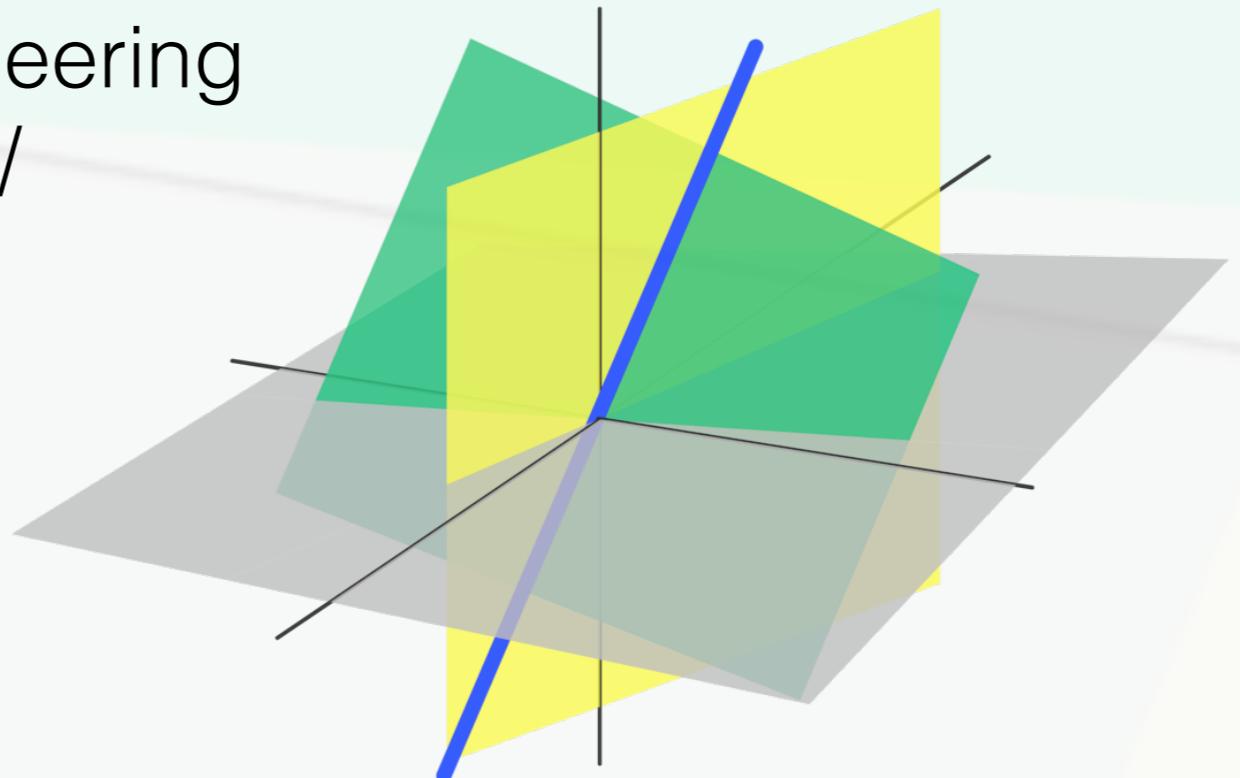


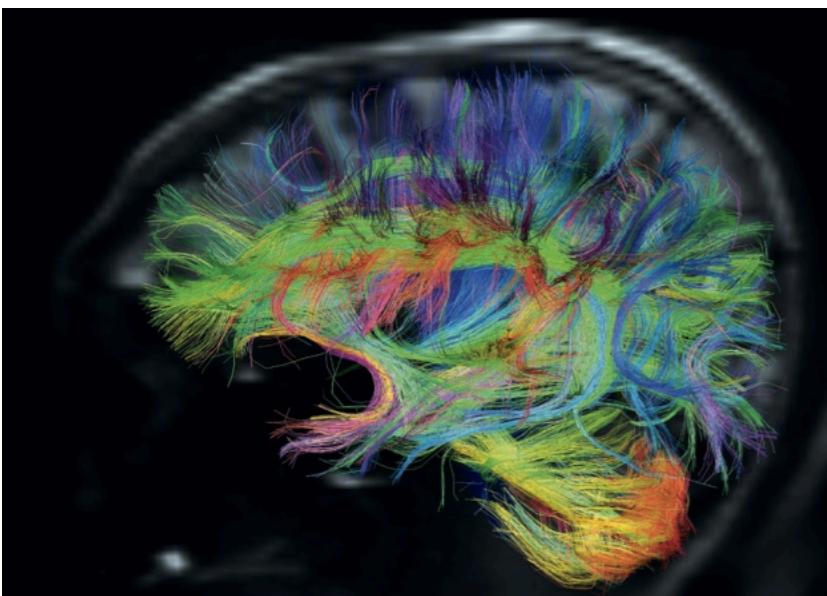
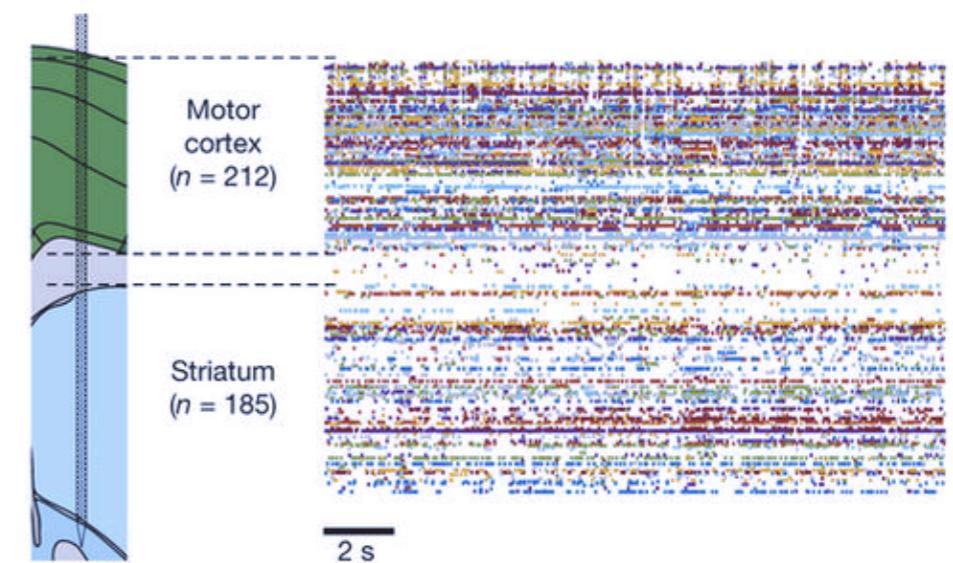
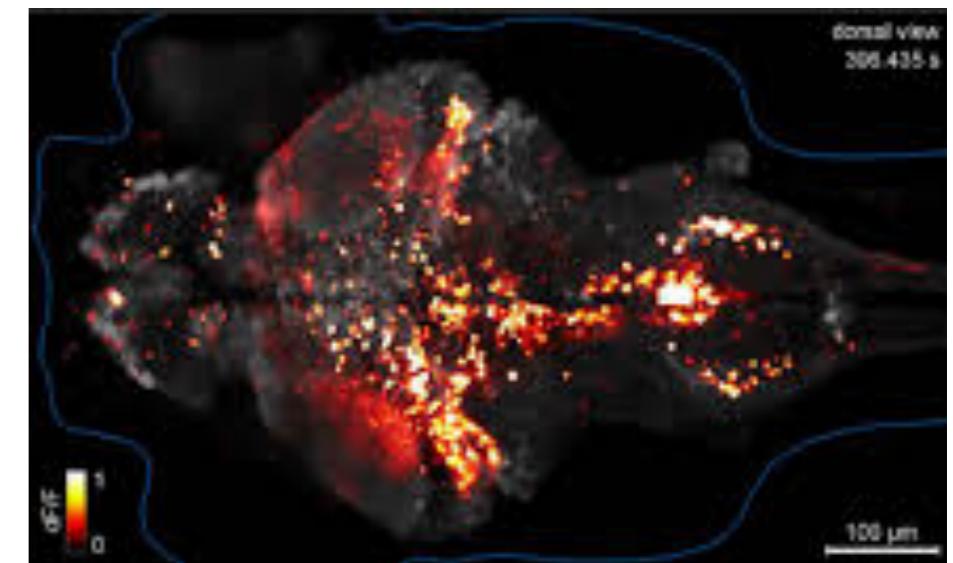
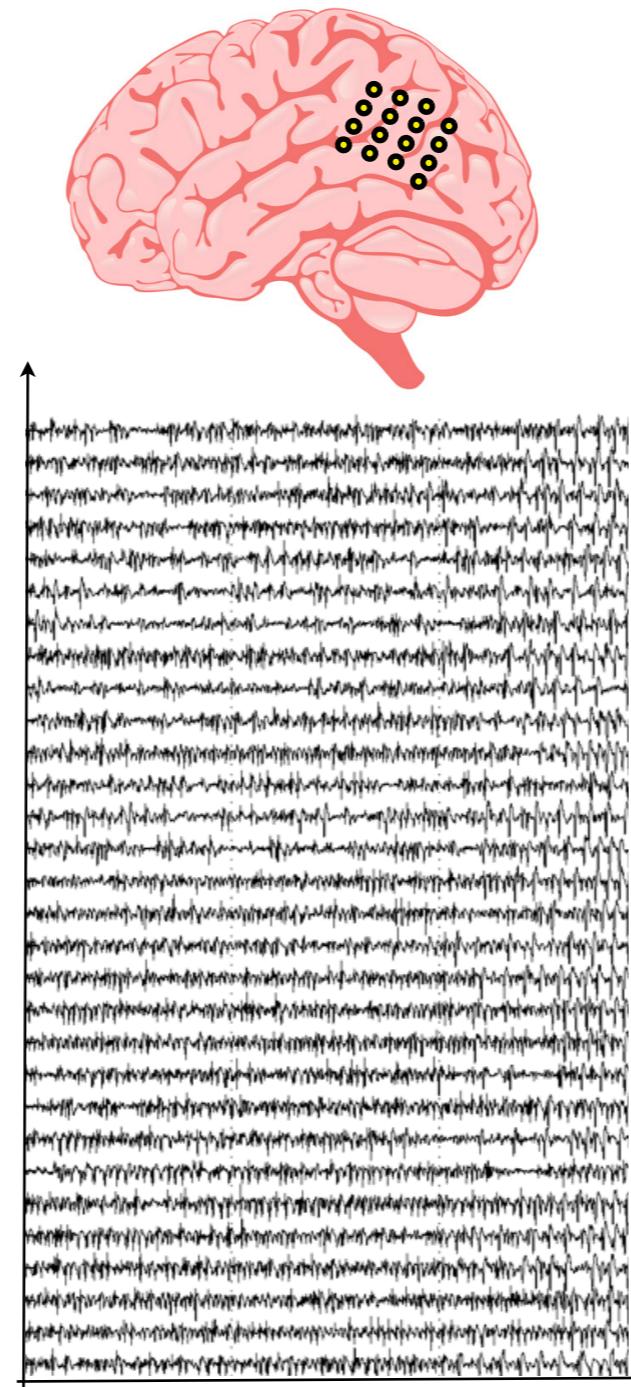
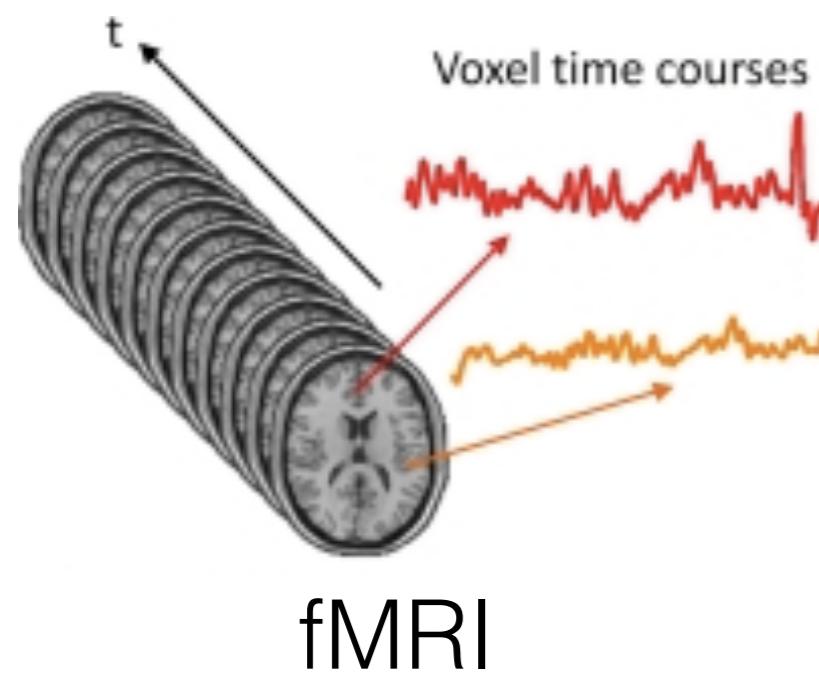
# Finding **low-dimensional** structure in **high-dimensional** datasets

Eva Dyer

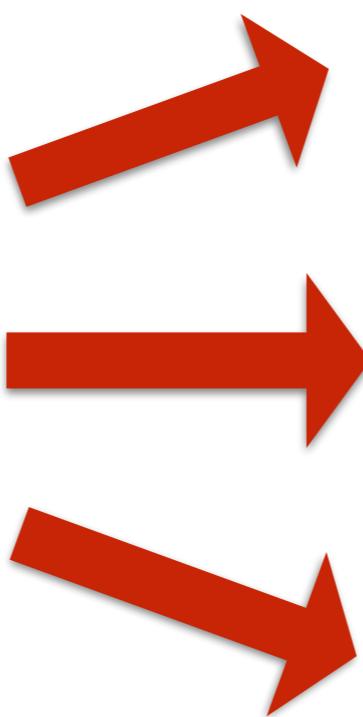
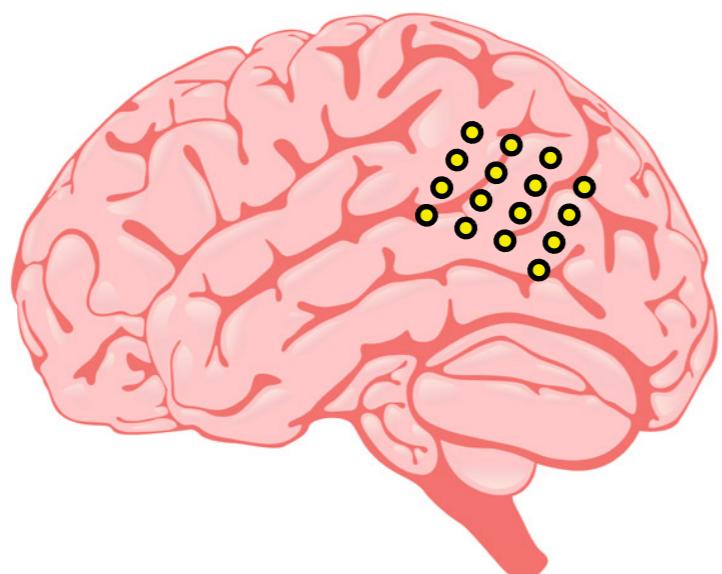
Department of Biomedical Engineering  
Georgia Institute of Technology //  
Emory University



