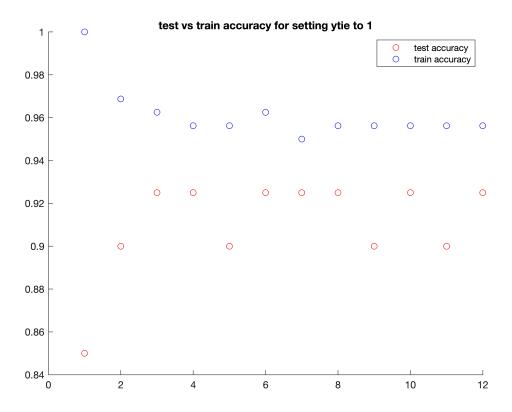
PROBLEM 1 ON HW 4

```
close all;
stat30 = readtable("UCLA_EE_grad_2030.csv");
stat31 = readtable("UCLA_EE_grad_2031.csv");
data = [stat30; stat31];
tes = table2array(data(1:40,:));
tra = table2array(data(41:end,:));
```

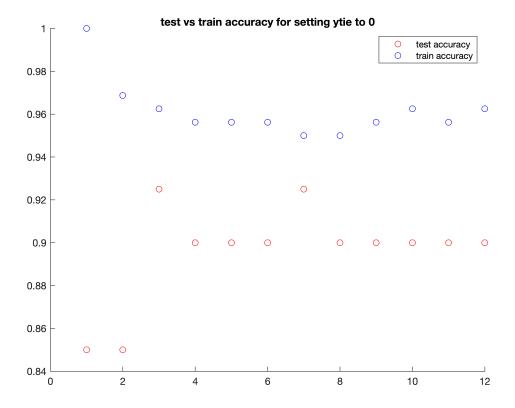
(a) $y_{tie} = 1$: implement k-NN algorithm and plot the training/testing accuracy for k = 1, 2, ...12.

```
testacc = zeros(2, 12);
traiacc = zeros(2, 12);
for k = 1:12
    testyay = [0;0];
    traiyay = [0;0];
    for i = 1:40
        d = sortrows([(tra(:,1)-tes(i,1)).^2+(tra(:,2)-tes(i,2)).^2 tra(:,3)]);
        y1 = sum(d(1:k,2));
        y2 = y1;
        if y1==0, y1 = 1; end
        if y2==0, y2 = -1; end
        y1 = y1 / abs(y1);
        y2 = y2 / abs(y2);
        if y1 == tes(i, 3)
            testyay(1) = testyay(1) + 1;
        end
        if y2 == tes(i, 3)
            testyay(2) = testyay(2) + 1;
        end
    end
    for i = 1:160
        d = sortrows([(tra(:,1)-tra(i,1)).^2+(tra(:,2)-tra(i,2)).^2 tra(:,3)]);
        y1 = sum(d(1:k,2));
        y2 = y1;
        if y1==0, y1 = 1; end
        if y2==0, y2 = -1; end
        y1 = y1 / abs(y1);
        y2 = y2 / abs(y2);
        if y1 == tra(i, 3)
            traiyay(1) = traiyay(1) + 1;
        end
        if y2 == tra(i, 3)
            traiyay(2) = traiyay(2) + 1;
        end
    testacc(1,k) = testyay(1) / 40;
    testacc(2,k) = testyay(2) / 40;
    traiacc(1,k) = traiyay(1) / 160;
    traiacc(2,k) = traiyay(2) / 160;
end
figure(1);
hold on;
```

```
scatter((1:1:12), testacc(1,:)', 'red');
scatter((1:1:12), traiacc(1,:)', 'blue');
legend('test accuracy', 'train accuracy');
title('test vs train accuracy for setting ytie to 1');
```



```
figure(2);
hold on;
scatter((1:1:12), testacc(2,:)', 'red');
scatter((1:1:12), traiacc(2,:)', 'blue');
legend('test accuracy', 'train accuracy');
title('test vs train accuracy for setting ytie to 0')
```



