

1. Intro. to Convex Optimization.

For an optimization problem to be convex:

- ① feasible region has to be a convex set
- ② objective function is a convex function

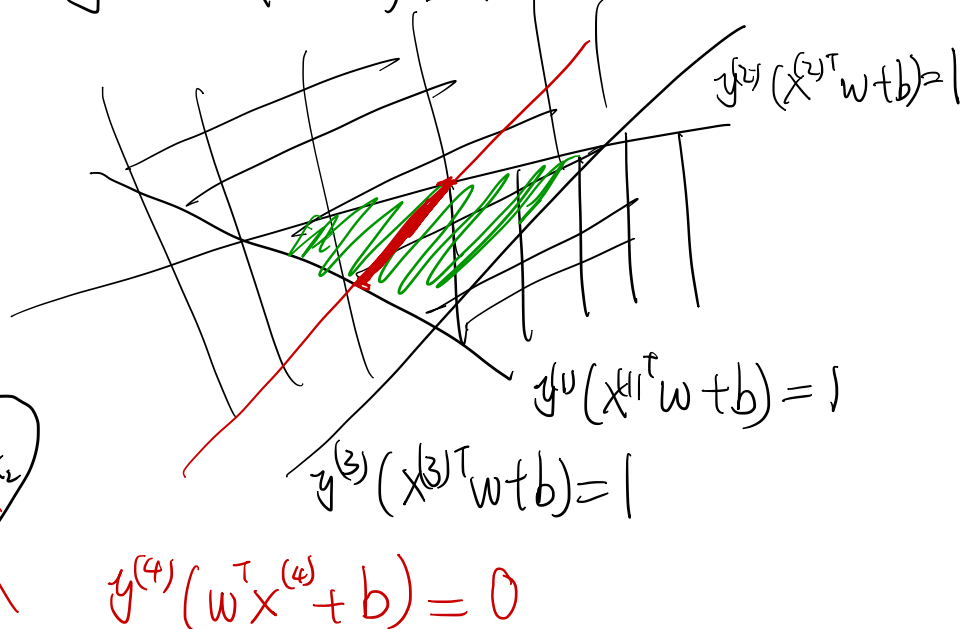
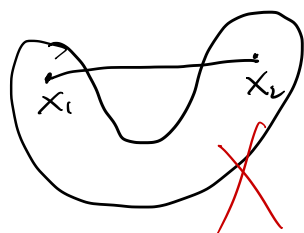
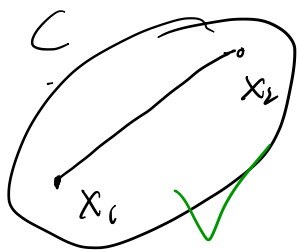
Feasible Region E.g. $SVM_{\min} \frac{1}{2} \|w\|^2$

$$\text{s.t. } y^{(i)} (w^T x^{(i)} + b) \geq 1 \quad i=1, \dots, m$$

Convex Set, C

$$x_1, x_2 \in C \quad 0 \leq \theta \leq 1$$

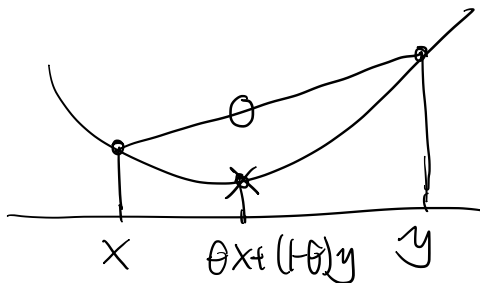
$$\Rightarrow \theta x_1 + (1-\theta) x_2 \in C$$



Convex Function

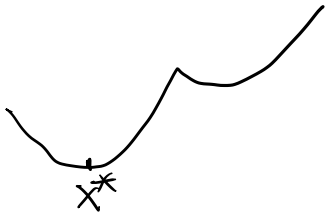
① Domain has to be convex set.

