

gSOAP 2.7.5 User Guide

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1 Introduction

The gSOAP compiler tools provide a SOAP/XML-to-C/C++ language binding to ease the development of SOAP/XML Web services and client application in C and/or C++. Most toolkits for C++ Web services adopt a SOAP-centric view and offer APIs for C++ that require the use of class libraries for SOAP-specific data structures. This often forces a user to adapt the application logic to these libraries. In contrast, gSOAP provides a C/C++ transparent SOAP API through the use of compiler technology that hides irrelevant SOAP-specific details from the user. The gSOAP stub and skeleton compiler automatically maps native and user-defined C and C++ data types to semantically equivalent XML data types and vice-versa. As a result, full SOAP interoperability is achieved with a simple API relieving the user from the burden of SOAP details, thus enabling him or her to concentrate on the application-essential logic. The compiler enables the integration of (legacy) C/C++ and Fortran codes (through a Fortran to C interface), embedded systems, and real-time software in SOAP applications that share computational resources and information with other SOAP applications, possibly across different platforms, language environments, and disparate organizations located behind firewalls.

gSOAP minimizes application adaptation for building Web Services. The gSOAP compiler generates SOAP marshalling routines that (de)serialize application-specific C/C++ data structures. gSOAP includes a WSDL generator to generate Web service descriptions for your Web services. The gSOAP WSDL parser and importer "closes the circle" in that it enables client development without the need for users to analyze Web service details to implement a client or a server.

Some of the highlights of gSOAP are:

- Unique interoperability features: the gSOAP compiler generates SOAP marshalling routines that (de)serialize native and user-defined C and C++ data structures.
- gSOAP supports WSDL 1.1, SOAP 1.1, SOAP 1.2, SOAP RPC encoding style, and literal/document style.
- gSOAP is one of the few SOAP toolkits that support the full range of SOAP 1.1 RPC encoding features including sparse multi-dimensional arrays and polymorphic types. For example, a remote method with a base class parameter may accept derived class instances from a client. Derived class instances keep their identity through dynamic binding.
- gSOAP supports MIME (SwA), DIME, and MTOM attachments.
- gSOAP is the only toolkit that supports *streaming* DIME attachment transfers, which allows you to exchange binary data of practically unlimited size in the fastest possible way (streaming) while ensuring the usefulness of XML interoperability.
- gSOAP supports SOAP-over-UDP.
- gSOAP supports IPv4 and IPv6.
- gSOAP supports Zlib deflate and gzip compression (for HTTP, TCP/IP, and XML file storage).
- gSOAP supports SSL (HTTPS).

- gSOAP supports HTTP/1.0, HTTP/1.1 keep-alive, chunking, and basic authentication,
- gSOAP supports SOAP one-way messaging.
- The schema-specific XML pull parser is fast and efficient and does not require intermediate data storage for demarshalling to save space and time.
- gSOAP includes a WSDL generator for convenient Web Service publishing.
- gSOAP includes a WSDL parser (WSDL converter to gSOAP header files) for automated client and server development.
- Generates source code for stand-alone Web Services and client applications.
- Ideal for small devices such as Palm OS, Symbian, Pocket PC, because the memory footprint is small.
- Ideal for building web services that are compute-intensive and are therefore best written in C and C++.
- Platform independent: Windows, Unix, Linux, Mac OS X, Pocket PC, Palm OS, Symbian, etc.
- Supports serializing of application's native C and C++ data structures, which allows you to save and load of XML serialized data structures to and from files.
- Selective input and output buffering is used to increase efficiency, but full message buffering to determine HTTP message length is not used. Instead, a three-phase serialization method is used to determine message length. As a result, large data sets such as base64-encoded images can be transmitted with or without DIME attachments by small-memory devices such as PDAs.
- Supports C++ single class inheritance, dynamic binding, overloading, arbitrary pointer structures such as lists, trees, graphs, cyclic graphs, fixed-size arrays, (multi-dimensional) dynamic arrays, enumerations, built-in XSD Schema types including base64Binary encoding, and hexBinary encoding.
- No need to rewrite existing C/C++ applications for Web service deployment. However, parts of an application that use unions, pointers to sequences of elements in memory, and **void*** need to be modified, but **only** if the data structures that adopt them are required to be serialized or deserialized as part of a remote method invocation.
- Three-phase marshalling: 1) analysis of pointers, single-reference, multi-reference, and cyclic data structures, 2) HTTP message-length determination, and 3) serialization as per SOAP 1.1 encoding style or user-defined encoding styles.
- Two-phase demarshalling: 1) SOAP parsing and decoding, which involves the reconstruction of multi-reference and cyclic data structures from the payload, and 2) resolution of "forward" pointers (i.e. resolution of the forward **href** attributes in SOAP).
- Full and customizable SOAP Fault processing (client receive and service send).

- Customizable SOAP Header processing (send and receive), which for example enables easy transaction processing for the service to keep state information.

2 Notational Conventions

The typographical conventions used by this document are:

`Sans serif or italics font` denotes C and C++ source code, file names, and shell/batch commands.

Bold font denotes C and C++ keywords.

`Courier font` denotes HTTP header content, HTML, XML, XML Schema content and WSDL content.

[Optional] denotes an optional construct.

The keywords "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in RFC-2119.

3 Differences Between gSOAP Versions 2.4 (and Earlier) and 2.5

To comply with WS-I Basic Profile 1.0a, gSOAP 2.5 and higher adopts SOAP RPC literal by default. There is no need for concern, because the WSDL parser `wsdl2h` automatically takes care of the differences when you provide a WSDL document, because SOAP RPC encoding, literal, and document style are supported. A new `soapcpp2` compiler option was added `-e` for backward compatibility with gSOAP 2.4 and earlier to adopt SOAP RPC encoding by default in case you want to develop a service that uses SOAP encoding. You can also use the gSOAP compiler directives to specify SOAP encoding for individual operations, when desired.

4 Differences Between gSOAP Versions 2.1 (and Earlier) and 2.2

You should read this section only if you are upgrading from gSOAP 2.1 to 2.2 and later.

Run-time options and flags have been changed to enable separate `recv/send` settings for transport, content encodings, and mappings. The flags are divided into four classes: transport (IO), content encoding (ENC), XML marshalling (XML), and C/C++ data mapping (C). The old-style flags `soap_disable_X` and `soap_enable_X`, where X is a particular feature, are deprecated. See Section 9.12 for more details.

5 Differences Between gSOAP Versions 1.X and 2.X

You should read this section only if you are upgrading from gSOAP 1.X to 2.X.

gSOAP versions 2.0 and later have been rewritten based on versions 1.X. gSOAP 2.0 and later is thread-safe, while 1.X is not. All files in the gSOAP 2.X distribution are renamed to avoid confusion with gSOAP version 1.X files:

gSOAP 1.X	gSOAP 2.X
soapcpp	soapcpp2
soapcpp.exe	soapcpp2.exe
stdsoap.h	stdsoap2.h
stdsoap.c	stdsoap2.c
stdsoap.cpp	stdsoap2.cpp

Changing the version 1.X application codes to accommodate gSOAP 2.X does not require a significant amount of recoding. The change to gSOAP 2.X affects all functions defined in `stdsoap2.c[pp]` (the gSOAP runtime environment API) and the functions in the sources generated by the gSOAP compiler (the gSOAP RPC+marshalling API). Therefore, clients and services developed with gSOAP 1.X need to be modified to accommodate a change in the calling convention used in 2.X: In 2.X, **all** gSOAP functions (including the remote method proxy routines) take an additional parameter which is an instance of the gSOAP runtime environment that includes file descriptors, tables, buffers, and flags. This additional parameter is **always** the first parameter of any gSOAP function.

The gSOAP runtime environment is stored in a **struct soap** type. A **struct** was chosen to support application development in C without the need for a separate gSOAP implementation. An object-oriented approach with a class for the gSOAP runtime environment would have prohibited the implementation of pure C applications. Before a client can invoke remote methods or before a service can accept requests, a runtime environment need to be allocated and initialized. Three new functions are added to gSOAP 2.X:

Function	Description
<code>soap_init(struct soap *soap)</code>	Initializes a runtime environment (required only once)
<code>struct soap *soap_new()</code>	Allocates, initializes, and returns a pointer to a runtime environment
<code>struct soap *soap_copy(struct soap *soap)</code>	Allocates a new runtime environment and copies contents of the argument environment such that the new environment does not share any data with the original environment

An environment can be reused as many times as necessary and does not need to be reinitialized in doing so. A new environment is only required for each new thread to guarantee exclusive access to a new runtime environment by each thread. For example, the following code stack-allocates the runtime environment which is used for multiple remote method calls:

```
int main()
{
    struct soap soap;
    ...
    soap_init(&soap); // initialize runtime environment
    ...
    soap_call_ns_...method1(&soap, ...); // make a remote call
    ...
}
```

```

    soap_call_ns_method2(&soap, ...); // make another remote call
    ...
    soap_end(&soap); // clean up
    ...
}

```

The runtime environment can also be heap allocated:

```

int main()
{
    struct soap *soap;
    ...
    soap = soap_new(); // allocate and initialize runtime environment
    if (!soap) // couldn't allocate: stop
    ...
    soap_call_ns_method1(soap, ...); // make a remote call
    ...
    soap_call_ns_method2(soap, ...); // make another remote call
    ...
    soap_end(soap); // clean up
    ...
    free(soap); // deallocate runtime environment
}

```

A service need to allocate and initialize an environment before calling `soap_serve`:

```

int main()
{
    struct soap soap;
    soap_init(&soap);
    soap_serve(&soap);
}

```

Or alternatively:

```

int main()
{
    soap_serve(soap_new());
}

```

The `soap_serve` dispatcher handles one request or multiple requests when HTTP keep-alive is enabled (with the `SOAP_IO_KEEPAIVE` flag see Section 19.11).

A service can use multi-threading to handle requests while running some other code that invokes remote methods:

```

int main()
{
    struct soap soap1, soap2;
    pthread_t tid;

```

```

...
soap_init(&soap1);
if (soap_bind(&soap1, host, port, backlog) < 0) exit(1);
if (soap_accept(&soap1) < 0) exit(1);
pthread_create(&tid, NULL, (void*)(*)(void*))soap_serve, (void*)&soap1);
...
soap_init(&soap2);
soap_call_ns_method(&soap2, ...); // make a remote call
...
soap_end(&soap2);
...
pthread_join(tid, NULL); // wait for thread to terminate
soap_end(&soap1); // release its data
}

```

In the example above, two runtime environments are required. In comparison, gSOAP 1.X statically allocates the runtime environment, which prohibits multi-threading (only one thread can invoke remote methods and/or accept requests due to the single runtime environment).

Section 8.2.4 presents a multi-threaded stand-alone Web Service that handles multiple SOAP requests by spawning a thread for each request.

6 Interoperability

gSOAP interoperability has been verified with the following SOAP implementations and toolkits:

Apache 2.2

Apache Axis

ASP.NET

Cape Connect

Delphi

easySOAP++

eSOAP

Frontier

GLUE

Iona XMLBus

kSOAP

MS SOAP

Phalanx

SIM

SOAP::Lite

SOAP4R

Spray

SQLData

Wasp Adv.

Wasp C++

White Mesa

xSOAP

ZSI

4S4C

7 Getting Started

To start building Web services applications with gSOAP, you need:

- a C or C++ compiler.
- the gSOAP 'stdsoap2' (stdsoap2.exe for windows) stub and skeleton compiler available in binary form in the platform-specific distribution packages.
- the gSOAP 'wsdl2h' (wsdl2h.exe for windows) WSDL parser, which convert WSDL into a gSOAP specification header file for the 'stdsoap2' stub and skeleton compiler. The WSDL parser is available in binary form in the platform-specific distribution packages.
- the 'stdsoap2.c' or 'stdsoap2.cpp' and 'stdsoap2.h' files containing the runtime library to be linked with your Web Services applications. You can build a DLL or shared object to simplify linkage.
- optionally, you may want to install OpenSSL and the Zlib libraries to enable SSL (HTTPS) and compression. These libraries are available for most platforms and are often already installed.

gSOAP is self-contained, so there is no need to download any third-party software (unless you want to use OpenSSL and the library is not already installed).

Although gSOAP is available in binary format for several platforms, the code generated by the gSOAP stub and skeleton compiler and the gSOAP runtime codes are equivalent. This means that the generated codes can be transferred to other platforms and compiled.

The platform-independent release of gSOAP requires you to build the 'soapcpp2' compiler and 'wsdl2h' parser. The minimal requirements for your platform to build these executables is:

- a C++ compiler (to build the 'wsdl2h' WSDL parser).
- Bison or Yacc
- Flex or Lex

Bison and Flex are preferred.

The gSOAP packages contain numerous examples in the 'samples' directory. Run 'make' to build the example applications. The examples are also meant to demonstrate different features of gSOAP. The simplest examples are the one-liners (samples/oneliners). Indeed, you can write a one-line Web service (requires CGI). A streaming DIME attachment server and client application demonstrate efficient file exchanges (samples/dime). An SSL-secure Web server application demonstrates the generation of dynamic content for Web browsing and Web services functionality at the same time. And much more.

8 Quick User Guide

This user guide offers a quick way to get started with gSOAP. This section requires a basic understanding of the SOAP 1.1 protocol and some familiarity with C and/or C++. In principle, SOAP clients and SOAP Web services can be developed in C and C++ with the gSOAP compiler without a detailed understanding of the SOAP protocol when gSOAP client-server applications are built as an ensemble and only communicate within this group (i.e. meaning that you don't have to worry about interoperability with other SOAP implementations). This section is intended to illustrate the implementation of gSOAP Web services and clients that connect to and interoperate with other SOAP implementations such as Apache Axis, SOAP::Lite, and .NET. This requires some details of the SOAP and WSDL protocols to be understood.

8.1 How to Use the gSOAP Stub and Skeleton Compiler to Build SOAP Clients

In general, the implementation of a SOAP client application requires a **stub** routine for each remote method that the client application needs to invoke. The primary stub's responsibility is to marshall the parameter data, send the request with the parameters to the designated SOAP service over the wire, to wait for the response, and to demarshall the parameter data of the response when it arrives. The client application invokes the stub routine for a remote method as if it would invoke a local method. To write a stub routine in C or C++ by hand is a tedious task, especially if the input and/or output parameters of a remote method contain elaborate data structures such as records, arrays, and graphs. Fortunately, the gSOAP 'wsdl2h' WSDL parser and 'soapcpp2' stub and skeleton compiler automate the development of Web service client and server applications.

The gSOAP stub and skeleton compiler is a **preprocessor** that generates the necessary C++ sources to build SOAP C++ clients. The input to the gSOAP stub and skeleton compiler consists of a standard C/C++ **header file**. The header file can be generated from a WSDL (Web Service Description Language) documentation of a service with the gSOAP WSDL parser.

Consider the following command (entered at the command prompt):

```
$ wsdl2h -o quote.h http://services.xmethods.net/soap/urn:xmethods-delayed-quotes.wsdl
```

This generates the file `quote.h` in C++ format from the WSDL at the specified URL.

To generate a header file to develop a pure C client application, issue the command: Consider the following command (entered at the command prompt):

```
$ wsdl2h -c -o quote.h http://services.xmethods.net/soap/urn:xmethods-delayed-quotes.wsdl
```

For more details on the WSDL parser and its options, see 8.2.10.

The `quote.h` header file is then processed by the gSOAP compiler to generate the stubs to develop client applications (and skeletons to develop a service).

The SOAP service methods are specified in the header file as **function prototypes**. Stub routines in C/C++ source form are automatically generated by the gSOAP compiler for these function prototypes of remote methods. The resulting stub routines allow C and C++ client applications to seamlessly interact with existing SOAP Web services.

The gSOAP stub and skeleton compiler also generates **skeleton** routines for each of the remote methods specified in the header file. The skeleton routines can be readily used to implement one or more of the remote methods in a new SOAP Web service. These skeleton routines are not used for building SOAP clients in C++, although they can be used to build mixed SOAP client/server applications (peer applications).

The input and output parameters of a SOAP service method may be simple data types or compound data types, either generated by the WSDL parser or specified by hand. The gSOAP stub and skeleton compiler automatically generates **serializers** and **deserializers** for the data types to enable the generated stub routines to encode and decode the contents of the parameters of the remote methods in XML.

8.1.1 Example

The `getQuote` remote method of XMethods Delayed Stock Quote service (defined in the `quote.h` file obtained with the 'wsdl2h' WSDL parser) provides a delayed stock quote for a given ticker name. The WSDL description of the XMethods Delayed Stock Quote service provides the following details:

Endpoint URL:	<code>http://services.xmethods.net:80/soap</code>
SOAP action:	<code>""</code> (2 quotes)
Remote method namespace:	<code>urn:xmethods-delayed-quotes</code>
Remote method name:	<code>getQuote</code>
Input parameter:	symbol of type <code>xsd:string</code>
Output parameter:	Result of type <code>xsd:float</code>

The following `getQuote.h` header file for C is created from the WSDL description with the WSDL parser (the actual contents may vary depending on the 'wsdl2h' release version and the options used to determine the output):

```
//gsoap ns1 service name: net_DOTxmethods_DOTservices_DOTstockquote_DOTStockQuoteBinding
//gsoap ns1 service type: net_DOTxmethods_DOTservices_DOTstockquote_DOTStockQuotePortType
```

```
//gsoap ns1 service port: http://66.28.98.121:9090/soap
//gsoap ns1 service namespace: urn:xmethods-delayed-quotes
//gsoap ns1 service documentation: Definitions generated by the gSOAP WSDL parser 1.0
// Service net.xmethods.services.stockquote.StockQuoteService : net.xmethods.services.stockquote.StockQuote
web service

//gsoap ns1 service method-style: getQuote rpc
//gsoap ns1 service method-encoding: getQuote http://schemas.xmlsoap.org/soap/encoding/
//gsoap ns1 service method-action: getQuote urn:xmethods-delayed-quotes#getQuote
int ns1_getQuote(char *symbol, float &Result);
```

The header file essentially specifies the service details in C/C++ with directives for the gSOAP compiler. The remote method is declared as a `ns1_getQuote` **function prototype** which specifies all of the necessary details for the gSOAP compiler to generate the stub routine for a client application to interact with the Delayed Stock Quote service.

The Delayed Stock Quote service description requires that the **input parameter** of the `getQuote` remote method is a symbol parameter of type string. The description also indicates that the **Result output parameter** is a floating point number that represents the current unit price of the stock in dollars. The gSOAP compiler uses the convention the **last parameter** of the function prototype must be the output parameter of the remote method, which is required to be passed by reference using the reference operator (&) or by using a pointer type. All other parameters except the last are input parameters of the remote method, which are required to be passed by value or passed using a pointer to a value (by reference is not allowed). The function prototype associated with a remote method is required to return an **int**, whose value indicates to the caller whether the connection to a SOAP Web service was successful or resulted in an exception, see Section 10.2 for the error codes.

The use of the namespace prefix `ns1_` in the remote method name in the function prototype declaration is discussed in detail in 8.1.2. Basically, a namespace prefix is distinguished by a **pair of underscores** in the function name, as in `ns1_getQuote` where `ns1` is the namespace prefix and `getQuote` is the remote method name. (A single underscore in an identifier name will be translated into a dash in XML, because dashes are more frequently used in XML compared to underscores, see Section 10.3.)

The gSOAP compiler is invoked from the command line with:

```
soapcpp2 getQuote.h
```

The compiler generates the stub routine for the `getQuote` remote method specified in the `getQuote.h` header file. This stub routine can be called by a client program at any time to request a stock quote from the Delayed Stock Quote service. The interface to the generated stub routine is the following function prototype generated by the gSOAP compiler:

```
int soap_call_ns1_getQuote(struct soap *soap, char *URL, char *action, char *symbol, float
&Result);
```

The stub routine is saved in `soapClient.cpp`. The file `soapC.cpp` contains the **serializer** and **deserializer** routines for the data types used by the stub. You can use option `-c` for the `soapcpp2` compiler to generate pure C code.

Note that the parameters of the `soap_call_ns1__getQuote` function are identical to the `ns1__getQuote` function prototype with three additional input parameters: `soap` must be a valid pointer to a gSOAP runtime environment, `URL` is the SOAP Web service **endpoint URL** passed as a string, and `action` is a string that denotes the **SOAP action** required by the Web service. Note that the XMethods Delayed Stock Quote service endpoint URL is `http://66.28.98.121:9090/soap` and the SOAP action required is "" (two quotes). You can change the endpoint and action dynamically. The endpoint and action are the second and third parameters of the `soap_call_ns1__getQuote`. When NULL, the values specified in the header file will be used.

The following example mixed C/C++ client program invokes the stub to retrieve the latest IBM stock quote from the XMethods Delayed Stock Quote service:

```
#include "soapH.h" // obtain the generated stub
#include "net_DOT_xmethods_DOT_services_DOT_stockquote_DOT_StockQuoteBinding.nsmap"
// obtain the namespace mapping table
int main()
{
    struct soap soap; // gSOAP runtime environment
    float quote;
    soap_init(&soap); // initialize runtime environment (only once)
    if (soap_call_ns1__getQuote(&soap, NULL, NULL, "IBM", &quote) == SOAP_OK)
        std::cout << "Current IBM Stock Quote = " << quote << std::endl;
    else // an error occurred
        soap_print_fault(&soap, stderr); // display the SOAP fault message on the stderr stream
    soap_destroy(&soap); // delete deserialized class instances (for C++ only)
    soap_end(&soap); // remove deserialized data and clean up
    soap_done(&soap); // detach the gSOAP environment
    return 0;
}
```

When successful, the stub returns `SOAP_OK` and `quote` contains the latest stock quote. Otherwise, an error occurred and the SOAP fault is displayed with the `soap_print_fault` function.

The gSOAP compiler also generates a proxy class for C++ client applications. This generated proxy class can be included into a client application together with the generated namespace table as shown in this example:

```
#include "soapnet_DOT_xmethods_DOT_services_DOT_stockquote_DOT_StockQuoteBindingProxy.h"
// get proxy
#include "net_DOT_xmethods_DOT_services_DOT_stockquote_DOT_StockQuoteBinding.nsmap"
// obtain the namespace mapping table
int main()
{
    net q; // "net" is the proxy class with a name that is the short name of the service
    float r;
    if (q.ns1__getQuote("IBM", r) == SOAP_OK)
        std::cout << r << std::endl;
    else
        soap_print_fault(q.soap, stderr);
    return 0;
}
```

The proxy class constructor allocates and initializes a gSOAP environment for the instance. All the HTTP and SOAP/XML processing is hidden and performed on the background. Note that you can change the name of the service in the header file generated by the WSDL parser. The name is extracted from the WSDL content and may not always be in a short format. Feel free to change the entry

```
//gsoap ns1 service name: net_DOT_xmethods_DOT_services_DOT_stockquote_DOT_StockQuoteBinding
```

to use a more suitable name. The name will control the file name of the proxy class file and the XML namespace mapping table.

The following functions can be used to explicitly setup a gSOAP runtime environment (**struct soap**):

Function	Description
<code>soap_init(struct soap *soap)</code>	Initializes a runtime environment (required on all threads)
<code>soap_init1(struct soap *soap, soap_mode imode)</code>	Initializes a runtime environment and set in/out mode flags
<code>soap_init2(struct soap *soap, soap_mode imode, soap_mode omode)</code>	Initializes a runtime environment and set separate in/out mode flags
<code>struct soap *soap_new()</code>	Allocates, initializes, and returns a pointer to a new runtime environment
<code>struct soap *soap_new1(soap_mode imode)</code>	Allocates, initializes, and returns a pointer to a new runtime environment and set in/out mode flags
<code>struct soap *soap_new2(soap_mode imode, soap_mode omode)</code>	Allocates, initializes, and returns a pointer to a new runtime environment and set separate in/out mode flags
<code>struct soap *soap_copy(struct soap *soap)</code>	Allocates a new runtime environment and copies the state of the argument environment such that the new environment does not share data with the argument environment
<code>soap_done(struct soap *soap)</code>	Reset, close communications, and remove call state

An environment can be reused as many times as necessary for client-side remote calls and does not need to be reinitialized in doing so. A new environment is required for each new thread to guarantee exclusive access to runtime environments by threads. Also the use of any client calls within an active service method requires a new environment.

When the example client application is invoked, the SOAP request is performed by the stub routine `soap_call_ns1_getQuote`, which generates the following SOAP RPC request message:

```
POST /soap HTTP/1.1
Host: services.xmethods.net
Content-Type: text/xml
Content-Length: 529
SOAPAction: ""

<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns1="urn:xmethods-delayed-quotes"
  SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
```

```

<SOAP-ENV:Body>
<ns1:getQuote>
<symbol>IBM</symbol>
</ns1:getQuote>
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

The XMethods Delayed Stock Quote service responds with the SOAP response message:

```

HTTP/1.1 200 OK
Date: Sat, 25 Aug 2001 19:28:59 GMT
Content-Type: text/xml
Server: Electric/1.0
Connection: Keep-Alive
Content-Length: 491

<?xml version="1.0" encoding="UTF-8"?>
<soap:Envelope xmlns:soap="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:soapenc="http://schemas.xmlsoap.org/soap/encoding/"
  soap:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
  <soap:Body>
    <n:getQuoteResponse xmlns:n="urn:xmethods-delayed-quotes">
      <Result xsi:type="xsd:float">41.81</Result>
    </n:getQuoteResponse>
  </soap:Body>
</soap:Envelope>

```

The server's SOAP RPC response is parsed by the stub. The stub routine further demarshalls the data of `Result` element of the SOAP response and stores it in the `quote` parameter of `soap_call_ns1__getQuote`.

A client program can invoke a remote method at any time and multiple times if necessary. Consider for example:

```

...
struct soap soap;
float quotes[3]; char *myportfolio[] = {"IBM", "MSDN"};
soap_init(&soap); // need to initialize only once
for (int i = 0; i < 3; i++)
  if (soap_call_ns1__getQuote(&soap, "http://services.xmethods.net:80/soap", "", myport-
folio[i], &quotes[i]) != SOAP_OK)
    break;
if (soap.error) // an error occurred
  soap_print_fault(&soap, stderr);
soap_end(&soap); // clean up all deserialized data
...

```

This client composes an array of stock quotes by calling the `ns1__getQuote` stub routine for each symbol in a portfolio array.

This example demonstrated how easy it is to build a SOAP client with gSOAP once the details of a Web service are available in the form of a WSDL document.

8.1.2 Namespace Considerations

The declaration of the `ns1_::getQuote` function prototype (discussed in the previous section) uses the namespace prefix `ns1_` of the remote method namespace, which is distinguished by a **pair of underscores** in the function name to separate the namespace prefix from the remote method name. The purpose of a namespace prefix is to associate a remote method name with a service in order to prevent naming conflicts, e.g. to distinguish identical remote method names used by different services.

Note that the XML response of the XMethods Delayed Stock Quote service example uses the **namespace prefix** `n` which is bound to the **namespace name** `urn:xmethods-delayed-quotes` through the `xmlns:n="urn:xmethods-delayed-quotes"` binding. The use of namespace prefixes and namespace names is also required to enable SOAP applications to validate the content of SOAP messages. The namespace name in the service response is verified by the stub routine by using the information supplied in a **namespace mapping table** that is required to be part of gSOAP client and service application codes. The table is accessed at run time to resolve namespace bindings, both by the generated stub's data structure serializer for encoding the client request and by the generated stub's data structure deserializer to decode and validate the service response. The namespace mapping table should **not** be part of the header file input to the gSOAP stub and skeleton compiler. Service details including namespace bindings may be provided with gSOAP directives in a header file, see Section 19.2.

The namespace mapping table for the Delayed Stock Quote client is:

```
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name"}
  {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"}, // MUST be first
  {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"}, // MUST be second
  {"xsi", "http://www.w3.org/2001/XMLSchema-instance"}, // MUST be third
  {"xsd", "http://www.w3.org/2001/XMLSchema"}, // 2001 XML Schema
  {"ns1", "urn:xmethods-delayed-quotes"}, // given by the service description
  {NULL, NULL} // end of table
};
```

The first four namespace entries in the table consist of the standard namespaces used by the SOAP 1.1 protocol. In fact, the namespace mapping table is explicitly declared to enable a programmer to specify the SOAP encoding style and to allow the inclusion of namespace-prefix with namespace-name bindings to comply to the namespace requirements of a specific SOAP service. For example, the namespace prefix `ns1`, which is bound to `urn:xmethods-delayed-quotes` by the namespace mapping table shown above, is used by the generated stub routine to encode the `getQuote` request. This is performed automatically by the gSOAP compiler by using the `ns1` prefix of the `ns1_::getQuote` method name specified in the `getQuote.h` header file. In general, if a function name of a remote method, **struct** name, **class** name, **enum** name, or field name of a **struct** or **class** has a pair of underscores, the name has a namespace prefix that must be defined in the namespace mapping table.

The namespace mapping table will be output as part of the SOAP Envelope by the stub routine. For example:

...

```

<SOAP-ENV:Envelope xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns1="urn:xmethods-delayed-quotes"
  SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
...

```

The namespace bindings will be used by a SOAP service to validate the SOAP request.

8.1.3 Example

The incorporation of namespace prefixes into C++ identifier names is necessary to distinguish remote methods that share the same name but are provided by separate Web services and/or organizations. Consider for example:

```

// Contents of file "getQuote.h":
int ns1_Quote(char *symbol, float &Result);
int ns2_Quote(char *ticker, char *&quote);

```

Recall that the namespace prefix is always separated from the name of a remote method by a pair of underscores (..).

This example enables a client program to connect to a (hypothetical) Stock Quote service with remote methods that can only be distinguished by their namespaces. Consequently, two different namespace prefixes had to be used as part of the remote method names.

The namespace prefix convention can also be applied to **class** declarations that contain SOAP compound values that share the same name but have different namespaces that refer to different XML Schemas. For example:

```

class e_Address // an electronic address
{
  char *email;
  char *url;
};
class s_Address // a street address
{
  char *street;
  int number;
  char *city;
};

```

The namespace prefix is separated from the name of a data type by a pair of underscores (..).

An instance of `e_Address` is encoded by the generated serializer for this type as an `Address` element with namespace prefix `e`:

```

<e:Address xsi:type="e:Address">
  <email xsi:type="string">me@home</email>
  <url xsi:type="string">www.me.com</url>
</e:Address>

```

While an instance of `s_Address` is encoded by the generated serializer for this type as an `Address` element with namespace prefix `s`:

```
<s:Address xsi:type="s:Address">
<street xsi:type="string">Technology Drive</street>
<number xsi:type="int">5</number>
<city xsi:type="string">Softcity</city>
</s:Address>
```

The namespace mapping table of the client program must have entries for `e` and `s` that refer to the XML Schemas of the data types:

```
struct Namespace namespaces[] =
{ ...
  {"e", "http://www.me.com/schemas/electronic-address"},
  {"s", "http://www.me.com/schemas/street-address"},
  ...
}
```

This table is required to be part of the client application to allow access by the serializers and deserializers of the data types at run time.

8.1.4 How to Generate C++ Client Proxy Classes

Proxy classes for C++ client applications are automatically generated by the gSOAP compiler. To illustrate the generation of a proxy class, the `getQuote.h` header file example of the previous section is augmented with the appropriate directives to enable the gSOAP compiler to generate the proxy class. Similar directives are included in the header file by the WSDL importer.

```
// Content of file "getQuote.h":
//gsoap ns1 service name: Quote
//gsoap ns1 service location: http://services.xmethods.net/soap
//gsoap ns1 service namespace: urn:xmethods-delayed-quotes
//gsoap ns1 service style: rpc
//gsoap ns1 service encoding: encoded
//gsoap ns1 service method-action: getQuote ""
int ns1_Quote(char *symbol, float &Result);
```

The first three directives provide the service name which is used to name the proxy class, the service location (endpoint), and the schema. The fourth and fifth directives specify that SOAP RPC encoding is used, which is required by this service. The last directive defines the optional SOAPAction, which is a string associated with SOAP 1.1 operations. This directive must be provided for each remote method when the SOAPAction is required. Compilation of this header file with the gSOAP compiler `soapcpp2` creates a new file `soapQuoteProxy.h` with the following contents:

```
#include "soapH.h"
class Quote
{ public:
  struct soap *soap;
```

```

    const char *endpoint;
    Quote() { soap = soap_new(); endpoint = "http://services.xmethods.net/soap"; };
    ~Quote() { if (soap) { soap_destroy(soap); soap_end(soap); soap_done(soap); free((void*)soap);
    }};
    int getQuote(char *symbol, float &Result) { return soap ? soap_call_ns1__getQuote(soap, end-
point, "", symbol, Result) : SOAP_EOM; };
};

```

The gSOAP environment and endpoint are declared public to enable access for run-time customization.

This generated proxy class can be included into a client application together with the generated namespace table as shown in this example:

```

#include "soapQuoteProxy.h" // get proxy
#include "Quote.nsmap" // get namespace bindings
int main()
{
    Quote q;
    float r;
    if (q.ns1__getQuote("IBM", r) == SOAP_OK)
        std::cout << r << std::endl;
    else
        soap_print_fault(q.soap, stderr);
    return 0;
}

```

The Quote constructor allocates and initializes a gSOAP environment for the instance. All the HTTP and SOAP/XML processing is hidden and performed on the background.

You can use soapcpp2 compiler option `-n` together with `-p` to create a local namespaces table to avoid link conflicts when you need multiple namespace tables or need to combine multiple clients, see also Sections 9.1 and 19.34, and you can use a C++ code **namespace** to create a namespace qualified proxy class, see Section 19.33.

8.1.5 XSD Type Encoding Considerations

Many SOAP services require the explicit use of XML Schema types in the SOAP payload. The default encoding, which is also adopted by the gSOAP compiler, assumes SOAP RPC encoding which only requires the use of types to handle polymorphic cases. Nevertheless, the use of XSD typed messages is advised to improve interoperability. XSD types are introduced with **typedef** definitions in the header file input to the gSOAP compiler. The type name defined by a **typedef** definition corresponds to an XML Schema type (XSD type). For example, the following **typedef** declarations define various built-in XSD types implemented as primitive C/C++ types:

```

// Contents of header file:
...
typedef char *xsd__string; // encode xsd__string value as the xsd:string schema type
typedef char *xsd__anyURI; // encode xsd__anyURI value as the xsd:anyURI schema type

```

```

typedef float xsd_float; // encode xsd_float value as the xsd:float schema type
typedef long xsd_int; // encode xsd_int value as the xsd:int schema type
typedef bool xsd_boolean; // encode xsd_boolean value as the xsd:boolean schema type
typedef unsigned long long xsd_positiveInteger; // encode xsd_positiveInteger value as the
xsd:positiveInteger schema type
...

```

This simple mechanism informs the gSOAP compiler to generate serializers and deserializers that explicitly encode and decode the primitive C++ types as built-in primitive XSD types when the typedefed type is used in the parameter signature of a remote method (or when used nested within structs, classes, and arrays). At the same time, the use of **typedef** does not force any recoding of a C++ client or Web service application as the internal C++ types used by the application are not required to be changed (but still have to be primitive C++ types, see Section 11.2.2 for alternative class implementations of primitive XSD types which allows for the marshalling of polymorphic primitive types).

8.1.6 Example

Reconsider the `getQuote` example, now rewritten with explicit XSD types to illustrate the effect:

```

// Contents of file "getQuote.h":
typedef char *xsd_string;
typedef float xsd_float;
int ns1_getQuote(xsd_string symbol, xsd_float &Result);

```

This header file is compiled by the gSOAP stub and skeleton compiler and the compiler generates source code for the function `soap_call_ns1_getQuote`, which is identical to the “old” proxy:

```

int soap_call_ns1_getQuote(struct soap *soap, char *URL, char *action, char *symbol, float
&Result);

```

The client application does not need to be rewritten and can still call the proxy using the “old” parameter signature. In contrast to the previous implementation of the stub however, the encoding and decoding of the data types by the stub has been changed to explicitly use the XSD types in the message payload.

For example, when the client application calls the proxy, the proxy produces a SOAP request with an `xsd:string`:

```

...
<SOAP-ENV:Body>
<ns1:getQuote><symbol xsi:type="xsd:string">IBM</symbol>
</ns1:getQuote>
</SOAP-ENV:Body>
...

```

The service response is:


```

...
<soap:Body>
<n:getQuoteResponse xmlns:n="urn:xmethods-delayed-quotes">
<Result xsi:type="xsd:float">41.81</Result>
</n:getQuoteResponse>
</soap:Body>
...

```

The validation of this service response by the stub routine takes place by matching the namespace names (URIs) that are bound to the `xsd` namespace prefix. The stub also expects the `getQuoteResponse` element to be associated with URI `urn:xmethods-delayed-quotes` through the binding of the namespace prefix `ns1` in the namespace mapping table. The service response uses namespace prefix `n` for the `getQuoteResponse` element. This namespace prefix is bound to the same URI `urn:xmethods-delayed-quotes` and therefore the service response is assumed to be valid. The response is rejected and a SOAP fault is generated when the URIs do not match.

8.1.7 How to Change the Response Element Name

There is no standardized convention for the response element name in a SOAP response message, although it is recommended that the response element name is the method name ending with “Response”. For example, the response element of `getQuote` is `getQuoteResponse`.

The response element name can be specified explicitly using a **struct** or **class** declaration in the header file. The **struct** or **class** name represents the SOAP response element name used by the service. Consequently, the output parameter of the remote method must be declared as a field of the **struct** or **class**. The use of a **struct** or a **class** for the service response is fully SOAP 1.1 compliant. In fact, the absence of a **struct** or **class** indicates to the gSOAP compiler to automatically generate a struct for the response which is internally used by a stub.

8.1.8 Example

Reconsider the `getQuote` remote method specification which can be rewritten with an explicit declaration of a SOAP response element as follows:

```

// Contents of "getQuote.h":
typedef char *xsd__string;
typedef float xsd__float;
struct ns1__getQuoteResponse {xsd__float Result;};
int ns1__getQuote(xsd__string symbol, struct ns1__getQuoteResponse &r);

```

The SOAP request is the same as before:

```

...
<SOAP-ENV:Body>
<ns1:getQuote><symbol xsi:type="xsd:string">IBM</symbol>
</ns1:getQuote>
</SOAP-ENV:Body>
...

```

The difference is that the service response is required to match the specified `getQuoteResponse` name and its namespace URI:

```
...
<soap:Body>
<n:getQuoteResponse xmlns:n='urn:xmethods-delayed-quotes'>
<Result xsi:type='xsd:float'>41.81</Result>
</n:getQuoteResponse>
</soap:Body>
...
```

This use of a **struct** or **class** enables the adaptation of the default SOAP response element name and/or namespace URI when required.

Note that the **struct** (or **class**) declaration may appear within the function prototype declaration. For example:

```
// Contents of "getQuote.h":
typedef char *xsd_string;
typedef float xsd_float;
int ns1_getQuote(xsd_string symbol, struct ns1_getQuoteResponse {xsd_float Result;} &r);
```

This example combines the declaration of the response element of the remote method with the function prototype of the remote method.

8.1.9 How to Specify Multiple Output Parameters

The gSOAP stub and skeleton compiler uses the convention that the **last parameter** of the function prototype declaration of a remote method in a header file is also the **only single output parameter** of the method. All other parameters are considered input parameters of the remote method. To specify a remote method with **multiple output parameters**, a **struct** or **class** must be declared for the remote method response, see also 8.1.7. The fields of the **struct** or **class** are the output parameters of the remote method. Both the order of the input parameters in the function prototype and the order of the output parameters (the fields in the **struct** or **class**) is not significant. However, the SOAP 1.1 specification states that input and output parameters may be treated as having anonymous parameter names which requires a particular ordering, see Section 8.1.13.

8.1.10 Example

As an example, consider a hypothetical remote method `getNames` with a single input parameter `SSN` and two output parameters `first` and `last`. This can be specified as:

```
// Contents of file "getNames.h":
int ns3_getNames(char *SSN, struct ns3_getNamesResponse {char *first; char *last;} &r);
```

The gSOAP stub and skeleton compiler takes this header file as input and generates source code for the function `soap_call_ns3_getNames`. When invoked by a client application, the proxy produces the SOAP request:

```

...
<SOAP-ENV:Envelope ... xmlns:ns3="urn:names" ...>
...
<ns3:getNames>
<SSN>999 99 9999</SSN>
</ns3:getNames>
...

```

The response by a SOAP service could be:

```

...
<m:getNamesResponse xmlns:m="urn:names">
<first>John</first>
<last>Doe</last>
</m:getNamesResponse>
...

```

where `first` and `last` are the output parameters of the `getNames` remote method of the service.

As another example, consider a remote method `copy` with an input parameter and an output parameter with identical parameter names (this is not prohibited by the SOAP 1.1 protocol). This can be specified as well using a response **struct**:

```

// Content of file "copy.h":
int X_rox_copy_name(char *name, struct X_rox_copy_nameResponse {char *name;} &r);

```

The use of a **struct** or **class** for the remote method response enables the declaration of remote methods that have parameters that are passed both as input and output parameters.

The gSOAP compiler takes the `copy.h` header file as input and generates the `soap_call_X_rox_copy_name` proxy. When invoked by a client application, the proxy produces the SOAP request:

```

...
<SOAP-ENV:Envelope ... xmlns:X-rox="urn:copy" ...>
...
<X-rox:copy-name>
<name>SOAP</name>
</X-rox:copy-name>
...

```

The response by a SOAP `copy` service could be something like:

