

Note: All coding problems to be submitted with Github Link. Do not Upload the files/folder. Use git commands only.

Note: this is the distribution of questions:

- (a) Question 1 to Question6: Required for everyone.
- (b) Question 7: Required only for Graduate Students

Problem 1 (20 points)

You have a convolutional neural network that takes as an input image of size $512 \times 512 \times 3$ and passes it through a layer that convolves the image using 3 filters of dimensions $5 \times 5 \times 3$ with a valid padding.

- (a) List all learnable parameters of this convolution layer.
- (b) What if you want to replicate the behavior of this convolutional layer using a fully connected layer? How many parameters would that fully connected layer have?

Problem 2 (20 points)

Given a binary input image of diagonal streaks (see example in Figure 2) and two filters (see Figure 1a) describe how would you build a detector for finding the location of pattern shown in Figure 1b on the input image. Allowed operations are convolution, summation, and argmax.

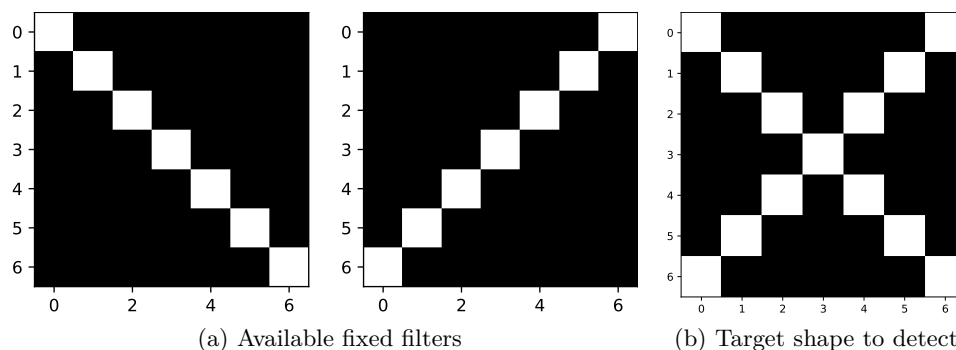


Figure 1: Filters to use (1a) and pattern to find (1b).

Bonus for undergraduates beyond this line

Problem 3 (20 points)

Demonstrate that convolution is translation invariant for 1D convolution (Note: this can be extended to N-D convolutions as well).

Bonus for both undergraduates and graduates beyond this line.

Problem 4 (20 points)

You have to choose between two papers given below:

- (a) Paper 1: [High-Performance Neural Networks for Visual Object Classification](#):
 - (i) Give a short summary of the paper.
 - (ii) What were the parameter sizes for CIFAR-10 and MNIST? why do you think the parameter size differed for CIFAR-10 vs MNIST?
- (b) Paper 2: [ImageNet Classification with Deep Convolutional Neural Networks](#):
 - (i) Give a short summary of the paper.
 - (ii) Why is there a big fluctuation of loss for the last epoch of training?

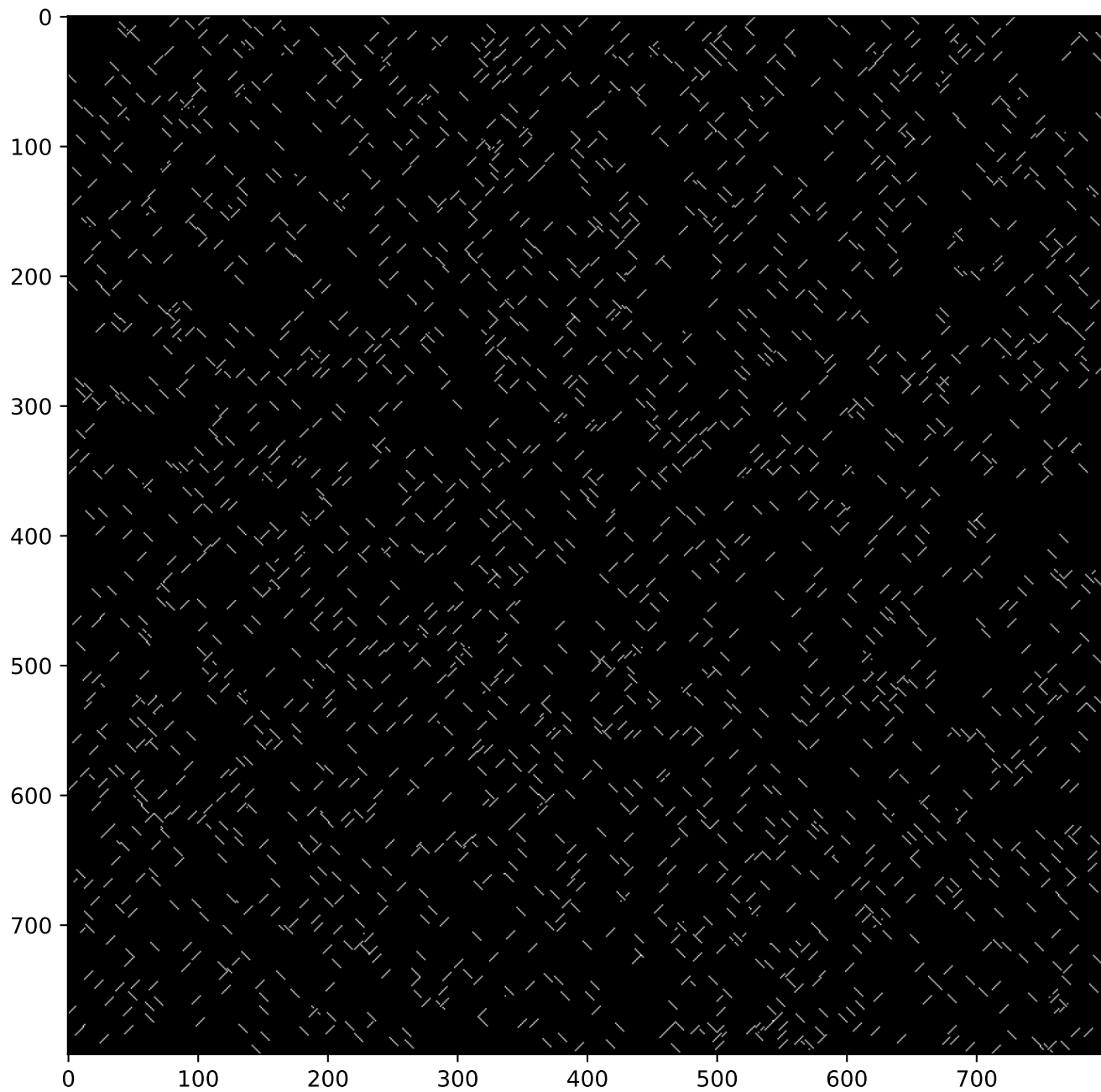


Figure 2: An example image for the architecture