Heuristic/Informed Search

- Heuristics are:
 - cntoria
 - Memors
 - Principles
 - for deciding which among
 the severals elematives of
 actions promises to be the
 - most effective in order to arbiene goal.

Hemistic function: helps

A heuristic function et noue

in is an estimate of the
optimum cost from the current

node to a goal node.

* It is denstes by him)

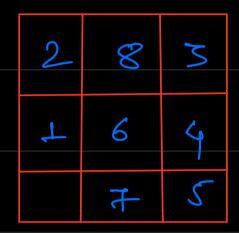
* h(n) = estimated cost of

the cheapest path from node

n'to goal node.

For example:

8-puzzle: Misplaced Tiles Heavistics is the number of tiles out of place.



_1	7	5
8		,
۵		9
7	6	5

Initial state
Tig @

Goal State

r Here, Fig @ shows the current state

n, & the fig @ present the goal

state. & h(w = 5

* Because tiles 2, 8, 1, 6, & 7 are out of



Belt First Search:

- evaluation function: f(u)

- gives an estimate - node with lawest cost is

expanded first.

- Key component of f(n) is h (n), which is additional knowledge of the problem.

* Based on evaluation function

fin

- Greedy Best-first search

- A** search

bireedy Best-first Search

It was evaluation function f(m)
to select which words is to be
expanded.

- Mode with lowest evaluation

cost is selected for expansion.

Evaluation function:

f(n) = h(n) (heuristic)

i.e. estimate of cont from

node n to goal node.

Fo example:

h_{SLD} (w) = Straight live déstance from nove n to goal

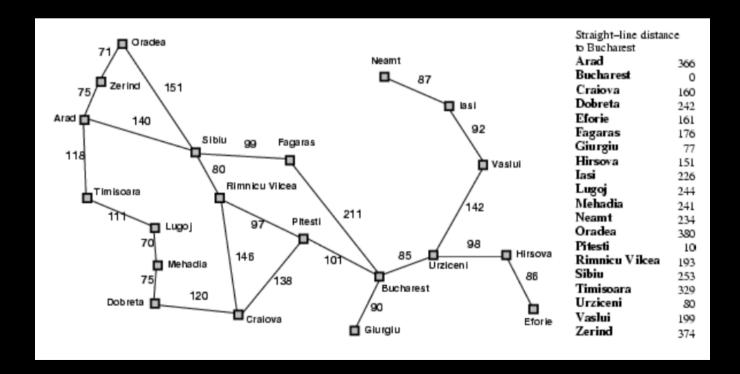
- hreedy best-first Search expand
the nose to se appear closest
to the goal.

- Jime & Space camplessity is:

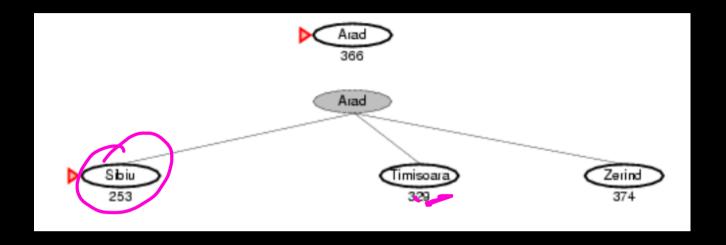
Where, b is boanding forter

m is max depth

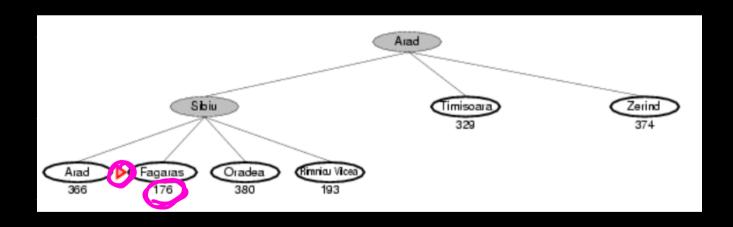
Example: Given following groph of cities storting at Arad, problem is to reach the Buchavest.