```

...
<m:copy-nameResponse xmlns:m="urn:copy">
<name>SOAP</name>
</m:copy-nameResponse>
...

```

The name will be parsed and decoded by the proxy and returned in the `name` field of the **struct** `X_rox_copy_nameResponse &r` parameter.

8.1.11 How to Specify Output Parameters With struct/class Compound Data Types

If the single output parameter of a remote method is a complex data type such as a **struct** or **class** it is necessary to specify the response element of the remote method as a **struct** or **class at all times**. Otherwise, the output parameter will be considered the response element (!), because of the response element specification convention used by gSOAP, as discussed in 8.1.7.

8.1.12 Example

This is best illustrated with an example. The Flighttracker service by ObjectSpace provides real time flight information for flights in the air. It requires an airline code and flight number as parameters. The remote method name is `getFlightInfo` and the method has two string parameters: the airline code and flight number, both of which must be encoded as `xsd:string` types. The method returns a `getFlightResponse` response element with a `return` output parameter that is of complex type `FlightInfo`. The type `FlightInfo` is represented by a **class** in the header file, whose field names correspond to the `FlightInfo` accessors:

```
// Contents of file "flight.h":
typedef char *xsd_string;
class ns2_FlightInfo
{
    public:
       xsd_string airline;
       xsd_string flightNumber;
       xsd_string altitude;
       xsd_string currentLocation;
       xsd_string equipment;
       xsd_string speed;
};
struct ns1_getFlightInfoResponse {ns2_FlightInfo _return;};
int ns1_getFlightInfo(xsd_string param1, xsd_string param2, struct ns1_getFlightInfoResponse
&r);
```

The response element `ns1_getFlightInfoResponse` is explicitly declared and it has one field: `return_` of type `ns2_FlightInfo`. Note that `return_` has a trailing underscore to avoid a name clash with the **return** keyword, see Section 10.3 for details on the translation of C++ identifiers to XML element names.

The gSOAP compiler generates the `soap_call_ns1_getFlightInfo` proxy. Here is an example fragment of a client application that uses this proxy to request flight information:

```
struct soap soap;
...
soap_init(&soap);
...
soap_call_ns1_getFlightInfo(&soap, "testvger.objectspace.com/soap/servlet/rpcrouter",
    "urn:galdemo:flighttracker", "UAL", "184", r);
...
struct Namespace namespaces[] =
{
```

```

{"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
{"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
{"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
{"xsd", "http://www.w3.org/2001/XMLSchema"},
{"ns1", "urn:galdemo:flighttracker"},
{"ns2", "http://galdemo.flighttracker.com"},
{NULL, NULL}
};

```

When invoked by a client application, the proxy produces the SOAP request:

```

POST /soap/servlet/rpcrouter HTTP/1.1
Host: testvger.objectspace.com
Content-Type: text/xml
Content-Length: 634
SOAPAction: "urn:galdemo:flighttracker"

<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns1="urn:galdemo:flighttracker"
  xmlns:ns2="http://galdemo.flighttracker.com"
  SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
<SOAP-ENV:Body>
<ns1:getFlightInfo xsi:type="ns1:getFlightInfo">
<param1 xsi:type="xsd:string">UAL</param1>
<param2 xsi:type="xsd:string">184</param2>
</ns1:getFlightInfo>
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

The Flighttracker service responds with:

```

HTTP/1.1 200 ok
Date: Thu, 30 Aug 2001 00:34:17 GMT
Server: IBM_HTTP_Server/1.3.12.3 Apache/1.3.12 (Win32)
Set-Cookie: sesessionid=2GFVTOGC30D0LGRGU2L4HFA;Path=/
Cache-Control: no-cache="set-cookie,set-cookie2"
Expires: Thu, 01 Dec 1994 16:00:00 GMT
Content-Length: 861
Content-Type: text/xml; charset=utf-8
Content-Language: en

<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema">
<SOAP-ENV:Body>
<ns1:getFlightInfoResponse xmlns:ns1="urn:galdemo:flighttracker"

```

```

    SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
<return xmlns:ns2="http://galdemo.flighttracker.com" xsi:type="ns2:FlightInfo">
<equipment xsi:type="xsd:string">A320</equipment>
<airline xsi:type="xsd:string">UAL</airline>
<currentLocation xsi:type="xsd:string">188 mi W of Lincoln, NE</currentLocation>
<altitude xsi:type="xsd:string">37000</altitude>
<speed xsi:type="xsd:string">497</speed>
<flightNumber xsi:type="xsd:string">184</flightNumber>
</return>
</ns1:getFlightInfoResponse>
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

The proxy returns the service response in variable `r` of type **struct** `ns1._getFlightInfoResponse` and this information can be displayed by the client application with the following code fragment:

```

cout << r.return._equipment << " flight " << r.return._airline << r.return._flightNumber
    << " traveling " << r.return._speed << " mph " << " at " << r.return._altitude
    << " ft, is located " << r.return._currentLocation << endl;

```

This code displays the service response as:

```

A320 flight UAL184 traveling 497 mph at 37000 ft, is located 188 mi W of Lincoln,
NE

```

Note: the flight tracker service is no longer available since 9/11/2001. It is kept in the documentation as an example to illustrate the use of structs/classes and response types.

8.1.13 How to Specify Anonymous Parameter Names

The SOAP 1.1 protocol allows parameter names to be anonymous. That is, the name(s) of the output parameters of a remote method are not strictly required to match a client's view of the parameters names. Also, the input parameter names of a remote method are not strictly required to match a service's view of the parameter names. Although this convention is likely to be deprecated in SOAP 1.2, the gSOAP compiler can generate stub and skeleton routines that support anonymous parameters. Parameter names are implicitly anonymous by omitting the parameter names in the function prototype of the remote method. For example:

```

// Contents of "getQuote.h":
typedef char *xsd__string;
typedef float xsd__float;
int ns1._getQuote(xsd__string, xsd__float&);

```

To make parameter names explicitly anonymous on the receiving side (client or service), the parameter names should start with an underscore (`_`) in the function prototype in the header file.

For example:

```
// Contents of "getQuote.h":
typedef char *xsd__string;
typedef float xsd__float;
int ns1__getQuote(xsd__string symbol, xsd__float &_return);
```

Or, alternatively with a response **struct**:

```
// Contents of "getQuote.h":
typedef char *xsd__string;
typedef float xsd__float;
struct ns1__getQuoteResponse {xsd__float _return;};
int ns1__getQuote(xsd__string symbol, struct ns1__getQuoteResponse &r);
```

In this example, `_return` is an anonymous output parameter. As a consequence, the service response to a request made by a client created with gSOAP using this header file specification may include any name for the output parameter in the SOAP payload. The input parameters may also be anonymous. This affects the implementation of Web services in gSOAP and the matching of parameter names by the service.

Caution: when anonymous parameter names are used, the order of the parameters in the function prototype of a remote method is significant.

8.1.14 How to Specify a Method with No Input Parameters

To specify a remote method that has no input parameters, just provide a function prototype with one parameter which is the output parameter. However, some C/C++ compilers (notably Visual C++TM) will not compile and complain about an empty **struct**. This **struct** is generated by gSOAP to contain the SOAP request message. To fix this, provide one input parameter of type **void*** (gSOAP can not serialize `void*` data). For example:

```
struct ns3__SOAPService
{
    public:
    int ID;
    char *name;
    char *owner;
    char *description;
    char *homepageURL;
    char *endpoint;
    char *SOAPAction;
    char *methodNamespaceURI;
    char *serviceStatus;
    char *methodName;
    char *dateCreated;
    char *downloadURL;
    char *wsdlURL;
    char *instructions;
    char *contactEmail;
    char *serverImplementation;
```

```
};
struct ArrayOfSOAPService {struct ns3_ SOAPService *_ptr; int _size;};
int ns_ _getAllSOAPServices(void *_ , struct ArrayOfSOAPService &_return);
```

The ns_ _getAllSOAPServices method has one **void*** input parameter which is ignored by the serializer to produce the request message.

Most C/C++ compilers allow empty **structs** and therefore the **void*** parameter is not required.

8.1.15 How to Specify a Method with No Output Parameters

To specify a remote method that has no output parameters, just provide a function prototype with a response struct that is empty. For example:

```
enum ns_ _event { off, on, stand_by };
int ns_ _signal(enum ns_ _event in, struct ns_ _signalResponse { } *out);
```

Since the response struct is empty, no output parameters are specified. Most C/C++ compilers allow empty **structs**. For those that don't, use a **void*** parameter in the struct. This parameter is not (de)serialized.

Some SOAP resources refer to SOAP RPC with empty responses as **one way** SOAP messaging. However, we refer to one-way messaging by asynchronous explicit send and receive operations as described in Section 8.3. The latter view of one-way SOAP messaging is also in line with Basic Profile 1.0.

8.2 How to Use the gSOAP Stub and Skeleton Compiler to Build SOAP Web Services

The gSOAP stub and skeleton compiler generates **skeleton** routines in C++ source form for each of the remote methods specified as function prototypes in the header file processed by the gSOAP compiler. The skeleton routines can be readily used to implement the remote methods in a new SOAP Web service. The compound data types used by the input and output parameters of SOAP remote methods must be declared in the header file, such as structs, classes, arrays, and pointer-based data structures (graphs) that are used as the data types of the parameters of a remote method. The gSOAP compiler automatically generates serializers and deserializers for the data types to enable the generated skeleton routines to encode and decode the contents of the parameters of the remote methods. The gSOAP compiler also generates a remote method request dispatcher routine that will serve requests by calling the appropriate skeleton when the SOAP service application is installed as a CGI application on a Web server.

8.2.1 Example

The following example specifies three remote methods to be implemented by a new SOAP Web service:


```
// Contents of file "calc.h":
typedef double xsd__double;
int ns__add(xsd__double a, xsd__double b, xsd__double &result);
int ns__sub(xsd__double a, xsd__double b, xsd__double &result);
int ns__sqrt(xsd__double a, xsd__double &result);
```

The `add` and `sub` methods are intended to add and subtract two double floating point numbers stored in input parameters `a` and `b` and should return the result of the operation in the `result` output parameter. The `qsrt` method is intended to take the square root of input parameter `a` and to return the result in the output parameter `result`. The `xsd__double` type is recognized by the gSOAP compiler as the `xsd:double` XSD Schema data type. The use of **typedef** is a convenient way to associate primitive C types with primitive XML Schema data types.

To generate the skeleton routines, the gSOAP compiler is invoked from the command line with:

```
soapcpp2 calc.h
```

The compiler generates the skeleton routines for the `add`, `sub`, and `sqrt` remote methods specified in the `calc.h` header file. The skeleton routines are respectively, `soap_serve_ns__add`, `soap_serve_ns__sub`, and `soap_serve_ns__sqrt` and saved in the file `soapServer.cpp`. The generated file `soapC.cpp` contains serializers and deserializers for the skeleton. The compiler also generates a service dispatcher: the `soap_serve` function handles client requests on the standard input stream and dispatches the remote method requests to the appropriate skeletons to serve the requests. The skeleton in turn calls the remote method implementation function. The function prototype of the remote method implementation function is specified in the header file that is input to the gSOAP compiler.

Here is an example Calculator service application that uses the generated `soap_serve` routine to handle client requests:

```
// Contents of file "calc.cpp":
#include "soapH.h"
#include <math.h> // for sqrt()
main()
{
    soap_serve(soap_new()); // use the remote method request dispatcher
}
// Implementation of the "add" remote method:
int ns__add(struct soap *soap, double a, double b, double &result)
{
    result = a + b;
    return SOAP_OK;
}
// Implementation of the "sub" remote method:
int ns__sub(struct soap *soap, double a, double b, double &result)
{
    result = a - b;
    return SOAP_OK;
}
// Implementation of the "sqrt" remote method:
```

```

int ns_sqrt(struct soap *soap, double a, double &result)
{
    if (a >= 0)
    {
        result = sqrt(a);
        return SOAP_OK;
    }
    else
        return soap_receiver_fault(soap, "Square root of negative number", "I can only take the square
root of a non-negative number");
}
// As always, a namespace mapping table is needed:
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name"}
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "urn:simple-calc"}, // bind "ns" namespace prefix
    {NULL, NULL}
};

```

Note that the remote methods have an extra input parameter which is a pointer to the gSOAP runtime environment. The implementation of the remote methods **MUST** return a SOAP error code. The code `SOAP_OK` denotes success, while `SOAP_FAULT` denotes an exception with details that can be defined by the user. The exception description can be assigned to the `soap->fault->faultstring` string and details can be assigned to the `soap->fault->detail` string. This is SOAP 1.1 specific. SOAP 1.2 requires the `soap->fault->SOAP_ENV__Reason` and the `soap->fault->SOAP_ENV__Detail` strings to be assigned. Better is to use the `soap_receiver_fault` function that allocates a fault struct and sets the SOAP Fault string and details regardless of the SOAP 1.1 or SOAP 1.2 version used. The `soap_receiver_fault` function returns `SOAP_FAULT`, i.e. an application-specific fault. The fault exception will be passed on to the client of this service.

This service application can be readily installed as a CGI application. The service description would be:

Endpoint URL:	the URL of the CGI application
SOAP action:	"" (2 quotes)
Remote method namespace:	<code>urn:simple-calc</code>
Remote method name:	<code>add</code>
Input parameters:	<code>a</code> of type <code>xsd:double</code> and <code>b</code> of type <code>xsd:double</code>
Output parameter:	<code>result</code> of type <code>xsd:double</code>
Remote method name:	<code>sub</code>
Input parameters:	<code>a</code> of type <code>xsd:double</code> and <code>b</code> of type <code>xsd:double</code>
Output parameter:	<code>result</code> of type <code>xsd:double</code>
Remote method name:	<code>sqrt</code>
Input parameter:	<code>a</code> of type <code>xsd:double</code>
Output parameter:	<code>result</code> of type <code>xsd:double</code> or a SOAP Fault

The `soapcpp2` compile generates a WSDL file for this service, see Section 8.2.8.

Unless the CGI application inspects and checks the environment variable SOAPAction which contains the SOAP action request by a client, the SOAP action is ignored by the CGI application. SOAP actions are specific to the SOAP protocol and provide a means for routing requests and for security reasons (e.g. firewall software can inspect SOAP action headers to grant or deny the SOAP request. Note that this requires the SOAP service to check the SOAP action header as well to match it with the remote method.)

The header file input to the gSOAP compiler does not need to be modified to generate client stubs for accessing this service. Client applications can be developed by using the same header file as for which the service application was developed. For example, the `soap_call_ns_add` stub routine is available from the `soapClient.cpp` file after invoking the gSOAP compiler on the `calc.h` header file. As a result, client and service applications can be developed without the need to know the details of the SOAP encoding used.

8.2.2 MSVC++ Builds

- Win32 builds need `winsock.dll` (MS Visual C++ "wssock32.lib") To do this in Visual C++ 6.0, go to "Project", "settings", select the "Link" tab (the project file needs to be selected in the file view) and add "wssock32.lib" to the "Object/library modules" entry.
- Use files with extension `.cpp` only (don't mix `.c` with `.cpp`).
- Turn pre-compiled headers off.
- When creating a new project, you can specify a custom build step to automatically invoke the gSOAP compiler on a gSOAP header file. In this way you can incrementally build a new service by adding new operations and data types to the header file. To specify a custom build step, select the "Project" menu item "Settings" and select the header file in the File view pane. Select the "Custom Build" tab and enter '`soapcpp2.exe "$(inputPath)"`' in the "Command" pane. Enter '`soapStub.h soapH.h soapC.cpp soapClient.cpp soapServer.cpp soapClientLib.cpp soapServerLib.cpp`'. Don't forget to add the `soapXYZProxy.h` `soapXYZProxy.cpp` `soapXYZObject.h` `soapXYZObject.cpp` files that are generated for C++ class proxies and server objects named XYZ. Click "OK". Run the `soapcpp2` compiler once to generate these files (you can simply do this by selecting your header file and select "Compile"). Add the files to your project. Each time you make a change to the header file, the project sources are updated automatically.
- You may want to use the WinInet interface available in the `mod_gsoap` directory of the gSOAP package to simplify Internet access and deal with encryption, proxies, and authentication. API instructions are included in the source.
- For the PocketPC, run the `wsdl2h` WSDL parser with option `-s` to prevent the generation of STL code. In addition, `time_t` serialization is not supported, which means that you should add the following line to `typemap.dat` indicating a mapping of `xsd_dateTime` to **char***: `xsd_dateTime = | char* | char*`.

8.2.3 How to Create a Stand-Alone gSOAP Service

The deployment of a Web service as a CGI application is an easy means to provide your service on the Internet. gSOAP services can also run as stand-alone services on any port by utilizing the built-in HTTP and TCP/IP stacks. The stand-alone services can be run on port 80 thereby providing Web server capabilities restricted to SOAP RPC.

To create a stand-alone service, only the main routine of the service needs to be modified as follows. Instead of just calling the `soap_serve` routine, the main routine is changed into:

```
int main()
{
    struct soap soap;
    int m, s; // master and slave sockets
    soap_init(&soap);
    m = soap_bind(&soap, "machine.cs.fsu.edu", 18083, 100);
    if (m < 0)
        soap_print_fault(&soap, stderr);
    else
    {
        fprintf(stderr, "Socket connection successful: master socket = %d\n", m);
        for (int i = 1; ; i++)
        {
            s = soap_accept(&soap);
            if (s < 0)
            {
                soap_print_fault(&soap, stderr);
                break;
            }
            fprintf(stderr, "%d: accepted connection from IP=%d.%d.%d.%d socket=%d", i,
                (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF, s);
            if (soap_serve(&soap) != SOAP_OK) // process RPC request
                soap_print_fault(&soap, stderr); // print error
            fprintf(stderr, "request served\n");
            soap_destroy(&soap); // clean up class instances
            soap_end(&soap); // clean up everything and close socket
        }
        soap_done(&soap); // close master socket and detach environment
    }
}
```

The `soap_serve` dispatcher handles one request or multiple requests when HTTP keep-alive is enabled (with the `SOAP_IO.KEEPALIVE` flag see Section 19.11).

The gSOAP functions that can be used are:

Function	Description
<code>soap_init(struct soap *soap)</code>	Initializes gSOAP runtime environment (required once)
<code>soap_bind(struct soap *soap, char *host, int port, int backlog)</code>	Returns master socket (backlog = max. queue size for requests). When <code>host==NULL</code> : host is the machine on which the service runs
<code>soap_accept(struct soap *soap)</code>	Returns slave socket
<code>soap_end(struct soap *soap)</code>	Clean up deserialized data (except class instances) and temporary data
<code>soap_free(struct soap *soap)</code>	Clean up temporary data only
<code>soap_destroy(struct soap *soap)</code>	Clean up deserialized class instances (note: this function will be renamed with option -n
<code>soap_done(struct soap *soap)</code>	Reset: close master/slave sockets and remove call-backs (see Section 19.7)

The *host* name in `soap_bind` may be `NULL` to indicate that the current host should be used.

The `soap_accept_timeout` attribute of the gSOAP run-time environment specifies the timeout value for a non-blocking `soap_accept(&soap)` call. See Section 19.17 for more details on timeout management.

See Section 9.13 for more details on memory management.

A client application connects to this stand-alone service with the endpoint `machine.cs.fsu.edu:18083`. A client may use the `http://` prefix. When absent, no HTTP header is send and no HTTP-based information will be communicated to the service.

8.2.4 How to Create a Multi-Threaded Stand-Alone Service

Multi-threading a Web Service is essential when the response times for handling requests by the service are (potentially) long or when keep-alive is enabled, see Section 19.11. In case of long response times, the latencies introduced by the unrelated requests may become prohibitive for a successful deployment of a stand-alone service. When HTTP keep-alive is enabled, a client may not close the socket on time, thereby preventing other clients from connecting.

gSOAP 2.0 and higher is thread safe and supports the implementation of multi-threaded stand-alone services in which a thread is used to handle a request.

The following example illustrates the use of threads to improve the quality of service by handling new requests in separate threads:

```
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
int main(int argc, char **argv)
{
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soap_serve(&soap); // serve request, one thread, CGI style
    }
}
```

```

    soap_destroy(&soap); // dealloc C++ data
    soap_end(&soap); // dealloc data and clean up
}
else
{
    soap.send_timeout = 60; // 60 seconds
    soap.recv_timeout = 60; // 60 seconds
    soap.accept_timeout = 3600; // server stops after 1 hour of inactivity
    soap.max_keep_alive = 100; // max keep-alive sequence
    void *process_request(void*);
    struct soap *tsoap;
    pthread_t tid;
    int port = atoi(argv[1]); // first command-line arg is port
    SOAP_SOCKET m, s;
    m = soap_bind(&soap, NULL, port, BACKLOG);
    if (!soap_valid_socket(m))
        exit(1);
    fprintf(stderr, "Socket connection successful %d\n", m);
    for (;;)
    {
        s = soap_accept(&soap);
        if (!soap_valid_socket(s))
        {
            if (soap.errnum)
            {
                soap_print_fault(&soap, stderr);
                exit(1);
            }
            fprintf(stderr, "server timed out\n");
            break;
        }
        fprintf(stderr, "Thread %d accepts socket %d connection from IP %d.%d.%d.%d\n",
i, s, (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF);
        tsoap = soap_copy(&soap); // make a safe copy
        if (!tsoap)
            break;
        pthread_create(&tid, NULL, (void*)(*)(void*))process_request, (void*)tsoap);
    }
}
soap_done(&soap); // detach soap struct
return 0;
}
void *process_request(void *soap)
{
    pthread_detach(pthread_self());
    soap_serve((struct soap*)soap);
    soap_destroy((struct soap*)soap); // dealloc C++ data
    soap_end((struct soap*)soap); // dealloc data and clean up
    soap_done((struct soap*)soap); // detach soap struct
    free(soap);
    return NULL;
}

```

```
}
```

Note: the code does not wait for threads to join the main thread upon program termination.

The `soap_serve` dispatcher handles one request or multiple requests when HTTP keep-alive is set with `SOAP_IO_KEEPALIVE`. The `soap.max_keep_alive` value can be set to the maximum keep-alive calls allowed, which is important to avoid a client from holding a thread indefinitely. The send and receive timeouts are set to avoid (intentionally) slow clients from holding a socket connection too long. The accept timeout is used to let the server terminate automatically after a period of inactivity.

The following example uses a pool of servers to limit the machine's resource utilization:

```
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
#define MAX_THR (10) // Max. threads to serve requests
int main(int argc, char **argv)
{
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soap_serve(&soap); // serve request, one thread, CGI style
        soap_destroy(&soap); // dealloc C++ data
        soap_end(&soap); // dealloc data and clean up
    }
    else
    {
        struct soap *soap_thr[MAX_THR]; // each thread needs a runtime environment
        pthread_t tid[MAX_THR];
        int port = atoi(argv[1]); // first command-line arg is port
        SOAP_SOCKET m, s;
        int i;
        m = soap_bind(&soap, NULL, port, BACKLOG);
        if (!soap_valid_socket(m))
            exit(1);
        fprintf(stderr, "Socket connection successful %d\n", m);
        for (i = 0; i < MAX_THR; i++)
            soap_thr[i] = NULL;
        for (;;)
        {
            for (i = 0; i < MAX_THR; i++)
            {
                s = soap_accept(&soap);
                if (!soap_valid_socket(s))
                {
                    if (soap.errnum)
                    {
                        soap_print_fault(&soap, stderr);
                        continue; // retry
                    }
                }
                else
            }
        }
    }
}
```

```

        {
            fprintf(stderr, "Server timed out\n");
            break;
        }
    }
    fprintf(stderr, "Thread %d accepts socket %d connection from IP %d.%d.%d.%d\n",
i, s, (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF);
    if (!soap_thr[i]) // first time around
    {
        soap_thr[i] = soap_copy(&soap);
        if (!soap_thr[i])
            exit(1); // could not allocate
    }
    else// recycle soap environment
    {
        pthread_join(tid[i], NULL);
        fprintf(stderr, " Thread %d completed\n", i);
        soap_destroy(soap_thr[i]); // deallocate C++ data of old thread
        soap_end(soap_thr[i]); // deallocate data of old thread
    }
    soap_thr[i]->socket = s; // new socket fd
    pthread_create(&tid[i], NULL, (void*)(*)(void*))soap_serve, (void*)soap_thr[i]);
}
}
for (i = 0; i < MAX_THR; i++)
    if (soap_thr[i])
    {
        soap_done(soap_thr[i]); // detach context
        free(soap_thr[i]); // free up
    }
}
return 0;
}

```

The following functions can be used to setup a gSOAP runtime environment (**struct soap**):

Function	Description
soap_init(struct soap *soap)	Initializes a runtime environment (required only once)
struct soap *soap_new()	Allocates, initializes, and returns a pointer to a runtime environment
struct soap *soap_copy(struct soap *soap)	Allocates a new runtime environment and copies contents of the argument environment such that the new environment does not share data with the argument environment
soap_done(struct soap *soap)	Reset, close communications, and remove callbacks

A new environment is initiated for each thread to guarantee exclusive access to runtime environments.

For clean termination of the server, the master socket can be closed and callbacks removed with soap_done(**struct soap** *soap).

The advantage of the code shown above is that the machine cannot be overloaded with requests, since the number of active services is limited. However, threads are still started and terminated. This overhead can be eliminated using a queue of requests (open sockets) as is shown in the code below.

```
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
#define MAX_THR (10) // Size of thread pool
#define MAX_QUEUE (1000) // Max. size of request queue
SOAP_SOCKET queue[MAX_QUEUE]; // The global request queue of sockets
int head = 0, tail = 0; // Queue head and tail
void *process_queue(void*);
int enqueue(SOAP_SOCKET);
SOAP_SOCKET dequeue();
pthread_mutex_t queue_cs;
pthread_cond_t queue_cv;
int main(int argc, char **argv)
{
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soap_serve(&soap); // serve request, one thread, CGI style
        soap_destroy(&soap); // dealloc C++ data
        soap_end(&soap); // dealloc data and clean up
    }
    else
    {
        struct soap *soap_thr[MAX_THR]; // each thread needs a runtime environment
        pthread_t tid[MAX_THR];
        int port = atoi(argv[1]); // first command-line arg is port
        SOAP_SOCKET m, s;
        int i;
        m = soap_bind(&soap, NULL, port, BACKLOG);
        if (!soap_valid_socket(m))
            exit(1);
        fprintf(stderr, "Socket connection successful %d\n", m);
        pthread_mutex_init(&queue_cs, NULL);
        pthread_cond_init(&queue_cv, NULL);
        for (i = 0; i < MAX_THR; i++)
        {
            soap_thr[i] = soap_copy(&soap);
            fprintf(stderr, "Starting thread %d\n", i);
            pthread_create(&tid[i], NULL, (void*)(*)process_queue, (void*)soap_thr[i]);
        }
        for (;;)
        {
            s = soap_accept(&soap);
            if (!soap_valid_socket(s))
            {

```

```

        if (soap.errnum)
        {
            soap_print_fault(&soap, stderr);
            continue; // retry
        }
        else
        {
            fprintf(stderr, "Server timed out\n");
            break;
        }
    }
    fprintf(stderr, "Thread %d accepts socket %d connection from IP %d.%d.%d.%d\n",
i, s, (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF);
    while (enqueue(s) == SOAP_EOM)
        sleep(1);
}
for (i = 0; i < MAX_THR; i++)
{
    while (enqueue(SOAP_INVALID_SOCKET) == SOAP_EOM)
        sleep(1);
}
for (i = 0; i < MAX_THR; i++)
{
    fprintf(stderr, "Waiting for thread %d to terminate... ", i);
    pthread_join(tid[i], NULL);
    fprintf(stderr, "terminated\n");
    soap_done(soap_thr[i]);
    free(soap_thr[i]);
}
pthread_mutex_destroy(&queue_cs);
pthread_cond_destroy(&queue_cv);
}
soap_done(&soap);
return 0;
}
void *process_queue(void *soap)
{
    struct soap *tsoap = (struct soap*)soap;
    for (;;)
    {
        tsoap->socket = dequeue();
        if (!soap_valid_socket(tsoap->socket))
            break;
        soap_serve(tsoap);
        soap_destroy(tsoap);
        soap_end(tsoap);
        fprintf(stderr, "served\n");
    }
    return NULL;
}
int enqueue(SOAP_SOCKET sock)

```

```

{
    int status = SOAP_OK;
    int next;
    pthread_mutex_lock(&queue_cs);
    next = tail + 1;
    if (next >= MAX_QUEUE)
        next = 0;
    if (next == head)
        status = SOAP_EOM;
    else
    {
        queue[tail] = sock;
        tail = next;
    }
    pthread_cond_signal(&queue_cv);
    pthread_mutex_unlock(&queue_cs);
    return status;
}
SOAP_SOCKET dequeue()
{
    SOAP_SOCKET sock;
    pthread_mutex_lock(&queue_cs);
    pthread_cond_wait(&queue_cv, &queue_cs);
    sock = queue[head++];
    if (head >= MAX_QUEUE)
        head = 0;
    pthread_mutex_unlock(&queue_cs);
    return sock;
}

```

8.2.5 How to Pass Application Data to Service Methods

The **void** *soap.user field can be used to pass application data to service methods. This field should be set before the soap_serve() call. The service method can access this field to use the application-dependent data. The following example shows how a non-static database handle is initialized and passed to the service methods:

```

{ ...
    struct soap soap;
    database_handle_type database_handle;
    soap_init(&soap);    soap.user = (void*)database_handle;
    ...
    soap_serve(&soap); // call the remove method dispatcher to handle request
    ...
}
int ns_myMethod(struct soap *soap, ...)
{ ...
    fetch(((database_handle_type*)soap->user);
    // get data    ...
    return SOAP_OK;
}

```

}

Another way to pass application data around in a more organized way is accomplished with plugins, see Section 19.36.

8.2.6 Some Web Service Implementation Issues

The same client header file specification issues apply to the specification and implementation of a SOAP Web service. Refer to

- 8.1.2 for namespace considerations.
- 8.1.5 for an explanation on how to change the encoding of the primitive types.
- 8.1.7 for a discussion on how the response element format can be controlled.
- 8.1.9 for details on how to pass multiple output parameters from a remote method.
- 8.1.11 for passing complex data types as output parameters.
- 8.1.13 for anonymizing the input and output parameter names.

8.2.7 How to Generate C++ Server Object Classes

Server object classes for C++ server applications are automatically generated by the gSOAP compiler. We illustrate the generation of an object class with a calculator example.

```
// Content of file "calc.h":
//gsoap ns service name: Calculator
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://www.cs.fsu.edu/~engelen/calc.cgi
//gsoap ns schema namespace: urn:calc
//gsoap ns service method-action: add ""
int ns__add(double a, double b, double &result); int ns__sub(double a, double b, double &result);
int ns__mul(double a, double b, double &result); int ns__div(double a, double b, double &result);
```

The first three directives provide the service name which is used to name the service class, the service location (endpoint), and the schema. The fourth directive defines the optional SOAPAction for the method, which is a string associated with SOAP 1.1 operations. Compilation of this header file with the gSOAP compiler soapcpp2 creates a new file soapCalculatorObject.h with the following contents:

```
#include "soapH.h"
class Calculator : public soap
{ public:
    Quote() { soap_init(this); };
    ~Quote() { soap_destroy(this); soap_end(this); soap_done(this); };
    int serve() { return soap_serve(this); };
};
```

This generated server object class can be included into a server application together with the generated namespace table as shown in this example:

```
#include "soapCalculatorObject.h" // get server object
#include "Calculator.nsmmap" // get namespace bindings
int main()
{
    Calculator c;
    return c.serve(); // calls soap_serve to serve as CGI application (using stdin/out)
}
int ns__add(double a, double b, double &result)
{
    result = a + b;
    return SOAP_OK;
}
... sub(), mul(), and div() implementations ...
```

You can use soapcpp2 compiler option `-n` together with `-p` to create a local namespaces table to avoid link conflict when you need to combine multiple tables and/or multiple servers, see also Sections 9.1 and 19.34, and you can use a C++ code **namespace** to create a namespace qualified server object class, see Section 19.33.

8.2.8 How to Generate WSDL Service Descriptions

The gSOAP stub and skeleton compiler soapcpp2 generates WSDL (Web Service Description Language) service descriptions and XML Schema files when processing a header file. The compiler produces one WSDL file for a set of remote methods. The names of the function prototypes of the remote methods must use the same namespace prefix and the namespace prefix is used to name the WSDL file. If multiple namespace prefixes are used to define remote methods, multiple WSDL files will be created and each file describes the set of remote methods belonging to a namespace prefix.

In addition to the generation of the `ns.wsdl` file, a file with a namespace mapping table is generated by the gSOAP compiler. An example mapping table is shown below:

```
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/*/XMLSchema-
instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"},
    {"ns", "http://tempuri.org"},
    {NULL, NULL}
};
```

This file can be incorporated in the client/service application, see Section 10.4 for details on namespace mapping tables.

To deploy a Web service, copy the compiled CGI service application to the designated CGI directory of your Web server. Make sure the proper file permissions are set (`chmod 755 calc.cgi` for

Unix/Linux). You can then publish the WSDL file on the Web by placing it in the appropriate Web server directory.

The gSOAP compiler also generates XML Schema files for all C/C++ complex types (e.g. **structs** and **classes**) when declared with a namespace prefix. These files are named `ns.xsd`, where `ns` is the namespace prefix used in the declaration of the complex type. The XML Schema files do not have to be published as the WSDL file already contains the appropriate XML Schema definitions.

8.2.9 Example

For example, suppose the following methods are defined in the header file:

```
typedef double xsd__double;
int ns__add(xsd__double a, xsd__double b, xsd__double &result);
int ns__sub(xsd__double a, xsd__double b, xsd__double &result);
int ns__sqrt(xsd__double a, xsd__double &result);
```

Then, one WSDL file will be created with the file name `ns.wsdl` that describes all three remote methods:

```
<?xml version="1.0" encoding="UTF-8"?>
<definitions name="Service"
  xmlns="http://schemas.xmlsoap.org/wsdl/"
  targetNamespace="http://location/Service.wsdl"
  xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:SOAP="http://schemas.xmlsoap.org/wsdl/soap/"
  xmlns:WSDL="http://schemas.xmlsoap.org/wsdl/"
  xmlns:xsd="http://www.w3.org/2000/10/XMLSchema"
  xmlns:tns="http://location/Service.wsdl"
  xmlns:ns="http://tempuri.org">
  <types>
    <schema
      xmlns="http://www.w3.org/2000/10/XMLSchema"
      targetNamespace="http://tempuri.org"
      xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
      xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
      <complexType name="addResponse">
        <all>
          <element name="result" type="double" minOccurs="0" maxOccurs="1"/>
        </all>
        <anyAttribute namespace="##other"/>
      </complexType>
      <complexType name="subResponse">
        <all>
          <element name="result" type="double" minOccurs="0" maxOccurs="1"/>
        </all>
        <anyAttribute namespace="##other"/>
      </complexType>
```

```

    <complexType name="sqrtResponse">
      <all>
        <element name="result" type="double" minOccurs="0" maxOccurs="1"/>
      </all>
      <anyAttribute namespace="##other"/>
    </complexType>
  </schema>
</types>
<message name="addRequest">
  <part name="a" type="xsd:double"/>
  <part name="b" type="xsd:double"/>
</message>
<message name="addResponse">
  <part name="result" type="xsd:double"/>
</message>
<message name="subRequest">
  <part name="a" type="xsd:double"/>
  <part name="b" type="xsd:double"/>
</message>
<message name="subResponse">
  <part name="result" type="xsd:double"/>
</message>
<message name="sqrtRequest">
  <part name="a" type="xsd:double"/>
</message>
<message name="sqrtResponse">
  <part name="result" type="xsd:double"/>
</message>
<portType name="ServicePortType">
  <operation name="add">
    <input message="tns:addRequest"/>
    <output message="tns:addResponse"/>
  </operation>
  <operation name="sub">
    <input message="tns:subRequest"/>
    <output message="tns:subResponse"/>
  </operation>
  <operation name="sqrt">
    <input message="tns:sqrtRequest"/>
    <output message="tns:sqrtResponse"/>
  </operation>
</portType>
<binding name="ServiceBinding" type="tns:ServicePortType">
  <SOAP:binding style="rpc" transport="http://schemas.xmlsoap.org/soap/http"/>
  <operation name="add">
    <SOAP:operation soapAction="http://tempuri.org#add"/>
    <input>
      <SOAP:body use="encoded" namespace="http://tempuri.org"
        encodingStyle="http://schemas.xmlsoap.org/soap/encoding"/>
    </input>
    <output>

```

```

        <SOAP:body use="encoded" namespace="http://tempuri.org"
            encodingStyle="http://schemas.xmlsoap.org/soap/encoding/" />
    </output>
</operation>
<operation name="sub">
    <SOAP:operation soapAction="http://tempuri.org#sub" />
    <input>
        <SOAP:body use="encoded" namespace="http://tempuri.org"
            encodingStyle="http://schemas.xmlsoap.org/soap/encoding/" />
    </input>
    <output>
        <SOAP:body use="encoded" namespace="http://tempuri.org"
            encodingStyle="http://schemas.xmlsoap.org/soap/encoding/" />
    </output>
</operation>
<operation name="sqrt">
    <SOAP:operation soapAction="http://tempuri.org#sqrt" />
    <input>
        <SOAP:body use="encoded" namespace="http://tempuri.org"
            encodingStyle="http://schemas.xmlsoap.org/soap/encoding/" />
    </input>
    <output>
        <SOAP:body use="encoded" namespace="http://tempuri.org"
            encodingStyle="http://schemas.xmlsoap.org/soap/encoding/" />
    </output>
</operation>
</binding>
<service name="Service">
    <port name="ServicePort" binding="tns:ServiceBinding">
        <SOAP:address location="http://location/Service.cgi" />
    </port>
</service>
</definitions>

```

8.2.10 How to Parse and Import WSDL Service Descriptions to Develop Clients and Servers

Note: see README.txt in the wsdl directory for installation instructions for the WSDL parser and importer.

The creation of SOAP Web Services applications from a WSDL service description is a two-step process.

First, execute `wsdl2h file.wsdl` which generates the a C++ header file `file.h` (use `wsdl2h -c file.wsdl` to generate pure C code). You can provide a URL instead of a file name, when applicable. The generated header file is a Web service specification that contains the parameter types and service function definitions. The functions are represented as function prototypes. The file contains various annotations related to the Web service. The header file must be processed by the gSOAP compiler. You cannot use it with a C/C++ compiler directly.

Second, the header file `file.h` is processed by the gSOAP compiler by executing `soapcpp2 -i file.h`. This

creates the C/C++ source files to build a client application, see 8.1. In addition, this generates a client proxy object declared in `soapServiceProxy.h`, where `Service` is the name of the service defined in the WSDL. To use this object, include the `soapServiceProxy.h` and `Service.nsmmap` files in your C++ client application. The `Service` class provides the remote Web service methods as class members.

Consider the following example commands (entered at the command prompt):

```
$ wsdl2h -o XMethodsQuery.h http://www.xmethods.net/wsdl/query.wsdl
...
$ soapcpp2 -i XMethodsQuery.h
```

The first command generates `XMethodsQuery.h` from the WSDL at the specified URL. The header file is then processed by the gSOAP compiler to generate the stubs and skeletons. See `XMethodsQuery.h` for the types and service functions. A C++ client application may use the generated `soapXMethodsQuerySoapProxy.h` class and `XMethodsQuerySoap.nsmmap` XML namespace table to access the Web service. Both need to be `#include-d` in your source. Then compile and link the `soapC.cpp`, `soapClient.cpp`, and `stdsoap2.cpp` sources to complete the build.

When parsing a WSDL, the output file name is the WSDL input file name with extension `.h` instead of `.wsdl`. When an input file is absent or a WSDL file from a Web location is accessed, the header output will be produced on the standard output. Schema files (`.xsd`) can also be parsed and processed.

The `wsdl2h` command line options are:

Option	Description
-c	generate C source code
-e	don't qualify enum names This option is for backward compatibility with gSOAP 2.4.1 and earlier. The option does not produce code that conforms to WS-I Basic Profile 1.0a.
-f	generate flat C++ class hierarchy for schema extensions
-g	generate global top-level element declarations
-h	print help information
-I path	use path to find files
-l	include license information in output
-m	use <code>xsd.h</code> module to import primitive types
-n name	use <code>name</code> as the base namespace prefix name instead of <code>ns</code>
-N name	use <code>name</code> as the base namespace prefix name for service namespaces
-o file	output to file
-p	create polymorphic types with C++ inheritance hierarchy with base <code>xsd__anyType</code> This is automatically performed when WSDL contains polymorphic definitions
-r host:port	connect via proxy host and port
-s	don't generate STL code (no <code>std::string</code> and no <code>std::vector</code>)
-t file	use type map file instead of the default file <code>typemap.dat</code>
-v	verbose output
-w	always wrap response parameters in a response struct
-x	don't generate <code>_XML any/anyAttribute</code> extensibility elements
-y	generate typedef synonyms for structs and enums
-?	print help information

8.2.11 The typemap.dat File

A typemap.dat file for wsdl2h contains custom XML Schema and C/C++ type bindings. An internal table is used by default.

An example typemap file is:

```
# This file contains custom definitions of the XML Schema types and
# C/C++ types for your project, and XML namespace prefix definitions.
# The wsdl2h WSDL importer consults this file to determine bindings.

