DIP Homework Assignment #2

Problem 1: EDGE DETECTION

(a)



sample1.png, result1.png and result2.png

Approach

1. Use Guassion filter (H) to perform low-pass filtering

$$H = rac{1}{9} * egin{bmatrix} 1 & 1 & 1 \ 1 & 1 & 1 \ 1 & 1 & 1 \end{bmatrix}$$

2. Use two matrix G_r, G_c to compute G for each pixels, obtaining the gradient image (result1.png)

$$G_r = egin{bmatrix} -1 & 0 & 1 \ -2 & 0 & 2 \ -1 & 0 & 1 \end{bmatrix}, G_c = egin{bmatrix} 1 & 2 & 1 \ 0 & 0 & 0 \ -1 & -2 & -1 \end{bmatrix}$$

$$G=\sqrt{G_R^2+G_R^2}$$

3. Select the threshold to generate edge map. Here I choose pixel value > 95 in gradient image

Discussion

Here are images in different threshold:



threshold = 95, threshold = 50 and threshold = 120

It shows that if threshold is too small, the image will look dazzled. I tried different threshold, finding threshold = 95 obtain the best result, especially the texture of the woman's hand. If threshold is bigger than 95 (here I take 120 for example), some details will disappear.

(b)



sample1.png and result3.png

Approach

- 1. Use Guassion filter H to perform low-pass filtering
- 2. Compute gradient magnitude and orientation
- 3. Do **non-maximal suppression**: For gradient of each pixels, check whether two neighbors along the orientation are both smaller than it. If so, verify it as a part of edge.
- 4. Label each pixels according to two threshold T_H, T_L , verify they are edge, candidate or non-edge pixels. Here I choose $T_H=90, T_L=10$

5. For each pixels that are verified with edge pixels, label its candidate neighbors with to be edges. Then label continuously with **dfs** method, obtaining the edge map (result3.png)

Discussion

Here are the images with different threshold T_{H}, T_{L}





(10, 90), (10, 120), (5, 90) and (30, 60)

I find that if T_H is too high , some details will disappear (like woman's left leg). If T_L is too low, the edge map show too much unimportant things. If we choose $T_L=30, T_H=90$, the image is pretty clear, but it lose some details. So I think (10, 90) is the most beautiful edge map after trying multiple thresholds

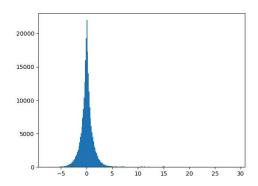


sample1.png and result4.png

- 1. Use Guassion filter \boldsymbol{H} to perform low-pass filtering by two times
- 2. Use Laplacian filter H^\prime to enhance edge

$$H' = rac{1}{4} * egin{bmatrix} 0 & -1 & 0 \ -1 & 4 & -1 \ 0 & -1 & 0 \end{bmatrix}$$

3. Generate the histogram to choose the threshold.

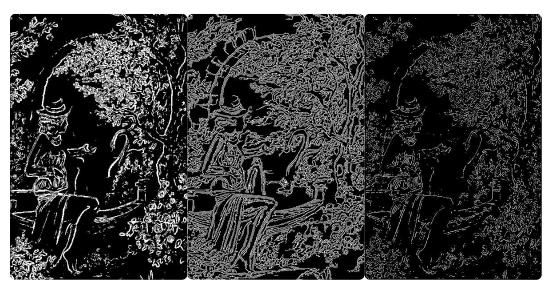


4. Choose a threshold to separate zero and non-zero. Here I choose threshold = 0.8

5. For each pixels that value = 0, check whether there are two oppsite neighbors being one postive and one negative. If so, verify it as an edge. Obtain the edge map (result4.png)

Disussion

Compare these three images:

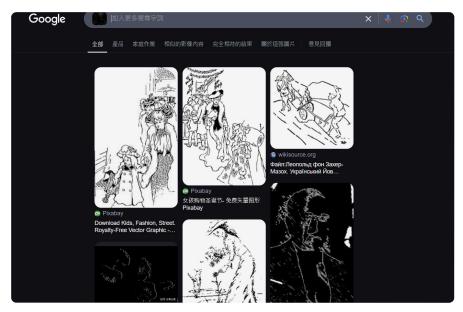


result2.png, result3.png and resul4.png

- 1. I find that result2.png has thicker edges, and it can generate a good edge map with simple way.
- 2. It's surprising that canny method gereate such a beautiful image, result3.png has very clear lines, while retaining good details. The stone arched door can only be seen clearly in result3.png I think it's the most beautiful edge map of the three.
- 3. Take a look at these three images, result4.png seem to be the worst edge map. But compare to result2.png in detail, it generate the most import edge in the image. It rarely contains unnecessary lines after performing Guassian filter.

