

#### Abstract

We present a scheme for K-means seeding, which results in a 3% geometric mean reduction in K-means loss as compared to vanilla K-means++ seeding, on 16 publicly available datasets. It is based on the CLARANS K-medoids algorithm of Ng and Han (1994).

### K-medoids

Given samples  $\mathcal{X} = \{x(1), \dots, x(N)\}$ , function  $dist : \mathcal{X} \times \mathcal{X} \to \mathbb{R}^+$  and monotonic energy function  $\psi : \mathbb{R}^+ \to \mathbb{R}^+$ , find  $\mathcal{C} \subset \{1, \dots, N\}$  where  $|\mathcal{C}| = K$  to minimize

$$E = \sum_{i=1}^{N} \min_{i' \in \mathcal{C}} \psi(dist(x(i), x(i'))).$$

It has applications in clustering sequences, graph vertices, sparse and dense vectors, etc. Two popular algorithms are,

- MEDLLOYD ((Hastie et al. (2001), Park and Jun (2009)): like Lloyd's algorithm, but centroids are replaced by medoids
- CLARANS (Ng and Han (1994)): random swaps between centers and non-centers are proposed, and only accepted if  $E(\mathcal{C})$  decreases.

### K-means and K-means seeding

The K-means task is to find K centers,  $\{C(1), \ldots, C(K)\}$ , not necessarily elements of  $\{x(1), \ldots, x(N)\}$ , to minimize

$$E = \sum_{i=1}^{N} \min_{k \in \{1, \dots, K\}} \|x(i) - C(k)\|_{2}^{2}.$$
 (1)

In the popular LLOYD algorithm centers are initialized or *seeded* as a subset of  $\mathcal{X}$ . Good seeding is critical to avoid poor local minima. Most seeding algorithms attempt to minimize initial energy (K-means++, Bradley-Fayad, etc.). Minimizing seeding energy is the special case of K-medoids with

$$dist(x(i), x(i')) = ||x(i) - x(i')||_2$$
 and  $\psi(v) = v^2$ .

This motivates the use of other popular and well established K-medoids algorithms for K-means seeding.

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# K-medoids for K-means seeding

James Newling & François Fleuret {james.newling,francois.fleuret}@idiap.ch

## The CLARANS K-medoids algorithm

The algorithm iteratively proposes swapping a medoid  $x(i_{-})$  with a non-medoid  $x(i_{+})$ . Only energy reducing swaps are implemented.

```
1: Initialize center indices \mathcal{C} \subset \{1, \ldots, N\}, where |\mathcal{C}| = K

2: E \leftarrow \sum_{i=1}^{N} \min_{i' \in \mathcal{C}} \psi(dist(x(i), x(i')))

3: while stopping criterion false do

4: sample i_{-} \in \mathcal{C} and i_{+} \in \{1, \ldots, N\} \setminus \mathcal{C}

5: E^{+} \leftarrow \sum_{i=1}^{N} \min_{i' \in \mathcal{C} \setminus \{i_{-}\} \cup \{i_{+}\}} \psi(dist(x(i), x(i')))

6: if E^{+} < E then

7: \mathcal{C} \leftarrow \mathcal{C} \setminus \{i_{-}\} \cup \{i_{+}\}

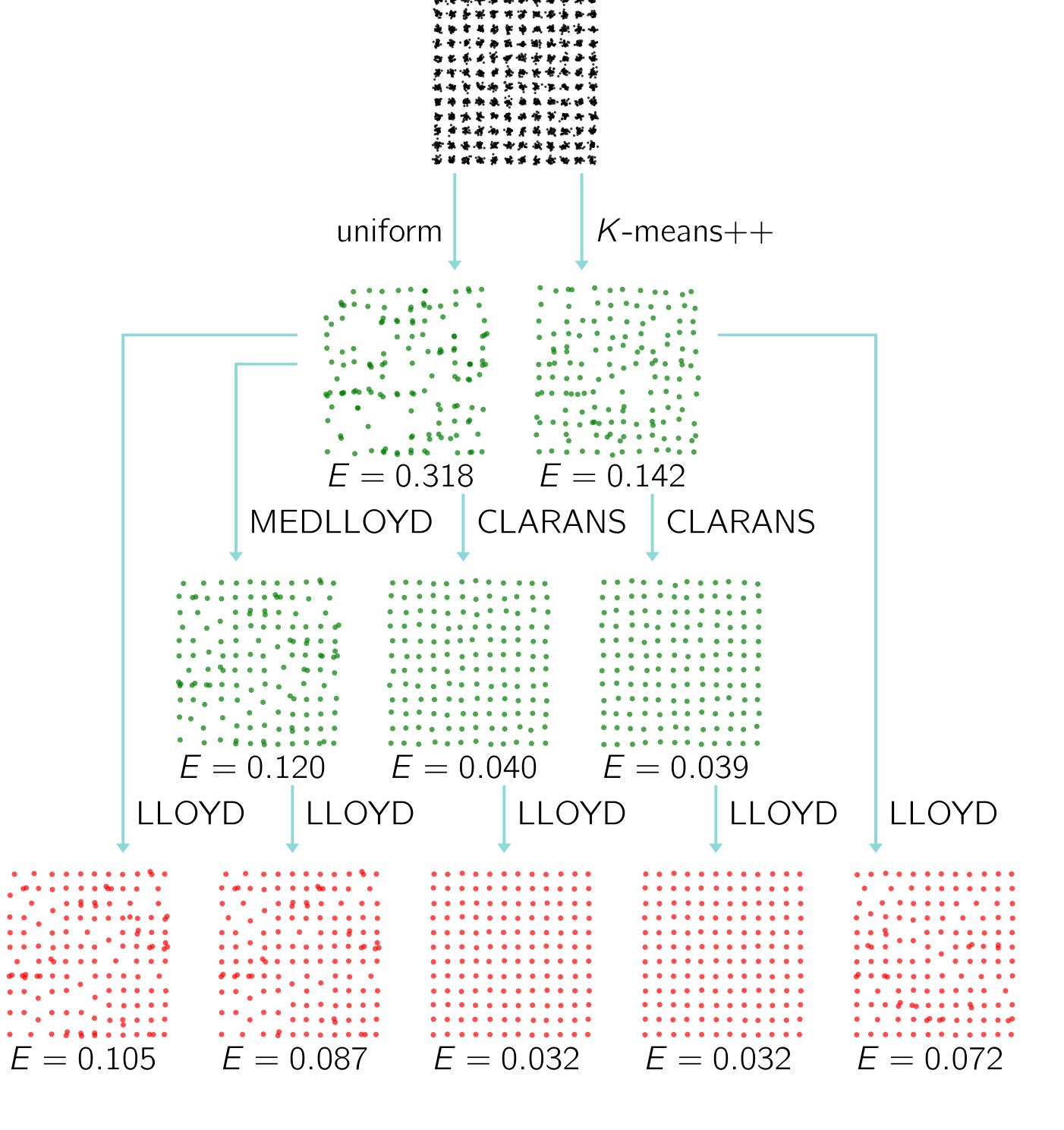
8: E \leftarrow E^{+}

9: end if

10: end while
```