# neural data deluge



# why reduce dimensionality?

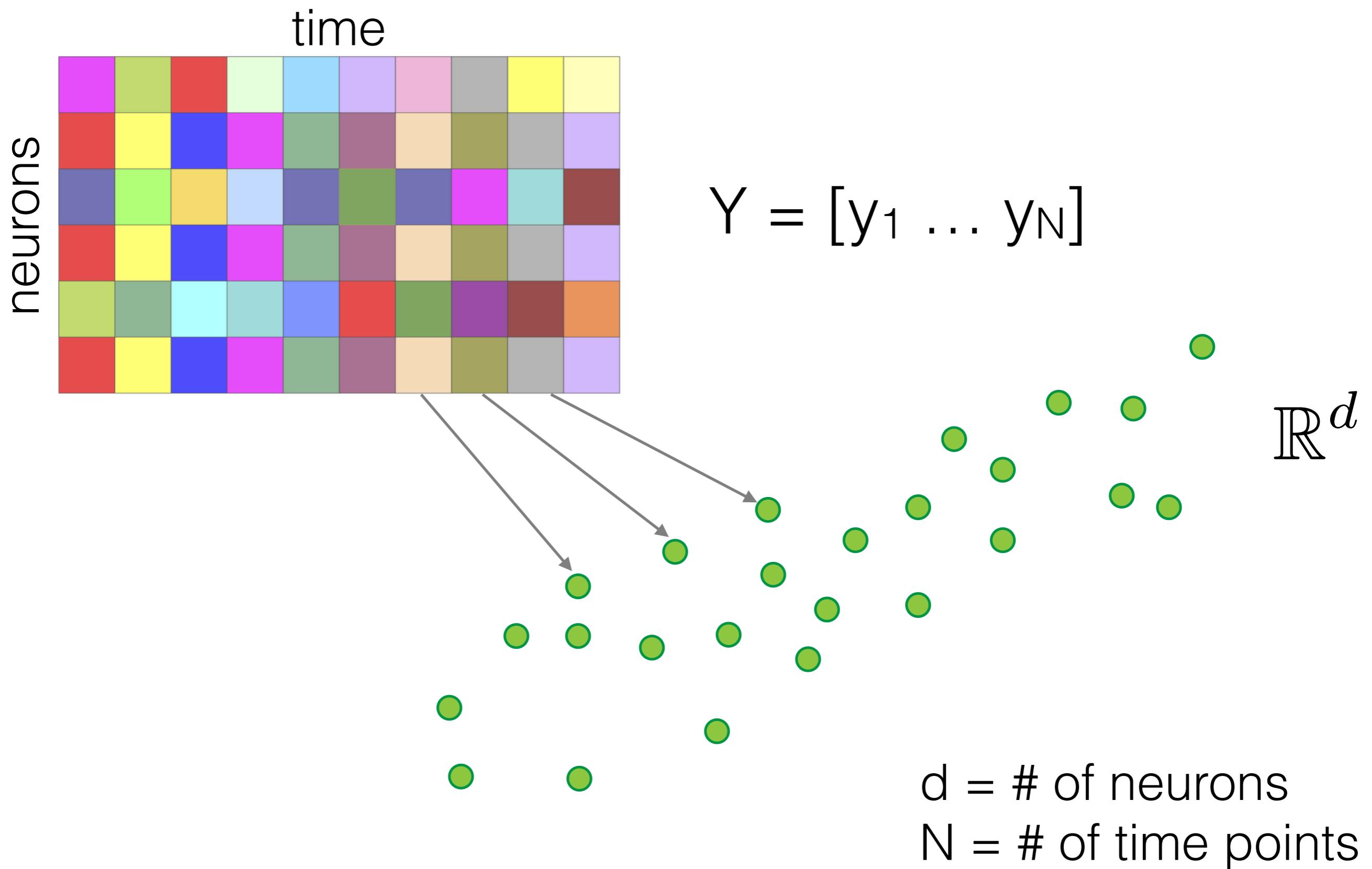


compression

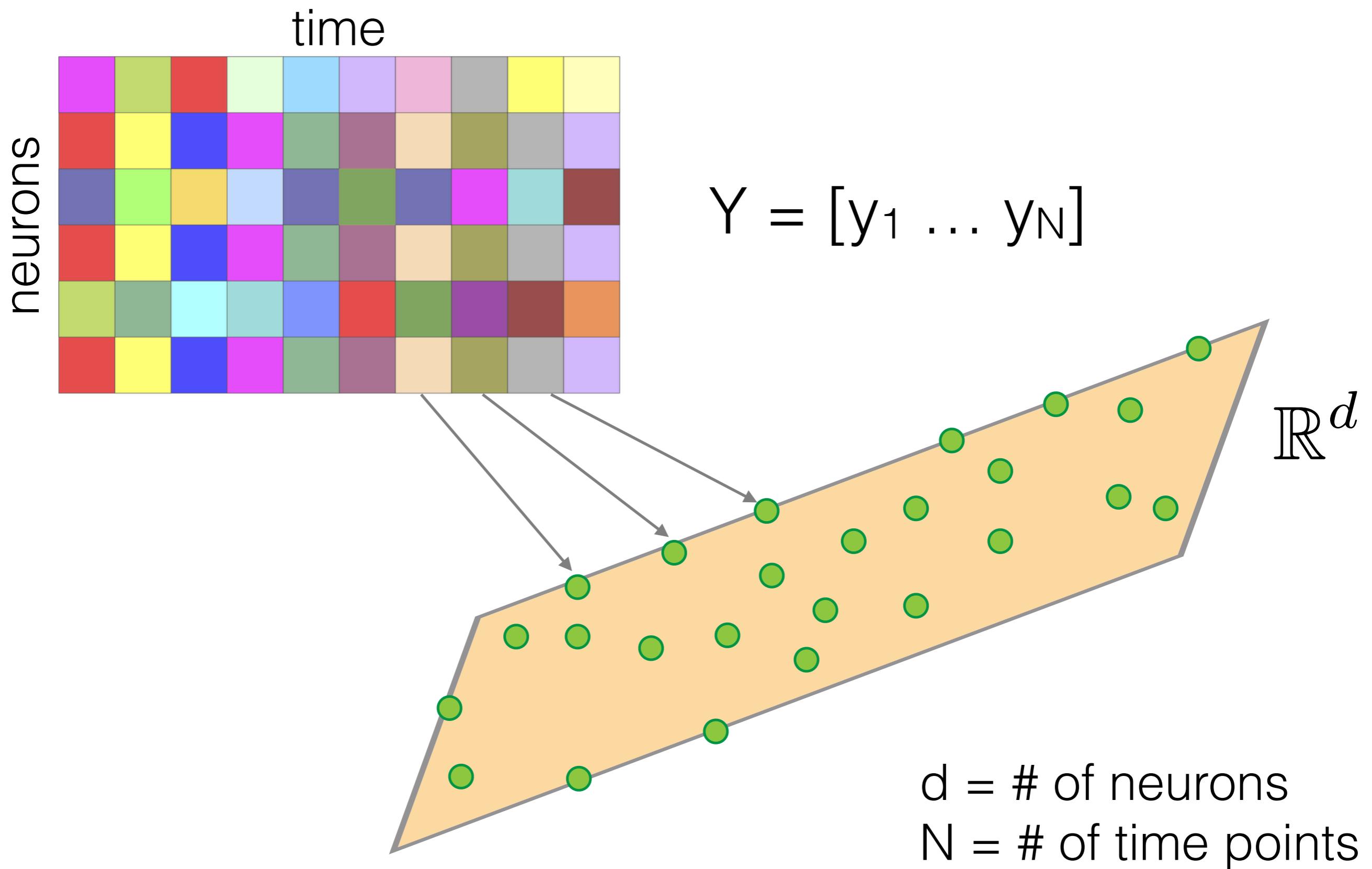
denoising

interpret complex data

# low-dimensional models

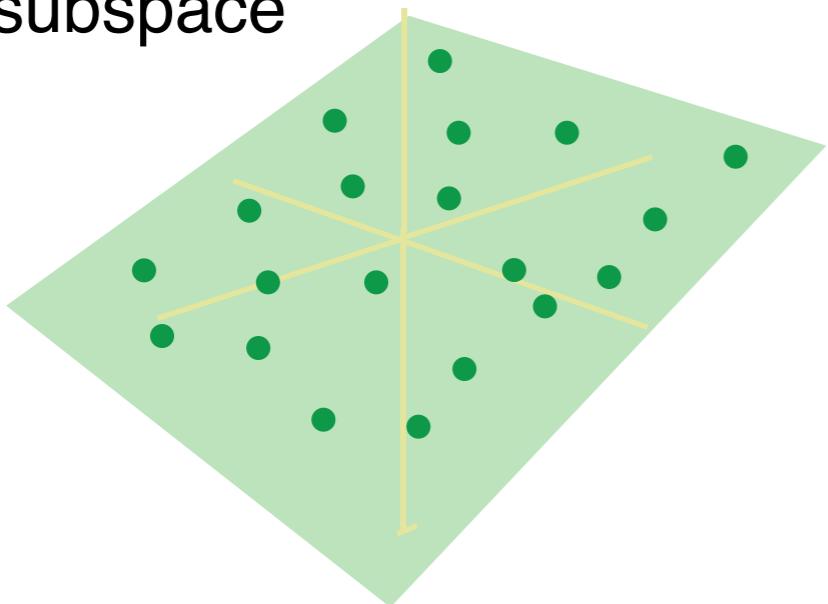


# low-dimensional models



# low rank model

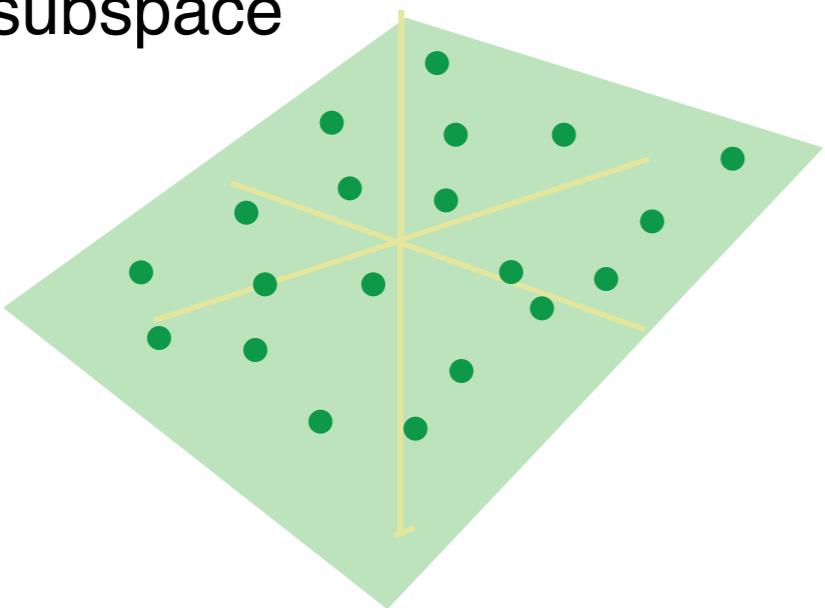
linear subspace  
PCA



**what is the objective underlying PCA?**

# low rank model

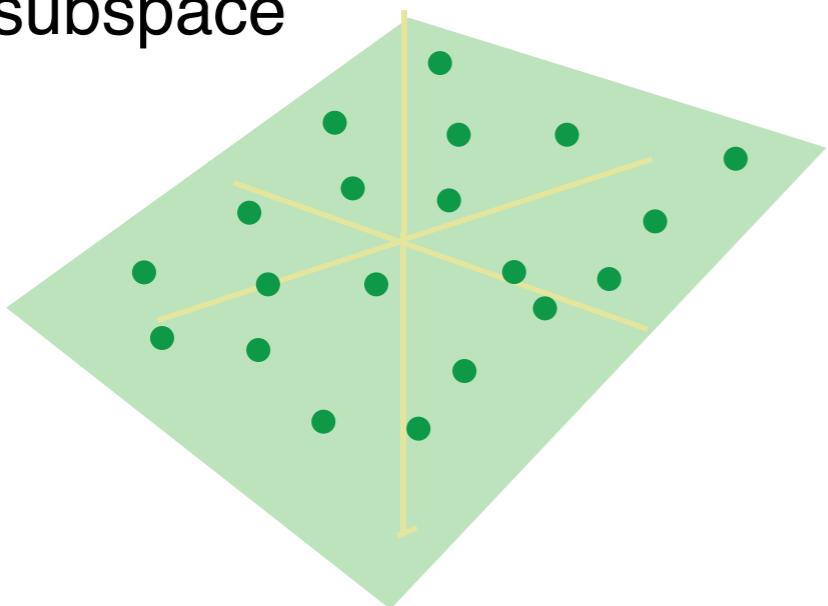
linear subspace  
PCA



$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$

# low rank model

linear subspace  
PCA



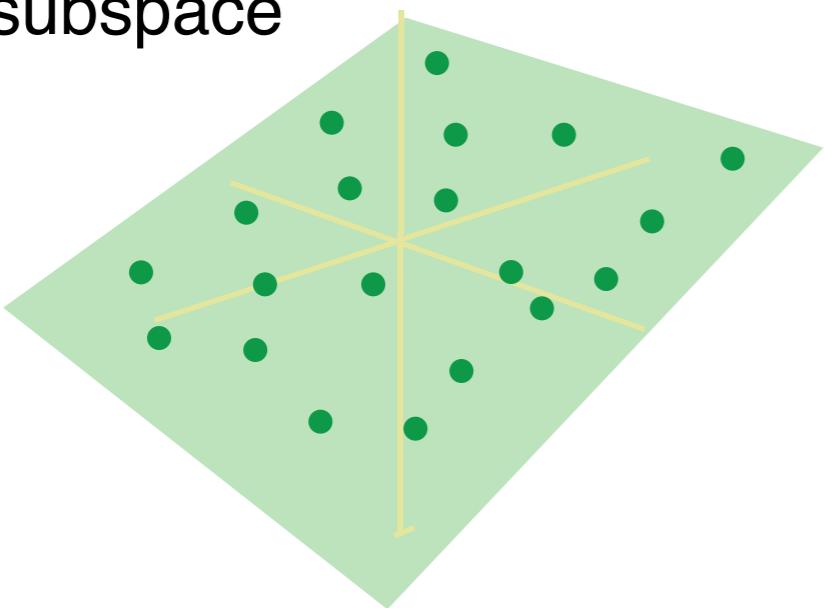
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



data matrix

# low rank model

linear subspace  
PCA



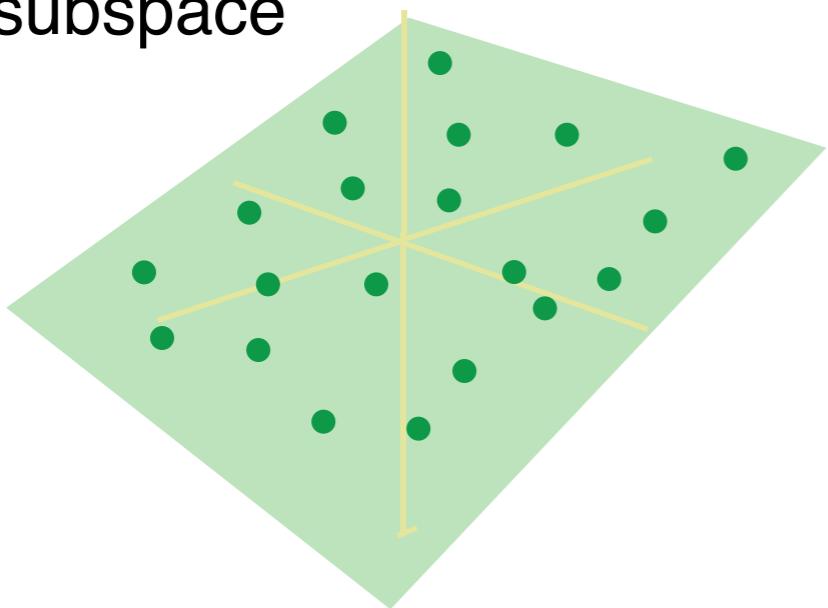
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



“low rank” approximation

# low rank model

linear subspace  
PCA



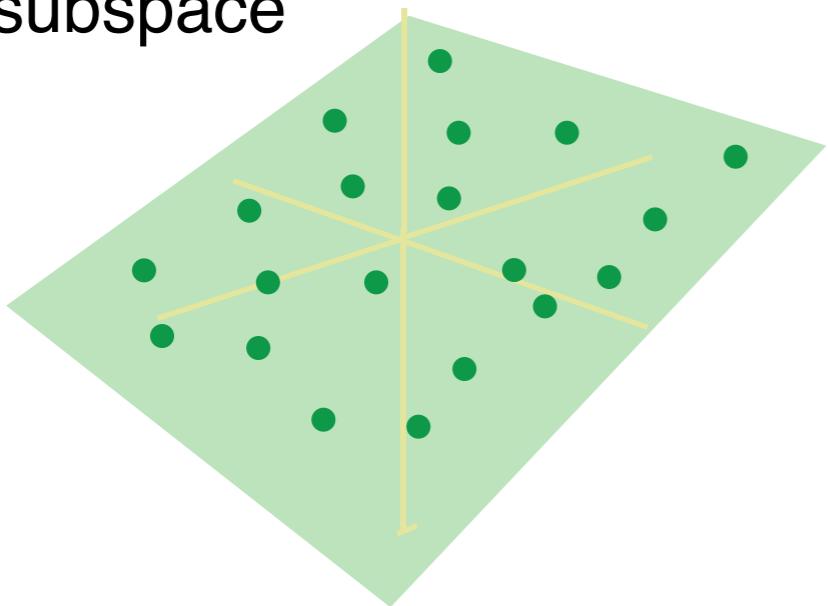
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



subject to == constraints

# low rank model

linear subspace  
PCA

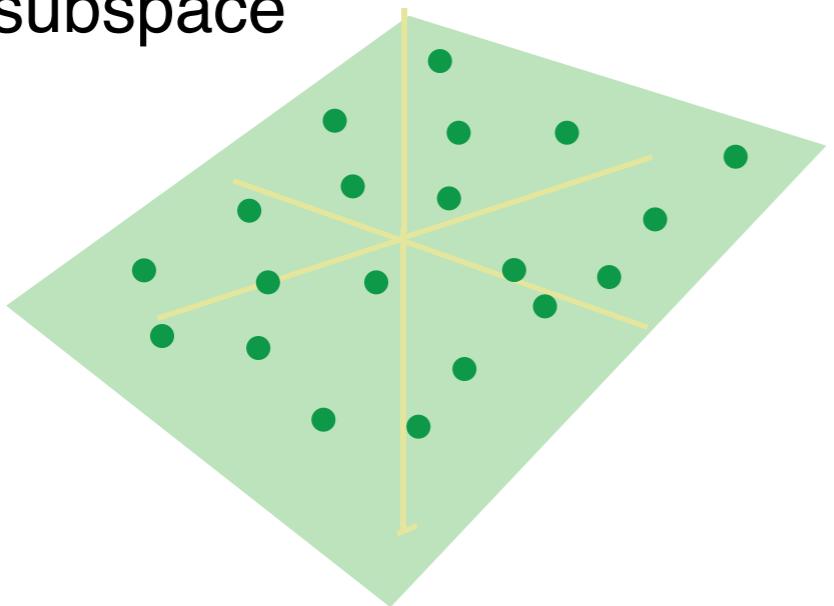


$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$

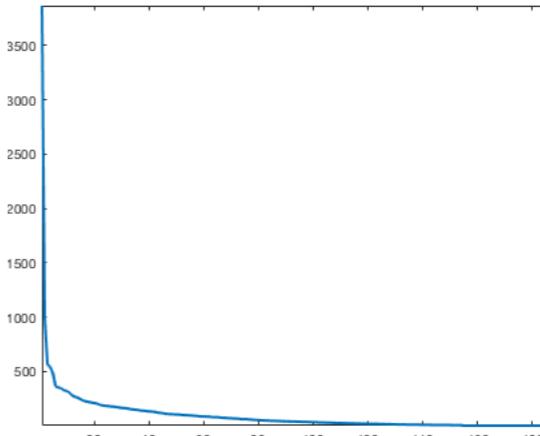
**rank(A) = ?**

# low rank model

linear subspace  
PCA



$$[U, S, V] = \text{svd}(Y)$$



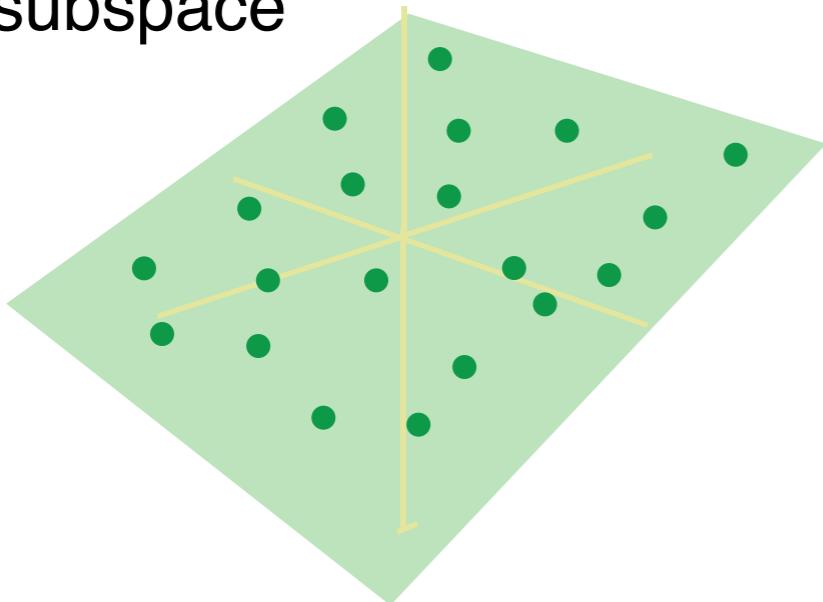
$$\min_{\mathbf{A}} \|\mathbf{Y} - \mathbf{A}\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}) \leq k$$



$$\mathbf{A} = \mathbf{U}_k \mathbf{S}_k \mathbf{V}_k^T \quad (\text{truncated SVD})$$

