \mathbf{w}_r \in \mathbb{R}^d$	$-\left\ (\mathbf{h} - \mathbf{w}_r^\top \mathbf{h} \mathbf{w}_r) + \mathbf{r} - (\mathbf{t} - \mathbf{w}_r^\top \mathbf{t} \mathbf{w}_r)\right\ _2^2$
	TransA [34]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d, \mathbf{M}_r \in \mathbb{R}^{d \times d}$	$(\ \mathbf{h} + \mathbf{r} - \mathbf{t}\ ^\top \mathbf{W}_r (\mathbf{h} + \mathbf{r} - \mathbf{t}))$
	TransF [35]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$(\mathbf{h} + \mathbf{r})^\top \mathbf{t} + (\mathbf{t} - \mathbf{r})^\top \mathbf{h}$
	ITransF [36]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\left\ \boldsymbol{\alpha}_r^H \cdot \mathbf{D} \cdot \mathbf{h} + \mathbf{r} - \boldsymbol{\alpha}_r^T \cdot \mathbf{D} \cdot \mathbf{t}\right\ _\ell$
	TransAt [37]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$P_r(\sigma(\mathbf{r}_h) \mathbf{h}) + \mathbf{r} - P_r(\sigma(\mathbf{r}_t) \mathbf{t})$
	TransD [33]	$\mathbf{h}, \mathbf{t}, \mathbf{w}_h, \mathbf{w}_t \in \mathbb{R}^d$	$\mathbf{r}, \mathbf{w}_r \in \mathbb{R}^k$	$-\left\ (\mathbf{w}_r \mathbf{w}_h^\top + \mathbf{I}) \mathbf{h} + \mathbf{r} - (\mathbf{w}_r \mathbf{w}_t^\top + \mathbf{I}) \mathbf{t}\right\ _2^2$
	TransM [211]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$-\theta_r \ \mathbf{h} + \mathbf{r} - \mathbf{t}\ _{1/2}$
	TransSparse [212]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^k, \mathbf{M}_r(\theta_r) \in \mathbb{R}^{k \times d}$ $\mathbf{M}_r^1(\theta_r^1), \mathbf{M}_r^2(\theta_r^2) \in \mathbb{R}^{k \times d}$	$-\ \mathbf{M}_r(\theta_r) \mathbf{h} + \mathbf{r} - \mathbf{M}_r(\theta_r) \mathbf{t}\ _{1/2}^2$ $-\ \mathbf{M}_r^1(\theta_r^1) \mathbf{h} + \mathbf{r} - \mathbf{M}_r^2(\theta_r^2) \mathbf{t}\ _{1/2}^2$

