

## FT64F0AX

# IR\_Receive Application note



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## FT64F0Ax IR\_Receive 应用

#### 1. IR 介绍

一个通用的红外遥控系统由发射和接收两大部分组成,如图 1 所示:

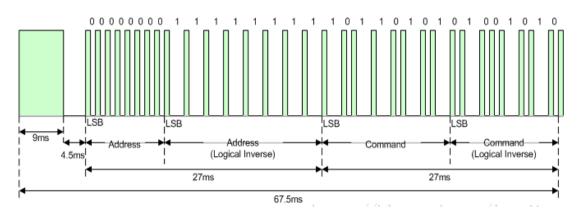


图 1-1

发射部分主要包括键盘矩阵、编码调制、红外发射管;接收部分包括光、电信号的转换以及放大、 解调、解码电路。

举例来说,通常我们家电遥控器信号的发射,就是将相应按键所对应的控制指令和系统码(由 0 和 1 组成的序列),调制在 32~56kHz 范围内的载波上(目的为: 抗干扰及低功率),然后经放大(接三极管)、驱动红外发射管(透明的头)将信号发射出去。

本讲解以 IC FT64F0A5 TSSOP20 为示范,采用一体的红外接收头,接收头输出脚连到 MCU 的 IO 口,IO 口通过识别高低电平时间长短来解码,当收到的数据是合法的,指示 LED 的状态(开与关)会翻转一次。接收的 IO 口使用电平变化中断来识别信号,并使用定时器记录电平的时间长短。



#### 2. 应用范例

```
/* 文件名: TEST 64F0Ax IR Receive.c
* 功能:
        FT64F0Ax IR Receive 功能演示
* IC:
         FT64F0A5 TSSOP20
* 内部:
        16M/4T
* 说明:
         演示程序中, IR 红外是采用 6122 协议, 起始信号是 9ms 低电平,
         到 4.5ms 高电平, 再到低 8 位用户识别码, 到高 8 位的用户识别码,
         8位数据码,8位数据码的反码。RXIO(RC3)每次收到遥控器发过来的数据后,
         数据是合法(两对补码,不对内容判断)的话,LED(RB3)开关状态就改变一次。)
        FT64F0A5 TSSOP20
* NC-----|1(PA5)
                  (PA4)20|----NC
                  (PA3)19|-----IRRIO
* NC-----|2(PA6)
* NC-----|3(PA7)
                  (PA2)18|----NC
* NC-----|4(PC0)
                  (PA1)17|----NC
* NC-----|5(PC1)
                  (PA0)16|----NC
* NC-----|6(PB7)
                  (PB0)15|----NC
* GND-----|7(GND)
                  (PB1)14|----NC
                  (PB2)13|----NC
* NC-----|8(PB6)
* VDD-----|9(VDD)
                  (PB3)12|-----LED
* NC-----|10(PB5)
                  (PB4)11|----NC
#include
         "SYSCFG.h";
#include
         "FT64F0AX.h";
#define
                  unsigned char
         uchar
#define
         LED
                  PB3
                              //LED 指示灯的 IO
#define
                  PA3
                              //IR 的接收脚
         IRRIO
uchar IRbitNum = 0;
                              //用于记录接收到第几位数据了
uchar IRbitTime = 0;
                              //用于计时一位的时间长短
volatile uchar IRDataTimer[4];
                              //存放 4 个数据
uchar bitdata=0x01;
                              //用于按位或的位数据
uchar ReceiveFinish = 0;
                              //用于记录接收完成
uchar ReadAPin = 0;
                              //用于读取 IO 口状态, 电平变化中断标志清除
volatile uchar rdata1,rdata2;
* 函数名: interrupt ISR
* 功能:
        定时器 4 中断和外部中断
```