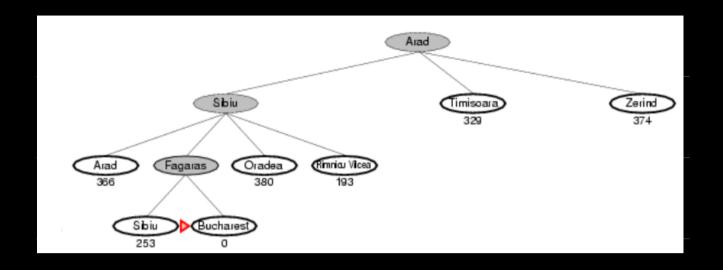
Step 1:



Step 2!



Step 8:



A* Search

- it is best-first informed graph Search algorithm.

- It was the hueristie h(n) & poth cost g(n)

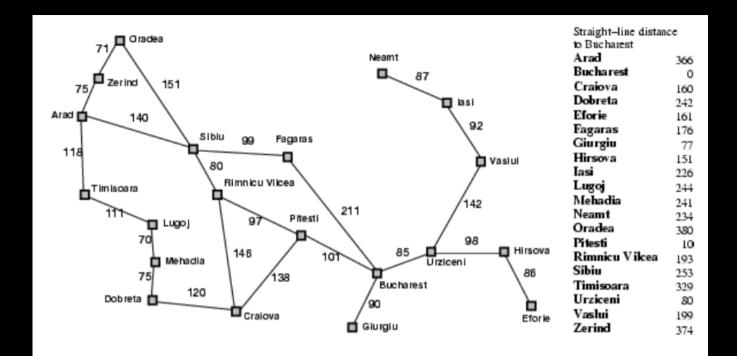
i.e. evaluation function f(n) = h(n) + g(n) Where,

f(n) is estimated toat cost of poten

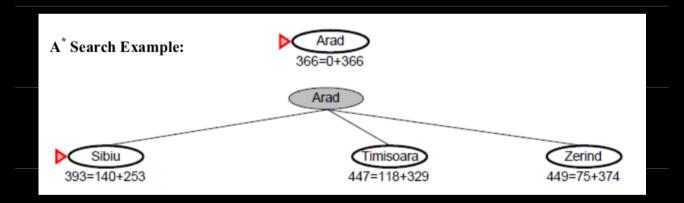
hon) is estimated ont to goal

g(n) Cost so for to reach in

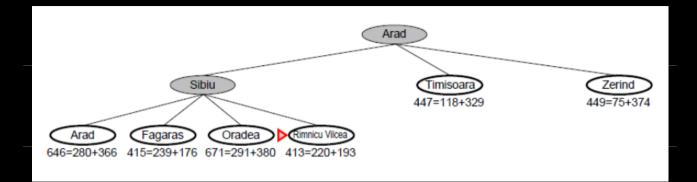
Example! At Search



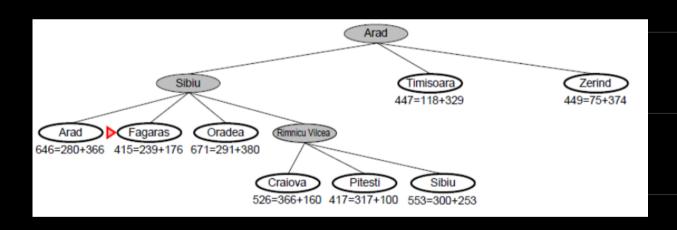
Step!



