

G. FRANÇA NOTES - MACHINE LEARNING

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BASIC LINEAR ALGEBRA

$A \in \mathbb{R}^{m \times m}$ or $A \in \mathbb{C}^{m \times m} \rightarrow$ Matrix.

If it is a linear map, $A: \mathbb{C}^n \rightarrow \mathbb{C}^m$, $\begin{cases} A(\lambda x) = \lambda Ax \\ x \mapsto Ax \\ A(x+y) = Ax + Ay \end{cases}$

- $b = Ax$, $b_i = \sum_{j=1}^m a_{ij} x_j$ (standard)

Can also be seen as

$$\begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} = \left(\begin{array}{c|c|c|c} a_1 & a_2 & \cdots & a_m \end{array} \right) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix} = \sum_{i=1}^m a_i x_i = b$$

Numbers Vectors Numbers \Downarrow

$$\begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & & & \\ a_{m1} & a_{m2} & \cdots & a_{mm} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}$$

linear
combination of
the columns of
 A

\Downarrow

$$\begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} = x_1 \underbrace{\begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{pmatrix}}_{a_1} + x_2 \underbrace{\begin{pmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{pmatrix}}_{a_2} + \cdots + x_m \underbrace{\begin{pmatrix} a_{1m} \\ a_{2m} \\ \vdots \\ a_{mm} \end{pmatrix}}_{a_m}$$

②

$$\bullet \quad B = AC \quad b_{ij} = \sum_{k=1}^n a_{ik} c_{kj} \quad (\text{standard})$$

$$(b_1 | b_2 | \dots | b_k) = A (c_1 | c_2 | \dots | c_k)$$

$$b_i = AC_i = \sum_{j=1}^n a_{ij} c_{ji}$$

i th column of B is a linear combination of the columns of A , with coefficients given by the i th column of C .

$$\begin{pmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{m1} & b_{m2} & \dots & b_{mn} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & & & \\ a_{m1} & a_{m2} & \dots & a_{mm} \end{pmatrix} \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1k} \\ c_{21} & c_{22} & \dots & c_{2k} \\ \vdots & & & \\ c_{m1} & c_{m2} & \dots & c_{mk} \end{pmatrix}$$

$$(b_1 | \dots | b_k) = (AC_1 | \dots | AC_n)$$

$$\text{Ex.: } u v^T = \begin{pmatrix} u \end{pmatrix} (v_1 \ v_2 \ \dots \ v_m) = (uv_1 \ | \ uv_2 \ | \ \dots \ | \ uv_m)$$

outer prod.

$$\begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix} (v_1 \ v_2 \ \dots \ v_m) = \begin{pmatrix} u_1 v_1 & u_1 v_2 & \dots & u_1 v_m \\ u_2 v_1 & u_2 v_2 & \dots & u_2 v_m \\ \vdots & \vdots & & \vdots \\ u_m v_1 & u_m v_2 & \dots & u_m v_m \end{pmatrix}$$

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Ex.: Let R be $r_{ij} = 1$ if $j > i$, $r_{ij} = 0$ if $j < i$. 3 ↗

$$R = \begin{pmatrix} 1 & 1 & 1 & 1 & \dots & 1 \\ 0 & 1 & 1 & 1 & \dots & 1 \\ 0 & 0 & 1 & 1 & \dots & 1 \\ 0 & 0 & 0 & 1 & \dots & 1 \\ 0 & 0 & 0 & 0 & \dots & 1 \\ \vdots & & & & & \end{pmatrix}$$

$$\vec{z} = A\vec{R}$$

$$z_j = \sum_{k=1}^m a_k r_{kj}$$

$$= \sum_{k=1}^j a_k \quad \text{Sum of the first } j \text{ columns of } A.$$

- $\text{Range}(A) = \{y \in \mathbb{C}^m \mid y = Ax \text{ for some } x \in \mathbb{C}^n\}$
- $\text{Null}(A) = \{x \in \mathbb{C}^n \mid Ax = 0\}$
- $\text{Rank}(A) = \# \text{ indep. cols of } A. \quad \text{Theorem (SVD)}$
 $= \# \text{ indep. rows of } A$
 $A \text{ has } \underline{\text{full rank}} \text{ if } \text{rank}(A) = \min(m, n)$

Theo. $\text{Range}(A)$ is the space spanned by the cols. of A .

