# Lecture 1: Boosting, Feature Importance estimation

Radoslav Neychev

### **Outline**

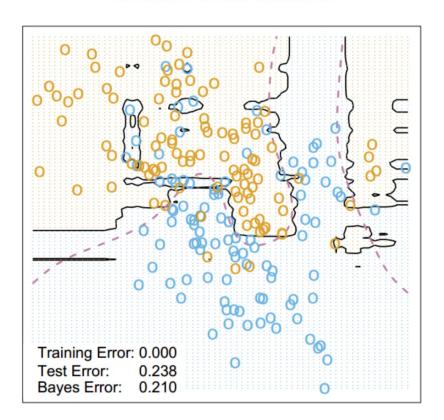
- 1. Ensembling methods recap
- 2. Boosting intuition
- 3. Gradient boosting
- 4. Feature importance estimation
- 5. Shap values

### Random Forest

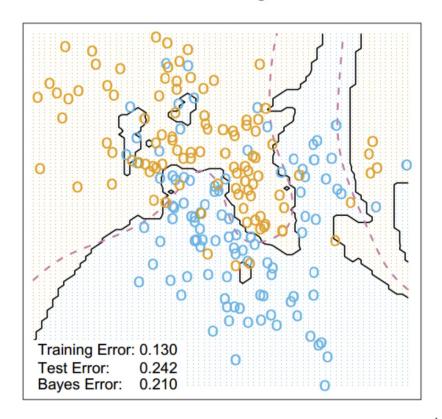
- One of the greatest "universal" models.
- There are some modifications: Extremely Randomized Trees, Isolation Forest, etc.
- Allows to use train data for validation: OOB

OOB = 
$$\sum_{i=1}^{\ell} L\left(y_i, \frac{1}{\sum_{n=1}^{N} [x_i \notin X_n]} \sum_{n=1}^{N} [x_i \notin X_n] b_n(x_i)\right)$$

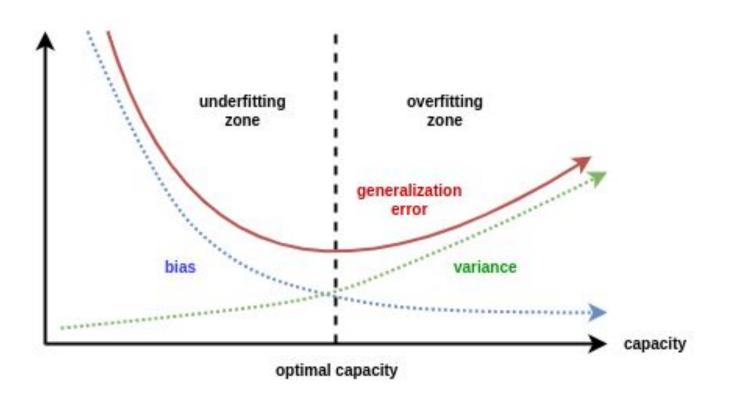
#### Random Forest Classifier



#### 3-Nearest Neighbors

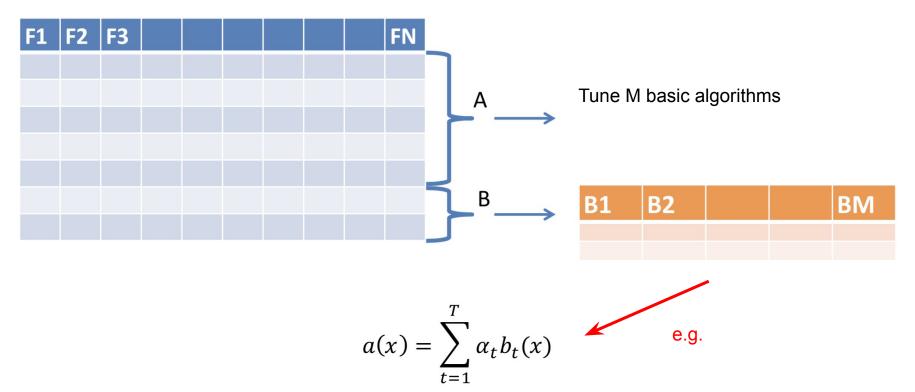


### Bias-variance tradeoff



### Stacking

How to build an ensemble from different models?



### Stacking

How to build an ensemble from *different* models?

- Use different datasets (or datasets parts) for different level models.
- Experiment with different models (linear, trees ensembles, simple networks, etc.)
- Or just different GBT ensembles (hola, kaggle :)

### Blending

Just combine several *strong/complex* models.