### Five routes to *K*-means local minima

(Below) Clustering with  $K=12^2$  centers on a 2-d grid, N=25K samples. First row: the generated samples. Second row: uniform and K-means++ seedings. Third row: K-medoids refinements. Fourth row: final LLOYD clusterings. CLARANS refinement results in reduced final E.



## Accelerating the CLARANS algorithm

There are many more *evaluations* (line 5) than *implementations*. Assuming balanced clusters, and that *dist* satisfies the triangle inequality, we present a technique where evaluation is O(N/K), and implementation is O(N). It requires recording,

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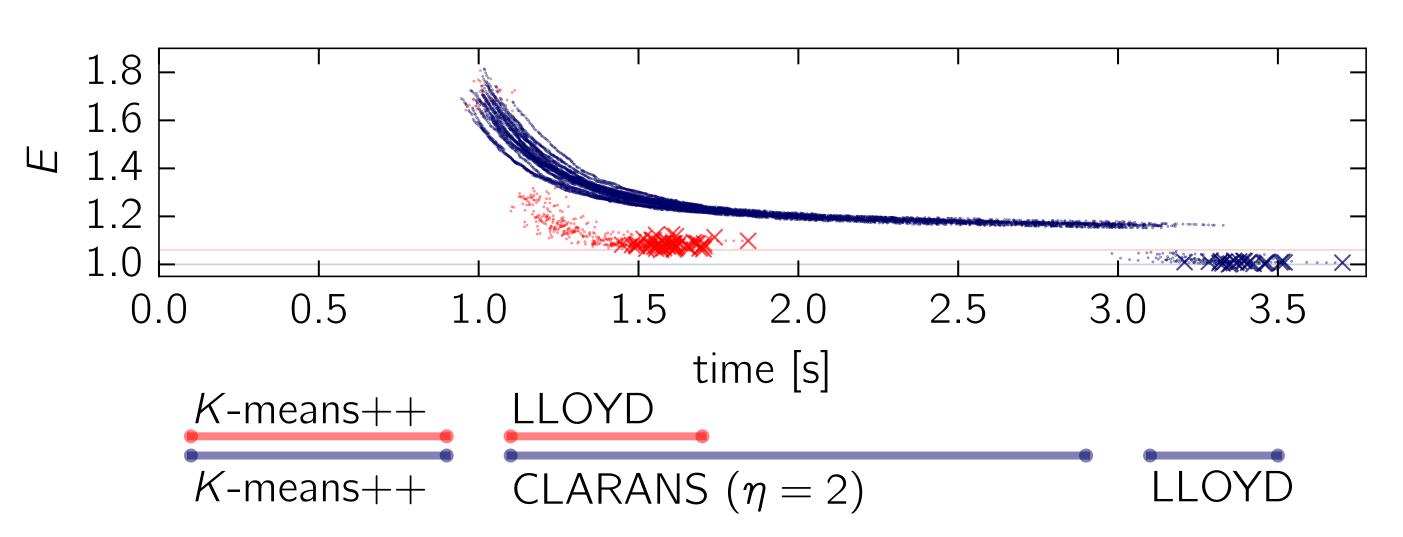
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- for non-centers (such as x(1) below), distance to nearest ( $d_1$ ) and second nearest ( $d_2$ ) centers (as in Ng and Han),
- for centers (such as x(2) below), maximum over cluster of  $d_1$  and  $d_2$  ( $R_1$  and  $R_2$  respectively), and distances to all centers.



#### Results

(Below) An experiment with an RNA dataset,  $N = 16 \times 10^4$ , d = 8 and  $K = 4 \times 10^2$ . With 50 runs seeded with K-means++ (red), and several runs with CLARANS inbetween K-means and K-means++ (blue). The best run without CLARANS has 6% higher E.



(Below) Summary for 16 datasets. Each point is an experiment with same setup as RNA, horizontal position is reduction in E with CLARANS. Dimensions range in  $d: 2 \rightarrow 90$ ,  $N: 1484 \rightarrow 488565$ . At  $K\sqrt{N}$ , mean reduction is 3.2% vs K-means++ and 1.2% vs greedy K-means++ (not shown).

