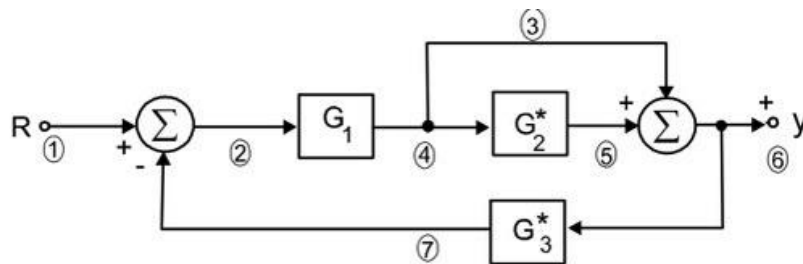


HOMEWORK 2 Solutions

3.21 a)



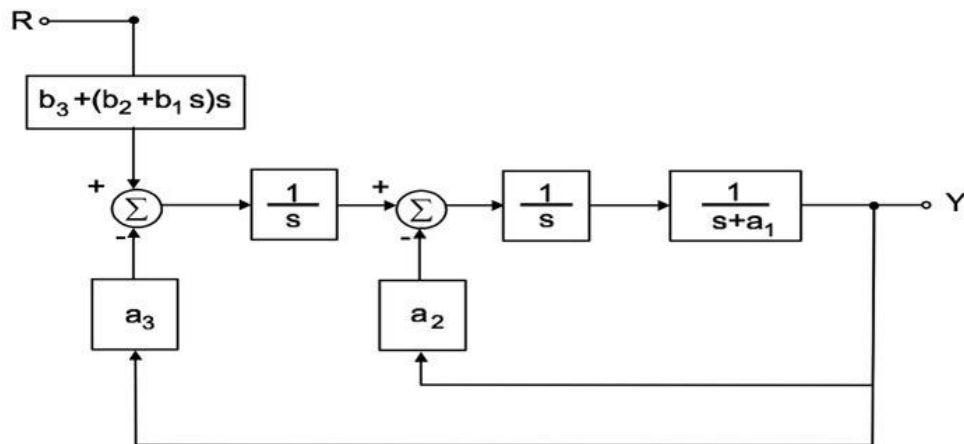
$$G_2^* = \frac{G_2}{1 - G_2 H_2}$$

$$G_3^* = \frac{G_3}{1 - G_3 H_3}$$

$$\frac{Y}{R} = \frac{G_1(1 + G_2^*)}{1 + G_1(1 + G_2^*)G_3^*} = \frac{G_1(1 - G_2 H_2)(1 - G_3 H_3) + G_1 G_2(1 - G_3 H_3)}{1 + (1 - G_2 H_2)(1 - G_3 H_3) + G_1 G_3(1 - G_2 H_2) + G_1 G_2 G_3}.$$

b)

