Introduction to Differentiable Probabilistic Models

Bill Watson

S&P Global

July 12, 2019

Primer: Standard Machine Learning

▶ Usually, we are given a set $\mathcal{D} = \{X, y\}$

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nm} \end{bmatrix} \qquad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

where X is our data matrix, and y are our labels.

Primer: Standard Machine Learning

▶ Usually, we are given a set $\mathcal{D} = \{X, y\}$

$$X = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1m} \\ x_{21} & x_{22} & \dots & x_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nm} \end{bmatrix} \qquad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

where X is our data matrix, and y are our labels.

▶ Attempt to fit a model f parameterized by θ with respect to an objective function $\mathcal L$

$$\theta^* = \underset{\theta}{\operatorname{argmin}} \ \mathcal{L}\big(f(X; \theta), \ y\big)$$

Reframed as a Probabilistic Model

- Consider our model is a probability distribution Q
 - ► No longer have labels y
 - But have probabilities and sampling

Reframed as a Probabilistic Model

- Consider our model is a probability distribution Q
 - ▶ No longer have labels y
 - But have probabilities and sampling
- Consider that our data is sampled from the real world P:

$$egin{aligned} egin{aligned} egin{aligned} X &\sim P \ \ heta^* = rgmin_{ heta} & \mathcal{L}ig(f(X; heta)ig) \end{aligned}$$

Reframed as a Probabilistic Model

- Consider our model is a probability distribution Q
 - No longer have labels y
 - But have probabilities and sampling
- Consider that our data is sampled from the real world P:

$$egin{aligned} m{X} \sim m{P} \ m{ heta}^* = rgmin_{m{ heta}} \ m{\mathcal{L}}ig(f(m{X}; m{ heta}) ig) \end{aligned}$$

- Examples:
 - Classification: Fitting two multinomial distributions
 - Regression: Fitting a Normal centered around the line of best fit

How do we "fit" Distributions?

- ► Fitting two distributions implies minimizing their difference, i.e. "distance"
- ► This "distance" is known as the divergence between the true distribution *P* and the learned distribution *Q*.

How do we "fit" Distributions?

- Fitting two distributions implies minimizing their difference, i.e.
 "distance"
- ► This "distance" is known as the divergence between the true distribution *P* and the learned distribution *Q*.
- ▶ Divergences must satisfy 2 properties:
 - ▶ $D(P \parallel Q) \ge 0 \quad \forall P, Q \in S$
 - $D(P \parallel Q) = 0 \iff P = Q$

The Kullback-Leibler Divergence

▶ The KL Divergence for distributions *P* and *Q* is defined as:

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} p(x) \log \left(\frac{p(x)}{q(x)}\right) dx$$

The Kullback-Leibler Divergence

▶ The KL Divergence for distributions *P* and *Q* is defined as:

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} p(x) \log \left(\frac{p(x)}{q(x)}\right) dx$$

Note: the KL Divergence is NOT symmetric:

$$D_{KL}(P \parallel Q) \neq D_{KL}(Q \parallel P)$$

But we will come back to this later...

Directionality: Forward KL

▶ This direction is known as the Forward KL

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} p(x) \log \left(\frac{p(x)}{q(x)}\right) dx$$

Directionality: Forward KL

▶ This direction is known as the Forward KL

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} p(x) \log \left(\frac{p(x)}{q(x)} \right) dx$$
$$= \mathbb{E}_{x \sim P} \left[\log \left(\frac{p(x)}{q(x)} \right) \right]$$

Digression: Implementing Expectations

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} p(x) \log \left(\frac{p(x)}{q(x)} \right) dx$$
$$= \mathbb{E}_{x \sim P} \left[\log \left(\frac{p(x)}{q(x)} \right) \right]$$

Algorithm 1 $\mathbb{E}_{x \sim P}[f(x)]$

Expectation of f(x) with respect to P

- 1: $x_1, \ldots, x_n \sim P$ independently
- 2: **return** $\frac{1}{N} \sum_{x_i} f(x_i)$

