

# In Gaze We Trust: Comparing Eye Tracking, Self-report, and Physiological Indicators of Dynamic Trust during HRI



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## BACKGROUND

Trust has been shown to affect outcomes of human-robot interactions (HRI) [1]. Human operators can over-trust and misuse the system by not providing sufficient monitoring, causing accidents, and it is also possible for them to disuse the robot due to under-trusting [2, 3]. Thus, it is important to continuously measure and understand the dynamics of shared space HRI trust and how trust is built, breached, and recovered.

## OBJECTIVE

Assess if eye tracking or physiological indicators offer greater sensitivity in capturing dynamic trust during HRI than the commonly used trust self-reports

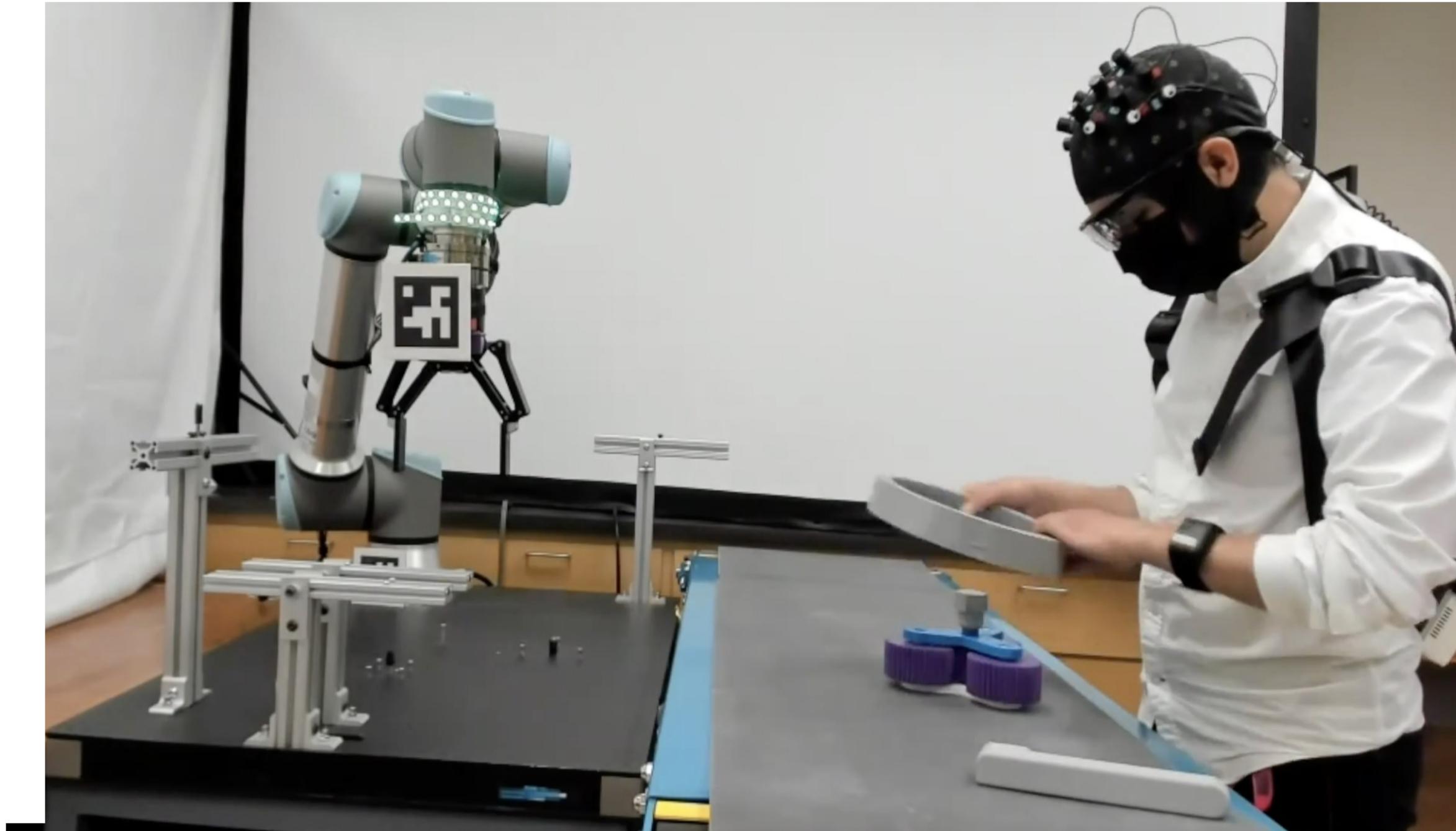
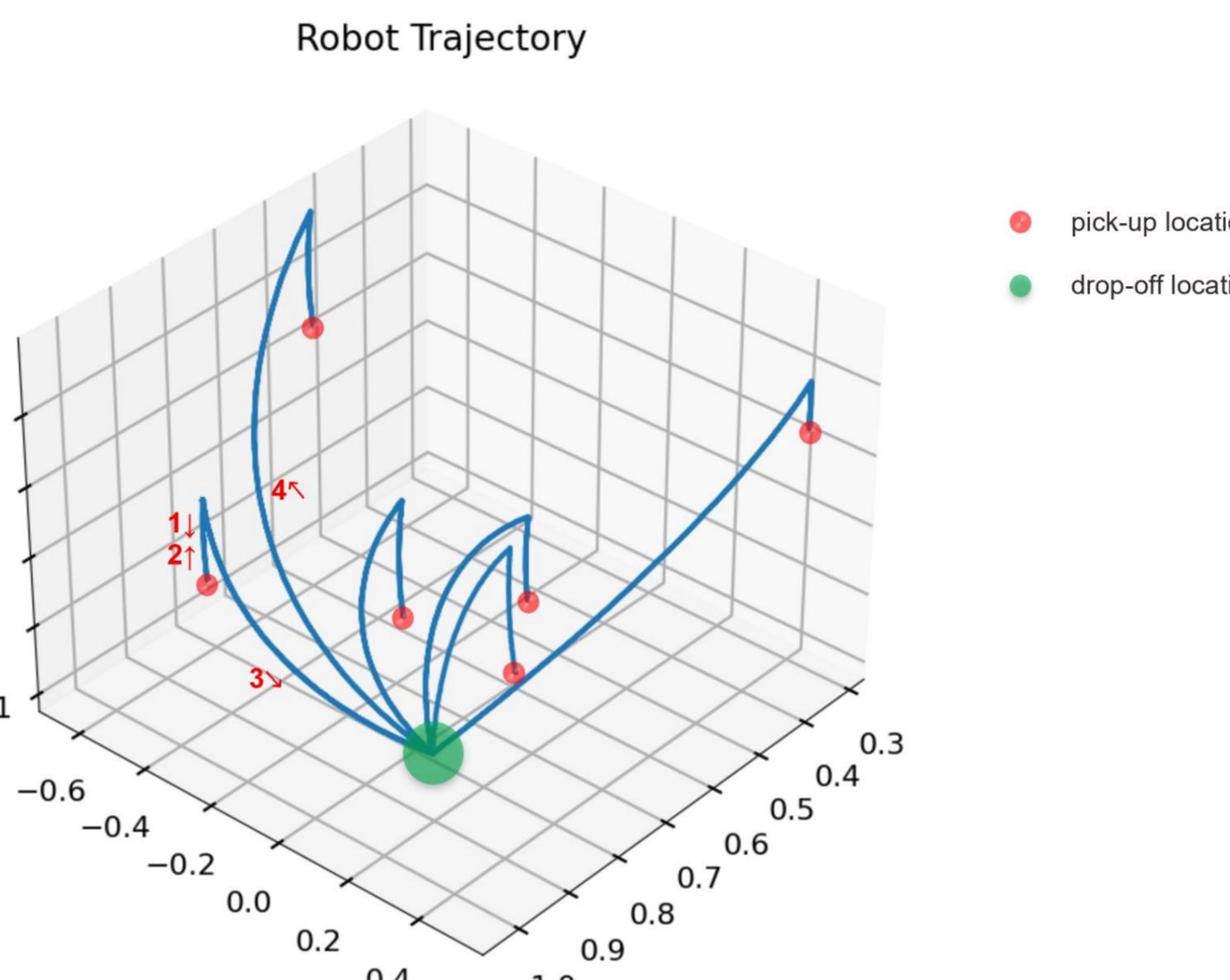
## METHODS

- 38 participants (18 males, 22 females), mean age  $25.88 \pm 5.27$  years
- Universal Robots collaborative-robot (UR10; Universal Robots, Denmark)
- **Ten 100% reliable trials**, then **ten 76% reliable trials to manipulate trust**

