FIRST PROJECT DAY IN LAB

- 1. Start with no batteries in RSLK.
- 2. Download Basic Code from CCLE, under Week 4.
- 3. Launch Energia.
- 4. Tools | Board | Boards Manager, scroll down to Energia MSP432 EMT RED boards. Check version #; should be 5.6.3 and have "INSTALLED" next to the version number.
- 5. insert USB cable, check for green LED.
- 6. Remove USB cable.
- 7. Insert batteries.
- 8. Push slide switch to ON, check for both blue and green LEDs.
- 9. Push slide switch to OFF, then depress pushbutton switch. Both LEDs should turn off.
- 10. insert USB cable.
- 11. File | Examples | 01.Basics | Blink
- 12. Click on right-facing arrow in upper left corner of window.
- 13. Blinky should compile and load successfully, red LED should start blinking.
- 14. In lines 28 & 30, change the numbers in the arguments to delay().
- 15. Click on right-facing arrow in upper left corner of window.
- 16. The red LED should blink at a different rate.
- 17. Push slide switch to ON, check for both blue and green LEDs.
- 18. Download Basic Code from CCLE, under Week 4, store in some appropriate place.
- 19. In Energia, File | New; Paste Basic Code into the sketch.
- 20. Pick up the RSLK, click on the right-pointing arrow. One wheel should turn, one yellow LED on right front of Chassis Board should flash.
- 21. Power down the Chassis Board. Download the MSP432 Pinchart on CCLE, under Week 4.
- 22. Modify the Basic Code to make the RSLK do a doughnut.
- 23. Modify the code to make the car run straight on the floor.
- 24. Download ECE3 from CCLE, under Week 1. Do NOT unzip the zip file.
- 25. Sketch | Include Library | Add. ZIP Library... navigate to ECE3.zip and select.
- 26. Sketch | Include Library; ECE3 Library should appear on pulldown list
- 27. ~/Documents/Energia/libraries/ECE3/examples/IR_Sensor_Example; double-click IR Sensor Example.ino
- 28. Power up the Chassis Board.
- 29. Compile and download to the RSLK.
- 30. Tools | Serial Monitor should show 8 columns of numbers from ~500 to ~2000, depending on amount of reflection from surface.

Class Project Basics:

(2)

(1) Pins, Inputs and Outputs:

```
//#include <ECE3_LCD7.h>
uint16_t sensorValues[8]; // right -> left, 0 -> 7
const int left_nslp_pin=31;
const int left_dir_pin=29;
const int left_pwm_pin=40;
const int LED_RF = 41;
void setup() {
// put your setup code here, to run once:
 pinMode(left_nslp_pin,OUTPUT);
 pinMode(left_dir_pin,OUTPUT);
 pinMode(left_pwm_pin,OUTPUT);
 digitalWrite(left_dir_pin,LOW);
 digitalWrite(left_nslp_pin,HIGH);
 pinMode(LED_RF, OUTPUT);
// ECE3_Init();
```

// set the data rate in bits/second for serial data transmission

Basic Energia Coding Scheme:

```
Serial.begin(9600);
 delay(2000); //Wait 2 seconds before starting
void loop() {
 // put your main code here, to run repeatedly:
 int leftSpd = 70;
// ECE3_read_IR(sensorValues);
 analogWrite(left_pwm_pin,leftSpd);
// ECE3_read_IR(sensorValues);
 digitalWrite(LED_RF, HIGH);
 delay(250);
 digitalWrite(LED_RF, LOW);
 delay(250);
(3)
      Important Functions:
      pinMode ( pin_number, OUTPUT/INPUT )
      digitalWrite ( pin_number, HIGH/LOW )
```

	analogWrite (pin_number,	integer between 0-255)
(4)	Important Pins for Motor Control:			
	Non-sleep pins	::		
	Direction pins:			
	PWM pins:			