$$\textcircled{2} f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y)$$

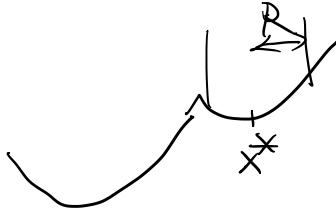


Globally and Locally Optimal

x^* is the globally optimal ^{solution} $f(x^*) \leq f(x) \quad \forall x \in \text{dom } f$



x^* is the locally optimal solution $f(x^*) \leq f(x)$



$$\forall x \in \{x \mid \|x - x^*\| \leq R\}$$

Standard form of convex optimization

Primal Problem

$$\min_x f_0(x) = \min_x \max_{\lambda, v} L$$

$$\text{s.t. } f_i(x) \leq 0 \quad i = 1, \dots, m \leftarrow \lambda_i$$

$$h_i(x) = 0 \quad i = 1, \dots, p \leftarrow v_i$$

If feasible
 $\lambda \geq 0$

$$L(x, \lambda, v) = f_0(x) + \underbrace{\sum_{i=1}^m \lambda_i f_i(x)}_{\neq 0} + \sum_{i=1}^p v_i h_i(x) \leq f_0(x)$$

Lagrange dual function

$$g(\lambda, v) = \inf_{x \in D}^{\rightarrow \min} L(x, \lambda, v)$$

x is feasible $\lambda \geq 0$

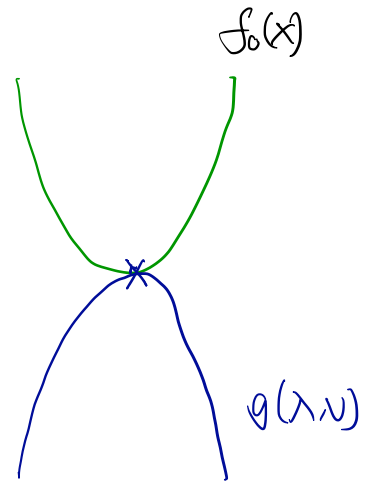
$$g(\lambda, v) \leq L(x, \lambda, v) \leq f_0(x) \quad \text{Weak Duality}$$

Dual Problem

$$\begin{aligned} \max_{\lambda, \nu} g(\lambda, \nu) &= \max_{\lambda, \nu} \min_x L \\ \text{s.t. } \lambda &\geq 0 \end{aligned}$$

Strong Duality:

$$g(\lambda^*, \nu^*) = L(x^*, \lambda^*, \nu^*) = f_0(x^*)$$



KKT Conditions:

1. Primal constraints. $f_i(x) \leq 0$ $h_i(x) = 0$
2. Dual constraints $\lambda \geq 0$
3. Complementary slackness
 $\lambda_i f_i(x) = 0$, $i = 1, \dots, m$
4. Gradient of $L(x, \lambda, \nu)$ w.r.t x vanishes
 $\nabla_x L(x, \lambda, \nu) = 0$

2. Find a dual problem

$$\min x^T P x$$

$$\text{s.t. } Ax \leq b \quad \lambda$$

$$L(x, \lambda) = x^T P x + \lambda^T (Ax - b)$$

$$g(\lambda) = \min_x L(x, \lambda)$$

$$\nabla_x L(x, \lambda) = 2Px + A^T \lambda = 0 \Rightarrow \underline{x = \frac{1}{2} P^{-1} A^T \lambda}$$