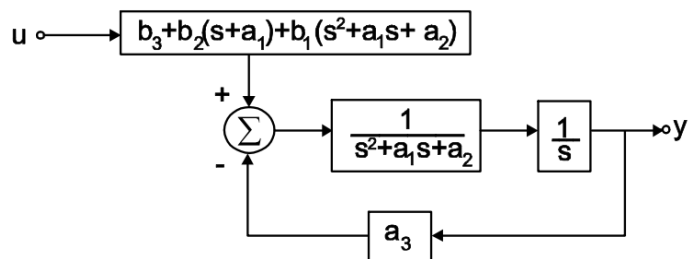
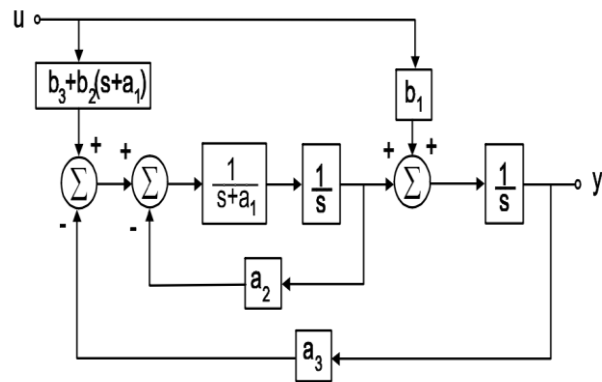
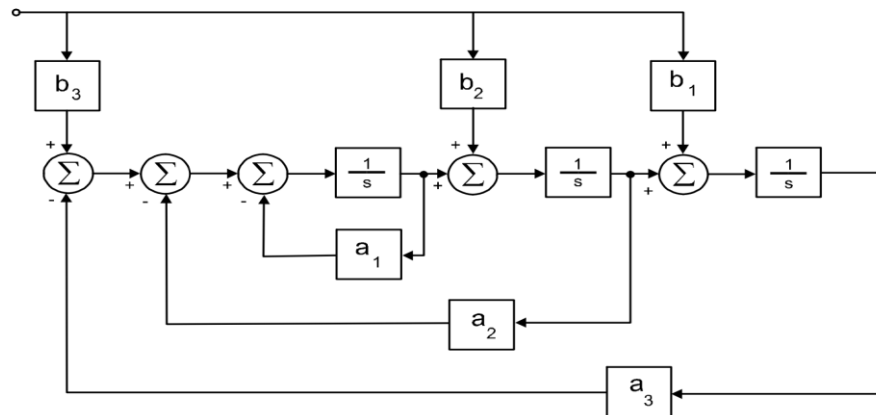
We move the summer on the right past the integrator to get $b_1 s$ and repeat to get $(b_2 + b_1 s)s$. Meanwhile we apply the feedback rule to the first inner loop to get $\frac{1}{s+a_1}$ as shown in the figure and repeat for the second and third loops to get:



$$\frac{Y}{R} = \frac{b_1 s^2 + b_2 s + b_3}{s^3 + a_1 s^2 + a_2 s + a_3}.$$

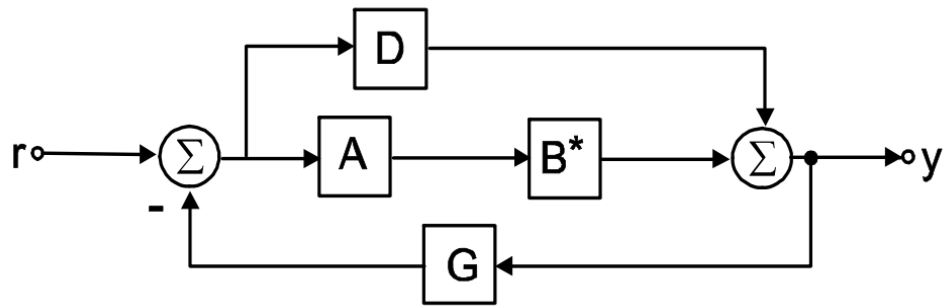
c)

Applying block diagram reduction: reduce innermost loop, shift b_2 to the b_3 node, reduce next innermost loop and continue systematically to obtain:



$$\frac{Y}{R} = \frac{b_1 s^2 + (a_1 b_1 + b_2) s + a_1 b_2 + a_2 b_1 + b_3}{s^3 + a_1 s^2 + a_2 s + a_3}.$$

d)



$$B^* = \frac{B}{1+BH}$$

$$\frac{Y}{R} = \frac{D + AB^*}{1 + G(D + AB^*)} = \frac{D + DBH + AB}{1 + BH + GD + GBDH + GAB}.$$

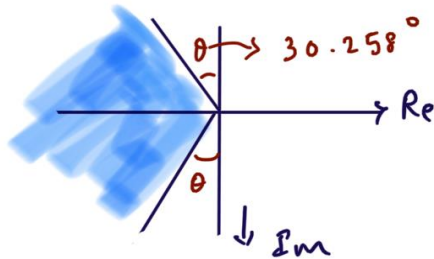
3.30) a)

