

Homework 4 solutions

1. *Exercise A5.6 (b)*. Denote the columns of X by X_1, X_2, \dots, X_n , and the columns of B by B_1, B_2, \dots, B_n . If we write the equation in terms of the columns of X and B we get

$$\begin{aligned} LX_1 + L_{11}X_1 &= B_1 \\ LX_2 + L_{21}X_1 + L_{22}X_2 &= B_2 \\ LX_3 + L_{31}X_1 + L_{32}X_2 + L_{33}X_3 &= B_3 \\ &\vdots \\ LX_n + L_{n1}X_1 + L_{n2}X_2 + \dots + L_{nn}X_n &= B_n. \end{aligned}$$

In other words,

$$\begin{aligned} (L + L_{11}I)X_1 &= B_1 \\ (L + L_{22}I)X_2 &= B_2 - L_{21}X_1 \\ (L + L_{33}I)X_3 &= B_3 - L_{31}X_1 - L_{32}X_2 \\ &\vdots \\ (L + L_{nn}I)X_n &= B_n - L_{n1}X_1 - L_{n2}X_2 - \dots - L_{n,n-1}X_{n-1}. \end{aligned}$$

We can solve for X_1 first, then evaluate the right-hand side of the second equation and solve for X_2 , then substitute X_1 and X_2 in the third right-hand side and solve for X_3 , et cetera. The matrices on the left-hand sides are upper triangular with nonzero diagonal elements (since we are given that $L_{ii} + L_{jj} \neq 0$ for all i and j), so each of the n equations can be solved by forward substitution.

To estimate the cost we look at the equation for the k th column:

$$(L + L_{kk}I)X_k = B_k - L_{k1}X_1 - L_{k2}X_2 - \dots - L_{k,k-1}X_{k-1}.$$

The vector on the right-hand side can be computed in $2(k-1)n$ operations: $(k-1)n$ for the scalar-vector multiplications and $(k-1)n$ for the vector subtractions. Adding L_{kk} to the diagonal elements of L takes n flops. Solving the equation costs n^2 . The complexity of step k is therefore $n^2 + (2k-1)n$ flops. The total complexity for the n columns is

$$\begin{aligned} n^3 + n \sum_{k=1}^n (2k-1) &= n^3 + n(1 + 3 + 5 + \dots + (2n-1)) \\ &= 2n^3. \end{aligned}$$

2. *Exercise A6.3.*

(a) The result in the hint follows from

$$x^T Sx = (x^T Sx)^T = x^T S^T x = -x^T Sx,$$

hence $x^T Sx = 0$. This can also be seen by noting that

$$x^T Sx = \sum_{i=1}^n \sum_{j=1}^n S_{ij} x_i x_j = \sum_{i=1}^n (S_{ii} x_i^2 + \sum_{j=i+1}^n (S_{ij} + S_{ji}) x_i x_j).$$

Since $S_{ii} = 0$ and $S_{ij} = -S_{ji}$ for a skew-symmetric matrix the sum is zero.

To prove that $I - S$ is nonsingular we show that $(I - S)x = 0$ implies $x = 0$:

$$\begin{aligned} (I - S)x = 0 &\implies x^T x - x^T Sx = x^T (I - S)x = 0 \\ &\implies x^T x = 0 \\ &\implies x = 0. \end{aligned}$$

(b) We have (for any matrix S)

$$(I - S)(I + S) = I - S + S - S^2 = (I + S)(I - S).$$

Multiplying with $(I - S)^{-1}$ on both sides gives

$$(I + S)(I - S)^{-1} = (I - S)^{-1}(I + S).$$

(c) We show that $A^T A = I$:

$$\begin{aligned} A^T A &= (I - S)^{-T} (I + S)^T (I + S) (I - S)^{-1} \\ &= (I + S)^{-1} (I - S) (I + S) (I - S)^{-1} \\ &= (I + S)^{-1} (I - S) (I - S)^{-1} (I + S) \\ &= I. \end{aligned}$$

On line 2 we use the skew-symmetry of S . Line 3 follows from part (b).

3. *Exercise A6.9.*

(a) For $k = 1$, the result is obvious because S^{k-1} and $\mathbf{diag}(We_1)$ are both equal to the $n \times n$ identity matrix.