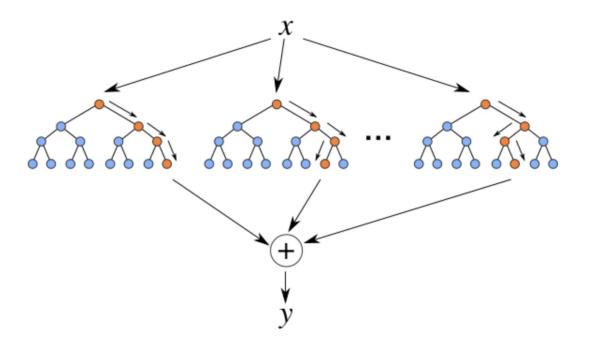
Weights should sum up to 1 and come from [0; 1]

$$a(x) = \sum_{t=1}^{I} \alpha_t b_t(x)$$

- Simple and intuitive ensembling method.
- Finding optimal weights could be tricky.
- Linear composition is not always enough.

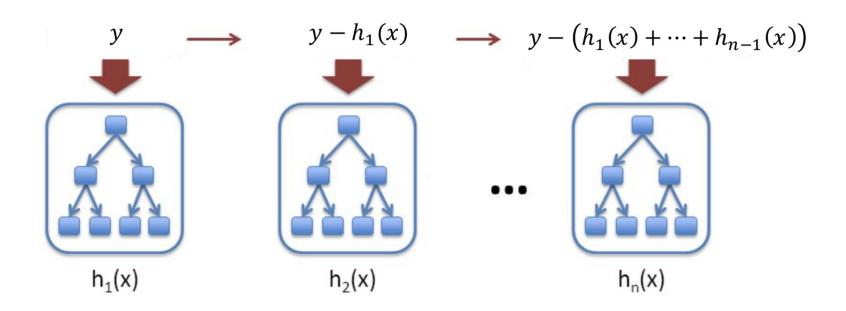
### Random Forest

### Bagging + RSM = Random Forest

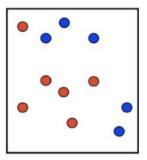


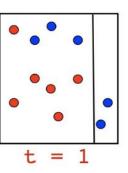
### Gradient boosting

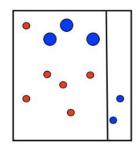
$$a_n(x) = h_1(x) + \dots + h_n(x)$$

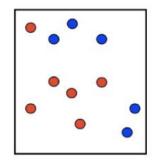


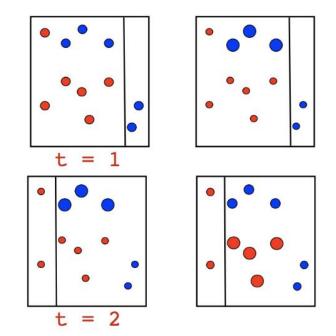
Binary classification problem. Models - decision stumps.

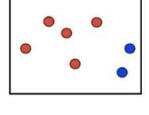


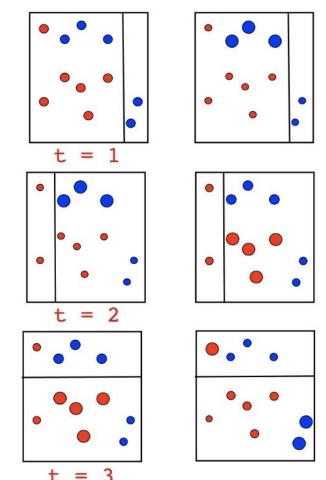




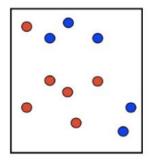


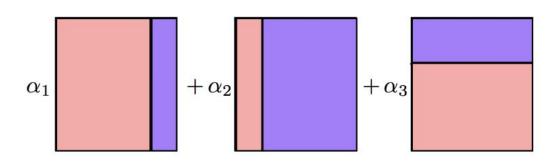


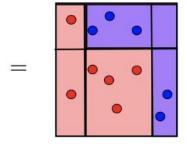




Binary classification problem. Models - decision stumps.







Denote dataset  $\{(x_i, y_i)\}_{i=1,...,n}$ , loss function L(y, f).

Denote dataset  $\{(x_i, y_i)\}_{i=1,...,n}$ , loss function L(y, f).

Optimal model:

$$\hat{f}(x) = \underset{f(x)}{\operatorname{arg\,min}} L(y, f(x)) = \underset{f(x)}{\operatorname{arg\,min}} \mathbb{E}_{x,y}[L(y, f(x))]$$

Denote dataset  $\{(x_i, y_i)\}_{i=1,...,n}$ , loss function L(y, f).