(a) Overshoot $M_p = e^{-\pi \xi / \sqrt{1-\xi^2}}$

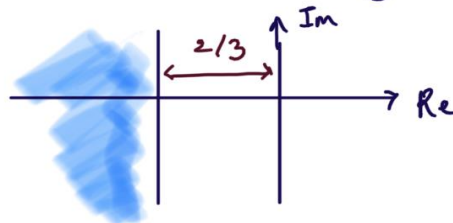
$$\Rightarrow \xi \leq \sqrt{\frac{\ln(M_p)^2}{\pi^2 + \ln(M_p)^2}} \quad \text{where } M_p = 0.16$$

$$\leq \sqrt{\frac{\ln(0.16)^2}{\pi^2 + \ln(0.16)^2}} \simeq 0.5039$$

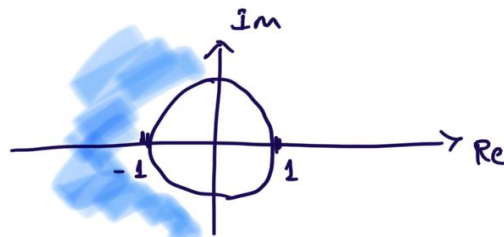
$$\therefore \theta = \sin^{-1}(0.5039) = 30.258^\circ$$



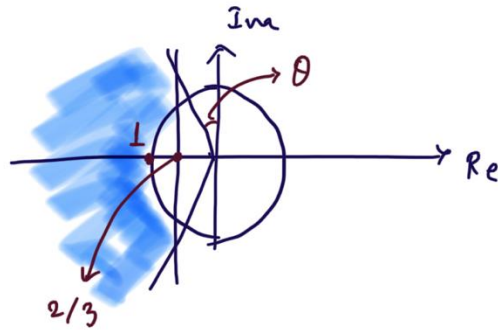
Settling time $t_s = \frac{4.6}{\delta} \leq 6.9 \text{ s} \Rightarrow \delta \geq 2/3$



Rising time $t_r = \frac{1.8}{\omega_n} \leq 1.8 \text{ s} \rightarrow \omega_n \geq 1$



\therefore Region of acceptable closed-loop poles
in the s-plane



b)

(b) $M_p = ?$

Given: $t_r = 1.8 \text{ s}$

$t_s = 6.9 \text{ s}$

$\Rightarrow \delta = 2/3 \quad \text{and} \quad \omega_n = 1$

$t_s = 4.6 / \xi \omega_n$

$6.9 = 4.6 / \xi (1) \Rightarrow \xi = 2/3$

$M_p = e^{-\pi \xi / \sqrt{1-\xi^2}}$

$= e^{-\pi (2/3) / \sqrt{1-(2/3)^2}}$

$M_p = 0.0602$

3.32)

(a)

$$T(s) = \frac{Y(s)}{R(s)} = \frac{G(s)}{1 + G(s)} = \frac{K}{s^2 + 2s + K} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

Equate the coefficients:

$$\begin{aligned} 2 &= 2\zeta\omega_n \quad (*) \\ K &= \omega_n^2 \\ \Rightarrow \omega_n &= \sqrt{K} \quad \zeta = \frac{1}{\sqrt{K}} \end{aligned}$$

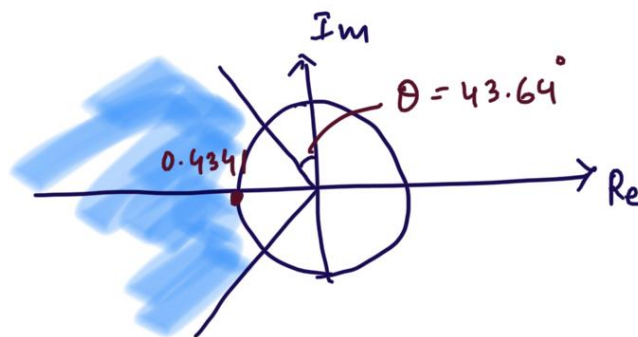
We would need:

$$\begin{aligned} \frac{M_p\%}{100} &= 0.05 = e^{\frac{-\pi\zeta}{\sqrt{1-\zeta^2}}} \quad \Rightarrow \quad \zeta = 0.69 \\ t_p = 1 \text{ sec} &= \frac{\pi}{\omega_d} = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}} \quad \Rightarrow \quad \omega_n = 4.34 \end{aligned}$$