The columns of WS^{k-1} are the columns of W , shifted circularly to the left over $k - 1$ positions. For $2 \leq k \leq n$, this gives

$$WS^{k-1} = \begin{bmatrix} 1 & \cdots & 1 & 1 & 1 & \cdots & 1 \\ \omega^{-(k-1)} & \cdots & \omega^{-(n-1)} & 1 & \omega^{-1} & \cdots & \omega^{-(k-2)} \\ \omega^{-2(k-1)} & \cdots & \omega^{-2(n-1)} & 1 & \omega^{-2} & \cdots & \omega^{-2(k-2)} \\ \vdots & & \vdots & \vdots & \vdots & & \vdots \\ \omega^{-(n-1)(k-1)} & \cdots & \omega^{-(n-1)(n-1)} & 1 & \omega^{-(n-1)} & \cdots & \omega^{-(n-1)(k-2)} \end{bmatrix}.$$

The column of ones on the right-hand side is column $n - k + 2$.

The k th column of W is the vector $We_k = (1, \omega^{-(k-1)}, \omega^{-2(k-1)}, \dots, \omega^{-(n-1)(k-1)})$, so the matrix $\mathbf{diag}(We_k)W$ is

$$\mathbf{diag}(We_k)W =$$

$$\begin{bmatrix} 1 & \dots & 1 & 1 & 1 & \dots & 1 \\ \omega^{-(k-1)} & \dots & \omega^{-(n-1)} & \omega^{-n} & \omega^{-(n+1)} & \dots & \omega^{-(n+k-2)} \\ \omega^{-2(k-1)} & \dots & \omega^{-2(n-1)} & \omega^{-2n} & \omega^{-2(n+1)} & \dots & \omega^{-2(n+k-2)} \\ \vdots & & \vdots & \vdots & \vdots & & \vdots \\ \omega^{-(n-1)(k-1)} & \dots & \omega^{-(n-1)(n-1)} & \omega^{-(n-1)n} & \omega^{-(n-1)(n+1)} & \dots & \omega^{-(n-1)(n+k-2)} \end{bmatrix}.$$

The column

$$(1, \omega^{-n}, \omega^{-2n}, \dots, \omega^{-(n-1)n})$$

on the right-hand side is column $n - k + 2$ of this matrix.

Comparing the expressions for WS^{k-1} and $\mathbf{diag}(We_k)W$, we see that the two matrices are equal because $\omega^{-n} = 1$.

(b) Column k of $T(a)$ is

$$\begin{aligned} S^{k-1}a &= \frac{1}{n} W^H \mathbf{diag}(We_k)Wa \\ &= \frac{1}{n} W^H ((We_k) \circ (Wa)) \\ &= \frac{1}{n} W^H \mathbf{diag}(Wa)We_k. \end{aligned}$$

On the second line we use $u \circ v$ to denote the componentwise vector product (lecture 1, page 1.13). Therefore

$$\begin{aligned} T(a) &= \begin{bmatrix} a & Sa & S^2a & \dots & S^{n-1}a \end{bmatrix} \\ &= \frac{1}{n} W^H \mathbf{diag}(Wa) \begin{bmatrix} We_1 & We_2 & We_3 & \dots & We_n \end{bmatrix} \\ &= \frac{1}{n} W^H \mathbf{diag}(Wa)W. \end{aligned}$$

(c) To evaluate

$$\begin{aligned} T(a)x &= \frac{1}{n} W^H \mathbf{diag}(Wa)W \\ &= W^{-1} ((Wa) \circ (Wx)), \end{aligned}$$

we compute the discrete Fourier transforms Wa and Wx of the vectors a and x , multiply them componentwise to get $y = (Wa) \circ (Wx)$ and take the inverse DFT $W^{-1}y$ of y . This requires two DFTs, one inverse DFT, and a componentwise product of length n . The complexity is order $n \log n$. In MATLAB or Julia, this is implemented as: `ifft(fft(a) .* fft(x))`.