(c) The accuracy against training and testing data is actually fairly good! As k increases the training accuracy drops quite a bit in the beginning but levels out at around 0.96 or 96%. As k increases the testing data accuracy increases by quite a lot in the beginning but levels out at around 0.9 or 90%. A larger k shouldn't make a big difference after 3 or 4. Looking at the graph for ytie = 1 an interesting pattern results. When k is even, the accuracy is noticeably higher than when k is odd. For the ytie = 0 though it doesn't really make a difference. Odd and even make a big difference, though, because when the two classes appear equally. Deciding comes down to your choice. They aren't contradictory to each other. It seems that when ytie is set to 0, even values of k do better, meaning that it is more likely that it is a 1. Setting ytie to 0 should not make it do better when it is even, and so it's the same odd vs even.

2).	(-2.5, 6.25), (-1.5,2.25)
(b)	
	(-2, 4,25)
	m=-4 lm= 1
	y = 1/4 x + 6
	4.25= -0.546
	6-4.75
(c) 92 y (2) X X X 4 b	
à, y (*) x t x (*)	
	$y = \omega^T x + b$
$ \qquad \qquad$	$0 = \frac{2}{57} \left[-1. \text{ m} \right] \left[\frac{1}{2} \right] -2.735 = 0.$
	I[-x,+4x2]-38-0
$Y = (a_{4} + a_{2}) - \frac{1}{2} \left[a_{2} \left[x^{(i)} ^{2} + a_{4}^{2} x^{(i)} ^{2} \right] \right]$	-2a2 a4 X (37 X (4)) - X14 4 X2 = 19
· · · · · · / · · · · · · · · · · · · ·	
	2 X(1)T X(4)= 17.813 . X2 = 0.75 x, 14.75 .
· · · · · · · · · · · · · · · · · · ·	save equetion.
292 - 217.92	
), f	٦٠٠٠٠٠٠٠٠
$\frac{\partial \lambda}{\partial a_1} = 2 - 17a_2 = 0 \Rightarrow a_2 = a_4 = \frac{2}{17}$	
	,, , , , , , , , , , , , , , , , , , ,
w= Z anynxn = 2 1. [x2] , 2. (-	n) [Ýu]
	1. 3
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	
[17. [.8.].	
5. 151 2 [tn-wixn] = 1 [-[-2]	(n. 4/17) (nx + (-1) - [-2/17 . 8/17] 726
- \-2:235	
· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·

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PROBLEM 3 ON HW 4

```
close all;
stat = readtable("UCLA_EE_grad_2031.csv");
```

(a)

```
y = stat{:,3};
GPA = stat{:,1};
GRE = stat{:,2};
hold on;
scatter(GPA(y == -1), GRE(y == -1), 'blue');
scatter(GPA(y == 1), GRE(y == 1), 'red');
```

(b)

```
x = stat{:,1:2};
y = stat{:,3};
cvx_begin
    variable w(2)
    variable b
    minimize( 1/2 * sum_square_abs(w) )
    subject to
        for i = 1:100
            y(i) * (w' * x(i,:)' + b) >= 1
        end
cvx_end
```

