

## Midterm solutions

### Problem 1

Formulate the following problem as a set of linear equations: find a polynomial of two variables  $s, t$ ,

$$f(s, t) = \sum_{i=1}^3 \sum_{j=1}^3 c_{ij} s^{i-1} t^{j-1}$$

that satisfies nine interpolation conditions

$$f(s_k, t_k) = y_k, \quad k = 1, \dots, 9.$$

The points  $(s_k, t_k)$  and values  $y_k$  are given. The unknowns are the coefficients  $c_{ij}$ .

1. Write the equations in matrix-vector form  $Ax = b$ . Clearly state what  $A$ ,  $x$ , and  $b$  are.
2. Solve the problem for the following interpolation conditions. The points  $(s_k, t_k)$  are

$$\begin{aligned} (s_1, t_1) &= (0, 0), & (s_2, t_2) &= (0, 1), & (s_3, t_3) &= (0, 2), \\ (s_4, t_4) &= (1, 0), & (s_5, t_5) &= (1, 1), & (s_6, t_6) &= (1, 2), \\ (s_7, t_7) &= (2, 0), & (s_8, t_8) &= (2, 1), & (s_9, t_9) &= (2, 2), \end{aligned}$$

and  $y_1, \dots, y_9$  are the nine digits of your UID.

In your answer, write the coefficients in an array

$$\begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix}.$$

### Solution.

1.

$$\begin{bmatrix} 1 & s_1 & s_1^2 & t_1 & s_1 t_1 & s_1^2 t_1 & t_1^2 & s_1 t_1^2 & s_1^2 t_1^2 \\ 1 & s_2 & s_2^2 & t_2 & s_2 t_2 & s_2^2 t_2 & t_2^2 & s_2 t_2^2 & s_2^2 t_2^2 \\ 1 & s_3 & s_3^2 & t_3 & s_3 t_3 & s_3^2 t_3 & t_3^2 & s_3 t_3^2 & s_3^2 t_3^2 \\ 1 & s_4 & s_4^2 & t_4 & s_4 t_4 & s_4^2 t_4 & t_4^2 & s_4 t_4^2 & s_4^2 t_4^2 \\ 1 & s_5 & s_5^2 & t_5 & s_5 t_5 & s_5^2 t_5 & t_5^2 & s_5 t_5^2 & s_5^2 t_5^2 \\ 1 & s_6 & s_6^2 & t_6 & s_6 t_6 & s_6^2 t_6 & t_6^2 & s_6 t_6^2 & s_6^2 t_6^2 \\ 1 & s_7 & s_7^2 & t_7 & s_7 t_7 & s_7^2 t_7 & t_7^2 & s_7 t_7^2 & s_7^2 t_7^2 \\ 1 & s_8 & s_8^2 & t_8 & s_8 t_8 & s_8^2 t_8 & t_8^2 & s_8 t_8^2 & s_8^2 t_8^2 \\ 1 & s_9 & s_9^2 & t_9 & s_9 t_9 & s_9^2 t_9 & t_9^2 & s_9 t_9^2 & s_9^2 t_9^2 \end{bmatrix} \begin{bmatrix} c_{11} \\ c_{21} \\ c_{31} \\ c_{12} \\ c_{22} \\ c_{32} \\ c_{13} \\ c_{23} \\ c_{33} \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \\ y_6 \\ y_7 \\ y_8 \\ y_9 \end{bmatrix}.$$

## Problem 2

Suppose  $b$  is an  $n$ -vector with nonzero elements ( $b_i \neq 0$  for all  $i$ ) and  $A$  is a diagonal  $n \times n$ -matrix with distinct diagonal elements ( $A_{ii} \neq A_{jj}$  for  $i \neq j$ ). Prove that the  $n \times n$  matrix

$$C = \begin{bmatrix} b & Ab & A^2b & \cdots & A^{n-1}b \end{bmatrix}$$

is nonsingular.