Note: Maximum Likelihood Estimation is equivalent to minimizing the Forward KL

- Note: Maximum Likelihood Estimation is equivalent to minimizing the Forward KL
- ▶ The KL Divergence can be decomposed into familiar terms:

$$\underset{Q}{\operatorname{argmin}} \ D_{\mathsf{KL}}(P \parallel Q) = \underset{Q}{\operatorname{argmin}} \sum_{x \in \mathcal{X}} p(x) \log \left(\frac{p(x)}{q(x)} \right)$$

- Note: Maximum Likelihood Estimation is equivalent to minimizing the Forward KL
- ▶ The KL Divergence can be decomposed into familiar terms:

$$\begin{aligned} \underset{Q}{\operatorname{argmin}} \ D_{\mathsf{KL}}(P \parallel Q) &= \underset{Q}{\operatorname{argmin}} \sum_{x \in \mathcal{X}} p(x) \log \left(\frac{p(x)}{q(x)} \right) \\ &= \underset{Q}{\operatorname{argmin}} - \sum_{x \in \mathcal{X}} p(x) \log q(x) \\ &+ \sum_{x \in \mathcal{X}} p(x) \log p(x) \end{aligned}$$

- Note: Maximum Likelihood Estimation is equivalent to minimizing the Forward KL
- ▶ The KL Divergence can be decomposed into familiar terms:

$$\begin{aligned} \underset{Q}{\operatorname{argmin}} \ D_{\mathit{KL}}(P \parallel Q) &= \underset{Q}{\operatorname{argmin}} \sum_{x \in \mathcal{X}} p(x) \log \left(\frac{p(x)}{q(x)} \right) \\ &= \underset{Q}{\operatorname{argmin}} - \sum_{x \in \mathcal{X}} p(x) \log q(x) \\ &+ \sum_{x \in \mathcal{X}} p(x) \log p(x) \\ &= \underset{Q}{\operatorname{argmin}} \underbrace{H(P,Q)}_{Cross-Entropy} - \underbrace{H(P)}_{Entropy} \end{aligned}$$

- Note: Maximum Likelihood Estimation is equivalent to minimizing the Forward KL
- ▶ The KL Divergence can be decomposed into familiar terms:

$$\begin{aligned} \operatorname*{argmin} D_{\mathit{KL}}(P \parallel Q) &= \operatorname*{argmin} \sum_{x \in \mathcal{X}} p(x) \log \left(\frac{p(x)}{q(x)} \right) \\ &= \operatorname*{argmin} - \sum_{x \in \mathcal{X}} p(x) \log q(x) \\ &+ \sum_{x \in \mathcal{X}} p(x) \log p(x) \\ &= \operatorname*{argmin} Q \underbrace{H(P,Q)}_{\mathit{Cross-Entropy}} - \underbrace{H(P)}_{\mathit{Entropy}} \\ &= \operatorname*{argmin} Q \underbrace{H(P,Q)}_{\mathit{Cross-Entropy}} - \underbrace{H(P)}_{\mathit{Entropy}} \end{aligned}$$

If we consider $P(y_i = 1|x_i) = p_i$ and $Q(y_i = 1|x_i) = \sigma(f_{\theta}(x_i))$: $\underset{\theta}{\operatorname{argmin}} D_{KL}(P \parallel Q) = \underset{\alpha}{\operatorname{argmin}} - \left[p_i \log \sigma(f_{\theta}(x_i)) + (1 - p_i) \log(1 - \sigma(f_{\theta}(x_i))) \right]$

► This is the Binary Cross-Entropy Loss

Forward KL: Learning a Normal Distribution (Initial)

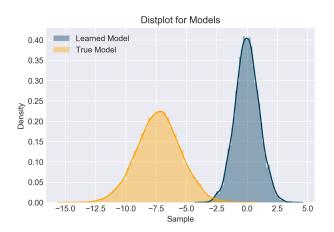


Figure: $P \sim \mathcal{N}(-7.3, 3.2), \ Q \sim \mathcal{N}(0, 1)$

Forward KL: Learning a Normal Distribution (Results)