- Inverse. $e_1 = (1, 0, 0, \dots, 0)^T$
 $e_2 = (0, 1, 0, \dots, 0)^T$
 \vdots

If A has full rank then $e_i = \sum_{j=1}^m a_{ji} z_{ji}$, or
 $J = A\vec{z}$, so there is \vec{z} such that $A\vec{z} = J$.
 \vec{z} is the inverse of A , $\vec{z} = A^{-1}$.



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Equivalent statements:

- (1) A has an inverse A^{-1}
- (2) A has full rank
- (3) $\det A \neq 0$
- (4) $\text{range}(A) = \mathbb{C}^m$
- (5) $\text{null}(A) = \{0\}$
- (6) $\lambda(A) \neq 0$
- (7) $\sigma(A) \neq 0$

$x = A^{-1}b$ think about $AX = b$, i.e.

$A^{-1}b$ is the vector of coefficients of the expansion of b in the basis (column) of A .

Let $A \in \mathbb{C}^{m \times n}$. The Hermitian Conjugate or adjoint of A is denoted by A^* and defined by

$$A^* = \begin{pmatrix} a_{11}^* & a_{12}^* & \cdots & a_{1n}^* \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}^* & a_{m2}^* & \cdots & a_{mn}^* \end{pmatrix} \quad \text{Transpose Conjugate}$$

A is Hermitian if $A = A^*$. If $A \in \mathbb{R}^{m \times n}$ then A is said to be Symmetric, $A = A^T$.

Inner product:

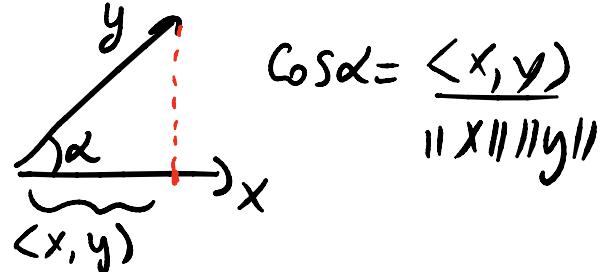
Let $x, y \in \mathbb{C}^n$. We define

$$\langle x, y \rangle = x^T y = \sum_{i=1}^m x_i^* y_i$$

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The norm of x is $\|x\| = \sqrt{\langle x, x \rangle}$.

Geometric interpretation:



$$\cos \alpha = \frac{\langle x, y \rangle}{\|x\| \|y\|}$$

$$\begin{aligned}
 \text{Bilinearity: } & \cdot \langle x_1 + x_2, y \rangle = (x_1 + x_2)^T y \\
 & = x_1^T y + x_2^T y = \langle x_1, y \rangle + \langle x_2, y \rangle \\
 & \cdot \langle x, y_1 + y_2 \rangle = x^T (y_1 + y_2) \\
 & = x^T y_1 + x^T y_2 = \langle x, y_1 \rangle + \langle x, y_2 \rangle \\
 & \cdot \langle x, \alpha y \rangle = x^T \alpha y = \alpha x^T y = \alpha \langle x, y \rangle \\
 & \cdot \langle \alpha x, y \rangle = (\alpha x)^T y = \alpha^* x^T y = \alpha^* \langle x, y \rangle
 \end{aligned}$$

Orthogonal vectors: $\langle x, y \rangle = 0$

$S = \{x_1, \dots, x_m\}$ is an orthogonal set if $\langle x_i, x_j \rangle = 0$ when $i \neq j$. In addition, S is orthonormal if $\|x_i\| = 1 \forall i$, or, $\langle x_i, x_j \rangle = \delta_{ij}$.

Notice that $\|x\|^2 = \langle x, x \rangle = \sum_{i=1}^m x_i^* x_i = \sum_{i=1}^m |x_i|^2 \geq 0$,
Thus $\|x\| = 0 \Leftrightarrow x = 0$.

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Theorem. The vectors in an orthogonal set are linearly independent. ⑥

Proof. Suppose they are not independent, i.e.

