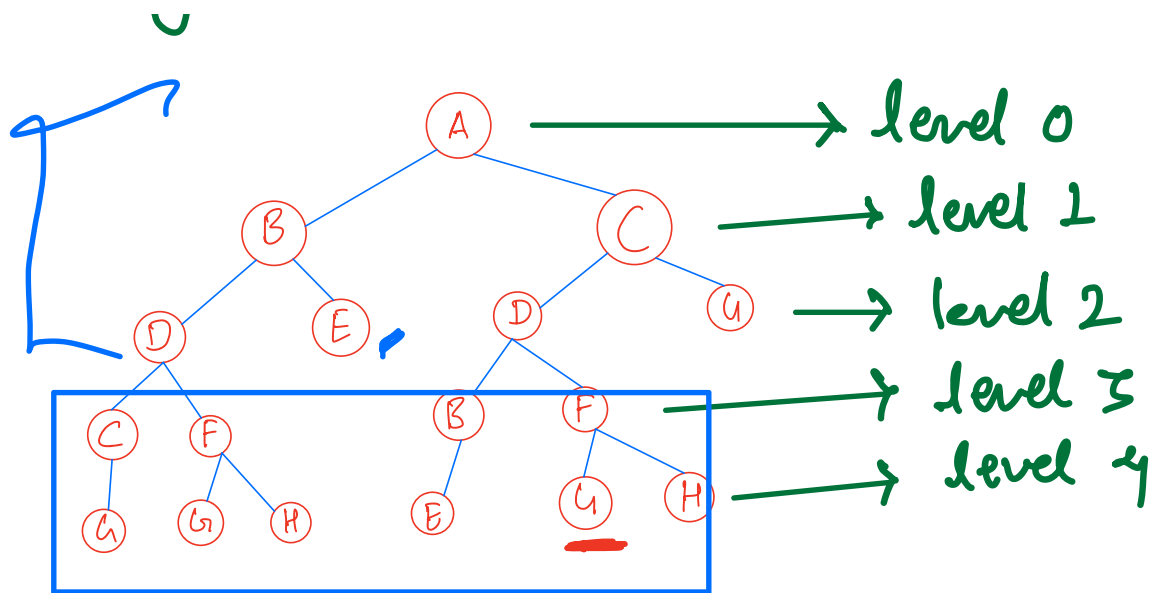


Depth Limited Search:

- To avoid infinite loop condition which may arise in DFS
- Depth limited search is carried out with a predetermined depth limit 'l'.
- Conditions:
 - If $l > d$, gives solutions
where, l is depth limit
 d is depth of goal
 - If $l < d$, incomplete because it cannot find solution at given depth.

For a given state space:

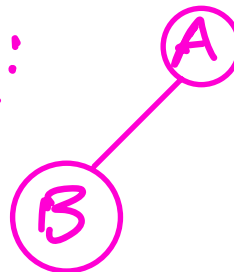


let the depth limit be 2, & the goal node is G

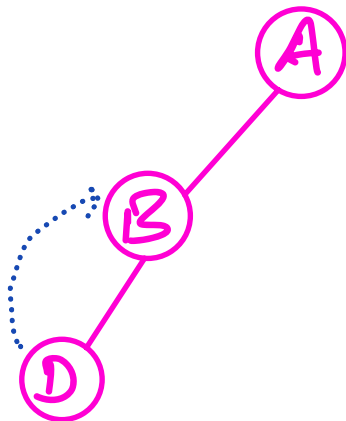
Here,
step 1:



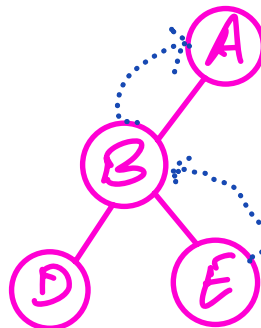
step 2:



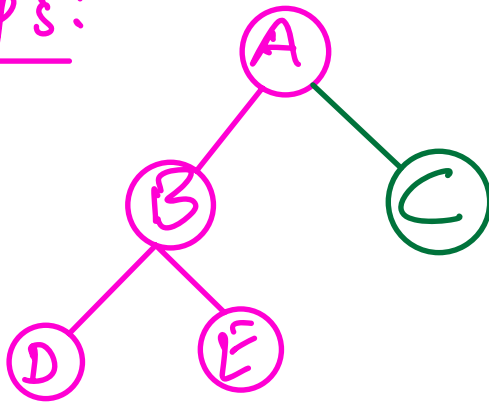
step 3:



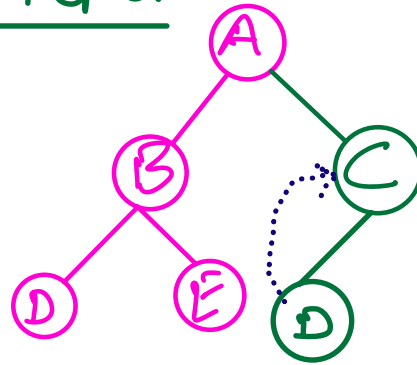
step 4:



