

NICHOLAS A. DEL GROSSO

PERSONAL INFO

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GOALS

- Obtain a PhD in cognitive neuroscience by studying multimodal sensory integration and sensorimotor interactions.
- Obtain teaching, project management, and laboratory experience sufficient to one day become a competent university professor.
- Build technical skills in a wide variety of fields in order to perform high-quality research at institutes with limited resources.

EDUCATION

<i>Aug 2012</i>	<i>M.Sc. Neuroscience</i>	Max Planck International Research School, Graduate School of Neural and Behavioural Sciences
<i>May 2010</i>	<i>B.Sc. Psychology</i>	Wittenberg University

TEACHING EXPERIENCE

<i>December 2015</i>	<i>Teaching Assistant</i>	Psychophysics In this 2-week block course, I provided technical and programming assistance to students programming and analysing their own psychophysics experiments in Matlab, R, and Excel.
<i>Winter 2015</i>	<i>Lecturer</i>	Introduction to Matlab I planned and taught Matlab to beginning programming students.
<i>May 2016</i>	<i>Lecturer</i>	Introduction to Scientific Programming in Python In this 10-week course, I taught beginning programmers data management, scientific data analysis, and programming skills in a new language (Python). Besides organizing and planning the course, I also prepared all course materials, homework assignments, and graded their final projects.

RESEARCH EXPERIENCE

<i>May 2013 - Present</i>	<i>Ludwig-Maximilians Universität</i>	Prof. Dr. Anton Sirota Programmed a 3D graphics engine in Python to build virtual reality system for freely moving rats, supervised students in programming, engineering, and cognitive science projects, organized weekly journal clubs, and ordered new equipment.
<i>Aug 2012 - May 2013</i>	<i>Universität Tübingen</i>	Prof. Dr. Christoph Braun Wrote a research grant to study the top-down and bottom-up interactions by computational modeling information propagation in early sensory pathways as measured by MEG, designed and administrated an institute wiki, organized a student lecture series, and supervised two students' EEG research projects.
<i>Nov 2011 - July 2012</i>	<i>Universität Tübingen</i>	Prof. Dr. Niels Birbaumer Programmed in Matlab a time-frequency and evoked potential analysis on three years' worth of MEG data assessing longitudinal changes in stroke patients receiving physiotherapy.

Oct 2012 -
Nov 2012

Universität Tübingen

Prof. Dr. Cornelius Schwarz

In this lab rotation, I trained rats to perform whisking in response to barrel cortex stimulation via chronically-implanted electrodes, mapping stimulation sensitivity to each cortical layer.

INDUSTRY EXPERIENCE

Technical Consultant

UKT Psychosomatic Med. and Sports Med.

I evaluated and designed a solution for performing medical science studies in a placebo study, and taught the PhD student who carried out the study over several remote sessions and a few travel consultations.

JOURNAL PUBLICATIONS

Broetz D., Del Grosso, N.A., Rea M., Ramos-Murguialday, A., Soekadar S.R., Birbaumer, N. "A New Hand Assessment Instrument for Severely Affected Stroke Patients." *Journal of Neurorehabilitation*. 2014; 34(3), 409-27.

Benoit, J.B., Del Grosso, N.A., Yoder, J.A., Denlinger, D.L. "Resistance to Dehydration between Bouts of Blood Feeding in the Bed Bug, *Cimex Lectularius*, is Enhanced by Water Conservation, Aggregation, and Quiescence." *American Journal of Tropical Medical Hygiene*. May 2007; 76(5), 987-93.

CONFERENCE PUBLICATIONS

June 2015

Synergy Munich

ratCAVE, A Novel Virtual Reality System for Freely-Moving Rodents

March 2015

Interact Munich

Demonstrating a Freely-Moving Virtual Reality Approach for Rodent Research

Nov 2014

Society for Neuroscience

ratCAVE, A Novel Virtual Reality System for Freely-Moving Rodents.

Nov. 2012

NENA Tübingen

Interpreting (M)EEG, A First Look at Dynamic Causal Modeling.

Introduced a probabilistic nonlinear modeling framework for interpretation of MEG and EEG data, along with the results of a pilot study in which we applied the approach.

Nov. 2011

NENA Tübingen

The Intrinsic Bias During the Blind-Walking Task is Not Caused by an Aberrant Intrinsic Ground-Slope Model.

SKILLS

- **Languages:** English (Mother Tongue), German (Level B1), French (Level A1-2)
- **Programming:** Python, Matlab, C-Sharp, GLSL, R, LabView, C, Bash/Linux, LaTeX
- **Stimulus Presentation:** Psychopy, Neurobs Presentation, Psychophysics Toolbox, OpenGL, Pyglet, SuperLab, RatCAVE
- **Statistical Analysis:** Statistical Parametric Mapping (SPM), SPSS, R, Matlab Statistics Toolbox, Fieldtrip, gTec Analyze, BrainVision Analyzer
- **Graphics:** Blender, Adobe Suite (Photoshop, Illustrator, and InDesign), OpenGL, Google SketchUp, GIMP, Inkspace

- **Wet Lab Skills:** Rat Neurosurgery, Animal Behavioral training (rats and monkeys), in vivo electrophysiology (single needle electrodes, chronically-implanted electrode arrays, noninvasive arrays of EEG electrodes and MEG sensors), Basic Electronics, Comfortable with building custom laboratory equipment
- **EEG System Experience:** BrainProducts, gTec, Grass Instruments, CTF

AWARDS

- 2015 Best Poster Award at Interact Munich Conference
- 2011 National Science Foundation Graduate Research Fellowship
- 2008 NSF Neuroscience REU Fellowship at Duke University

Full List of Positions and Publications Available Upon Request.



June 1, 2016