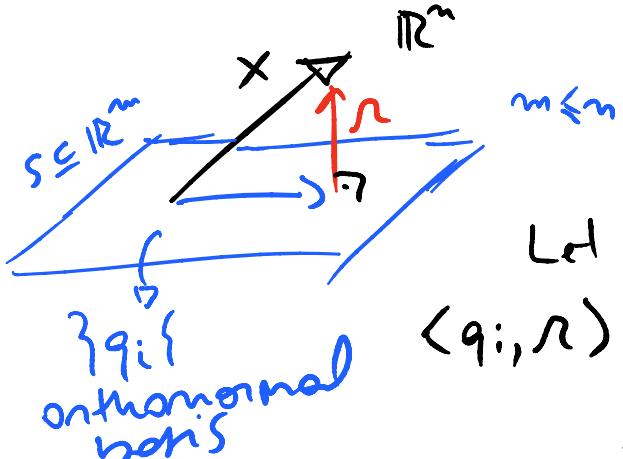
$$x_k = \sum_{\substack{j=1 \\ j \neq k}}^m a_j x_j.$$

Then $\langle x_k, x_k \rangle = \sum_{\substack{j=1 \\ j \neq k}}^m a_j \langle x_k, x_j \rangle = 0$ since they are orthogonal by assumption. But this implies that

$x_k = 0$ which is a contradiction. □

Corollary. If $S \subseteq \mathbb{R}^m$ and S has m orthogonal vectors, then S is a basis of \mathbb{R}^m .

Inner products can be used to decompose a vector into orthogonal projections.



$$\bar{x} = \sum_{i=1}^m \langle q_i, x \rangle q_i$$

$$\begin{aligned} \text{Let } r &= x - \bar{x}. \text{ Then,} \\ \langle q_i, r \rangle &= \langle q_i, x \rangle - \sum_{j=1}^m \underbrace{\langle q_j, x \rangle}_{\langle q_i, q_j \rangle} \underbrace{\langle q_i, q_j \rangle}_{\delta_{ij}} \\ &= \langle q_i, x \rangle - \langle q_i, x \rangle \delta_{ij} \\ &= 0 \end{aligned}$$

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$$\begin{aligned}
 \text{Thus } X &= R + \sum_{i=1}^m \langle q_i, x \rangle q_i \\
 &= R + \sum_{i=1}^m (q_i^T x) q_i = R + \sum_{i=1}^m q_i (q_i^T x) \\
 &= R + \left(\sum_{i=1}^m q_i q_i^T \right) x
 \end{aligned}$$

The operator $P_i = q_i q_i^T$ projects x into the ray of q_i . Notice that $\text{Rank}(P_i) = 1$. The operator $P = \sum_{i=1}^m q_i q_i^T$ projects x into $S \subseteq \mathbb{R}^m$ subspace.

$\text{rank}(P) = m$. If $m = n$ then $\{q_i\}$ is a basis for \mathbb{R}^n and $X = \sum_{i=1}^m c_i q_i$, thus

$$\langle q_j, x \rangle = \sum_{i=1}^m c_i \underbrace{\langle q_j, q_i \rangle}_{S_{ij}} = c_j \quad \therefore X = \sum_{i=1}^m \langle q_i, x \rangle q_i$$

$$\text{or } X = \sum_{i=1}^m q_i^T x q_i = \left(\sum_{i=1}^m q_i q_i^T \right) x \quad \therefore P = \sum_{i=1}^m q_i q_i^T = I.$$

This is known as completeness relation.

Unitary Matrices

$$U U^T = U^T U = I \quad (\text{unitary}, U \in \mathbb{C}^{n \times n})$$

$$Q Q^T = Q^T Q = I \quad (\text{orthogonal}, Q \in \mathbb{R}^{n \times n})$$

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(B)