**Solution.** Denote the diagonal elements of  $A$  by  $t_1, \dots, t_n$ . We show that the columns of  $C$  are linearly independent:  $Cx = 0$  only if  $x = 0$ .

$$\begin{aligned} Cx &= x_1b + x_2Ab + x_3A^2b + \cdots + x_nA^{n-1}b \\ &= (x_1I + x_2A + x_3A^2 + \cdots + x_nA^{n-1})b \\ &= \begin{bmatrix} p(t_1) & 0 & \cdots & 0 \\ 0 & p(t_2) & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & p(t_n) \end{bmatrix} b \\ &= \begin{bmatrix} p(t_1)b_1 \\ p(t_2)b_2 \\ \vdots \\ p(t_n)b_n \end{bmatrix} \end{aligned}$$

where  $p(t) = x_1 + x_2t + \cdots + x_nt^{n-1}$ . Since the elements  $b_i$  are nonzero,  $Cx = 0$  holds only if

$$p(t_1) = \cdots = p(t_n) = 0,$$

and since the diagonal elements  $t_i$  are distinct this is only possible if  $x_1 = \cdots = x_n = 0$ .

## Problem 3

Let  $A = \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix}$  be a matrix with three columns and QR factorization  $A = QR$  where

$$R = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}.$$

1. What are the norms  $\|a_1\|$ ,  $\|a_2\|$ ,  $\|a_3\|$  of the columns of  $A$ ?
2. Denote by  $\theta_{ij}$  the angle between columns  $a_i$  and  $a_j$  of  $A$ . What are  $\theta_{12}$ ,  $\theta_{13}$ ,  $\theta_{23}$  (in degrees)?

Explain your answers.

**Solution.** We have

$$a_1 = q_1R_{11}, \quad a_2 = q_1R_{12} + q_2R_{22}, \quad a_3 = q_1R_{13} + q_2R_{23} + q_3R_{33}.$$

Since  $q_1, q_2, q_3$  are orthonormal,

$$\|a_1\| = R_{11} = 1, \quad \|a_2\| = (R_{12}^2 + R_{22}^2)^{1/2} = \sqrt{2}, \quad \|a_3\| = (R_{13}^2 + R_{23}^2 + R_{33}^2)^{1/2} = \sqrt{3}.$$

The cosines of the angles are

$$\cos \theta_{12} = \frac{a_1^T a_2}{\|a_1\| \|a_2\|} = \frac{R_{11} R_{12}}{R_{11} \sqrt{R_{12}^2 + R_{22}^2}} = \frac{-1}{\sqrt{2}},$$

$$\cos \theta_{13} = \frac{a_1^T a_3}{\|a_1\| \|a_3\|} = \frac{R_{11} R_{13}}{R_{11} \sqrt{R_{13}^2 + R_{23}^2 + R_{33}^2}} = \frac{-1}{\sqrt{3}},$$

and

$$\cos \theta_{23} = \frac{a_2^T a_3}{\|a_2\| \|a_3\|} = \frac{R_{12} R_{13} + R_{22} R_{23}}{\sqrt{R_{12}^2 + R_{22}^2} \sqrt{R_{13}^2 + R_{23}^2 + R_{33}^2}} = 0.$$

Hence

$$\theta_{12} = 135^\circ, \quad \theta_{13} = 125.3^\circ, \quad \theta_{23} = 90^\circ.$$

#### Problem 4

Recall (from exercise A2.8) the definition of the Kronecker product  $A \otimes B$  of two  $n \times n$  matrices:

$$A \otimes B = \begin{bmatrix} A_{11}B & A_{12}B & \cdots & A_{1n}B \\ A_{21}B & A_{22}B & \cdots & A_{2n}B \\ \vdots & \vdots & & \vdots \\ A_{n1}B & A_{n2}B & \cdots & A_{nn}B \end{bmatrix}.$$

This is a matrix of size  $n^2 \times n^2$ . A useful property of the Kronecker product is

$$(A \otimes B)(C \otimes D) = (AC) \otimes (BD).$$

(You are not asked to prove this.) We consider the linear equation

$$(A \otimes A)x = b, \tag{1}$$

where  $A$  is an  $n \times n$  matrix,  $b$  is an  $n^2$ -vector, and the variable  $x$  is an  $n^2$ -vector. By partitioning  $x$  and  $b$  in subvectors  $b_1, \dots, b_n$  and  $x_1, \dots, x_n$  of length  $n$ , we can write the equation as

$$\begin{bmatrix} A_{11}A & A_{12}A & \cdots & A_{1n}A \\ A_{21}A & A_{22}A & \cdots & A_{2n}A \\ \vdots & \vdots & & \vdots \\ A_{n1}A & A_{n2}A & \cdots & A_{nn}A \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

