

# Thread

## 1. 함수 포인터

```
#define _CRT_SECURE_NO_WARNINGS
#include <stdio.h>
#include <stdlib.h>
#include <thread>

#define THRD_SIZE 10

void CallBack_ThrdFunc(void *pParam)
{
    int nNum = *((int*)pParam);

    int nCNT = 0;
    while (nCNT < nNum)
    {
        printf("[%d] %d Thrd\n", nCNT++, nNum);
    }
}

int main(void)
{
    int nThrdSize = THRD_SIZE;
    std::thread thrd[THRD_SIZE];
    for (int i = 0; i < THRD_SIZE; ++i)
    {
        thrd[i] = std::thread(CallBack_ThrdFunc, &i);
    }
}
```

```
        for (int i = 0; i < THRD_SIZE; ++i)
        {
            thrd[i].join();
        }

        system("pause");
        return 0;
    }
```

## 2. 함수 객체

```
#define _CRT_SECURE_NO_WARNINGS
#include <stdio.h>
#include <stdlib.h>
#include <thread>

class Counter
{
public:
    Counter(char* strName, int nFir, int nSec)
    {
        m_strName = (char*)malloc(10);
        //strcpy(m_strName, strName);

        m_nFir = nFir;
        m_nSec = nSec;
    }

    void operator()() const
```

```

        {
            for (int i = m_nFir; i <= m_nSec; ++i)
            {
                printf("[%s] %d\n", m_strName, i);
            }
        }

private:
    char *m_strName;
    int m_nFir;
    int m_nSec;
};

int main(void)
{
    char strName[10] = "Thrd1";
    std::thread t1{ Counter(strName, 1, 5) };

    t1.join();

    system("pause");
    return 0;
}

```

### 3. 클래스 메소드

```

#define _CRT_SECURE_NO_WARNINGS
#include <stdio.h>
#include <stdlib.h>

```

```
#include <thread>

class Counter
{
public:
    Counter(char* strName, int nFir, int nSec)
    {
        m_strName = (char*)malloc(10);
        strcpy(m_strName, strName);

        m_nFir = nFir;
        m_nSec = nSec;
    }

    void loop() const
    {
        for (int i = m_nFir; i <= m_nSec; ++i)
        {
            printf("[%s] %d\n", m_strName, i);
        }
    }

private:
    char *m_strName;
    int m_nFir;
    int m_nSec;
};

int main(void)
{
```

```
    char strName[10] = "Thrd1";

    Counter c1(strName, 1, 5);
    std::thread t1{ &Counter::loop, &c1};

    t1.join();

    system("pause");
    return 0;
}
```

## 4. 람다표현식

```
#define _CRT_SECURE_NO_WARNINGS
#include <stdio.h>
#include <stdlib.h>
#include <thread>

int main(void)
{
    char strName[10] = "Thrd1";

    std::thread t1([](char* strName, int nFir, int nSec)
    {
        for (int i = nFir; i <= nSec; ++i)
        {
            printf("[%s] %d\n", strName, i);
        }
    }, strName, 1, 5);
```

```
        t1.join();

        system("pause");
        return 0;
    }
```

## 5. 클래스 메소드 (고급)

### 1. Thread.h

```
#pragma once
#include <process.h>

struct _ST_CREATE_THREAD_DATA
{
    int(*pfEntry)(void* pContext);
    void* pContext;
};

static unsigned WINAPI _InternalThreadCaller(void* pContext)
{
    _ST_CREATE_THREAD_DATA* pData = (_ST_CREATE_THREAD_DATA*)pContext;
    int nRet = pData->pfEntry(pData->pContext);
    delete pData;
    return nRet;
}

HANDLE _CreateThread(int(*pfEntry)(void* pContext), void* pContext)
{

```

```

        _ST_CREATE_THREAD_DATA* pData = new _ST_CREATE_THREAD_
DATA;

        pData->pfEntry = pfEntry;
        pData->pContext = pContext;

        HANDLE hThread = (HANDLE)::_beginthreadex(NULL, 0, _In
ternalThreadCaller, pData, 0, NULL);
        if (INVALID_HANDLE_VALUE == hThread)
        {
            printf("_beginthreadex operation failure");
            delete pData;
            return NULL;
        }

        return hThread;
    }

struct INTERNAL_COMMON_THREAD_DATA
{
    virtual ~INTERNAL_COMMON_THREAD_DATA(void) {}
    virtual int ThreadFunc(void) = 0;
};

template<typename T>
struct INTERNAL_TEMPLATE_THREAD_DATA : public INTERNAL_COMMON_
THREAD_DATA
{
    T* pInstance;
    int (T::*pfMemberFunc)(void* pContext);
    void* pContext;

```

```

        int ThreadFunc(void) { return (pInstance->*pfMemberFunc)(pContext); }
};

int InternalThreadCaller(void* pContext)
{
    INTERNAL_COMMON_THREAD_DATA* pThreadData = (INTERNAL_COMMON_THREAD_DATA*)pContext;
    int nErrCode = pThreadData->ThreadFunc();
    delete pThreadData;
    return nErrCode;
}

template<typename T>
HANDLE CreateThread(T* pInstance, int (T::*pfEntry)(void*), void* pContext)
{
    INTERNAL_TEMPLATE_THREAD_DATA<T>* pThreadData = new INTERNAL_TEMPLATE_THREAD_DATA<T>;
    if (NULL == pThreadData)
        return NULL;
    pThreadData->pInstance = pInstance;
    pThreadData->pfMemberFunc = pfEntry;
    pThreadData->pContext = pContext;
    return _CreateThread(InternalThreadCaller, pThreadData);
}

```

## 2. Main.cpp

```

#define _CRT_SECURE_NO_WARNINGS
#include <stdio.h>

```



```

#include <windows.h>

#include "Thread.h"

class TestClass
{
public:
    TestClass() {}
    ~TestClass() {}

private:
    HANDLE m_thrd;
    bool m_bCheck;

public:
    void StartUp()
    {
        m_bCheck = true;
        m_thrd = CreateThread(this, &TestClass::Thread
_Func, NULL);
    }
    void ShutDown(DWORD dwTimeOut = 1000)
    {
        m_bCheck = false;

        DWORD dwRet = ::WaitForSingleObject(m_thrd, dw
TimeOut);

        if (WAIT_OBJECT_0 != dwRet)
        {
            printf("ShutDown Error : %d.", dwRet);

```

```

        ::TerminateThread(m_thrd, 0);
    }
    else
        printf("ShutDown Success.\n");
        ::CloseHandle(m_thrd);
}

private:
    int      Thread_Func(void* pContext)
    {
        printf("Start\n");
        while (m_bCheck)
        {
            printf("TEST");
            Sleep(1000);
        }
        printf("\nEnd\n");
        return 0;
    }
};

int main(void)
{
    TestClass Test;
    Test.StartUp();

    int nCNT = 0;
    while (nCNT++ < 10)
    {
        Sleep(1000);
    }
}

```

```
    }  
    Test.ShutDown();  
  
    system("pause");  
    return 0;  
}
```