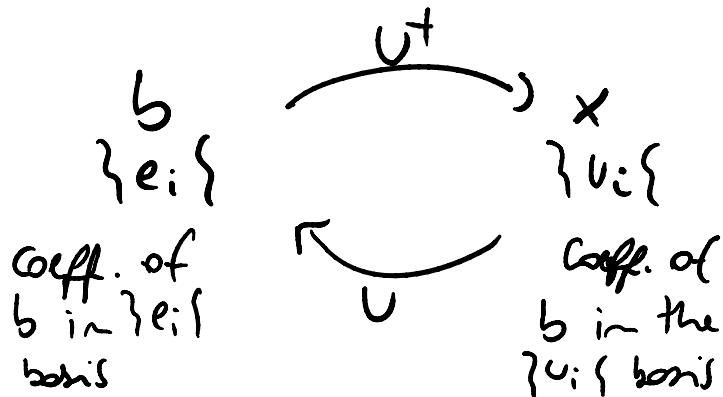
Viewing as before:

$$\begin{pmatrix} u_1^+ \\ u_2^+ \\ \vdots \\ u_m^+ \end{pmatrix} (|u_1| |u_2| \dots |u_m|) = (1, 1, \dots)$$

$$u_i^+ u_j = \delta_{ij}$$

so the columns of U are orthogonal vectors.

UX is a linear combination of the columns of U . $U^+ b$ is the vector whose components are the expansion of b in the basis of U .



Now let $\tilde{x} = UX$, $\tilde{y} = Uy$, thus

$$\langle \tilde{x}, \tilde{y} \rangle = \tilde{x}^+ U^+ U y = x^+ y = \langle x, y \rangle$$

Thus unitary transformations preserve the inner product, or norm of vectors.

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vector norms

$\|\cdot\|: \mathbb{C}^m \rightarrow \mathbb{R}$ such that

1. $\|x\| \geq 0$ and $\|x\|=0$ iff $x=0$.
2. $\|x+y\| \leq \|x\| + \|y\|$ (triangle inequality)
3. $\|\alpha x\| = |\alpha| \|x\|$

Unit ball: $B = \{x \in \mathbb{C}^m \mid \|x\| \leq 1\}$.

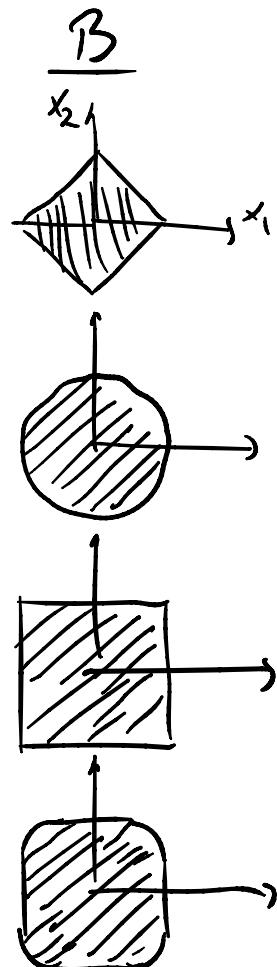
p-norms $\|x\|_p$

$$\|x\|_1 = \sum_{i=1}^m |x_i|$$

$$\|x\|_2 = \left(\sum_{i=1}^m |x_i|^2 \right)^{1/2}$$

$$\|x\|_\infty = \max \{|x_i|\}$$

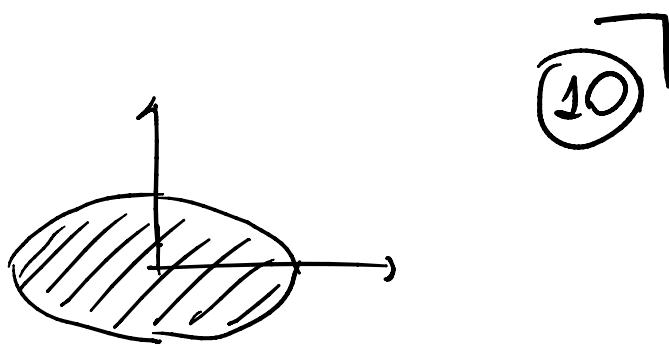
$$\|x\|_p = \left(\sum_{i=1}^m |x_i|^p \right)^{1/p}$$