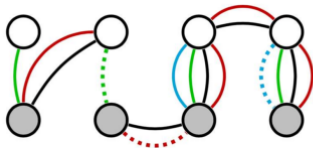
from Yu et al., 2021

- Different approaches arising from problems with relation properties preserving

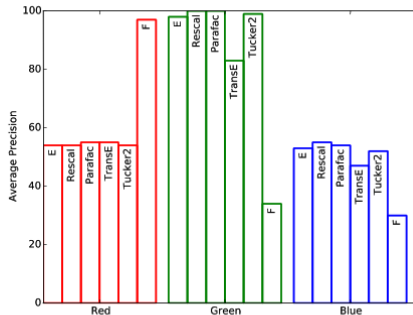
Semantic Matching	TATEC [213]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d, \mathbf{M}_r \in \mathbb{R}^{d \times d}$	$\mathbf{h}^\top \mathbf{M}_r \mathbf{t} + \mathbf{h}^\top \mathbf{r} + \mathbf{t}^\top \mathbf{r} + \mathbf{h}^\top \mathbf{D} \mathbf{t}$
	ANALOGY [22]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{M}_r \in \mathbb{R}^{d \times d}$	$\mathbf{h}^\top \mathbf{M}_r \mathbf{t}$
	CrossE [42]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\sigma \left(\tanh(\mathbf{c}_r \circ \mathbf{h} + \mathbf{c}_r \circ \mathbf{h} \circ \mathbf{r} + \mathbf{b}) \mathbf{t}^\top \right)$
	SME [39]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$g_{\text{left}}(\mathbf{h}, \mathbf{r})^\top g_{\text{right}}(\mathbf{r}, \mathbf{t})$
	DistMult [32]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\mathbf{h}^\top \text{diag}(\mathbf{M}_r) \mathbf{t}$
	HolE [21]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\mathbf{r}^\top (\mathbf{h} \star \mathbf{t})$
	HolEx [40]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\sum_{j=0}^l p(\mathbf{h}, \mathbf{r}; \mathbf{c}_j) \cdot \mathbf{t}$
	SE [8]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{M}_r^1, \mathbf{M}_r^2 \in \mathbb{R}^{d \times d}$	$-\ \mathbf{M}_r^1 \mathbf{h} - \mathbf{M}_r^2 \mathbf{t} \ _1$
	Simple [48]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r}, \mathbf{r}' \in \mathbb{R}^d$	$\frac{1}{2} \ (\mathbf{h} \circ \mathbf{r} \mathbf{t} + \mathbf{t} \circ \mathbf{r}' \mathbf{t})$
	RESCAL [49]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{M}_r \in \mathbb{R}^{d \times d}$	$\mathbf{h}^\top \mathbf{M}_r \mathbf{t}$
	LFM [51]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{u}_r, \mathbf{v}_r \in \mathbb{R}^p$	$\mathbf{h}^\top \sum_{i=1}^d \alpha_i^\top \mathbf{u}_i \mathbf{v}_i^\top \mathbf{t}$
	TuckER [52]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}_e^d$	$\mathbf{r} \in \mathbb{R}_r^d$	$\mathcal{W} \times_1 \mathbf{h} \times_2 \mathbf{r} \times_3 \mathbf{t}$
	LowFER [53]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$(\mathbf{S}^k \text{diag}(\mathbf{U}^\top \mathbf{h}) \mathbf{V}^\top \mathbf{r})^\top \mathbf{t}$
Neural Networks	MLP [3]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\sigma(\mathbf{w}^\top \sigma(\mathbf{W}[\mathbf{h}, \mathbf{r}, \mathbf{t}]))$
	NAM [54]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\sigma(\mathbf{z}^{(L)} \cdot \mathbf{t} + \mathbf{B}^{(L+1)} \mathbf{r})$
	ConvE [55]	$\mathbf{M}_h \in \mathbb{R}^{d_w \times d_h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{M}_r \in \mathbb{R}^{d_w \times d_h}$	$\sigma(\text{vec}(\sigma([\mathbf{M}_h; \mathbf{M}_r] * \omega))) \mathbf{W} \mathbf{t}$
	ConvKB [43]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$\text{concat}(\sigma([\mathbf{h}, \mathbf{r}, \mathbf{t}] * \omega)) \cdot \mathbf{w}$
	HypER [56]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{w}_r \in \mathbb{R}^{d_r}$	$\sigma(\text{vec}(\mathbf{h} * \text{vec}^{-1}(\mathbf{w}_r \mathbf{H})) \mathbf{W}) \mathbf{t}$
	SACN [44]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r} \in \mathbb{R}^d$	$g(\text{vec}(\mathbf{M}(\mathbf{h}, \mathbf{r})) \mathbf{W}) \mathbf{t}$
	NTN [18]	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$	$\mathbf{r}, \mathbf{b}_r \in \mathbb{R}^k, \widehat{\mathbf{M}} \in \mathbb{R}^{d \times d \times k}$ $\mathbf{M}_{r,1}, \mathbf{M}_{r,2} \in \mathbb{R}^{k \times d}$	$\mathbf{r}^\top \sigma(\mathbf{h}^\top \widehat{\mathbf{M}} \mathbf{t} + \mathbf{M}_{r,1} \mathbf{h} + \mathbf{M}_{r,2} \mathbf{t} + \mathbf{b}_r)$

from Yu et al., 2021

KG Completion



- **Red**: deterministically implied by **Black**
 - needs *pair-specific* embedding
 - Only **F** is able to generalize
- **Green**: needs to estimate entity types
 - needs *entity-specific* embedding
 - Tensor factorization generalizes, **F** doesn't
- **Blue**: implied by **Red** and **Green**
 - Nothing works much better than random