# low rank model

linear subspace  
PCA



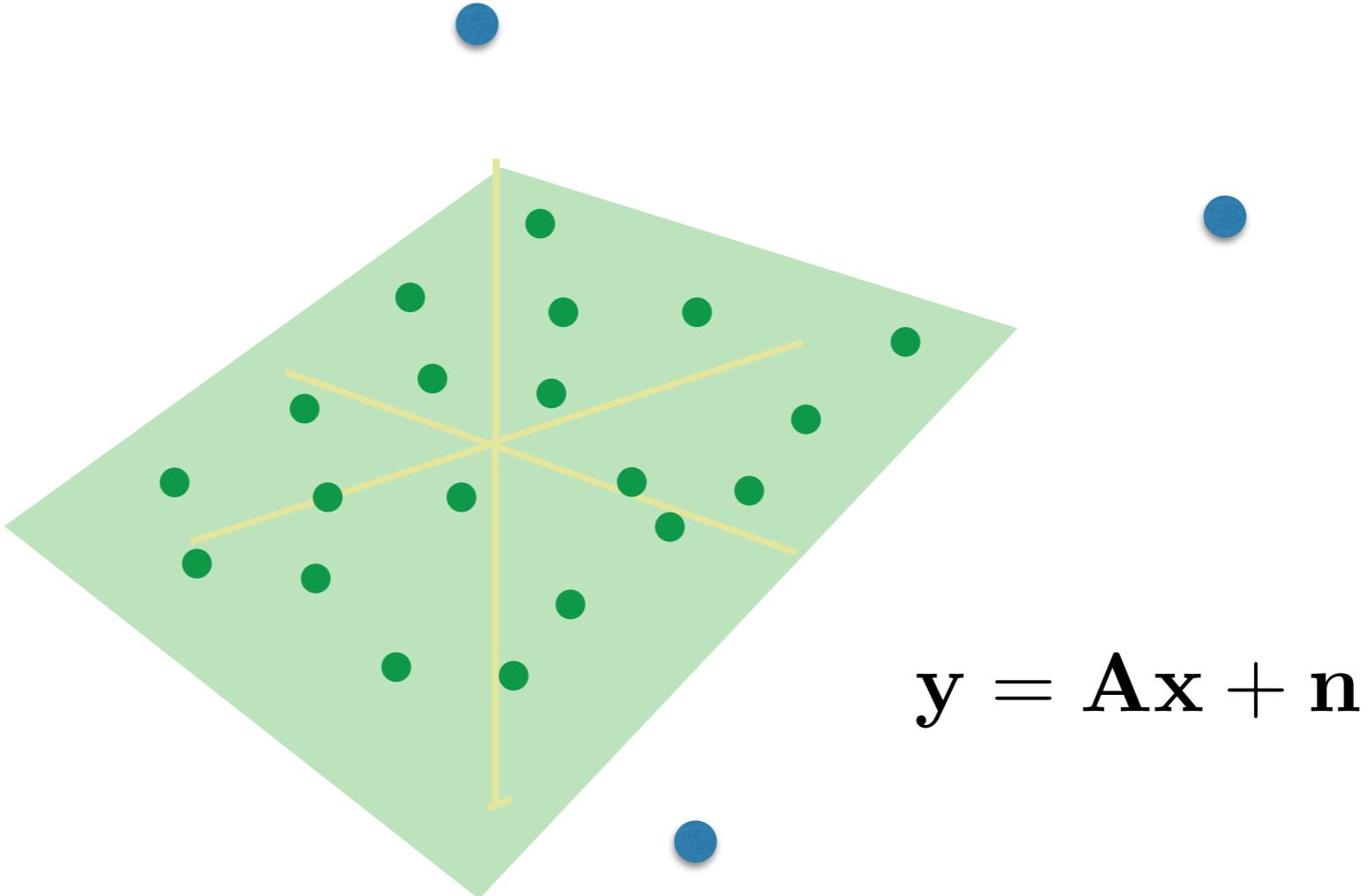
## Covariance matrix

$$C = (\mathbf{Y} - \bar{\mathbf{y}})^T (\mathbf{Y} - \bar{\mathbf{y}})^T$$

### PCA:

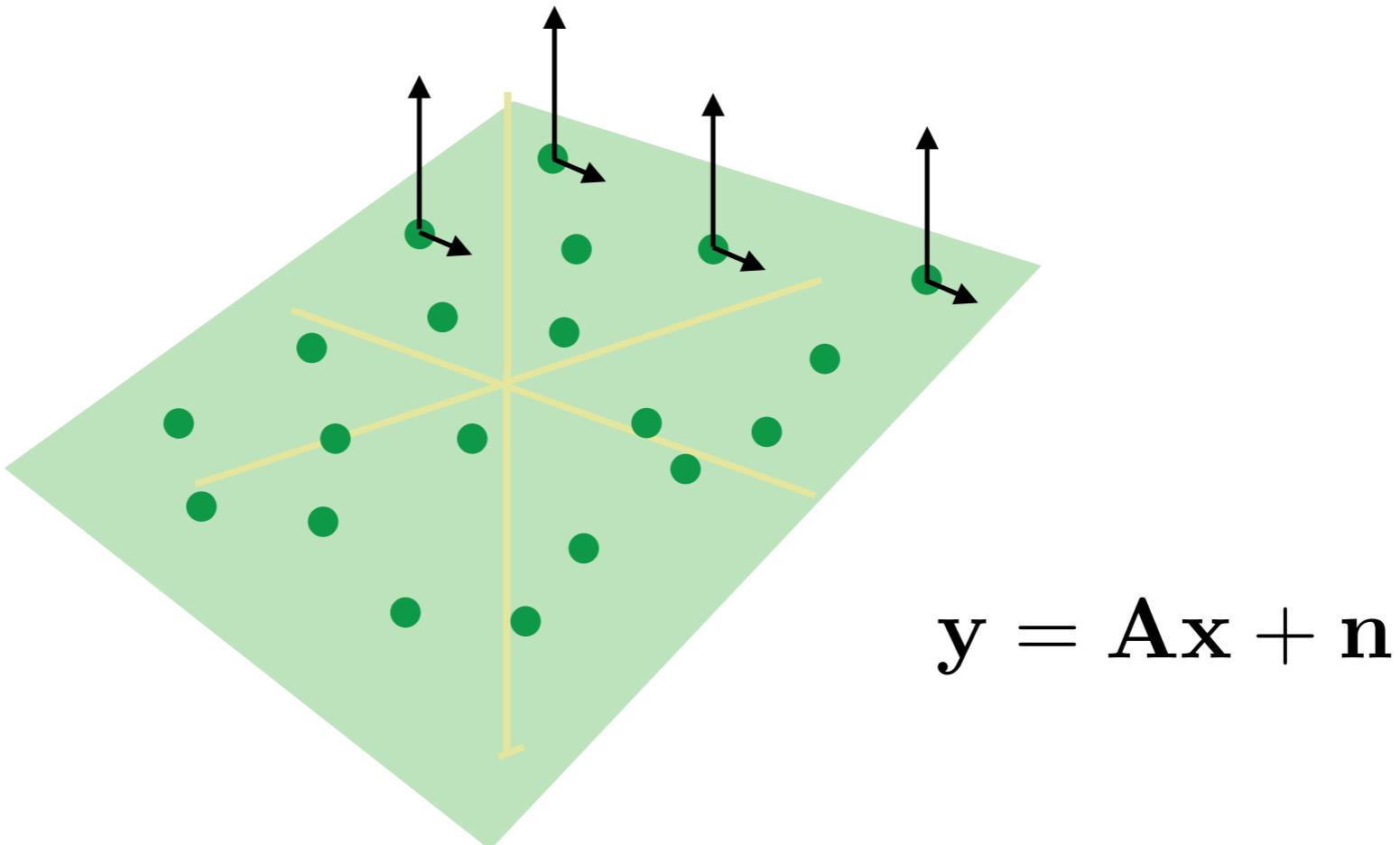
1. Compute the covariance matrix ( $C$ )
2. Compute eigenvalue decomposition of  $C$
3. Output > top  $k$  eigenvectors and their eigenvalues

# extensions of PCA



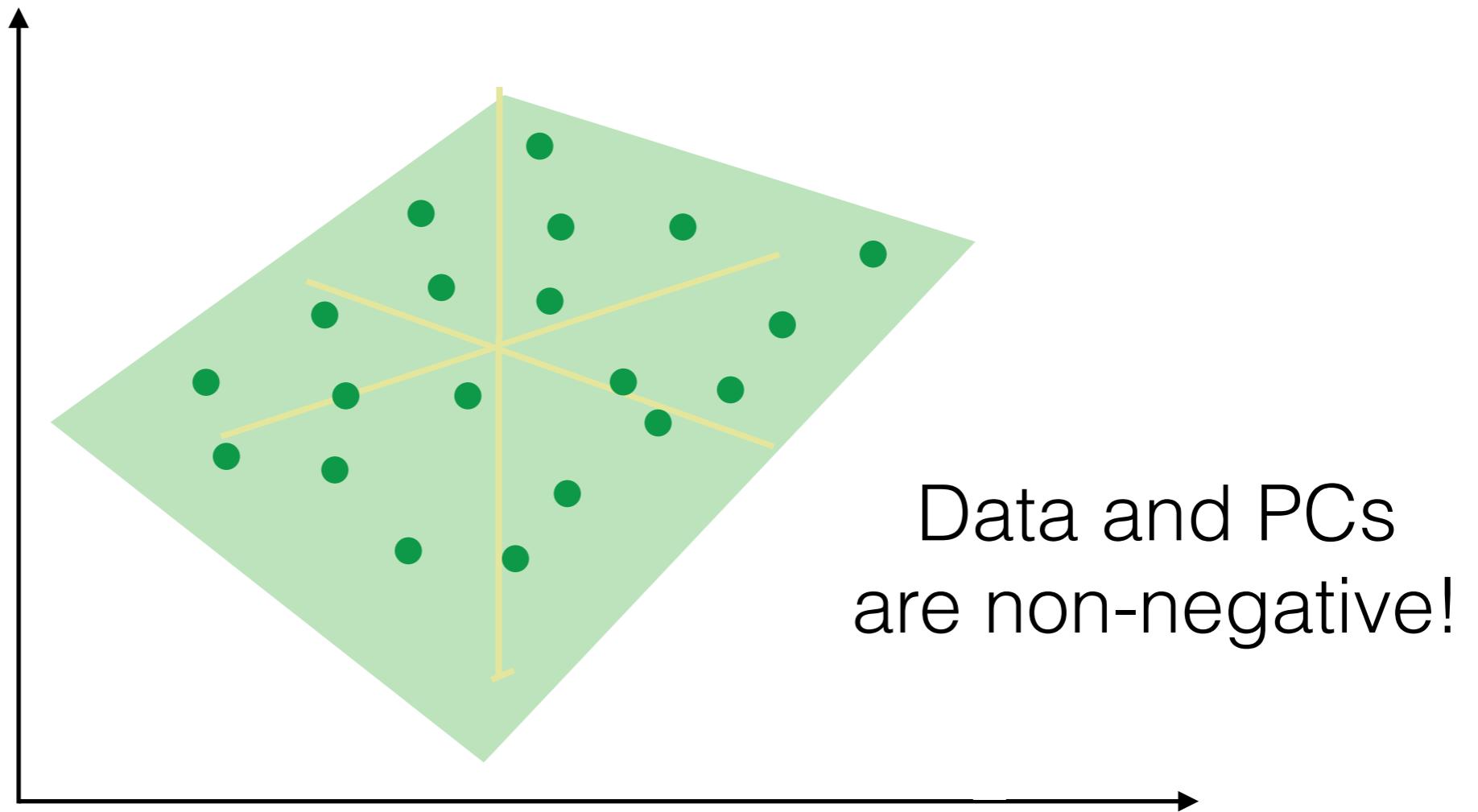
1. **Robust PCA - sparse LARGE errors**
2. Factor analysis (FA) - noise of unequal variance
3. Non-negative matrix factorization (NMF)

# extensions of PCA



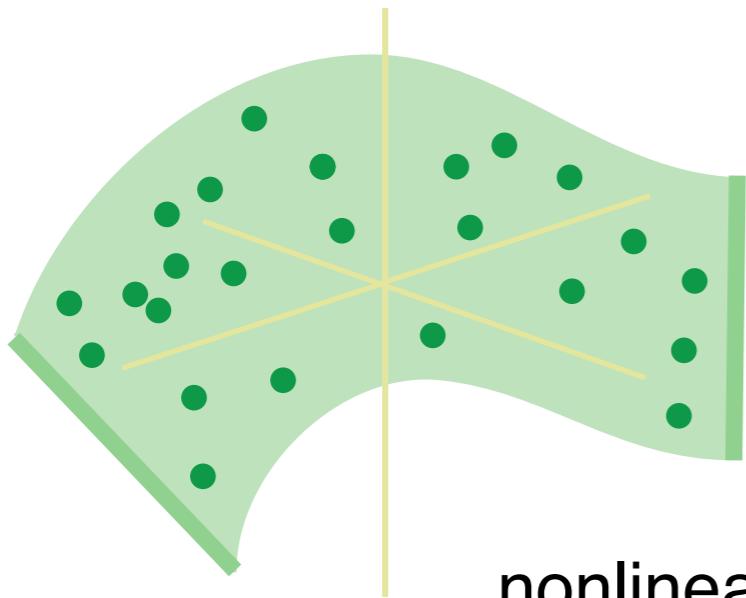
1. Robust PCA - sparse errors
2. **Factor analysis (FA) - noise of unequal variance**
3. Non-negative matrix factorization (NMF)

# extensions of PCA



1. Robust PCA - sparse errors
2. Factor analysis (FA) - noise of unequal variance
- 3. Non-negative matrix factorization (NMF)**

# nonlinear models (manifolds)



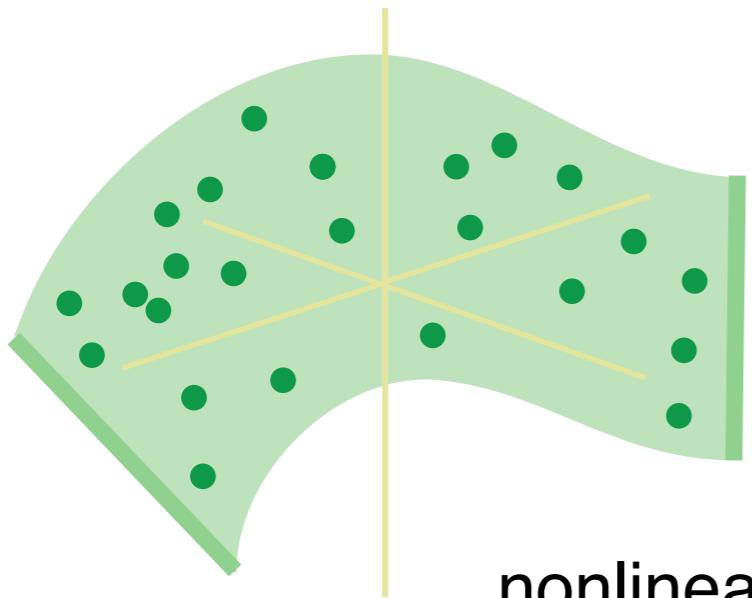
nonlinear manifold  
*Isomap, LLE*

$$\min_{\mathcal{P}} |d(y_i, y_j) - d(\mathcal{P}y_i, \mathcal{P}y_j)|$$



distance between original data points

# nonlinear models (manifolds)



nonlinear manifold  
*Isomap, LLE*

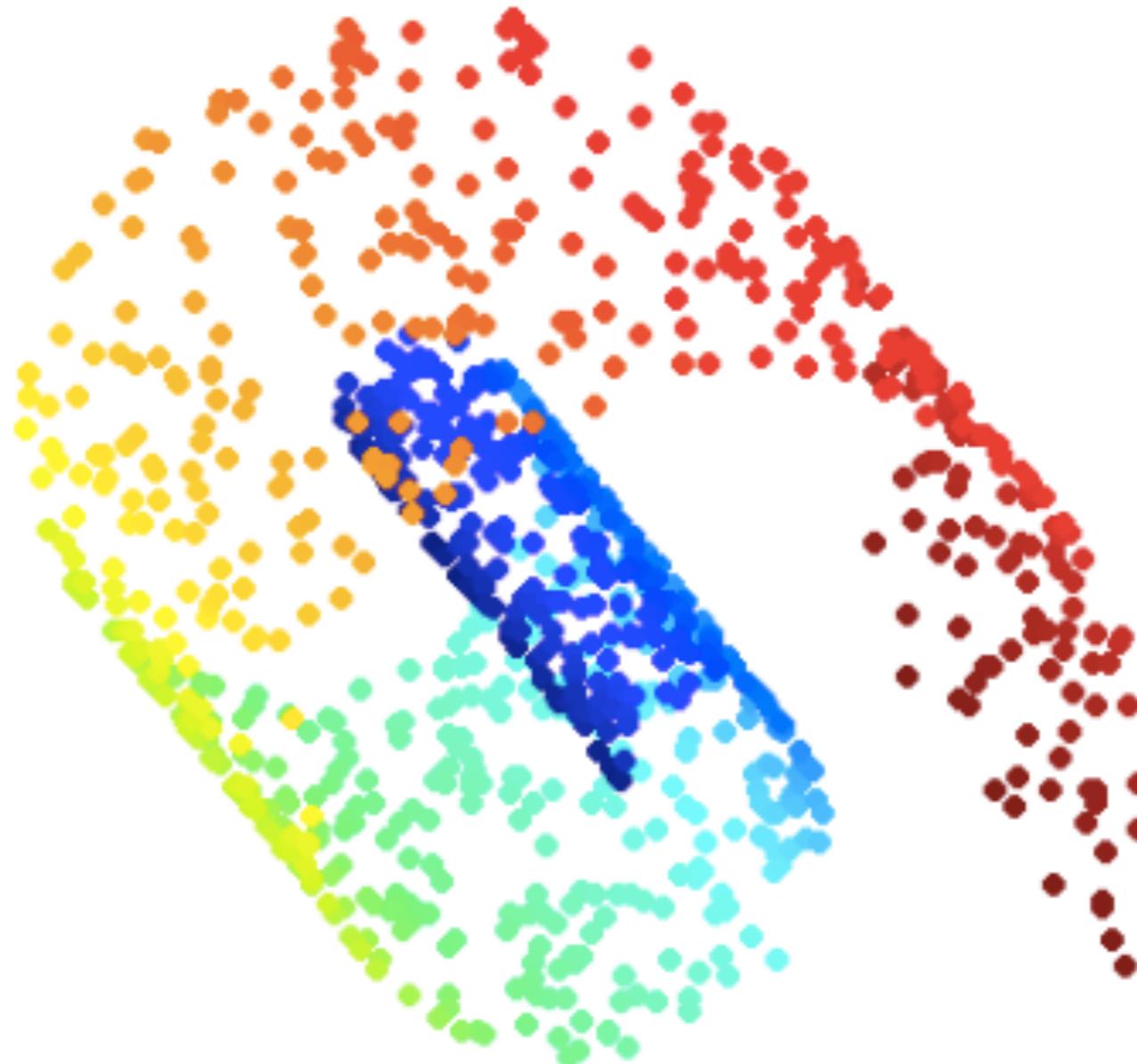
$$\min_{\mathcal{P}} |d(y_i, y_j) - d(\mathcal{P}y_i, \mathcal{P}y_j)|$$