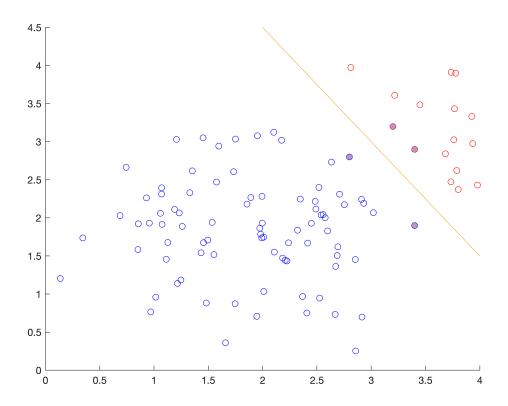
```
Calling SDPT3 4.0: 104 variables, 4 equality constraints
  For improved efficiency, SDPT3 is solving the dual problem.
num. of constraints = 4
\dim. of socp var = 4,
                         num. of socp blk = 1
dim. of linear var = 100
SDPT3: Infeasible path-following algorithms
*******************
version predcorr gam expon scale data
   NT 1 0.000 1 0
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
_____
0|0.000|0.000|1.6e+03|2.3e+01|4.9e+04|-2.000000e+03 0.000000e+00| 0:0:00| chol 1 1
1|0.523|0.525|7.6e+02|1.1e+01|3.3e+04|-1.174305e+03|-7.513991e+01|0:0:00| chol 1 1
2|0.366|0.386|4.8e+02|6.8e+00|2.7e+04|-6.430873e+02 -2.287892e+02| 0:0:00| chol 1 1
3|0.247|0.294|3.6e+02|4.8e+00|2.4e+04|-2.901923e+02 -4.170541e+02| 0:0:00| chol 1 1
4|0.164|0.240|3.0e+02|3.6e+00|2.3e+04|-1.945426e+01 -6.129483e+02| 0:0:00| chol 1
5|0.109|0.224|2.7e+02|2.8e+00|2.3e+04| 2.095194e+02 -8.126945e+02| 0:0:00| chol 1
6|0.084|0.288|2.5e+02|2.0e+00|2.4e+04| 4.355619e+02 -1.044117e+03| 0:0:00| chol 1
7|0.129|0.943|2.2e+02|1.1e-01|2.3e+04| 7.382631e+02 -1.392626e+03| 0:0:00| chol 1
8|0.122|1.000|1.9e+02|2.2e-06|2.7e+04| 1.327483e+03 -2.316356e+03| 0:0:00| chol
9|0.720|0.346|5.3e+01|1.7e-06|1.2e+04| 2.505271e+03 -2.620171e+03| 0:0:00| chol
10|0.749|1.000|1.3e+01|2.0e-07|9.5e+03| 4.258390e+03 -3.243073e+03| 0:0:00| chol
11|1.000|1.000|6.4e-13|9.9e-08|5.1e+03| 1.695448e+03 -3.379264e+03| 0:0:00| chol
12|1.000|0.962|5.9e-12|3.2e-08|2.2e+03| 1.483001e+03 -6.791601e+02| 0:0:00| chol
13|0.963|1.000|1.9e-12|9.0e-09|7.2e+02| 2.406002e+02 -4.755744e+02| 0:0:00| chol
14|1.000|1.000|2.6e-12|9.0e-10|2.4e+02| 1.396521e+02 -9.596010e+01| 0:0:00| chol
15|1.000|1.000|2.5e-13|9.1e-11|8.5e+01| 2.447638e+01 -6.007492e+01| 0:0:00| chol
```

```
19|1.000|0.839|7.7e-13|1.2e-12|3.5e+00|-4.119932e+00 -7.627466e+00| 0:0:00| chol 1 1
 20|0.942|0.958|4.2e-14|1.1e-12|2.4e-01|-6.797549e+00 -7.040376e+00| 0:0:00| chol 1 1
 21|0.985|0.974|6.3e-14|1.0e-12|4.1e-03|-6.996935e+00 -7.000998e+00| 0:0:00| chol 1 1
 22|0.987|0.982|5.7e-14|1.0e-12|5.6e-05|-6.999961e+00 -7.000017e+00| 0:0:00| chol 1 1
 23|0.989|0.985|1.6e-13|1.0e-12|1.5e-06|-6.999999e+00 -7.000000e+00| 0:0:00| chol 1 1
 24|0.989|0.987|2.0e-13|1.0e-12|3.8e-08|-7.000000e+00 -7.000000e+00| 0:0:00|
   stop: max(relative gap, infeasibilities) < 1.49e-08
  number of iterations = 24
  primal objective value = -6.99999997e+00
  dual objective value = -7.000000000e+00
                       = 3.79e-08
  gap := trace(XZ)
  relative gap
                        = 2.53e-09
  actual relative gap = 2.53e-09
  rel. primal infeas (scaled problem)
                                     = 1.99e-13
              11
                    11 11
  rel. dual
                                    = 1.01e-12
  rel. primal infeas (unscaled problem) = 0.00e+00
  rel. dual " " = 0.00e+00
  norm(X), norm(y), norm(Z) = 1.2e+01, 1.7e+01, 4.9e+01
  norm(A), norm(b), norm(C) = 3.5e+01, 2.0e+00, 1.1e+01
  Total CPU time (secs) = 0.12
  CPU time per iteration = 0.00
  termination code = 0
  DIMACS: 2.0e-13 0.0e+00 5.6e-12 0.0e+00 2.5e-09 2.5e-09
 Status: Solved
 Optimal value (cvx_optval): +6.5
 W
 w = 2 \times 1
     3.0000
     2,0000
 b
 b = -15.0000
 xv = (2:0.01:4);
 plot(xv, (15 - 3 * xv) / 2);
(c)
 P = zeros(100, 100);
 for i = 1:100
      for j = 1:100
          P(i,j) = y(i) * y(j) * x(i,:) * x(j,:)';
      end
 end
 cvx begin
      variable a(100)
      maximize ( sum(a) - 1/2 * quad form(a, P) )
      subject to
          sum(a \cdot y) == 0
           for i = 1:100
```

```
a(i) >= 0
end
cvx_end
```

```
Calling SDPT3 4.0: 104 variables, 4 equality constraints
num. of constraints = 4
                       num. of socp blk = 1
dim. of socp var = 4,
dim. of linear var = 100
SDPT3: Infeasible path-following algorithms
*****************
version predcorr gam expon scale_data
 NT 1 0.000 1 0
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
______
0|0.000|0.000|6.8e+02|8.3e-01|2.3e+04|-1.480616e+03 0.000000e+00| 0:0:00| chol 1 1
1|0.750|0.996|1.7e+02|4.9e-03|6.8e+03|-4.713686e+02 -9.722811e+01| 0:0:00| chol 1 1
2|0.972|1.000|4.8e+00|2.7e-04|2.7e+02| 2.188681e+01-5.537854e+01| 0:0:00| chol 1 1
3|0.969|1.000|1.5e-01|2.7e-05|1.0e+02| 4.551568e+01-4.852598e+01| 0:0:00| chol 1 1
4|1.000|1.000|3.1e-07|2.7e-06|5.0e+01| 1.599313e+01 -3.367612e+01| 0:0:00| chol 1
5|1.000|1.000|2.6e-08|3.3e-07|1.6e+01| 5.895252e+00 -9.707110e+00| 0:0:00| chol 1
6|1.000|0.593|2.6e-09|1.6e-07|7.3e+00|-1.614783e+00 -8.923866e+00| 0:0:00| chol 1
7|0.918|1.000|1.2e-08|3.3e-09|2.4e+00|-4.590305e+00|-7.007706e+00|0:0:00| chol
8|0.981|0.974|2.8e-09|1.1e-09|7.9e-02|-6.440585e+00 -6.520081e+00| 0:0:00| chol
9|0.988|0.987|1.1e-09|5.9e-10|9.6e-04|-6.499293e+00 -6.500255e+00| 0:0:00| chol
10|0.988|0.981|1.4e-11|2.4e-10|1.3e-05|-6.499991e+00 -6.500004e+00| 0:0:00| chol
11|0.997|0.954|1.7e-14|1.4e-11|6.5e-07|-6.500000e+00 -6.500000e+00| 0:0:00| chol 1
12|1.000|0.924|1.0e-14|2.0e-12|4.8e-08|-6.500000e+00 -6.500000e+00| 0:0:00|
 stop: max(relative gap, infeasibilities) < 1.49e-08
_____
number of iterations = 12
primal objective value = -6.49999997e+00
dual objective value = -6.50000001e+00
gap := trace(XZ) = 4.84e-08
relative gap
                  = 3.46e-09
actual relative gap = 3.39e-09
rel. primal infeas (scaled problem) = 1.03e-14
rel. dual " " = 2.03e-12
rel. primal infeas (unscaled problem) = 0.00e+00
rel. dual " " = 0.00e+00
norm(X), norm(Y), norm(Z) = 7.8e+00, 8.4e+01, 3.8e+02
norm(A), norm(b), norm(C) = 1.1e+01, 2.0e+00, 3.7e+02
Total CPU time (secs) = 0.08
CPU time per iteration = 0.01
termination code = 0
DIMACS: 1.0e-14 0.0e+00 2.9e-12 0.0e+00 3.4e-09 3.5e-09
______
Status: Solved
Optimal value (cvx optval): +6.5
```

```
scatter(GPA(a \ge 0.00001), GRE(a \ge 0.00001), 'filled', 'MarkerFaceAlpha', 0.5);
```