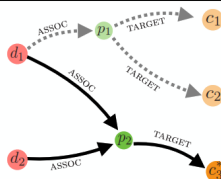
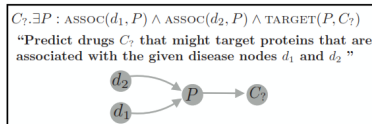
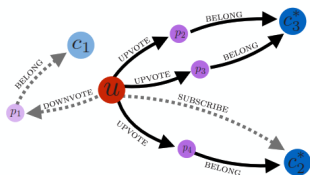
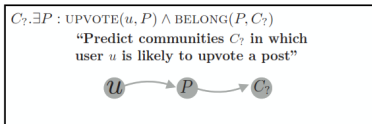


from Singh et al., 2015

Query Embedding to Knowledge Graph

Embedding Logical Queries on Knowledge Graphs

- Simple conjunctive graph queries
- Example on the left shows a path query on the Reddit data with multiple answers
- Example on the right shows a more complex query with a polytree structure on the biological interaction data



from Leskovec et al., 2018

Embedding Logical Queries on Knowledge Graphs

- GQE framework takes input query q , represents this query according to its DAG (directed acyclic graph) structure
- Embedding of the query is generated based on this DAG by applying geometric operations P (projection) and I (intersection)
- Generated query embedding is used to predict the likelihood that a node satisfies the query via kNN in the embedding space

Algorithm 1: Query embedding generation

Input : Query anchor nodes A , query variable nodes B , query edges \mathcal{E}_q , a map d_q from query variables to their degree in the query DAG

Output : Query embedding q

Q = dictionary mapping every $V_i \in B$ to an empty set;

for $\tau(v_i, V_i) \in \mathcal{E}_q : v_i \in A$ **do**

$Q[V_i] = Q[V_i] \cup \mathcal{P}(z_{v_i}, \tau)$

while $|Q.key_set| > 0$ **do**

A = empty dictionary;

for $V_i \in Q.key_set : |Q[V_i]| = d_q(V_i)$ **do**

$A[V_i] = \mathcal{I}(Q[V_i]);$

 delete $Q[V_i];$

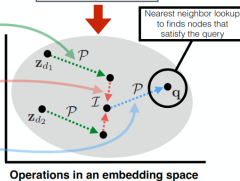
for $V_i \in A.key_set$ **do**

for $\tau(V_j, V_k) \in \mathcal{E}_q : V_j = V_i$ **do**

$Q[V_k] = Q[V_k] \cup \mathcal{P}(A[V_i], \tau);$

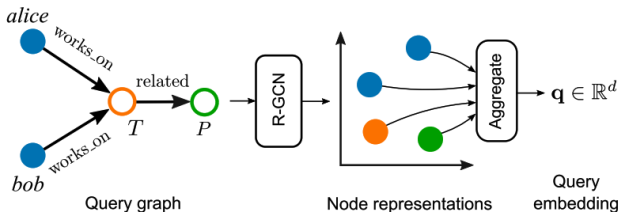
return $A[V_i];$

$C_7, \exists P : \text{TARGET}(C_7, P) \wedge \text{ASSOC}(P, d_2) \wedge \text{ASSOC}(P, d_2)$
Input query



Message Passing Query Embedding

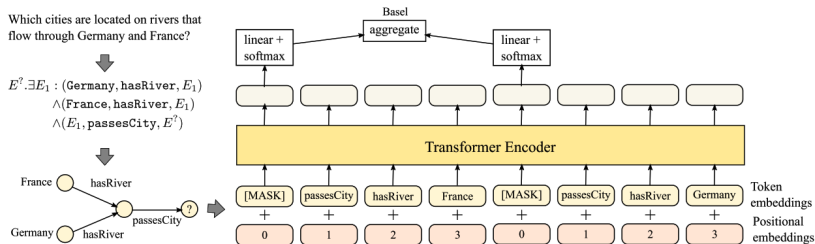
- Message Passing Query Embedding takes as input a query graph and outputs a query embedding.
- Features for each node in the query graph are embeddings of entities in the KG, or type embeddings.
- GNN propagates information across the graph, and an aggregation function yields the query embedding.



from Cochez et al., 2020

Answering Complex Queries in Knowledge Graphs with Bidirectional Sequence Encoders

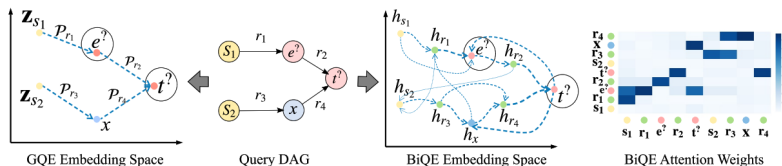
- Use of Transformers of sentences from KG
- Bidirectional Query Embedding (BIQE) embeds conjunctive queries with models based on bi-directional attention mechanisms.



from Niepert et al., 2020

Answering Complex Queries in Knowledge Graphs with Bidirectional Sequence Encoders