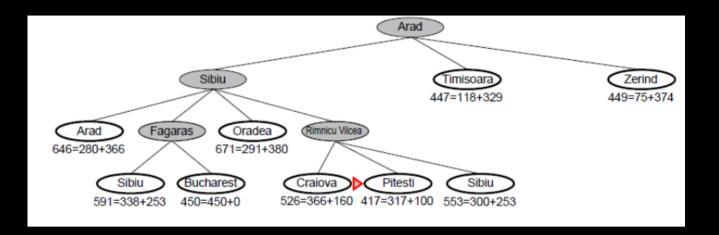
STOD



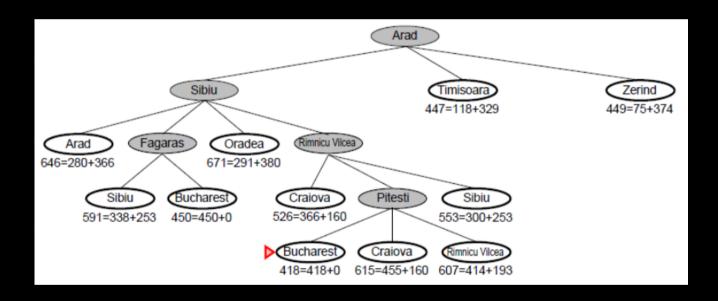
Stop 3

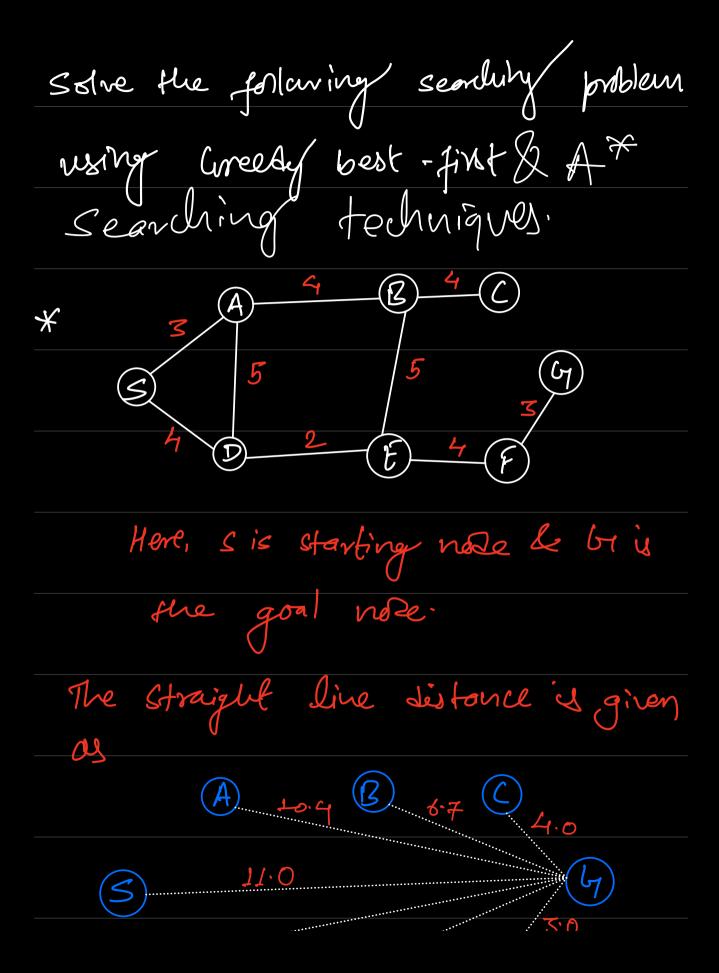


STOPY



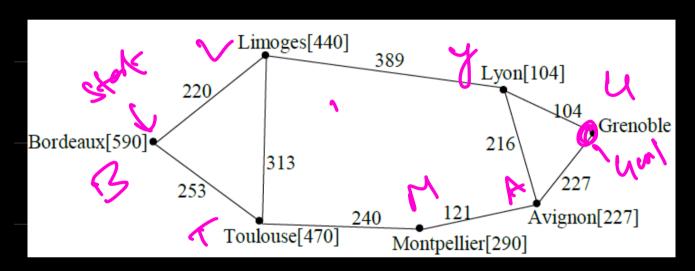
Ctop (



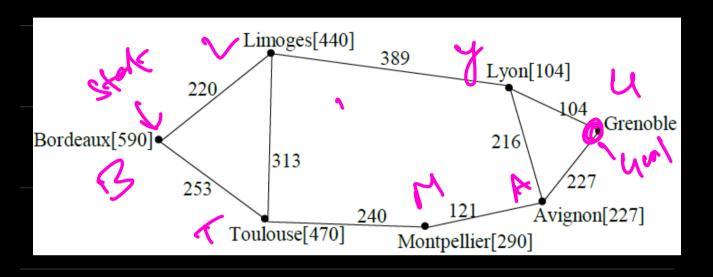




of French cities