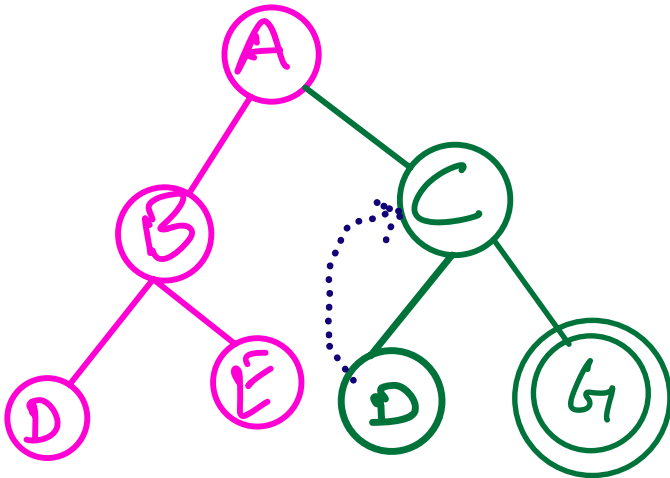
Step 5:



Step 6:



Step 7:



Hence, at the given depth limit 2, the search algorithms terminate finding goal node G.

Performance evaluation:

Completeness:

— complete if solution is above the depth limit l .

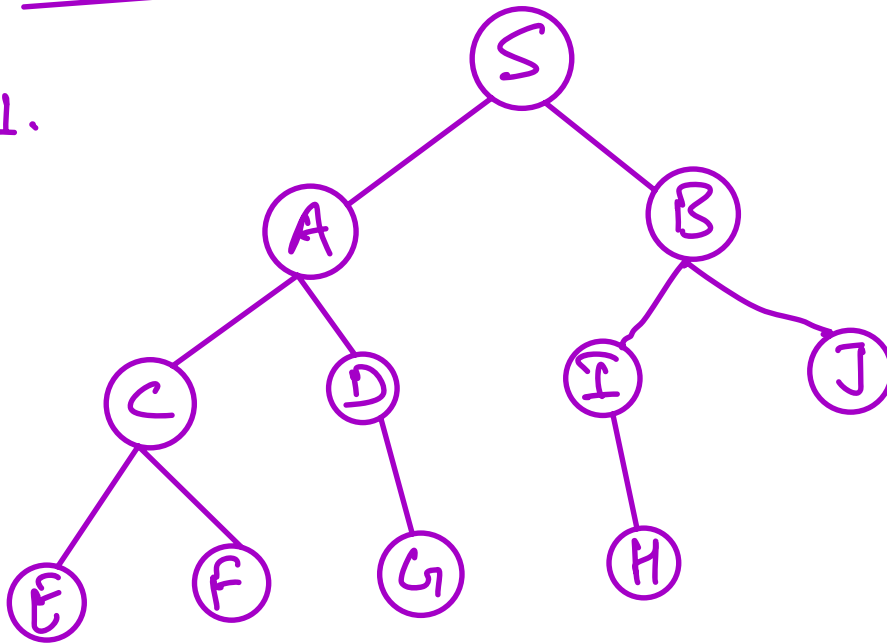
Time complexity: $O(b^l)$

Space complexity: $O(bl)$

Optimal: it can be taken as special case of DFS & not optimal even if $l > d$.

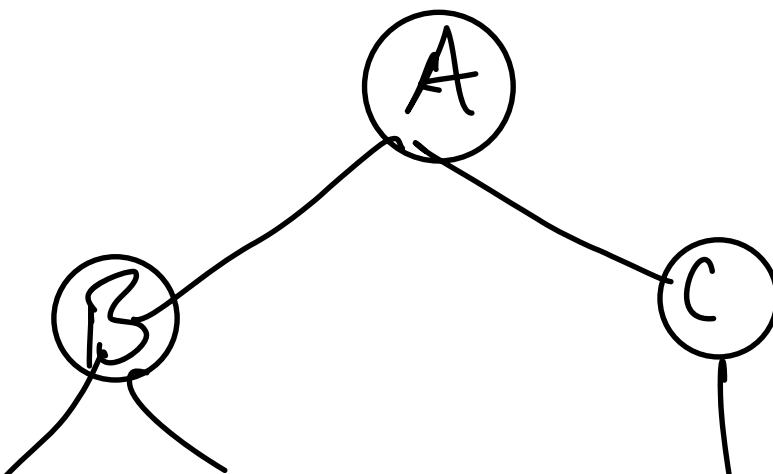
Practice:

1.



perform depth limited search for the above given state space with depth limit 3. Here, start node is S & goal node is G.

2.





limit $(\ell) \approx 3$

with start node A &
goal node M.