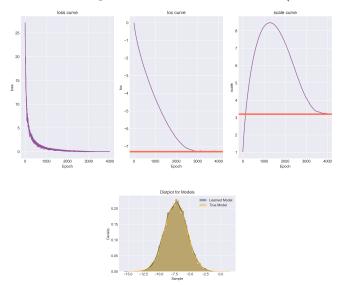


Figure: $P \sim \mathcal{N}(-7.3, 3.2), \ Q \sim \mathcal{N}(-7.28, 3.24)$

Digression: Gaussian Mixture Models

• We can build a K multi-modal distribution, with weights π , as follows:

$$z \sim \mathsf{Categorical}(\pi)$$

 $x \mid z = k \sim \mathsf{Normal}(\mu_k, \sigma_k)$

▶ We can calculate log probabilities by marginalizing out *z*:

$$\log p(x) = \log \sum_{k=1}^{K} \underbrace{p(z=k)}_{\text{Categorical}} \cdot \underbrace{p(x \mid z=k)}_{\text{Normal}}$$

Digression: Mixture Models (Visual)

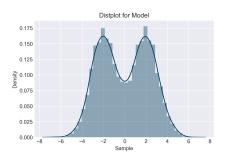


Figure: 2 Mixture Components, Even Weights

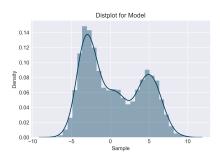


Figure: 3 Mixture Components, Uneven Weights

Forward KL: Learning a Bimodal (Initial)

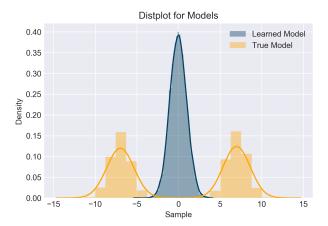
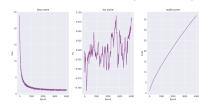


Figure: $P \sim \{\mathcal{N}(-7.3, 1.4), \ \mathcal{N}(7.3, 1.4)\}$ $Q \sim \mathcal{N}(0, 1)$

Forward KL: Learning a Bimodal (Results)



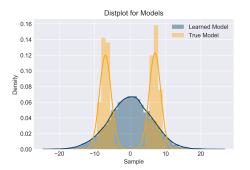


Figure: $Q \sim \mathcal{N}(0.08, 36.76)$



Forward KL: Zero-Avoiding

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} \overbrace{p(x)}^{Constant} \log \left(\frac{\overbrace{p(x)}^{Constant}}{\overbrace{q(x)}^{Variable}} \right) dx$$

- ightharpoonup p(x) is constant-valued, q(x) is variable
- ▶ If Q does not support P, then we will sample a point that has a low probability with respect to Q

Forward KL: Zero-Avoiding

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} \overbrace{p(x)}^{Constant} \log \left(\frac{\overbrace{p(x)}^{Constant}}{\overbrace{q(x)}^{Variable}} \right) dx$$

- ightharpoonup p(x) is constant-valued, q(x) is variable
- If Q does not support P, then we will sample a point that has a low probability with respect to Q
- ▶ As $q(x) \rightarrow 0$, our loss $D_{KL} \rightarrow \infty$

Forward KL: Zero-Avoiding

$$D_{KL}(P \parallel Q) = \int_{-\infty}^{\infty} \overbrace{p(x)}^{\text{Constant}} \log \left(\frac{\overbrace{p(x)}^{\text{Constant}}}{\overbrace{q(x)}^{\text{Variable}}} \right) dx$$

- ightharpoonup p(x) is constant-valued, q(x) is variable
- If Q does not support P, then we will sample a point that has a low probability with respect to Q
- ▶ As $q(x) \rightarrow 0$, our loss $D_{KL} \rightarrow \infty$
- \blacktriangleright Hence, the optimal solution is for Q to cover P, i.e. averaging