1. Suppose  $A$  is upper or lower triangular and nonsingular. Then  $A \otimes A$  is upper or lower triangular. Describe an efficient method for solving (1). What is the complexity (number of flops for large  $n$ )? Compare with the complexity of solving a general triangular set of linear equations of size  $n^2 \times n^2$ .
2. Suppose  $A$  is nonsingular. Explain how you can solve (1) using the LU factorization of  $A$ . Clearly state the different steps in the algorithm, the complexity of each step, and the overall complexity. Compare with the complexity of solving a general set of linear equations of size  $n^2 \times n^2$ .

**Solution.**

1. Consider lower triangular  $A$ .

$$\begin{bmatrix} A_{11}A & 0 & \cdots & 0 & 0 \\ A_{21}A & A_{22}A & \cdots & 0 & 0 \\ \vdots & \vdots & & \vdots & \vdots \\ A_{n-1,1}A & A_{n-1,2}A & \cdots & A_{n-1,n-1}A & 0 \\ A_{n1}A & A_{n2}A & \cdots & A_{n,n-1}A & A_{nn}A \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_{n-1} \\ b_n \end{bmatrix}.$$

We first solve for  $y_1 = Ax_1, \dots, y_n = Ax_n$  from the equations

$$\begin{aligned} A_{11}y_1 &= b_1 \\ A_{21}y_1 + A_{22}y_2 &= b_2 \\ &\vdots \\ A_{n-1,1}y_1 + A_{n-1,2}y_2 + \cdots + A_{n-1,n-1}y_{n-1} &= b_{n-1} \\ A_{n1}y_1 + A_{n2}y_2 + \cdots + A_{n,n-1}y_{n-1} + A_{nn}y_n &= b_n. \end{aligned}$$

The system can be solved by forward substitution in

$$n(1 + 2 + 3 + \cdots + n - 1) = n^3 \text{ flops.}$$

Next we solve the  $n$  equations

$$Ax_1 = y_1, \quad Ax_2 = y_2, \quad \dots, \quad Ax_n = y_n,$$

each by forward substitution, at a total cost of  $n^3$ . The total for the two steps is  $2n^3$ , one order faster than the cost of  $n^4$  for a general triangular system of this size.

As an alternative solution, we can note that the equation  $(A \otimes A)x = b$  can be written as a matrix equation

$$AXA^T = B$$

where  $X$  is the  $n \times n$  matrix with columns  $x_1, \dots, x_n$  and  $B$  is the  $n \times n$  matrix with columns  $b_1, \dots, b_n$ . In the method just described, we first solve the matrix equation  $YA^T = B$  or, equivalently,  $AY^T = B^T$ , row by row. Then we solve the matrix equation  $AX = Y$  for the columns of  $X$ .

2. Substituting  $A = PLU$  in  $(A \otimes A)x = b$  and using the property in the statement gives

$$(P \otimes P)(L \otimes L)(U \otimes U)x = b.$$

We can solve this in three steps.

- Solve  $(P \otimes P)z = b$ . Zero flops because  $P \otimes P$  is a permutation matrix.
- Solve  $(L \otimes L)y = z$  using the method in part 1.  $2n^3$  flops.
- Solve  $(U \otimes U)x = y$  using the method in part 1.  $2n^3$  flops.

The total is  $(2/3)n^3 + 4n^3 = (14/3)n^3$ , as compared to  $(2/3)n^6$  for a general system of this size.

As in part 1 we can interpret the problem as a matrix equation

$$AXA^T = B.$$

If we substitute the LU factorization of  $A$ , this becomes

$$PLUXU^TL^TP^T = B.$$

In the method described we first solve  $PZP^T = B$  for  $Z$ . The solution  $Z = P^TB P$  is a symmetric reordering of the matrix  $B$ . In step 2 we solve  $LYL^T = Z$  for  $Y$ , using the method of part 1. In step 3 we solve  $UXU^T = Y$  for  $X$ .

Other possibilities exist, with the same complexity. For example, we can first solve the matrix equation  $PLUW = B$  column by column for the matrix  $W$ . Then we solve  $XU^TL^TP^T = W$  for  $X$  or, equivalently,  $PLUX^T = W^T$  for  $X^T$ .