K-medoids for K-means seeding

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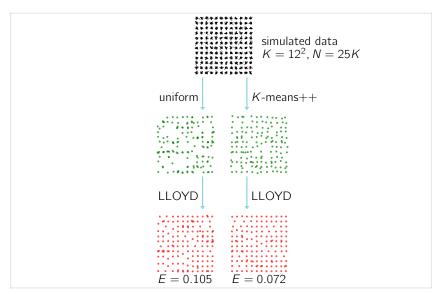
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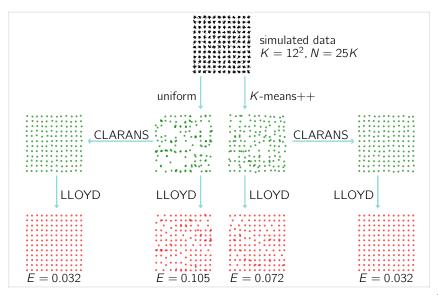


The standard K-means pipeline

First step: Seeding. Second step: Lloyd's algorithm



The standard K-means pipeline (+CLARANS)



Talk Outline

- 1) K-medoids, K-means++ and LLOYD
- 2) The CLARANS algorithm of Ng and Han (1994), algorithmic complexity and improvements
- 3) Results

K-medoids problem

Input:

- *N* samples $\mathcal{X} = \{x(1), ..., x(N)\}$
- Dissimilarity function $\mathit{diss}: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$

Task:

• Find K indices $c(1), \ldots, c(K) \in \{1, \ldots, N\}$ to minimize

$$E = \sum_{i=1}^{N} \min_{k=1:K} diss\left(x(i), x(c(k))\right).$$

• NP-hard.

K-means++ seeding

- Arthur and Vassilvitskii (2007)
- A K-medoids algorithm for

$$diss(x(i), x(i')) = ||x(i) - x(i')||^2.$$

```
    select c(1) uniformly from {1, ..., N}
    for k = 2 : K do
    select c(k) = i with prob ~ min<sub>k'<k</sub> diss(x(i), x(c(k')))
    end for
```

 Provides 8 In K + 2 approximation bound to optimal K-means solution in expectation

LLOYD and MEDLLOYD

LLOYD for K-means:

- 1: $C(k) \leftarrow x(c(k))$ for $k \in \{1, ..., K\}$
- 2: while not converged do

3: for
$$i = 1 \rightarrow N$$
 set $a(i) = \underset{k=1:K}{\operatorname{argmin}} \|x(i) - C(k)\|$

4: for
$$k = 1 \rightarrow K$$
 set $C(k) \leftarrow \frac{\sum_{i:a(i)=k} x(i)}{||i:a(i)=k||}$

5: end while

LLOYD for K-means:

- 1: $C(k) \leftarrow x(c(k))$ for $k \in \{1, ..., K\}$
- 2: while not converged do
- 3: for $i = 1 \rightarrow N$ set $a(i) = \operatorname{argmin}_{k=1:K} \|x(i) C(k)\|$ 4: for $k = 1 \rightarrow K$ set $C(k) \leftarrow \frac{\sum_{i:a(i)=k} x(i)}{\|i:a(i)=k\|}$
- 5 end while

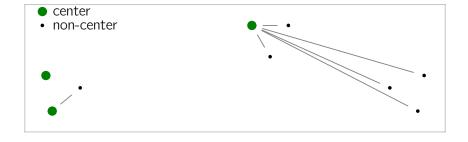
MEDLLOYD for K-medoids similar, with the constraint that centers are always samples,

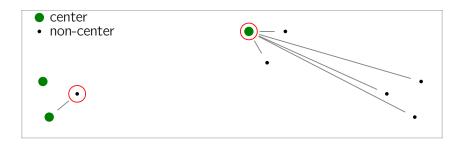
$$C(k) \leftarrow x \left(\underset{i:a(i)=k}{\operatorname{argmin}} \sum_{i':a(i')=k} \|x(i) - x(i')\|^2 \right)$$

CLARANS

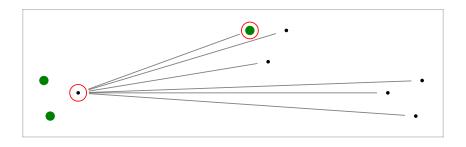
A very simple *K*-medoids algorithm:

Randomly propose swaps between 1 center and 1 non-center, accept if E decreases.

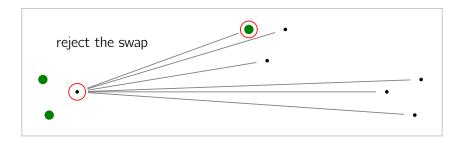




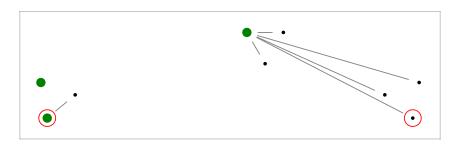
1) propose a swap



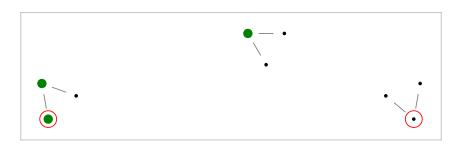
- 1) propose a swap
- 2) evaluate energy



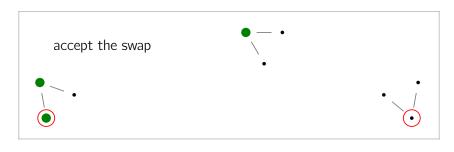
- 1) propose a swap
- 2) evaluate energy
- 3) implement or reject