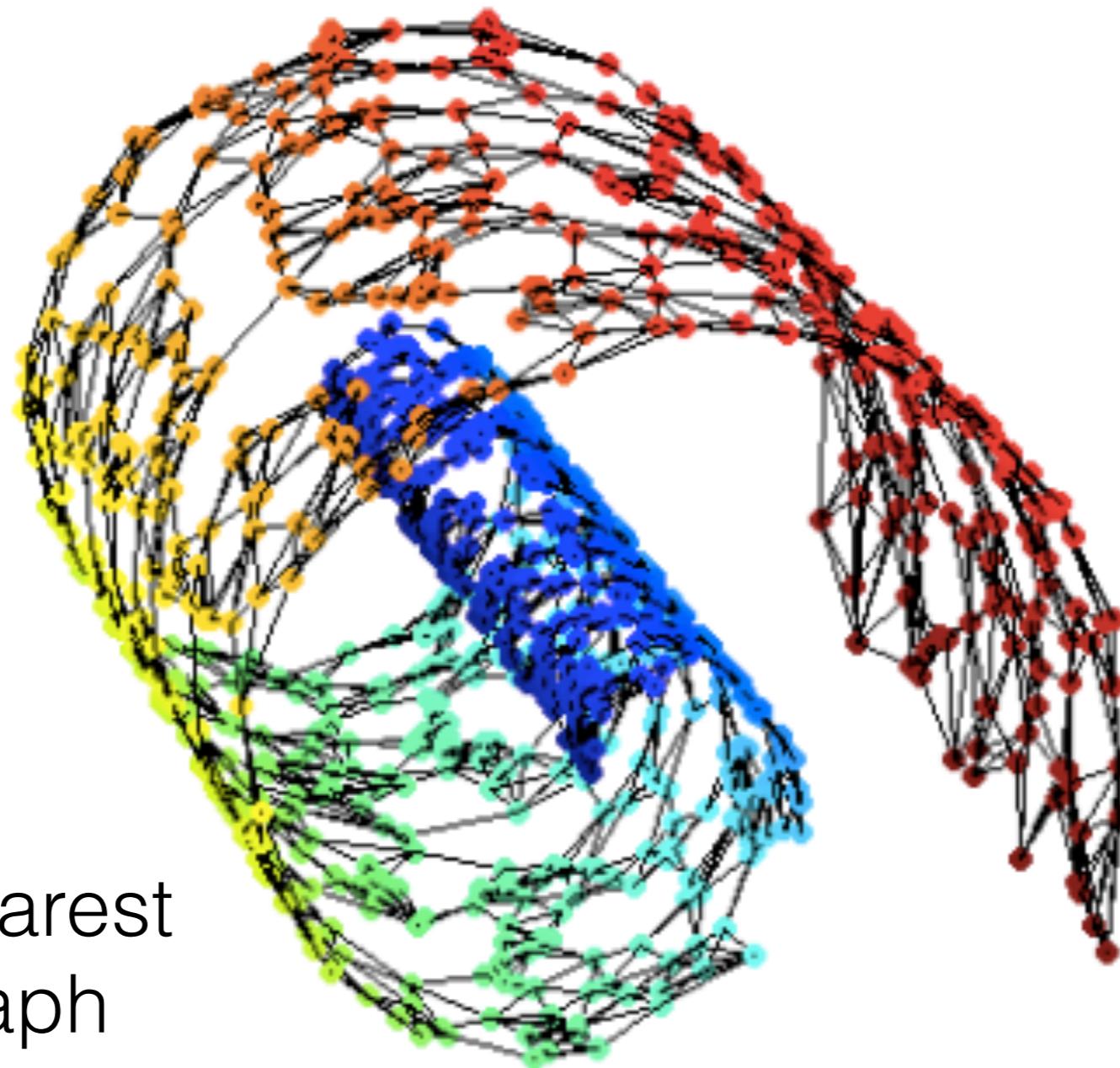
distance between projected data points

# nonlinear models (manifolds)

swiss roll

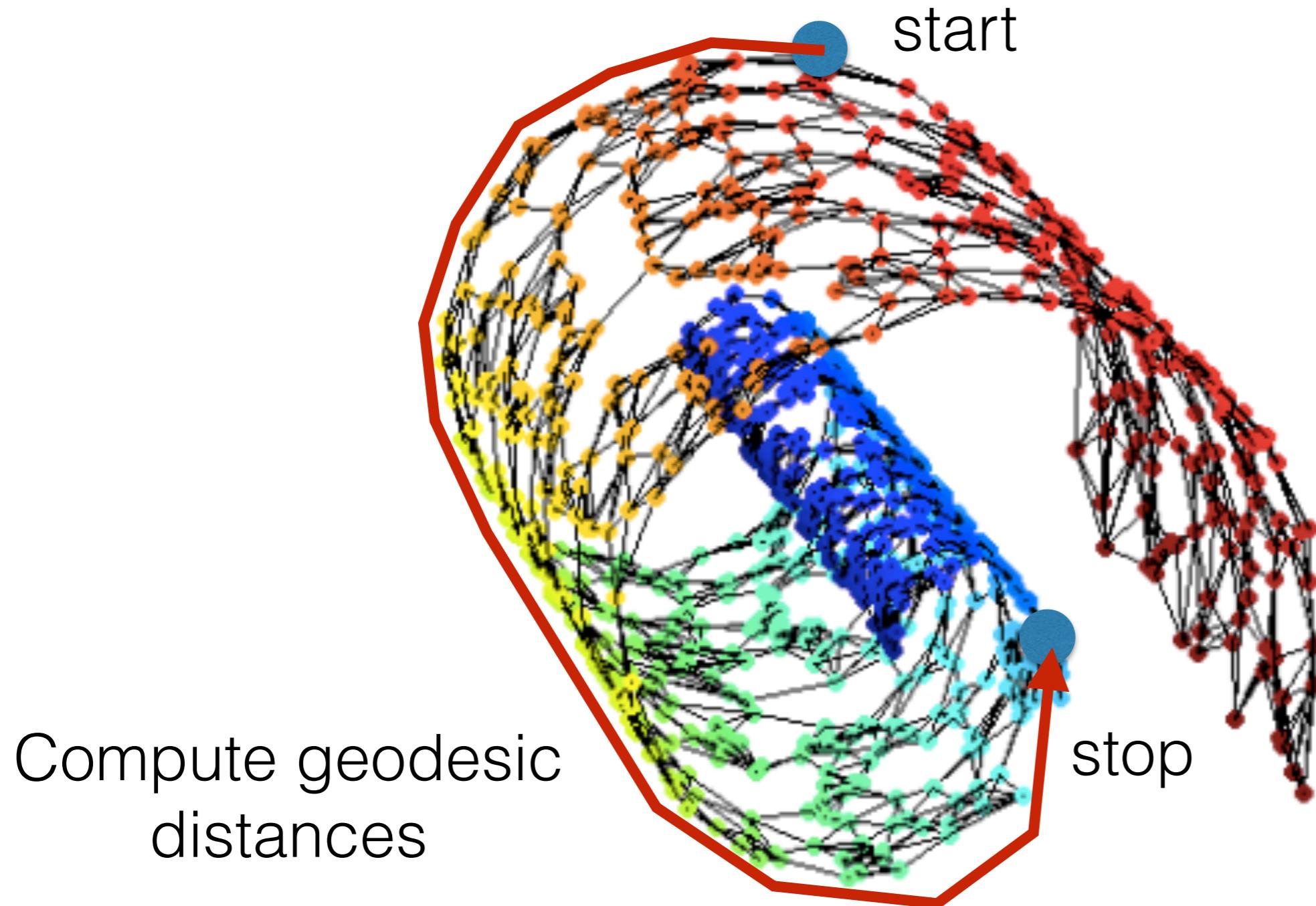


# nonlinear models (manifolds)

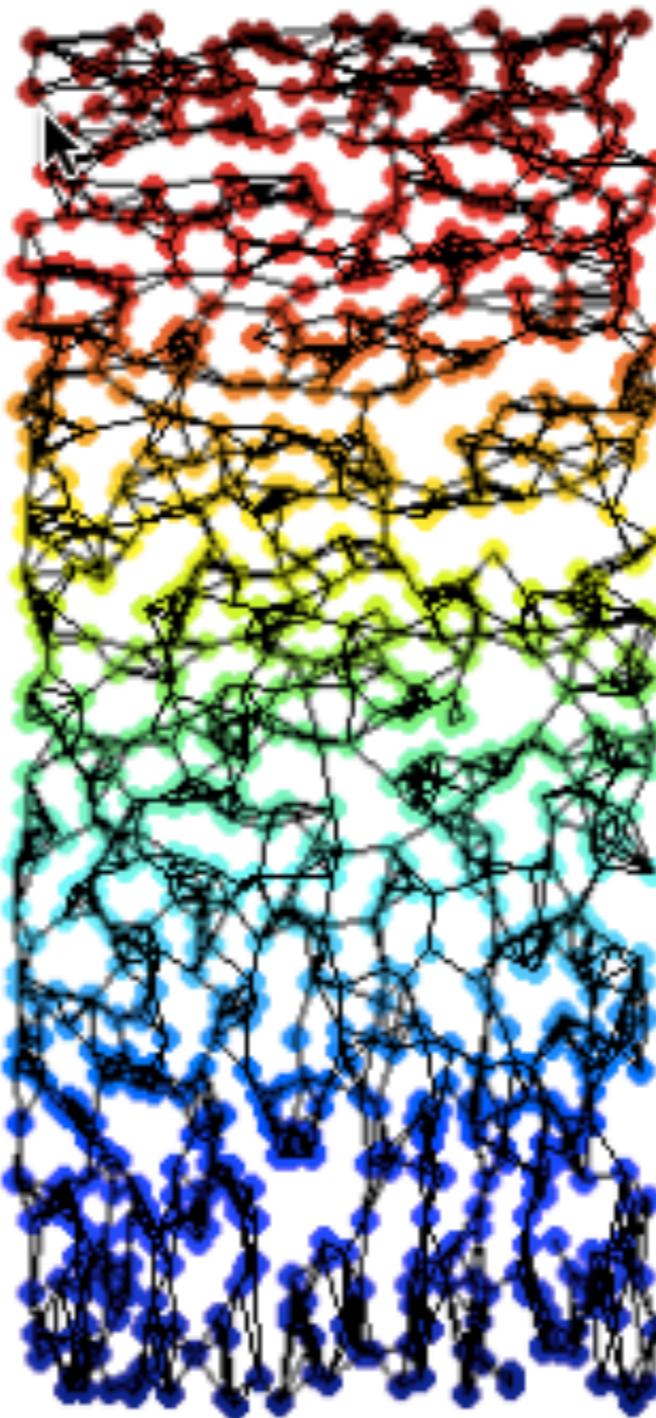


Compute k-nearest  
neighbor graph

# nonlinear models (manifolds)

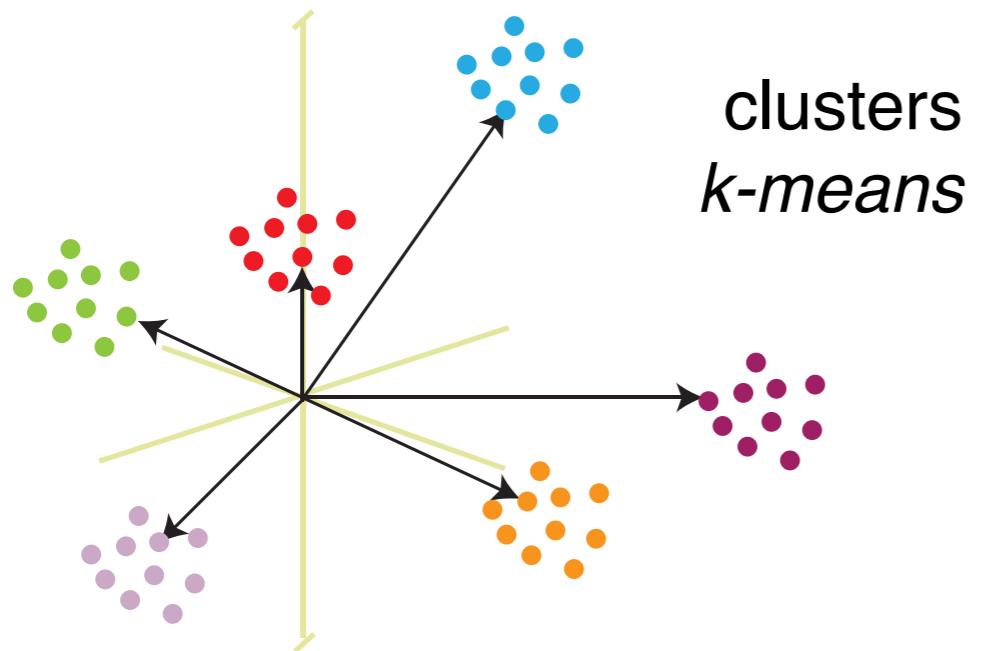


# nonlinear models (manifolds)



Compute leading  
eigenvectors

# cluster model

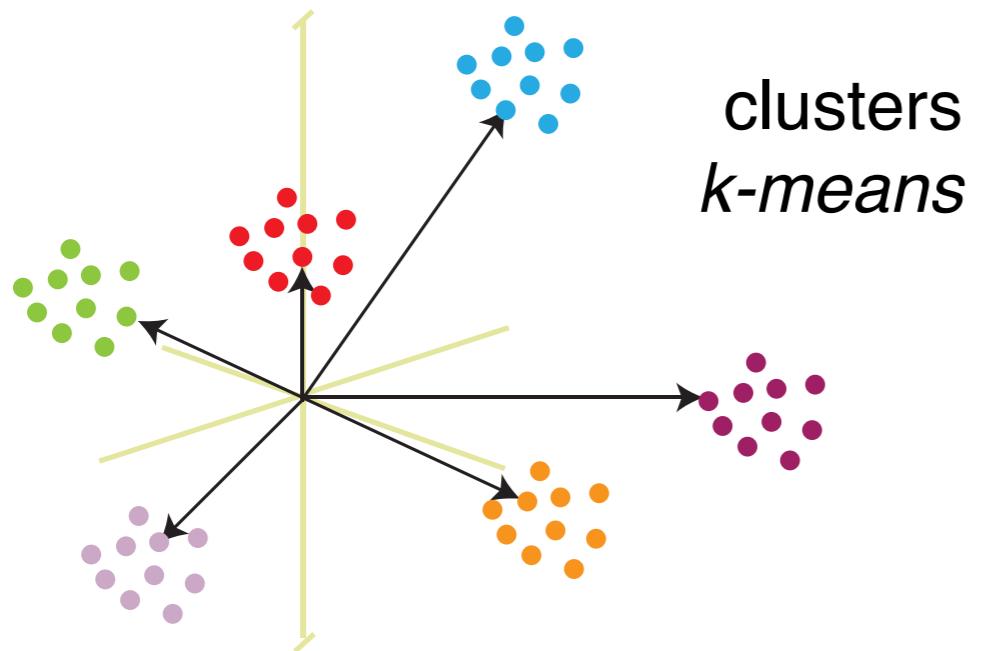


clusters  
*k-means*

$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

ith data point

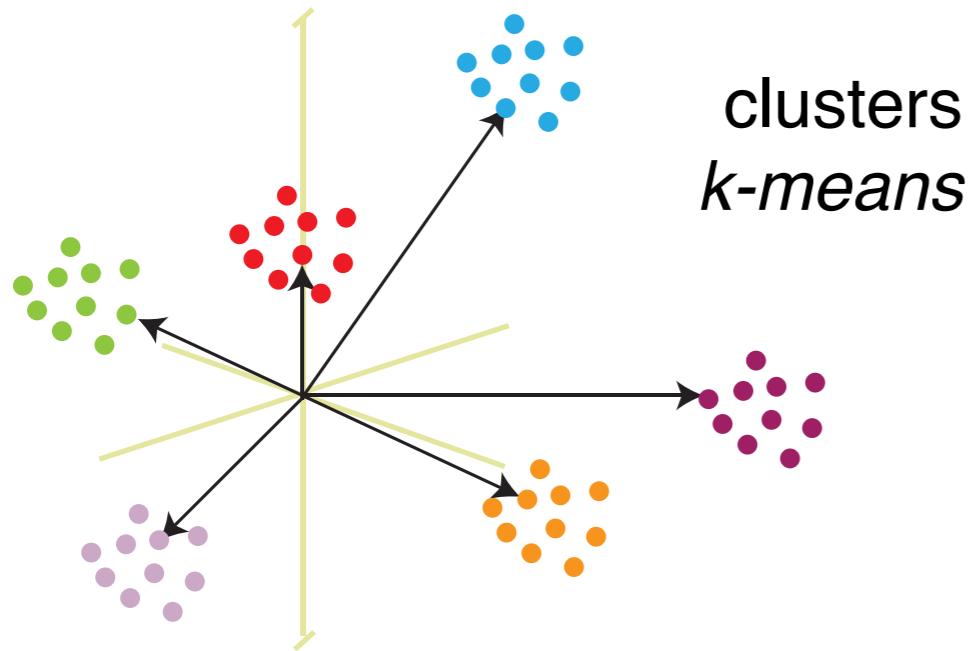
# cluster model



$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

↑  
jth cluster center

# cluster model

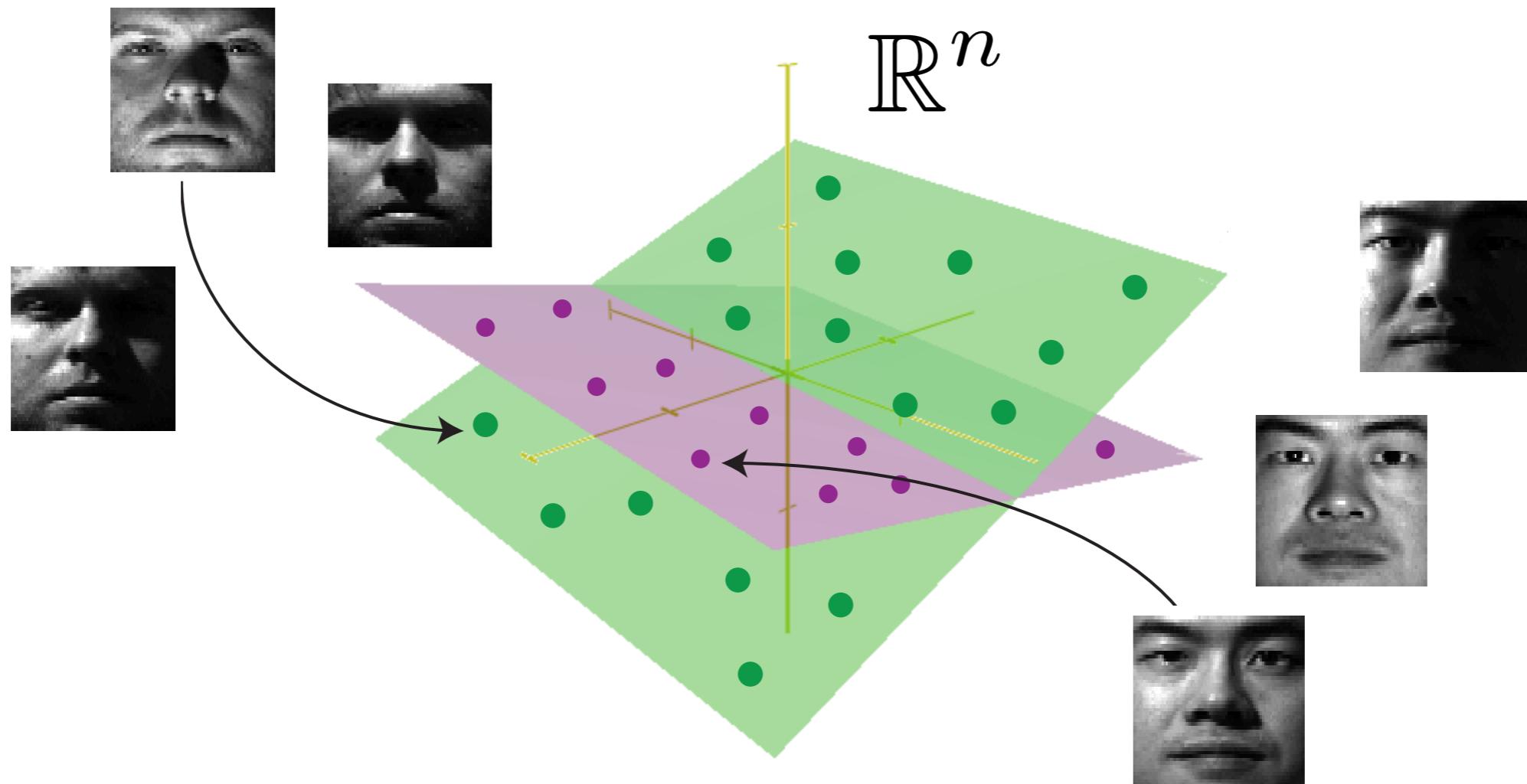