Optimal model:

$$\hat{f}(x) = \underset{f(x)}{\operatorname{arg \, min}} \ L(y, f(x)) = \underset{f(x)}{\operatorname{arg \, min}} \ \mathbb{E}_{x,y}[L(y, f(x))]$$

Let it be from parametric family:  $\hat{f}(x) = f(x, \hat{\theta}),$ 

$$\hat{\theta} = \underset{\theta}{\operatorname{arg\,min}} \mathbb{E}_{x,y}[L(y, f(x, \theta))]$$

$$\hat{f}(x) = \sum_{i=0}^{t-1} \hat{f}_i(x),$$

$$(\rho_t, \theta_t) = \underset{\rho, \theta}{\arg\min} \ \mathbb{E}_{x,y} [L(y, \hat{f}(x) + \rho \cdot h(x, \theta))],$$

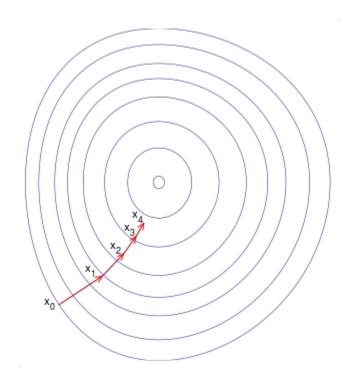
$$\hat{f}_t(x) = \rho_t \cdot h(x, \theta_t)$$

$$\hat{f}(x) = \sum_{i=0}^{t-1} \hat{f}_i(x),$$

$$(\rho_t, \theta_t) = \underset{\rho, \theta}{\operatorname{arg\,min}} \mathbb{E}_{x,y}[L(y, \hat{f}(x) + \rho \cdot h(x, \theta))],$$

$$\hat{f}_t(x) = \rho_t \cdot h(x, \theta_t)$$

What if we could use gradient descent in space of our models?



What if we could use gradient descent in space of our models?

$$\hat{f}(x) = \sum_{i=1}^{t-1} \hat{f}_i(x),$$

$$r_{it} = -\left[\frac{\partial L(y_i, f(x_i))}{\partial f(x_i)}\right]_{f(x) = \hat{f}(x)}, \quad \text{for } i = 1, \dots, n,$$

$$\theta_t = \underset{\theta}{\operatorname{arg\,min}} \sum_{i=1}^n (r_{it} - h(x_i, \theta))^2,$$

$$\rho_t = \underset{\rho}{\operatorname{arg\,min}} \sum_{i=1}^n L(y_i, \hat{f}(x_i) + \rho \cdot h(x_i, \theta_t))$$

In linear regression case with MSE loss:

$$r_{it} = -\left[\frac{\partial L(y_i, f(x_i))}{\partial f(x_i)}\right]_{f(x) = \hat{f}(x)} = -2(\hat{y}_i - y_i) \propto \hat{y}_i - y_i$$

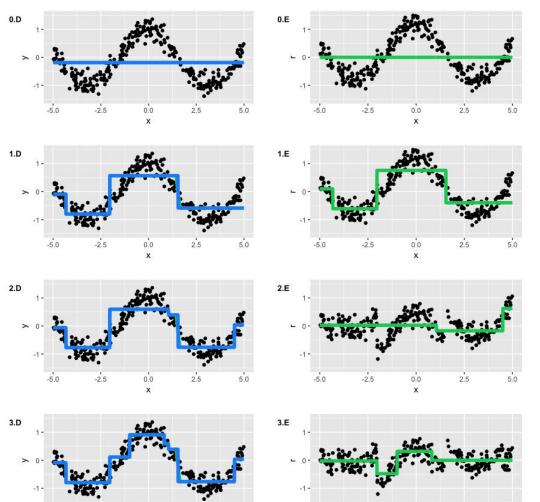
#### What we need:

- Data.
- Loss function and its gradient.
- Family of algorithms (with constraints on hyperparameters if necessary).
- Number of iterations M.
- Initial value (GBM by Friedman): constant.