weighted norm: $\|x\|_w = \|Wx\|$ where $W = \text{diag}(w_1, \dots, w_m)$

For example

$$\|x\|_w = \left(\sum_{i=1}^m |w_i x_i|^2 \right)^{1/2}$$



Induced Matrix Norms

Let $A \in \mathbb{C}^{m \times n}$, $\|x\|_m$ a norm of $x \in \mathbb{C}^n$, and $\|y\|_m$ a norm of $y \in \mathbb{C}^m$. These two vector norms induces a matrix norm $\|A\|_{(m,n)}$ as follows:

$$\|A\|_{(m,n)} = \sup_x \frac{\|Ax\|_m}{\|x\|_m} = \sup_{\|x\|_m=1} \|Ax\|_m$$

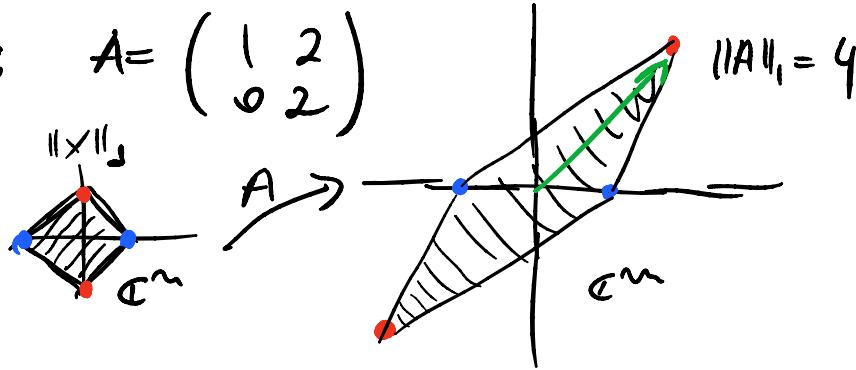
In other words $\|A\|_{(m,n)}$ is the smallest C such that

$$\|Ax\|_m \leq C \|x\|_m$$

holds for any $x \in \mathbb{C}^n$. This is the maximum factor that A can stretch a vector.

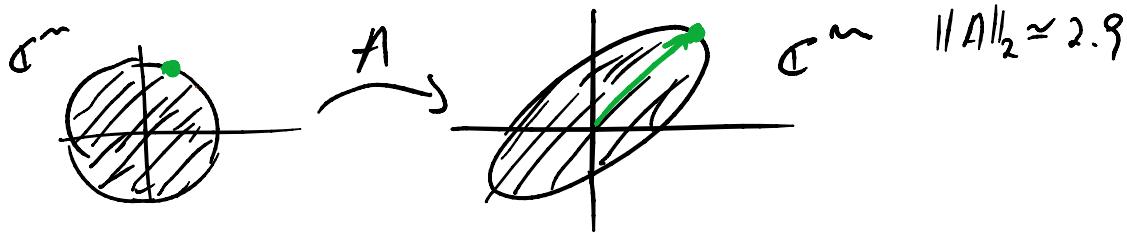
Example in 2D: $A = \begin{pmatrix} 1 & 2 \\ 0 & 2 \end{pmatrix}$

