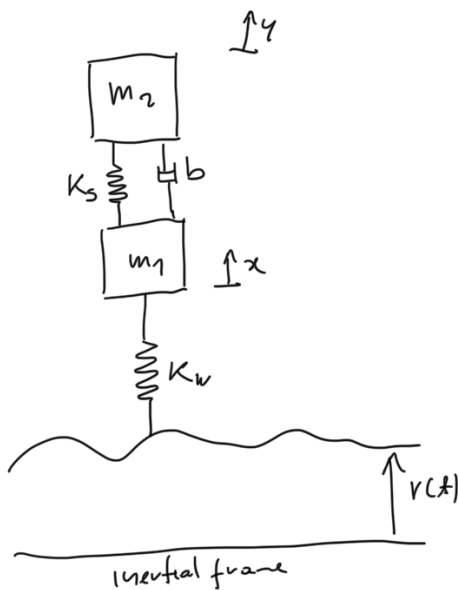
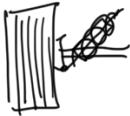
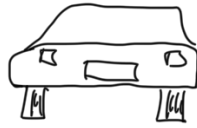


ECE 141
Lecture 1



$$m_2 \ddot{y} = \overbrace{-b(\dot{y} - \dot{x})}^{\text{damper}} - \overbrace{K_S(y - x)}^{\text{spring}}$$

$$m_1 \ddot{x} = -b(\dot{x} - \dot{y}) - K_S(x - y) - K_W(x - v)$$

$$\mathcal{L}\{m_2 \ddot{y}\} = \mathcal{L}\{-b(\dot{y} - \dot{x}) - K_S(y - x)\}$$

Review of Laplace transform

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$\mathcal{L}\{f\} = F(s) = \int_{0^-}^{\infty} f(t) e^{-st} dt$$

$$s = \sigma + j\omega$$

One sided Laplace transform

Step function

$$u(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$1(t)$ book's notation

$$\begin{aligned}
 \mathcal{L}\{u\} &= \int_{0^-}^{\infty} u(t) e^{-st} dt = \int_{0^-}^{\infty} e^{-st} dt = \left. \frac{e^{-st}}{-s} \right|_{0^-}^{\infty} \\
 &= \lim_{t \rightarrow +\infty} \frac{e^{-st}}{-s} - \lim_{t \rightarrow 0^-} \frac{e^{-st}}{-s} = 0 - \left(-\frac{1}{s} \right) = \frac{1}{s}
 \end{aligned}$$

when $\sigma > 0$, 0

Impulse function

$\delta(t)$ defined by the sifting property: $\int_{-\infty}^{+\infty} f(t) \delta(t-\tau) dt = f(\tau)$

$$\mathcal{L}\{\delta\} = \int_{0^-}^{+\infty} \delta(t) e^{-st} dt = e^{-s \cdot 0} = 1$$

Properties of Laplace function

Superposition

$$\begin{aligned}
 \mathcal{L}\{\alpha f(t) + \beta g(t)\} &= \alpha \mathcal{L}\{f(t)\} + \beta \mathcal{L}\{g(t)\} \\
 &= \alpha F(s) + \beta G(s), \quad \forall \alpha, \beta \in \mathbb{R}
 \end{aligned}$$

Time-delay

$$\mathcal{L}\{f(t-\tau)\} = e^{-s\tau} \mathcal{L}\{f(t)\} = e^{-s\tau} F(s)$$

Time-scaling

$$\mathcal{L}\{f(at)\} = \frac{1}{|a|} F\left(\frac{s}{a}\right)$$

Shifts in the s-domain

$$\mathcal{L}\{f(t)\} = F(s)$$

$$\mathcal{L}\{?\} = F(s+a)$$

$$\mathcal{L}\{e^{-at}f(t)\} = F(s+a)$$

Differentiation

$$\mathcal{L}\left\{\frac{df}{dt}\right\} = sF(s) - f(0^-)$$

$$\mathcal{L}\left\{\frac{d^2f}{dt^2}\right\} = ? \quad g \stackrel{\text{def}}{=} \frac{df}{dt} \Rightarrow \frac{d^2f}{dt^2} = \frac{dg}{dt}$$

$$\begin{aligned} \mathcal{L}\left\{\frac{dg}{dt}\right\} &= sG(s) - g(0^-) \\ &= sG(s) - \frac{df}{dt}(0^-) \end{aligned}$$

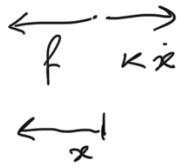
$$\downarrow$$
$$\mathcal{L}\{g(t)\} = \mathcal{L}\left\{\frac{df}{dt}\right\} = sF(s) - f(0^-)$$

$$\mathcal{L}\left\{\frac{d^2g}{dt^2}\right\} = s^2F(s) - sf(0^-) - \frac{df}{dt}(0^-)$$

$$\begin{aligned} \mathcal{L}\left\{\frac{d^m f}{dt^m}\right\} &= s^m F(s) - s^{m-1}f(0^-) - s^{m-2}\frac{df}{dt}(0^-) - \dots \\ &\quad - \frac{d^{m-1}f}{dt^{m-1}}(0^-) \end{aligned}$$