		$\begin{bmatrix} k(x_1, x_1) & k(x_1, x_2) \\ k(x_2, x_1) & k(x_2, x_2) \end{bmatrix} = \begin{bmatrix} k(x_1, x_2) \\ -k(x_1, x_2) \end{bmatrix}$
· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·	$y^{7}Ky = \begin{bmatrix} k(x_{1}, x_{2}) & -k(x_{1}, x_{2}) \end{bmatrix} \begin{bmatrix} k(x_{1}, x_{1}) & k(x_{1}, x_{2}) \\ k(x_{2}, x_{1}) & k(x_{1}, x_{2}) \end{bmatrix} \begin{bmatrix} k(x_{1}, x_{2}) \\ -k(x_{1}, x_{2}) \end{bmatrix}$
		$\int_{\mathbb{R}^{n}} \left(k(\lambda^{1}, \lambda^{2}) k(\lambda^{1}, \lambda^{1}) - k(\lambda^{1}, \lambda^{2}) k(\lambda^{1}, \lambda^{2}) \right)$
· · · · · · · · · · · · · · · · · · ·		k(x2, x2) le(x1, x2) - le(x1, x3) k(x2, x2) [k(x2, x2)] [k(x1, x2)]
	· · · · · · · · · · · · · · · · · · ·	= 1c(Y2, X2) k(Y1, X1) k(Y2, X2) - k(X1, X2) k(X1, X2) le(X2, X2)
		- (2,2) k(1,0) = k(x,x) (k(x,x)) k(x,x)
		$ c(x_1,x_1) = c(x_2,x_1) + c(x_1,x_1) ^2 > 0$ $ c(x_1,x_1) = c(x_2,x_1) + c(x_1,x_1) ^2 > 0$
		tleefoc,
		$(k(x_1,x_1) + k(x_1,x_2)^2 \rightarrow 0$
		k(x, x,) (x, x,) (e(x, x,))