- (d) The factorization of $T(a)$ show that $T(a)$ is nonsingular if and only if the elements of Wa are nonzero. The inverse of $T(a)$ is

$$T(a)^{-1} = W^{-1} \mathbf{diag}(Wa)^{-1} W.$$

We can therefore evaluate $T(a)^{-1}b = W^{-1} \mathbf{diag}(Wa)^{-1}Wb$ by computing the DFTs Wa and Wb of a and b , then dividing Wb componentwise by Wa , and computing the inverse DFT of the result. In MATLAB notation:

```
x = ifft( fft(b) ./ fft(a)).
```

We test this algorithm in MATLAB for $n = 10000$.

```
>> n = 10000; a = randn(n,1); b = randn(n,1);
>> A = toeplitz(a, [a(1), flipud(a(2:n))']);
>> % solve using standard method
>> tic, x1 = A\b; toc
Elapsed time is 9.560306 seconds.
>> % solve using fast method
>> tic, x2 = ifft( fft(b) ./ fft(a)); toc
Elapsed time is 0.000545 seconds.
>> % compare the results
>> norm(x1-x2)
ans =
1.7278e-12
```

The results in Julia are similar.

```
julia> using FFTW
julia> n = 10000; a = randn(n,1); b = randn(n,1);
julia> A = hcat( [ circshift(a,k) for k = 0:n-1 ]... );
julia> @time x1 = A\b;
9.421464 seconds (11 allocations: 763.092 MiB, 0.91% gc time)
julia> @time x2 = ifft( fft(b) ./ fft(a));
0.000934 seconds (206 allocations: 948.656 KiB)
julia> norm(x1-x2)
2.0815737580478035e-12
```

4. Exercise A6.13.

- (a) We verify that $A^T A = I$.

$$\begin{aligned} A^T A &= \begin{bmatrix} aa^T & I - aa^T \\ I - aa^T & aa^T \end{bmatrix} \begin{bmatrix} aa^T & I - aa^T \\ I - aa^T & aa^T \end{bmatrix} \\ &= \begin{bmatrix} aa^T aa^T + I - 2aa^T + aa^T aa^T & 2(aa^T - aa^T aa^T) \\ 2(aa^T - aa^T aa^T) & I - 2aa^T + aa^T aa^T + aa^T aa^T \end{bmatrix} \end{aligned}$$

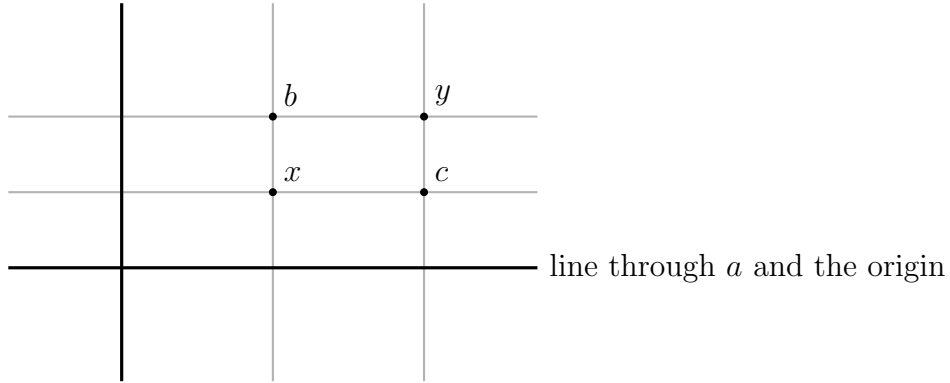
$$\begin{aligned}
&= \begin{bmatrix} aa^T + I - 2aa^T + aa^T & 2(aa^T - aa^T) \\ 2(aa^T - aa^T) & I - 2aa^T + aa^T + aa^T \end{bmatrix} \\
&= \begin{bmatrix} I & 0 \\ 0 & I \end{bmatrix}.
\end{aligned}$$

The simplifications on line 3 follow because $a^T a = 1$.

(b) Since $A^{-1} = A$, the solution is

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} aa^T & I - aa^T \\ I - aa^T & aa^T \end{bmatrix} \begin{bmatrix} b \\ c \end{bmatrix} = \begin{bmatrix} aa^T b + (I - aa^T)c \\ (I - aa^T)b + (aa^T)c \end{bmatrix}$$

The vectors $aa^T b$ and $aa^T c$ are the projections of b and c on the line through a on the origin. The vectors $(I - aa^T)b$ and $(I - aa^T)c$ are the projections on the line orthogonal to a .