$$g(\lambda) = -\frac{1}{4} \lambda^T A P^{-1} A^T \lambda - b^T \lambda$$

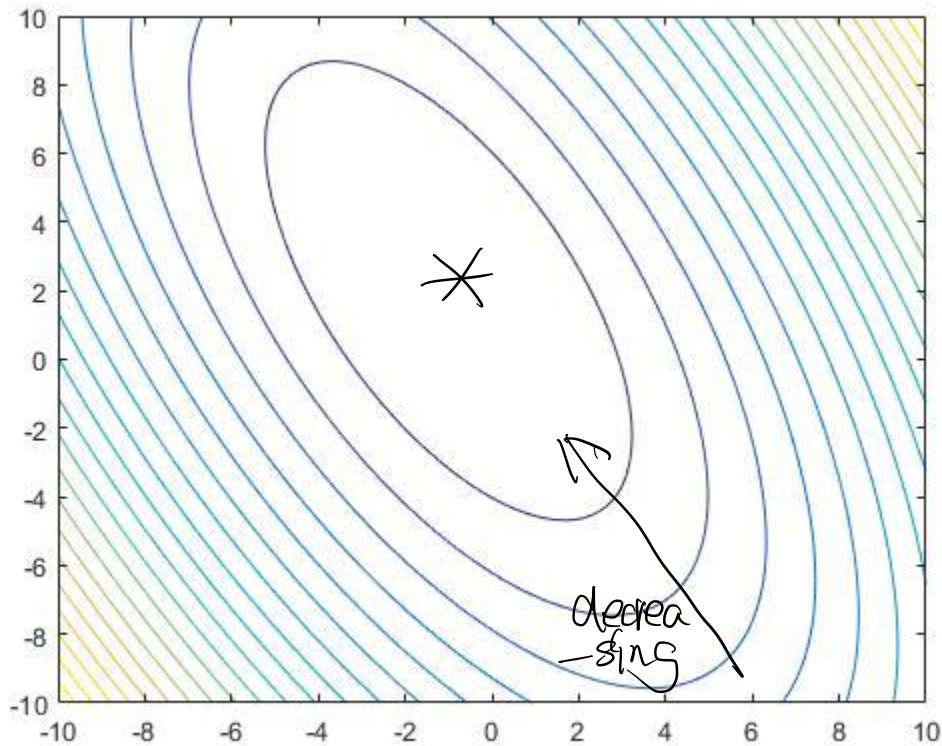
Dual Problem

$$\max_{\lambda} g(\lambda)$$

$$\text{s.t. } \lambda \geq 0$$

Unconstrained QP

We want to minimize: $J(x_1, x_2) = 5x_1^2 + 4x_1x_2 + 2x_2^2 + 2x_1 - 4x_2$.

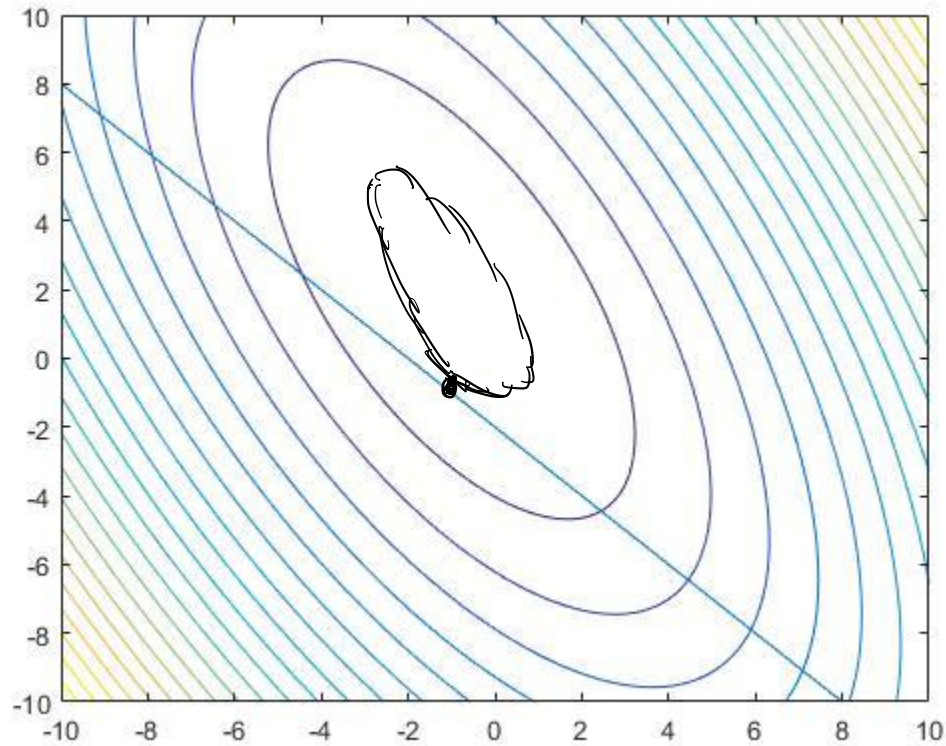


```
A = [5 2; 2 2];  
b = [2 -4];  
cvx_begin  
    variable x(2)  
    minimize quad_form(x,A)+b*x  
cvx_end
```

$x = [-1; 2]$.

