

# Zihan Lin

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## Education

<b>Northeastern University</b> , Boston, MA <i>Master of Science in Robotics</i>	Dec 2025
<b>Northeastern University</b> , Boston, MA <i>Bachelor of Science in Mechanical Engineering</i> Dean's Honor List · Presidential Global Scholars · Dual Husky Scholars	Dec 2023

## Project Experience

<b>Micro/Nano Biomechanical Characterization Lab</b>   <i>Lab Assistant</i>	Jun 2022 - Dec 2025
• Designed and fabricated multi-geometry test indenters in SolidWorks via DLP 3D printing; created verification protocols to characterize force-displacement responses in soft matrices.	
• Automated indentation testing via Raspberry Pi/Python/PID-controlled X-Y stage with serial communication to motor controllers, reducing per-sample cycle time by 5x.	
• Engineered 3D-printed compliant linkage with dual-IMU sensor fusion for real-time trajectory reconstruction; co-authored publication in European Journal of Mechanics - A/Solids.	
<b>6-DOF Robotic Arm Trajectory Control</b>   <i>Mechatronic Systems</i>	Sep - Dec 2024
• Designed a 6-DOF robotic arm control system in MATLAB/Simulink using NMPC with a Gaussian Process-augmented state-space model precise trajectory tracking and disturbance rejection.	
<b>Composite Pressure Vessel FEA</b>   <i>MechE Computation and Design</i>	Jan - May 2022
• Performed FEA in ANSYS Workbench to model fibrous composite layups in a high-pressure liquid tank, verifying peak von Mises stress remained within safety margins of yield strength under designated internal pressures.	
<b>GPS/IMU Driver Development &amp; Sensor Fusion</b>   <i>Robotics Sensing and Navigation</i>	Sep - Dec 2025
• Engineered a ROS 2 device driver for VectorNav VN-100 IMU over USB serial, configuring register-level 40 Hz sampling; developed sensor fusion pipeline with magnetometer calibration for vehicle trajectory reconstruction.	

## Work Experience

<b>Shark Ninja, Needham, MA</b>   <i>Test Engineer Co-op</i>	Jan - Jun 2023
• Designed sealed test chambers with pressure sensors and compressed-air fixtures in SolidWorks; configured Prometheus for automated data logging, replacing manual recording.	
• Developed test procedure and test cases for air purifier filter qualification — covering fabrication, assembly fitment, and adsorption performance — with documentation for reproducibility.	
• Isolated root causes of test-fixture failures on Robotic Vacuums (worn fittings, seal degradation); updated test protocols and wrote Python scripts to flag out-of-spec data.	
• Logged defects in Excel tracker; delivered weekly test-result summaries to engineering leadership in cross-functional reviews with Product Engineers.	
<b>HiRain Technology, Beijing, China</b>   <i>Mechanical Design &amp; Product Test Engineer Co-op</i>	Jul - Dec 2021
• Constructed PCB test fixtures; validated circuit performance through firmware flashing, Linux debugging, and soldering rework in post-production testing.	
• Optimized 2D/3D CAD models for PCBA enclosures in AutoCAD and Creo, ensuring DFM compliance; created engineering drawings for manufacturing handoff.	
• Interpreted wiring diagrams and schematics to troubleshoot board-level hardware failures.	

## Skills

**Design & Prototyping:** SolidWorks, Creo, AutoCAD, 3D Printing (DLP/FDM), DFM, Serial Communication.

**Simulation & Analysis:** ANSYS FEA (Mechanical & Thermal), MATLAB, Simulink, Simscape.

**Programming & Tools:** Python, PID Control, C#, Java, Raspberry Pi, Arduino, Linux/Bash, Git, ROS 2, Sensor Fusion.