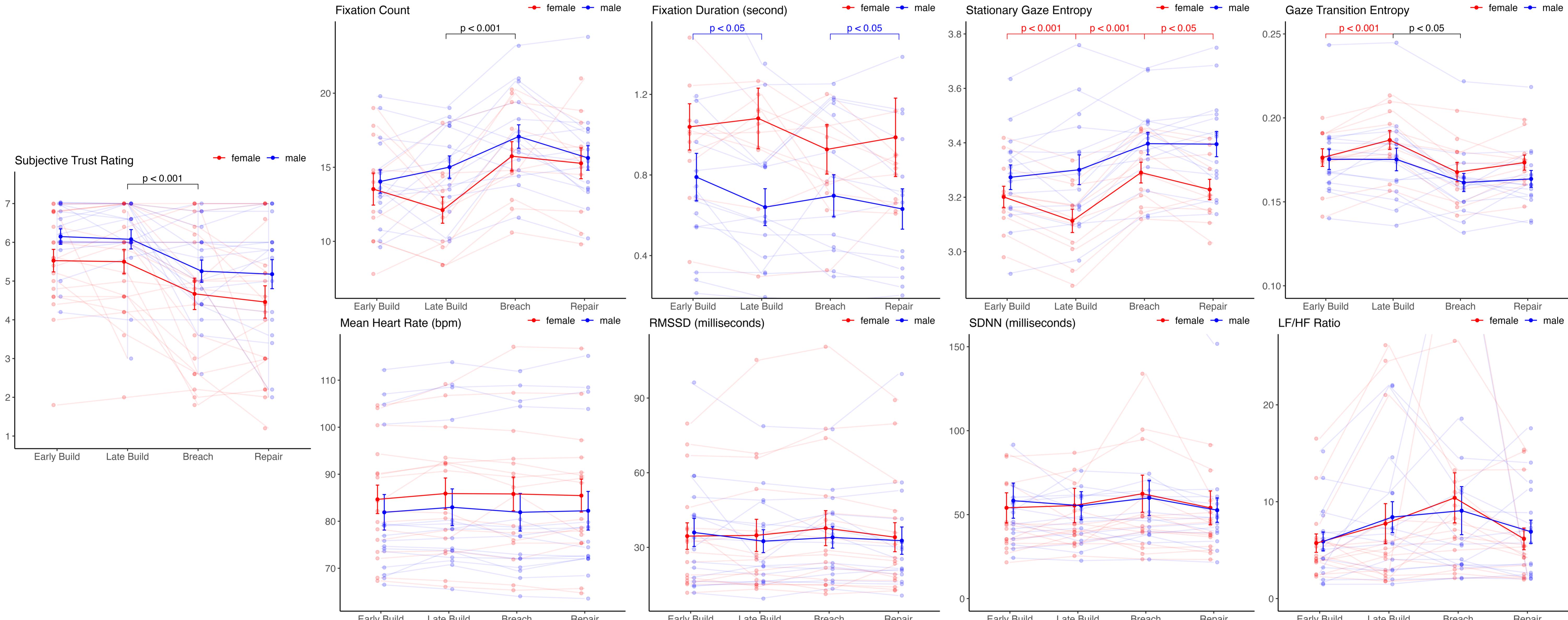


### Robot Perturbations

1. Sudden increase in speed to 100% max designed joint speed (120%/Sec.)
2. Sudden loss of speed to 30% max designed joint speed
3. Sudden change in robot indicator light to idle color during operation
4. Invasion of human space while delivering part
5. Variation ( $\pm 20$  cm) in X and Y drop-off location
6. Providing a part in the incorrect sequence
7. Dropping a part from 30 cm above the workspace table



## RESULTS



Subjective trust

**Only captured trust breach**, with no change during the build and repair phases. No sex differences.

Heart rate variability

**Not sensitive to dynamic trust change**, potentially due to complex motor movements.

Eye tracking fixation

**Decrease in subjective trust was associated with increased fixation counts**, reaffirming evidence of the negative relationship between human-automation trust and monitoring frequency [5].

Eye tracking entropy

**Decreased GTE during the trust breach resembled distrusting behavior** [6], supported by decreased trust ratings.

**Sex differences – Only males exhibited less automation monitoring during the late build and repair phase; females' unique changes were in entropies throughout the phases.**

## KEY TAKEAWAYS

- Subjective trust measure was not sensitive to all trust manipulations and additional gaze behavior differences were observed across trust build, breach, and repair phases.
- Gaze behavior is a cognitive outcome, and males & Females demonstrated different cognitive behaviors during trust changes.
- Ultra-short-term HR metrics (<5min) did not capture trust changes, and its sensitivity can be context-based.

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