Linear equality constraint

We add a linear equality constraint: $x_1 + x_2 + 2 = 0$. ✓



```
A = [5 2; 2 2];  
b = [2 -4];  
cvx_begin  
    variable x(2)  
    minimize quad_form(x,A)+b*x  
    subject to  
        x1+x2+2 == 0;  
cvx_end
```

$$x = [-1; -1].$$

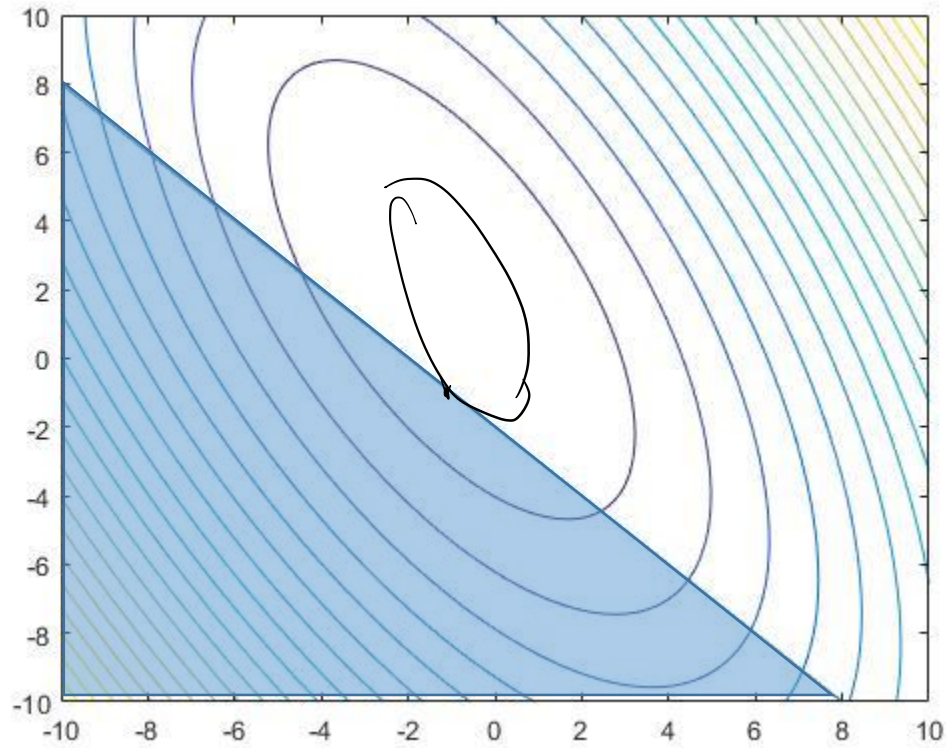
$$L(x, \lambda) = 5x_1^2 + 4x_1x_2 + 2x_2^2 + 2x_1 - 4x_2 + \lambda(x_1 + x_2 + 2)$$

$$\nabla_x L(x, \lambda) \Rightarrow \begin{cases} x_1 + 4x_2 + 2 + \lambda = 0 \\ 4x_1 + 4x_2 - 4 + \lambda = 0 \end{cases}$$

$$\lambda(x_1 + x_2 + 2) = 0$$

Linear inequality constraint

We add a linear inequality constraint: $x_1 + x_2 + 2 \leq 0$.