[
// This comment will be included in the generated .h file
// You can include any additional declarations, includes, imports, etc.
// within [ ] sections. The brackets MUST appear at the start of a line
]
# XML namespace prefix definitions can be provided to override the
# default choice of ns1, ns2, ... prefixes. For example:

i = "http://www.soapinterop.org/"
s = "http://www.soapinterop.org/xsd"

# Type definitions are of the form: # type = declaration | use | pointer-use
# where
# type is the XML Schema type (or an application type in a namespace
# that has a prefix definition given as above).
# declaration is an optional C/C++ type declaration
# use is how the type is referred to in code
# pointer-use is how the type should be referred to as a pointer (opt)
# Example XML Schema and C/C++ type bindings:

xsd__int = | int
xsd__string = | char* | char*
xsd__boolean = enum xsd__boolean false_, true_ ; | enum xsd__boolean
xsd__base64Binary = class xsd__base64Binary unsigned char *_ptr; int __size; ; |
xsd__base64Binary | xsd__base64Binary
# You can extend structs and classes with member data and functions.
# For example, adding a constructor to ns__myClass: ns__myClass = $ ns__myClass();
# The general form is # class_name = $ member;
```

The *i* and *s* prefixes are declared such that the header file output by the WSDL parser will use these to produce C/C++ code. XML Schema types are associated with an optional C/C++ type declaration, a use reference, and a pointer-use reference. The pointer-use reference of the *xsd__byte* type for example, is **int*** because **char*** is reserved for strings.

8.2.12 How to Use Client Functionalities Within a Service

A gSOAP service may make client calls to other services from within its remove methods. This is best illustrated with an example. The following example is a more sophisticated example that

combines the functionality of two Web services into one new SOAP Web service. The service provides a currency-converted stock quote. To serve a request, the service in turn requests the stock quote and the currency-exchange rate from two XMethods services.

In addition to being a client of two XMethods services, this service application can also be used as a client of itself to test the implementation. As a client invoked from the command-line, it will return a currency-converted stock quote by connecting to a copy of itself installed as a CGI application on the Web to retrieve the quote after which it will print the quote on the terminal.

The header file input to the gSOAP compiler is given below:

```
// Contents of file "quotex.h":
int ns1_getQuote(char *symbol, float &result); // XMethods delayed stock quote service remote
method
int ns2_getRate(char *country1, char *country2, float &result); // XMethods currency-exchange
service remote method
int ns3_getQuote(char *symbol, char *country, float &result); // the new currency-converted
stock quote service
```

The quotex.cpp client/service application source is:

```
// Contents of file "quotex.cpp":
#include "soapH.h" // include generated proxy and SOAP support
int main(int argc, char **argv)
{
    struct soap soap;
    float q;
    soap_init(&soap);
    if (argc <= 2)
        soap_serve(&soap);
    else if (soap_call_ns3_getQuote(&soap, "http://www.cs.fsu.edu/~engelen/quotex.cgi",
    "", argv[1], argv[2], q))
        soap_print_fault(&soap, stderr);
    else
        printf("\nCompany %s: %f (%s)\n", argv[1], q, argv[2]);
    return 0;
}
int ns3_getQuote(struct soap *soap, char *symbol, char *country, float &result)
{
    float q, r;
    int socket = soap->socket; // save socket (stand-alone service only, does not support keep-alive)
    if (soap_call_ns1_getQuote(soap, "http://services.xmethods.net/soap", "", symbol, &q)
    == 0 &&
        soap_call_ns2_getRate(soap, "http://services.xmethods.net/soap", NULL, "us", coun-
    try, &r) == 0)
    {
        result = q*r;
        soap->socket = socket;
        return SOAP_OK;
    }
    soap->socket = socket;
```

```

    return SOAP_FAULT; // pass soap fault messages on to the client of this app
}
/* Since this app is a combined client-server, it is put together with
one header file that describes all remote methods. However, as a consequence we
have to implement the methods that are not ours. Since these implementations are
never called (this code is client-side), we can make them dummies as below.
/
int ns1_getQuote(struct soap *soap, char *symbol, float &result)
{ return SOAP_NO_METHOD; } // dummy: will never be called
int ns2_getRate(struct soap *soap, char *country1, char *country2, float &result)
{ return SOAP_NO_METHOD; } // dummy: will never be called

struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/*/XMLSchema-
instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"},
    {"ns1", "urn:xmethods-delayed-quotes"},
    {"ns2", "urn:xmethods-CurrencyExchange"},
    {"ns3", "urn:quotex"},
    {NULL, NULL}
};

```

To compile:

```

soapcpp2 quotex.h
g++ -o quotex.cgi quotex.cpp soapC.cpp soapClient.cpp soapServer.cpp stdsoap2.cpp -lsocket -lnet
-lnsl

```

Note: under Linux and Mac OS X you can often omit the `-l` libraries.

The `quotex.cgi` executable is installed as a CGI application on the Web by copying it in the designated directory specific to your Web server. After this, the executable can also serve to test the service. For example

```
quotex.cgi IBM uk
```

returns the quote of IBM in uk pounds by communicating the request and response quote from the CGI application. See <http://xmethods.com/detail.html?id=5> for details on the currency abbreviations.

When combining clients and service functionalities, it is required to use one header file input to the compiler. As a consequence, however, stubs and skeletons are available for **all** remote methods, while the client part will only use the stubs and the service part will use the skeletons. Thus, dummy implementations of the unused remote methods need to be given which are never called.

Three WSDL files are created by gSOAP: `ns1.wsd1`, `ns2.wsd1`, and `ns3.wsd1`. Only the `ns3.wsd1` file is required to be published as it contains the description of the combined service, while the others are generated as a side-effect (and in case you want to develop these separate services).

8.3 How to Use gSOAP for Asynchronous One-Way Message Passing

SOAP RPC client-server interaction is synchronous: the client blocks until the server responds to the request. gSOAP also supports asynchronous one-way message passing and the interoperable synchronous one-way message passing over HTTP. The two styles are similar, but only the latter is interoperable and is compliant to Basic Profile 1.0. The interoperable synchronous one-way message passing style over HTTP is discussed in Section 8.4 below.

SOAP messaging routines are declared as function prototypes, just like remote methods for SOAP RPC. However, the output parameter is a **void** type to indicate the absence of a return value.

For example, the following header file specifies a event message for SOAP messaging:

```
int ns_event(int eventNo, void dummy);
```

The gSOAP stub and skeleton compiler generates the following functions in soapClient.cpp:

```
int soap_send_ns_event(struct soap *soap, const char URL, const char action, int event);  
int soap_recv_ns_event(struct soap *soap, struct ns_event *dummy);
```

The `soap_send_ns_event` function transmits the message to the destination URL by opening a socket and sending the SOAP encoded message. The socket will remain open after the send and has to be closed with `soap_closesock()`. The open socket connection can also be used to obtain a service response, e.g. with a `soap_recv` function call.

The `soap_recv_ns_event` function waits for a SOAP message on the currently open socket (`soap.socket`) and fills the **struct** `ns_event` with the `ns_event` parameters (e.g. **int** `eventNo`). The **struct** `ns_event` is automatically created by gSOAP and is a mirror image of the `ns_event` parameters:

```
struct ns_event  
{ int eventNo;  
}
```

The gSOAP generated `soapServer.cpp` code includes a skeleton routine to accept the message. (The skeleton routine does not respond with a SOAP response message.)

```
int soap_serve_ns_event(struct soap *soap);
```

The skeleton routine calls the user-implemented `ns_event(struct soap *soap, int eventNo)` routine (note the absence of the void parameter!).

As usual, the skeleton will be automatically called by the remote method request dispatcher that handles both the remote method requests (RPCs) and messages:

```
main()  
{ soap_serve(soap_new());  
}  
int ns_event(struct soap *soap, int eventNo)  
{  
    ... // handle event  
    return SOAP_OK;  
}
```

8.4 One-Way Message Passing over HTTP

One-way SOAP message passing over HTTP as defined by the SOAP specification and Basic Profile 1.0 is synchronous, meaning that the server must respond with an HTTP OK header and an empty body. To implement synchronous one-way messaging, the same setup for asynchronous one-way messaging discussed in Section 8.3 is used, but with one simple addition at the client and server side.

At the server side, we need to return an empty HTTP OK response. This is accomplished as follows. For each one-way operation implemented in C/C++, we replace the **return** SOAP_OK with:

```
int ns_event(struct soap *soap, int eventNo)
{
    ... // handle event
    return soap_send_empty_response(soap);
}
```

At the client side, the empty response header must be parsed as follows:

```
if (soap_send_ns_event(soap, eventNo) != SOAP_OK
    || soap_recv_empty_response(soap) != SOAP_OK)
    soap_print_fault(soap, stderr);
...
```

The synchronous (and asynchronous) one-way messaging supports HTTP keep-alive and chunking.

8.5 How to Use the SOAP Serializers and Deserializers to Save and Load Application Data

The gSOAP stub and skeleton compiler generates serializers and deserializers for all user-defined data structures that are specified in the header file input to the compiler. The serializers and deserializers can be found in the generated `soapC.cpp` file. These serializers and deserializers can be used separately by an application without the need to build a full client or service application. This is useful for applications that need to save or export their data in XML or need to import or load data stored in XML format.

The following attributes can be set to control the destination and source for serialization and deserialization:

Variable	Description
int soap.socket	socket file descriptor for input and output or -1
ostream *soap.os	(C++ only) output stream used for send operations
istream *soap.is	(C++ only) input stream used for receive operations
int soap.sendfd	when soap_socket<0, this fd is used for send operations
int soap.recvfd	when soap_socket<0, this fd is used for receive operations

The following initializing and finalizing functions can be used:

Function	Description
void soap_begin_send(struct soap*)	start a send/write phase
int soap_end_send(struct soap*)	flush the buffer
int soap_begin_rcv(struct soap*)	start a rec/read phase (if an HTTP header is present, parse it first)
int soap_end_rcv(struct soap*)	perform a id/href consistency check on deserialized data

These operations do not open or close the connections. The application should open and close connections or files and set the `soap.socket`, `soap.os` or `soap.sendfd`, `soap.is` or `soap.recvfd` streams or descriptors. When `soap.socket < 0` and none of the streams and descriptors are set, then the standard input and output will be used.

See also Section 9.12 to control the I/O buffering and content encoding such as compression and DIME encoding.

8.5.1 Serializing a Data Type

To serialize a data type to a stream, two functions should be called to prepare for serialization of the data and to send the data, respectively. The first function, `soap_serialize`, analyzes pointers and determines if multi-references are required to encode the data and if cycles are present the object graph. The second function, `soap_put`, produces the XML output on a stream.

The `soap_serialize` and `soap_put` function names are specific to a data type. For example, `soap_serialize_float(&soap, &d)` is called to serialize an **float** value and `soap_put_float(&soap, &d, "number", NULL)` is called to output the floating point value in SOAP tagged with the name `<number>`. To initialize data, the `soap_default` function of a data type can be used. For example, `soap_default_float(&soap, &d)` initializes the float to 0.0. The `soap_default` functions are useful to initialize complex data types such as arrays, **structs**, and **class** instances. Note that the `soap_default` functions do not need the gSOAP runtime environment as a first parameter.

The following table lists the type naming conventions used by gSOAP:

Type	Type Name
char*	string
wchar_t*	wstring
char	byte
bool	bool
double	double
int	int
float	float
long	long
LONG64	LONG64 (Win32)
long long	LONG64 (Unix/Linux)
short	short
time_t	time
unsigned char	unsignedByte
unsigned int	unsignedInt
unsigned long	unsignedLong
ULONG64	unsignedLONG64 (Win32)
unsigned long long	unsignedLONG64 (Unix/Linux)
unsigned short	unsignedShort
<u>T</u> [<u>N</u>]	Array <u>N</u> Of <u>Type</u> where <u>Type</u> is the type name of <u>T</u>
<u>T</u> *	PointerTo <u>Type</u> where <u>Type</u> is the type name of <u>T</u>
struct Name	Name
class Name	Name
enum Name	Name

Consider for example the following C code with a declaration of `p` as a pointer to a **struct** `ns._Person`:

```
struct ns._Person { char *name; } *p;
```

To serialize `p`, its address is passed to the function `soap_serialize_PointerTons._Person` generated for this type by the gSOAP compiler:

```
soap_serialize_PointerTons._Person(&soap, &p);
```

The **address of** `p` is passed, so the serializer can determine whether `p` was already serialized and to discover cycles in graph data structures. To generate the output, the address of `p` is passed to the function `soap_put_PointerTons._Person` together with the name of an XML element and an optional type string (to omit a type, use `NULL`):

```
soap_begin_send(&soap);
soap_put_PointerTons._Person(&soap, &p, "ns:element-name", "ns:type-name");
soap_end_send(&soap);
```

This produces:

```
<ns:element-name xmlns:SOAP-ENV="..." xmlns:SOAP-ENC="..." xmlns:ns="..."
  ... xsi:type="ns:type-name">
<name xsi:type="xsd:string">...</name>
</ns:element-name>
```


The serializer is initialized with the `soap_begin_send(soap)` function and closed with `soap_end_send(soap)`. All temporary data structures and data structures deserialized on the heap are destroyed with the `soap_end()` function. The `soap_free()` function can be used to remove the temporary data only and keep the deserialized data on the heap. Temporary data structures are only created if the encoded data uses pointers. Each pointer in the encoded data has an internal hash table entry to determine all multi-reference parts and cyclic parts of the complete data structure.

You can assign an output stream to `soap.os` or a file descriptor to `soap.sendfd`. For example

```
soap.sendfd = open(file, O_RDWR|O_CREAT, S_IWUSR|S_IRUSR);
soap_serialize_PointerTons_Person(&soap, &p);
soap_begin_send(&soap);
soap_put_PointerTons_Person(&soap, &p, "ns:element-name", "ns:type-name");
soap_end_send(&soap);
```

The `soap_serialize` function is optional. It **MUST** be used when the object graph contains cycles. It **MUST** be called to preserve the logical coherence of pointer-based data structures, where pointers may refer to co-referenced objects. By calling `soap_serialize`, data structures shared through pointers are serialized only once and referenced in XML using id-refs attributes. This actual id-refs used depend on the SOAP encoding. To turn off SOAP encoding, remove or avoid using the SOAP-ENV and SOAP-ENC namespace bindings in the namespace table. In addition, the SOAP_XML_TREE and SOAP_XML_GRAPH flags can be used to control the output.

To save the data as an XML tree (with one root) without any id-ref attributes, use the SOAP_XML_TREE flag. The data structure **MUST NOT** contain pointer-based cycles.

To preserve the exact structure of the data object graph and create XML with one root, use the SOAP_XML_GRAPH output-mode flag (see Section 9.12). Use this flag and the `soap_serialize` function to prepare the serialization of data with in-line id-ref attributes. Using the SOAP_XML_GRAPH flag assures the preservation of the logical structure of the data

For example, to encode the contents of two variables `var1` and `var2` that may share data through pointer structures, the serializers are called before the output routines:

```
T1 var1;
T2 var2;
struct soap soap;
...
soap_init(&soap); // initialize
[soap_omode(&soap, flags);] // set output-mode flags (e.g. SOAP_ENC_XML|SOAP_ENC_ZLIB)
soap_begin(&soap); // start new (de)serialization phase
soap_set_omode(&soap, SOAP_XML_GRAPH);
soap_serialize_Type1(&soap, &var1);
soap_serialize_Type2(&soap, &var2);
...
[soap.socket = a_socket_file_descriptor;] // when using sockets
[soap.os = an_output_stream;] // C++
[soap.sendfd = an_output_file_descriptor;] // C
soap_begin_send(&soap);
soap_put_Type1(&soap, &var1, "[namespace-prefix:]element-name1", "[namespace-prefix:]type-name1");
soap_put_Type2(&soap, &var2, "[namespace-prefix:]element-name2", "[namespace-prefix:]type-name2");
```

```

...
soap_end_send(&soap); // flush
soap_end(&soap); // remove temporary data structures after phase
soap_done(&soap); // finalize last use of this environment
...

```

where Type1 is the type name of T1 and Type2 is the type name of T2 (see table above). The strings [namespace-prefix:]type-name1 and [namespace-prefix:]type-name2 describe the schema types of the elements. Use NULL to omit this type information.

For serializing class instances, method invocations **MUST** be used instead of function calls, for example `obj.soap_serialize(&soap)` and `obj.soap_put(&soap, "elt", "type")`. This ensures that the proper serializers are used for serializing instances of derived classes.

You can serialize a class instance to a stream as follows:

```

struct soap soap;
myClass obj;
soap_init(&soap); // initialize
soap_begin(&soap); // start new (de)serialization phase
soap_set_omode(&soap, SOAP_XML_GRAPH);
obj.serialize(&soap);
soap.os = cout; // send to cout
soap_begin_send(&soap);
obj.put(&soap, "[namespace-prefix:]element-name1", "[namespace-prefix:]type-name1");
...
soap_end_send(&soap); // flush
soap_end(&soap); // remove temporary data structures after phase
soap_done(&soap); // finalize last use of this environment

```

When you declare a soap struct pointer as a data member in a class, you can overload the << operator to serialize the class to streams:

```

ostream &operator<<(ostream &o, const myClass &e)
{
    if (!e.soap)
        ... error: need a soap struct to serialize (could use global struct) ...
    else
    {
        ostream *os = e.soap->os;
        e.soap->os = &o;
        soap_set_omode(e.soap, SOAP_XML_GRAPH);      e.serialize(e.soap);
        soap_begin_send(e.soap);
        e.put(e.soap, "myClass", NULL);
        soap_end_send(e.soap);
        e.soap->os = os;
        soap_clr_omode(e.soap, SOAP_XML_GRAPH);
    }
    return o;
}

```

Of course, when you construct an instance you must set its soap struct to a valid environment. Deserialized class instances with a soap struct data member will have their soap structs set automatically, see Section 9.13.2.

In principle, XML output for a data structure can be produced with `soap_put` without calling the `soap_serialize` function first. In this case, the result is similar to `SOAP_XML_TREE` which means that no id-refs are output. Cycles in the data structure will crash the serialization algorithm, even when the `SOAP_XML_GRAPH` is set.

Consider the following **struct**:

```
// Contents of file "tricky.h":
struct Tricky
{
    int *p;
    int n;
    int *q;
};
```

The following fragment initializes the pointer fields `p` and `q` to the value of field `n`:

```
struct soap soap;
struct Tricky X;
X.n = 1;
X.p = &X.n;
X.q = &X.n;
soap_init(&soap);
soap_begin(&soap);
soap_serialize_Tricky(&soap, &X);
soap_put_Tricky(&soap, &X, "Tricky", NULL);
soap_end(&soap); // Clean up temporary data used by the serializer
```

What is special about this data structure is that `n` is 'fixed' in the Tricky structure, and `p` and `q` both point to `n`. The gSOAP serializers strategically place the id-ref attributes such that `n` will be identified as the primary data source, while `p` and `q` are serialized with ref/href attributes.

The resulting output is:

```
<Tricky xsi:type="Tricky">
<p href="#2"/> <n xsi:type="int">1</n> <q href="#2"/> <r xsi:type="int">2</r> </Tricky>
<id id="2" xsi:type="int">1</id>
```

which uses an independent element at the end to represent the multi-referenced integer, assuming the SOAP-ENV and SOAP-ENC namespaces indicate SOAP 1.1 encoding.

With the `SOAP_XML_GRAPH` flag the output is:

```
<Tricky xsi:type="Tricky">
<p href="#2"/> <n id="2" xsi:type="int">1</n> <q href="#2"/> </Tricky>
```

In this case, the XML is self-contained and multi-referenced data is accurately serialized. The gSOAP generated deserializer for this data type will be able to accurately reconstruct the data from the XML (on the heap).

8.5.2 Deserializing a Data Type

To deserialize a data type, its `soap_get` function is used. The outline of a program that deserializes two variables `var1` and `var2` is for example:

```
T1 var1;
T2 var2;
struct soap soap;
...
soap_init(&soap); // initialize at least once
[soap_imode(&soap, flags);] // set input-mode flags
soap_begin(&soap); // begin new decoding phase
[soap.is = an_input_stream;] // C++
[soap.recvfd = an_input_file_desriptpr;] // C
soap_begin_recv(&soap); // if HTTP/MIME/DIME/GZIP headers are present, parse them
if (!soap_get_Type1(&soap, &var1, "[namespace-prefix:]element-name1", "[namespace-prefix:]type-name1"))
    ... error ...
if (!soap_get_Type2(&soap, &var2, "[namespace-prefix:]element-name2", "[namespace-prefix:]type-name1"))
    ... error ...
...
soap_end_recv(&soap); // check consistency of id/hrefs
soap_destroy(&soap); // remove deserialized class instances
soap_end(&soap); // remove temporary data, including the decoded data on the heap
soap_done(&soap); // finalize last use of the environment
```

The strings `[namespace-prefix:]type-name1` and `[namespace-prefix:]type-name2` are the schema types of the elements and should match the `xsi:type` attribute of the receiving message. To omit the match, use `NULL` as the type. For class instances, method invocation can be used instead of a function call if the object is already instantiated, i.e. `obj.soap_get(&soap, "...", "...")`.

The `soap_begin` call resets the deserializers. The `soap_destroy` and `soap_end` calls remove the temporary data structures **and** the decoded data that was placed on the heap.

To remove temporary data while retaining the deserialized data on the heap, the function `soap_free` should be called instead of `soap_destroy` and `soap_end`.

One call to the `soap_get_Type` function of a type `Type` scans the entire input to process its XML content and to capture SOAP 1.1 independent elements (which contain multi-referenced objects). As a result, `soap.error` will set to `SOAP_EOF`. Also storing multiple objects into one file will fail to decode them properly with multiple `soap_get` calls. A well-formed XML document should only have one root anyway, so don't save multiple objects into one file. If you must save multiple objects, create a linked list or an array of objects and save the linked list or array. You could use the `soap_in_Type` function instead of the `soap_get_Type` function. The `soap_in_Type` function parses one XML element at a time.

You can deserialize class instances from a stream as follows:

```
myClass obj;
struct soap soap;
```

```

soap_init(&soap); // initialize
soap_begin(&soap); // begin new decoding phase
soap.is = cin; // read from cin
soap_begin_recv(&soap); // if HTTP header is present, parse it
if (!obj.get(&soap, "myClass", NULL))
    ... error ...
soap_end_recv(&soap); // check consistency of id/hrefs
...
soap_destroy(&soap); // remove deserialized class instances
soap_end(&soap); // remove temporary data, including the decoded data on the heap
soap_done(&soap); // finalize last use of the environment

```

When you declare a soap struct pointer as a data member in a class, you can overload the >> operator to parse and deserialize a class instance from a stream:

```

istream &operator>>(istream &i, myClass &e)
{
    if (!e.soap)
        ... error: need soap struct to deserialize (could use global struct)...
    istream *is = e.soap->is;
    e.soap->is = &i;
    if (soap_begin_recv(e.soap) || e.in(e.soap, NULL, NULL) || soap_end_recv(e.soap))
        ... error ...
    e.soap->is = is;
    return i;
}

```

8.5.3 Example

As an example, consider the following data type declarations:

```

// Contents of file "person.h":
typedef char *xsd__string;
typedef char *xsd__Name;
typedef unsigned int xsd__unsignedInt;
enum ns__Gender {male, female};
class ns__Address
{
    public:
        xsd__string street;
        xsd__unsignedInt number;
        xsd__string city;
};
class ns__Person
{
    public:
        xsd__Name name;
        enum ns__Gender gender;
        ns__Address address;
        ns__Person *mother;
}

```

```

    ns_.Person *father;
};

```

The following program uses these data types to write to standard output a data structure that contains the data of a person named "John" living at Downing st. 10 in London. He has a mother "Mary" and a father "Stuart". After initialization, the class instance for "John" is serialized and encoded in XML to the standard output stream using gzip compression (requires the Zlib library, compile sources with -DWITH_GZIP):

```

// Contents of file "person.cpp":
#include "soapH.h"
int main()
{
    struct soap soap;
    ns_.Person mother, father, john;
    mother.name = "Mary";
    mother.gender = female;
    mother.address.street = "Downing st.";
    mother.address.number = 10;
    mother.address.city = "London";
    mother.mother = NULL;
    mother.father = NULL;
    father.name = "Stuart";
    father.gender = male;
    father.address.street = "Main st.";
    father.address.number = 5;
    father.address.city = "London";
    father.mother = NULL;
    father.father = NULL;
    john.name = "John";
    john.gender = male;
    john.address = mother.address;
    john.mother = &mother;
    john.father = &father;
    soap_init(&soap);
    soap_omode(&soap, SOAP_ENC_ZLIB|SOAP_XML_GRAPH); // see 9.12
    soap_begin(&soap);
    soap_begin_send(&soap);
    john.soap_serialize(&soap);
    john.soap_put(&soap, "johnnie", NULL);
    soap_end_send(&soap);
    soap_end(&soap);
    soap_done(&soap);
}
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "urn:person"}, // Namespace URI of the "Person" data type
}

```

```

    {NULL, NULL}
};

```

The header file is processed and the application compiled on Linux/Unix with:

```

soapcpp2 person.h
g++ -DWITH_GZIP -o person person.cpp soapC.cpp stdsoap2.cpp -lsocket -lnet -lnsl -lz

```

(Depending on your system configuration, the libraries libsocket.a, libxnet.a, libnsl.a are required. Compiling on Linux typically does not require the inclusion of those libraries.) See 19.25 for details on compression with gSOAP.

Running the person application results in the compressed XML output:

```

<johnnie xsi:type="ns:Person" xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns="urn:person"
  SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
  <name xsi:type="xsd:Name">John</name>
  <gender xsi:type="ns:Gender">male</gender>
  <address xsi:type="ns:Address">
    <street id="3" xsi:type="xsd:string">Dowling st.</street>
    <number xsi:type="unsignedInt">10</number>
    <city id="4" xsi:type="xsd:string">London</city>
  </address>
  <mother xsi:type="ns:Person">
    <name xsi:type="xsd:Name">Mary</name>
    <gender xsi:type="ns:Gender">female</gender>
    <address xsi:type="ns:Address">
      <street href="#3"/>
      <number xsi:type="unsignedInt">5</number>
      <city href="#4"/>
    </address>
  </mother>
  <father xsi:type="ns:Person">
    <name xsi:type="xsd:Name">Stuart</name>
    <gender xsi:type="ns:Gender">male</gender>
    <address xsi:type="ns:Address">
      <street xsi:type="xsd:string">Main st.</street>
      <number xsi:type="unsignedInt">13</number>
      <city href="#4"/>
    </address>
  </father>
</johnnie>

```

The following program fragment decodes this content from standard input and reconstructs the original data structure on the heap:

```

#include "soapH.h"
int main()

```

```

{
    struct soap soap;
    ns__Person *mother, *father, *john = NULL;
    soap_init(&soap);
    soap_imode(&soap, SOAP_ENC_ZLIB); // optional: gzip is detected automatically
    soap_begin(&soap);
    soap_begin_recv(&soap);
    if (soap_get_ns__Person(&soap, john, "johnnie", NULL) == NULL)
        ... error ...
    mother = john->mother;
    father = john->father;
    ...
    soap_end_recv(&soap);
    soap_free(&soap); // Clean up temporary data but keep deserialized data
}
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "urn:person"}, // Namespace URI of the "Person" data type
    {NULL, NULL}
};

```

It is REQUIRED to either pass NULL to the `soap_get` routine, or a valid pointer to a data structure that can hold the decoded content. The following example explicitly passes NULL:

```
john = soap_get_ns__Person(&soap, NULL, "johnnie", NULL);
```

Note: the second NULL parameter indicates that the schema type attribute of the receiving message can be ignored. The deserializer stores the SOAP contents on the heap, and returns the address. The allocated storage is released with the `soap_end` call, which removes all temporary and deserialized data from the heap, or with the `soap_free` call, which removes all temporary data only.

Alternatively, the XML content can be decoded within an existing allocated data structure. The following program fragment decodes the SOAP content in a **struct** `ns__Person` allocated on the stack:

```

#include "soapH.h"
main()
{
    struct soap soap;
    ns__Person *mother, *father, john;
    soap_init(&soap);
    soap_imode(&soap, SOAP_ENC_ZLIB); // optional
    soap_begin(&soap);
    soap_begin_recv(&soap);
    soap_default_ns__Person(&soap, &john);
    if (soap_get_ns__Person(&soap, &john, "johnnie", NULL) == NULL)
        ... error ...
}

```



```

    ...
}
struct Namespace namespaces[] =
    ...

```

Note the use of `soap_default_ns_1_Person`. This routine is generated by the gSOAP stub and skeleton compiler and assigns default values to the fields of `john`.

8.5.4 Serializing and Deserializing Class Instances to Streams

C++ applications can define appropriate stream operations on objects for (de)serialization of objects on streams. This is best illustrated with an example. Consider the class

```

class ns_1_person
{ public:
    char *name;
    struct soap *soap; // we need this, see below
    ns_1_person();
    ~ns_1_person();
};

```

The **struct** `soap` member is used to bind the instances to a gSOAP environment for (de)serialization. We use the gSOAP compiler from the command prompt to generate the class (de)serializers (assuming that `person.h` contains the class declaration):

```
soapcpp2 person.h
```

gSOAP generates the (de)serializers and an instantiation function for the class `soap_new_ns_1_person(struct soap *soap, int array)` to instantiate one or more objects and associate them with a gSOAP environment. The array parameter should be -1 to instantiate one object or should be the number of objects to instantiate as an array of objects.

```

#include "soapH.h"
#include "ns.nsmmap"
...
struct soap *soap = soap_new();
ns_1_person *p = soap_new_ns_1_person(soap, -1);
...
cout << p; // serialize p in XML
...
in >> p; // parse XML and deserialize p
...
soap_destroy(soap); // deletes p too
soap_end(soap);
soap_done(soap);

```

The stream operations are implemented as follows

```

ostream &operator<<(ostream &o, const ns_ person &p)
{
    if (!p->soap)
        return o; // need a gSOAP environment to serialize
    p.soap->os = &o;
    soap_omode(p.soap, SOAP_XML_GRAPH); // XML tree or graph
    p->soap_serialize(p.soap);
    soap_begin_send(p.soap);
    if (p->soap_put(p.soap, "person", NULL)
        || soap_end_send(p.soap))
        ; // handle I/O error
    return o;
}

istream &operator>>(istream &i, ns_ person &p)
{
    if (!p->soap)
        return o; // need a gSOAP environment to parse XML and deserialize
    p.soap->is = &i;
    if (soap_begin_rcv(p.soap)
        || p->soap_in(p.soap, NULL, NULL)
        || soap_end_rcv(p.soap))
        ; // handle I/O error
    return i;
}

```

8.5.5 How to Specify Default Values for Omitted Data

The gSOAP compiler generates `soap_default` functions for all data types. The default values of the primitive types can be easily changed by defining any of the following macros in the `stdsoap2.h` file:

```

#define SOAP_DEFAULT_bool
#define SOAP_DEFAULT_byte
#define SOAP_DEFAULT_double
#define SOAP_DEFAULT_float
#define SOAP_DEFAULT_int
#define SOAP_DEFAULT_long
#define SOAP_DEFAULT_LONG64
#define SOAP_DEFAULT_short
#define SOAP_DEFAULT_string
#define SOAP_DEFAULT_time
#define SOAP_DEFAULT_unsignedByte
#define SOAP_DEFAULT_unsignedInt
#define SOAP_DEFAULT_unsignedLong
#define SOAP_DEFAULT_unsignedLONG64
#define SOAP_DEFAULT_unsignedShort
#define SOAP_DEFAULT_wstring

```

Instead of adding these to `stdsoap2.h`, you can also compile with option `-DWITH_SOAPDEFS_H` and include your definitions in file `userdefs.h`. The absence of a data value in a receiving SOAP message will result in the assignment of a default value to a primitive type upon deserialization.

Default values can also be assigned to individual **struct** and **class** fields of primitive type. For example,

```
struct MyRecord
{
    char *name = "Unknown";
    int value = 9999;
    enum Status { active, passive } status = passive;
}
```

Default values are assigned to the fields on receiving a SOAP/XML message in which the data values are absent.

Because method requests and responses are essentially structs, default values can also be assigned to method parameters. The default parameter values do not control the parameterization of C/C++ function calls, i.e. all actual parameters must be present when calling a function. The default parameter values are used in case an inbound request or response message lacks the XML elements with parameter values. For example, a Web service can use default values to fill-in absent parameters in a SOAP/XML request:

```
int ns_login(char *uid = "anonymous", char *pwd = "guest", bool granted);
```

When the request message lacks uid and pwd parameters, e.g.:

```
<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
  xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns="http://tempuri.org">
  <SOAP-ENV:Body encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
    <ns:login>
    </ns:login>
  </SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```

then the service uses the default values. In addition, the default values will show up in the SOAP/XML request and response message examples generated by the gSOAP compiler.

9 Using the gSOAP Stub and Skeleton Compiler

The gSOAP stub and skeleton compiler is invoked from the command line and optionally takes the name of a header file as an argument or, when the file name is absent, parses the standard input:

```
soapcpp2 [aheaderfile.h]
```

where `aheaderfile.h` is a standard C++ header file. The compiler acts as a preprocessor and produces C++ source files that can be used to build SOAP client and Web service applications in C++. The files generated by the compiler are:

File Name	Description
soapStub.h	A modified and annotated header file produced from the input header file
soapH.h	Main header file to be included by all client and service sources
soapC.cpp	Serializers and deserializers for the specified data structures
soapClient.cpp	Client stub routines for remote operations
soapServer.cpp	Service skeleton routines
soapClientLib.cpp	Client stubs combined with local static (de)serializers
soapServerLib.cpp	Service skeletons combined with local static (de)serializers
soapXYZProxy.h	A C++ proxy object (can be used instead of soapClient.cpp)
soapXYZProxy.cpp	Implementation of C++ proxy object
soapXYZObject.h	A C++ server object (can be used instead of soapServer.cpp)
soapXYZObject.cpp	Implementation of C++ server object
.xsd	An ns.xsd file is generated with an XML Schema for each namespace prefix ns used by a data structure in the header file input to the compiler, see Section 8.2.8
.wsdl	A ns.wsdl file is generated with an WSDL description for each namespace prefix ns used by a remote method in the header file input to the compiler, see Section 8.2.8
.xml	Several SOAP/XML request and response files are generated. These are example message files are valid provided that sufficient schema namespace directives are added to the header file or the generated .nsmap namespace table for the client/service is not modified by hand
.nsmap	A ns.nsmap file is generated for each namespace prefix ns used by a remote method in the header file input to the compiler, see Section 8.2.8. The file contains a namespace mapping table that can be used in the client/service sources

Both client and service applications are developed from a header file that specifies the remote methods. If client and service applications are developed with the same header file, the applications are guaranteed to be compatible because the stub and skeleton routines use the same serializers and deserializers to encode and decode the parameters. Note that when client and service applications are developed together, an application developer does not need to know the details of the internal SOAP encoding used by the client and service.

The soapClientLib.cpp and soapServerLib.cpp can be used to build (dynamic) client and server libraries. The serialization routines are local (static) to avoid link symbol conflicts. You must create a separate library for SOAP Header and Fault handling, as described in Section 19.34.

The following files are part of the gSOAP package and are required to build client and service applications:

File Name	Description
stdsoap2.h	Header file of stdsoap2.cpp runtime library
stdsoap2.c	Runtime C library with XML parser and run-time support routines
stdsoap2.cpp	Runtime C++ library identical to stdsoap2.c

9.1 Compiler Options

The compiler supports the following options:

Option	Description
-1	Use SOAP 1.1 namespaces and encodings (default)
-2	Use SOAP 1.2 namespaces and encodings
-C	Generate client-side code only
-S	Generate server-side code only
-c	Generate pure C code
-h	Print a brief usage message
-w	Do not generate WSDL and schema files
-m	Generate Matlab [™] code for MEX compiler
-l <path>	Use <path> (or paths separated with ':') for #import
-d <path>	Save sources in directory specified by <path>
-p <name>	Save sources with file name prefix <name> instead of "soap"
-n	When used with -p, enables multi-client and multi-server builds: Sets compiler option WITH_NONNAMESPACES, see Section 9.11 Saves the namespace mapping table with name <name>_namespaces instead of namespaces Renames soap_serve() into <name>_serve() and soap_destroy() into <name>_destroy()
-t	Generates code to send typed messages (with the xsi:type attribute)

For example

```
soapcpp2 -cd '../projects' -pmy file.h
```

Saves the sources:

```
../projects/myH.h
../projects/myC.c
../projects/myClient.c
../projects/myServer.c
../projects/myStub.h
```

MS Windows users can use the usual "/" for options, for example:

```
soapcpp2 /cd '..\projects' /pmy file.h
```

Compiler options c, i, n, l, w can be set in the gSOAP header file using the //gsoapopt directive. For example,

```
// Generate pure C and do not produce WSDL output:
//gsoapopt cw
int ns_myMethod(char*,char**); // takes a string and returns a string
```

9.2 SOAP 1.1 Versus SOAP 1.2

gSOAP supports SOAP 1.1 by default. SOAP 1.2 support is automatically turned on when the appropriate SOAP 1.2 namespace is used in the namespace mapping table:

```
struct Namespace namespaces[] =
{
```

```

    {"SOAP-ENV", "http://www.w3.org/2002/06/soap-envelope"},
    {"SOAP-ENC", "http://www.w3.org/2002/06/soap-encoding"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/*/XMLSchema-
instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"}, ...
}

```

gSOAP Web services and clients can automatically switch from SOAP 1.1 to SOAP 1.2 by providing the SOAP 1.2 namespace as a pattern in the third column of a namespace table:

```

struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/", "http://www.w3.org/2002/06/soap-
encoding"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/", "http://www.w3.org/2002/06/soap-
envelope"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/*/XMLSchema-
instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"}, ...
}

```

This way, gSOAP Web services can respond to either SOAP 1.1 or SOAP 1.2 requests. gSOAP will automatically return SOAP 1.2 responses for SOAP 1.2 requests.

The gSOAP `soapcpp2` compiler generates a `.nsmap` file with SOAP-ENV and SOAP-ENC namespace patterns similar to the above. Since clients issue a send first, they will always use SOAP 1.1 for requests when the namespace table is similar as shown above. Clients can accept SOAP 1.2 responses by inspecting the response message. To restrict gSOAP services and clients to SOAP 1.2 and to generate SOAP 1.2 service WSDLs, use `soapcpp2` compiler option `-2` to generate SOAP 1.2 conformant `.nsmap` and `.wsdl` files.

Caution: SOAP 1.2 does not support partially transmitted arrays. So the `_offset` field of a dynamic array is meaningless.

Caution: SOAP 1.2 requires the use of `SOAP_ENV__Code`, `SOAP_ENV__Reason`, and `SOAP_ENV__Detail` fields in a `SOAP_ENV__Fault` fault struct, while SOAP 1.1 uses `faultcode`, `faultstring`, and `detail` fields. Use `soap_receiver_fault(struct soap *soap, const char *faultstring, const char *detail)` to set a SOAP 1.1/1.2 fault at the server-side. Use `soap_sender_fault(struct soap *soap, const char *faultstring, const char *detail)` to set a SOAP 1.1/1.2 unrecoverable Bad Request fault at the server-side.

9.3 The `soapdefs.h` Header File

The `soapdefs.h` header file is included in `stdsoap2.h` when compiling with option `-DWITH_SOAPDEFS_H`:

```
g++ -DWITH_SOAPDEFS_H -c stdsoap2.cpp
```

The `soapdefs.h` file allows users to include definitions and add includes without requiring changes to `stdsoap2.h`. For example,

```
// Contents of soapdefs.h
#include <ostream>
#define SOAP_BUFLEN 20480 // use large send/recv buffer
```

The following header file can now refer to `ostream`:

```
extern class ostream; // ostream can't be (de)serialized, but need to be declared to make it visible
                        to gSOAP
class ns_::myClass
{ ...
    virtual void print(ostream &s) const; // need ostream here
    ...
};
```

See also Section 19.3.

9.4 How to Build Modules and Libraries with the gSOAP `#module` Directive

The `#module` directive is used to build modules. A library can be build from a module and linked with multiple Web services applications. The directive should appear at the top of the header file and has the following format:

```
#module "name"
```

where *name* is a unique name for the module. The name is case insensitive and MUST not exceed 4 characters in length. The rest of the content of the header file should include type declarations and optionally the declarations of remote methods and SOAP Headers/Faults. When the gSOAP compiler processes the header file module, it will generate the source codes for a library. The Web services application that uses the library should use a header file that imports the module with the `#import` directive.

For example:

```
/* Contents of module.h */
#module "test"
long;
char*;
struct ns_::S
{ ... }
```

The `module.h` header file declares a **long**, **char***, and a **struct** `ns_::X`. The module name is "test", so the gSOAP compiler produces a `testC.cpp` file with the (de)serializers for these types. The `testC.cpp` library can be separately compiled and linked with an application that is built from a header file that imports "module.h" using `#import "module.h"`. You should also compile `testClient.cpp` when you want to build a library that includes the remote methods that you defined in the module header file.

A module **MUST** be imported into another header file to use it and you cannot use a module alone to build a SOAP or XML application. That is, the top most header file in the import tree **SHOULD NOT** be a module.