5. *Exercise A6.16.* This follows from $Q = AR^{-1}$ and the fact that R^{-1} is upper triangular. Therefore the k th column of Q is a linear combination of the first k columns of A .
6. *Exercise A7.5.* We evaluate the expression as $x = b + y + v + w$ where

$$y = A^{-1}b, \quad v = A^{-2}b = A^{-1}y, \quad w = A^{-3}c = A^{-1}v.$$

- (a) LU factorization $A = PLU$ ($(2/3)n^3$ flops).
- (b) Calculate $y = A^{-1}b$ by solving $PLUy = b$.
 - i. Calculate $\tilde{v} = P^T b$ (0 flops, because $P^T b$ is a permutation of b).
 - ii. Solve $L\tilde{w} = \tilde{v}$ by forward substitution (n^2 flops).
 - iii. Solve $Uy = \tilde{w}$ by backward substitution (n^2 flops).
- (c) Calculate $v = A^{-2}b = A^{-1}y$ by solving $PLUv = y$ ($2n^2$).
- (d) Calculate $w = A^{-3}b = A^{-1}v$ by solving $PLUw = v$ ($2n^2$).
- (e) $x = b + y + v + w$ ($3n$).

Total: $(2/3)n^3 + 6n^2 + 3n$.

7. Exercise A7.30.

- (a) Define $u = A^{-1}c$. The coefficients of u express c as a linear combination of the columns of A :

$$c = Au = \sum_{j=1}^n u_j a_j.$$

If $u_i = (A^{-1}c)_i = 0$, then the vector a_i does not appear in this sum, and we can write it as

$$0 = \sum_{j=1}^{i-1} u_j a_j - c + \sum_{j=i+1}^n u_j a_j = \tilde{A}x$$

with $x_i = -1$ and $x_j = u_j$ for $j \neq i$. This proves that the columns of \tilde{A} are linearly dependent.

Alternatively, multiplying \tilde{A} on the left with A^{-1} gives the matrix

$$A^{-1}\tilde{A} = I + (A^{-1}c - e_i)e_i^T = (I - e_i e_i^T) + A^{-1}c e_i^T.$$

This is the identity matrix with its i th column replaced by $A^{-1}c$. Since $(A^{-1}c)_i = 0$, the matrix $A^{-1}\tilde{A}$ has a zero i th row, and therefore is singular. If $A^{-1}\tilde{A}$ is singular, then \tilde{A} is singular.

- (b) We multiply \tilde{A} with the proposed inverse, and verify that the product is the identity matrix.

$$\begin{aligned} & (A + (c - a_i)e_i^T)(A^{-1} - \frac{1}{e_i^T A^{-1}c}(A^{-1}c - e_i)e_i^T A^{-1}) \\ &= I + (c - a_i)e_i^T A^{-1} - \frac{1}{e_i^T A^{-1}c}(c - a_i)e_i^T A^{-1} - \frac{(e_i^T A^{-1}c - 1)}{e_i^T A^{-1}c}(c - a_i)e_i^T A^{-1} \\ &= I + (1 - \frac{1}{e_i^T A^{-1}c} - (1 - \frac{1}{e_i^T A^{-1}c}))(c - a_i)e_i^T A^{-1} \\ &= I. \end{aligned}$$

- (c) From the expression in part (b),

$$\tilde{A}^{-1}b = A^{-1}b - \frac{(A^{-1}b)_i}{(A^{-1}c)_i}(A^{-1}c - e_i).$$

This shows we need $x = A^{-1}b$ and $z = A^{-1}c$, and a few vector operations.

- LU factorization $A = PLU$. $(2/3)n^3$ flops.
- Solve $PLUx = b$ by forward and backward substitution. $2n^2$ flops.
- Solve $PLUz = c$ by forward and backward substitution. $2n^2$ flops.
- Compute $\alpha = x_i/z_i$. 1 flop.
- Compute $y = x - \alpha(z - e_i)$. $2n + 1$ flops.

The total is $(2/3)n^3$ plus lower order terms.