But the combination ($\zeta = 0.69$, $\omega_n = 4.34$) that we need is not possible by varying K alone. Observe that from equations (*) $\zeta\omega_n = 1 \neq 0.69 \times 4.34$

b)

Associated region in s-plane:



b) Let $M_p = 0.05 \tau$ where τ is the
 $t_p = (1 \text{ sec}) \tau$ relaxation factor

$$M_p = e^{-\pi \xi / \sqrt{1-\xi^2}} = 0.05 \tau \quad \dots (i)$$

$$t_p = \pi / \omega_d = \pi / \omega_n \sqrt{1-\xi^2} = \tau \quad \dots (ii)$$

$$\Rightarrow \frac{\pi}{\sqrt{1-\xi^2}} = \tau \omega_n$$

$$e^{-\tau \omega_n \xi} = 0.05 \tau$$

$$\text{where } \omega_n = 4.3410$$

$$\xi = 0.6901$$

$$\Rightarrow \tau = 2.205$$

$$\text{Let } d(s) = s^2 + 2s + \omega_n^2$$

$$\left\{ \begin{array}{l} 2 = 2 \xi \omega_n \rightarrow \xi \omega_n = 1 \Rightarrow \omega_n = 1/\xi \\ \omega_n^2 = \kappa \Rightarrow \kappa = 1/\xi^2 \end{array} \right\} \rightarrow \xi = 1/\sqrt{\kappa} \quad \dots (iii)$$

$$(i) \text{ and } (iii) \Rightarrow e^{-\pi/\kappa / \sqrt{1-1/\kappa}} = 0.05 \tau$$