When multiple modules are linked, the types that they declare **MUST** be declared in one module only to avoid name clashes and link errors. You cannot create two modules that share the same type declaration and link the modules. When necessary, you should consider creating a module hierarchy such that types are declared only once and by only one module when these modules must be linked.

9.5 How to use the gSOAP #import Directive

The `#import` directive is used to include gSOAP header files into other gSOAP header files for processing with the gSOAP compiler `soapcpp2`. The C `#include` directive cannot be used to include gSOAP header files. The `#include` directive is reserved to control the post-gSOAP compilation process, see 9.6.

The `#import` directive is used for two purposes: you can use it to include the contents of a header file into another header file and you can use it to import a module, see 9.4.

An example of the `#import` directive:

```
#import "mydefs.gsoap"
int ns__mymethod(xsd__string in, xsd__int *out);
```

where "mydefs.gsoap" is a gSOAP header file that defines `xsd__string` and `xsd__int`:

```
typedef char *xsd__string;
typedef int xsd__int;
```

9.6 How to Use #include and #define Directives

The `#include` and `#define` directives are normally ignored by the gSOAP compiler. The use of the directives is enabled with the `-i` option of the gSOAP compiler, see Section 9.1. However, the gSOAP compiler will not actually parse the contents of the header files provided by the `#include` directives in a header file. Instead, the `#include` and `#define` directives will be added to the generated `soapH.h` header file **before** any other header file is included. Therefore, `#include` and `#define` directives can be used to control the C/C++ compilation process of the sources of an application.

The following example header file refers to `ostream` by including `<ostream>`:

```
#include <ostream>
#define WITH_COOKIES // use HTTP cookie support (you must compile stdsoap2.cpp with -DWITH_COOKIES)
#define WITH_OPENSSL // enable HTTPS (SSL) support (you must compile stdsoap2.cpp with -DWITH_OPENSSL)
#define SOAP_DEFAULT_float FLT_NAN // use NaN instead of 0.0
extern class ostream; // ostream can't be (de)serialized, but need to be declared to make it visible to gSOAP
```



```

class ns_::myClass
{ ...
    virtual void print(ostream &s) const; // need ostream here
    ...
};

```

This example also uses `#define` directives for various settings.

Caution: Note that the use of `#define` in the header file does not automatically result in compiling `stdsoap2.cpp` with these directives. You **MUST** use the `-DWITH_COOKIES` and `-DWITH_OPENSSL` options when compiling `stdsoap2.cpp` before linking the object file with your codes. As an alternative, you can use `#define WITH_SOAPDEFS_H` and put the `#define` directives in the `soapdefs.h` file.

9.7 Compiling a gSOAP Client

After invoking the gSOAP stub and skeleton compiler on a header file description of a service, the client application can be compiled on a Linux machine as follows:

```
g++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp
```

Or on a Unix machine:

```
g++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lnet -lnsl
```

(Depending on your system configuration, the libraries `libsocket.a`, `libxnet.a`, `libnsl.a` or dynamic `*.so` versions of those libraries are required.)

The `myclient.cpp` file must include `soapH.h` and must define a global namespace mapping table. A typical client program layout with namespace mapping table is shown below:

```

// Contents of file "myclient.cpp"
#include "soapH.h";
...
// A remote method invocation:
soap_call_some_remote_method(...);
...
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name"}
  {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
  {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
  {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
  {"xsd", "http://www.w3.org/2001/XMLSchema"},
  {"ns1", "urn:my-remote-method"},
  {NULL, NULL}
};
...

```

A mapping table is generated by the gSOAP compiler that can be used in the source, see Section 8.2.8.

9.8 Compiling a gSOAP Web Service

After invoking the gSOAP stub and skeleton compiler on a header file description of the service, the server application can be compiled on a Linux machine as follows:

```
g++ -o myserver myserver.cpp stdsoap2.cpp soapC.cpp soapServer.cpp
```

Or on a Unix machine:

```
g++ -o myserver myserver.cpp stdsoap2.cpp soapC.cpp soapServer.cpp -lsocket -lnet -lnsl
```

(Depending on your system configuration, the libraries libsocket.a, libxnet.a, libnsl.a or dynamic *.so versions of those libraries are required.)

The myserver.cpp file must include soapH.h and must define a global namespace mapping table. A typical service program layout with namespace mapping table is shown below:

```
// Contents of file "myserver.cpp"
#include "soapH.h";
int main()
{
    soap_serve(soap_new());
}
...
// Implementations of the remote methods as C++ functions
...
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name"}
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns1", "urn:my-remote-method"},
    {NULL, NULL}
};
...
```

When the gSOAP service is compiled and installed as a CGI application, the soap_serve function acts as a service dispatcher. It listens to standard input and invokes the method via a skeleton routine to serve a SOAP client request. After the request is served, the response is encoded in SOAP and send to standard output. The method must be implemented in the server application and the type signature of the method must be identical to the remote method specified in the header file. That is, the function prototype in the header file must be a valid prototype of the method implemented as a C/C++ function.

9.9 Using gSOAP for Creating Web Services and Clients in Pure C

The gSOAP compiler can be used to create pure C Web services and clients. The gSOAP stub and skeleton compiler soapcpp2 generates .cpp files by default. The compiler generates .c files with the

-c option. However, these files only use C syntax and data types **if** the header file input to soapcpp2 uses C syntax and data types. For example:

```
soapcpp2 -c quote.h
gcc -o quote quote.c stdsoap2.c soapC.c soapClient.c
```

Warnings will be issued by the compiler when C++ class declarations occur in the header file.

9.10 Limitations of gSOAP

gSOAP is SOAP 1.1 and SOAP 1.2 compliant and supports SOAP RPC and document/literal operations.

From the perspective of the C/C++ language, a few C++ language features are not supported by gSOAP and these features cannot be used in the specification of SOAP remote methods.

There are certain limitations for the following C++ language constructs:

STL and STL templates The gSOAP compiler supports STL strings `std::string` and `std::wstring` (see Section 11.2.6) and the STL containers `std::deque`, `std::list`, `std::vector`, and `std::set`, (see Section 11.10.8).

Templates The gSOAP compiler is a preprocessor that cannot determine the template instantiations used by the main program, nor can it generate templated code. You can however implement containers similar to the STL containers.

Multiple inheritance Single class inheritance is supported. Multiple inheritance cannot be supported due to limitations of the SOAP protocol.

Abstract methods A class must be instantiatable to allow decoding of instances of the class.

Directives Directives and pragmas such as `#include` and `#define` are interpreted by the gSOAP compiler. However, the interpretation is different compared to the usual handling of directives, see Section 9.6. If necessary, a traditional C++ preprocessor can be used for the interpretation of directives. For example, Unix and Linux users can use “`cpp -B`” to expand the header file, e.g. `cpp -B myfile.h | soapcpp2`. Use the gSOAP `#import` directive to import gSOAP header files, see 9.5.

C and C++ programming statements All class methods of a class should be declared within the class declaration in the header file, but the methods should not be implemented in code. All class method implementations must be defined within another C++ source file and linked to the application.

The following data types require some attention to ensure they are serialized:

union types A **union** data type can not be serialized unless run-time information is associated with a **union** in a struct/class as discussed in Section 11.6. An alternative is to use a **struct** with a pointer type for each field. Because NULL pointers are not encoded, the resulting encoding will appear as a union type if only one pointer field is valid (i.e. non-NULL) at the time that the data type is encoded.

void and void* types The **void** data type cannot be serialized unless run-time type information is associated with the pointer using a **int** `__type` field in the struct/class that contains the **void***. The **void*** data type is typically used to point to some object or to some array of some type of objects at run-time. The compiler cannot determine the type of data pointed to and the size of the array pointed to. A struct or class with a **void*** field can be augmented to support the (de)serialization of the **void*** using a **int** `__type` field as described in Section 11.8.

Pointers to sequences of elements in memory Any pointer, except for C strings which are pointers to a sequence of characters, are treated by the compiler as if the pointer points to **only one element in memory** at run-time. Consequently, the encoding and decoding routines will ignore any subsequent elements that follow the first in memory. For the same reason, arrays of undetermined length, e.g. **float a[]** cannot be used. gSOAP supports dynamic arrays using a special type convention, see Section 11.10.

Uninitialized pointers Obviously, all pointers that are part of a data structure must be valid or NULL to enable serialization of the data structure at run time.

There are a number of programming solutions that can be adopted to circumvent these limitations. Instead of using **void***, a program can in some cases be modified to use a pointer to a known type. If the pointer is intended to point to different types of objects, a generic base class can be declared and the pointer is declared to point to the base class. All the other types are declared to be derived classes of this base class. For pointers that point to a sequence of elements in memory dynamic arrays should be used instead, see 11.10.

9.11 Compile Time Flags

The following macros (`#defines`) can be used to enable certain optional features:

Macro	Description
WITH_SOAPDEFS_H	includes the <code>soapdefs.h</code> file for custom settings, see Section 9.3
WITH_COOKIES	enables HTTP cookies, see Sections 19.26 19.27
WITH_OPENSSL	enables OpenSSL, see Sections 19.20 19.19
WITH_IPV6	enables IPv6 support
WITH_FASTCGI	enables FastCGI, see Sections 19.29
WITH_GZIP	enables gzip and deflate compression, see Section 19.25
WITH_ZLIB	enables deflate compression only, see Section 19.25
WITH_UDP	enables UDP support (SOAP-over-UDP), see Section 18
WITH_FAST	(obsolete)
WITH_NOIO	eliminates need for file IO and BSD socket library, see Section 19.31
WITH_NOHTTP	eliminates HTTP stack to reduce code size
WITH_LEAN	creates a small-footprint executable, see Section 19.30
WITH_LEANER	creates an even smaller footprint executable, see Section 19.30
WITH_NONAMESPACES	omit initialization of soap struct with global <code>namespaces</code> table and you MUST explicitly initialize <code>soap.namespaces</code> to point to a table see also Section 10.4
WITH_NOGLOBAL	omit SOAP Header and Fault serialization code
WITH_CDATA	retain the parsed CDATA sections in literal XML strings (no conversion)
WITH_CASEINSENSITIVETAGS	enable case insensitive XML parsing

Caution: it is important that the macros **MUST** be consistently defined to compile the sources, such as `stdsoap2.cpp`, `soapC.cpp`, `soapClient.cpp`, `soapServer.cpp`, and all application sources that include `stdsoap2.h` or `soapH.h`. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP environment.

9.12 Run Time Flags

gSOAP provides flags to control the input and output mode settings at runtime. These flags are divided into four categories: transport (IO), content encoding (ENC), XML marshalling (XML), and C/C++ data mapping (C).

Although gSOAP is fully SOAP 1.1 compliant, some SOAP implementations may have trouble accepting multi-reference data and/or require explicit nil data so these flags can be used to put gSOAP in “safe mode”. In addition, the embedding (or inlining) of multi-reference data is adopted in the SOAP 1.2 specification, which gSOAP automatically supports when handling with SOAP 1.2 messages. The flags are:

Flag	Description
SOAP_IO_FLUSH	Disable buffering and flush output (default for all file-based output)
SOAP_IO_BUFFER	Enable buffering (default for all socket-oriented connections)
SOAP_IO_STORE	Store entire message to calculate HTTP content length
SOAP_IO_CHUNK	Use HTTP chunking
SOAP_IO_LENGTH	Require apriori calculation of content length (this is automatic)
SOAP_IO_KEEPALIVE	Attempt to keep socket connections alive (open)
SOAP_IO_UDP	Use UDP (datagram) transport, maximum message length is SOAP_BUFLLEN
SOAP_ENC_XML	Use plain XML encoding without HTTP headers (useful with SOAP_ENC_ZLIB)
SOAP_ENC_DIME	Use DIME encoding (automatic when DIME attachments are used)
SOAP_ENC_MIME	Use MIME encoding (activate using <code>soap_set_mime</code>)
SOAP_ENC_MTOM	Use MTOM XOP attachments (instead of DIME)
SOAP_ENC_ZLIB	Compress encoding with Zlib (deflate or gzip format)
SOAP_ENC_SSL	Encrypt encoding with SSL (automatic with “https:” endpoints)
SOAP_XML_CANONICAL	Produce canonical XML output
SOAP_XML_STRICT	XML strict validation
SOAP_XML_TREE	Serialize data as XML trees (no multi-ref, duplicate data when necessary)
SOAP_XML_GRAPH	Serialize data as an XML graph with inline multi-ref (SOAP 1.2 default)
SOAP_XML_NIL	Serialize NULL data as <code>xsi:nil</code> elements (omit by default)
SOAP_C_NOIOB	Do not fault with SOAP_IOB
SOAP_C_UTFSTRING	(De)serialize 8-bit strings “as is” (strings MUST have UTF-8 encoded content)
SOAP_C_MBSTRING	Activate multibyte character support (depends on locale)

The flags can be selectively turned on/off at any time, for example when multiple Web services are accessed by a client that require special treatment.

All flags are orthogonal, except `SOAP_IO_FLUSH`, `SOAP_IO_BUFFER`, `SOAP_IO_STORE`, and `SOAP_IO_CHUNK` which are enumerations and only one of these I/O flags can be used. Also the XML serialization flags `SOAP_XML_TREE` and `SOAP_XML_GRAPH` should not be mixed.

The flags control the inbound and outbound message transport, encoding, and (de)serialization. The following functions are used to set and reset the flags for input and output modes:

Function	Description
soap_init2(struct soap *soap, int imode, int omode)	Initialize the runtime and set flags
soap_imode(struct soap *soap, int imode)	Set all input mode flags
soap_omode(struct soap *soap, int omode)	Set all output mode flags
soap_set_imode(struct soap *soap, int imode)	Enable input mode flags
soap_set_omode(struct soap *soap, int omode)	Enable output mode flags
soap_clr_imode(struct soap *soap, int imode)	Disable input mode flags
soap_clr_omode(struct soap *soap, int omode)	Disable output mode flags

The default setting is SOAP_IO_DEFAULT for both input and output modes.

For example

```
struct soap soap;
soap_init2(&soap, SOAP_IO_KEEPAIVE,
    SOAP_IO_KEEPAIVE|SOAP_ENC_ZLIB|SOAP_XML_TREE|SOAP_XML_CANONICAL);
if (soap_call_ns_myMethod(&soap, ...))
...

```

sends a compressed client request with keep-alive enabled and all data serialized as canonical XML trees.

In many cases, setting the input mode will have no effect, especially with HTTP transport because gSOAP will determine the optimal input buffering and the encoding used for an inbound message. The flags that have an effect on handling inbound messages are SOAP_IO_KEEPAIVE, SOAP_ENC_SSL (but automatic when "https:" endpoints are used or soap_ssl_accept), SOAP_C_NOIOB, SOAP_C_UTFSTRING, and SOAP_C_MBSTRING.

Caution: The SOAP_XML_TREE serialization flag can be used to improve interoperability with SOAP implementations that are not fully SOAP 1.1 compliant. However, a tree serialization will duplicate data when necessary and will crash the serializer for cyclic data structures.

9.13 Memory Management

Understanding gSOAP's run-time memory management is important to optimize client and service applications by eliminating memory leaks and/or dangling references.

There are two forms of dynamic (heap) allocations made by gSOAP's runtime for serialization and deserialization of data. Temporary data is created by the runtime such as hash tables to keep pointer reference information for serialization and hash tables to keep XML id/href information for multi-reference object deserialization. Deserialized data is created upon receiving SOAP messages. This data is stored on the heap and requires several calls to the malloc library function to allocate space for the data and **new** to create class instances. All such allocations are tracked by gSOAP's runtime by linked lists for later deallocation. The linked list for malloc allocations uses some extra space in each malloced block to form a chain of pointers through the malloced blocks. A separate malloced linked list is used to keep track of class instance allocations.

gSOAP does not enforce a deallocation policy and the user can adopt a deallocation policy that works best for a particular application. As a consequence, deserialized data is never deallocated by the gSOAP runtime unless the user explicitly forces deallocation by calling functions to deallocate data collectively or individually.

The deallocation functions are:

Function Call	Description
<code>soap_end(struct soap *soap)</code>	Remove temporary data and deserialized data except class instances
<code>soap_free(struct soap *soap)</code>	Remove temporary data only
<code>soap_destroy(struct soap *soap)</code>	Remove all dynamically allocated class instances. Need to be called before <code>soap_end()</code>
<code>soap_dealloc(struct soap *soap, void *p)</code>	Remove malloced data at <code>p</code> . When <code>p==NULL</code> : remove all dynamically allocated (deserialized) data except class instances
<code>soap_delete(struct soap *soap, void *p)</code>	Remove class instance at <code>p</code> . When <code>p==NULL</code> : remove all dynamically allocated (deserialized) class instances (this is identical to calling <code>soap_destroy(struct soap *soap)</code>)
<code>soap_unlink(struct soap *soap, void *p)</code>	Unlink data/object at <code>p</code> from gSOAP's deallocation chain so gSOAP won't deallocate it
<code>soap_done(struct soap *soap)</code>	Reset: close master/slave sockets and remove callbacks (see Section 19.7)

Temporary data (i.e. the hash tables) are automatically removed with calls to the `soap_free` function which is made within `soap_end` and `soap_done` or when the next call to a stub or skeleton routine is made to send a message or receive a message. Deallocation of non-class based data is straightforward: `soap_end` removes all dynamically allocated deserialized data (data allocated with `soap_malloc`. That is, when the client/service application does not use any class instances that are (de)marshalled, but uses structs, arrays, etc., then calling the `soap_end` function is safe to remove all deserialized data. The function can be called after processing the deserialized data of a remote method call or after a number of remote method calls have been made. The function is also typically called after `soap_serve`, when the service finished sending the response to a client and the deserialized client request data can be removed.

Individual data objects can be unlinked from the deallocation chain if necessary, to prevent deallocation by the collective `soap_end` or `soap_destroy` functions.

9.13.1 Memory Management Policies

There are three situations to consider for memory deallocation policies for class instances:

1. the program code deletes the class instances and the class destructors in turn **SHOULD** delete and free any dynamically allocated data (deep deallocation) without calling the `soap_end` and `soap_destroy` functions,
2. or the class destructors **SHOULD NOT** deallocate any data and the `soap_end` and `soap_destroy` functions can be called to remove the data.
3. or the class destructors **SHOULD** mark their own deallocation and mark the deallocation of any other data deallocated by it's destructors by calling the `soap_unlink` function. This allows `soap_destroy` and `soap_end` to remove the remaining instances and data without causing duplicate deallocations.

It is advised to use pointers to class instances that are used within other structs and classes to avoid the creation of temporary class instances during deserialization. The problem with temporary class

instances is that the destructor of the temporary may affect data used by other instances through the sharing of data parts accessed with pointers. Temporaries and even whole copies of class instances can be created when deserializing SOAP multi-referenced objects. A dynamic array of class instances is similar: temporaries may be created to fill the array upon deserialization. To avoid problems, use dynamic arrays of pointers to class instances. This also enables the exchange of polymorphic arrays when the elements are instances of classes in an inheritance hierarchy. In addition, allocate data and class instances with `soap_malloc` and `soap_new_X` functions (more details below).

To summarize, it is advised to pass class data types by pointer to a remote method. For example:

```
class X { ... };
ns_->_remoteMethod(X *in, ...);
```

Response elements that are class data types can be passed by reference, as in:

```
class X { ... };
class ns_->_remoteMethodResponse { ... };
ns_->_remoteMethod(X *in, ns_->_remoteMethodResponse &out);
```

But dynamic arrays declared as class data types should use a pointer to a valid object that will be overwritten when the function is called, as in:

```
typedef int xsd_->_int;
class X { ... };
class ArrayOfint { xsd_->_int *__ptr; int _size; };
ns_->_remoteMethod(X *in, ArrayOfint *out);
```

Or a reference to a valid or NULL pointer, as in:

```
typedef int xsd_->_int;
class X { ... };
class ArrayOfint { xsd_->_int *__ptr; int _size; };
ns_->_remoteMethod(X *in, ArrayOfint *&out);
```

The gSOAP memory allocation functions can be used in client and/or service code to allocate temporary data that will be automatically deallocated. These functions are:

Function Call	Description
void *soap_malloc(struct soap *soap, size_t n)	return pointer to n bytes
<u>Class</u> *soap_new_<u>Class(struct soap *soap, int n)	instantiate n <u>Class</u> objects

The `soap_new_X` functions are generated by the gSOAP compiler for every class X in the header file. Parameter n MUST be -1 to instantiate a single object, or larger or equal to 0 to instantiate an array of n objects.

Space allocated with `soap_malloc` will be released with the `soap_end` and `soap_dealloc` functions. Objects instantiated with `soap_new_X(struct soap*)` are removed altogether with `soap_destroy(struct soap*)`. Individual objects instantiated with `soap_new_X` are removed with `soap_delete_X(struct soap*, X*)`. For example, the following service uses temporary data in the remote method implementation:


```

int main()
{ ...
    struct soap soap;
    soap_init(&soap);
    soap_serve(&soap);
    soap_end(&soap);
    ...
}

```

An example remote method that allocates a temporary string is:

```

int ns_itoa(struct soap *soap, int i, char **a)
{
    *a = (char*)soap_malloc(soap, 11);
    sprintf(*a, "%d", i);
    return SOAP_OK;
}

```

This temporary allocation can also be used to allocate strings for the SOAP Fault data structure. For example:

```

int ns_...mymethod(...)
{ ...
    if (exception)
    {
        char *msg = (char*)soap_malloc(soap, 1024); // allocate temporary space for detailed message
        sprintf(msg, "...", ...); // produce the detailed message
        return soap_receiver_fault(soap, "An exception occurred", msg); // return the server-side fault
    }
    ...
}

```

Use `soap_receiver_fault(struct soap *soap, const char *faultstring, const char *detail)` to set a SOAP 1.1/1.2 fault at the server-side. Use `soap_sender_fault(struct soap *soap, const char *faultstring, const char *detail)` to set a SOAP 1.1/1.2 unrecoverable Bad Request fault at the server-side.

gSOAP provides a function to duplicate a string into gSOAP's memory space:

```

char *soap_strdup(struct soap *soap, const char *s)

```

The function allocates space for `s` with `soap_malloc`, copies the string, and returns a pointer to the duplicated string. When `s` is `NULL`, the function does not allocate and copy the string and returns `NULL`.

9.13.2 Intra-Class Memory Management

When a class declaration has a `struct soap *` field, this field will be set to point to the current gSOAP run-time environment by gSOAP's deserializers and by the `soap_new_Class` functions. This simplifies memory management for class instances. The `struct soap*` pointer is implicitly set by the gSOAP deserializer for the class or explicitly by calling the `soap_new_X` function for class `X`. For example:

```

class Sample
{ public:
    struct soap *soap; // reference to gSOAP's run-time
    ...
    Sample();
    ~Sample();
};

```

The constructor and destructor for class Sample are:

```

Sample::Sample()
{ this->soap = NULL;
}
Sample::~~Sample()
{ soap_unlink(this->soap, this);
}

```

The `soap_unlink()` call removes the object from gSOAP's deallocation chain. In that way, `soap_destroy` can be safely called to remove all class instances. The following code illustrates the explicit creation of a Sample object and cleanup:

```

struct soap *soap = soap_new(); // new gSOAP runtime
Sample *obj = soap_new_Sample(soap, -1); // new Sample object with obj->soap set to runtime
...
delete obj; // also calls soap_unlink to remove obj from the deallocation chain
soap_destroy(soap); // deallocate all (other) class instances
soap_end(soap); // clean up

```

Here is another example:

```

class ns_ _myClass
{ ...
    struct soap *soap; // set by soap_new_ns_ _myClass()
    char *name;
    void setName(const char *s);
    ...
};

```

Calls to `soap_new_ns_ _myClass(soap, n)` will set the `soap` field in the class instance to the current gSOAP environment. Because the deserializers invoke the `soap_new` functions, the `soap` field of the `ns_ _myClass` instances are set as well. This mechanism is convenient when Web Service methods need to return objects that are instantiated in the methods. For example

```

int ns_ _myMethod(struct soap *soap, ...)
{
    ns_ _myClass *p = soap_new_ns_ _myClass(soap, -1);
    p->setName("SOAP");
    return SOAP_OK;
}
void ns_ _myClass::ns_ _setName(const char *s)

```

```

{
    if (soap)
        name = (char*)soap_malloc(soap, strlen(s)+1);
    else
        name = (char*)malloc(strlen(s)+1);
    strcpy(name, s);
}
ns_myClass::ns_myClass()
{
    soap = NULL;
    name = NULL;
}
ns_myClass::~ns_myClass()
{
    if (!soap && name) free(name);
    soap_unlink(soap, this);
}

```

Calling `soap_destroy` right after `soap_serve` in the Web Service will destroy all dynamically allocated class instances.

9.14 Debugging

To activate message logging for debugging, un-comment the `#define DEBUG` directive in `stdsoap2.h`. Compile the client and/or server applications as described above (or simply use `g++ -DDEBUG ...` to compile with debugging activated). When the client and server applications run, they will log their activity in three separate files:

File	Description
SENT.log	The SOAP content transmitted by the application
RECV.log	The SOAP content received by the application
TEST.log	A log containing various activities performed by the application

Caution: The client and server applications may run slow due to the logging activity.

Caution: When installing a CGI application on the Web with debugging activated, the log files may sometimes not be created due to file access permission restrictions imposed on CGI applications. To get around this, create empty log files with universal write permissions. Be careful about the security implication of this.

You can test a service CGI application without deploying it on the Web. To do this, create a client application for the service and activate message logging by this client. Remove any old `SENT.log` file and run the client (which connects to the Web service or to another dummy, but valid address) and copy the `SENT.log` file to another file, e.g. `SENT.tst`. Then redirect the `SENT.tst` file to the service CGI application. For example,

```
myservice.cgi < SENT.tst
```

This should display the service response on the terminal.

The file names of the log files and the logging activity can be controlled at the application level. This allows the creation of separate log files by separate services, clients, and threads. For example, the following service logs all SOAP messages (but no debug messages) in separate directories:

```

struct soap soap;
soap_init(&soap);
...
soap_set_recv_logfile(&soap, "logs/recv/service12.log"); // append all messages received in /logs/recv/service12.log
soap_set_sent_logfile(&soap, "logs/sent/service12.log"); // append all messages sent in /logs/sent/service12.log
soap_set_test_logfile(&soap, NULL); // no file name: do not save debug messages
...
soap_serve(&soap);
...

```

Likewise, messages can be logged for individual client-side remote method calls.

9.15 Required Libraries

- The socket library is essential and requires the inclusion of the appropriate libraries with the compile command for Sun Solaris systems:

```
g++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lnet -lnsl
```

These library loading options are not required with Linux.

- The gSOAP runtime uses the math library for the NaN, INF, and -INF floating point representations. The library is not strictly necessary and the `<math.h>` header file import can be commented out from the `stdsoap2.h` header file. The application can be linked without the `-lm` math library e.g. under Sun Solaris:

```
g++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lnet -lnsl
```

10 The gSOAP Remote Method Specification Format

A SOAP remote method is specified as a C/C++ function prototype in a header file. The function is REQUIRED to return **int**, which is used to represent a SOAP error code, see Section 10.2. Multiple remote methods MAY be declared together in one header file.

The general form of a SOAP remote method specification is:

```
[int] [namespace_prefix_]method_name([inparam1, inparam2, ...,] outparam);
```

where

`namespace_prefix_` is the optional namespace prefix of the method (see identifier translation rules 10.3)

`method_name` is the remote method name (see identifier translation rules 10.3)

`inparam` is the declaration of an input parameter of the remote method

`outparam` is the declaration of the output parameter of the remote method

This simple form can only pass a single, non-**struct** and non-**class** type output parameter. See 10.1 for passing multiple output parameters. The name of the declared function `namespace_prefix_method_name` must be unique and cannot match the name of a **struct**, **class**, or **enum** declared in the same header file.

The method request is encoded in SOAP as an XML element and the namespace prefix, method name, and input parameters are encoded using the format:

```
<[namespace-prefix:]method_name xsi:type="[namespace-prefix:]method_name">
<inparam-name1 xsi:type="...">...</inparam-name1>
<inparam-name2 xsi:type="...">...</inparam-name2>
...
</[namespace-prefix:]method_name>
```

where the `inparam-name` accessors are the element-name representations of the `inparam` parameter name declarations, see Section 10.3. (The optional parts are shown enclosed in `[]`.)

The XML response by the Web service is of the form:

```
<[namespace-prefix:]method-nameResponse xsi:type="[namespace-prefix:]method-nameResponse">
<outparam-name xsi:type="...">...</outparam-name>
</[namespace-prefix:]method-nameResponse>
```

where the `outparam-name` accessor is the element-name representation of the `outparam` parameter name declaration, see Section 10.3. By convention, the response element name is the method name ending in `Response`. See 10.1 on how to change the declaration if the service response element name is different.

The gSOAP stub and skeleton compiler generates a stub routine for the remote method. This stub is of the form:

```
int soap_call_[namespace_prefix_]method_name(struct soap *soap, char *URL, char *action, [inparam1,
inparam2, ...,] outparam);
```

This proxy can be called by a client application to perform the remote method call.

The gSOAP stub and skeleton compiler generates a skeleton routine for the remote method. The skeleton function is:

```
int soap_serve_[namespace_prefix_]method_name(struct soap *soap);
```

The skeleton routine, when called by a service application, will attempt to serve a request on the standard input. If no request is present or if the request does not match the method name, `SOAP_NO_METHOD` is returned. The skeleton routines are automatically called by the generated `soap_serve` routine that handles all requests.

10.1 Remote Method Parameter Passing

The input parameters of a remote method **MUST** be passed by value. Input parameters cannot be passed by reference with the `&` reference operator, but an input parameter value **MAY** be passed by a pointer to the data. Of course, passing a pointer to the data is preferred when the size of the data of the parameter is large. Also, to pass instances of (derived) classes, pointers to the instance need to be used to avoid passing the instance by value which requires a temporary and prohibits passing derived class instances. When two input parameter values are identical, passing them using a pointer has the advantage that the value will be encoded only once as multi-reference (hence, the parameters are aliases). When input parameters are passed using a pointer, the data pointed to will not be modified by the remote method and returned to the caller.

The output parameter **MUST** be passed by reference using `&` or by using a pointer. Arrays are passed by reference by default and do not require the use of the reference operator `&`.

The input and output parameter types have certain limitations, see Section 9.10

If the output parameter is a **struct** or **class** type, it is considered a SOAP remote method response element instead of a simple output parameter value. That is, the name of the **struct** or **class** is the name of the response element and the **struct** or **class** fields are the output parameters of the remote method, see also 8.1.7. Hence, if the output parameter has to be a **struct** or **class**, a response **struct** or **class** **MUST** be declared as well. In addition, if a remote method returns multiple output parameters, a response **struct** or **class** **MUST** be declared. By convention, the response element is the remote method name ending with “Response”.

The general form of a response element declaration is:

```
struct [namespace_prefix_]response_element_name
{
    outparam1;
    outparam2;
    ...
};
```

where

`namespace_prefix_` is the optional namespace prefix of the response element (see identifier translation rules 10.3)

`response_element_name` is the name of the response element (see identifier translation rules 10.3)

`outparam` is the declaration of an output parameter of the remote method

The general form of a remote method specification with a response element declaration for (multiple) output parameters is:

```
[int] [namespace_prefix_]method_name([inparam1, inparam2, ...,] struct [namespace_prefix_]response_element_name
{outparam1[, outparam2, ...]} &anyparam);
```

The choice of name for `anyparam` has no effect on the SOAP encoding and decoding and is only used as a place holder for the response.

The method request is encoded in SOAP as an independent element and the namespace prefix, method name, and input parameters are encoded using the format:

```
<[namespace-prefix:]method-name xsi:type="[namespace-prefix:]method-name">
  <inparam-name1 xsi:type="...">...</inparam-name1>
  <inparam-name2 xsi:type="...">...</inparam-name2>
  ...
</[namespace-prefix:]method-name>
```

where the `inparam-name` accessors are the element-name representations of the `inparam` parameter name declarations, see Section 10.3. (The optional parts resulting from the specification are shown enclosed in `[]`.)

The method response is expected to be of the form:

```
<[namespace-prefix:]response-element-name xsi:type="[namespace-prefix:]response-element-name">
  <outparam-name1 xsi:type="...">...</outparam-name1>
  <outparam-name2 xsi:type="...">...</outparam-name2>
  ...
</[namespace-prefix:]response-element-name>
```

where the `outparam-name` accessors are the element-name representations of the `outparam` parameter name declarations, see Section 10.3. (The optional parts resulting from the specification are shown enclosed in `[]`.)

The input and/or output parameters can be made anonymous, which allows the deserialization of requests/responses with different parameter names as is endorsed by the SOAP 1.1 specification, see Section 8.1.13.

10.2 Error Codes

The error codes returned by the stub and skeleton routines are listed below.

Code	Description
SOAP_OK	No error
SOAP_CLI_FAULT*	The service returned a client fault (SOAP 1.2 Sender fault)
SOAP_SVR_FAULT*	The service returned a server fault (SOAP 1.2 Receiver fault)
SOAP_TAG_MISMATCH	An XML element didn't correspond to anything expected
SOAP_TYPE	An XML Schema type mismatch
SOAP_SYNTAX_ERROR	An XML syntax error occurred on the input
SOAP_NO_TAG	Begin of an element expected, but not found
SOAP_IOB	Array index out of bounds
SOAP_MUSTUNDERSTAND*	An element needs to be ignored that need to be understood
SOAP_NAMESPACE	Namespace name mismatch (validation error)
SOAP_OBJ_MISMATCH	Mismatch in the size and/or shape of an object
SOAP_FATAL_ERROR	Internal error
SOAP_FAULT	An exception raised by the service
SOAP_NO_METHOD	Skeleton error: the skeleton cannot serve the method
SOAP_GET_METHOD	Unsupported HTTP GET
SOAP_EOM	Out of memory
SOAP_NULL	An element was null, while it is not supposed to be null
SOAP_MULTI_ID	Multiple occurrences of the same element ID on the input
SOAP_MISSING_ID	Element ID missing for an HREF on the input
SOAP_HREF	Reference to object is incompatible with the object referred to
SOAP_UDP_ERROR	Message too large to store in UDP packet
SOAP_TCP_ERROR	A connection error occurred
SOAP_HTTP_ERROR	An HTTP error occurred
SOAP_SSL_ERROR	An SSL error occurred
SOAP_ZLIB_ERROR	A Zlib error occurred
SOAP_PLUGIN_ERROR	Failed to register plugin
SOAP_MIME_ERROR	MIME parsing error
SOAP_DIME_ERROR	DIME parsing error
SOAP_DIME_END	End of DIME error
SOAP_DIME_HREF	DIME attachment has no href from SOAP body (and no DIME callbacks were defined to save the attachment)
SOAP_DIME_MISMATCH	DIME version/transmission error
SOAP_VERSIONMISMATCH*	SOAP version mismatch or no SOAP message
SOAP_DATAENCODINGUNKNOWN	SOAP 1.2 DataEncodingUnknown fault
SOAP_REQUIRED	Attributed required validation error
SOAP_PROHIBITED	Attributed prohibited validation error
SOAP_OCCURS	Element minOccurs/maxOccurs validation error
SOAP_LENGTH	Element length validation error
SOAP_EOF	Unexpected end of file, no input, or timeout while receiving data

The error codes that are returned by a stub routine (proxy) upon receiving a SOAP Fault from the server are marked (*). The remaining error codes are generated by the proxy itself as a result of problems with a SOAP payload. The error code is `SOAP_OK` when the remote method call was successful (the `SOAP_OK` predefined constant is guaranteed to be 0). The error code is also stored in `soap.error`, where `soap` is a variable that contains the current runtime environment. The function `soap_print_fault(struct soap *soap, FILE *fd)` can be called to display an error message on `fd` where current value of the `soap.error` variable is used by the function to display the error. The function `soap_print_fault_location(struct soap *soap, FILE *fd)` prints the location of the error if the error is a result from parsing XML.

A remote method implemented in a SOAP service MUST return an error code as the function's return value. SOAP_OK denotes success and SOAP_FAULT denotes an exception. The exception details can be assigned with the soap_receiver_fault(**struct** soap *soap, **const char** *faultstring, **const char** *detail) which sets the strings soap.fault->faultstring and soap.fault->detail for SOAP 1.1, and soap.fault->SOAP_ENV__Reason and soap.fault->SOAP_ENV__Detail for SOAP 1.2, where soap is a variable that contains the current runtime environment, see Section 12. A receiver error indicates that the service can't handle the request, but can possibly recover from the error. To return an unrecoverable error, use soap_receiver_fault(**struct** soap *soap, **const char** *faultstring, **const char** *detail).

To return a HTTP error code a service method can simply return the HTTP error code number. For example, **return 404;** returns a "404 Not Found" HTTP error back to the client. The soap.error is set to the HTTP error code at the client side. The HTTP 1.1 error codes are:

#	Error
201	Created
202	Accepted
203	Non-Authoritative Information
204	No Content
205	Reset Content
206	Partial Content
300	Multiple Choices
301	Moved Permanently
302	Found
303	See Other
304	Not Modified
305	Use Proxy
307	Temporary Redirect
400	Bad Request
401	Unauthorized
402	Payment Required
403	Forbidden
404	Not Found
405	Method Not Allowed
406	Not Acceptable
407	Proxy Authentication Required
408	Request Time-out
409	Conflict
410	Gone
411	Length Required
412	Precondition Failed
413	Request Entity Too Large
414	Request-URI Too Large
415	Unsupported Media Type
416	Requested range not satisfiable
417	Expectation Failed
500	Internal Server Error
501	Not Implemented
502	Bad Gateway
503	Service Unavailable
504	Gateway Time-out
505	HTTP Version not supported

The error codes are given for informational purposes only. The HTTP protocol requires the proper actions after an error is issued. gSOAP's HTTP 1.0/1.1 handling is automatic.

10.3 C/C++ Identifier Name to XML Name Translations

One of the “secrets” behind the power and flexibility of gSOAP's encoding and decoding of remote method names, class names, type identifiers, and struct or class fields is the ability to specify namespace prefixes with these names that are used to denote their encoding style. More specifically, a C/C++ identifier name of the form

`[namespace_prefix_]element_name`

will be encoded in XML as

`<[namespace-prefix:]element-name ...>`

The **underscore pair** (..) separates the namespace prefix from the element name. Each namespace prefix has a namespace URI specified by a namespace mapping table 10.4, see also Section 8.1.2. The namespace URI is a unique identification that can be associated with the remote methods and data types. The namespace URI disambiguates potentially identical remote method names and data type names used by disparate organizations.

XML element names are NCNames (restricted strings) that MAY contain **hyphens**, **dots**, and **underscores**. The special characters in the XML element names of remote methods, structs, classes, typedefs, and fields can be controlled using the following conventions: A **single underscore** in a namespace prefix or identifier name is replaced by a hyphen (-) in the XML element name. For example, the identifier name SOAP_ENC..ur.type is represented in XML as SOAP-ENC:ur-type. The sequence DOT is replaced by a dot (.), and the sequence USCORE is replaced by an underscore (_) in the corresponding XML element name. For example:

```
class n_s_._biz_DOTcom
{
    char *n_s_._biz_USCOREname;
};
```

is encoded in XML as:

```
<n-s:biz.com xsi:type="n-s:biz.com">
  <n-s:biz.name xsi:type="string">Bizybiz</n-s:biz.name>
</n-s:biz.com>
```

Trailing underscores of an identifier name are not translated into the XML representation. This is useful when an identifier name clashes with a C++ keyword. For example, **return** is often used as an accessor name in a SOAP response element. The **return** element can be specified as **return_** in the C++ source code. Note that XML should be treated as case sensitive, so the use of e.g. **Return** may not always work to avoid a name clash with the **return** keyword. The use of trailing underscores also allows for defining **structs** and **classes** with essentially the same XML Schema type name, but that have to be distinguished as separate C/C++ types.

For decoding, the underscores in identifier names act as wildcards. An XML element is parsed and matches the name of an identifier if the name is identical to the element name (case insensitive) and the underscores in the identifier name are allowed to match any character in the element name. For example, the identifier name `I_want_soap_fun_the_bea_DOTcom` matches the element name `I-want:SOAP4fun@the-beach.com`.

10.4 Namespace Mapping Table

A namespace mapping table **MUST** be defined by clients and service applications. The mapping table is used by the serializers and deserializers of the stub and skeleton routines to produce a valid SOAP payload and to validate an incoming SOAP payload. A typical mapping table is shown below:

```
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name"}
  {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"}, // MUST be first
  {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"}, // MUST be second
  {"xsi", "http://www.w3.org/2001/XMLSchema-instance"}, // MUST be third
  {"xsd", "http://www.w3.org/2001/XMLSchema"}, // Required for XML Schema types
  {"ns1", "urn:my-service-URI"}, // The namespace URI of the remote methods
  {NULL, NULL} // end of table
};
```

Each namespace prefix used by a identifier name in the header file specification (see Section 10.3) **MUST** have a binding to a namespace URI in the mapping table. The end of the namespace mapping table **MUST** be indicated by the NULL pair. The namespace URI matching is case insensitive. A namespace prefix is distinguished by the occurrence of a pair of underscores (..) in an identifier.