Forward KL: Loss Landscape

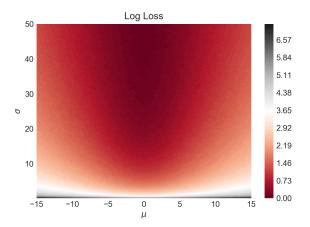


Figure: Loss Landscape for Forward KL Divergence

Directionality: Reverse KL

$$D_{KL}(Q \parallel P) = \int_{-\infty}^{\infty} q(x) \log \left(\frac{q(x)}{p(x)} \right) dx$$
$$= \mathbb{E}_{x \sim Q} \left[\log \left(\frac{q(x)}{p(x)} \right) \right]$$

- ► The Reverse KL will sample from Q, and evaluate the log probabilities from P and Q
- Recall: KL Divergence is not symmetric, and this has drastic implications...

Digression: Differentiable Sampling via the Reparameterization Trick

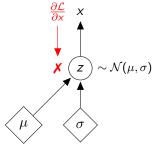


Figure: Original Form

Digression: Differentiable Sampling via the Reparameterization Trick

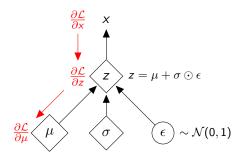


Figure: Reparameterized Version

Digression: Common Reparameterization Tricks

	Reparameterized
$\mathcal{N}(\mu,\sigma)$	$\mu + \sigma \odot \mathcal{N}(0,1)$
$\mathcal{U}(a,b)$	$a+(b-a)\odot\mathcal{U}(0,1)$
$Exp(\lambda)$	$Exp(1)/\lambda$
$Cauchy(\mu,\gamma)$	$\mu + \gamma \odot Cauchy(0,1)$

Digression: Common Reparameterization Tricks

	Reparameterized
$\mathcal{N}(\mu,\sigma)$	$\mu + \sigma \odot \mathcal{N}(0,1)$
$\mathcal{U}(a,b)$	$a + (b - a) \odot \mathcal{U}(0, 1)$
$Exp(\lambda)$	$Exp(1)/\lambda$
$Cauchy(\mu,\gamma)$	$\mu + \gamma \odot Cauchy(0,1)$
$Laplace(\mu, \pmb{b})$	$egin{aligned} u &\sim \mathcal{U}(-1,1) \ \mu - b \odot \operatorname{sgn}(u) \odot \operatorname{In} ig[- u +1 ig] \end{aligned}$

Digression: Common Reparameterization Tricks

	Reparameterized
$\mathcal{N}(\mu,\sigma)$	$\mu + \sigma \odot \mathcal{N}(0,1)$
$\mathcal{U}(a,b)$	$a+(b-a)\odot\mathcal{U}(0,1)$
$Exp(\lambda)$	$Exp(1)/\lambda$
$Cauchy(\mu,\gamma)$	$\mu + \gamma \odot Cauchy(0,1)$
$Laplace(\mu, \pmb{b})$	$egin{aligned} u &\sim \mathcal{U}(-1,1) \ \mu - b \odot sgn(u) \odot ln\left[- u + 1 ight] \end{aligned}$
$Categorical(\pi)$	×

Reverse KL: Learning a Bimodal (Initial)

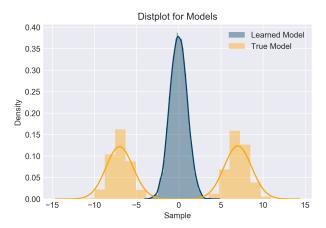
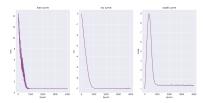


Figure: $P \sim \{\mathcal{N}(-7.3, 1.4), \ \mathcal{N}(7.3, 1.4)\}$ $Q \sim \mathcal{N}(0, 1)$

Reverse KL: Learning a Bimodal (Results)



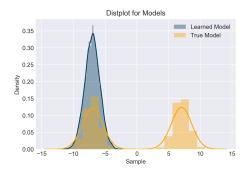
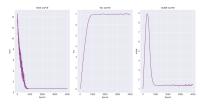


