

Monthly Project Report for SIMPLEX DARPA Grant: From RAGs to Riches: Utilizing Richly Attributed Graphs to Reason from Heterogeneous Data

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Overview

This monthly report lists cumulative progress on our SIMPLEX statement of work. It is organized into Tasks (capital roman numerals), their respective subtasks (capital alphabet), and subsubtasks (black bold headings). The most recent month's progress is highlighted in red. The appendix lists all cumulative deliverables, including manuscripts, code, data, and resulting derivatives.

I Mathematical Framework

I(A) RAG Embedding

Tensor Factorization:

- **May:** While many tensor factorization algorithms exist, all of them must solve the question of: how many factors to keep. We formulate this question as a model selection question, and are developing model selection for tensor factorization. In preliminary work, we have written four manuscripts detailing these methods over the last couple years: <http://arxiv.org/abs/1312.7559>, <http://arxiv.org/abs/1406.6315>, and <http://arxiv.org/pdf/1406.6319v3.pdf>. In May, we have begun to further develop these methods, make the code open source, and transition to more scalable implementations.
- **June:** We are using tensor and matrix factorization techniques for two subsequent inference tasks. First, we are computing the population average graph. Theory, simulations, and real data experiments demonstrate that we can significantly improve the current state of the art using these methods. Second, we have developed a community detection technique using such methods. Here, numerical experiments demonstrate a significant inference advantage, with a minimal increase in computational cost.

II Computational Infrastructure

II(A) Data Management

Dense Spatial Multi-way Arrays:

- **May:** In previous work, we built a n-way dense spatial database for petascale data (<http://arxiv.org/abs/1306.3543>). However, for the data types we used previously (serial electron microscopy

and array tomography), the data were anisotropic. To visualize that data, our collaborators want to downsample only along the xy dimensions, keeping the z dimension fixed. However, for the new datasets that we will work with for this grant, CLARITY and M³RI, our collaborators desire isotropic downsampling. Thus, we have extended our infrastructure to support multiple types of downsampling, as appropriate for different datasets, including a uniform downsampling. We have already begun using this Web-service to support alignment of CLARITY brains to the Allen Institute for Brain Science's mouse atlas, which is 25 micron isotropic.

- **June:** We have refactored our code such that all projects now have multiple tokens. This is important for both MRI and CLARITY datasets, as both of them might have many tokens per dataset, corresponding to different color channels (in CLARITY), or different modalities (in MRI). We are testing and debugging this code, which will go live shortly.

III Datafication

III(A) Data Ingest

Diffusion MRI:

- **May:** To ingest diffusion MRI data into our spatial database and corresponding annotation database, we require to additional object types in our data model. First, a *skeleton* object type, to store tracts. Second, a *region of interest* (ROI) object type, to store anatomical regions. In May, we have implemented the skeleton object type into our RAMON framework. We have also been working with the designers of COINS and the Human Brain Project, to register our data with them, to enable search across datasets.
- **June:** We have implemented 3 new RAMON object types: *skeleton*, *point*, and *ROI*, to subserve three different functions. ROI can be used for MRI and CLARITY brains, for storing ROIs, and then eventually build new atlases. Skeletons can be used to store fiber tracks from diffusion MRI, or in electron microscopy and array tomography and CLARITY, to trace microscale processes. Points can be used to store any kind of point, be it a synapse, a cell body, or some other point.

IV Discovery

IV(A) RAG Construction

RAG Random Walks:

- **May:** We have empirical evidence as well as theoretical results adapted from Rohe, Chatterjee and Yu (2011) showing that the spectrum of the graph Laplacian is robust to noise. In practice, for dimensionality reduction and embedding purposes, we build the graph Laplacian on the near neighbor matrix of a data set rather than on a dense graph, so one would like to know if similar properties hold when instead of simply adding independent entry-wise noise to a kernel matrix, we have a noisy version of the near neighbor matrix. The core idea is to use the fact that the graph Laplacian is related to the commute times of the graph: we want to show that certain kinds of noise do not change the random walks on that graph, and hence do not greatly change the Laplacian eigenmap embedding.
- **June:** We are investigating the computational trade-offs associated with computing normalized versus unnormalized adjacency and Laplacian matrices.

Phase	Task	#	Sub-Task	Phase I					Phase II				Phase III				Responsible
	GPU		Milestone	Q1	Q2	Q3	Q4	Q5	Q6	Q7	Q8	Q9	Q10	Q11	Q12	Q13	Agent
I	RAG Embedding	I.1.A	Tensor Factorization														Priebe
		I.1.B	JOFIC														Priebe
		I.1.C	Benchmarking														Priebe
II	FlashRAG	II.1.A	FlashMatrix														Priebe
		II.1.B	FlashAttributes														Priebe
		II.1.C	FlashR														Priebe
III	Rag Testing	III.1.A	1-sample														Priebe
		III.1.B	2-sample														Priebe
		III.1.C	independence														Priebe
I	Data Management	I.2.A	Dense Arrays														Burns
		I.2.B	Sparse Arrays														Burns
		I.2.C	Sparse Cutsouts														Burns
II	Remote Access	II.1.A	2D Web Viz														Burns
		II.1.B	Surface Extraction														Burns
		II.1.C	3D Web Viz														Burns
III	Local Analysis	III.1.D	Graph Viz														Burns
		III.1.A	API														Burns
		III.1.B	Downloads														Burns
		III.1.C	GPU 3D Viz														Burns
		III.1.D	Remote Annotation														Burns
I	Data Ingest	I.3.A	diffusion MRI														Vogelstein
		I.3.B	functional MRI														Vogelstein
		I.3.C	CLARITY														Vogelstein
II	Data Register	I.3.D	LFM														Vogelstein
		II.3.A	Human Align														Vogelstein
		II.3.B	Mouse Align														Vogelstein
III	Quality Control	II.3.C	Multi-Graph-Match														Vogelstein
		III.3.A	diffusion MRI														Vogelstein
		III.3.B	functional MRI														Vogelstein
		III.3.C	CLARITY													Vogelstein	
		III.3.D	LFM													Vogelstein	
I	RAG Construct	I.4.A	Random Walks														Lee
		I.4.B	Graph Sparsification														Lee
		I.4.C	Benchmarking														Lee
II	RAG Summary Statistics	I.4.A	Moments														Lee
		II.4.B	Motifs														Lee
		II.4.C	Modes														Lee
III	RAG Predict	II.4.A	Nearest Neighbor														Lee
		III.4.B	Network of Networks														Lee
		III.4.C	Tensor Factorization														Lee
		III.4.D	Benchmarking													Lee	
	Monthly Tech Reports	5		X	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	Vogelstein
	Monthly Financial Reports	5		X	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XXX	Vogelstein
	Quarterly Reports	5		X	X	X	X	X	X	X	X	X	X	X	X	X	Vogelstein
	Final Report	5						X				X				X	Vogelstein