L -Norm $\|A\|_1$

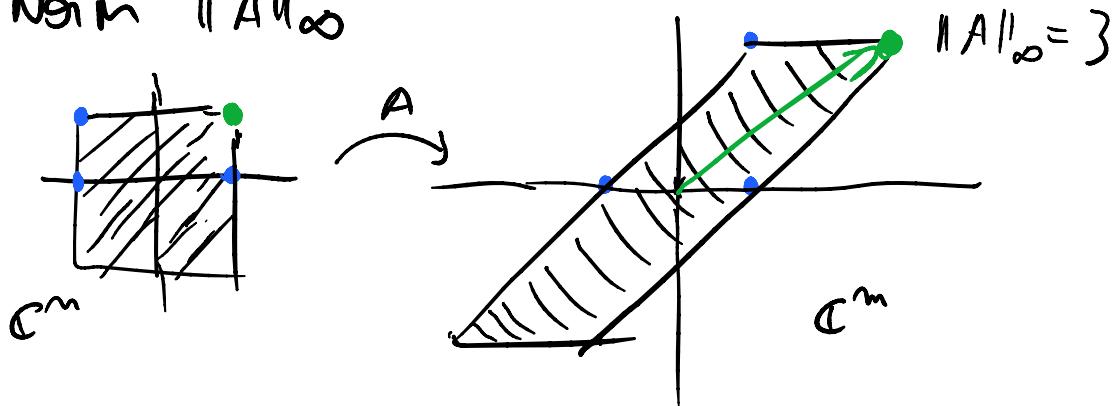


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2-norm $\|A\|_2$



∞ -norm $\|A\|_\infty$



$$\|A\|_2 \leq \|A\|_\infty \leq \|A\|_1$$

Example. $D = \text{diag}(d_1, \dots, d_m)$. The unit circle $\|x\|$ is mapped into an hyperellipse whose semi-axes have size $|d_i|$. Thus $\|D\|_2 = \max |d_i|$. The same holds for $\|D\|_p = \max |d_i|$.

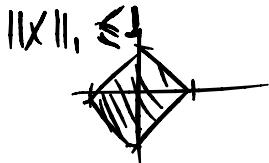
Now consider the 1-norm of $A = (a_1 | \dots | a_m)$.

$$\text{we have } \|A\|_1 = \max_{\|x\|=1} \|Ax\|_1$$

$$= \max_{\|x\|=1} \left\| \sum_{j=1}^m x_j a_j \right\| \leq \max_{\|x\|=1} \sum_{j=1}^m |x_j| \|a_j\|_1$$

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Consider the unit ball, i.e.



$$\max_{\|x\|=1} \sum_{j=1}^m |x_j| = \max_{\|x\|=1} \|x\|_1 = 1$$

and replace $\|a_j\|_1 \rightarrow \max_j \|a_j\|_1$. Then

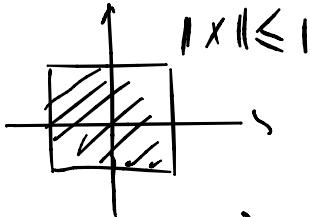
$$\|A\|_1 \leq \max_j \|a_j\|_1$$

Now choose x such that $AX = a_j$ where $a_j = \max_k \|a_k\|_1$.
Thus the above bound is attainable and

$$\|A\|_1 = \max_j \|a_j\|_1$$

$\|A\|_1$ is the maximum "column sum" of A .

Consider $\|A\|_\infty$. $\|x\|_\infty = \max_i |x_i|$ and the unit ball is



$$\|A\|_\infty = \max_{\|x\|=1} \|Ax\|_\infty = \max_{\|x\|=1} \left\{ |(Ax)_i| \right\}$$

$$|(Ax)_i| = \left| \sum_{j=1}^m a_{ij} x_j \right| \leq \sum_{j=1}^m |a_{ij}| |x_j| \leq \sum_{j=1}^m |a_{ij}| = \|\tilde{a}_i\|_1$$

where \tilde{a}_i is the i th row of A .

where m_i is the i -th row of A .

Thus $\|A\|_\infty \leq \max_i \|\tilde{a}_i\|_1$. But it is possible to choose a unit vector x such that the bound is attainable, thus

$$\|A\|_\infty = \max_i \|\tilde{a}_i\|_1$$

is the maximum "row sum" of A .

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Cauchy-Schwarz and Hölder

We have Cauchy-Schwarz inequality.

$$|x^T y| \leq \|x\|_2 \|y\|_2.$$



$$\langle x, y \rangle = \|x\| \|y\| \cos \alpha$$

This can be generalized to

$$|x^T y| \leq \|x\|_p \|y\|_q$$

provided $\frac{1}{p} + \frac{1}{q} = 1$ for $p, q \geq 1$. This is Hölder's inequality.

Ex.: Outer product $A = u v^T = \begin{pmatrix} u_1 \\ \vdots \\ u_m \end{pmatrix} (v_1^T \dots v_m^T)$

$$\|A\|_2 = \max_{\|X\|_2} \|AX\|_2 = \max_{\|X\|_2} \|u v^T x\|_2 = \max_{\|X\|_2} \|u\|_2 |v^T x|$$

$$\text{but } |v^T x| \leq \|v\|_2 \|x\|_2 \therefore \|A\|_2 \leq \max_{\|X\|_2} \|u\|_2 \|v\|_2.$$

This is attainable, just make $x = v$. Therefore,

$$\|u\|_2 \leq \|v\|_2 \wedge \|v\|_2 \leq \|u\|_2 \Rightarrow \|u\|_2 = \|v\|_2.$$

This is attainable, just take $x = v$. Therefore,

$$\|uv^T\| = \|u\|_2 \|v\|_2.$$

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Notice that $\|Ax\| \leq C\|x\|$ where $C = \|A\|$.