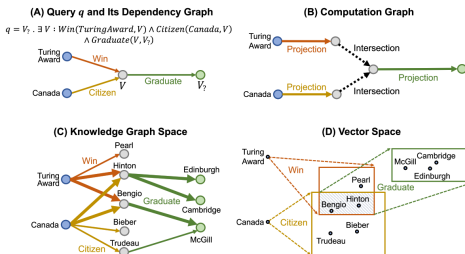
- Query embedding in GQE (left) vs. BIQE (right).
- For GQE, when computing the intersection of e or t , only the previous query context is considered and not the future.
- For BIQE, every element can attend to every other element of the query.



from Niepert et al., 2020

Query2Box: Reasoning over knowledge graphs in vector space using box embeddings

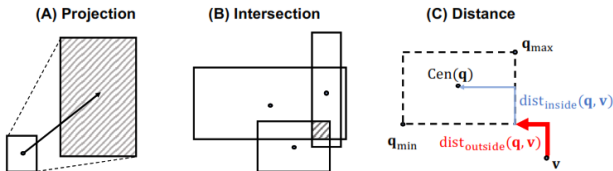
- Conjunctive query is represented with a dependency graph
- Computation graph specifies the reasoning procedure
- Knowledge graph, where green nodes denote answers to the query
- In QUERY2BOX, nodes of the KG are embedded
- Query embedding is computed according to the computation graph as a sequence of box operations



from Leskovec et al., 2020

Query2Box: Reasoning over knowledge graphs in vector space using box embeddings

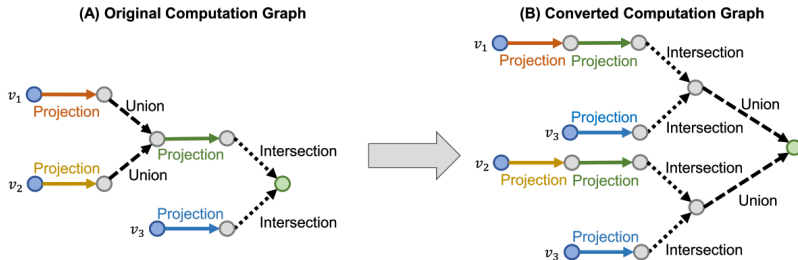
- Projection generates a larger box with a translated center
- Intersection generates a smaller box lying inside the given set of boxes
- Distance dist_{box} is the weighted sum of $\text{dist}_{\text{outside}}$ and $\text{dist}_{\text{inside}}$ with lesser weight.



from Leskovec et al., 2020

Query2Box: Reasoning over knowledge graphs in vector space using box embeddings

- Balancing query depth with disjunctive normal form transformation
- Better generalizability for queries with many variables



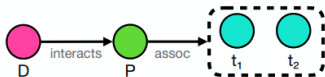
from Leskovec et al., 2020

Complex query answering with neural link predictors

- Consequent link prediction and query probabilistic scoring over combinatorial optimized set of candidates
- Łukasiewicz loic

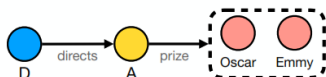
“Which drugs interact with proteins associated with diseases t_1 or t_2 ?”

$?D : \exists P . \text{interacts}(D, P) \wedge [\text{assoc}(P, t_1) \vee \text{assoc}(P, t_2)]$



“Which directors directed actors that won either an Oscar or an Emmy?”

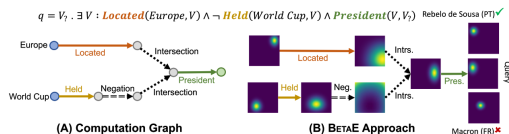
$?D : \exists A . \text{directs}(D, A) \wedge [\text{prize}(A, \text{Oscar}) \vee \text{prize}(A, \text{Emmy})]$



from Cochez et al., 2020

Beta Embeddings for Multi-Hop Logical Reasoning in Knowledge Graphs

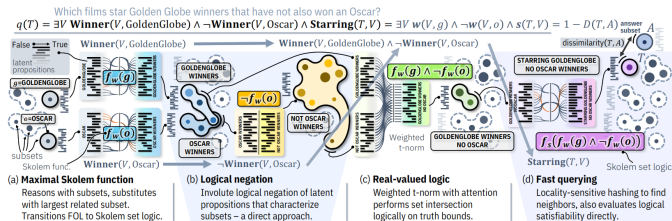
- BetaE answers first-order logic queries modeling each node of the computation graph as a Beta distribution over the entity embedding space
- Each edge of the computation graph transforms the distribution via a projection, negation, or intersection probabilistic operation.
- Negation $N(\alpha, \beta) \rightarrow N(1/\alpha, 1/\beta)$, disjunction via De Morgan's laws