$$\min_{\mathbf{c}_1, \dots, \mathbf{c}_k} \sum_{j=1}^k \sum_{i \in \Omega_j} \|y_i - c_j\|_2$$

## kmeans:

1. Randomly initialize cluster centers
2. Assign each data point to its closest cluster center
3. Update cluster centers (mean of all assigned points)
4. Iterate steps 2-3 until convergence

# union of subspaces



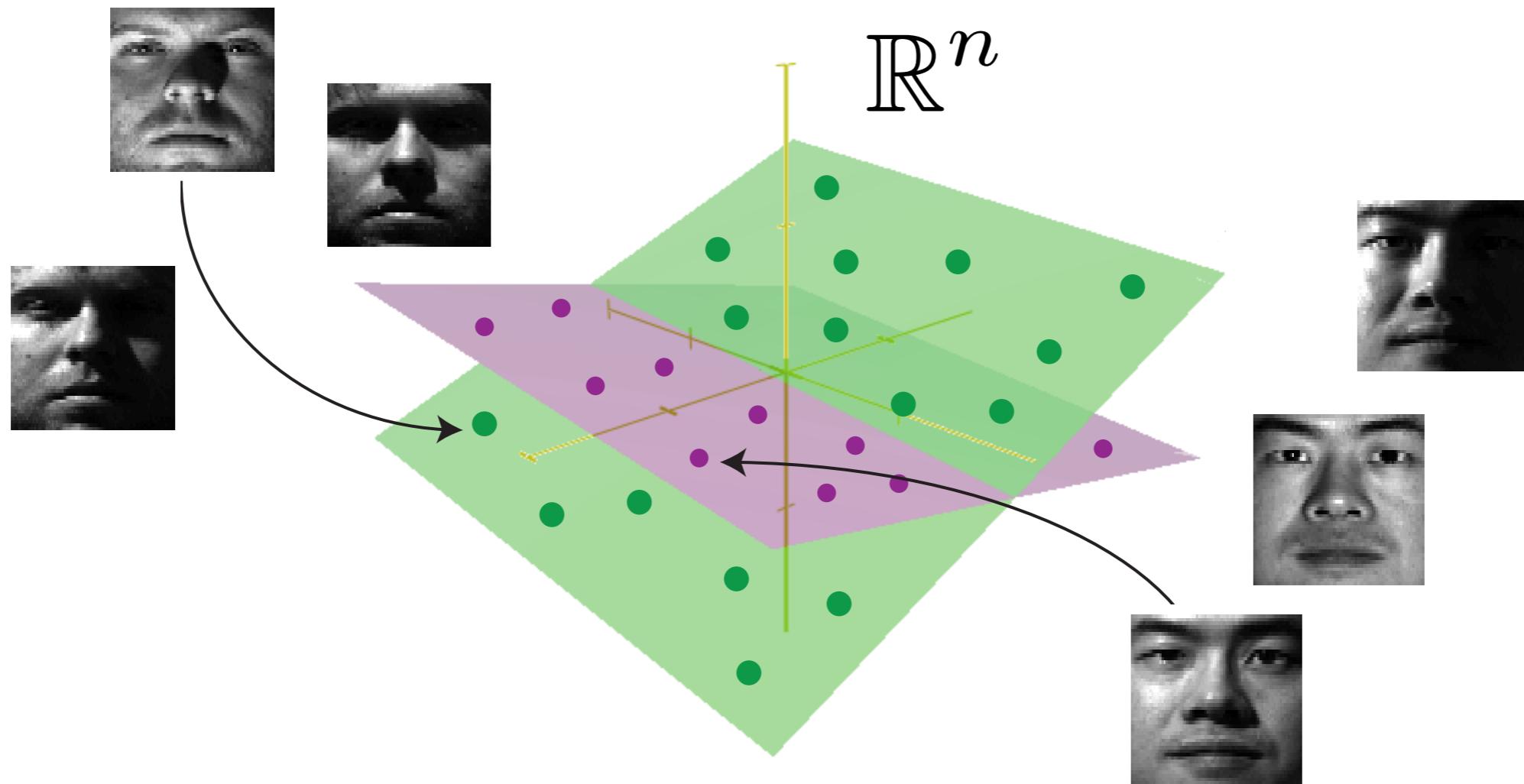
$$\min_{\mathbf{A}_i, \Omega_i} \sum \|\mathbf{Y}_{\Omega_i} - \mathbf{A}_i\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}_i) \leq k_i$$



subset of data in ith subspace

Elhamifar, 2012

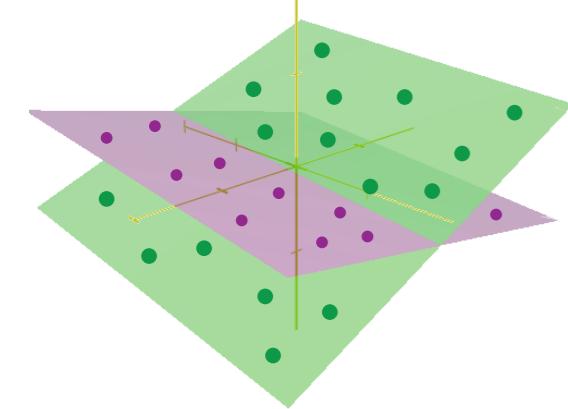
# union of subspaces



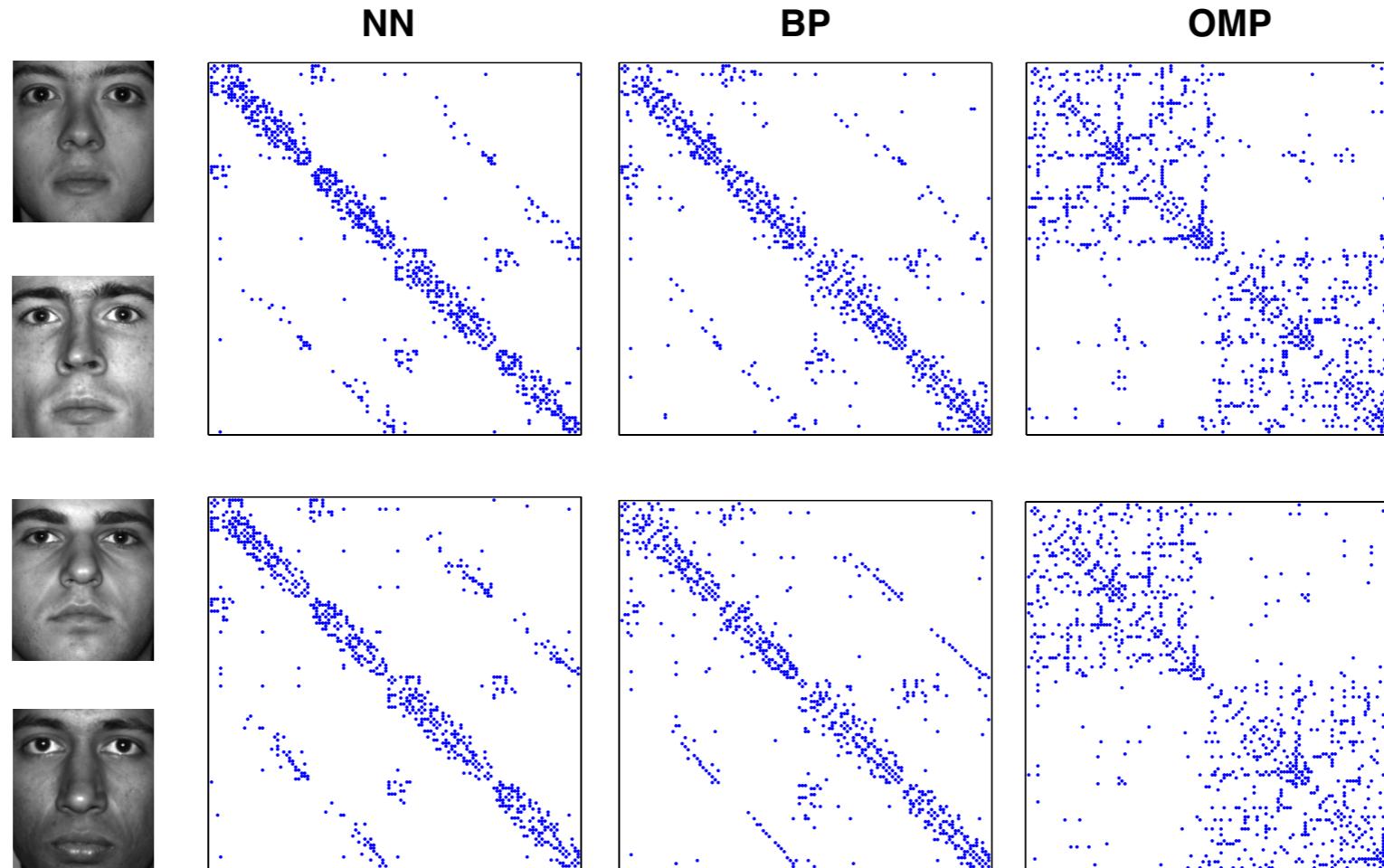
$$\min_{\mathbf{A}_i, \Omega_i} \sum \|\mathbf{Y}_{\Omega_i} - \mathbf{A}_i\|_F \quad \text{s.t.} \quad \text{rank}(\mathbf{A}_i) \leq k_i$$