An optional namespace pattern **MAY** be provided with each namespace mapping table entry. The patterns provide an alternative namespace matching for the validation of decoded SOAP messages. In this pattern, dashes (-) are single-character wildcards and asterisks (*) are multi-character wildcards. For example, to decode different versions of XML Schema type with different authoring dates, four dashes can be used in place of the specific dates in the namespace mapping table pattern:

```
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name", "ns-name validation pattern"}
  ...
  {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/----/XMLSchema-
instance"},
  {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/----/XMLSchema"},
  ...
};
```

Or alternatively, asterisks can be used as wildcards for multiple characters:

```
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name", "ns-name validation pattern"}
  ...
};
```

```

...
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance", "http://www.w3.org/*/XMLSchema-
instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"},
...

```

A namespace mapping table is automatically generated together with a WSDL file for each namespace prefix that is used for a remote method in the header file. This namespace mapping table has entries for all namespace prefixes. The namespace URIs need to be filled in. These appear as `http://tempuri.org` in the table. See Section 19.2 on how to specify the namespace URIs in the header file.

For decoding elements with namespace prefixes, the namespace URI associated with the namespace prefix (through the `xmlns` attribute of an XML element) is searched from the beginning to the end in a namespace mapping table, and for every row the following tests are performed as part of the validation process:

1. the string in the second column matches the namespace URI (case insensitive)
2. the string in the optional third column matches the namespace URI (case insensitive), where - is a one-character wildcard and * is a multi-character wildcard

When a match is found, the namespace prefix in the first column of the table is considered semantically identical to the namespace prefix used by the XML element to be decoded, though the prefix names may differ. A service will respond with the namespace that it received from a client in case it matches a pattern in the third column.

For example, let's say we have the following structs:

```

struct a_elt { ... };
struct b_elt { ... };
struct k_elt { ... };

```

and a namespace mapping table in the program:

```

struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name", "ns-name validation pattern"}
...
    {"a", "some uri"},
    {"b", "other uri"},
    {"c", "his uri", "* uri"},
...

```

Then, the following XML elements will match the structs:

```

<n:elt xmlns:n="some URI">      matches the struct name a_elt
...
<m:elt xmlns:m="other URI">    matches the struct name b_elt
...

```

```
<k:elt xmlns:k="my URI">      matches the struct name c__elt
...
```

The response of a service to a client request that uses the namespaces listed above, will include my URI for the name space of element k.

It is possible to use a number of different namespace tables and select the one that is appropriate. For example, an application might contact many different Web services all using different namespace URIs. If all the URIs are stored in one table, each remote method invocation will dump the whole namespace table in the SOAP payload. There is no technical problem with that, but it can be ugly when the table is large. To use different namespace tables, declare a pointer to a table and set the pointer to a particular table before remote method invocation. For example:

```
struct Namespace namespacesTable1[] = { ... };
struct Namespace namespacesTable2[] = { ... };
struct Namespace namespacesTable3[] = { ... };
struct Namespace *namespaces;
...
struct soap soap;
...
soap_init(&soap);
soap_set_namespaces(&soap, namespacesTable1);
soap_call_remote_method(&soap, URL, Action, ...);
...
```

11 gSOAP Serialization and Deserialization Rules

This section describes the serialization and deserialization of C and C++ data types for SOAP 1.1 and 1.2 compliant encoding and decoding.

11.1 Primitive Type Encoding

The default encoding rules for the primitive C and C++ data types are given in the table below:

Type	XSD Type
bool	boolean
char* (C string)	string
char	byte
double	double
float	float
int	int
long	long
LONG64	long
long long	long
short	short
time_t	dateTime
unsigned char	unsignedByte
unsigned int	unsignedInt
unsigned long	unsignedLong
ULONG64	unsignedLong
unsigned long long	unsignedLong
unsigned short	unsignedShort
wchar_t*	string

Objects of type **void** and **void*** cannot be encoded. Enumerations and bit masks are supported as well, see 11.3.

11.2 How to Encode and Decode Primitive Types as XSD Types

By default, encoding of the primitive types will take place as per SOAP encoding style. The encoding can be changed to any XML Schema type (XSD type) with an optional namespace prefix by using a **typedef** in the header file input to the gSOAP stub and skeleton compiler. The declaration enables the implementation of built-in XML Schema types (also known as XSD types) such as `positiveInteger`, `xsd:anyURI`, and `xsd:date` for which no built-in data structures in C and C++ exist but which can be represented using standard data structures such as strings, integers, and floats.

The **typedef** declaration is frequently used for convenience in C. A **typedef** declares a type name for a (complex) type expression. The type name can then be used in other declarations in place of the more complex type expression, which often improves the readability of the program code.

The gSOAP compiler interprets **typedef** declarations the same way as a regular C compiler interprets them, i.e. as types in declarations. In addition however, the gSOAP compiler will also use the type name in the encoding of the data in SOAP. The **typedef** name will appear as the XML element name of an independent element and as the value of the `xsi:type` attribute in the SOAP payload.

Many built-in primitive and derived XSD types such as `xsd:anyURI`, `positiveInteger`, and `decimal` can be stored by standard primitive data structures in C++ as well such as strings, integers, floats, and doubles. To serialize strings, integers, floats, and doubles as built-in primitive and derived XSD types. To this end, a **typedef** declaration can be used to declare an XSD type.

For example, the declaration

```
typedef unsigned int xsd__positiveInteger;
```

creates a named type `positiveInteger` which is represented by **unsigned int** in C++. For example, the encoding of a `positiveInteger` value 3 is

```
<positiveInteger xsi:type="xsd:positiveInteger">3</positiveInteger>
```

The built-in primitive and derived numerical XML Schema types are listed below together with their recommended **typedef** declarations. Note that the SOAP encoding schemas for primitive types are derived from the built-in XML Schema types, so `SOAP_ENC_...` can be used as a namespace prefix instead of `xsd_...`.

xsd:anyURI Represents a Uniform Resource Identifier Reference (URI). Each URI scheme imposes specialized syntax rules for URIs in that scheme, including restrictions on the syntax of allowed fragment identifiers. It is recommended to use strings to store `xsd:anyURI` XML Schema types. The recommended type declaration is:

```
typedef char *xsd__anyURI;
```

xsd:base64Binary Represents Base64-encoded arbitrary binary data. For using the `xsd:base64Binary` XSD Schema type, the use of the `base64Binary` representation of a dynamic array is **strongly** recommended, see Section 11.11. However, the type can also be declared as a string and the encoding will be string-based:

```
typedef char *xsd__base64Binary;
```

With this approach, it is solely the responsibility of the application to make sure the string content is according to the Base64 Content-Transfer-Encoding defined in Section 6.8 of RFC 2045.

xsd:boolean For declaring an `xsd:boolean` XSD Schema type, the use of a `bool` is **strongly** recommended. If a pure C compiler is used that does not support the `bool` type, see Section 11.3.5. The corresponding type declaration is:

```
typedef bool xsd__boolean;
```

Type `xsd__boolean` declares a Boolean (0 or 1), which is encoded as

```
<xsd:boolean xsi:type="xsd:boolean">...</xsd:boolean>
```

xsd:byte Represents a byte (-128...127). The corresponding type declaration is:

```
typedef char xsd__byte;
```

Type `xsd__byte` declares a byte which is encoded as

```
<xsd:byte xsi:type="xsd:byte">...</xsd:byte>
```

xsd:dateTime Represents a date and time. The lexical representation is according to the ISO 8601 extended format `CCYY-MM-DDThh:mm:ss` where "CC" represents the century, "YY" the year, "MM" the month and "DD" the day, preceded by an optional leading "-" sign to indicate a negative number. If the sign is omitted, "+" is assumed. The letter "T" is the date/time separator and "hh", "mm", "ss" represent hour, minute and second respectively. It is recommended to use the `time_t` type to store `xsd:dateTime` XSD Schema types and the type declaration is:

```
typedef time_t xsd__dateTime;
```

However, note that calendar times before the year 1902 or after the year 2037 cannot be represented. Upon receiving a date outside this range, the `time_t` value will be set to -1.

Strings (**char***) can be used to store `xsd:dateTime` XSD Schema types. The type declaration is:

```
typedef char *xsd__dateTime;
```

In this case, it is up to the application to read and set the `dateTime` representation.

`xsd:date` Represents a date. The lexical representation for date is the reduced (right truncated) lexical representation for `dateTime`: CCYY-MM-DD. It is recommended to use strings (**char***) to store `xsd:date` XSD Schema types. The type declaration is:

```
typedef char *xsd__date;
```

`xsd:decimal` Represents arbitrary precision decimal numbers. It is recommended to use the **double** type to store `xsd:decimal` XSD Schema types and the type declaration is:

```
typedef double xsd__decimal;
```

Type `xsd__decimal` declares a double floating point number which is encoded as

```
<xsd:double xsi:type="xsd:decimal">...</xsd:double>
```

`xsd:double` Corresponds to the IEEE double-precision 64-bit floating point type. The type declaration is:

```
typedef double xsd__double;
```

Type `xsd__double` declares a double floating point number which is encoded as

```
<xsd:double xsi:type="xsd:double">...</xsd:double>
```

`xsd:duration` Represents a duration of time. The lexical representation for duration is the ISO 8601 extended format `PnYn MnDTnH nMnS`, where `nY` represents the number of years, `nM` the number of months, `nD` the number of days, `T` is the date/time separator, `nH` the number of hours, `nM` the number of minutes and `nS` the number of seconds. The number of seconds can include decimal digits to arbitrary precision. It is recommended to use strings (**char***) to store `xsd:duration` XSD Schema types. The type declaration is:

```
typedef char *xsd__duration;
```

`xsd:float` Corresponds to the IEEE single-precision 32-bit floating point type. The type declaration is:

```
typedef float xsd__float;
```

Type `xsd__float` declares a floating point number which is encoded as

```
<xsd:float xsi:type="xsd:float">...</xsd:float>
```


xsd:hexBinary Represents arbitrary hex-encoded binary data. It has a lexical representation where each binary octet is encoded as a character tuple, consisting of two hexadecimal digits ([0-9a-fA-F]) representing the octet code. For example, "0FB7" is a hex encoding for the 16-bit integer 4023 (whose binary representation is 111110110111. For using the **xsd:hexBinary** XSD Schema type, the use of the hexBinary representation of a dynamic array is **strongly** recommended, see Section 11.12. However, the type can also be declared as a string and the encoding will be string-based:

```
typedef char *xsd_hexBinary;
```

With this approach, it is solely the responsibility of the application to make sure the string content consists of a sequence of octets.

xsd:int Corresponds to a 32-bit integer in the range -2147483648 to 2147483647. If the C++ compiler supports 32-bit **int** types, the type declaration can use the **int** type:

```
typedef int xsd_int;
```

Otherwise, the C++ compiler supports 16-bit **int** types and the type declaration should use the **long** type:

```
typedef long xsd_int;
```

Type **xsd_int** declares a 32-bit integer which is encoded as

```
<xsd:int xsi:type="xsd:int">...</xsd:int>
```

xsd:integer Corresponds to an unbounded integer. Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

```
typedef long long xsd_integer;
```

Type **xsd_integer** declares a 64-bit integer which is encoded as an unbounded **xsd:integer**:

```
<xsd:integer xsi:type="xsd:integer">...</xsd:integer>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:long Corresponds to a 64-bit integer in the range -9223372036854775808 to 9223372036854775807. The type declaration is:

```
typedef long long xsd_long;
```

Or in Visual C++:

```
typedef LONG64 xsd_long;
```

Type **xsd_long** declares a 64-bit integer which is encoded as

```
<xsd:long xsi:type="xsd:long">...</xsd:long>
```

xsd:negativeInteger Corresponds to a negative unbounded integer (< 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef long long xsd__negativeInteger;

Type xsd__negativeInteger declares a 64-bit integer which is encoded as a xsd:negativeInteger:

```
<xsd:negativeInteger xsi:type="xsd:negativeInteger">...</xsd:negativeInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:nonNegativeInteger Corresponds to a non-negative unbounded integer (> 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef unsigned long long xsd__nonNegativeInteger;

Type xsd__nonNegativeInteger declares a 64-bit unsigned integer which is encoded as a non-negative unbounded xsd:nonNegativeInteger:

```
<xsd:nonNegativeInteger xsi:type="xsd:nonNegativeInteger">...</xsd:nonNegativeInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:nonPositiveInteger Corresponds to a non-positive unbounded integer (≤ 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef long long xsd__nonPositiveInteger;

Type xsd__nonPositiveInteger declares a 64-bit integer which is encoded as a xsd:nonPositiveInteger:

```
<xsd:nonPositiveInteger xsi:type="xsd:nonPositiveInteger">...</xsd:nonPositiveInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:normalizedString Represents normalized character strings. Normalized character strings do not contain the carriage return (#xD), line feed (#xA) nor tab (#x9) characters. It is recommended to use strings to store xsd:normalizeString XSD Schema types. The type declaration is:

typedef char *xsd__normalizedString;

Type xsd__normalizedString declares a string type which is encoded as

```
<xsd:normalizedString xsi:type="xsd:normalizedString">...</xsd:normalizedString>
```

It is solely the responsibility of the application to make sure the strings do not contain carriage return (#xD), line feed (#xA) and tab (#x9) characters.

xsd:positiveInteger Corresponds to a positive unbounded integer (≥ 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef unsigned long long xsd__positiveInteger;

Type xsd__positiveInteger declares a 64-bit unsigned integer which is encoded as a xsd:positiveInteger:

```
<xsd:positiveInteger xsi:type="xsd:positiveInteger">...</xsd:positiveInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:short Corresponds to a 16-bit integer in the range -32768 to 32767. The type declaration is:

```
typedef short xsd__short;
```

Type `xsd__short` declares a short 16-bit integer which is encoded as

```
<xsd:short xsi:type="xsd:short">...</xsd:short>
```

xsd:string Represents character strings. The type declaration is:

```
typedef char *xsd__string;
```

Type `xsd__string` declares a string type which is encoded as

```
<xsd:string xsi:type="xsd:string">...</xsd:string>
```

The type declaration for wide character strings is:

```
typedef wchar_t *xsd__string_;
```

Both type of strings can be used at the same time, but requires one typedef name to be changed by appending an underscore which is invisible in XML. For example:

```
typedef wchar_t *xsd__string_;
```

xsd:time Represents a time. The lexical representation for time is the left truncated lexical representation for `dateTime`: `hh:mm:ss.sss` with optional following time zone indicator. It is recommended to use strings (**char***) to store `xsd:time` XSD Schema types. The type declaration is:

```
typedef char *xsd__time;
```

xsd:token Represents tokenized strings. Tokens are strings that do not contain the line feed (`#xA`) nor tab (`#x9`) characters, that have no leading or trailing spaces (`#x20`) and that have no internal sequences of two or more spaces. It is recommended to use strings to store `xsd:token` XSD Schema types. The type declaration is:

```
typedef char *xsd__token;
```

Type `xsd__token` declares a string type which is encoded as

```
<xsd:token xsi:type="xsd:token">...</xsd:token>
```

It is solely the responsibility of the application to make sure the strings do not contain the line feed (`#xA`) nor tab (`#x9`) characters, that have no leading or trailing spaces (`#x20`) and that have no internal sequences of two or more spaces.

xsd:unsignedByte Corresponds to an 8-bit unsigned integer in the range 0 to 255. The type declaration is:

```
typedef unsigned char xsd_unsignedByte;
```

Type `xsd_unsignedByte` declares a unsigned 8-bit integer which is encoded as

```
<xsd:unsignedByte xsi:type="xsd:unsignedByte">...</xsd:unsignedByte>
```

`xsd:unsignedInt` Corresponds to a 32-bit unsigned integer in the range 0 to 4294967295. If the C++ compiler supports 32-bit **int** types, the type declaration can use the **int** type:

```
typedef unsigned int xsd_unsignedInt;
```

Otherwise, the C++ compiler supports 16-bit **int** types and the type declaration should use the **long** type:

```
typedef unsigned long xsd_unsignedInt;
```

Type `xsd_unsignedInt` declares an unsigned 32-bit integer which is encoded as

```
<xsd:unsignedInt xsi:type="xsd:unsignedInt">...</xsd:unsignedInt>
```

`xsd:unsignedLong` Corresponds to a 64-bit unsigned integer in the range 0 to 18446744073709551615. The type declaration is:

```
typedef unsigned long long xsd_unsignedLong;
```

Or in Visual C++:

```
typedef ULONG64 xsd_unsignedLong;
```

Type `xsd_unsignedLong` declares an unsigned 64-bit integer which is encoded as

```
<xsd:unsignedLong xsi:type="xsd:unsignedLong">...</xsd:unsignedLong>
```

`xsd:unsignedShort` Corresponds to a 16-bit unsigned integer in the range 0 to 65535. The type declaration is:

```
typedef unsigned short xsd_unsignedShort;
```

Type `xsd_unsignedShort` declares an unsigned short 16-bit integer which is encoded as

```
<xsd:unsignedShort xsi:type="xsd:unsignedShort">...</xsd:unsignedShort>
```

Other XSD Schema types such as `gYearMonth`, `gYear`, `gMonthDay`, `gDay`, `xsd:gMonth`, `QName`, `NOTATION`, etc., can be encoded similarly using a **typedef** declaration.

11.2.1 How to Use Multiple C/C++ Types for a Single Primitive XSD Type

Trailing underscores (see Section 10.3) can be used in the type name in a **typedef** to enable the declaration of multiple storage formats for a single XML Schema type. For example, one part of a C/C++ application's data structure may use plain strings while another part may use wide character strings. To enable this simultaneous use, declare:

```
typedef char *xsd_string;
typedef wchar_t *xsd_string_;
```

Now, the `xsd_string` and `xsd_string_` types will both be encoded and decoded as XML string types and the use of trailing underscores allows multiple declarations for a single XML Schema type.

11.2.2 How to use Wrapper Classes to Specify Polymorphic Primitive Types

SOAP 1.1 supports polymorphic types, because XSD Schema types form a hierarchy. The root of the hierarchy is called `xsd:anyType` (`xsd:ur-type` in the older 1999 schema). So, for example, an array of `xsd:anyType` in SOAP may actually contain any mix of element types that are the derived types of the root type. The use of polymorphic types is indicated by the WSDL and schema descriptions of a Web service and can therefore be predicted/expected for each particular case.

On the one hand, the **typedef** construct provides a convenient way to associate C/C++ types with XML Schema types and makes it easy to incorporate these types in a (legacy) C/C++ application. However, on the other hand the **typedef** declarations cannot be used to support polymorphic XML Schema types. Most SOAP clients and services do not use polymorphic types. In case they do, the primitive polymorphic types can be declared as a hierarchy of C++ **classes** that can be used simultaneously with the **typedef** declarations.

The general form of a primitive type declaration that is derived from a super type is:

```
class xsd_type_name: [public xsd_super_type_name]
{ public: Type _item;
  [public:] [private] [protected:]
  method1;
  method2;
  ...
};
```

where `Type` is a primitive C type. The `_item` field **MUST** be the first field in this wrapper class.

For example, the XML Schema type hierarchy can be copied to C++ with the following declarations:

```
class xsd_anyType { };
class xsd_anySimpleType: public xsd_anyType { };
typedef char *xsd_anyURI;
class xsd_anyURI_: public xsd_anySimpleType { public: xsd_anyURI _item; };
typedef bool xsd_boolean;
class xsd_boolean_: public xsd_anySimpleType { public: xsd_boolean _item; };
typedef char *xsd_date;
class xsd_date_: public xsd_anySimpleType { public: xsd_date _item; };
typedef time_t xsd_dateTime;
class xsd_dateTime_: public xsd_anySimpleType { public: xsd_dateTime _item; };
typedef double xsd_double;
class xsd_double_: public xsd_anySimpleType { public: xsd_double _item; };
typedef char *xsd_duration;
class xsd_duration_: public xsd_anySimpleType { public: xsd_duration _item; };
typedef float xsd_float;
```

```

class xsd__float_: public xsd__anySimpleType { public: xsd__float __item; };
typedef char *xsd__time;
class xsd__time_: public xsd__anySimpleType { public: xsd__time __item; };
typedef char *xsd__decimal;
class xsd__decimal_: public xsd__anySimpleType { public: xsd__decimal __item; };
typedef char *xsd__integer;
class xsd__integer_: public xsd__decimal_ { public: xsd__integer __item; };
typedef LONG64 xsd__long;
class xsd__long_: public xsd__integer_ { public: xsd__long __item; };
typedef long xsd__int;
class xsd__int_: public xsd__long_ { public: xsd__int __item; };
typedef short xsd__short;
class xsd__short_: public xsd__int_ { public: xsd__short __item; };
typedef char xsd__byte;
class xsd__byte_: public xsd__short_ { public: xsd__byte __item; };
typedef char *xsd__nonPositiveInteger;
class xsd__nonPositiveInteger_: public xsd__integer_ { public: xsd__nonPositiveInteger __item; };
typedef char *xsd__negativeInteger;
class xsd__negativeInteger_: public xsd__nonPositiveInteger_ { public: xsd__negativeInteger __item; };
};
typedef char *xsd__nonNegativeInteger;
class xsd__nonNegativeInteger_: public xsd__integer_ { public: xsd__nonNegativeInteger __item; };
typedef char *xsd__positiveInteger;
class xsd__positiveInteger_: public xsd__nonNegativeInteger_ { public: xsd__positiveInteger __item; };
};
typedef ULONG64 xsd__unsignedLong;
class xsd__unsignedLong_: public xsd__nonNegativeInteger_ { public: xsd__unsignedLong __item; };
};
typedef unsigned long xsd__unsignedInt;
class xsd__unsignedInt_: public xsd__unsignedLong_ { public: xsd__unsignedInt __item; };
typedef unsigned short xsd__unsignedShort;
class xsd__unsignedShort_: public xsd__unsignedInt_ { public: xsd__unsignedShort __item; };
typedef unsigned char xsd__unsignedByte;
class xsd__unsignedByte_: public xsd__unsignedShort_ { public: xsd__unsignedByte __item; };
typedef char *xsd__string;
class xsd__string_: public xsd__anySimpleType { public: xsd__string __item; };
typedef char *xsd__normalizedString;
class xsd__normalizedString_: public xsd__string_ { public: xsd__normalizedString __item; };
typedef char *xsd__token;
class xsd__token_: public xsd__normalizedString_ { public: xsd__token __item; };

```

Note the use of the trailing underscores for the **class** names to distinguish the **typedef** type names from the **class** names. Only the most frequently used built-in schema types are shown. It is also allowed to include the `xsd:base64Binary` and `xsd:hexBinary` types in the hierarchy:

```

class xsd__base64Binary: public xsd__anySimpleType { public: unsigned char *_ptr; int __size; };
class xsd__hexBinary: public xsd__anySimpleType { public: unsigned char *_ptr; int __size; };

```

See Sections 11.11 and 11.12.

Methods are allowed to be added to the classes above, such as constructors and getter/setter methods, see Section 11.5.4.

Wrapper structs are supported as well, similar to wrapper classes. But they cannot be used to implement polymorphism. Rather, the wrapper structs facilitate the use of XML attributes with a primitive typed object, see 11.5.7.

11.2.3 XSD Schema Type Decoding Rules

The decoding rules for the primitive C and C++ data types is given in the table below:

Type	Allows Decoding of	Precision Lost?
bool	[xsd:] boolean	no
char* (C string)	any type, see 11.2.5	no
wchar_t * (wide string)	any type, see 11.2.5	no
double	[xsd:] double	no
	[xsd:] float	no
	[xsd:] long	no
	[xsd:] int	no
	[xsd:] short	no
	[xsd:] byte	no
	[xsd:] unsignedLong	no
	[xsd:] unsignedInt	no
	[xsd:] unsignedShort	no
	[xsd:] unsignedByte	no
	[xsd:] decimal	possibly
	[xsd:] integer	possibly
	[xsd:] positiveInteger	possibly
	[xsd:] negativeInteger	possibly
	[xsd:] nonPositiveInteger	possibly
	[xsd:] nonNegativeInteger	possibly
float	[xsd:] float	no
	[xsd:] long	no
	[xsd:] int	no
	[xsd:] short	no
	[xsd:] byte	no
	[xsd:] unsignedLong	no
	[xsd:] unsignedInt	no
	[xsd:] unsignedShort	no
	[xsd:] unsignedByte	no
	[xsd:] decimal	possibly
	[xsd:] integer	possibly
	[xsd:] positiveInteger	possibly
	[xsd:] negativeInteger	possibly
	[xsd:] nonPositiveInteger	possibly
	[xsd:] nonNegativeInteger	possibly
long long	[xsd:] long	no
	[xsd:] int	no
	[xsd:] short	no
	[xsd:] byte	no
	[xsd:] unsignedLong	possibly
	[xsd:] unsignedInt	no
	[xsd:] unsignedShort	no
	[xsd:] unsignedByte	no
	[xsd:] integer	possibly
	[xsd:] positiveInteger	possibly
	[xsd:] negativeInteger	possibly
	[xsd:] nonPositiveInteger	possibly
	[xsd:] nonNegativeInteger	possibly

Type	Allows Decoding of	Precision Lost?
long	<div>[xsd:]long</div> <div>[xsd:]int</div> <div>[xsd:]short</div> <div>[xsd:]byte</div> <div>[xsd:]unsignedLong</div> <div>[xsd:]unsignedInt</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>possibly, if long is 32 bit</div> <div>no</div> <div>no</div> <div>no</div> <div>possibly</div> <div>no</div> <div>no</div> <div>no</div>
int	<div>[xsd:]int</div> <div>[xsd:]short</div> <div>[xsd:]byte</div> <div>[xsd:]unsignedInt</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>no</div> <div>no</div> <div>no</div> <div>possibly</div> <div>no</div> <div>no</div>
short	<div>[xsd:]short</div> <div>[xsd:]byte</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>no</div> <div>no</div> <div>no</div> <div>no</div>
char	<div>[xsd:]byte</div> <div>[xsd:]unsignedByte</div>	<div>no</div> <div>possibly</div>
unsigned long long	<div>[xsd:]unsignedLong</div> <div>[xsd:]unsignedInt</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div> <div>[xsd:]positiveInteger</div> <div>[xsd:]nonNegativeInteger</div>	<div>no</div> <div>no</div> <div>no</div> <div>no</div> <div>possibly</div> <div>possibly</div>
unsigned long	<div>[xsd:]unsignedLong</div> <div>[xsd:]unsignedInt</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>possibly, if long is 32 bit</div> <div>no</div> <div>no</div> <div>no</div>
unsigned int	<div>[xsd:]unsignedInt</div> <div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>no</div> <div>no</div> <div>no</div>
unsigned short	<div>[xsd:]unsignedShort</div> <div>[xsd:]unsignedByte</div>	<div>no</div> <div>no</div>
unsigned char	<div>[xsd:]unsignedByte</div>	<div>no</div>
time_t	<div>[xsd:]dateTime</div>	<div>no(?)</div>

Due to limitations in representation of certain primitive C++ types, a possible loss of accuracy may occur with the decoding of certain XSD Schema types as is indicated in the table. The table does not indicate the possible loss of precision of floating point values due to the textual representation of floating point values in SOAP.

All explicitly declared XSD Schema encoded primitive types adhere to the same decoding rules. For example, the following declaration:

```
typedef unsigned long long xsd_nonNegativeInteger;
```

enables the encoding and decoding of `xsd:nonNegativeInteger` XSD Schema types (although decoding takes place with a possible loss of precision). The declaration also allows decoding of `xsd:positiveInteger` XSD Schema types, because of the storage as a **unsigned long long** data type.

11.2.4 Multi-Reference Strings

If more than one **char** pointer points to the same string, the string is encoded as a multi-reference value. Consider for example

```
char *s = "hello", *t = s;
```

The `s` and `t` variables are assigned the same string, and when serialized, `t` refers to the content of `s`:

```
<string id="123" xsi:type="string">hello</string>
...
<string href="#123"/>
```

The example assumed that `s` and `t` are encoded as independent elements.

Note: the use of **typedef** to declare a string type such as `xsd_string` will not affect the multi-reference string encoding. However, strings declared with different **typedefs** will never be considered multi-reference even when they point to the same string. For example

```
typedef char *xsd_string;
typedef char *xsd_anyURI;
xsd_anyURI *s = "http://www.myservice.com";
xsd_string *t = s;
```

The variables `s` and `t` point to the same string, but since they are considered different types their content will not be shared in the SOAP payload through a multi-referenced string.

11.2.5 “Smart String” Mixed-Content Decoding

The implementation of string decoding in gSOAP allows for mixed content decoding. If the SOAP payload contains a complex data type in place of a string, the complex data type is decoded in the string as plain XML text.

For example, suppose the `getInfo` remote method returns some detailed information. The remote method is declared as:

```
// Contents of header file "getInfo.h":
getInfo(char *detail);
```

The proxy of the remote method is used by a client to request a piece of information and the service responds with:

```
HTTP/1.1 200 OK
Content-Type: text/xml
Content-Length: nnn

<SOAP-ENV:Envelope xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  >
  <SOAP-ENV:Body>
    <getInfoResponse>
      <detail>
        <picture>Mona Lisa by <i>Leonardo da Vinci</i></picture>
      </detail>
    </getInfoResponse>
  </SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```

As a result of the mixed content decoding, the detail string contains “<picture>Mona Lisa by <i>Leonardo da Vinci</i></picture>”.

11.2.6 STL Strings

gSOAP supports STL strings `std::string` and `std::wstring`. For example:

```
typedef std::string xsd_string;
class ns_myClass
{ public:
  xsd_string s; // serialized with xsi:type="xsd:string"
  std::string t; // serialized without xsi:type
  ...
};
```

Caution: Please avoid mixing `std::string` and C strings (`char*`) in the header file when using SOAP 1.1 encoding. The problem is that multi-referenced strings in SOAP encoded messages cannot be assigned simultaneously to a `std::string` and a `char*` string.

11.2.7 Changing the Encoding Precision of float and double Types

The double encoding format is by default set to “%.18G” (see a manual on `printf` text formatting in C), i.e. at most 18 digits of precision to limit a loss in accuracy. The float encoding format is by default “%.9G”, i.e. at most 9 digits of precision.

The encoding format of a double type can be set by assigning a format string to `soap.double_format`, where `soap` is a variable that contains the current runtime environment. For example:

```

struct soap soap;
soap_init(&soap); // sets double_format = "%.18G"
soap.double_format = "%e"; // redefine

```

which causes all doubles to be encoded in scientific notation. Likewise, the encoding format of a float type can be set by assigning a format string to the static `soap.float_format` string variable. For example:

```

struct soap soap;
soap_init(&soap); // sets float_format = "%.9G"
soap.float_format = "%.4f"; // redefine

```

which causes all floats to be encoded with four digits precision.

Caution: The format strings are not automatically reset before or after SOAP communications. An error in the format string may result in the incorrect encoding of floating point values.

11.2.8 INF, -INF, and NaN Values of float and double Types

The gSOAP runtime `stdsoap2.cpp` and header file `stdsoap2.h` support the marshalling of IEEE INF, -INF, and NaN representations. Under certain circumstances this may break if the hardware and/or C/C++ compiler does not support these representations. To remove the representations, remove the inclusion of the `<math.h>` header file from the `stdsoap2.h` file. You can control the representations as well, which are defined by the macros:

```

#define FLT_NAN
#define FLT_PINFTY
#define FLT_NINFTY
#define DBL_NAN
#define DBL_PINFTY
#define DBL_NINFTY

```

11.3 Enumeration Serialization

Enumerations are generally useful for the declaration of named integer-valued constants, also called enumeration constants.

11.3.1 Serialization of Symbolic Enumeration Constants

The gSOAP stub and skeleton compiler encodes the constants of enumeration-typed variables in symbolic form using the names of the constants when possible to comply to SOAP's enumeration encoding style. Consider for example the following enumeration of weekdays:

```

enum weekday {Mon, Tue, Wed, Thu, Fri, Sat, Sun};

```

The enumeration-constant `Mon`, for example, is encoded as

```
<weekday xsi:type="weekday">Mon</weekday>
```

The value of the `xsi:type` attribute is the enumeration-type identifier's name. If the element is independent as in the example above, the element name is the enumeration-type identifier's name.

The encoding of complex types such as enumerations requires a reference to an XML Schema through the use of a namespace prefix. The namespace prefix can be specified as part of the enumeration-type identifier's name, with the usual namespace prefix conventions for identifiers. This can be used to explicitly specify the encoding style. For example:

```
enum ns1:_weekday {Mon, Tue, Wed, Thu, Fri, Sat, Sun};
```

The enumeration-constant `Sat`, for example, is encoded as:

```
<ns1:weekday xsi:type="ns1:weekday">Sat</ns1:weekday>
```

The corresponding XML Schema for this enumeration data type would be:

```
<xsd:element name="weekday" type="tns:weekday"/>
<xsd:simpleType name="weekday">
  <xsd:restriction base="xsd:string">
    <xsd:enumeration value="Mon"/>
    <xsd:enumeration value="Tue"/>
    <xsd:enumeration value="Wed"/>
    <xsd:enumeration value="Thu"/>
    <xsd:enumeration value="Fri"/>
    <xsd:enumeration value="Sat"/>
    <xsd:enumeration value="Sun"/>
  </xsd:restriction>
</xsd:simpleType>
```

11.3.2 Encoding of Enumeration Constants

If the value of an enumeration-typed variable has no corresponding named constant, the value is encoded as a signed integer literal. For example, the following declaration of a `workday` enumeration type lacks named constants for Saturday and Sunday:

```
enum ns1:_workday {Mon, Tue, Wed, Thu, Fri};
```

If the constant 5 (Saturday) or 6 (Sunday) is assigned to a variable of the `workday` enumeration type, the variable will be encoded with the integer literals 5 and 6, respectively. For example:

```
<ns1:workday xsi:type="ns1:workday">5</ns1:workday>
```

Since this is legal in C++ and SOAP allows enumeration constants to be integer literals, this method ensures that non-symbolic enumeration constants are correctly communicated to another party if the other party accepts literal enumeration constants (as with the gSOAP stub and skeleton compiler).

Both symbolic and literal enumeration constants can be decoded.

To enforce the literal enumeration constant encoding and to get the literal constants in the WSDL file, use the following trick:

```
enum ns1_._nums { _1 = 1, _2 = 2, _3 = 3 };
```

The difference with an enumeration type without a list of values and the enumeration type above is that the enumeration constants will appear in the WSDL service description.

11.3.3 Initialized Enumeration Constants

The gSOAP compiler supports the initialization of enumeration constants, as in:

```
enum ns1_._relation { LESS = -1, EQUAL = 0, GREATER = 1};
```

The symbolic names LESS, EQUAL, and GREATER will appear in the SOAP payload for the encoding of the ns1_._relation enumeration values -1, 0, and 1, respectively.

11.3.4 How to “Reuse” Symbolic Enumeration Constants

A well-known deficiency of C and C++ enumeration types is the lack of support for the reuse of symbolic names by multiple enumerations. That is, the names of all the symbolic constants defined by an enumeration cannot be reused by another enumeration. To force encoding of the same symbolic name by different enumerations, the identifier of the symbolic name can end in an underscore (_) or any number of underscores to distinguish it from other symbolic names in C++. This guarantees that the SOAP encoding will use the same name, while the symbolic names can be distinguished in C++. Effectively, the underscores are removed from a symbolic name prior to encoding.

Consider for example:

```
enum ns1_._workday {Mon, Tue, Wed, Thu, Fri};  
enum ns1_._weekday {Mon_, Tue_, Wed_, Thu_, Fri_, Sat_, Sun_};
```

which will result in the encoding of the constants of enum ns1_._weekday without the underscore, for example as Mon.

Caution: The following declaration:

```
enum ns1_._workday {Mon, Tue, Wed, Thu, Fri};  
enum ns1_._weekday {Sat = 5, Sun = 6};
```

will not properly encode the weekday enumeration, because it lacks the named constants for workday in its enumeration list.

11.3.5 Boolean Enumeration Serialization for C

When developing a C Web service application, the C++ `bool` type should not be used since it is not usually supported by the C compiler. Instead, an enumeration type should be used to serialize true/false values as `xsd:boolean` Schema type enumeration values. The `xsd:boolean` XML Schema type is defined as:

```
enum xsd__boolean {false_, true_};
```

The value `false_`, for example, is encoded as:

```
<xsd:boolean xsi:type="xsd:boolean">false</xsd:boolean>
```

Peculiar of the SOAP boolean type encoding is that it only defines the values 0 and 1, while the built-in XML Schema boolean type also defines the `false` and `true` symbolic constants as valid values. The following example declaration of an enumeration type lacks named constants altogether to force encoding of the enumeration values as literal constants:

```
enum SOAP_ENC__boolean {};
```

The value 0, for example, is encoded with an integer literal:

```
<SOAP-ENC:boolean xsi:type="SOAP-ENC:boolean">0<SOAP-ENC:boolean>
```

11.3.6 Bitmask Enumeration Serialization

A bitmask is an enumeration of flags such as declared with C#'s [Flags] `enum` annotation. gSOAP supports bitmask encoding and decoding for interoperability. However, bitmask types are not standardized with SOAP RPC.

A special syntactic convention is used in the header file input to the gSOAP compiler to indicate the use of bitmasks with an asterisk:

```
enum * name { enum-constant, enum-constant, ... };
```

The gSOAP compiler will encode the enumeration constants as flags, i.e. as a series of powers of 2 starting with 1. The enumeration constants can be or-ed to form a bitvector (bitmask) which is encoded and decoded as a list of symbolic values in SOAP. For example:

```
enum * ns__machineStatus { ON, BELT, VALVE, HATCH};  
int ns__getMachineStatus(char *name, char *enum ns__machineStatus result);
```

Note that the use of the `enum` does not require the asterisk, only the definition. The gSOAP compiler generates the enumeration:

```
enum ns__machineStatus { ON=1, BELT=2, VALVE=4, HATCH=8};
```

A remote method implementation in a Web service can return:

```
int ns._getMachineStatus(struct soap *soap, char *name, enum ns._machineStatus result)
{ ...
  *result = BELT — HATCH;
  return SOAP_OK;
}
```

11.4 Struct Serialization

A **struct** data type is encoded as an XML Schema complexType (SOAP-encoded compound data type) such that the **struct** name forms the data type's element name and schema type and the fields of the **struct** are the data type's accessors. This encoding is identical to the **class** instance encoding without inheritance and method declarations, see Section 11.5 for further details. However, the encoding and decoding of **structs** is more efficient compared to **class** instances due to the lack of inheritance and the requirement by the serialization routines to check inheritance properties at run time.

Certain type of fields of a **struct** can be (de)serialized as XML attributes. See 11.5.7 for more details.

11.5 Class Instance Serialization

A **class** instance is serialized as an XML Schema complexType (SOAP-encoded compound data type) such that the **class** name forms the data type's element name and schema type and the data member fields are the data type's accessors. Only the data member fields are encoded in the SOAP payload. Class methods are not encoded.

The general form of a **class** declaration is:

```
class [namespace_prefix_]class_name1 [:[public:] [private:] [protected:] [namespace_prefix_]class_name2]
{
  [public:] [private:] [protected:]
  field1;
  field2;
  ...
  [public:] [private:] [protected:]
  method1;
  method2;
  ...
};
```

where

`namespace_prefix_` is the optional namespace prefix of the compound data type (see identifier translation rules 10.3)

`class_name1` is the element name of the compound data type (see identifier translation rules 10.3).

`class_name2` is an optional base class.

`field` is a field declaration (data member). A field MAY be declared **static** and **const** and MAY be initialized.

`method` is a method declaration. A method MAY be declared **virtual**, but abstract methods are not allowed. The method parameter declarations are REQUIRED to have parameter identifier names.

[**public:**] [**private:**] [**protected:**] are OPTIONAL. Only members with **public** access permission can be serialized.

A class name is REQUIRED to be unique and cannot have the same name as a **struct**, **enum**, or remote method name specified in the header file input to the gSOAP compiler. The reason is that remote method requests are encoded similarly to class instances in SOAP and they are in principle undistinguishable (the method parameters are encoded just as the fields of a **class**).

Only single inheritance is supported by the gSOAP compiler. Multiple inheritance is not supported, because of the limitations of the SOAP protocol.

If a constructor method is present, there MUST also be a constructor declaration with empty parameter list.

Classes should be declared “volatile” if you don’t want gSOAP to add serialization methods to these classes, see Section 19.4 for more details.

Class templates are not supported by the gSOAP compiler, but you can use STL containers, see Section 11.10.8. You can also define your own containers similar to STL containers.

Certain fields of a **class** can be (de)serialized as XML attributes. See 11.5.7 for more details.

Arrays may be embedded within a class (and struct) using a pointer field and size information, see Section 11.10.7. This defines what is sometimes referred to in SOAP as “generics”.

Void pointers may be used in a class (or struct), but you have to add a type field so the gSOAP runtime can determine the type of object pointed to, see Section 11.8.

A **class** instance is encoded as:

```
<[namespace-prefix:]class-name xsi:type="[namespace-prefix:]class-name">
<basefield-name1 xsi:type="...">...</basefield-name1>
<basefield-name2 xsi:type="...">...</basefield-name2>
...
<field-name1 xsi:type="...">...</field-name1>
<field-name2 xsi:type="...">...</field-name2>
...
</[namespace-prefix:]class-name>
```

where the `field-name` accessors have element-name representations of the class fields and the `basefield-name` accessors have element-name representations of the base class fields. (The optional parts resulting from the specification are shown enclosed in [].)

The decoding of a class instance allows any ordering of the accessors in the SOAP payload. However, if a base class field name is identical to a derived class field name because the field is overloaded,

the base class field name **MUST** precede the derived class field name in the SOAP payload for decoding. gSOAP guarantees this, but interoperability with other SOAP implementations is cannot be guaranteed.