Integration

$$\mathcal{L}\left\{\int_0^t f(\tau) d\tau\right\} = \frac{1}{s}F(s)$$



$$m\ddot{x} = f - kx$$

$$\ddot{x} = \frac{1}{m}f - \frac{k}{m}x$$

$$\mathcal{L}\{\ddot{x}\} = \mathcal{L}\left\{\frac{1}{m}f - \frac{k}{m}x\right\}$$

$$s^2 X(s) = \frac{1}{m}F(s) - \frac{k}{m}X(s)s \quad (\text{assuming } x(0) = 0)$$

$$X(s)\left[s^2 + \frac{k}{m}s\right] = \frac{1}{m}F(s)$$

$$X(s) = \frac{1/m}{s^2 + s\frac{k}{m}} F(s)$$

$$x(t) = \mathcal{L}^{-1}\{X(s)\} = \mathcal{L}^{-1}\left\{\frac{1/m}{s^2 + s\frac{k}{m}} F(s)\right\}$$

Inverse Laplace transform

$$H(s) = \frac{b_1 s^m + b_2 s^{m-1} + \dots + b_{m+1}}{\underbrace{s^n + a_1 s^{n-1} + \dots + a_n}_{\text{monic polynomial}}}$$

Zeros
poles
roots

$m \leq n$ proper transfer function
 $m < n$ strictly proper

always the case
for physical systems

$$H(s) = K \frac{\prod_{i=1}^m (s - z_i)}{\prod_{i=1}^n (s - p_i)}$$

$$H(s) = \frac{C_1}{s - p_1} + \frac{C_2}{s - p_2} + \dots + \frac{C_n}{s - p_n}$$

partial fraction expansion

$$\mathcal{L}^{-1}\{H(s)\} = C_1 \underbrace{\mathcal{L}^{-1}\left\{\frac{1}{s - p_1}\right\}} + C_2 \mathcal{L}^{-1}\left\{\frac{1}{s - p_2}\right\} + \dots + C_n \mathcal{L}^{-1}\left\{\frac{1}{s - p_n}\right\}$$

$$\mathcal{L}^{-1} \{ \sum_{k=1}^n \frac{P_k}{Q(s)} \}$$

$$= C_1 \mathcal{L}^{-1} \left\{ \frac{P_1}{Q(s)} \right\} + C_2 \mathcal{L}^{-1} \left\{ \frac{P_2}{Q(s)} \right\} + \dots + C_n \mathcal{L}^{-1} \left\{ \frac{P_n}{Q(s)} \right\}$$

$$Y(s) = \frac{s+1}{s(s+2)} = \frac{C_1}{s} + \frac{C_2}{s+2}$$

$$\frac{s+1}{s+2} = C_1 + \frac{C_2 s}{s+2}$$

$$\text{for } s=0 \quad \frac{1}{2} = C_1$$

$$\frac{s+1}{s} = \frac{s+2}{s} C_1 + C_2$$

$$\text{for } s=-2 \quad \frac{-1}{-2} = C_2$$

$$C_2 = (s+2) Y(s) \Big|_{s=-2}$$

$$C_1 = s Y(s) \Big|_{s=0}$$

$$Y(s) = \frac{1/2}{s} + \frac{1/2}{s+2} \Rightarrow \mathcal{L}^{-1} \{ Y(s) \} = \frac{1}{2} \mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} + \frac{1}{2} \mathcal{L}^{-1} \left\{ \frac{1}{s+2} \right\}$$

Back to example

$$x(t) = \mathcal{L}^{-1} \left\{ \frac{1/m}{s^2 + s \frac{k}{m}} F(s) \right\}$$

Assume $f(t) = C \delta(t)$

$$F(s) = C$$

$$\mathcal{L}^{-1} \left\{ \frac{c/m}{\underbrace{s^2 + s \frac{k}{m}}_{s(s + \frac{k}{m})}} \right\} = \mathcal{L}^{-1} \left\{ \frac{c_1}{s} \right\} + \mathcal{L}^{-1} \left\{ \frac{c_2}{s + \frac{k}{m}} \right\}$$

$$c_1 = s X(s) \Big|_{s=0} = \frac{c/m}{k/m} = \frac{c}{k}$$

$$c_2 = (s + \frac{k}{m}) X(s) \Big|_{s = -\frac{k}{m}} = \frac{c/m}{-\frac{k}{m}} = -\frac{c}{k}$$

$$x(t) = \underbrace{\frac{c}{k}}_{\frac{c}{k} e^{0t}} e^{0t} - \frac{c}{k} e^{-\frac{k}{m}t} e^{0t}$$

$$\lim_{t \rightarrow \infty} x(t) = \frac{c}{k} //$$

How to compute this limit without computing \mathcal{L}^{-1} ?

Final Value Theorem

If all the poles of $sY(s)$ are on the left half of the s -plane, then:

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sY(s)$$

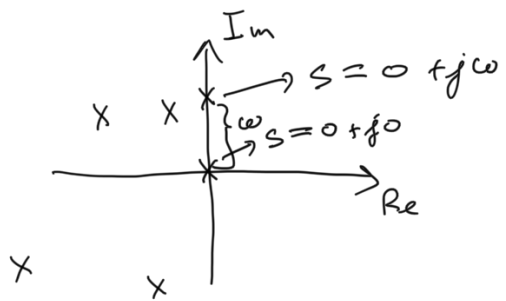
$$Y(s) = X(s) = \frac{c/m}{s(s + k/m)}$$

$$sX(s) = \frac{c/m}{s + \frac{k}{m}}$$

$$p = -\frac{k}{m}$$

$$\dots \quad c/m \quad \dots \quad p \neq 0$$

$$\lim_{s \rightarrow 0} s X(s) = \lim_{s \rightarrow 0} \frac{1}{s + \frac{k}{m}} = \frac{1}{\frac{k}{m}} = \frac{m}{k}$$



$$s = j\omega$$

$$= -j\omega$$

$$\sin(\omega t)$$