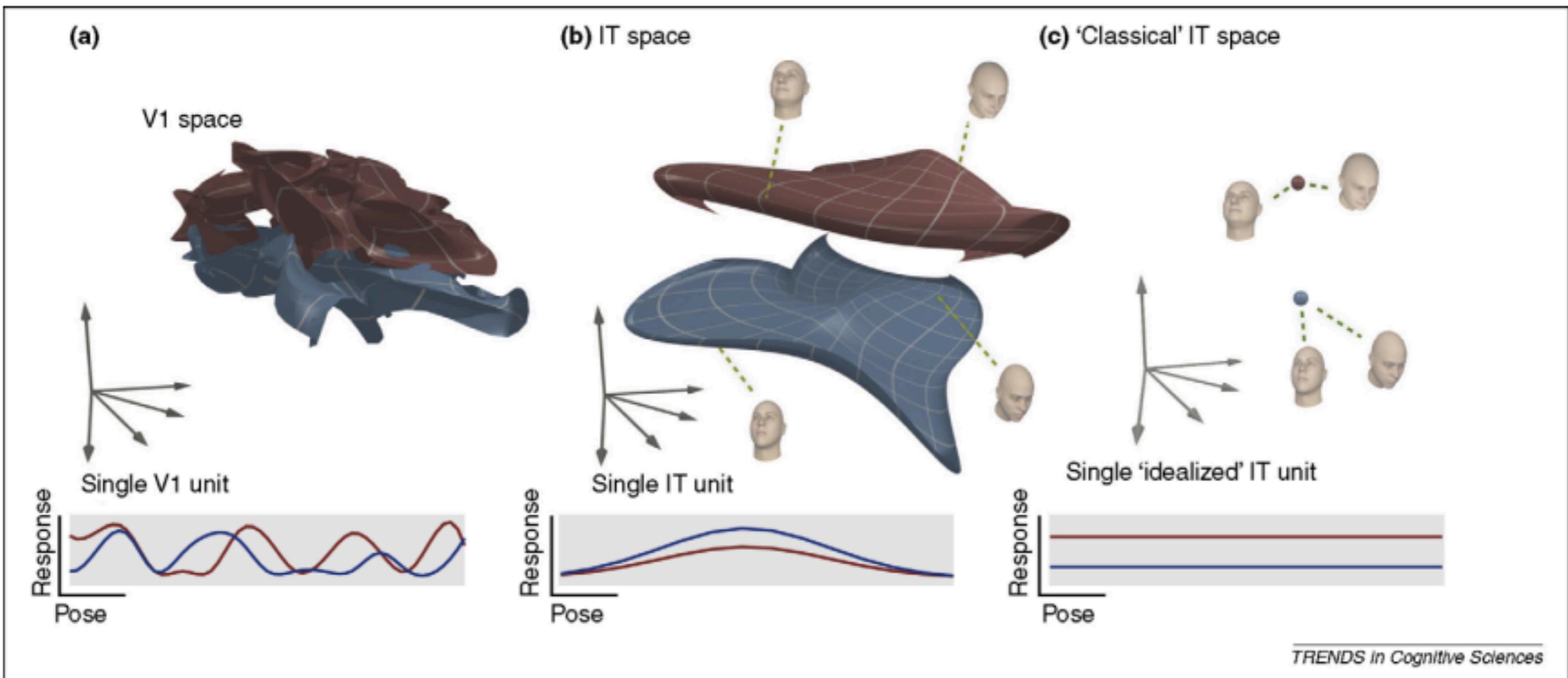
low rank approx of ith cluster



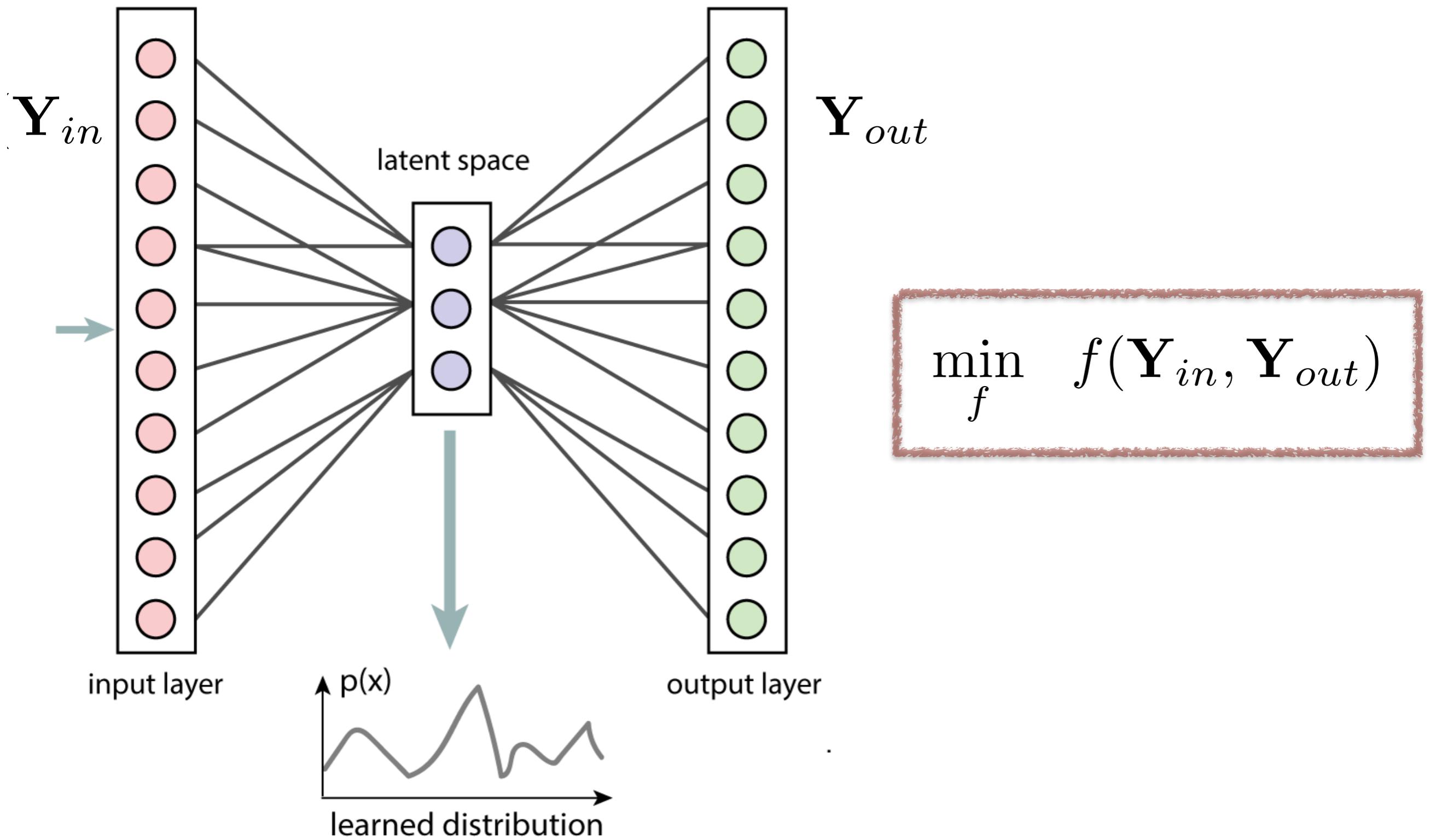
# union of subspaces



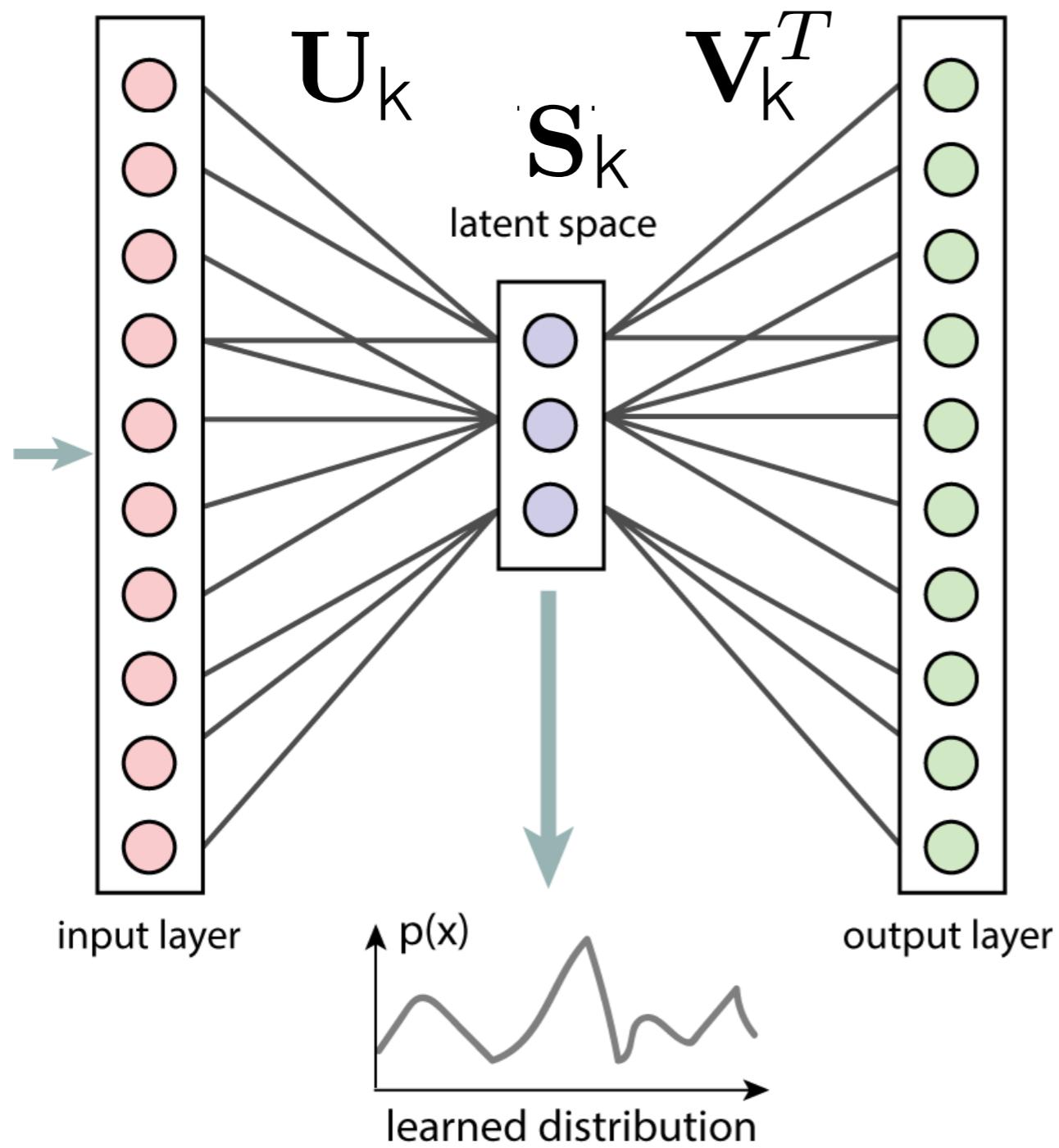
# “tangled” manifolds



# autoencoder architecture



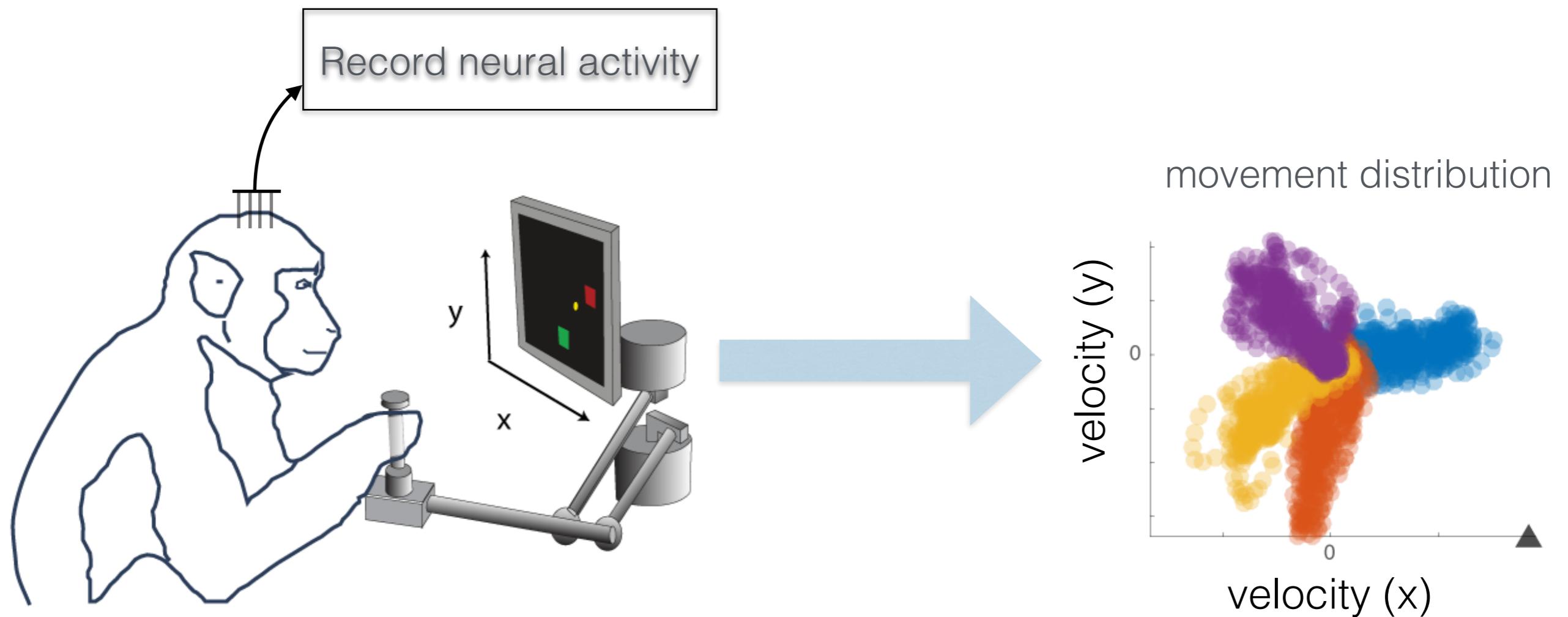
# linear autoencoder -> PCA



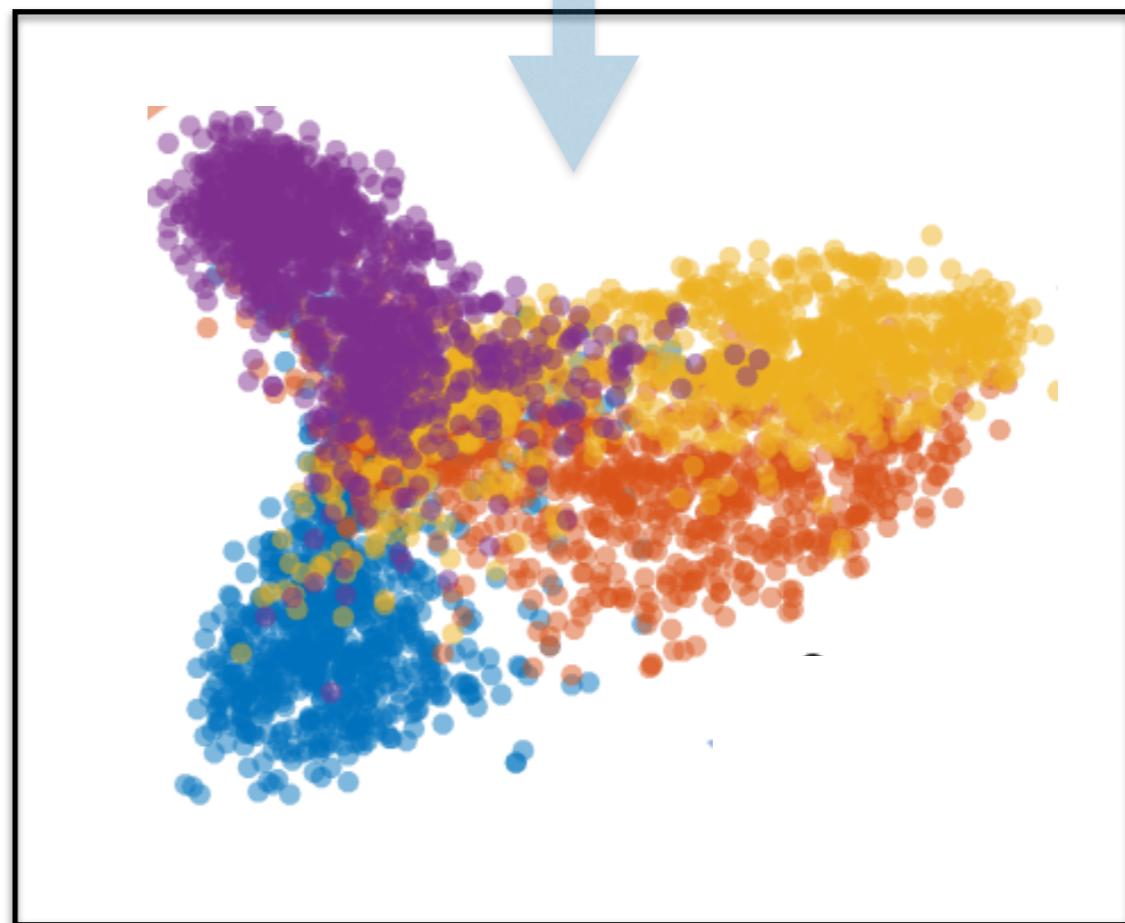
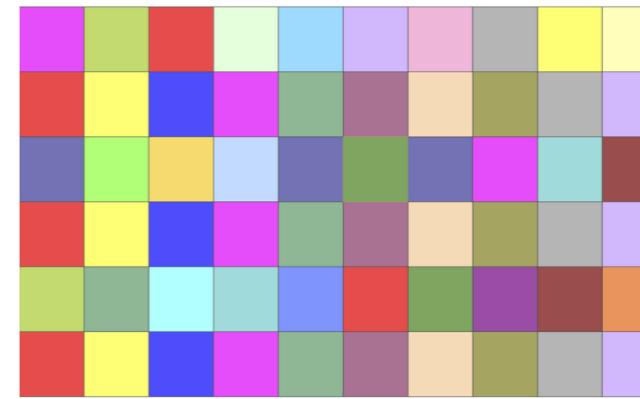
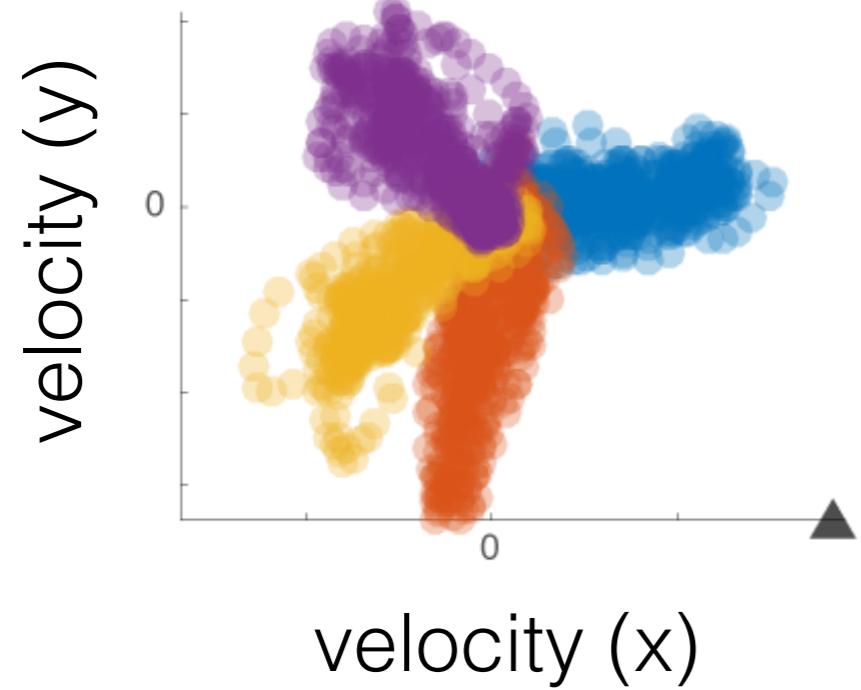
$$\mathbf{Y} \approx \mathbf{U}_k \mathbf{S}_k \mathbf{V}_k^T$$