This is the maximum stretch. Thus $\|Ax\| \leq \|A\| \|x\|$ for any x . Now let $A \in \mathbb{C}^{l \times n}$, $B \in \mathbb{C}^{m \times n}$, $x \in \mathbb{C}^n$:

$$\begin{aligned}\|ABx\|_{(l)} &\leq \|A\|_{(l, m)} \|Bx\|_{(m)} \\ &\leq \|A\|_{(l, m)} \|B\|_{(m, n)} \|x\|_{(n)}\end{aligned}$$

$$\|AB\| = \max_x \frac{\|ABx\|}{\|x\|} \therefore \|AB\| \leq \|A\| \|B\|$$

In general the equality is not attainable.

General Matrix Norms

Matrices $A \in \mathbb{C}^{m \times n}$ form a vector space, thus one can define an arbitrary norm $\|A\|$, which does not need to be induced by a vector norm, provided

1. $\|A\| \geq 0$, $\|A\| = 0 \Leftrightarrow A = 0$
2. $\|A+B\| \leq \|A\| + \|B\|$
3. $\|\alpha A\| = |\alpha| \|A\|$

hold. An important example is the Frobenius norm:

$$\begin{aligned}\|A\|_F &= \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2 \right)^{1/2} \\ &= \left(\sum_{i=1}^m \|a_i\|^2 \right)^{1/2}\end{aligned}$$

$$= \left(\sum_{i=1}^n \|Q_i\|_2^2 \right)^{1/2}$$

Notice also that $(A^T A)_{kk} = \sum_{j=1}^m Q_{jk}^* Q_{jk}$.

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Thus $(A^T A)_{kk} = \sum_{j=1}^m Q_{jk}^* Q_{jk} = \sum_{j=1}^m |Q_{jk}|^2$. Summing over k given

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$$\|A\|_F^2 = \text{Tr}(A^T A) = \text{Tr}(AA^T)$$

Let $C = AB$. $c_{ij} = \sum_{k=1}^m Q_{ik} b_{kj} = \underbrace{Q_i^+ b_j}_{\text{column}}$.

$$\begin{aligned} \|AB\|_F^2 &= \sum_{i=1}^m \sum_{j=1}^l |c_{ij}|^2 = \sum_{i=1}^m \sum_{j=1}^l \|Q_i^+ b_j\|^2 \\ &\leq \sum_{i=1}^m \sum_{j=1}^l \|Q_i^+\|_2^2 \|b_j\|_2^2 \\ &= \sum_{i=1}^m \|Q_i^+\|_2^2 \sum_{j=1}^l \|b_j\|_2^2 \\ &= \|A\|_F^2 \|B\|_F^2 \end{aligned}$$

$$\|AB\|_F \leq \|A\|_F \|B\|_F$$

Theorem. Let U be unitary, $UU^T = I = U^T U$. Then

$$\|UA\|_2 = \|A\|_2 \quad \text{and} \quad \|UA\|_F = \|A_F\|.$$

Proof. $\|UA\|_2^2 = \max_{\|X\|=1} \|UAX\|_2^2 = \max_{\|X\|=1} (UAX)^T (UAX)$

$$\begin{aligned}
 \text{proof. } \|UA\|_2^2 &= \max_{\|X\|=1} \|UAX\|_2^2 = \max_{\|X\|=1} (UAX)^T(UAX) \\
 &= \max_{\|X\|=1} X^T A^T U^T U A X = \max_{\|X\|=1} \|AX\|_2^2 = \|A\|_2^2
 \end{aligned}$$

$$\|UA\|_F = \text{Tr}((UA)^T UA) = \text{Tr}(A^T U^T UA) = \text{Tr}(A^T A) = \|A\|_F \quad \square$$