11.5.1 Example

The following example declares a base class `ns__Object` and a derived class `ns__Shape`:

```
// Contents of file "shape.h":
class ns__Object
{
    public:
    char *name;
};
class ns__Shape : public ns__Object
{
    public:
    int sides;
    enum ns__Color {Red, Green, Blue} color;
    ns__Shape();
    ns__Shape(int sides, enum ns__Color color);
    ~ns__Shape();
};
```

The implementation of the methods of `class ns__Shape` must not be part of the header file and need to be defined elsewhere.

An instance of `class ns__Shape` with name Triangle, 3 sides, and color Green is encoded as:

```
<ns:Shape xsi:type="ns:Shape">
<name xsi:type="string">Triangle</name>
<sides xsi:type="int">3</sides>
<color xsi:type="ns:Color">Green</color>
</ns:shape>
```

The namespace URI of the namespace prefix `ns` must be defined by a namespace mapping table, see Section 10.4.

11.5.2 Initialized static const Fields

A data member field of a class declared as **static const** is initialized with a constant value at compile time. This field is encoded in the serialization process, but is not decoded in the deserialization process. For example:

```
// Contents of file "triangle.h":
class ns__Triangle : public ns__Object
{
    public:
    int size;
```

```

    static const int sides = 3;
};

```

An instance of **class** `ns_Triangle` is encoded in SOAP as:

```

<ns:Triangle xsi:type="ns:Triangle">
  <name xsi:type="string">Triangle</name>
  <size xsi:type="int">15</size>
  <sides xsi:type="int">3</sides>
</ns:Triangle>

```

Decoding will ignore the `sides` field's value.

Caution: The current gSOAP implementation does not support encoding **static const** fields, due to C++ compiler compatibility differences. This feature may be provided the future.

11.5.3 Class Methods

A **class** declaration in the header file input to the gSOAP compiler MAY include method declarations. The method implementations MUST NOT be part of the header file but are required to be defined in another C++ source that is externally linked with the application. This convention is also used for the constructors and destructors of the **class**.

Dynamic binding is supported, so a method MAY be declared **virtual**.

11.5.4 Getter and Setter Methods

Setter and getter methods are invoked at run time upon serialization and deserialization of class instances, respectively. The use of setter and getter methods adds more flexibility to the serialization and deserialization process.

A setter method is called in the serialization phase from the virtual `soap_serialization` method generated by the gSOAP compiler. You can use setter methods to process a class instance just before it is serialized. A setter method can be used to convert application data, such as translating transient application data into serializable data, for example. You can also use setter methods to retrieve dynamic content and use it to update a class instance right before serialization. Remember setters as "set to serialize" operations.

Getter methods are invoked after deserialization of the instance. You can use them to adjust the contents of class instances after all their members have been deserialized. Getters can be used to convert deserialized members into transient members and even invoke methods to process the deserialized data on the fly.

Getter and setter methods have the following signature:

```

[virtual] int get(struct soap *soap) [const];
[virtual] int set(struct soap *soap);

```

The active soap struct will be passed to the `get` and `set` methods. The methods should return `SOAP_OK` when successful. A setter method should prepare the contents of the class instance for serialization. A getter method should process the instance after deserialization.

Here is an example of a base64 binary class:

```
class xsd__base64Binary
{ public:
    unsignedchar *_ptr;
    int _size;
    int get(struct soap *soap);
    int set(struct soap *soap);
};
```

Suppose that the type and options members of the attachment should be set when the class is about to be serialized. This can be accomplished with the `set` method from the information provided by the `_ptr` to the data and the soap struct passed to the `set` method (you can pass data via the `void*soap.user` field).

The `get` method is invoked after the base64 data has been processed. You can use it for post-processing purposes.

Here is another example. It defines a primitive `update` type. The class is a wrapper for the `time_t` type, see Section 11.2.2. Therefore, elements of this type contain `xsd:dateType` data.

```
class update
{ public:
    time_t _item;
    int set(struct soap *soap);
};
```

The setter method assigns the current time:

```
int update::set(struct soap *soap)
{
    this->_item = time(NULL);
    return SOAP_OK;
}
```

Therefore, serialization results in the inclusion of a time stamp in XML.

Caution: a `get` method is invoked only when the XML element with its data was completely parsed. The method is not invoked when the element is an `xsi:nil` element or has an `href` attribute.

Caution: The `soap_serialize` method of a class calls the setter (when provided). However, the `soap_serialize` method is declared `const` while the setter should be allowed to modify the contents of the class instance. Therefore, the gSOAP-generated code recasts the instance and the `const` is removed when invoking the setter.

11.5.5 Streaming XML with Getter and Setter Methods

Getter methods enable streaming XML operations. A getter method is invoked when the object is deserialized and the rest of the SOAP/XML message has not been processed yet. For example, you can add a getter method to the SOAP Header class to implement header processing logic that is activated as soon as the SOAP Header is received. An example code is shown below:

```

class h_._Authentication
{
public:
    char *id;
    int get(struct soap *soap);
};
class SOAP_ENV_._Header
{
public:
    h_._Authentication *h_._authentication;
};

```

The Authentication SOAP Header field is instantiated and decoded. After decoding, the getter method is invoked, which can be used to check the id before the rest of the SOAP message is processed.

11.5.6 Polymorphism, Derived Classes, and Dynamic Binding

Interoperability between client and service applications developed with gSOAP is established even when clients and/or services use derived classes instead of the base classes used in the declaration of the remote method parameters. A client application MAY use pointers to instances of derived classes for the input parameters of a remote method. If the service was compiled with a declaration and implementation of the derived class, the remote method base class input parameters are demarshalled and a derived class instance is created instead of a base class instance. If the service did not include a declaration of the derived class, the derived class fields are ignored and a base class instance is created. Therefore, interoperability is guaranteed even when the client sends an instance of a derived classes and when a service returns an instance of a derived class.

The following example declares Base and Derived classes and a remote method that takes a pointer to a Base class instance and returns a Base class instance:

```

// Contents of file "derived.h"
class Base
{
public:
    char *name;
    Base();
    virtual void print();
};
class Derived : public Base
{
public:
    int num;
    Derived();
    virtual void print();
};
int method(Base *in, struct methodResponse { Base *out; } &result);

```

This header file specification is processed by the gSOAP compiler to produce the stub and skeleton routines which are used to implement a client and service. The pointer of the remote method is also allowed to point to Derived class instances and these instances will be marshalled as Derived

class instances and send to a service, which is in accord to the usual semantics of parameter passing in C++ with dynamic binding.

The Base and Derived class method implementations are:

```
// Method implementations of the Base and Derived classes:
#include "soapH.h"
...
Base::Base()
{
    cout << "created a Base class instance" << endl;
}
Derived::Derived()
{
    cout << "created a Derived class instance" << endl;
}
Base::print()
{
    cout << "print(): Base class instance " << name << endl;
}
Derived::print()
{
    cout << "print(): Derived class instance " << name << " " << num << endl;
}
```

Below is an example CLIENT application that creates a Derived class instance that is passed as the input parameter of the remote method:

```
// CLIENT
#include "soapH.h"
int main()
{
    struct soap soap;
    soap_init(&soap);
    Derived obj1;
    Base *obj2;
    struct methodResponse r;
    obj1.name = "X";
    obj1.num = 3;
    soap_call_method(&soap, url, action, &obj1, r);
    r.obj2->print();
}
...
```

The following example SERVER1 application copies a class instance (Base or Derived class) from the input to the output parameter:

```
// SERVER1
#include "soapH.h"
int main()
{
```

```

    soap_serve(soap_new());
}
int method(struct soap *soap, Base *obj1, struct methodResponse &result)
{
    obj1->print();
    result.obj2 = obj1;
    return SOAP_OK;
}
...

```

The following messages are produced by the CLIENT and SERVER1 applications:

```

CLIENT: created a Derived class instance
SERVER1: created a Derived class instance
SERVER1: print(): Derived class instance X 3
CLIENT: created a Derived class instance
CLIENT: print(): Derived class instance X 3

```

Which indicates that the derived class kept its identity when it passed through SERVER1. Note that instances are created both by the CLIENT and SERVER1 by the demarshalling process.

Now suppose a service application is developed that only accepts Base class instances. The header file is:

```

// Contents of file "base.h":
class Base
{
    public:
    char *name;
    Base();
    virtual void print();
};
int method(Base *in, Base *out);

```

This header file specification is processed by the gSOAP stub and skeleton compiler to produce skeleton routine which is used to implement a service (so the client will still use the derived classes).

The method implementation of the Base class are:

```

// Method implementations of the Base class:
#include "soapH.h"
...
Base::Base()
{
    cout << "created a Base class instance" << endl;
}
Base::print()
{
    cout << "print(): Base class instance " << name << endl;
}

```

And the SERVER2 application is that uses the Base class is:

```
// SERVER2
#include "soapH.h"
int main()
{
    soap_serve(soap_new());
}
int method(struct soap *soap, Base *obj1, struct methodResponse &result)
{
    obj1->print();
    result.obj2 = obj1;
    return SOAP_OK;
}
...
```

Here are the messages produced by the CLIENT and SERVER2 applications:

```
CLIENT: created a Derived class instance
SERVER2: created a Base class instance
SERVER2: print(): Base class instance X
CLIENT: created a Base class instance
CLIENT: print(): Base class instance X
```

In this example, the object was passed as a Derived class instance to SERVER2. Since SERVER2 only implements the Base class, this object is converted to a Base class instance and send back to CLIENT.

11.5.7 XML Attributes

The SOAP RPC/LIT and SOAP DOC/LIT encoding styles support XML attributes in SOAP messages while SOAP RPC with “Section 5” encoding does not support XML attributes other than the SOAP and XSD specific attributes. SOAP RPC “Section 5” encoding has advantages for cross-language interoperability and data encodings such as graph serialization. However, RPC/LIT and DOC/LIT enables direct exchange of XML documents, which may include encoded application data structures. Language interoperability is compromised, because no mapping between XML and the typical language data types is defined. The meaning of the RPC/LIT and DOC/LIT XML content is Schema driven rather than application/language driven.

gSOAP supports XML attribute (de)serialization of members in structs and classes. Attributes are primitive XSD types, such as strings, enumerations, boolean, and numeric types. To declare an XML attribute in a struct/class, the qualifier @ is used with the type of the attribute. The type must be primitive type (including enumerations and strings), which can be declared with or without a **typedef** to associate a XSD type with the C/C+ type. For example

```
typedef char *xsd_string;
typedef bool *xsd_boolean;
enum ns_state { _0, _1, _2 };
struct ns_myStruct
```



```

{
    @ xsd:_string ns:_type; // encode as XML attribute 'ns:type' of type 'xsd:string'
    @ xsd:_boolean ns:_flag = false; // encode as XML attribute 'ns:flag' of type 'xsd:boolean'
    @ enum ns:_state ns:_state = _2; // encode as XML attribute 'ns:state' of type 'ns:state'
    struct ns:_myStruct *next;
};

```

The @ qualifier indicates XML attribute encoding for the `ns:_type`, `ns:_flag`, and `ns:_state` fields. Note that the namespace prefix `ns` is used to distinguish these attributes from any other attributes such as `xsi:type` (`ns:type` is not to be confused with `xsi:type`).

Default values can be associated with any field that has a primitive type in a struct/class, as is illustrated in this example. The default values are used when the receiving message does not contain the corresponding values.

String attributes are optional. Other type of attributes should be declared as pointers to make them optional:

```

struct ns:_myStruct
{
    @int *a; // omitted when NULL };

```

Because a remote method request and response is essentially a struct, XML attributes can also be associated with method requests and responses. For example

```

int ns:_myMethod(@char *ns:_name, ...);

```

Attributes can also be attached to the dynamic arrays, binary types, and wrapper classes/structs of primitive types. Wrapper classes are described in Section 11.2.2. For example

```

struct xsd:_string
{
    char *_item;
    @ xsd:_boolean flag;
};

```

and

```

struct xsd:_base64Binary
{
    unsigned char *_ptr;
    int _size;
    @ xsd:_boolean flag;
};

```

The attribute declarations MUST follow the `_item`, `_ptr`, and `_size` fields which define the characteristics of wrapper structs/classes and dynamic arrays.

Caution: Do not use XML attributes with SOAP RPC encoding. You can only use attributes with RPC literal encoding.

11.5.8 QName Attributes and Elements

gSOAP ensures the proper decoding of XSD QNames. An element or attribute with type QName (Qualified Name) contains a namespace prefix and a local name. You can declare a QName type as a **typedef char *xsd_QName**. Values of type QName are internally handled as regular strings. gSOAP takes care of the proper namespace prefix mappings when deserializing QName values. For example

```
typedef char *xsd_QName;
struct ns_myStruct
{
    xsd_QName elt = "ns:xyz"; // QName element with default value "ns:xyz"
    @ xsd_QName att = "ns:abc"; // QName attribute with default value "ns:abc"
};
```

When the `elt` and `att` fields are serialized, their string contents are just transmitted (which means that the application is responsible to ensure proper formatting of the QName strings prior to transmission). When the fields are deserialized however, gSOAP takes care mapping the qualifiers to the appropriate namespace prefixes. Suppose that the inbound value for the `elt` is `x:def`, where the namespace name associated with the prefix `x` matches the namespace name of the prefix `ns` (as defined in the namespace mapping table). Then, the value is automatically converted into `ns:def`. If the namespace name is not in the table, then `x:def` is converted to `"URI":def` where `"URI"` is the namespace URI bound to `x` in the message received. This enables an application to retrieve the namespace information, whether it is in the namespace mapping table or not.

Note: QName is a pre-defined typedef type and used by gSOAP to (de)serialize SOAP Fault codes which are QName elements.

11.6 Union Serialization

A **union** is only serialized if the **union** is used within a **struct** or **class** declaration that includes a **int _union** field that acts as a *discriminant* or *selector* for the **union** fields. The selector stores run-time usage information about the **union** fields. That is, the selector is used to enumerate the **union** fields such that the gSOAP engine is able to select the correct **union** field to serialize.

A **union** within a **struct** or **class** with a selector field represents `xs:choice` within a Schema complexType component. For example:

```
struct ns_PO
{ ... };
struct ns_Invoice
{ ... };
union ns_PO_or_Invoice
{
    struct ns_PO po;
    struct ns_Invoice invoice;
}; struct ns_composite
{
    char *name;
```

```

    int __union;
    union ns__PO_or_Invoice value;
};

```

The **union** ns__PO_or_Invoice is expanded as a `xs:choice`:

```

<complexType name="composite">
  <sequence>
    <element name="name" type="xsd:string"/>
    <choice>
      <element name="po" type="ns:PO"/>
      <element name="invoice" type="ns:Invoice"/>
    </choice>
  </sequence>
</complexType>

```

Therefore, the name of the **union** and field can be freely chosen. However, the **union** name should be qualified (as shown in the example) to ensure instances of XML Schemas with `elementFormDefault="qualified"` are correctly serialized (`po` and `invoice` are `ns:` qualified).

The **int** __union field selector's values are determined by the `soapcpp2` compiler. Each **union** field name has a selector value formed by:

`SOAP_UNION_`*union-name_field-name*

These selector values enumerate the **union** fields starting with 1. The value 0 can be assigned to omit the serialization of the **union**, but only if explicitly allowed by validation rules, which requires `minOccurs="0"` for the `xs:choice` as follows:

```

struct ns__composite
{
    char *name;
    int __union 0; // <choice minOccurs="0">
    union ns__PO_or_Invoice value;
};

```

This way we can treat the **union** as an optional data item by setting `__union=0`.

The following example shows how the **struct** ns__composite instance is initialized for serialization:

```

struct ns__composite data;
data.name = "...";
data.__union = SOAP_UNION_ns__PO_or_Invoice_po; // select PO
data.value.po.number = ...; // populate the PO

```

Note that failing to set the selector to a valid **union** field can lead to a crash of the gSOAP serializer because it will attempt to serialize an invalid **union** field.

For deserialization of **union** types, the `__union` selector will be set to 0 (when permitted) by the gSOAP deserializer or set to one of the **union** field selector values as determined by the XML payload.

When more than one **union** is used in a **struct** or **class**, the `__union` selectors must be renamed to avoid name clashes by using suffixes as in:

```
struct ns__composite
{
    char *name;
    int __union_value; // added suffix "_value"
    union ns__PO_or_Invoice value;
    int __union_data; // added suffix "_data"
    union ns__Email_or_Fax data;
};
```

11.7 Serializing Pointer Types

The serialization of a pointer to a data type amounts to the serialization of the data type in SOAP and the SOAP encoded representation of a pointer to the data type is indistinguishable from the encoded representation of the data type pointed to.

11.7.1 Multi-Referenced Data

A data structure pointed to by more than one pointer is serialized as SOAP multi-reference data. This means that the data will be serialized only once and identified with a unique `id` attribute. The encoding of the pointers to the shared data is done through the use of `href` attributes to refer to the multi-reference data (also see Section 9.12 on options to control the serialization of multi-reference data). Cyclic C/C++ data structures are encoded with multi-reference SOAP encoding. Consider for example the following a linked list data structure:

```
typedef char *xsd__string;
struct ns__list
{
    xsd__string value;
    struct ns__list *next;
};
```

Suppose a cyclic linked list is created. The first node contains the value "abc" and points to a node with value "def" which in turn points to the first node. This is encoded as:

```
<ns:list id="1" xsi:type="ns:list">
  <value xsi:type="xsd:string">abc</value>
  <next xsi:type="ns:list">
    <value xsi:type="xsd:string">def</value>
    <next href="#1"/>
  </next>
</ns:list>
```

In case multi-referenced data is received that “does not fit in a pointer-based structure”, the data is copied. For example, the following two **structs** are similar, except that the first uses pointer-based fields while the other uses non-pointer-based fields:

```

typedef long xsd_int;
struct ns_record
{
    xsd_int *a;
    xsd_int *b;
} P;
struct ns_record
{
    xsd_int a;
    xsd_int b;
} R;
...
    P.a = &n;
    P.b = &n;
...

```

Since both a and b fields of P point to the same integer, the encoding of P is multi-reference:

```

<ns:record xsi:type="ns:record">
  <a href="#1"/>
  <b href="#1"/>
</ns:record>
<id id="1" xsi:type="xsd:int">123</id>

```

Now, the decoding of the content in the R data structure that does not use pointers to integers results in a copy of each multi-reference integer. Note that the two **structs** resemble the same XML data type because the trailing underscore will be ignored in XML encoding and decoding.

11.7.2 NULL Pointers and Nil Elements

A NULL pointer is **not** serialized, unless the pointer itself is pointed to by another pointer (but see Section 9.12 to control the serialization of NULLs). For example:

```

struct X
{
    int *p;
    int **q;
}

```

Suppose pointer q points to pointer p and suppose p=NULL. In that case the p pointer is serialized as

```

<... id="123" xsi:nil="true"/>

```

and the serialization of q refers to href="#123". Note that SOAP 1.1 does not support pointer to pointer types (!), so this encoding is specific to gSOAP. The pointer to pointer encoding is rarely used in codes anyway. More common is a pointer to a data type such as a **struct** with pointer fields.

Caution: When the deserializer encounters an XML element that has a `xsi:nil="true"` attribute but the corresponding C++ data is not a pointer or reference, the deserializer will terminate with a

SOAP_NULL fault when the SOAP_XML_STRICT flag is set. The types section of a WSDL description contains information on the “nilability” of data.

11.8 Void Pointers

In general, void pointers (**void***) cannot be (de)serialized because the type of data referred to is untyped. To enable the (de)serialization of the void pointers that are members of structs or classes, you can insert a **int** `__type` field right before the void pointer field. The **int** `__type` field contains run time information on the type of the data pointed to by **void*** member in a struct/class to enable the (de)serialization of this data. The **int** `__type` field is set to a SOAP_TYPE_X value, where X is the name of a type. gSOAP generates the SOAP_TYPE_X definitions in `soapH.h` and uses them internally to uniquely identify the type of each object. The type naming conventions outlined in Section 8.5.1 are used to determine the type name for X.

Here is an example to illustrate the (de)serialization of a **void*** field in a struct:

```
struct myStruct
{
    int __type; // the SOAP_TYPE pointed to by p
    void *p;
};
```

The `__type` integer can be set to 0 at run time to omit the serialization of the void pointer field.

The following example illustrates the initialization of `myStruct` with a void pointer to an int:

```
struct myStruct S;
int n;
S.p = &n;
S.__type = SOAP_TYPE_int;
```

The serialized output of S contains the integer.

The deserializer for `myStruct` will automatically set the `__type` field and void pointer to the deserialized data, provided that the XML content for p carries the `xsi:type` attribute from which gSOAP can determine the type.

Important: when (de)serializing strings via a **void*** field, the **void*** pointer MUST directly point to the string value rather than indirectly as with all other types. For example:

```
struct myStruct S;
S.p = (void*)"Hello";
S.__type = SOAP_TYPE_string;
```

This is the case for all string-based types, including types defined with **typedef char***.

You may use an arbitrary suffix with the `__type` fields to handle multiple void pointers in structs/classes. For example

```

struct myStruct
{
    int _typeOfp; // the SOAP_TYPE pointed to by p
    void *p;
    int _typeOfq; // the SOAP_TYPE pointed to by q
    void *q;
};

```

Because service method parameters are stored within structs, you can use `_type` and `void*` parameters to pass polymorphic arguments without having to define a C++ class hierarchy (Section 11.5.6). For example:

```

typedef char *xsd_string;
typedef int xsd_int;
typedef float xsd_float;
enum ns_status { on, off };
struct ns_widget { xsd_string name; xsd_int part; }; int ns_myMethod(int _type, void *data,
struct ns_myMethodResponse { int _type; void *return_; } *out);

```

This method has a polymorphic input parameter `data` and a polymorphic output parameter `return_`. The `_type` parameters can be one of `SOAP_TYPE_xsd_string`, `SOAP_TYPE_xsd_int`, `SOAP_TYPE_xsd_float`, `SOAP_TYPE_ns_status`, or `SOAP_TYPE_ns_widget`. The WSDL produced by the gSOAP compiler declares the polymorphic parameters of type `xsd:anyType` which is "too loose" and doesn't allow the gSOAP importer to handle the WSDL accurately. Future gSOAP releases might replace `xsd:anyType` with a choice schema type that limits the choice of types to the types declared in the header file.

11.9 Fixed-Size Arrays

Fixed size arrays are encoded as per SOAP 1.1 one-dimensional array types. Multi-dimensional fixed size arrays are encoded by gSOAP as nested one-dimensional arrays in SOAP. Encoding of fixed size arrays supports partially transmitted and sparse array SOAP formats.

The decoding of (multi-dimensional) fixed-size arrays supports the SOAP multi-dimensional array format as well as partially transmitted and sparse array formats.

An example:

```

// Contents of header file "fixed.h":
struct Example
{
    float a[2][3];
};

```

This specifies a fixed-size array part of the `struct` `Example`. The encoding of array `a` is:

```

<a xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="float [] [2]">
<SOAP-ENC:Array xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="float [3]"
<float xsi:type="float">...</float>

```

```

<float xsi:type="float">...</float>
<float xsi:type="float">...</float>
</SOAP-ENC:Array>
<SOAP-ENC:Array xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="float[3]"
<float xsi:type="float">...</float>
<float xsi:type="float">...</float>
<float xsi:type="float">...</float>
</SOAP-ENC:Array>
</a>

```

Caution: Any decoded parts of a (multi-dimensional) array that do not “fit” in the fixed size array are ignored by the deserializer.

11.10 Dynamic Arrays

As the name suggests, dynamic arrays are much more flexible than fixed-size arrays and dynamic arrays are better adaptable to the SOAP encoding and decoding rules for arrays. In addition, a typical C application allocates a dynamic array using `malloc`, assigns the location to a pointer variable, and deallocates the array later with `free`. A typical C++ application allocates a dynamic array using `new`, assigns the location to a pointer variable, and deallocates the array later with `delete`. Such dynamic allocations are flexible, but pose a problem for the serialization of data: how does the array serializer know the length of the array to be serialized given only a pointer to the sequence of elements? The application stores the size information somewhere. This information is crucial for the array serializer and has to be made explicitly known to the array serializer by packaging the pointer and array size information within a **struct** or **class**.

11.10.1 SOAP Array Bounds Limits

SOAP encoded arrays use the `SOAP-ENC:Array` type and the `SOAP-ENC:arrayType` attribute to define the array dimensionality and size. As a security measure to avoid denial of service attacks based on sending a huge array size value requiring the allocation of large chunks of memory, the total number of array elements set by the `SOAP-ENC:arrayType` attribute cannot exceed `SOAP_MAXARRAYSIZE`, which is set to 100,000 by default. This constant is defined in `stdsoap2.h`. This constant **only** affects multi-dimensional arrays and the dimensionality of the receiving array will be lost when the number of elements exceeds 100,000. One-dimensional arrays will be populated in sequential order as expected.

11.10.2 One-Dimensional Dynamic Arrays

A special form of **struct** or **class** is used for one-dimensional dynamic arrays that contains a pointer variable and a field that records the number of elements the pointer points to in memory.

The general form of the **struct** declaration for one-dimensional dynamic SOAP arrays is:

```

struct some_name
{
    Type *_ptr; // pointer to array

```



```

    int _size; // number of elements pointed to
    [[static const] int _offset [= ...];] // optional SOAP 1.1 array offset
    ... // anything that follows here will be ignored
};

```

where Type MUST be a type associated with an XML Schema or MUST be a primitive type. If these conditions are not met, a vector-like XML (de)serialization is used (see Section 11.10.7). A primitive type can be used with or without a **typedef**. If the array elements are structs or classes, then the struct/class type names should have a namespace prefix for schema association, or they should be other (nested) dynamic arrays.

An alternative to a **struct** is to use a **class** with optional methods that MUST appear after the `_ptr` and `_size` fields:

```

class some_name
{
    public:
    Type *_ptr;
    int _size;
    [[static const] int _offset [= ...];]
    method1;
    method2;
    ... // any fields that follow will be ignored
};

```

To encode the data type as an array, the name of the **struct** or **class** SHOULD NOT have a namespace prefix, otherwise the data type will be encoded and decoded as a generic vector, see Section 11.10.7.

The deserializer of a dynamic array can decode partially transmitted and/or SOAP sparse arrays, and even multi-dimensional arrays which will be collapsed into a one-dimensional array with row-major ordering.

Caution: SOAP 1.2 does not support partially transmitted arrays. So the `_offset` field of a dynamic array is ignored.

11.10.3 Example

The following example header file specifies the XMethods Service Listing service `getAllSOAPServices` remote method and an array of `SOAPService` data structures:

```

// Contents of file "listing.h":
class ns3_SOAPService
{
    public:
    int ID;
    char *name;
    char *owner;
    char *description;
    char *homepageURL;
    char *endpoint;
};

```

```

    char *SOAPAction;
    char *methodNameNamespaceURI;
    char *serviceStatus;
    char *methodName;
    char *dateCreated;
    char *downloadURL;
    char *wsdlURL;
    char *instructions;
    char *contactEmail;
    char *serverImplementation;
};
class ServiceArray
{
public:
    ns3__SOAPService *__ptr; // points to array elements
    int __size; // number of elements pointed to
    ServiceArray();
    ~ServiceArray();
    void print();
};
int ns__getAllSOAPServices(ServiceArray &return_);

```

An example client application:

```

#include "soapH.h" ...
// ServiceArray class method implementations:
ServiceArray::ServiceArray()
{
    __ptr = NULL;
    __size = 0;
}
ServiceArray::~ServiceArray()
{ // destruction handled by gSOAP
}
void ServiceArray::print()
{
    for (int i = 0; i < __size; i++)
        cout << __ptr[i].name << ": " << __ptr[i].homepage << endl;
}
...
// Request a service listing and display results:
{
    struct soap soap;
    ServiceArray result;
    const char *endpoint = "www.xmethods.net:80/soap/servlet/rpcrouter";
    const char *action = "urn:xmethodsServicesManager#getAllSOAPServices";
    ...
    soap_init(&soap);
    soap_call_ns__getAllSOAPServices(&soap, endpoint, action, result);
    result.print();
    ...
}

```

```

    soap_destroy(&soap); // dealloc class instances
    soap_end(&soap); // dealloc deserialized data
    soap_done(&soap); // cleanup and detach soap struct
}

```

11.10.4 One-Dimensional Dynamic Arrays With Non-Zero Offset

The declaration of a dynamic array as described in 11.10 MAY include an **int** `_offset` field. When set to an integer value, the serializer of the dynamic array will use this field as the start index of the array and the SOAP array offset attribute will be used in the SOAP payload. Note that array offsets is a SOAP 1.1 specific feature which is not supported in SOAP 1.2.

For example, the following header file declares a mathematical Vector class, which is a dynamic array of floating point values with an index that starts at 1:

```

// Contents of file "vector.h":
typedef float xsd_float;
class Vector
{
    xsd_float *_ptr;
    int _size;
    int _offset;
    Vector();
    Vector(int n);
    float& operator[](int i);
}

```

The implementations of the Vector methods are:

```

Vector::Vector()
{
    _ptr = NULL;
    _size = 0;
    _offset = 1;
}
Vector::Vector(int n)
{
    _ptr = (float*)malloc(n*sizeof(float));
    _size = n;
    _offset = 1;
}
Vector::~Vector()
{
    if (_ptr)
        free(_ptr);
}
float& Vector::operator[](int i)
{
    return _ptr[i-_offset];
}

```

An example program fragment that serializes a vector of 3 elements:

```
struct soap soap;
soap_init(&soap);
Vector v(3);
v[1] = 1.0;
v[2] = 2.0;
v[3] = 3.0;
soap_begin(&soap);
v.serialize(&soap);
v.put("vec");
soap_end(&soap);
```

The output is a partially transmitted array:

```
<vec xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="xsd:float[4]" SOAP-ENC:offset="[1]">
<item xsi:type="xsd:float">1.0</item>
<item xsi:type="xsd:float">2.0</item>
<item xsi:type="xsd:float">3.0</item>
</vec>
```

Note that the size of the encoded array is necessarily set to 4 and that the encoding omits the non-existent element at index 0.

The decoding of a dynamic array with an `__offset` field is more efficient than decoding a dynamic array without an `__offset` field, because the `__offset` field will be assigned the value of the `SOAP-ENC:offset` attribute instead of padding the initial part of the array with default values.

11.10.5 Nested One-Dimensional Dynamic Arrays

One-dimensional dynamic arrays MAY be nested. For example, using **class** `Vector` declared in the previous section, **class** `Matrix` is declared:

```
// Contents of file "matrix.h":
class Matrix
{
    public:
    Vector * __ptr;
    int __size;
    int __offset;
    Matrix();
    Matrix(int n, int m);
    ~Matrix();
    Vector& operator[(int i)];
};
```

The `Matrix` type is essentially an array of pointers to arrays which make up the rows of a matrix. The encoding of the two-dimensional dynamic array in SOAP will be in nested form.

11.10.6 Multi-Dimensional Dynamic Arrays

The general form of the **struct** declaration for K -dimensional ($K > 1$) dynamic arrays is:

```
struct some_name
{
    Type *_ptr;
    int _size[K];
    int _offset[K];
    ... // anything that follows here will be ignored
};
```

where Type MUST be a type associated with an XML Schema, which means that it must be a **typedefed** type in case of a primitive type, or a **struct/class** name with a namespace prefix for schema association, or another dynamic array. If these conditions are not met, a generic vector XML (de)serialization is used (see Section 11.10.7).

An alternative is to use a **class** with optional methods:

```
class some_name
{
    public:
    Type *_ptr;
    int _size[K];
    int _offset[K];
    method1;
    method2;
    ... // any fields that follow will be ignored
};
```

In the above, K is a constant denoting the number of dimensions of the multi-dimensional array.

To encode the data type as an array, the name of the **struct** or **class** SHOULD NOT have a namespace prefix, otherwise the data type will be encoded and decoded as a generic vector, see Section 11.10.7.

The deserializer of a dynamic array can decode partially transmitted multi-dimensional arrays.

For example, the following declaration specifies a matrix class:

```
typedef double xsd_double;
class Matrix
{
    public:
    xsd_double *_ptr;
    int _size[2];
    int _offset[2];
};
```

In contrast to the matrix class of Section 11.10.5 that defined a matrix as an array of pointers to matrix rows, this class has one pointer to a matrix stored in row-major order. The size of the matrix is determined by the `_size` field: `_size[0]` holds the number of rows and `_size[1]` holds the number of columns of the matrix. Likewise, `_offset[0]` is the row offset and `_offset[1]` is the columns offset.

11.10.7 Encoding XML Generics Containing Dynamic Arrays

XML “generics” extend the concept of a struct by allowing repetitions of elements within the struct. A simple generic is an array-like data structure with a repetition of one element. To achieve this, declare a dynamic array as a **struct** or **class** with a name that is qualified with a namespace prefix. SOAP arrays are declared without prefix.

For example:

```
struct ns_Map
{
    struct ns_Binding {char *key; char *val;} *_ptr;
    int _size;
};
```

This declares a dynamic array, but the array will be serialized and deserialized as a generic with a list-like data structure. For example:

```
<ns:Map xsi:type="ns:Map">
  <ns:Binding xsi:type="ns:Binding">
    <key>Joe</key>
    <val>555 77 1234</val>
  </ns:Binding>
  <ns:Binding xsi:type="ns:Binding">
    <key>Susan</key>
    <val>555 12 6725</val>
  </ns:Binding>
  <ns:Binding xsi:type="ns:Binding">
    <key>Pete</key>
    <val>555 99 4321</val>
  </ns:Binding>
</ns:Map>
```

Deserialization is less efficient compared to an array, because the size of the list is not part of the SOAP encoding. Internal buffering is used by the deserializer to collect the elements. When the end of the list is reached, the buffered elements are copied to a newly allocated space on the heap for the dynamic array.

Multiple arrays can be used in a struct/class to support the concept of generics. Each array results in a repetition of elements in the struct/class. This is achieved with a **int** `_size` field in the struct/class where the next field (i.e. below the `_size` field) is a pointer type. The pointer type is assumed to point to an array of values at run time. The `_size` field holds the number of values at run time. Multiple arrays can be embedded in a struct/class with `_size` fields that have a distinct names. To make the `_size` fields distinct, you can end them with a unique name suffix such as `_sizeOfstrings`, for example.

The general convention for embedding arrays is:

```
struct ns_SomeStruct
{
```

```

...
int _sizename1; // number of elements pointed to
Type1 *field1; // by this field
...
int _sizename2; // number of elements pointed to
Type2 *field2; // by this field
...
};

```

where name1 and name2 are identifiers used as a suffix to distinguish the `_size` field. These names can be arbitrary and are not visible in XML.

For example, the following struct has two embedded arrays:

```

struct ns_Contact
{
    char *firstName;
    char *lastName;
    int _sizePhones;
    ULONG64 *phoneNumber; // array of phone numbers
    int _sizeEmails;
    char **emailAddress; // array of email addresses
    char *socSecNumber;
};

```

The XML serialization of an example `ns_Contact` is:

```

<mycontact xsi:type="ns:Contact">
  <firstName>Joe</firstName>
  <lastName>Smith</lastName>
  <phoneNumber>5551112222</phoneNumber>
  <phoneNumber>5551234567</phoneNumber>
  <phoneNumber>5552348901</phoneNumber>
  <emailAddress>Joe.Smith@mail.com</emailAddress>
  <emailAddress>Joe@Smith.com</emailAddress>
  <socSecNumber>999999999</socSecNumber>
</mycontact>

```

11.10.8 STL Containers

gSOAP supports the STL containers `std::deque`, `std::list`, `std::set`, and `std::vector`.

STL containers can only be used within classes to declare members that contain multiple values. This is somewhat similar to the embedding of arrays in structs in C as explained in Section 11.10.7, but the STL container approach is more flexible.

You need to import `stddeque.h`, `stlset.h`, or `stlvector.h` to enable `std::deque`, `std::list`, `std::set`, and `std::vector` (de)serialization. Here is an example:

```

#import "stlvector.h"
class ns_myClass

```

```

{ public:
    std::vector<int> *number;
    std::vector<xsd::string> *name;
    ...
};

```

The use of pointer members is not required but advised. The reason is that interoperability with other SOAP toolkits may lead to copying of `ns::myClass` instances at run time when (de)serializing multi-referenced data. When a copy is made, certain parts of the containers will be shared between the copies which could lead to disaster when the classes with their containers are deallocated. Another way to avoid this is to declare class `ns::myClass` within other data types via a pointer. (Interoperability between gSOAP clients and services does not lead to copying.)

The XML Schema that corresponds to the `ns::myClass` type is

```

<complexType name="myClass">
  <sequence>
    <element name="number" type="xsd:int" minOccurs="1" maxOccurs="unbounded"/>
    <element name="name" type="xsd:string" minOccurs="1" maxOccurs="unbounded"/>
    ...
  </sequence>
</complexType>

```

You can specify the `minOccurs` and `maxOccurs` values as explained in Section 19.2.

You can also implement your own containers similar to STL containers. The containers must be class templates and should define an iterator type, and **void** `clear()`, `iterator begin()`, `iterator end()`, and `iterator insert(iterator pos, const_reference val)`. The iterator should have a dereference operator to access the container's elements. The dereference operator is used by gSOAP to send a sequence of XML element values. The `insert` method can be used as a setter method. gSOAP reads a sequence of XML element values and inserts them in the container via this method.

Here is an example user-defined container template class:

```

// simpleVector.h
template <class T>
class simpleVector
{
public:
    typedef T value_type;
    typedef value_type * pointer;
    typedef const value_type * const_pointer;
    typedef value_type & reference;
    typedef const value_type & const_reference;
    typedef pointer iterator;
    typedef const_pointer const_iterator;
protected:
    iterator start;
    iterator finish;
    size_t size;
public:

```



```

simpleVector() { clear(); }
~simpleVector() { delete[] start; }
void clear() { start = finish = NULL; }
iterator begin() { return start; }
const_iterator begin() const { return start; }
iterator end() { return finish; }
const_iterator end() const { return finish; }
iterator insert(iterator pos, const_reference val)
{
    if (!start)
        start = finish = new value_type[size = 4];
    else if (finish >= start + size)
    {
        iterator i = start;
        iterator j = new value_type[2 * size];
        start = j;
        finish = start + size;
        size *= 2;
        if (pos)
            pos = j + (pos - i);
        while (i != finish)
            *j++ = *i++;
    }
    if (pos && pos != finish)
    {
        iterator i = finish;
        iterator j = i - 1;
        while (j != pos)
            *i-- = *j--;
    }
    *finish++ = val;
    return pos;
}
};

```

To enable the container, we add the following two lines to our gSOAP header file:

```

#include "simpleVector.h"
template <class T> class simpleVector;

```

The container class should not be defined in the gSOAP header file. It must be defined in a separate header file (e.g. "simpleVector.h"). The **template <class T> class simpleVector** declaration ensures that gSOAP will recognize **simpleVector** as a container class.

Caution: when parsing XML content the container elements may not be stored in the same order given in the XML content. When gSOAP parses XML it uses the **insert** container methods to store elements one by one. However, element content that is "forwarded" with **href** attributes will be appended to the container. Forwarding can take place with multi-referenced data that is referred to from the main part of the SOAP 1.1 XML message to the independent elements that carry **ids**. Therefore, your application should not rely on the preservation of the order of elements in a container.

11.10.9 Polymorphic Dynamic Arrays and Lists

Polymorphic arrays (arrays of polymorphic element types) can be encoded when declared as an array of pointers to class instances. and lists. For example:

```
class ns_Object
{
    public:
    ...
};
class ns_Data: public ns_Object
{
    public:
    ...
};
class ArrayOfObject
{
    public:
    ns_Object **_ptr; // pointer to array of pointers to Objects
    int _size; // number of Objects pointed to
    int _offset; // optional SOAP 1.1 array offset
};
```

The pointers in the array can point to the `ns_Object` base class or `ns_Data` derived class instances which will be serialized and deserialized accordingly in SOAP. That is, the array elements are polymorphic.

11.10.10 How to Change the Tag Names of the Elements of a SOAP Array or List

The `_ptr` field in a **struct** or **class** declaration of a dynamic array may have an optional suffix part that describes the name of the tags of the SOAP array XML elements. The suffix is part of the field name:

Type *_ptrarray_elt_name

The suffix describes the tag name to be used for all array elements. The usual identifier to XML translations apply, see Section 10.3. The default XML element tag name for array elements is `item` (which corresponds to the use of field name `_ptritem`).

Consider for example:

```
struct ArrayOfstring
{
    xsd_string *_ptrstring;    int _size; };
```

The array is serialized as:

```
<array xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="xsd:string[2]">
<string xsi:type="xsd:string">Hello</string>
<string xsi:type="xsd:string">World</string>
</array>
```

SOAP 1.1 and 1.2 do not require the use of a specific tag name for array elements. gSOAP will deserialize a SOAP array while ignoring the tag names. Certain XML Schemas used in doc/literal encoding may require the declaration of array element tag names.

11.11 Base64Binary XML Schema Type Encoding

The `base64Binary` XML Schema type is a special form of dynamic array declared with a pointer (`__ptr`) to an **unsigned char** array.