.PSD states that K is valid of yTKy 20 yg ytky = yt (K. (x,x) + k2 (x,x') y = (yTK; (x,x')+ yTK2 (x,x'))y J' K((x,x') y + y * k' (x,x') y [K; (x, x') = a(x) T, a(x') 5 K=K, K, = Zam(x) am(x') . Z5m(x) bm(x') = $\frac{1}{2}$ $\frac{$ let. Cmin(x) = am(x). Jnx. = \frac{m}{2} \frac{m}{2} \cdot \ Cis. mxn.-dwersurd = C(x) c(x') K can be writer as a nimer product of the feature map (c) exy(k,(x,x')) = exp(a)= 1+ a+ a2 + a) 14 K1(x,x)+ [K1(x,x)]+ [K1(x,x)]+ each of these terms . K, (x, x')". I is a kind by part (b) tisim of all of these benefit is a leened by part (o.). 12.

tn (wT: xi+3) = 1- &

(= 9 intexe) T Xn +b = to (1-E) O/Mindido all natures than y (1) (7 x 1) +5

IMI = 2 (there) (5 9 the x) Xn)

Wmb= 5 (tn-(Zaktexe)Txn)

= 2 (y(n) Z akyk) XT,Xn

 $= \sum_{n \in \mathcal{N}} \left(y^{(n)} - \sum_{n \in \mathcal{N}} a_m y^{(n)} \langle x^{(n)}, x^{(n)} \rangle \right)$

Nm nem (y(n) - 5 am y(n) < x(n))