Figure: $Q \sim \mathcal{N}(-7.02, 1.41)$

Reverse KL: Learning a Bimodal Attempt 2 (Results)



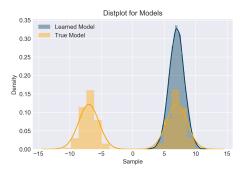


Figure: $Q \sim \mathcal{N}(7.01, 1.46)$

Reverse KL: Zero-Forcing

$$D_{KL}(Q \parallel P) = \int_{-\infty}^{\infty} q(x) \log \left(\frac{q(x)}{p(x)}\right) dx$$

- Unlike the Forward KL, Reverse KL is Zero-forcing
- Why? Because we no longer suffer a penalty from q(x) = 0
- ► However, if p(x) = 0, then the optimal value for q(x)is 0
- ▶ Result ⇒ Mode Collapse

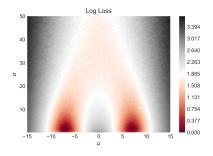


Figure: Loss Landscape for Reverse KL Divergence

Jensen - Shannon Divergence: A Symmetric Divergence

$$JSD(P \parallel Q) = \frac{1}{2}D_{KL}(P \parallel M) + \frac{1}{2}D_{KL}(Q \parallel M)$$
$$M = \frac{1}{2}(P + Q)$$

- ► The JS Divergence is a symmetrized version of the KL Divergence
- M is the average of distributions P and Q, and can be represented as a Mixture Model

Jensen - Shannon Divergence: Bimodal (Initial)

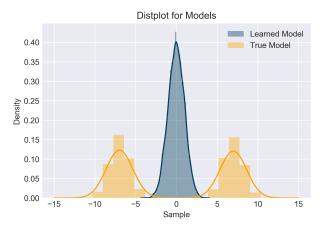
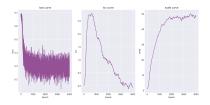


Figure: $P \sim \{\mathcal{N}(-7.3, 1.4), \ \mathcal{N}(7.3, 1.4)\}$ $Q \sim \mathcal{N}(0, 1)$

Jensen - Shannon Divergence: Bimodal (Result)



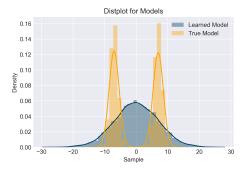


Figure: $Q \sim \mathcal{N}(-0.04, 48.20)$

Jensen - Shannon Divergence: Right Shift (Attempt 2)

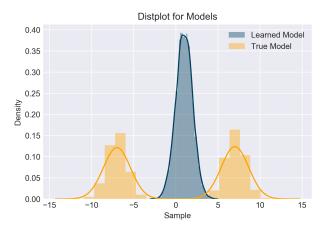
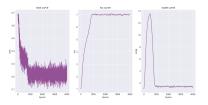


Figure: $P \sim \{\mathcal{N}(-7.3, 1.4), \ \mathcal{N}(7.3, 1.4)\}$ $Q \sim \mathcal{N}(1, 1)$

Jensen - Shannon Divergence: Right Shift (Result)



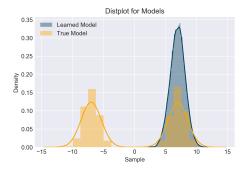


Figure: $Q \sim \mathcal{N}(6.99, 1.43)$

Jensen - Shannon Divergence: Left Shift (Attempt 3)

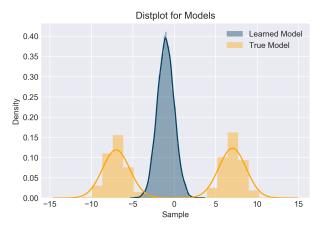
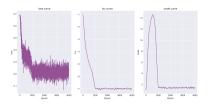


Figure: $P \sim \{\mathcal{N}(-7.3, 1.4), \ \mathcal{N}(7.3, 1.4)\}$ $Q \sim \mathcal{N}(-1, 1)$

Jensen - Shannon Divergence: Left Shift (Result)