application to  
neural decoding

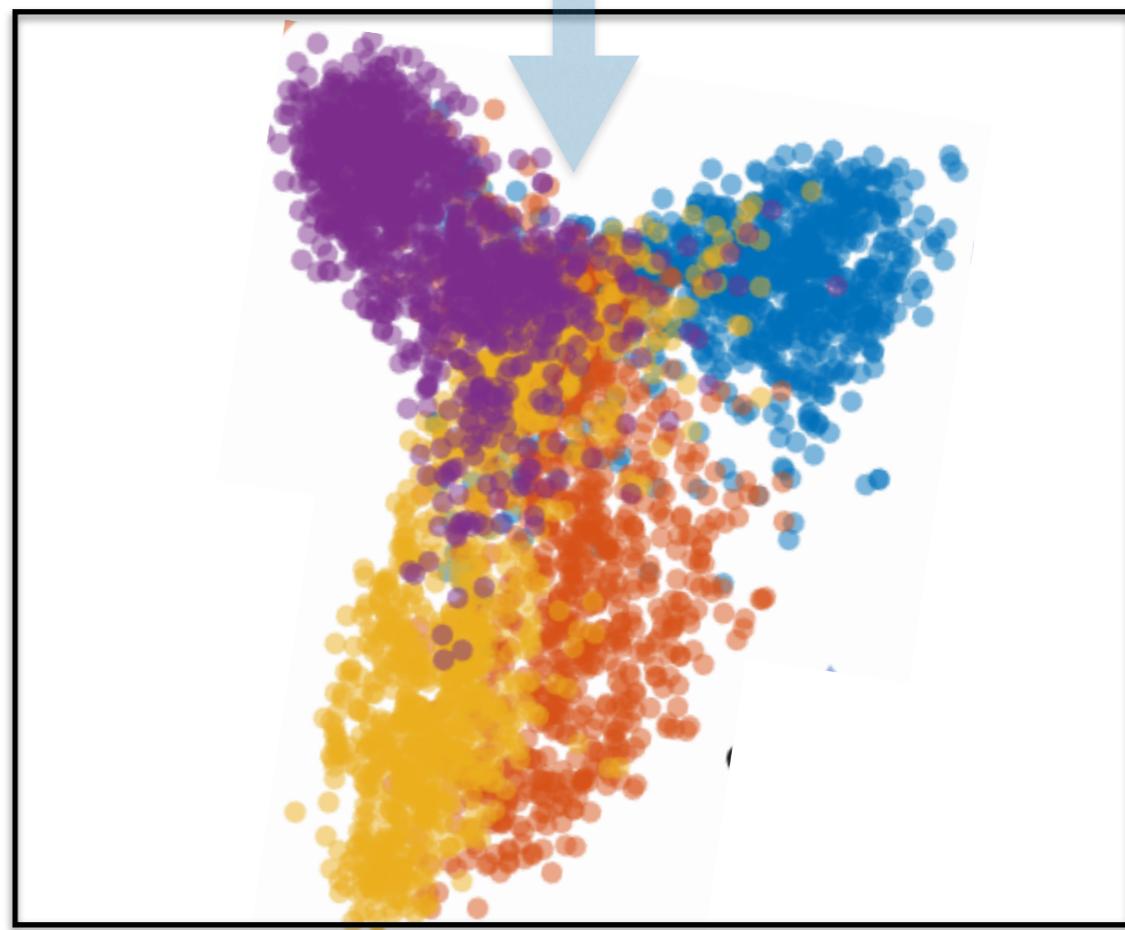
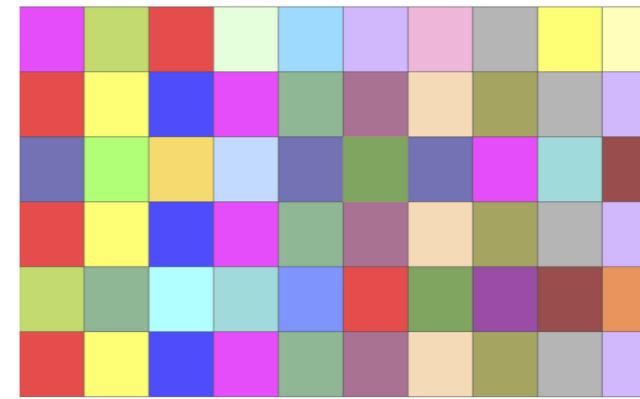
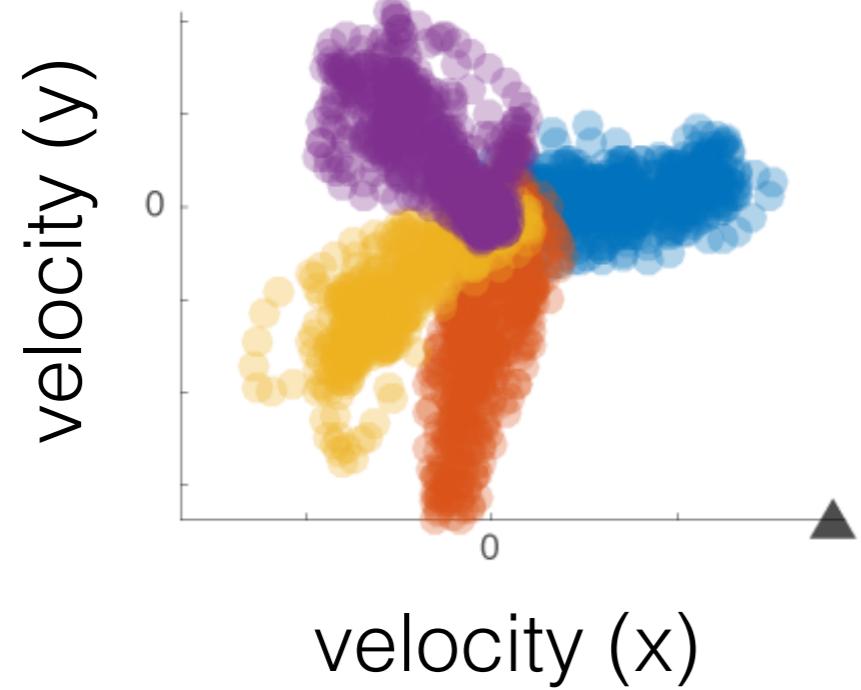
# movement decoding



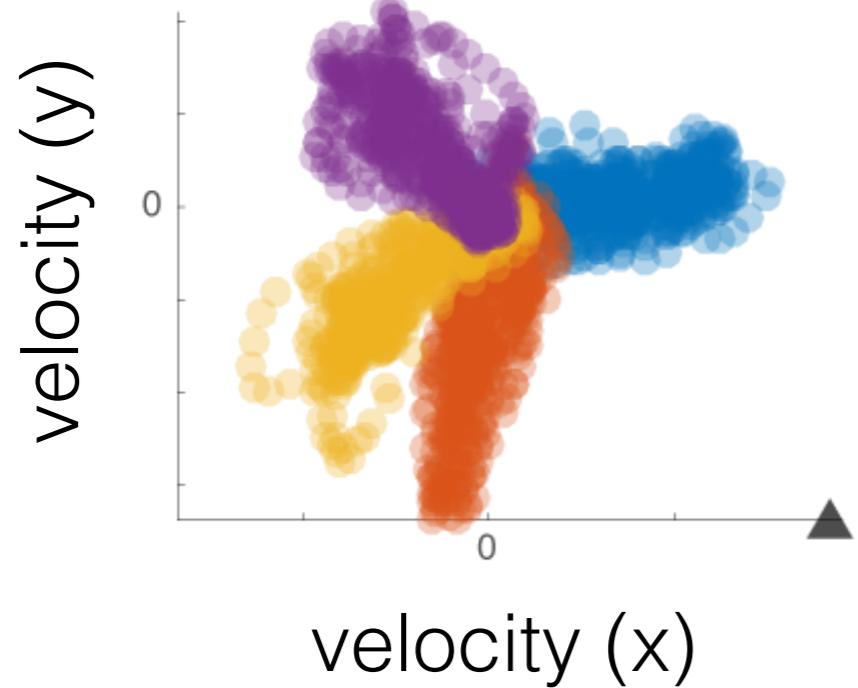
# neural responses are low-d



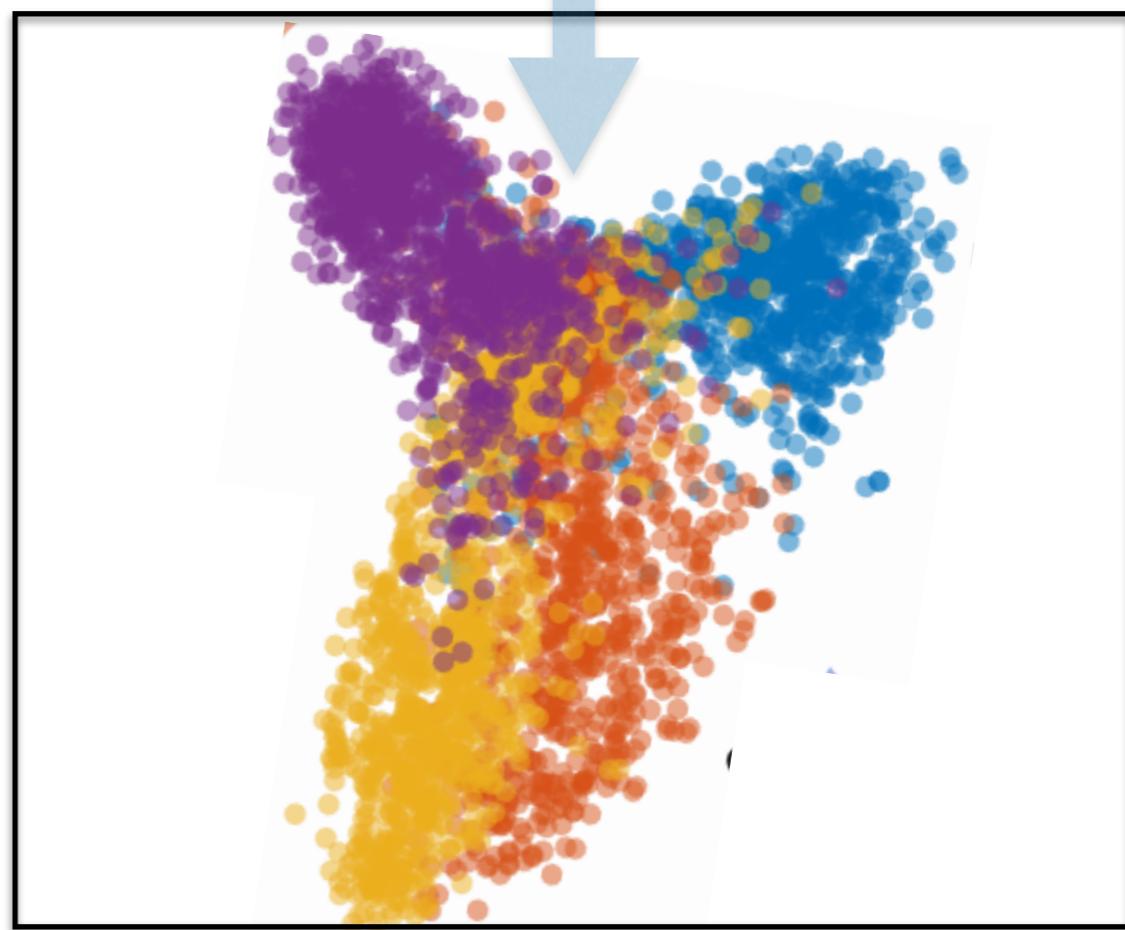
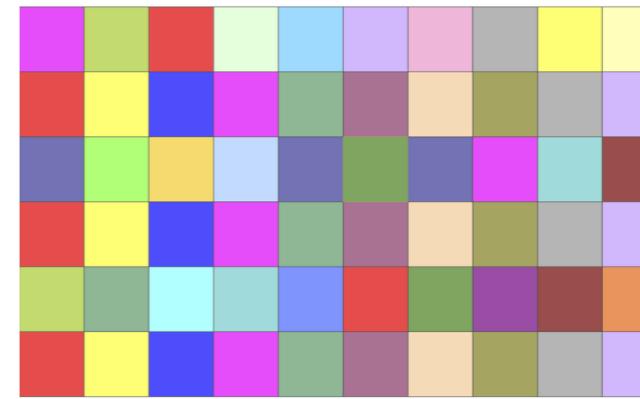
# neural responses are low-d



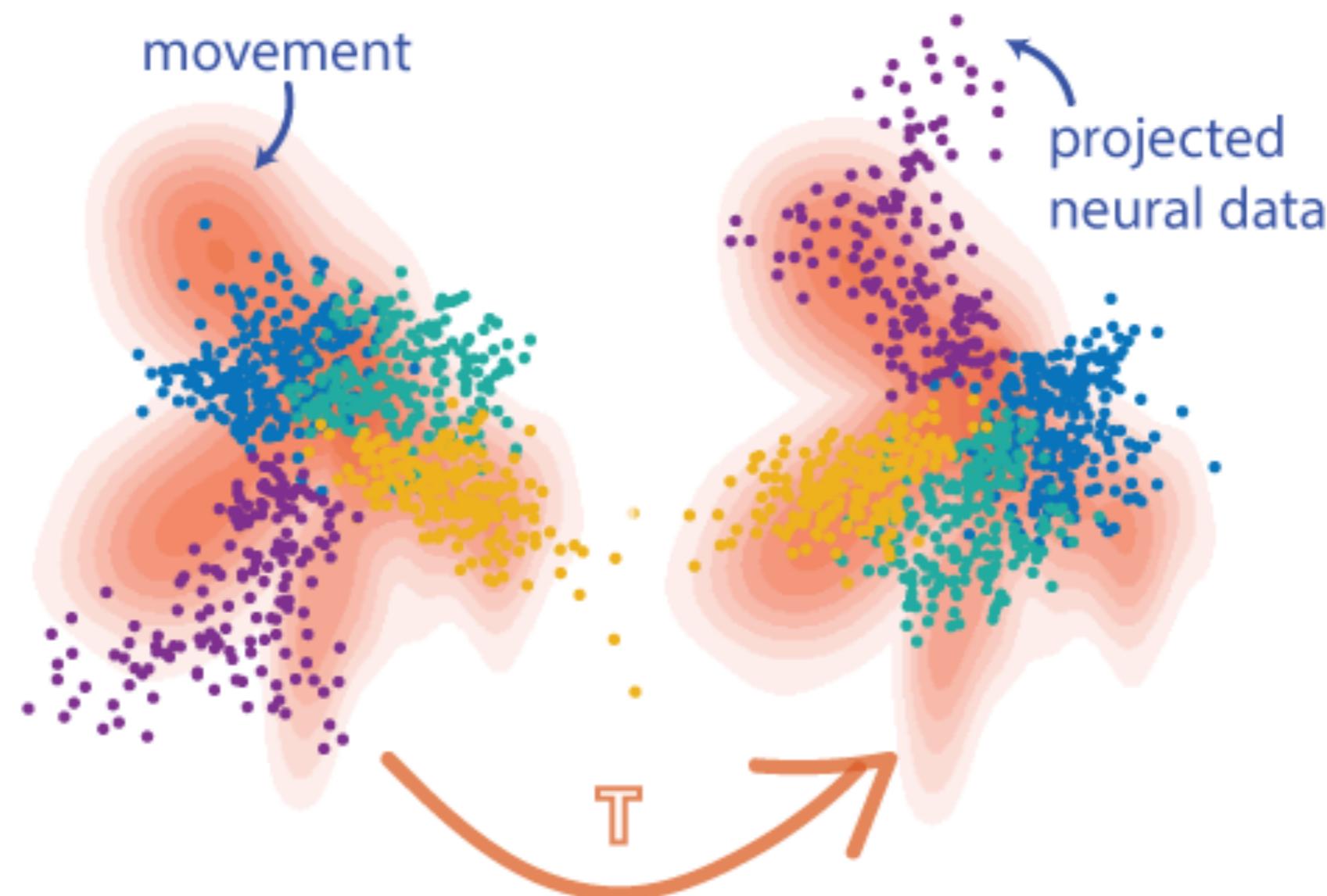
# neural responses are low-d



**solution:** leverage  
distribution of known  
movements



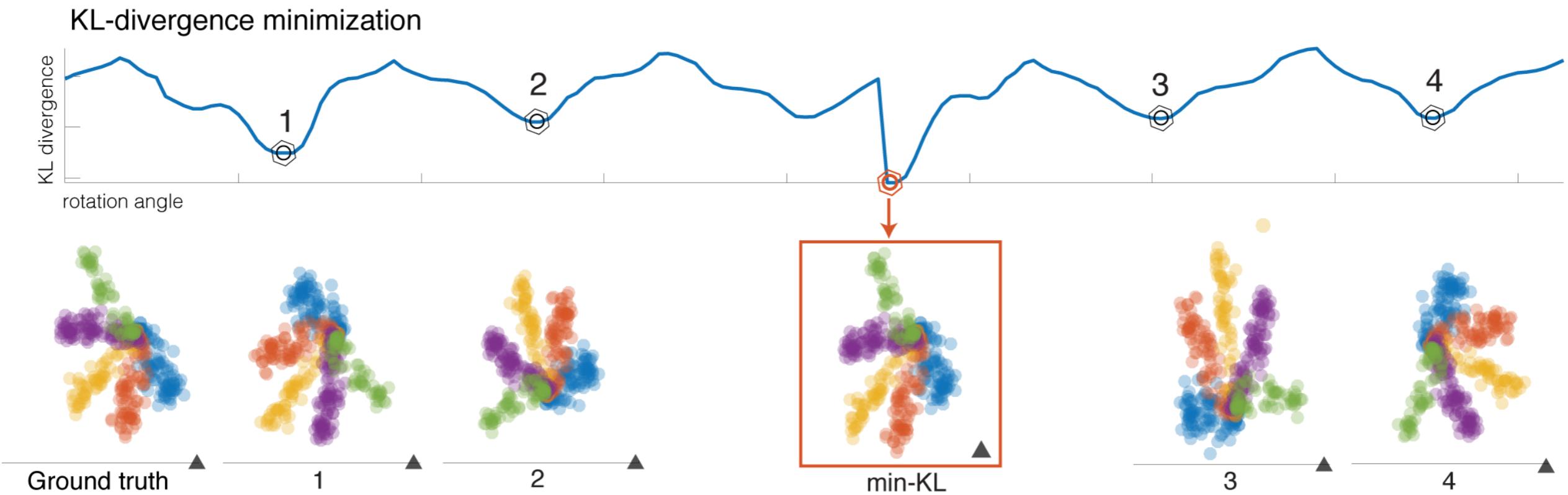
# neural distribution alignment



$$\min_{T \in \mathcal{T}} \mathcal{D}(T(\mu), \nu)$$

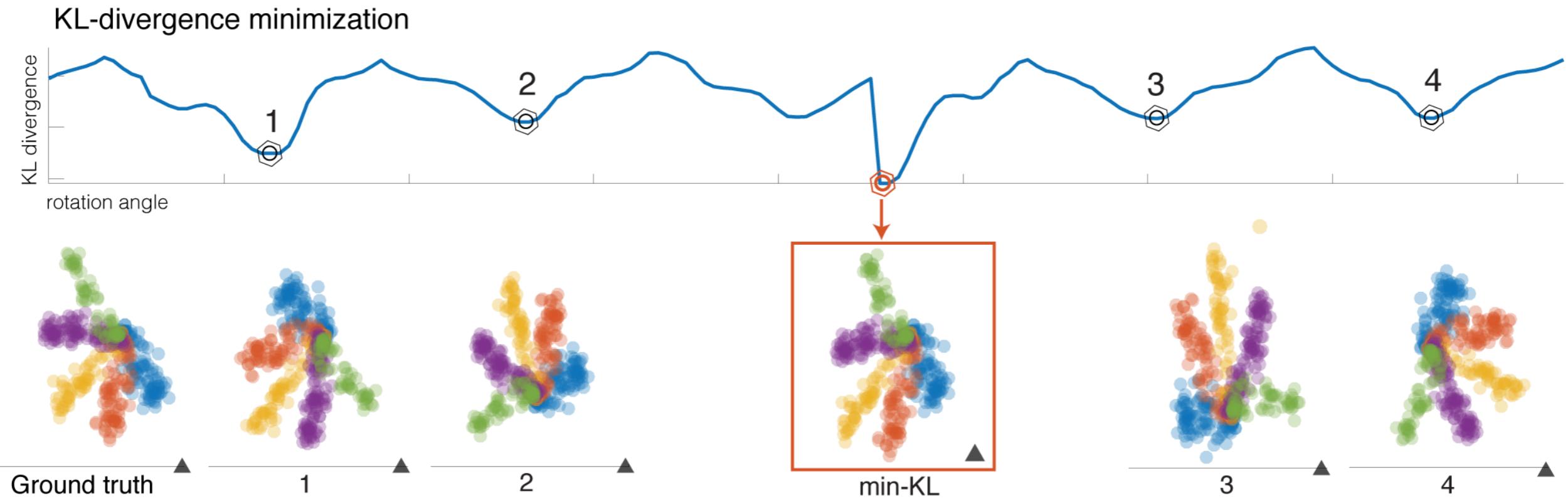
Dyer, Nature BME, 2017  
[github.com/nerdslab/DAD](https://github.com/nerdslab/DAD)