$$e^{-\pi/\sqrt{\kappa-1}} = 0.05 \tau$$

$$-\pi/\sqrt{\kappa-1} = \ln(0.05 \tau)$$

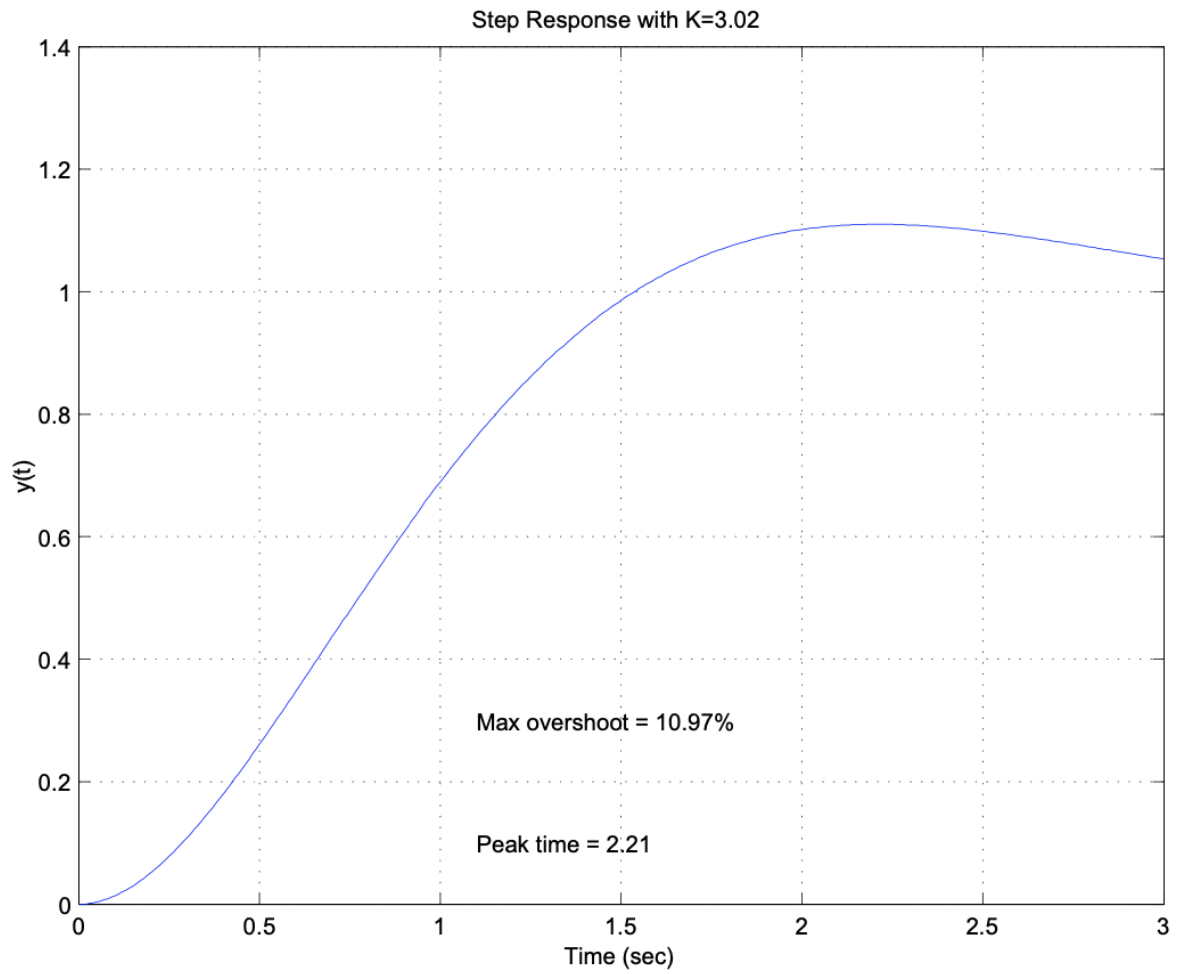
$$\boxed{\kappa = 3.303}$$

$$(i) \Rightarrow M_p = 0.05 \tau = 0.05(2.205) = 0.11025$$

$$(ii) \Rightarrow t_p = \tau = 2.205 \text{ sec}$$

c)

```
K = 3.02;
num = [K];
den = [1, 2, K];
sys = tf(num,den);
t = 0:0.01:3;
y = step(sys,t);
plot(t,y);
yss = dcgain(sys);
Mp = (max(y) - yss)*100;
% Finding maximum overshoot
msg_overshoot = sprintf('Max overshoot = %3.2f%%', Mp);
% Finding peak time
idx = max(find(y == (max(y)))));
tp = t(idx);
msg_peaktime = sprintf('Peak time = %3.2f', tp);
xlabel('Time (sec)');
ylabel('y(t)');
msg_title = sprintf('Step Response with K = %3.2f',K);
title(msg_title);
text(1.1, 0.3, msg_overshoot);
text(1.1, 0.1, msg_peaktime);
grid on;
```



Closed-loop step response

3.36)

$$J\ddot{\theta} + B\dot{\theta} = T_c$$

(a)

$$\begin{aligned} J\Theta s^2 + B\Theta s &= T_c(s) \\ \frac{\Theta(s)}{T_c(s)} &= \frac{1}{Js + B} \\ J &= 600,000 \text{ kg} \cdot \text{m}^2 \\ B &= 20,000 \text{ N} \cdot \text{m} \cdot \text{sec} \\ \frac{\Theta(s)}{T_c(s)} &= \frac{1.667 \times 10^{-6}}{s(s + \frac{1}{30})} \end{aligned}$$

(b)

$$\begin{aligned} \Theta(s) &= \frac{1.667 \times 10^{-6} K (\Theta_r - \Theta)}{s(s + \frac{1}{30})} \\ \frac{\Theta(s)}{\Theta_r(s)} &= \frac{1.667 K \times 10^{-6}}{s^2 + \frac{1}{30}s + 1.667 K \times 10^{-6}} \end{aligned}$$