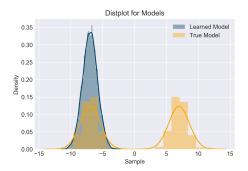


Figure: $Q \sim \mathcal{N}(-6.98, 1.38)$

Jensen - Shannon Divergence Loss

$$JSD(P \parallel Q) = \frac{1}{2}D_{KL}(P \parallel M) + \frac{1}{2}D_{KL}(Q \parallel M)$$
$$M = \frac{1}{2}(P + Q)$$

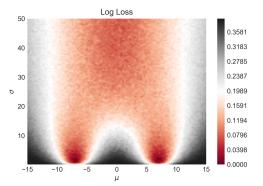


Figure: Loss Landscape for JS Divergence

A Family of Divergences: f-Divergence

- ► KL Divergence is a special case of the *f*-divergence
- ► The *f*-divergence is a family of divergences that can be written as:

$$D_f(P \parallel Q) = \int \underbrace{q(x)}^{\text{Weight}} f \underbrace{\left(\frac{p(x)}{q(x)}\right)}_{\text{Odds Ratio}} dx$$

A Family of Divergences: f-Divergence

$$D_f(P \parallel Q) = \int \underbrace{q(x)}^{\text{Weight}} f \underbrace{\left(\frac{p(x)}{q(x)}\right)}_{\text{Odds Ratio}} dx$$

Divergence	f(t)
Forward KL Reverse KL	t log t — log t
Hellinger Distance	$(\sqrt{t}-1)^2, 2(1-\sqrt{t})$
Total Variation	$ \frac{1}{2} t-1 $
Pearson χ^2 Neyman χ^2 (Reverse Pearson)	$ \left \begin{array}{c} (t-1)^2, \ t^2 - 1, \ t^2 - t \\ \frac{1}{t} - 1, \ \frac{1}{t} - t \end{array} \right $

Earth Mover's Distance (Wasserstein-1)

$$W(P,Q) = \inf_{\gamma \in \prod (P,Q)} \mathbb{E}_{(x,y) \sim \gamma} [\parallel x - y \parallel]$$

- ► $\prod(P,Q)$ is the set of joint distributions $\gamma(x,y)$ whose marginals are P and Q
- $\gamma(x,y)$ indicated how much "mass" must be transported from x to y to transform P to Q
- ► EMD is the "cost" of the optimal transport plan

Summary of Methods

	Р		Q	
	$\log p(x)$	$x \sim P$	$\log q(x)$	$x \sim Q$
Cross-Entropy		✓	✓	
Forward KL	✓	✓	✓	
Reverse KL	✓		✓	✓
JS Divergence	✓	✓	✓	✓
<i>f</i> -Divergence	✓	✓	✓	\checkmark

Practical Uses of Divergences

- Forward Kullback-Leibler
 - Maximum Likelihood Estimation
- Reverse Kullback-Leibler
 - Variational Autoencoders
 - Variational Inference
- Jensen-Shannon Divergence
 - Generative Adversarial Network (Original)
- Earth Mover's Distance
 - Wasserstein GAN (WGAN)
- ▶ Pearson χ^2 Divergence
 - Least Squares GAN (LSGAN)

Potpourri: Advanced Techniques

	Р		Q	
	$\log p(x)$	$x \sim P$	$\log q(x)$	$x \sim Q$
Cross-Entropy		✓	✓	
Forward KL	✓	✓	✓	
Reverse KL	✓		✓	✓
JS Divergence	✓	✓	✓	✓
f-Divergence	✓	✓	✓	\checkmark
Adversarial		✓		✓

Potpourri: Advanced Techniques

- 1. Transforms
 - Normalizing Flow Models
- 2. Expectation–Maximization
- 3. Variational Inference
 - ELBO
- 4. Adversarial Training (GANs, GANs, GANs)
- 5. Markov Chain Monte Carlo
 - Metropolis-Hastings
 - Gibbs Sampling
 - ► Hamiltonian Monte Carlo
 - NUTS