# KL-divergence minimization



**goal:** align neural activities with prior movement distribution

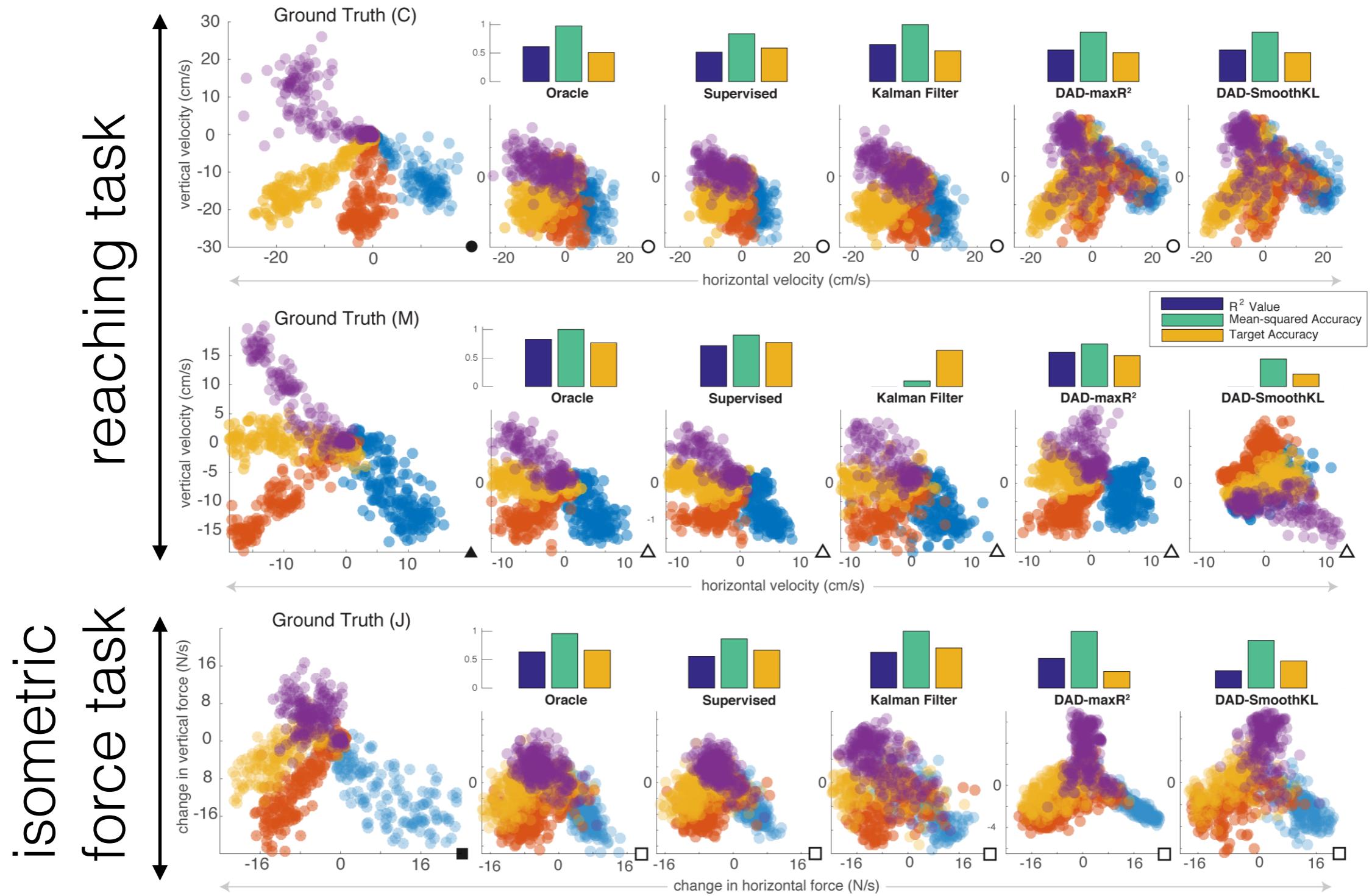
# KL-divergence minimization



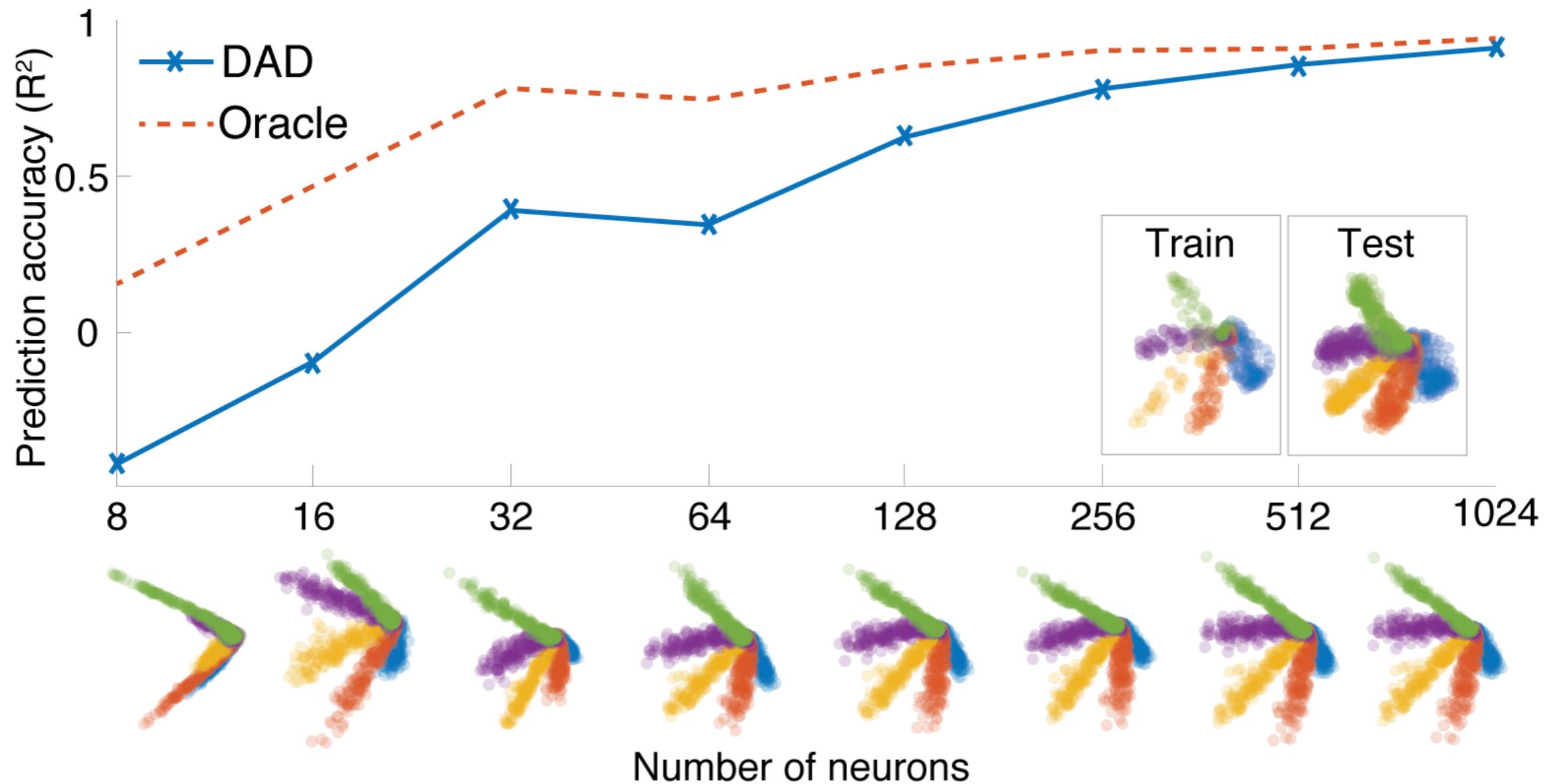
$$\mathbf{H}^* = \arg \min_{\mathbf{H} \in \mathbb{R}^{d \times 3}} \text{KL}(p || q)$$

Estimate  $\mathbf{p}$  from  $\tilde{\mathbf{V}}$   
Estimate  $\mathbf{q}$  from  $\hat{\mathbf{V}} = \mathbf{H}\mathbf{Y}_p$

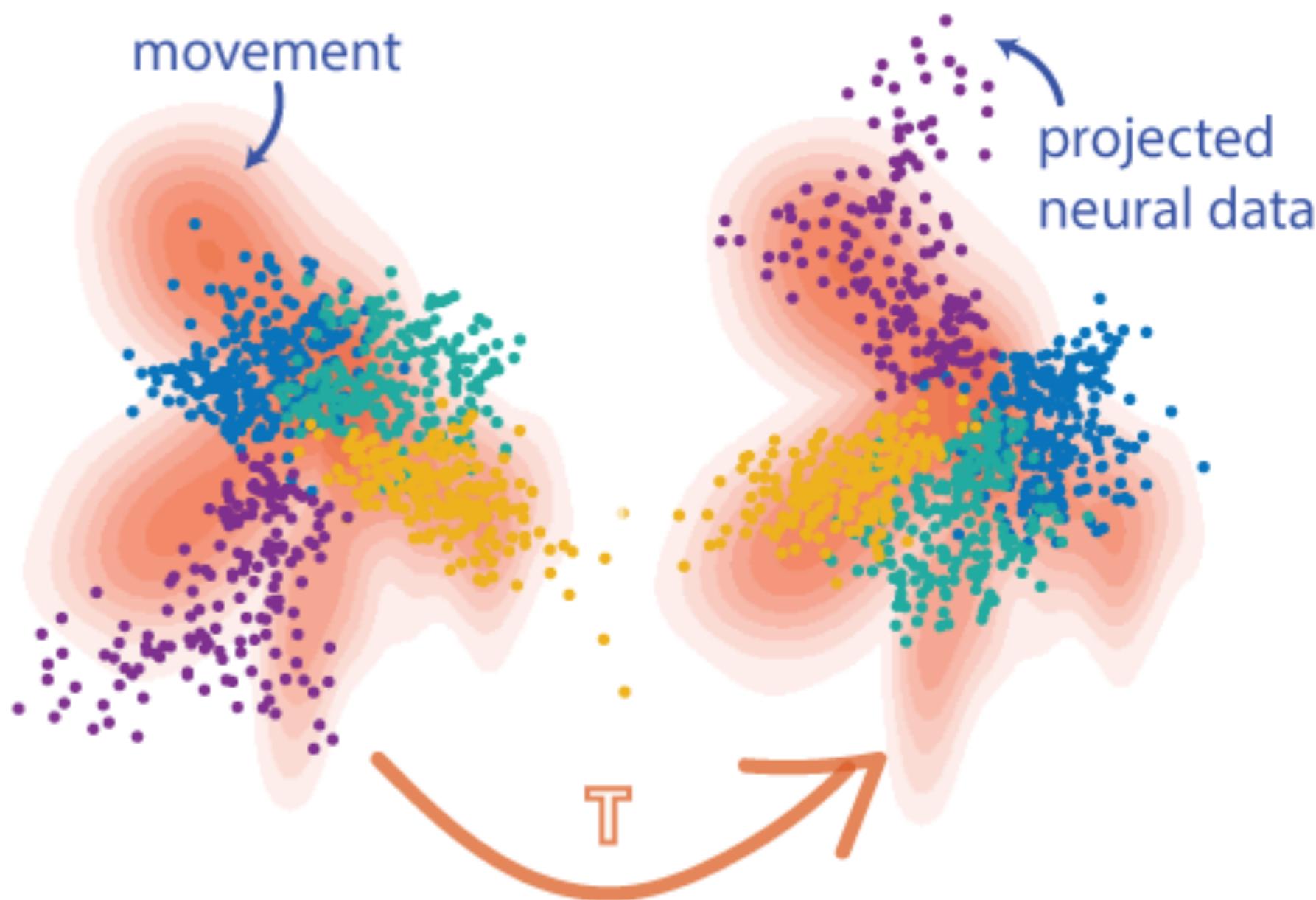
# decoding results



# increasing the population size



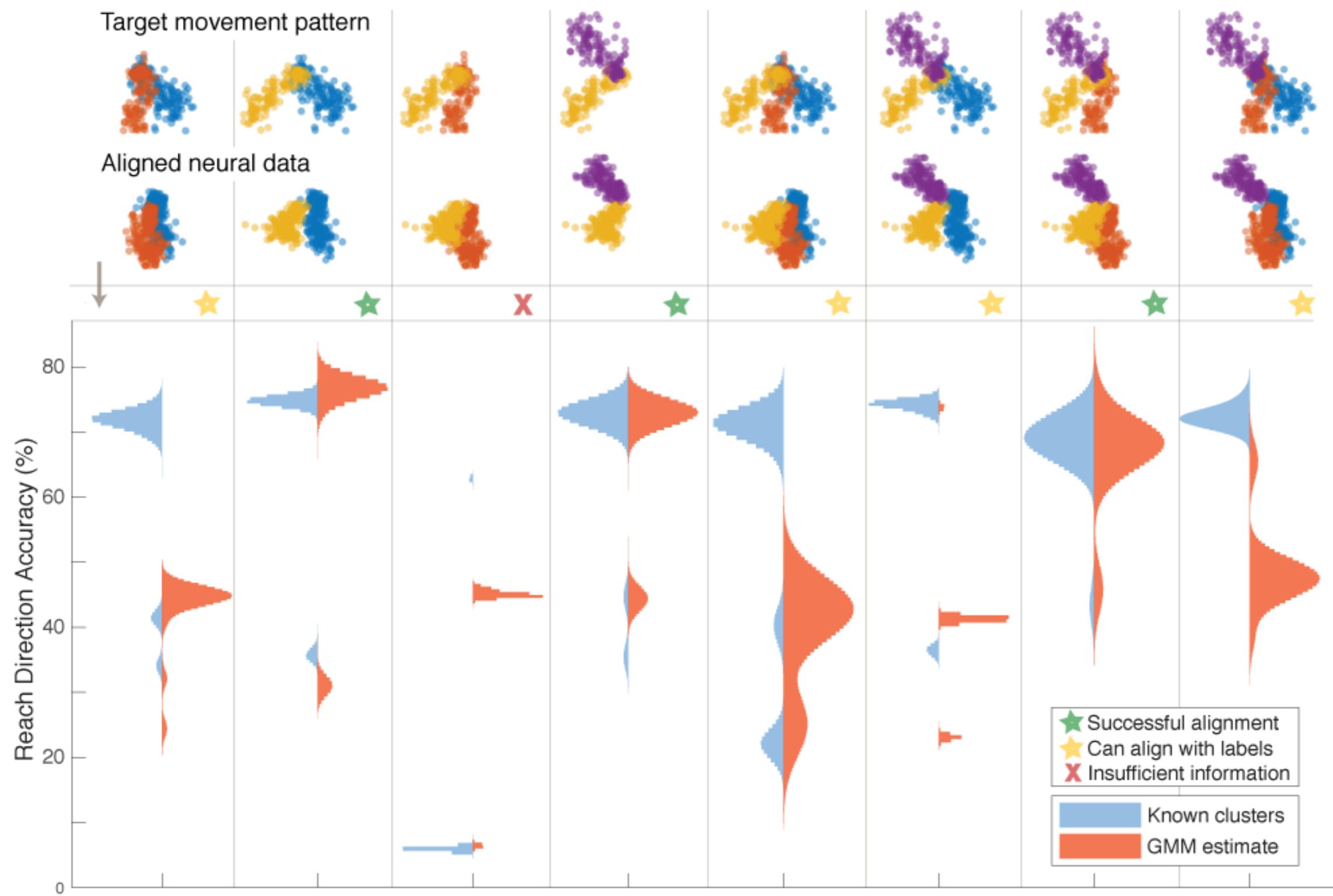
# alignment with optimal transport



Lee et al., 2019

<https://github.com/siplab-gt/hiwa-matlab>

# alignment with optimal transport



# summary and references

## overview of low-dimensional models

- Linear subspace models (PCA, FA, NMF)
- Robust PCA
- Manifold models (Isomap, LLE)
- Clustering models (kmeans)
- Unions of subspaces (SSC)
- Autoencoders

## example: movement decoding

- use movement priors to guide factorizations
- decode without supervised data

# acknowledgements

Max Dabagia (Georgia Tech, NerDS Lab)

John Lee (Georgia Tech)

Chris Rozell (Georgia Tech)

Mohammad Gheshlagi Azar (DeepMind)

Konrad Kording (UPenn)

Lee Miller (Northwestern)

# code / tutorials

## **Matlab Toolbox for dimensionality reduction**

- <https://lvdmaaten.github.io/drtoolbox/>

## **Python Tutorials on PCA**

- [https://sebastianraschka.com/Articles/2015\\_pca\\_in\\_3\\_steps.html](https://sebastianraschka.com/Articles/2015_pca_in_3_steps.html)

## **MATLAB Tutorial on Isomap**

- [http://www.numerical-tours.com/matlab/shapes\\_7\\_isomap/](http://www.numerical-tours.com/matlab/shapes_7_isomap/)

## **Distribution Alignment Decoding (DAD)**

- <https://github.com/KordingLab/DAD/tree/master/data/demo>

## **Hierarchical Optimal Transport**

- <https://github.com/siplab-gt/hiwa-matlab>

# **thank you!**

**(web)**

**dyerlab.gatech.edu**

**github.com/nerdslab**