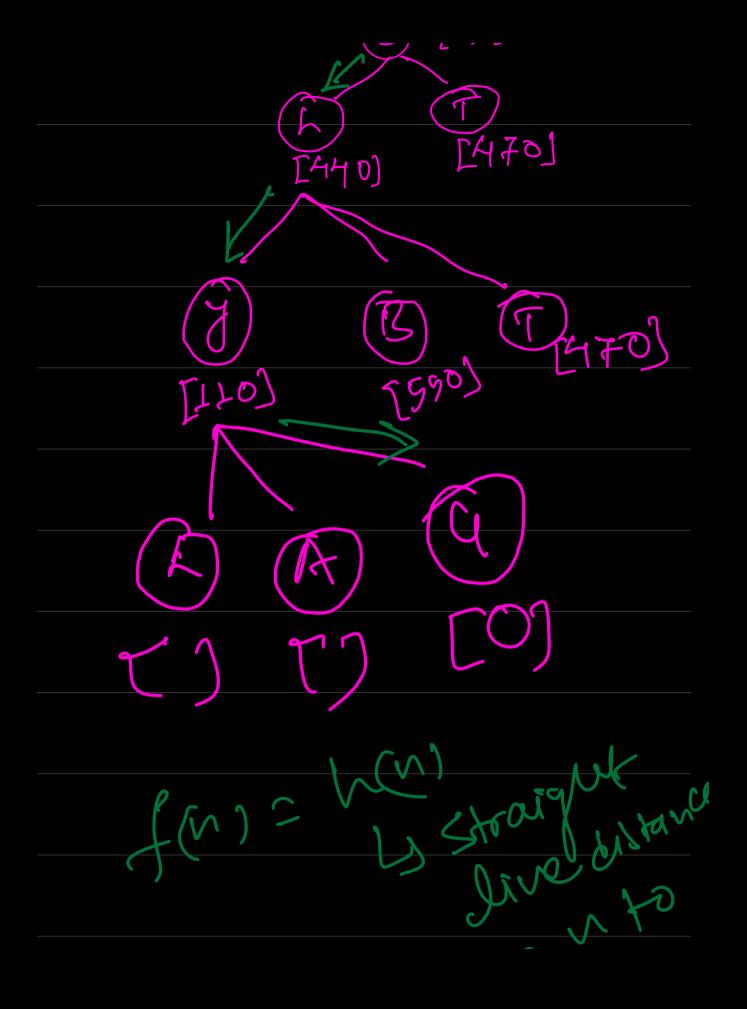


tansider, stort vode & Bordeaux le gant vode to be Grenoble.



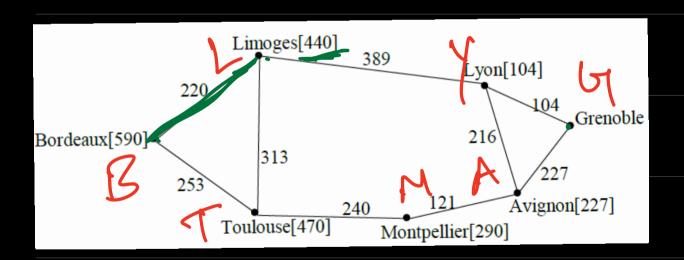
Step 3. [590] B [470] <u>[4</u>40] [470] 7590)

stopy.









evalvation f(v):

f (m) = (g(m) + h(m))

120 f 490 253 f 4760 = 660 = 723