(c)

$$\begin{aligned} M_p &= e^{-\pi\zeta/\sqrt{1-\zeta^2}} = 0.1 \quad (10\%) \\ \zeta &= 0.591 \\ Y(s) &= \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} \\ 2\zeta\omega_n &= \frac{1}{30} \\ \omega_n &= \frac{\frac{1}{30}}{2(0.591)} = 0.0282 \text{ rads/sec} \\ \omega_n^2 &= 1.667 K \times 10^{-6} \\ K &< 477 \end{aligned}$$

(d)

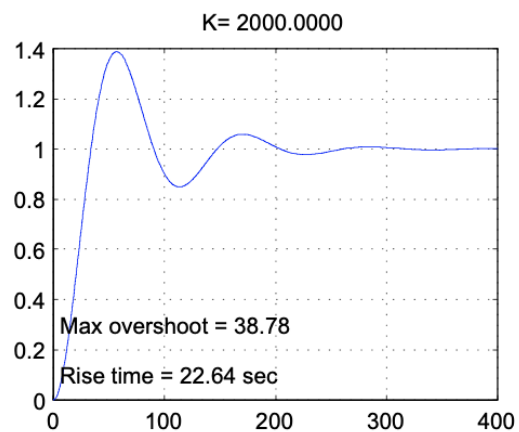
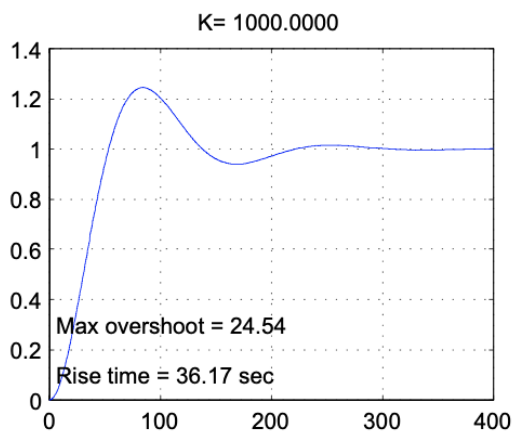
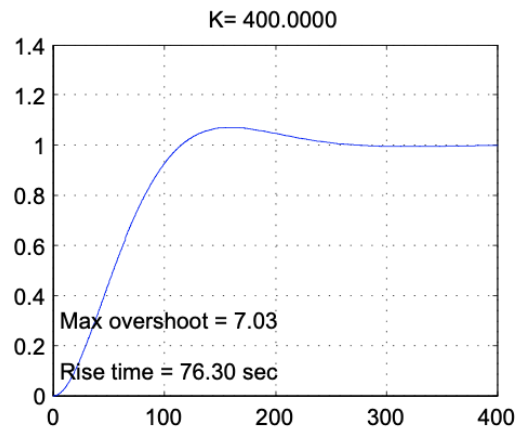
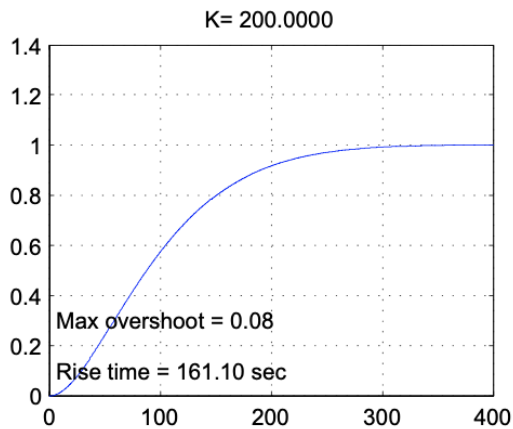
$$\omega_n \geq \frac{1.8}{t_r}$$

$$\omega_n^2 = 1.667K \times 10^{-6}$$

$$K \geq 304$$

(e)

Step Responses:



The results compare favorably with the predictions made in parts c and d. For $K < 477$, the overshoot was less than 10 and the rise time was less than 80 seconds.