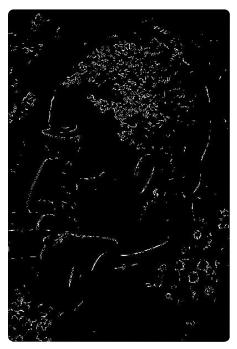


sampl1.png and portait



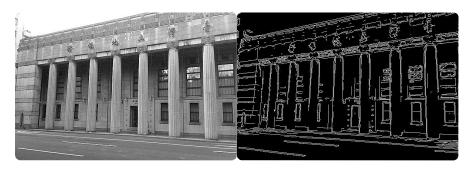
search result

- 1. I observe that Sobel method can easily show different edge map with different thresholds, so I choose to use it.
- 2. I tried threshold = 180 and 200, they both work.

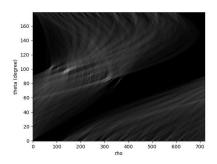




(e)



sample.png and result5.png





result6.png and result7.png

- 1. First perform Canny edge detection by using $threshold_{low}=60, threshold_{high}=70,$ obtaining result5.png
- 2. Apply hough transform to results.png and obtain Hough space result6.png
- 3. Find the point that its slope is close to vertical line in result6.png, then we can count how many vertical line it has and count the number of pillars

Problem 2: GEOMETRICAL MODIFICATION

(a)





sample3.png and result8.png

Approach

1. Using barrel distortion formula by using backward treatment. Here I let $k_1=0.001, k_2=0$

$$r_{new} = \sqrt{(x_{new} - x_{center})^2 + (y_{new} - y_{center})^2}$$

And then

$$r_{old} = r(1 + k_1 r_{new}^2 + k_2 r_{new}^4)$$

We obtain x_{old}, y_{old} :

$$x_{old} = x_{center} + (x_{new} - x_{center}) rac{r_{old}}{r_{new}}$$

$$y_{old} = y_{center} + (y_{new} - y_{center}) rac{r_{old}}{r_{new}}$$

So, we obtain the image after barrel distortion.

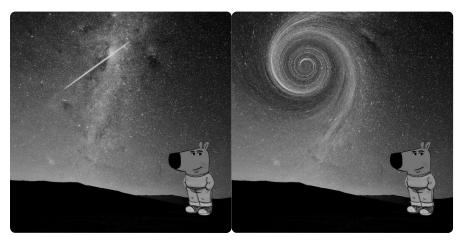


2. Then I use multiple matrixes to control its scale, position and angle. Here I move left 70 pixels and up 60 pixels, rotate 15 degrees counterclockwise, and scale 2 times both of x and y. Finally, we obtain the result image.

$$egin{bmatrix} x_{new} \ y_{new} \ 1 \end{bmatrix} = T^{-1}S^{-1}R^{-1} egin{bmatrix} x_{old} \ y_{old} \ 1 \end{bmatrix}$$

Note: I always use the center of image to be the pivot

(b)



sample5.png and result9.png

Using swirling formula by using backward treatment.

Here I let center=(200,450), radius=300, strength=20, rotation=0.

$$heta_{new} = rctan(rac{y_{new} - y_{center}}{x_{new} - x_{center}})$$

$$ho = \sqrt{(x_{new} - x_{center})^2 + (y_{new} - y_{center})^2}$$

Then transform them according to

$$r=\ln(2)rac{radius}{5}$$

$$\phi = rotation$$

$$s = strength$$

$$heta_{old} = \phi + se^{-
ho/r} + heta$$

Here we obtain original points angle and distance, so we can compute their positions

$$x_{old} = x_{center} +
ho \cos(heta_{old})$$

$$y_{old} = y_{center} +
ho \cos(heta_{old})$$

Finally we obtain the new image through swirling.

Discussion

I think the most important part of this problem is **the center of the swirl**. sample6.png looks very smooth, and there is a perfect shape of its center. The arcs in result9.png look more clearly, but doesn't look such smooth as sample6.png overall. And I think it looks almost the same around the swirl.