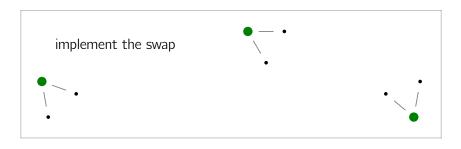
1) propose a swap



- 1) propose a swap
- 2) evaluate energy



- 1) propose a swap
- 2) evaluate energy
- 3) implement or reject



- 1) propose a swap
- 2) evaluate energy
- 3) implement or reject

CLARANS Advantages

Advantages of CLARANS over MEDLLOYD (and LLOYD) are,

- updates are not local
- assignments and centers change simultaneously

Easy to show that,

• {local minima of CLARANS} \subseteq {local minima of MEDLLOYD}.

CLARANS Complexity

Ng and Han use N^2 dissimilarity matrix, infeasible now Useful to distinguish between evaluate and implement steps:

```
1: while stopping condition is false do
       randomly select center and non-center
 2:
       evaluate proposal energy
 3:
       if proposal energy lower then
 4:
           implement proposed swap
 5.
       end if
 6.
 7: end while
  10^{3}
evaluate
   10^{2}
   10^{1}
                                   150
                                             200
                                                      250
                                                                300
               50
                         100
                           implement (cumulative)
```

CLARANS Improving complexity

We present different levels of optimization:

- 1. For all samples, record distances to nearest and second nearest centers (d_1 and d_2 respectively).
- 2. Also record for all clusters maximum d_1 and d_2 , and inter-center distances. (\triangle)

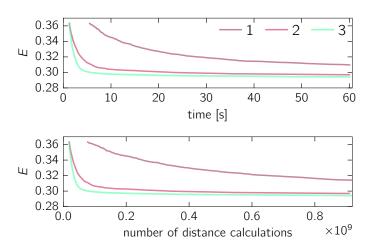
Assuming largest cluster is O(N/K),

$$\begin{array}{c|cc} & 1. & 2. \\ \hline \text{evaluate} & O(N) & O(\frac{N}{K}) \\ \text{implement} & O(N) & O(N) \\ \end{array}$$

3. Terminate evaluation early if swap unpromising.

Empirical speed-up

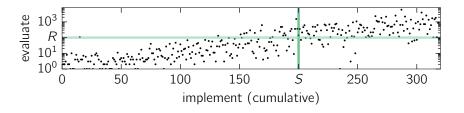
 $N = 10^6/2$, $K = 10^3/2$, data from 4-d Gaussian with I covariance.



CLARANS for *K*-means seeding Stopping criterion

Two possible stopping criteria

- Ng and Han stop after R consecutive swap rejections
- Can stop after S implementations (swap accepts)

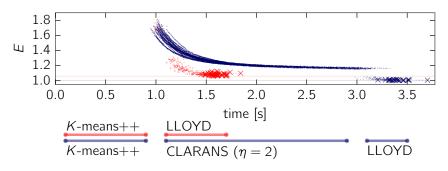


We prefer a time based criterion

• If first seeding (with K-means++) takes T_0 , stop afer ηT_0 .

Experiment 1

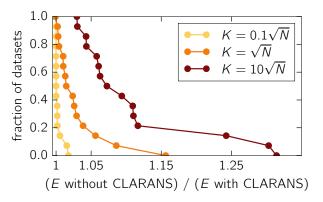
Subset of RNA dataset, d = 8, $N = 16 \times 10^4$, K = 400.



50 runs of K-means++ \rightarrow LLOYD, and several with CLARANS. Number with CLARANS chosen so total times equal. Comparing best solutions, using CLARANS results in 6% lower E.

Results Summary

Summary of experiments. Each point is an experiment with same setup as previous slide, horizontal position is reduction in *E* obtained using CLARANS.



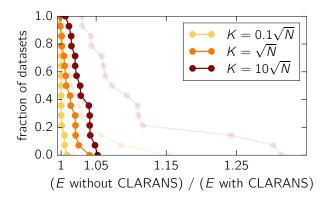
Dataset dimensions range in $d: 2 \rightarrow 90$, $N: 1484 \rightarrow 488565$.

K-means++ revisited

From conclusion of K-means++ paper of Arthur and Vassilvitskii (2007):

"Also, experiments showed that k-means++ generally performed better if it selected several new centers during each iteration, and then greedily chose the one that decreased E as much as possible. Unfortunately, our proofs do not carry over to this scenario."

K-means++ revisited



Comparison to version of K-means++ referred to in Conclusion of Arthur and Vassilvitskii (2007) (selecting from best of 5 new centers). Using CLARANS still improves results, but by less.

Clustering library: zentas

$$(\triangle)$$
: $diss(x(i), x(i')) = \psi(dist(x(i), x(i')))$, where

- $\psi: \mathbb{R} \to \mathbb{R}$ is non-decreasing
- $dist: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ satisfies the \triangle -inequality

Our software zentas implements accelerated CLARANS for different metrics. Levenshtein for sequence data, $l_0, l_1, \ldots, l_{\infty}$ for sparse/dense vectors. Also fast K-means++, LLOYD, many others.



Conclusion

We discussed CLARANS, and how

- to accelerate it
- it improves seeding for *K*-means
- it is a versatile clustering algorithm in its own right.

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