### Gradient boosting: example

#### What we need:

- Data: toy dataset  $y = cos(x) + \epsilon, \epsilon \sim \mathcal{N}(0, \frac{1}{5}), x \in [-5, 5]$
- Loss function: MSE
- Family of algorithms: decision trees with depth 2
- Number of iterations M = 3
- Initial value: just mean value

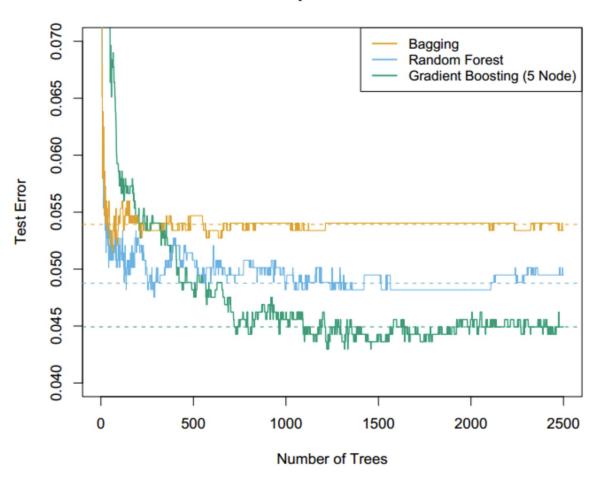


## Gradient boosting: example

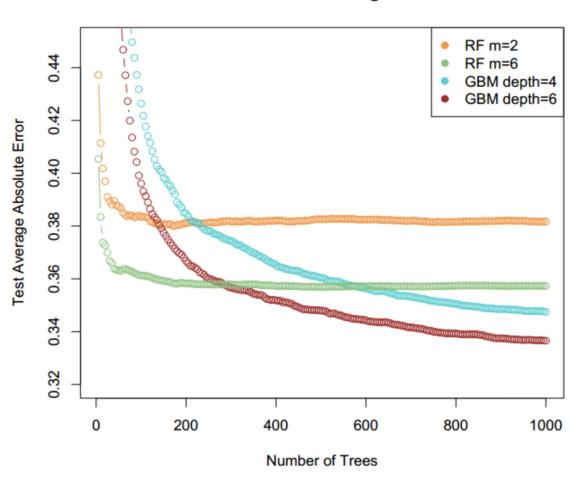
Left: full ensemble on each step.

Right: additional tree decisions.

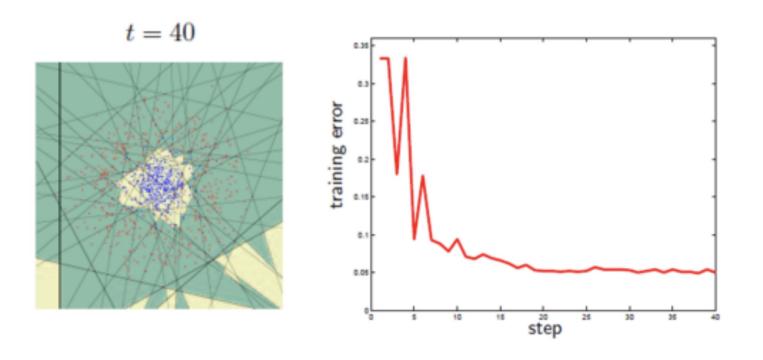
#### **Spam Data**



#### **California Housing Data**



### Boosting with linear classification methods



### Technical side: training in parallel

Which of the ensembling methods could be parallelized?

### Technical side: training in parallel

Which of the ensembling methods could be parallelized?

Random Forest: parallel on the forest level (all trees are independent)

### Technical side: training in parallel

Which of the ensembling methods could be parallelized?

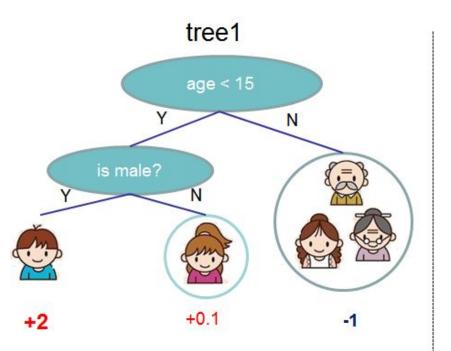
- Random Forest: parallel on the forest level (all trees are independent)
- Gradient boosting: parallel on one tree level

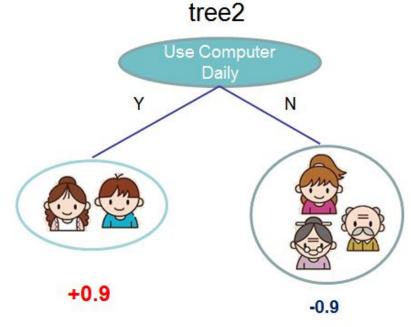
### Recap: ensembling methods

- 1. Bagging.
- 2. Random subspace method (RSM).
- 3. Bagging + RSM + Decision trees = Random Forest.
- 4. Gradient boosting.
- 5. Stacking.
- 6. Blending.