from Leskovec et al., 2020

Logic Embeddings for Complex Query Answering

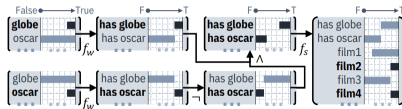
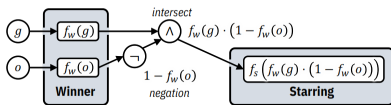
- Real-valued logic on latent propositions (latents), an array of truth bounds that describes any subset of entities.
- Learned Skolem function maps latents of singleton Oscar to latents of maximal subset of Oscar winners, and similarly for GoldenGlobe
- Complement of a subset is logical negation of latents
- Intersection of subsets is logical conjunction of latents
- $q(T) = 1 - D(T; A)$ measures logic satisfiability of candidate answer followed by KNN.



from Gray et al., 2021

Logic Embeddings for Complex Query Answering

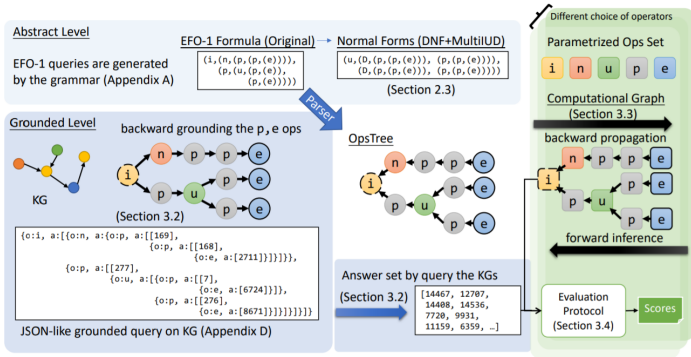
- Computation graph for t-norm for intersect.
- Nodes are truth vectors that identify entity subsets.
- Embedding query logic reduces to a simple vectorized calculation.
- Propositions identify features, relations substitute propositions, negation flips truths, intersect retains common features.
- The final query embedding is closer to propositions of film2/4 (answer set) than film1/3.



from Gray et al., 2021

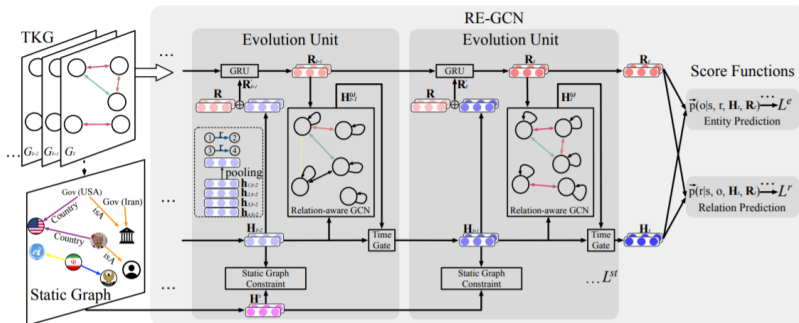
Benchmarking the Combinatorial Generalizability of Complex Query Answering on Knowledge Graphs

- Benchmarking query generation for training and validation
- Different tree-based representations of queries lead to different model performance



Temporal Knowledge Graph Reasoning Based on Evolutional Representation Learning

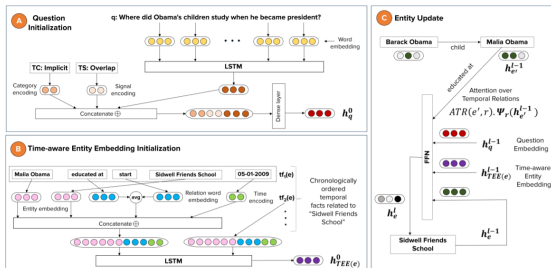
- Temporal KG (TKG) predicts facts via Recurrent Evolution network based on Graph Convolution Network (RE-GCN)
- Temporal component is implemented via autogressive GRU module over structural snapshot-based embeddings



from Cheng et al., 2021

Complex Temporal Question Answering on Knowledge Graphs

- Exact processed temporal intents in questions over KGs
- First, it computes question-relevant compact subgraphs within the KG, and judiciously enhances them with pertinent temporal facts, using Group Steiner Trees and fine-tuned BERT models.
- Secondly, relational graph convolutional networks (R-GCNs) with temporal attention and dynamic entity embeddings.



from Weikum et al., 2021

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