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{

```
* 输入:
           无
 * 输出:
          无
void interrupt ISR(void)
   //定时器 4 的中断处理
   if(T4UIE&&T4UIF)
                                        //写 1 清零标志位
        T4UIF=1;
        IRbitTime++;
        if(IRbitTime>50)
            T4UIE=0;
            IRbitTime=0;
        }
   }
   //Px 电平变化中断
   if(EPIF0&0X08)
        EPIF0|=0X08;
                                        //写 1 清零标志位
        if(IRRIO==0)
        {
            T4UIE=1;
            if(IRbitTime>21)
                IRDataTimer[0]=0;
                IRDataTimer[1]=0;
                IRDataTimer[2]=0;
                IRDataTimer[3]=0;
                IRbitNum=0;
                bitdata=0x00;
           }
            else if(IRbitTime>3)
                IRDataTimer[IRbitNum-1]|=bitdata;
            IRbitTime = 0;
            bitdata<<=1;
            if(bitdata==0)
                bitdata=0x01;
```

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```
IRbitNum++;
          }
          if(IRbitNum>4)
             IRbitNum=0;
             T4UIE=0;
             ReceiveFinish=1;
          }
      }
   }
}
* 函数名: POWER_INITIAL
* 功能:
         上电系统初始化
* 输入:
         无
* 输出:
void POWER INITIAL(void)
{
   OSCCON=0B01110001;
                                  //16MHz,分频比为 1:1
                                  //禁止所有中断
   INTCON=0;
   PORTA=0B000000000;
   PORTB=0B000000000;
   PORTC=0B00000000;
   WPUA=0B00001000;
                                  //弱上拉的开关, 0-关, 1-开
   WPUB=0B00000000;
   WPUC=0B00000000;
   WPDA=0B00000000;
                                  //弱下拉的开关, 0-关, 1-开
   WPDB=0B00000000;
   WPDC=0B00000000;
                                  //输入输出设置, 0-输出, 1-输入
   TRISA=0B111111111;
   TRISB=0B11110111;
                                  //PB3-OUT
   TRISC=0B00000011;
                                  //源电流设置最大
   PSRC0=0B11111111;
   PSRC1=0B11111111;
   PSRC2=0B00001111;
   PSINK0=0B11111111;
                                  //灌电流设置最大
   PSINK1=0B11111111;
```



```
PSINK2=0B00000011;
  ANSELA=0B00000000;
                              //设置对应的 IO 为数字 IO
}
* 函数名: TIMER4_INITIAL
* 功能: 初始化定时器,设置 TIMER4 定时时长 560 µs
* 输入: 无
* 输出: 无
void TIMER4_INITIAL(void)
{
   PCKEN|=0B00001000;
                              //使能 TIMER4 时钟模块
                              //允许自动装载,使能计数器
   TIM4CR1=0B00000101;
   TIM4IER=0B00000001;
                               //允许更新中断
   TIM4SR=0B000000000;
   TIM4EGR=0B00000000;
   TIM4CNTR=0;
   TIM4PSCR=0B00000110;
                              //Bit[2:0]:预分频比为 1:64
   TIM4ARR=140;
                               //自动装载值
}
* 函数名: Px Level Change INITIAL
* 功能: 端口电平变化中断初始化
* 输入: 无
* 输出: 无
void Px Level Change INITIAL(void)
{
                               //选择 PA3 管脚中断
   EPS0=0B00000000;
   EPS1=0B000000000;
   ITYPE0=0B11000000;
                               //双边沿中断
   ITYPE1=0B00000000;
   EPIE0=0B00001000;
                              //允许外部中断 3
   INTCON=0B01000000;
                               //使能外设中断
}
/*-----
* 函数名: main
* 功能: 主函数
* 输入: 无
* 输出: 无
void main(void)
```

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```
POWER_INITIAL();
                                       //系统初始化
   TIMER4_INITIAL();
   Px_Level_Change_INITIAL();
   GIE=1;
                                       //开启总中断
   while(1)
   {
       if(ReceiveFinish==1)
       {
            ReceiveFinish=0;
            rdata1=0xFF-IRDataTimer[0];
            rdata2=0xFF-IRDataTimer[2];
            if((rdata1==IRDataTimer[1])&&(rdata2==IRDataTimer[3]))
                                       //翻转电平
               LED=~LED;
           }
       }
   }
}
```

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