Great demo: <a href="http://arogozhnikov.github.io/2016/06/24/gradient\_boosting\_explained.html">http://arogozhnikov.github.io/2016/06/24/gradient\_boosting\_explained.html</a>

### Feature importance estimation





$$) = 2 + 0.9 = 2.9$$

$$)=-1-0.9=-1.9$$

### Feature importance estimation

- 1. Permutation importance
- 2. Partial Dependence Plots (PDP)
- 3. Tree specific:
  - a. Gain
  - b. Frequency (Split Count)
  - c. Cover (weighted Split Count)
- 4. Shap

### Permutation importance

Height at age 20 (cm)	Height at age 10 (cm)	 Socks owned at age 10
182	155	 20
175	147	 10
156	142	 8
153	130	 24

### Permutation importance

Height at age 20 (cm)	Height at age 10 (cm)	 Socks owned at age 10
182	155	 20
175	147	 10
	( <del>A</del>	 
156	142	 8
153	130	 24

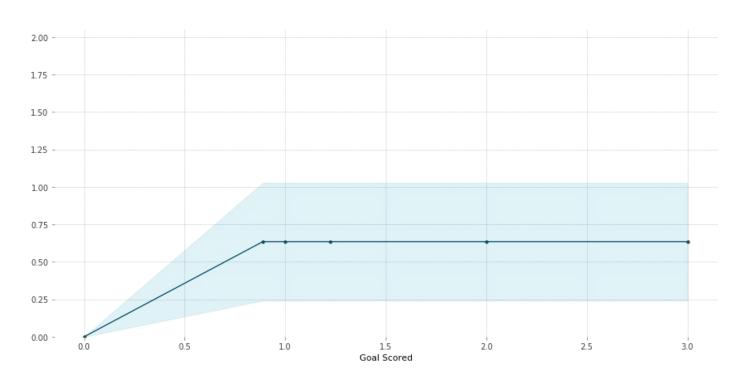
#### Train model

Observe changes caused by feature random permutations

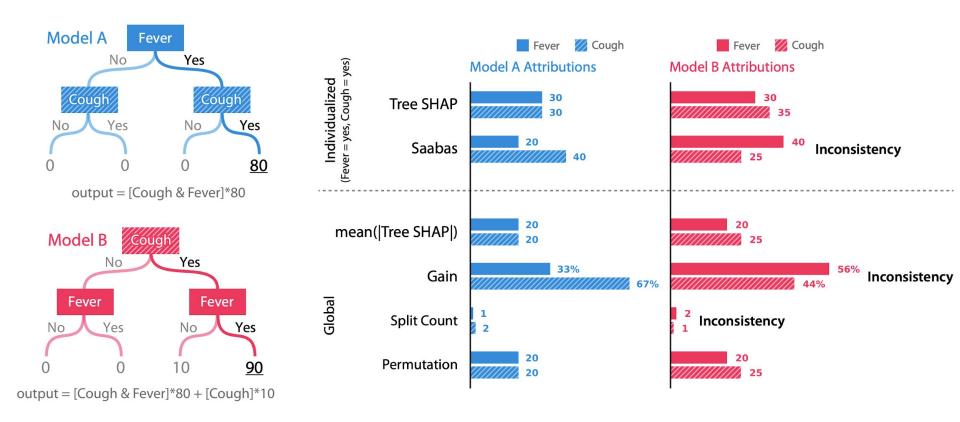
### Partial Dependence Plots

#### PDP for feature "Goal Scored"

Number of unique grid points: 6



### Importance estimation problems



### Shap values

Consider i-th feature. Shap value will be

$$\phi_i(p) = \sum_{S \subseteq N/\{i\}} rac{|S|!(n-|S|-1)!}{n!} (p(S \cup \{i\}) - p(S))$$

where  $p(S \cup \{i\})$  is model prediction on feature subset S with *i-th* feature added.

### Shap values

Consider i-th feature. Shap value will be

$$\phi_i(p) = \sum_{S \subseteq N/\{i\}} rac{|S|!(n-|S|-1)!}{n!} (p(S \cup \{i\}) - p(S))$$

where  $p(S \cup \{i\})$  is model prediction on feature subset S with *i-th* feature added.

SHAP values are the only consistent and locally accurate individualized feature attributions

### Outro

- 1. Bagging + RSM + Decision trees = Random Forest.
- 2. Gradient boosting is powerful but prone to overfitting
- 3. Stacking & Blending are great techniques
- 4. Consider using SHAP values to estimate feature importances.

Great demo: <a href="http://arogozhnikov.github.io/2016/06/24/gradient boosting explained.html">http://arogozhnikov.github.io/2016/06/24/gradient boosting explained.html</a>