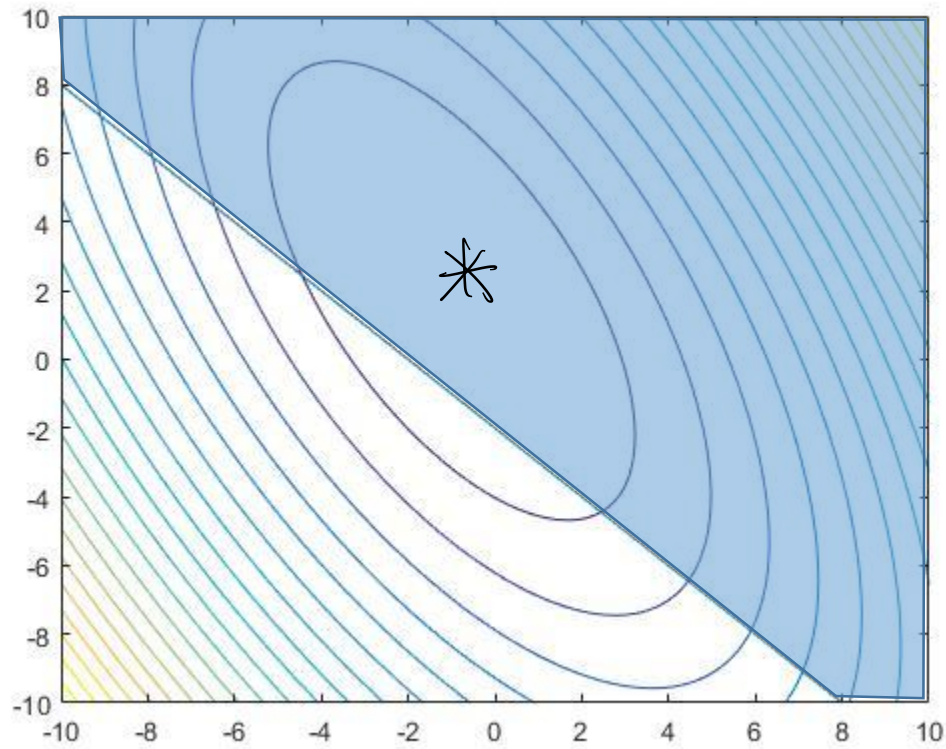


```
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cvx_begin  
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    minimize quad_form(x,A)+b*x  
    subject to  
        x1+x2+2 <= 0;  
cvx_end
```

$x = [-1; -1]$.

Linear inequality constraint

We add a linear inequality constraint: $x_1 + x_2 + 2 \geq 0$.



```
A = [5 2; 2 2];  
b = [2 -4];  
cvx_begin  
    variable x(2)  
    minimize quad_form(x,A)+b*x  
    subject to  
        x1+x2+2 >= 0;  
cvx_end
```

$x = [-1; 2]$.

Kernelized Linear Regression

When can kernel trick be used:

- ① Model parameter only depends on inner products of features.
- ② At test time, the result also only depends on inner product.

$$w = (\underline{X^T X + \lambda I})^{-1} \underline{X^T y} \quad \times \text{ Kernel trick}$$

Rewriting

$$(X^T X + \lambda I) w = X^T y$$

$$w = \frac{1}{\lambda} (X^T y - X^T X w) = X^T \cdot \underbrace{\frac{1}{\lambda} (y - Xw)}_a$$

$$w = X^T a$$

$$\lambda a = Y - X \cdot X^T a$$

$$a = (X \cdot X^T + \lambda I)^{-1} y$$

At test time:

$$\begin{matrix} \rightarrow & \begin{bmatrix} x_1^T x_1 & \dots \\ x_1^T x_2 & \dots \\ \vdots & \ddots \end{bmatrix} & \rightarrow & \begin{bmatrix} k(x_1, x_1) & \dots \\ \vdots & \ddots \end{bmatrix} \end{matrix}$$

$$\begin{aligned} w^T z &= X^T a \cdot z = a^T X^T z \\ &= \sum_{i=1}^N a_i \underbrace{x_i^T z}_{k(x_i, z)} \end{aligned}$$

Kernalized Perceptron

$$w^{(l+1)} = w^{(l)} + x_n y_n \quad \text{when misclassified}$$

$$w = a_1 x_1 y_1 + a_2 x_2 y_2 + a_3 x_3 y_3 - \dots$$

$$\{x_1, y_1\} \quad - \quad \{x_2, y_2\} \quad - \quad \dots$$

$$w = \sum_{i=1}^N a_i x_i y_i$$

At test time:

$$\text{sign}(w^T z) = \text{sign} \sum_{i=1}^N a_i \underbrace{x_i^T z}_{\downarrow K(x_i, z)} y_i$$