For example using a **struct**:

```
struct xsd__base64Binary
{
    unsigned char *__ptr;
    int __size;
};
```

Or with a **class**:

```
class xsd__base64Binary
{
    public:
        unsigned char *__ptr;
        int __size;
};
```

When compiled by the gSOAP stub and skeleton compiler, this header file specification will generate `base64Binary` serializers and deserializers.

The `SOAP_ENC:base64` encoding is another type for base 64 binary encoding specified by the SOAP data type schema and some SOAP applications may use this form (as indicated by their WSDL descriptions). It is declared by:

```
struct SOAP_ENC__base64
{
    unsigned char *__ptr;
    int __size;
};
```

Or with a **class**:

```
class SOAP_ENC__base64
{
    unsigned char *__ptr;
    int __size;
};
```

When compiled by the gSOAP stub and skeleton compiler, this header file specification will generate `SOAP-ENC:base64` serializers and deserializers.

The advantage of using a **class** is that methods can be used to initialize and manipulate the `__ptr` and `__size` fields. The user can add methods to this class to do this. For example:

```

class xsd__base64Binary
{
public:
    unsigned char *_ptr;
    int _size;
    xsd__base64Binary(); // Constructor
    xsd__base64Binary(struct soap *soap, int n); // Constructor
    ~xsd__base64Binary(); // Destructor
    unsigned char *location(); // returns the memory location
    int size(); // returns the number of bytes
};

```

Here are example method implementations:

```

xsd__base64Binary::xsd__base64Binary()
{
    _ptr = NULL;
    _size = 0;
}
xsd__base64Binary::xsd__base64Binary(struct soap *soap, int n)
{
    _ptr = (unsigned char*)soap_malloc(soap, n);
    _size = n;
}
xsd__base64Binary::~xsd__base64Binary()
{ }
unsigned char *xsd__base64Binary::location()
{
    return _ptr;
}
int xsd__base64Binary::size()
{
    return _size;
}

```

The following example in C/C++ reads from a raw image file and encodes the image in SOAP using the base64Binary type:

```

...
FILE *fd = fopen("image.jpg", "rb");
xsd__base64Binary image(&soap, filesize(fd));
fread(image.location(), image.size(), 1, fd);
fclose(fd);
soap_begin(&soap);
image.soap_serialize(&soap);
image.soap_put(&soap, "jpegimage", NULL);
soap_end(&soap);
...

```

where filesize is a function that returns the size of a file given a file descriptor.

Reading the xsd:base64Binary encoded image.

```

...
xsd_base64Binary image;
soap_begin(&soap);
image.get(&soap, "jpegimage");
soap_end(&soap);
...

```

The **struct** or **class** name `soap_enc_base64` should be used for `SOAP-ENC:base64` schema type instead of `xsd_base64Binary`.

11.12 hexBinary XML Schema Type Encoding

The `hexBinary` XML Schema type is a special form of dynamic array declared with the name `xsd_hexBinary` and a pointer (`_ptr`) to an **unsigned char** array.

For example, using a **struct**:

```

struct xsd_hexBinary
{
    unsigned char *_ptr;
    int _size;
};

```

Or using a **class**:

```

class xsd_hexBinary
{
public:
    unsigned char *_ptr;
    int _size;
};

```

When compiled by the gSOAP stub and skeleton compiler, this header file specification will generate `base64Binary` serializers and deserializers.

11.13 Literal XML Encoding Style

gSOAP supports SOAP RPC encoding by default. Literal encoding is optional. Just as with SOAP RPC encoding, literal encoding requires the XML Schema of the message data to be provided e.g. in WSDL in order for the gSOAP compiler to generate the (de)serialization routines. Alternatively, the optional DOM parser (`dom.c` and `dom++.cpp`) can be used to handle generic XML or arbitrary XML documents can be (de)serialized into regular C strings or wide character strings (`wchar_t*`) by gSOAP (see Section 11.13.1).

gSOAP supports literal encoding by default. The `//gsoap service encoding`, `//gsoap service method-encoding`, and `//gsoap service method-response-encoding` directives explicitly enable SOAP encoded or literal encoded messages. For example, to enable RPC encoding style for the entire service, use:

```

//gsoap ns service encoding: encoded

```

To enable encoding for particular service methods, use:

```
//gsoap ns service method-encoding: myMethod encoded
int ns_._myMethod(...)
```

To enable encoding for particular service methods responses when the method request is literal, use:

```
//gsoap ns service method-response-encoding: myMethod encoded
int ns_._myMethod(...)
```

Instead of the encoded value, you can use literal, or a specific encoding style value.

Consider the following example that uses the directive to make the literal encoding explicit. The LocalTimeByZipCode remote service method of the LocalTime service provides the local time given a zip code and uses literal encoding (with MS .NET). The following header file declares the method:

```
int LocalTimeByZipCode(char *ZipCode, char **LocalTimeByZipCodeResult);
```

Note that none of the data types need to be namespace qualified using namespace prefixes.

```
//gsoap ns service name: localtime
//gsoap ns service encoding: literal
//gsoap ns service namespace: http://alethea.net/webservices/
int ns_._LocalTimeByZipCode(char *ZipCode, char **LocalTimeByZipCodeResult);
```

In this case, the method name requires to be associated with a schema through a namespace prefix, e.g. ns is used in this example. See Section 19.2 for more details on gSOAP directives. With these directives, the gSOAP compiler generates client and server sources with the specified settings.

The example client program is:

```
#include "soapH.h"
#include "localtime.nsmap" // include generated map file
int main()
{
    struct soap soap;
    char *t;
    soap_init(&soap);
    if (soap_call_ns_._LocalTimeByZipCode(&soap, "http://alethea.net/webservices/LocalTime.asmx",
    "http://alethea.net/webservices/LocalTimeByZipCode", "32306", &t))
        soap_print_fault(&soap, stderr);
    else
        printf("Time = %s\n", t);
    return 0;
}
```

To illustrate the manual doc/literal setting, the following client program sets the required properties before the call:

```

#include "soapH.h"
#include "localtime.nsmap" // include generated map file
int main()
{
    struct soap soap;
    char *t;
    soap_init(&soap);
    soap.encodingStyle = NULL; // don't use SOAP encoding
    soap_set_omode(&soap, SOAP_XML_TREE); // don't produce multi-ref data (but can accept)
    if (soap_call_ns_LocalTimeByZipCode(&soap, "http://alethea.net/webservices/LocalTime.asmx",
    "http://alethea.net/webservices/LocalTimeByZipCode", "32306", &t))
        soap_print_fault(&soap, stderr);
    else
        printf("Time = %s\n", t);
    return 0;
}

```

The SOAP request is:

```

POST /webservices/LocalTime.asmx HTTP/1.0
Host: alethea.net
Content-Type: text/xml; charset=utf-8
Content-Length: 479
SOAPAction: "http://alethea.net/webservices/LocalTimeByZipCode"

<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
  xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  >SOAP-ENV:Body>
  <LocalTimeByZipCode xmlns="http://alethea.net/webservices/"
  <ZipCode>32306</ZipCode></LocalTimeByZipCode>
  </SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

11.13.1 Serializing and Deserializing Mixed Content XML With Strings

To declare a literal XML “type” to hold XML documents in regular strings, use:

```
typedef char *XML;
```

To declare a literal XML “type” to hold XML documents in wide character strings, use:

```
typedef wchar_t *XML;
```

Note: only one of the two storage formats can be used. The differences between the use of regular strings versus wide character strings for XML documents are:

- Regular strings for XML documents MUST hold UTF-8 encoded XML documents. That is, the string MUST contain the proper UTF-8 encoding to exchange the XML document in SOAP messages.
- Wide character strings for XML documents SHOULD NOT hold UTF-8 encoded XML documents. Instead, the UTF-8 translation is done automatically by the gSOAP runtime marshalling routines.

Here is an example of a remote method specification in which the parameters of the remote method uses literal XML encoding to pass an XML document to a service and back:

```
typedef char *XML;
ns__GetDocument(XML m_XMLDoc, XML &m_XMLDoc);
```

The `ns_`Document is essentially a **struct** that forms the root of the XML document. The use of the underscore in the `ns_`Document response part of the message avoids the name clash between the **structs**. Assuming that the namespace mapping table contains the binding of `ns` to `http://my.org/` and the binding of `m` to `http://my.org/mydoc.xsd`, the XML message is:

```
<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
  xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
  xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns:xsd="http://www.w3.org/2001/XMLSchema"
  xmlns:ns="http://my.org/"
  xmlns:m="http://my.org/mydoc.xsd"
  SOAP-ENV:encodingStyle="">
  <SOAP-ENV:Body>
    <ns:GetDocument>
      <XMLDoc xmlns="http://my.org/mydoc.xsd">
        ...
      </XMLDoc>
    </ns:Document>
  </SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```

When using literal encoding of method parameters and response as shown in the example above, the literal XML encoding style MUST be specified by setting `soap.encodingStyle`. For example, to specify no constraints on the encoding style (which is typical) use `NULL`:

```
struct soap soap;
soap_init(&soap);
soap.encodingStyle = NULL;
```

As a result, the `SOAP-ENV:encodingStyle` attribute will not appear in the SOAP payload.

For interoperability with Apache SOAP, use


```

struct soap soap;
soap_init(&soap);
soap.encodingStyle = "http://xml.apache.org/xml-soap/literalxml";

```

When the response parameter is an XML type, it will store the entire XML response content but without the enveloping response element.

The XML type can be used as part of any data structure to enable the rendering and parsing of custom XML documents. For example:

```

typedef char *XML;
struct ns__Data /* data in namespace 'ns' */
{
    int number;
    char *name;
    XML m__document; /* XML document in default namespace 'm' */
};
ns__Example(struct ns__Data data, struct ns__ExampleResponse { struct ns__Data data; } *out);

```

12 SOAP Fault Processing

A predeclared standard SOAP Fault data structure is generated by the gSOAP stub and skeleton compiler for exchanging exception messages. The built-in **struct** SOAP_ENV__Fault data structure is defined as:

```

struct SOAP_ENV__Fault
{
    _QName faultcode; // _QName is builtin
    char *faultstring;
    char *faultactor;
    struct SOAP_ENC__Detail *detail;
    struct SOAP_ENV__Code *SOAP_ENV__Code; // MUST be a SOAP_ENV__Code struct defined
below
    char *SOAP_ENV__Reason;
    char *SOAP_ENV__Node;
    char *SOAP_ENV__Role;
    struct SOAP_ENV__Detail SOAP_ENV__Detail; // SOAP 1.2 detail field
}; struct SOAP_ENV__Code
{
    _QName SOAP_ENV__Value;
    struct SOAP_ENV__Code *SOAP_ENV__Subcode; };
struct SOAP_ENV__Detail
{
    int __type; // The SOAP_TYPE_ of the object serialized as Fault detail
    void *fault; // pointer to the fault object, or NULL
    char *__any; // any other detail element content (stored in XML format)
};

```

The first four fields in SOAP_ENV__Fault are SOAP 1.1 specific. The last five fields are SOAP 1.2 specific. You can redefine these structures in the header file. For example, you can use a class for

the SOAP_ENV_ _Fault and add methods for convenience.

The data structure content can be changed to the need of an application, but this is generally not necessary because the application-specific SOAP Fault details can be serialized via the `_type` and `fault` fields in the SOAP_ENV_ _Detail field, see Section 11.8 on the serialization of data referred to by `_type` and `fault`.

The `_type` field allows application data to be serialized as part of the SOAP Fault. The application data SHOULD be defined as XML elements, which requires you to declare the type names with a leading underscore to ensure that the types are compatible with XML elements and not just `simpleTypes` and `complexType`s.

When the skeleton of a remote method returns an error (see Section 10.2), then `soap.fault` contains the SOAP Fault data at the receiving side (client).

Server-side faults are raised with `soap_sender_fault` or `soap_receiver_fault`. The `soap_sender_fault` call should be used to inform that the sender is at fault and the sender (client) should not resend the request. The `soap_receiver_fault` call should be used to indicate a temporary server-side problem, so a sender (client) can resend the request later. For example:

```
int ns1_ _myMethod(struct soap *soap, ...)
{
    ...
    return soap_receiver_fault(soap, "Resource temporarily unavailable", NULL); // return fault to
sender
}
```

In the example, the SOAP Fault details were empty (NULL). You may pass an XML fragment, which will be literally included in the SOAP Fault message. For WS-I Basic Profile compliance, you must pass an XML string with one or more namespace qualified elements, such as:

```
return soap_receiver_fault(soap, "Resource temporarily unavailable", "<errorcode xmlns='http://tempuri.org'>123</er
xmlns='http://tempuri.org'>abc</errorinfo>");
```

When a remote method must raise an exception with application SOAP Fault details, it does so by assigning the `soap.fault` field of the current reference to the runtime environment with appropriate data associated with the exception and by returning the error SOAP_FAULT. For example:

```
soap_receiver_fault(soap, "Stack dump", NULL);
if (soap->version == 2) // SOAP 1.2 is used
{
    soap->fault->SOAP_ENV_ _Detail = (struct SOAP_ENV_ _Detail*)soap_malloc(soap, sizeof(struct
SOAP_ENV_ _Detail);
    soap->fault->SOAP_ENV_ _Detail->_type = SOAP_TYPE_ns1_ _myStackDataType; // stack
type
    soap->fault->SOAP_ENV_ _Detail->fault = sp; // point to stack
    soap->fault->SOAP_ENV_ _Detail->_any = NULL; // no other XML data
}
else
{
    soap->fault->detail = (struct SOAP_ENV_ _Detail*)soap_malloc(soap, sizeof(struct SOAP_ENV_ _Detail);
```

```

        soap->fault->detail->_type = SOAP_TYPE_ns1__myStackDataType; // stack type
        soap->fault->detail->fault = sp; // point to stack
        soap->fault->detail->_any = NULL; // no other XML data
    }
    return SOAP_FAULT; // return from remote method call

```

When `soap_receiver_fault` allocates a fault struct, this data is removed with the `soap_end` call (or `soap_dealloc`). Note that the `soap_receiver_fault` function is called to allocate the fault struct and set the fault string and detail fields, i.e. `soap_receiver_fault(soap, "Stack dump", NULL)`. The advantage is that this is independent of SOAP 1.1 and SOAP 1.2. However, setting the custom detail fields requires inspecting the SOAP version used, using the `soap->version` attribute which is 1 for SOAP 1.1 and 2 for SOAP 1.2.

Each remote method implementation in a service application can return a SOAP Fault upon an exception by returning an error code, see Section 8.2.1 for details and an example. In addition, a SOAP Fault can be returned by a service application through calling the `soap_send_fault` function. This is useful in case the initialization of the application fails, as illustrated in the example below:

```

int main()
{
    struct soap soap;
    soap_init(&soap);
    some initialization code
    if (initialization failed)
    {
        soap.error = soap_receiver_fault(&soap, "Init failed", NULL); // set the error condition (SOAP_FAULT)
        soap_send_fault(&soap); // Send SOAP Fault to client
        return 0; // Terminate
    }
}

```

13 SOAP Header Processing

A predeclared standard SOAP Header data structure is generated by the gSOAP stub and skeleton compiler for exchanging SOAP messages with SOAP Headers. This predeclared data structure is:

```

struct SOAP_ENV__Header
{ void *dummy;
};

```

which declares an empty header (some C and C++ compilers don't accept empty structs so a transient dummy field is provided).

To adapt the data structure to a specific need for SOAP Header processing, a new **struct** `SOAP_ENV__Header` can be added to the header file input to the gSOAP compiler. A **class** for the SOAP Header data structure can be used instead of a **struct**.

For example, the following header can be used for transaction control:

```

struct SOAP_ENV__Header
{ char *t__transaction;
};

```

with client-side code:

```

struct soap soap;
soap_init(&soap);
...
soap.header = NULL; // do not use a SOAP Header for the request (as set with soap_init)
soap.actor = NULL; // do not use an actor (receiver is actor)
soap_call_method(&soap, ...);
if (soap.header) // a SOAP Header was received
    cout << soap.header->t__transaction;
// Can reset, modify, or set soap.header here before next call
soap_call_method(&soap, ...); // reuse the SOAP Header of the service response for the request
...

```

The SOAP Web service response can include a SOAP Header with a transaction number that the client is supposed to use for the next remote method invocation to the service. Therefore, the next request includes a transaction number:

```

...
<SOAP-ENV:Envelope ...>
<SOAP-ENV:Header>
<transaction xmlns="..." xsi:type="int">12345</transaction>
</SOAP-ENV:Header>
<SOAP-ENV:Body>
...
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

This is just an example and the transaction control is not a feature of SOAP but can be added on by the application layer to implement stateful transactions between clients and services. At the client side, the `soap.actor` attribute can be set to indicate the recipient of the header (the SOAP `SOAP-ENV:actor` attribute).

A Web service can read and set the SOAP Header as follows:

```

int main()
{
    struct soap soap;
    soap.actor = NULL; // use this to accept all headers (default)
    soap.actor = "http://some/actor"; // accept headers destined for "http://some/actor" only
    soap_serve(&soap);
}
...
int method(struct soap *soap, ...)
{
    if (soap->header) // a Header was received

```

```

    ... = soap->header->t_transaction;
else
    soap->header = soap_malloc(sizeof(struct SOAP_ENV_Header)); // alloc new header
...    soap->header->t_transaction = ...;
return SOAP_OK;
}

```

See Section 19.2 on how to generate WSDL with the proper method-to-header-part bindings.

The `SOAP-ENV:mustUnderstand` attribute indicates the requirement that the recipient of the SOAP Header (who must correspond to the `SOAP-ENV:actor` attribute when present or when the attribute has the value `SOAP-ENV:actor="http://schemas.xmlsoap.org/soap/actor/next"`) MUST handle the Header part that carries the attribute. gSOAP handles this automatically on the background. However, an application still needs to inspect the header part's value and handle it appropriately. If a remote method in a Web service is not able to do this, it should return `SOAP_MUSTUNDERSTAND` to indicate this failure.

The syntax for the header file input to the gSOAP compiler is extended with a special storage qualifier `mustUnderstand`. This qualifier can be used in the SOAP Header declaration to indicate which parts should carry a `SOAP-ENV:mustUnderstand="1"` attribute. For example:

```

struct SOAP_ENV_Header
{
    char *t_transaction;
    mustUnderstand char *t_authentication;
};

```

When both fields are set and `soap.actor="http://some/actor"` then the message contains:

```

<SOAP-ENV:Envelope ...>
<SOAP-ENV:Header>
<transaction xmlns="...">5</transaction>
<authentication xmlns="..." SOAP-ENV:actor="http://some/actor" SOAP-ENV:mustUnderstand="1">XX
</authentication>
</SOAP-ENV:Header>
<SOAP-ENV:Body>
...
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

```

14 MIME Attachments

The gSOAP toolkit supports MIME attachments as per SOAP with Attachments (SwA) specification (<http://www.w3.org/TR/SOAP-attachments>). MIME attachment data must be memory resident for sending operations and MIME attachments received will be stored in memory. DIME attachments on the other hand can be streamed and therefore DIME attachment data does not need to be stored in memory, see Section 15.

Transmitting multipart/related MIME attachments with a SOAP/XML message is accomplished with two functions, `soap_set_mime` and `soap_set_mime_attachment`. The first function is for initialization purposes and the latter function is used to specify meta data and content data for each attachment.

14.1 Sending a Collection of MIME Attachments

The following functions should be used to set up a collection of multipart/related MIME attachments for transmission with a SOAP/XML message.

Function

void `soap_set_mime(struct soap *soap, const char *boundary, const char *start)`

This function must be called first to initialize MIME attachment send operations (receives are automatic). The function specifies a MIME boundary and start content ID used for the SOAP message body. When `boundary` is NULL, an appropriate MIME boundary will be chosen (important: boundaries cannot occur in the SOAP/XML message and cannot occur in any of the MIME attachments content). When a specific boundary value is provided, gSOAP will NOT verify that the boundary is valid. When `start` is NULL, the start ID of the SOAP message is `<SOAP-ENV:Envelope>`.

int `soap_set_mime_attachment(struct soap *soap, char *ptr, size_t size, enum soap_mime_encoding encoding, const char *type, const char *id, const char *location, const char *description)`

This function adds a new attachment to the list of attachments, where `ptr` and `size` refer to the block of memory that holds the attachment data. The `encoding` parameter specifies the content encoding of this block, where the value of `encoding` is one of `SOAP_MIME_7BIT`, `SOAP_MIME_8BIT`, `SOAP_MIME_BINARY`, `SOAP_MIME_QUOTED_PRINTABLE`, `SOAP_MIME_BASE64`, `SOAP_MIME_IETF_TOKEN`, or `SOAP_MIME_X_TOKEN`. These constants reflect the content encoding defined in RFC2045 and you MUST adhere to the content encoding rules defined by RFC2045. When in doubt, use `SOAP_MIME_BINARY`, since this encoding type covers any content. The mandatory `type` string parameter is the MIME type of the data. The `id` string parameter is the content ID of the MIME attachment. The optional `location` string parameter is the content location of the attachment. The optional `description` string parameter holds a textual description of the attachment (it may not contain any control characters). All parameter values are copied, except `ptr` which must point to a valid location of the attachment data during the transfer. The value `SOAP_OK` is returned when the attachment was added. Otherwise a gSOAP error code is returned.

void `soap_clr_mime(struct soap *soap)`

Disables MIME attachments, e.g. to avoid MIME attachments to be part of a SOAP Fault response message.

When providing a MIME boundary with `soap_set_mime`, you have to make sure the boundary cannot match any SOAP/XML message content. Therefore, it is recommended to include an invalid XML sequence such as `<>`. Or you can simply pass NULL and let gSOAP select a safe boundary for you.

The internal list of attachments is destroyed with `soap_end`, you should call this function sometime after the message exchange was completed (the content of the block of memory referred to by the `ptr` parameter is unaffected).

The following example shows how a multipart/related HTTP message with three MIME attachments is set up and transmitted to a server. The first attachment contains the SOAP message. The second and third attachments contain image data. In this example we let the SOAP message body refer to the attachments using `href` attributes. The `struct claim_form` data type includes a definition of a `href` attribute for this purpose.

```

struct claim_form form1, form2;
form1.href = "cid:claim061400a.tiff@claiming-it.com";
form2.href = "cid:claim061400a.jpeg@claiming-it.com";
/* initialize and enable MIME */
soap_set_mime(soap, "MIME_boundary", "<claim061400a.xml@claiming-it.com>");
/* add a base64 encoded tiff image (tiffImage points to base64 data) */
soap_set_mime_attachment(soap, tiffImage, tiffLen, SOAP_MIME_BASE64, "image/tiff", "<claim061400a.tiff@cl
NULL, NULL);
/* add a raw binary jpeg image (jpegImage points to raw data) */
soap_set_mime_attachment(soap, jpegImage, jpegLen, SOAP_MIME_BINARY, "image/jpeg", "<claim061400a.jpeg@
NULL, NULL);
/* send the forms as MIME attachments with this invocation */
if (soap_call_claim_insurance_claim_auto(soap, form1, form2, ...))
    // an error occurred
else
    // process response

```

where the `claim_form` struct is declared in the gSOAP header file as:

```

struct claim_form
{
    @char *href;
};

```

This data type defines the parameter data of the operation. The claim forms in the SOAP/XML message consist of `hrefs` to the claim forms attached. The produced message is similar to the last example shown in the SOAP with Attachments specification (<http://www.w3.org/TR/SOAP-attachments>). Note that the use of `href` or other attributes for referring to the MIME attachments is optional.

Note: the above example assumes that the boundary `MIME_boundary` does not occur in the SOAP/XML message.

The server-side code to transmit MIME attachments back to a client is similar:

```

int claim_insurance_claim_auto(struct soap *soap, ...)
{
    soap_set_mime(soap, NULL, NULL); // enable MIME
    // add a HTML document (htmlDoc points to data, where the HTML doc is stored in compliance
    with 7bit encoding RFC2045)
    if (soap_set_mime_attachment(soap, htmlDoc, strlen(htmlDoc), SOAP_MIME_7BIT, "text/html",
    "<claim061400a.html@claiming-it.com>", NULL, NULL))
    {
        soap_clr_mime(soap); // don't want fault with attachments
        return soap->error;
    }
    return SOAP_OK;
}

```

It is also possible to attach data to a SOAP fault message.

Caution: DIME in MIME is supported. However, gSOAP will not verify whether the MIME boundary is present in the DIME attachments and therefore will not select a boundary that is

guaranteed to be unique. Therefore, you must provide a MIME boundary with `soap_set_mime` that is unique when using DIME in MIME.

14.2 Retrieving a Collection of MIME Attachments

MIME attachments are automatically parsed and stored in memory. After receiving a set of MIME attachments, either at the client-side or the server-side, the list of MIME attachments can be traversed to extract meta data and the attachment content. The first attachment in the collection of MIME attachments always contains meta data about the SOAP message itself (because the SOAP message was processed the attachment does not contain any useful data).

To traverse the list of MIME attachments in C, you use a loop similar to:

```
struct soap_multipart *attachment;
for (attachment = soap.mime.list; attachment; attachment = attachment->next)
{
    printf("MIME attachment:\n");
    printf("Memory=%p\n", (*attachment).ptr);
    printf("Size=%ul\n", (*attachment).size);
    printf("Encoding=%d\n", (int)(*attachment).encoding);
    printf("Type=%s\n", (*attachment).type?(*attachment).type:" null");
    printf("ID=%s\n", (*attachment).id?(*attachment).id:" null");
    printf("Location=%s\n", (*attachment).location?(*attachment).location:" null");
    printf("Description=%s\n", (*attachment).description?(*attachment).description:" null");
}
```

C++ programmers can use an iterator instead, as in:

```
for (soap_multipart::iterator attachment = soap.mime.begin(); attachment != soap.mime.end();
    ++attachment)
{
    cout << "MIME attachment:" << endl;
    cout << "Memory=" << (void*)(*attachment).ptr << endl;
    cout << "Size=" << (*attachment).size << endl;
    cout << "Encoding=" << (*attachment).encoding << endl;
    cout << "Type=" << ((*attachment).type?(*attachment).type:" null") << endl;
    cout << "ID=" << ((*attachment).id?(*attachment).id:" null") << endl;
    cout << "Location=" << ((*attachment).location?(*attachment).location:" null") << endl;
    cout << "Description=" << ((*attachment).description?(*attachment).description:" null") << endl;
}
```

Note: keep in mind that the first attachment is associated with the SOAP message and you may want to ignore it.

A call to `soap_end` removes all of the received MIME data. To preserve an attachment in memory, use `soap_unlink` on the `ptr` field of the `soap_multipart` struct. Recall that the `soap_unlink` function is commonly used to prevent deallocation of deserialized data.

14.3 WSDL Bindings for MIME Attachments

The `wsdl2h` WSDL parser recognizes MIME attachments and produces an annotated header file. However, the ordering of MIME parts in the `multipartRelated` elements is not reflected in the header file. Application developers should adhere the standards and ensure that `multipart/related` attachments are transmitted in compliance with the WSDL operation declarations.

As of this writing, the gSOAP compiler `soapcpp2` does not yet produce a WSDL with MIME extensions.

15 DIME Attachments

The gSOAP toolkit supports DIME attachments as per DIME specification, see for example (<http://msdn.microsoft.com/library/en-us/dnglobspec/html/draft-nielsen-dime-02.txt>)

Applications developed with gSOAP can transmit binary DIME attachments with or without streaming. Without streaming, all data is stored and retrieved in memory, which can be prohibitive when transmitting large files on small devices. In contrast with DIME streaming, data handlers are used to pass the data to and from a resource, such as a file or device. With DIME output streaming, raw binary data is send from a data source in chunks on the fly without buffering the entire content to save memory. With DIME input streaming, raw binary data will be passed to data handlers (callbacks).

15.1 Sending a Collection of DIME Attachments

The following functions should be used to set up a collection of `multipart/related` MIME attachments for transmission with a SOAP/XML message. The attachments can be streamed, as described in Section 15.4. Without streaming, each attachment must refer to a block of data in memory.

Function

void `soap_set_dime(struct soap *soap)`

This function must be called first to initialize DIME attachment send operations (receives are automatic).

int `soap_set_dime_attachment(struct soap *soap, char *ptr, size_t size, const char *type, const char *id, unsigned short otype, const char *option)`

This function adds a new attachment to the list of attachments, where `ptr` and `size` refer to the block of memory that holds the attachment data (except when DIME streaming callback handlers are used as described in Section 15.4. The `type` string parameter is the MIME type of the data. The `id` string parameter is the content ID of the DIME attachment. The `option` string parameter holds optional text (gSOAP supports DIME options, but it can send only one) and `otype` is a user-defined option type (as per DIME option specification format). All parameter values are copied, except `ptr`. The value `SOAP_OK` is returned when the attachment was added. Otherwise a gSOAP error code is returned.

void `soap_clr_mime(struct soap *soap)`

Disables DIME attachments, unless the serialized SOAP message contains attachments for transmission.

15.2 Retrieving a Collection of DIME Attachments

DIME attachments are automatically parsed and stored in memory (or passed to the streaming handlers). After receiving a set of DIME attachments, either at the client-side or the server-side, the list of DIME attachments can be traversed to extract meta data and the attachment content.

To traverse the list of DIME attachments in C, you use a loop similar to:

```
struct soap_multipart *attachment;
for (attachment = soap.dime.list; attachment; attachment = attachment->next)
{
    printf("DIME attachment:\n");
    printf("Memory=%p\n", (*attachment).ptr);
    printf("Size=%ul\n", (*attachment).size);
    printf("Type=%s\n", (*attachment).type?(*attachment).type:" null");
    printf("ID=%s\n", (*attachment).id?(*attachment).id:" null");
}
```

C++ programmers can use an iterator instead, as in:

```
for (soap_multipart::iterator attachment = soap.dime.begin(); attachment != soap.dime.end(); ++attachment)
{
    cout << "DIME attachment:" << endl;
    cout << "Memory=" << (void*)(*attachment).ptr << endl;
    cout << "Size=" << (*attachment).size << endl;
    cout << "Type=" << ((*attachment).type?(*attachment).type:" null") << endl;
    cout << "ID=" << ((*attachment).id?(*attachment).id:" null") << endl;
}
```

The options field is available as well. The options content is formatted according to the DIME specification: the first two bytes are reserved for the option type, the next two bytes store the size of the option data, followed by the (binary) option data.

A call to `soap_end` removes all of the received DIME data. To preserve an attachment in memory, use `soap_unlink` on the `ptr` field of the `soap_multipart` struct. Recall that the `soap_unlink` function is commonly used to prevent deallocation of deserialized data.

15.3 Serializing Binary Data in DIME

Binary data stored in extended `xsd:base64Binary` and `xsd:hexBinary` types can be serialized and deserialized as DIME attachments. These attachments will be transmitted prior to the sequence of secondary DIME attachments defined by the user with `soap_set_dime_attachment` as explained in the previous section. The serialization process is automated and DIME attachments will be send even when `soap_set_dime` or `soap_set_dime_attachment` are not used.

The `xsd:base64Binary` XSD type is defined in gSOAP as a struct or class by

```
struct xsd__base64Binary
{
```

```

    unsigned char *_ptr; // pointer to raw binary data
    int _size; // size of the block of data
};

```

To enable serialization of the data in DIME, we extend this type with three additional fields:

```

struct xsd__base64Binary
{
    unsigned char *_ptr;
    int _size;
    char *id;
    char *type;
    char *options;
};

```

The three additional fields consist of an `id` field for attachment referencing (typically a content id (CID) or UUID), a `type` field to specify the MIME type of the binary data, and an `options` field to piggy-back additional information with a DIME attachment. The order of the declaration of the fields is significant. In addition, no other fields or methods may be declared before any of these fields in the struct/class, but additional fields and methods may appear after the field declarations. An extended `xsd__hexBinary` declaration is similar.

The `id` and `type` fields contain text. The set the DIME-specific options field, you can use the `soap_dime_option` function:

```

char *soap_dime_option(struct soap *soap, unsigned short type, const char *option)

```

returns a string with this encoding. For example

```

struct xsd__base64Binary image;
image._ptr = ...;
image._size = ...;
image.id = "uuid:09233523-345b-4351-b623-5dsf35sgs5d6";
image.type = "image/jpeg";
image.options = soap_dime_option(soap, 0, "My wedding picture");

```

When either the `id` or `type` field values are non-NULL at run time, the data will be serialized as a DIME attachment. The SOAP/XML message refers to the attachments using `href` attributes. This generally works with SOAP RPC, because `href` attributes are permitted. However, with document/literal style the referencing mechanism must be explicitly defined in the schema of the binary type. The gSOAP declaration of an extended binary type is

```

struct ns__myBinaryDataType
{
    unsigned char *_ptr;
    int _size;
    char *id;
    char *type;
    char *options;
};

```

C++ programmers can use inheritance instead of textual extension required in C, as in

```
class xsd__base64Binary
{
    unsigned char *_ptr;
    int __size;
};
class ns__myBinaryDataType : xsd__base64Binary
{
    char *id;
    char *type;
    char *options;
};
```

This defines an extension of `xsd:base64Binary`, such that the data can be serialized as DIME attachments using `href` attributes for referencing. When a different attribute name is in fact used, it must be explicitly defined:

```
//gsoap WSref schema import: http://schemas.xmlsoap.org/ws/2002/04/reference/
struct ns__myBinaryDataType
{
    unsigned char *_ptr;
    int __size;
    char *id;
    char *type;
    char *options;
    @char *WSref__location;
};
```

The example above uses the `location` attribute defined in the content reference schema, as defined in one of the vendor's specific WSDL extensions for DIME (http://www.gotdotnet.com/team/xml_wsspecs/dime/Extension-for-DIME.htm).

When receiving DIME attachments, the DIME meta data and binary data content is stored in binary data types only when the XML parts of the message uses `href` attributes to refer to these attachments. The gSOAP toolkit may support automatic (de)serialization with other user-defined (or WSDL-defined) attributes in future releases.

Messages may contain binary data that references external resources not provided as attachments. In that case, the `_ptr` field is NULL and the `id` field refers to the external data source.

The `dime_id_format` attribute of the current gSOAP run-time environment can be set to the default format of DIME id fields. The format string MUST contain a `%d` format specifier (or any other **int**-based format specifier). The value of this specifier is a non-negative integer, with zero being the value of the DIME attachment id for the SOAP message. For example,

```
struct soap soap;
soap_init(&soap);
soap.dime_id_format = "uuid:09233523-345b-4351-b623-5dsf35sgs5d6-%x";
```

As a result, all attachments with a NULL id field will use a gSOAP-generated id value based on the format string.

Caution: Care must be taken not to introduce duplicate content id values, when assigning content id values to the id fields of DIME extended binary data types. Content ids must be unique.

15.4 Streaming DIME

Streaming DIME is achieved with callback functions to fetch and store data during transmission. Three function callbacks for streaming DIME output and three callbacks for streaming DIME input are available.

Callback (function pointer)

void (*soap.fdimereadopen)(**struct** soap *soap, **void** *handle, **const** **char** *id, **const** **char** *type, **const** **char** *options)

Called by the gSOAP run-time DIME attachment sender to start reading from a (binary) data source for outbound transmission. The content will be read from the application's data source in chunks using the `fdimeread` callback and streamed into the SOAP/XML/DIME output stream. The `handle` contains the value of the `_ptr` field of an attachment struct/class, which could be a pointer to specific information such as a file descriptor or a pointer to a string to be passed to this callback. Both `_ptr` and `_size` fields should have been set by the application prior to the serialization of the content. The `id`, `type`, and `options` arguments are the DIME id, type, and options, respectively. The callback should return `handle`, or another pointer value which will be passed as a handle to `fdimeread` and `fdimereadclose`. The callback should return `NULL` and set `soap->error` when an error occurred. The callback should return `NULL` (and not set `soap->error`) when this particular DIME attachment is not to be streamed.

size_t (*soap.fdimeread)(**struct** soap *soap, **void** *handle, **char** *buf, **size_t** len)

Called by the gSOAP run-time DIME attachment sender to read more data from a (binary) data source for streaming into the output stream. The `handle` contains the value returned by the `fdimereadopen` callback. The `buf` argument is the buffer of length `len` into which a chunk of data should be stored. The actual amount of data stored in the buffer may be less than `len` and this amount should be returned by the application. A return value of 0 indicates an error (the callback may set `soap->errnum` to `errno`). The `_size` field of the attachment struct/class should have been set by the application prior to the serialization of the content. The value of `_size` indicates the total size of the content to be transmitted. When the `_size` is zero then DIME chunked transfers can be used under certain circumstances to stream content without prior determination of attachment size, see Section 15.5 below.

void (*soap.fdimereadclose)(**struct** soap *soap, **void** *handle)

Called by the gSOAP run-time DIME attachment sender at the end of the streaming process to close the data source. The `handle` contains the value returned by the `fdimereadopen` callback. The `fdimewriteclose` callback is called after successfully transmitting the data or when an error occurred.

void (*soap.fdimewriteopen)(**struct** soap *soap, **const** **char** *id, **const** **char** *type, **const** **char** *options)

Called by the gSOAP run-time DIME attachment receiver to start writing an inbound DIME attachment to an application's data store. The content is streamed into an application data store through multiple `fdimewrite` calls from the gSOAP attachment receiver. The `id`, `type`, and `options` arguments are the DIME id, type, and options respectively. The callback should return a handle which is passed to the `fdimewrite` and `fdimewriteclose` callbacks. The `_ptr` field of the attachment struct/class is set to the value of this handle. The `_size` field is set to the total size of the attachment after receiving the entire content. The size is unknown in advance because DIME attachments may be chunked.

int (*soap.fdimewrite)(**struct** soap *soap, **void** *handle, **const** **char** *buf, **size_t** len)

Called by the gSOAP run-time DIME attachment receiver to write part of an inbound DIME attachment to an application's data store. The `handle` contains the value returned by the `fdimewriteopen` callback. The `buf` argument contains the data of length `len`. The callback should return a gSOAP error code (e.g. `SOAP_OK` when no error occurred).

void (*soap.fdimewriteclose)(**struct** soap *soap, **void** *handle)

Called by the gSOAP run-time DIME attachment receiver at the end of the streaming process to close the data store. The `fdimewriteclose` callback is called after successfully receiving the data or when an error occurred. The `handle` contains the value returned by the `fdimewriteopen` callback.

In addition, a **void***`user` field in the **struct** `soap` data structure is available to pass user-defined data to the callbacks. This way, you can set `soap.user` to point to application data that the callbacks

need such as a file name for example.

The following example illustrates the client-side initialization of an image attachment struct to stream a file into a DIME attachment:

```
int main()
{
    struct soap soap;
    struct xsd__base64Binary image;
    FILE *fd;
    struct stat sb;
    soap_init(&soap);
    if (!fstat(fileno(fd), &sb) && sb.st_size > 0)
    { // because we can get the length of the file, we can stream it
        soap.fdimereadopen = dime_read_open;
        soap.fdimereadclose = dime_read_close;
        soap.fdimeread = dime_read;
        image._ptr = (unsigned char*)fd; // must set to non-NULL (this is our fd handle which we
need in the callbacks)
        image._size = sb.st_size; // must set size
    }
    else
    { // don't know the size, so buffer it
        size_t i;
        int c;
        image._ptr = (unsigned char*)soap_malloc(&soap, MAX_FILE_SIZE);
        for (i = 0; i < MAX_FILE_SIZE; i++)
        {
            if ((c = fgetc(fd)) == EOF)
                break;
            image._ptr[i] = c;
        }
        fclose(fd);
        image._size = i;
    }
    image.type = "image/jpeg";
    image.options = soap_dime_option(&soap, 0, "My picture");
    soap_call_ns__method(&soap, ...);
    ...
}

void *dime_read_open(struct soap *soap, void *handle, const char *id, const char *type, const
char *options)
{ return handle;
}

void dime_read_close(struct soap *soap, void *handle)
{ fclose((FILE*)handle);
}

size_t dime_read(struct soap *soap, void *handle, char *buf, size_t len)
{ return fread(buf, 1, len, (FILE*)handle);
}
```

The following example illustrates the streaming of a DIME attachment into a file by a client:

```

int main()
{
    struct soap soap;
    soap_init(&soap);
    soap.fdimewriteopen = dime_write_open;
    soap.fdimewriteclose = dime_write_close;
    soap.fdimewrite = dime_write;
    soap_call_ns__method(&soap, ...);
    ...
}

void *dime_write_open(struct soap *soap, const char *id, const char *type, const char *options)
{
    FILE *handle = fopen("somefile", "wb");
    if (!handle)
    {
        soap->error = SOAP_EOF;
        soap->errnum = errno; // get reason
    }
    return (void*)handle;
}

void dime_write_close(struct soap *soap, void *handle)
{
    fclose((FILE*)handle);
}

int dime_write(struct soap *soap, void *handle, const char *buf, size_t len)
{
    size_t nwritten;
    while (len)
    {
        nwritten = fwrite(buf, 1, len, (FILE*)handle);
        if (!nwritten)
        {
            soap->errnum = errno; // get reason
            return SOAP_EOF;
        }
        len -= nwritten;
        buf += nwritten;
    }
    return SOAP_OK;
}

```

Note that compression can be used with DIME to compress the entire message. However, compression requires buffering to determine the HTTP content length header, which cancels the benefits of streaming DIME. To avoid this, you should use chunked HTTP (with the output-mode SOAP_IO_CHUNK flag) with compression and streaming DIME. At the server side, when you set SOAP_IO_CHUNK before calling `soap_serve`, gSOAP will automatically revert to buffering (SOAP_IO_STORE flag is set). You can check this flag with `(soap->iomode & SOAP_IO) == SOAP_IO_CHUNK` to see if the client accepts chunking. More information about streaming chunked DIME can be found in Section 15.5.

Caution: The options field is a DIME-specific data structure, consisting of a 4 byte header containing the option type info (hi byte, lo byte), option string length (hi byte, lo byte), followed by a non-'\0' terminated string. The gSOAP DIME handler recognizes one option at most.

15.5 Streaming Chunked DIME

gSOAP automatically handles inbound chunked DIME attachments (streaming or non-streaming). To transmit outbound DIME attachments, the attachment sizes **MUST** be determined in advance to calculate HTTP message length required to stream DIME over HTTP. However, gSOAP also supports the transmission of outbound chunked DIME attachments without prior determination of DIME attachment sizes when certain conditions are met. These conditions require either non-HTTP transport (use the output-mode `SOAP_ENC_XML` flag), or chunked HTTP transport (use the output-mode `SOAP_IO_CHUNK` flag). You can also use the `SOAP_IO_STORE` flag (which is also used automatically with compression to determine the HTTP content length header) but that cancels the benefits of streaming DIME.

To stream chunked DIME, set the `_size` field of an attachment to zero and enable HTTP chunking. The DIME `fdimeread` callback then fetches data in chunks and it is important to fill the entire buffer unless the end of the data has been reached and the last chunk is to be send. That is, `fdimeread` should return the value of the last `len` parameter and fill the entire buffer `buf` for all chunks except the last.

15.6 WSDL Bindings for DIME Attachments

The `wsdl2h` WSDL parser recognizes DIME attachments and produces an annotated header file. Both open and closed layouts are supported for transmitting DIME attachments. For closed formats, all DIME attachments must be referenced from the SOAP message, e.g. using hrefs with SOAP encoding and using the application-specific reference attribute included in the `base64Binary` struct/class for doc/lit.

As of this writing, the gSOAP compiler `soapcpp2` does not yet produce a WSDL with DIME extensions.

16 MTOM Attachments

MTOM (Message Transmission Optimization Mechanism) is a relatively new format for transmitting attachments with SOAP messages (see <http://www.w3.org/TR/soap12-mtom>). MTOM is a W3C working draft as of this writing. MTOM attachments are essentially MIME attachments with standardized mechanisms for cross referencing attachments from the SOAP body, which is absent in (plain) MIME attachments and optional with DIME attachments.

Unlike the name suggests, the speed by which attached data is transmitted is not increased compared to MIME, DIME, or even XML encoded base64 data (at least the performance differences in gSOAP will be small). The advantage of the format is the standardized attachment reference mechanism, which should improve interoperability.

The MTOM specification mandates SOAP 1.2 and the use of the XOP namespace. The XOP Include element `xop:Include` is used to reference attachment(s) from the SOAP message body.

Because references from within the SOAP message body to attachments are mandatory with MTOM, the implementation of the serialization and deserialization of MTOM MIME attachments

in gSOAP uses the extended binary type comparable to DIME support in gSOAP. This binary type is predefined in the `import/xop.h` file:

```
//gsoap xop schema import: http://www.w3.org/2004/08/xop/include
struct _xop_Include
{
    unsigned char *_ptr;
    int _size;
    char *id;
    char *type;
    char *options;
};
typedef struct _xop_Include _xop_Include;
```

The additional `id`, `type`, and `option` fields enable MTOM attachments for the data pointed to by `_ptr` of size `_size`. The process for sending and receiving MTOM XOP attachments is fully automated. Streaming techniques however, such as for DIME are not (yet) available. The `id` field references the attachment (typically a content id CID or UUID). When set to NULL, gSOAP assigns a unique CID. The `type` field specifies the required MIME type of the binary data, and the optional `options` field can be used to piggy-back descriptive text with an attachment. The order of the declaration of the fields is significant.

You can explicitly import the `xop.h` in your header file to use the MTOM attachments in your service, for example:

```
#import "import/soap12.h"
/* alternatively, without the import above, use:
//gsoap SOAP-ENV schema namespace: http://www.w3.org/2003/05/soap-envelope
//gsoap SOAP-ENC schema namespace: http://www.w3.org/2003/05/soap-encoding
/
#import "import/xop.h"
#import "import/xmlmime.h"

//gsoap x schema namespace: http://my.first.mtom.net
struct x_myData
{
    _xop_Include xop_Include; // attachment
    @char *xmlmime_contentType; // and its contentType
};
int x_myMTOMtest(struct x_myData *in, struct x_myData *out);
```

As you can see, there is really no difference between the specification of MTOM and DIME attachments in a gSOAP header file. Except that you MUST use SOAP 1.2 and the `xop_Include` element.

When an instance of `x_myDataType` is serialized and either or both the `id` and `type` fields are non-NULL, the data is transmitted as MTOM MIME attachment if the `SOAP_ENC_MTOM` flag is set in the gSOAP's `soap` struct context:

```
struct soap *soap = soap_new1(SOAP_ENC_MTOM);
```

Without this flag, the attachments will be transmitted in DIME format (Section 15). If your current clients and services are based on non-streaming DIME attachments using the SOAP body reference mechanism (thus, without using the `soap_set_dime_attachment` function) or plain base64 binary XML data elements, it is very easy to adopt MTOM by renaming the binary types to `xop_include` and using the `SOAP_ENC_MTOM` flag with the SOAP 1.2 namespace.

16.1 Generating Multipart-Related MIME Attachment Bindings in WSDL

To generate multipart-related bindings in the WSDL file, use the `//gsoap ... service method-mime-type` directive (see also Section 19.2). The directive can be repeated for each attachment you want to associate with a method's request and response messages.

For example:

```
#import "import/soap12.h"
#import "import/xop.h"
#import "import/xmlmime.h"

//gsoap x schema namespace: http://my.first.mtom.net
struct x_myData
{
    _xop_include xop_include; // attachment
    @char *xmlmime_contentType; // and its contentType
};
//gsoap x service method-mime-type: myMTOMtest text/xml
int x_myMTOMtest(struct x_myData *in, struct x_myData *out);
```

The `//gsoap x service method-mime-type` directive indicates that this operation accepts `text/xml` MIME attachments. See the SOAP-with-Attachment specification for the MIME types to use (for example, `/*` is a wildcard). If the operation has more than one attachment, just repeat this directive for each attachment you want to bind to the operation.

To bind attachments only to the request message of an operation, use `//gsoap x service method-input-mime-type`. Similarly, to bind attachments only to the response message of an operation, use `//gsoap x service method-output-mime-type`.

16.2 Sending and Receiving MTOM Attachments

A receiver must be told to recognize MTOM attachments by setting the `SOAP_ENC_MTOM` flag of the gSOAP context. Otherwise, the regular MIME attachment mechanism will be used to store attachments and in this process the references from the SOAP message body to the attachments are lost.

When using `wsdl2h` to build clients and/or services, you should use the `typemap.dat` file included in the distribution package. The `typemap.dat` file defines the XOP namespace and XML MIME namespaces as imported namespaces:

```
xop = <http://www.w3.org/2004/08/xop/include>
xmime = <http://www.w3.org/2004/06/xmlmime>
xmlmime = <http://www.w3.org/2004/11/xmlmime>
```

The `wsdl2h` tool uses the `typemap.dat` file (see also option `-t`) to convert WSDL into a gSOAP header file. In this case we don't want the `wsdl2h` tool to read the XOP schema and translate it, since we have a special `_xop_Include` element already defined in `xop.h`. Therefore, the above bindings will not translate the XOP and XML MIME schemas, but instead generates `#import` statements:

```
#import "xop.h"
#import "xmlmime.h"
```

The `#import` statements are only added for those namespaces that are actually used by the service. Let's take a look at an example. The `wsdl2h` importer generates a header file with `#import "xop.h"` from a WSDL that references XOP, for example:

```
#import "xop.h"
#import "xmlmime.h"
struct ns_ _Data
{
    _xop_Include xop_Include;
    @char *xmlmime_ContentType;
};
```

Suppose the WSDL defines an operation:

```
int ns_ _echoData(struct ns_ _Data *in, struct ns_ _Data *out);
```

After generating the stubs/proxies with the `soapcpp2` compiler, we can invoke the stub at the client side with:

```
struct soap *soap = soap_new1(SOAP_ENC_MTOM);
struct ns_ _Data data;
data.xop_Include._ptr = (unsigned char*)"<b>Hello world!</b>";
data.xop_Include._size = 20;
data.xop_Include.id = NULL; // CID automatically generated by gSOAP engine
data.xop_Include.type = "text/html"; // MIME type
data.xop_Include.options = NULL; // no descriptive info added
data.xmlmime_ContentType = "text/html"; // MIME type
if (soap_call_ns_ _echoData(soap, endpoint, action, &data, &data))    soap_print_fault(soap, stderr);
else
    printf("Got data\n");
soap_destroy(soap); // remove deserialized class instances (C++ only)
soap_end(soap); // remove temporary and deserialized data
soap_done(soap); // detach
free(soap);
```

Note that the `xop_Include.type` field must be set to transmit MTOM attachments, otherwise plain base64 XML will be used.

At the server side, we can implement an operation handler that just copies the input data to output to implement the echo operation as follows:

```

int ns__echoData(struct soap *soap, struct ns__Data *in, struct ns__data *out)
{
    *out = *in;
    return SOAP_OK;
}

```

The server must use the SOAP_ENC_MTOM flag to initialize the soap struct to receive and send MTOM attachments.

17 XML Validation

The gSOAP XML parser applies basic rules to validate content. However, occurrence constraints are not automatically verified unless explicitly indicated. This helps to avoid interoperability problems with toolkits that do not strictly enforce validation rules. In addition, we cannot always use strict validation for SOAP RPC encoded messages, since SOAP RPC encoding adopts a very loose serialization format.

Validation constraints are checked by gSOAP with the SOAP_XML_STRICT input mode flag set, e.g. with `soap_set_imode(soap, SOAP_XML_STRICT)` or `soap_new(SOAP_XML_STRICT)`, see Section 9.12 for a complete list of flags.

17.1 Occurrence Constraints

17.1.1 Elements with minOccurs and maxOccurs Restrictions

To force the validation of minOccurs and maxOccurs constraints the SOAP_XML_STRICT input mode flag must be set. The minOccurs and maxOccurs constraints are specified for fields of a struct and members of a class in a header file using the following syntax:

Type fieldname [minOccurs[:maxOccurs]] [= value]

The minOccurs and maxOccurs values must be integer literals. A default value can be provided when minOccurs is zero. Default values must be primitive types, integer, float, string, etc. By default the minOccurs constraint is zero.

For example

```

struct ns__MyRecord
{
    int n = 5; // element with default value 5, minOccurs=0, maxOccurs=1
    int m 1; // element with minOccurs=1
    int _size 0:10; // sequence jitem_ with minOccurs=0, maxOccurs=10
    int *item;
    std::vector<double> nums 2; // sequence jnums_ with minOccurs=2, maxOccurs=unbounded
};
struct arrayOfint
{
    int *_ptr 1:100; // minOccurs=1, maxOccurs=100
}

```

```

    int size;
};

```

Pointer-based struct fields and class members are allowed to be nillable when minOccurs is zero.

17.1.2 Required and Prohibited Attributes

Similar to the minOccurs and maxOccurs annotations defined in the previous section, attributes in a struct or class can be annotated with occurrence constraints to make them optional (0), required (1), or prohibited (0:0). Default values can be assigned to optional attributes.

For example

```

struct ns_._MyRecord
{
    @int m 1; // required attribute (occurs at least once)
    @int n = 5; // optional attribute with default value 5
    @int o 0; // optional attribute (may or may not occur)
    @int p 0:0; // prohibited attribute
};

```

Remember to set the SOAP_XML_STRICT input mode flag to enable the validation of attribute occurrence constraints.

17.1.3 Data Length Restrictions

A schema simpleType is defined with a **typedef** by taking a base primitive to defined a derived simpleType. For example:

```

typedef int time._seconds;

```

This defines the following schema type in time.xsd:

```

<simpleType name="seconds">
  <restriction base="xsd:int"/>
</simpleType>

```

A complexType with simpleContent is defined with a wrapper struct/class:

```

struct time._date
{
    char *_item; // some custom format date (restriction of string)
    @enum time._zone { EST, GMT, ... } zone;
}

```

This defines the following schema type in time.xsd:

```

<complexType name="date">
  <simpleContent>
    <extension base="xsd:string"/>
  </simpleContent>
  <attribute name="zone" type="time:zone" use="optional"/>
</complexType> <simpleType name="zone">
  <restriction base="xsd:string">
    <enumeration value="EST"/>
    <enumeration value="GMT"/>
    ...
  </restriction>
</simpleType>

```

Data value length constraints of simpleTypes and complexTypes with simpleContent are defined as follows.

```

typedef char *ns__string256 0:256; // simpleType restriction of string with max length 256 characters
typedef char *ns__string10 10:10; // simpleType restriction of string with length of 10 characters
typedef std::string *ns__string8 8; // simpleType restriction of string with at least 8 characters
struct ns__data
{
  char *__item :256; // simpleContent with at most 256 characters
  @char *name 1; // required name attribute
}; struct time__date
{
  char *__item :100;  @enum time__zone { EST, GMT, ... } zone = GMT;
}

```

Remember to set the SOAP_XML_STRICT input mode flag to enable the validation of value length constraints.

17.2 Other Constraints

To associate a pattern with a simpleType, you can define a simpleType with a **typedef** and a pattern string:

```

typedef int time__second "[1-5]?[0-9]—60";

```

This defines the following schema type in time.xsd:

```

<simpleType name="second">
  <restriction base="xsd:int">
    <pattern value="[1-5]?[0-9] |60"/>
  </restriction base="xsd:int"/>
</simpleType>

```

The pattern string MUST contain a valid regular expression. Patterns are currently not checked in the validation process.

18 SOAP-over-UDP

UDP is a simple, unreliable datagram protocol: UDP sockets are connectionless. UDP address formats are identical to those used by TCP. In particular UDP provides a port identifier in addition to the normal Internet address format. The UDP port space is separate from the TCP port space (i.e. a UDP port may not be “connected” to a TCP port). In addition broadcast packets may be sent (assuming the underlying network supports this) by using a reserved “broadcast address”; this address is network interface dependent.

To enable SOAP-over-UDP with gSOAP, `stdsoap2.c` and `stdsoap2.cpp` MUST be compiled with `-DWITH_UDP` prior to linking with your application.

Client-side messages with SOAP-over-UDP endpoint URLs (`soap.udp://...`) will be automatically transmitted as datagrams. Server-side applications should set the `SOAP_IO_UDP` mode flag to accept UDP requests, e.g. using `soap_init1` or `soap_set_mode`.

The maximum message length for datagram packets is restricted by the buffer size `SOAP_BUFLLEN`, which is 65536 by default, unless compiled with `WITH_LEAN` to support small-scale embedded systems. For UDP transport `SOAP_BUFLLEN` must not exceed the maximum UDP packet size 65536 (the size of datagram messages is constrained by the UDP packet size $2^{16} = 65536$ as per UDP standard). You can use gzip compression to reduce the message size, but note that compressed SOAP-over-UDP is a gSOAP-specific feature because it is not part of the SOAP-over-UDP specification.

The SOAP-over-UDP specification relies on WS-Addressing. The `wsa.h` file in the `import` directory defines the WS-Addressing elements for client and server applications.

The gSOAP implementation conforms to the SOAP-over-UDP requirements:

- SOAP-over-UDP server endpoint URL format: `soap.udp://host:port/path`
- Support one-way message-exchange pattern (MEP) where a SOAP envelope is carried in a user datagram.
- Support request-response message-exchange pattern (MEP) where SOAP envelopes are carried in user datagrams.
- Support multicast transmission of SOAP envelopes carried in user datagrams.
- Support both SOAP 1.1 and SOAP 1.2 envelopes.

The following additional features are also available, but are not supported by the SOAP-over-UDP specification:

- Zlib/gzip message compression (compile `-DWITH_GZIP`).
- SOAP with DIME attachments over UDP.
- SOAP with MIME attachments (SwA) over UDP.
- Support for IPv6 (compile `-DWITH_IPV6`)

18.1 Using WS-Addressing with SOAP-over-UDP

A SOAP-over-UDP application **MUST** use WS-Addressing to control message delivery as per SOAP-over-UDP specification.

The `wsa.h` file in the `import` directory defines the WS-Addressing elements. To include the WS-Addressing elements in the SOAP Header for messaging, a **struct** `SOAP_ENV__Header` structure must be defined in your header file with the appropriate WS-Addressing elements. For example:

```
#import "wsa.h"
struct SOAP_ENV__Header
{
    mustUnderstand _wsa__MessageID wsa__MessageID 0;
    mustUnderstand _wsa__RelatesTo *wsa__RelatesTo 0;
    mustUnderstand _wsa__From *wsa__From 0;
    mustUnderstand _wsa__ReplyTo *wsa__ReplyTo 0;
    mustUnderstand _wsa__FaultTo *wsa__FaultTo 0;
    mustUnderstand _wsa__To wsa__To 0;
    mustUnderstand _wsa__Action wsa__Action 0;
};
```

We also included a `//gsoap wsa schema import` directive in the `wsa.h` file to enable the generation of WSDL specifications that import (instead of includes) the WS-Addressing elements. Note that the `//gsoapopt w` directive must not be present in your header file to enable WSDL generation.

One-way SOAP-over-UDP messages (see Section 8.3) should be declared to include the `wsa:MessageID`, `wsa:To`, and `wsa:Action` elements in the SOAP Header of the request message as follows:

```
//gsoap ns service method-header-part: sendString wsa__MessageID
//gsoap ns service method-header-part: sendString wsa__To
//gsoap ns service method-header-part: sendString wsa__Action
int ns__sendString(char *str, void);
```

Request-response SOAP-over-UDP messages should be declared to include the `wsa:MessageID`, `wsa:To`, `wsa:Action`, and `wsa:ReplyTo` elements in the SOAP Header of the request message, and the `wsa:MessageID`, `wsa:To`, `wsa:Action`, and `wsa:RelatesTo` elements in the SOAP Header of the response message:

```
//gsoap ns service method-header-part: echoString wsa__MessageID
//gsoap ns service method-header-part: echoString wsa__To
//gsoap ns service method-header-part: echoString wsa__Action
//gsoap ns service method-input-header-part: sendString wsa__ReplyTo
//gsoap ns service method-output-header-part: echoString wsa__RelatesTo
int ns__echoString(char *str, char **res);
```

For the content requirements of these elements, please consult the SOAP-over-UDP specification and/or read the next sections explaining SOAP-over-UDP unicast, multicast, one-way, and request-response client and server applications.

18.2 Client-side One-way Unicast

This example assumes that the gSOAP header file includes the SOAP Header with WS-Addressing elements and the `ns_`sendString function discussed in Section 18.1

```
struct soap soap;
struct SOAP_ENV__Header header; // the SOAP Header
soap_init(&soap);
soap.send_timeout = 1; // 1s timeout
soap.default_SOAP_ENV__Header(&soap, &header); // init SOAP Header
header.wsa__MessageID = "message ID";
header.wsa__To = "server URL";
header.wsa__Action = "server action";
soap.header = &header; // bind the SOAP Header for transport
// Send the message over UDP:
if (soap_send_ns_
```

echoString(&soap, "soap.udp://...", NULL, "hello world!"))
 soap_print_fault(&soap, stderr); // report error
 soap_end(&soap); // cleanup
 soap_destroy(&soap); // cleanup
 soap_done(&soap); // close connection (should not use soap struct after this)

18.3 Client-side One-way Multicast

This example is similar to the one-way unicast example discussed above, but uses a broadcast address and the `SO_BROADCAST` socket option:

```
struct soap soap;
struct SOAP_ENV__Header header; // the SOAP Header
soap_init(&soap);
soap.send_timeout = 1; // 1s timeout
soap.connect_flags = SO_BROADCAST; // required for broadcast
soap.default_SOAP_ENV__Header(&soap, &header); // init SOAP Header
header.wsa__MessageID = "message ID";
header.wsa__To = "server URL";
header.wsa__Action = "server action";
soap.header = &header; // bind the SOAP Header for transport
// Send the message over UDP to a broadcast address:
if (soap_send_ns_
```

echoString(&soap, "soap.udp://...", NULL, "hello world!"))
 soap_print_fault(&soap, stderr); // report error
 soap_end(&soap); // cleanup
 soap_destroy(&soap); // cleanup
 soap_done(&soap); // close connection (should not use soap struct after this)

18.4 Client-side Request-Response Unicast

This example assumes that the gSOAP header file includes the SOAP Header with WS-Addressing elements and the `ns_`echoString function discussed in Section 18.1

```
struct soap soap;
struct SOAP_ENV__Header header; // the SOAP Header
```

```

struct wsa_EndpointReferenceType replyTo; // (anonymous) reply address
char *res; // server response
soap_init(&soap);
soap.send_timeout = 1; // 1s timeout
soap.recv_timeout = 1; // 1s timeout
soap_default_SOAP_ENV_Header(&soap, &header); // init SOAP Header
soap_default_wsa_EndpointReferenceType(&soap, &replyTo); // init reply address
replyTo.Address = "http://schemas.xmlsoap.org/ws/2004/08/addressing/role/anonymous";
header.wsa_MessageID = "message ID";
header.wsa_To = "server URL";
header.wsa_Action = "server action";
header.wsa_ReplyTo = &replyTo;
soap.header = &header; // bind the SOAP Header for transport
// Send and receive messages over UDP:
if (soap_call_ns_echoString(&soap, "soap.udp://...", NULL, "hello world!", &res))
{
    if (soap.error == SOAP_EOF && soap.errnum == 0)
        // Timeout: no response from server (message already delivered?)
    else
        soap_print_fault(&soap, stderr);
}
else
    // UDP server response is stored in 'res'
    // check SOAP header received, if applicable
    check_header(&soap.header);
    soap_end(&soap); // cleanup
    soap_destroy(&soap); // cleanup
    soap_done(&soap); // close connection (should not use soap struct after this)

```

18.5 Client-side Request-Response Multicast

This example is similar to the request-response unicast example discussed above, but uses a broadcast address and the `SO_BROADCAST` socket option. Because we expect to receive multiple responses, we also need to use separate request-response messages to send one request and consume multiple responses. In this example we defined a `bcastString` request and a `bcastStringResponse` response message, which are essentially declared as one-way messages in the header file:

```

//gsoap ns service method-header-part: bcastString wsa_MessageID
//gsoap ns service method-header-part: bcastString wsa_To
//gsoap ns service method-header-part: bcastString wsa_Action
//gsoap ns service method-header-part: bcastString wsa_ReplyTo
int ns_bcastString(char *str, void);
//gsoap ns service method-header-part: bcastStringResponse wsa_MessageID
//gsoap ns service method-header-part: bcastStringResponse wsa_To
//gsoap ns service method-header-part: bcastStringResponse wsa_Action
//gsoap ns service method-header-part: bcastStringResponse wsa_RelatesTo
int ns_bcastStringResponse(char *res, void);

```

The client code includes a loop to receive response messages until a timeout occurs:

```

struct soap soap;
struct SOAP_ENV__Header header;
struct wsa__EndpointReferenceType replyTo;
char *res;
soap_init(&soap);
soap.connect_flags = SO_BROADCAST;
soap.send_timeout = 1; // 1s timeout
soap.recv_timeout = 1; // 1s timeout
soap.default_SOAP_ENV__Header(&soap, &header);
soap.header = &header;
soap.default_wsa__EndpointReferenceType(&soap, &replyTo);
replyTo.Address = "http://schemas.xmlsoap.org/ws/2004/08/addressing/role/anonymous";
header.wsa__MessageID = "message ID";
header.wsa__To = "server URL";
header.wsa__Action = "server action";
header.wsa__ReplyTo = &replyTo;
if (soap_send_ns__bcastString(&soap, "soap.udp://...", NULL, "hello world!"))
    soap_print_fault(&soap, stderr);
else
{
    for (;;)
    {
        if (soap_recv_ns__bcastStringResponse(&soap, &res))
            break;
        // Got response 'res' from a server
    }
    if (soap.error == SOAP_EOF && soap.errnum == 0)
        // Timeout: no more messages received
    else
        soap_print_fault(&soap, stderr);
}
soap_end(&soap); // cleanup
soap_destroy(&soap); // cleanup
soap_done(&soap); // close connection (should not use soap struct after this)

```

Note that a server for the `bcastString` does not need to use two-way messages. Thus, multicast request-response message pattern can be declared and implemented as request-response operations at the server side.

18.6 SOAP-over-UDP Server

The following example code illustrates a SOAP-over-UDP server for one-way `sendString` and request-response `echoString` messages. This example assumes that the `gSOAP` header file includes the `SOAP` Header with WS-Addressing elements and the `ns__echoString` function discussed in Section 18.1.

```

main()
{
    struct soap soap;
    soap_init1(&soap, SOAP_IO_UDP); // must set UDP flag
    // bind to host (NULL=current host) and port:

```

```

if (!soap_valid_socket(soap_bind(&soap, host, port, 100)))
{
    soap_print_fault(&soap, stderr);
    exit(1);
}
for (;;)
{
    if (soap_serve(&soap))
        soap_print_fault(&soap, stderr); // report the problem
    soap_destroy(&soap);
    soap_end(&soap);
}
soap_done(&soap); // close connection
}
int ns__echoString(struct soap *soap, char *str, char **res)
{
    if (!soap->header)
        return soap_sender_fault(soap, "No SOAP header", NULL);
    if (!soap->header->wsa__MessageID)
        return soap_sender_fault(soap, "No WS-Addressing MessageID", NULL);
    soap->header->wsa__RelatesTo = (struct wsa__Relationship*)soap_malloc(soap, sizeof(struct
wsa__Relationship));
    soap_default_wsa__Relationship(soap, soap->header->wsa__RelatesTo);
    soap->header->wsa__RelatesTo->_item = soap->header->wsa__MessageID;
    // must check for duplicate messages
    if (check_received(soap->header->wsa__MessageID))
    {
        // Request message already received
        return SOAP_STOP; // don't return response
    }
    if (!soap->header->wsa__ReplyTo || !soap->header->wsa__ReplyTo->Address)
        return soap_sender_fault(soap, "No WS-Addressing ReplyTo address", NULL);
    soap->header->wsa__To = soap->header->wsa__ReplyTo->Address;
    soap->header->wsa__MessageID = soap_strdup(soap, soap_int2s(soap, id_count++)) ;
    soap->header->wsa__Action = "http://genivia.com/udp/echoStringResponse";
    *res = str;
    return SOAP_OK;
}
int ns__sendString(struct soap *soap, char *str)
{
    if (!soap->header)
        return SOAP_STOP;
    if (!soap->header->wsa__MessageID)
        return SOAP_STOP;
    // must check for duplicate messages
    if (check_received(soap->header->wsa__MessageID))
        return SOAP_STOP;
    return SOAP_OK;
}
int ns__sendStringResponse(struct soap *soap, char *res)
{ return SOAP_NO_METHOD; } // we don't expect to serve this message

```

The server binds to a host and port and accepts messages in a tight sequential loop. Because UDP does not have the equivalent of an accept the messages cannot be dispatched to threads, the `soap_serve` waits for a message and immediately accepts it. You can use a receive timeout to make `soap_serve` non-blocking.

19 Advanced Features

19.1 Internationalization

gSOAP uses regular strings by default. Regular strings cannot be used to hold UCS characters outside of the character range [1,255]. gSOAP can handle wide-character content in two ways. First, applications can utilize wide-character strings (`wchar_t*`) instead of regular strings to store wide-character content. For example, the `xsd:string` string schema type can be declared as a wide-character string and used subsequently:

```
typedef wchar_t *xsd__string;
...
int ns__myMethod(xsd__string input, xsd__string *output);
```

Second, regular strings can be used to hold wide-character content in UTF-8 format. This is accomplished with the `SOAP_C_UTFSTRING` flag (for both input/output mode), see Section 9.12. With this flag set, gSOAP will deserialize XML into regular strings in UTF-8 format. An application is responsible for filling regular strings with UTF-8 content to ensure that strings can be correctly serialized XML. Third, the `SOAP_C_MBSTRING` flag (for both input/output mode) can be used to activate multibyte character support. Multibyte support depends on the locale settings for dealing with extended natural language encodings.

Both regular strings and wide-character strings can be used together within an application. For example, the following header file declaration introduces two string schema types:

```
typedef wchar_t *xsd__string;
typedef char *xsd__string_; // trailing '_' avoids name clash
...
int ns__myMethod(xsd__string input, xsd__string_ *output);
```

The input string parameter is a wide-character string and the output string parameter is a regular string. The regular string has UCS character content in the range [1,255] unless the `SOAP_C_UTFSTRING` flag is set. With this flag, the string has UTF-8 encoded content.

Please consult the UTF-8 specification for details on the UTF-8 format. Note that the ASCII character set [1-127] is a subset of UTF-8. Therefore, with the `SOAP_C_UTFSTRING` flag set, strings may hold ASCII character data and UTF-8 extensions.

19.2 Customizing the WSDL and Namespace Mapping Table File Contents With gSOAP Directives

A header file can be augmented with directives for the gSOAP Stub and Skeleton compiler to automatically generate customized WSDL and namespace mapping tables contents. The WSDL

and namespace mapping table files do not need to be modified by hand (Sections 8.2.8 and 10.4). In addition, the sample SOAP/XML request and response files generated by the compiler are valid provided that XML Schema namespace information is added to the header file with directives so that the gSOAP compiler can produce example SOAP/XML messages that are correctly namespace qualified. These compiler directives are specified as `//`-comments. (Note: blanks can be used anywhere in the directive, except between `//` and `gsoap`.)

Three directives are currently supported that can be used to specify details associated with namespace prefixes used by the remote method names in the header file. To specify the name of a Web Service in the header file, use:

```
//gsoap namespace-prefix service name: service-name
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *service-name* is the name of a Web Service (only required to create new Web Services). The name may be followed by text up to the end of the line which is incorporated into the WSDL service documentation. Alternatively, the service documentation can be provided with the directive below.

To specify the name of the WSDL definitions in the header file, use:

```
//gsoap namespace-prefix service definitions: definitions-name
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *definitions-name* is the name of the WSDL definitions. By default, the WSDL definitions name is the same as the service name.

To specify the documentation of a Web Service in the header file, use:

```
//gsoap namespace-prefix service documentation: text
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *text* is the documentation text up to the end of the line. The text is incorporated into the WSDL service documentation.

To specify the portType of a Web Service in the header file, use:

```
//gsoap namespace-prefix service portType: portType-name
```

or

```
//gsoap namespace-prefix service type: portType-name
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *portType-name* is the portType name of the WSDL service portType.

To specify the binding name of a Web Service in the header file, use:

```
//gsoap namespace-prefix service binding: binding-name
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *binding-name* is the binding name of the WSDL service binding element. By default, the binding name is the same as the service name.

To specify the binding's transport protocol of a Web Service in the header file, use:

```
//gsoap namespace-prefix service transport: transport-URL
```

where *namespace-prefix* is a namespace prefix used by identifiers in the header file and *transport-URL* is the URL of the transport protocol such as `http://schemas.xmlsoap.org/soap/http` for HTTP. HTTP transport is assumed by default.

To specify the location (or port endpoint) of a Web Service in the header file, use:

```
//gsoap namespace-prefix service location: URL
```

or alternatively

```
//gsoap namespace-prefix service port: URL
```

where *URL* is the location of the Web Service (only required to create new Web Services). The *URL* specifies the path to the service executable (so *URL/service-executable* is the actual location of the executable when declared).

To specify the name of the executable of a Web Service in the header file, use:

```
//gsoap namespace-prefix service executable: executable-name
```

where *executable-name* is the name of the executable of the Web Service.

When doc/literal encoding is required for the entire service, the service encoding can be specified in the header file as follows:

```
//gsoap namespace-prefix service encoding: literal
```

or when the `SOAP-ENV:encodingStyle` attribute is different from the SOAP 1.1/1.2 encoding style:

```
//gsoap namespace-prefix service encoding: encoding-style
```

To specify the namespace URI of a Web Service in the header file, use:

```
//gsoap namespace-prefix service namespace: namespace-URI
```

where *namespace-URI* is the URI associated with the namespace prefix.

In addition, the schema namespace URI can be specified in the header file:

```
//gsoap namespace-prefix schema namespace: namespace-URI
```


where *namespace-URI* is the schema URI associated with the namespace prefix. If present, it defines the schema-part of the generated WSDL file and the URI in the namespace mapping table. This declaration is useful when the service declares its own data types that need to be associated with a namespace. Furthermore, the header file for client applications do not need the full service details and the specification of the schema namespaces for namespace prefixes suffices.

The directive above specifies a new schema and the gSOAP compiler generates a schema files (.xsd) file for the schema. An existing schema namespace URI can be imported with:

```
//gsoap namespace-prefix schema import: namespace-URI
```

where *namespace-URI* is the schema URI associated with the namespace prefix. gSOAP does not produce XML Schema files for imported schemas and imports the schema namespaces in the generated WSDL file.

A schema namespace URI can be imported from a location with:

```
//gsoap namespace-prefix schema namespace: namespace-URI  
//gsoap namespace-prefix schema import: schema-location
```

The `elementFormDefault` and `attributeFormDefault` qualification of a schema can be defined with:

```
//gsoap namespace-prefix schema elementForm: qualified  
//gsoap namespace-prefix schema attributeForm: qualified
```

or:

```
//gsoap namespace-prefix schema elementForm: unqualified  
//gsoap namespace-prefix schema attributeForm: unqualified
```

A shortcut to define the default qualification of elements and attributes of a schema:

```
//gsoap namespace-prefix schema form: qualified
```

or:

```
//gsoap namespace-prefix schema form: unqualified
```

To document a data type, use:

```
//gsoap namespace-prefix schema type-documentation: type-name //text
```

where *type-name* is the unqualified name of the data type and *text* is a line of text terminated by a newline. Do not use any XML reserved characters in *text* such as `<` and `>`. Use well-formed XML and XHTML markup instead. For example:

```
//gsoap ns schema type-documentation: tdata stores <a href="transaction.html">transaction</a>  
data  
class ns_tdata  
{ ... }
```

To document a method, use:

```
//gsoap namespace-prefix service method-documentation: method-name //text
```

where *method-name* is the unqualified name of the method and *text* is a line of text terminated by a newline. Do not use any XML reserved characters in *text* such as < and >. Use well-formed XML and XHTML markup instead. For example:

```
//gsoap ns service method-documentation: getQuote returns a <i>stock quote</i>  
int ns._getQuote(char *symbol, float &_result);
```

To specify the SOAPAction for a method, use:

```
//gsoap namespace-prefix service method-action: method-name action
```

where *method-name* is the unqualified name of the method and *action* is a quoted or non-quoted string (spaces and blanks are not allowed). For example:

```
//gsoap ns service method-action: getQuote ""  
int ns._getQuote(char *symbol, float &_result);
```

When document style is preferred for a particular service method, use:

```
//gsoap namespace-prefix service method-style: method-name document
```

When SOAP RPC encoding is required for a particular service method, use:

```
//gsoap namespace-prefix service method-encoding: method-name encoded
```

When literal encoding is required for a particular service method, use:

```
//gsoap namespace-prefix service method-encoding: method-name literal
```

or when the SOAP-ENV:encodingStyle attribute is different from the SOAP 1.1/1.2 encoding style, use:

```
//gsoap namespace-prefix service method-encoding: method-name encoding-style
```

When SOAP RPC encoding is required for a particular service method response when the request message is literal, use:

```
//gsoap namespace-prefix service method-response-encoding: method-name encoded
```

When literal encoding is required for a particular service method response when the request message is encoded, use:

```
//gsoap namespace-prefix service method-response-encoding: method-name literal
```

or when the SOAP-ENV:encodingStyle attribute is different from the SOAP 1.1/1.2 encoding style, use:

```
//gsoap namespace-prefix service method-response-encoding: method-name encoding-style
```

Note that the method-response-encoding is set to the value of method-encoding by default.

When header processing is required, each method declared in the WSDL should provide a binding to the parts of the header that may appear as part of a method request message. Such a binding is given by:

```
//gsoap namespace-prefix service method-header-part: method-name header-part
```

For example:

```
struct SOAP_ENV__Header
{
    char *h__transaction;
    struct UserAuth *h__authentication;
};
```

Suppose method ns_login uses both header parts (at most), then this is declared as:

```
//gsoap ns service method-header-part: login h__transaction
//gsoap ns service method-header-part: login h__authentication
int ns_login(...);
```

Suppose method ns_search uses only the first header part, then this is declared as:

```
//gsoap ns service method-header-part: search h__transaction
int ns_search(...);
```

Note that the method name and header part names MUST be namespace qualified. The headers MUST be present in all operations that declared the header parts.

To specify the header parts for the method input (method request message), use:

```
//gsoap namespace-prefix service method-input-header-part: method-name header-part
```

Similarly, to specify the header parts for the method output (method response message), use:

```
//gsoap namespace-prefix service method-output-header-part: method-name header-part
```

The declarations above only affect the WSDL. For example:

```
struct SOAP_ENV__Header
{
    char *h__transaction;
    struct UserAuth *h__authentication;
};
//gsoap ns service method-input-header-part: login h__authentication
//gsoap ns service method-input-header-part: login h__transaction
//gsoap ns service method-output-header-part: login h__transaction
int ns_login(...);
```

The headers **MUST** be present in all operations that declared the header parts.

To specify MIME attachments for the method input and output (method request and response messages), use:

```
//gsoap namespace-prefix service method-mime-type: method-name mime-type
```

You can repeat this directive for all multipartRelated MIME attachments you want to associate with the method.

To specify MIME attachments for the method input (method request message), use:

```
//gsoap namespace-prefix service method-input-mime-type: method-name mime-type
```

Similarly, to specify MIME attachments for the method output (method response message), use:

```
//gsoap namespace-prefix service method-output-mime-type: method-name mime-type
```

You can repeat these directives for all multipartRelated MIME attachments you want to associate with the method.

19.2.1 Example

The use of directives is best illustrated with an example. The `quotex.h` header file of the `quotex` example in the `gSOAP` distribution for Unix/Linux is:

```
//gsoap ns1 service namespace: urn:xmethods-delayed-quotes
int ns1_Quote(char *symbol, float &result);

//gsoap ns2 service namespace: urn:xmethods-CurrencyExchange
int ns2_GetRate(char *country1, char *country2, float &result);

//gsoap ns3 service name: quotex
//gsoap ns3 service style: rpc
//gsoap ns3 service encoding: encoded
//gsoap ns3 service location: http://www.cs.fsu.edu/~engelen
//gsoap ns3 service namespace: urn:quotex
int ns3_Quote(char *symbol, char *country, float &result);
```

The `quotex` example is a new Web Service created by combining two existing Web Services: the XMethods Delayed Stock Quote service and XMethods Currency Exchange service.

Namespace prefix `ns3` is used for the new `quotex` Web Service with namespace URI `urn:quotex`, service name `quotex`, and location `http://www.cs.fsu.edu/~engelen`. Since the new Web Service invokes the `ns1_Quote` and `ns2_GetRate` remote methods, the service namespaces of these methods are given. The service names and locations of these methods are not given because they are only required for setting up a new Web Service for these methods (but may also be provided in the header file for documentation purposes). After invoking the `gSOAP` Stub and Skeleton compiler on the `quotex.h` header file:

soapcpp2 quotex.h

the WSDL of the new quotex Web Service is saved as quotex.wsdl. Since the service name (quotex), location (<http://www.cs.fsu.edu/~engelen>), and namespace URI (urn:quotex) were provided in the header file, the generated WSDL file does not need to be changed by hand and can be published immediately together with the compiled Web Service installed as a CGI application at the designated URL (<http://www.cs.fsu.edu/~engelen/quotex.cgi> and <http://www.cs.fsu.edu/~engelen/quotex.wsdl>).

The namespace mapping table for the quotex.cpp Web Service implementation is saved as quotex.nsmmap. This file can be directly included in quotex.cpp instead of specified by hand in the source of quotex.cpp:

```
#include "quotex.nsmmap"
```

The automatic generation and inclusion of the namespace mapping table requires compiler directives for **all** namespace prefixes to associate each namespace prefix with a namespace URI. Otherwise, namespace URIs have to be manually added to the table (they appear as <http://tempuri.org>).

19.3 Transient Data Types

There are situations when certain data types have to be ignored by gSOAP for the compilation of (de)marshalling routines. For example, in certain cases only a few members of a class or struct need not be (de)serialized, or the base class of a derived class should not be (de)serialized. Certain built-in classes such as ostream cannot be (de)serialized. Data parts that should be kept invisible to gSOAP are called “transient”. Transient data types and transient struct/class members are declared with the **extern** keyword or are declared within [and] blocks in the header file. The **extern** keyword has a special meaning to the gSOAP compiler and won’t affect the generated codes. The special [and] block construct can be used with data type declarations and within **struct** and **class** declarations. The use of **extern** or [] achieve the same effect, but [] may be more convenient to encapsulate transient types in a larger part of the header file. The use of **extern** with **typedef** is reserved for the declaration of user-defined external (de)serializers for data types, see Section 19.5.

First example:

```
extern class ostream; // ostream can't be (de)serialized, but need to be declared to make it visible
                        to gSOAP
class ns_::myClass
{ ...
    virtual void print(ostream &s) const; // need ostream here
    ...
};
```

Second example:

```
[
    class myBase // base class need not be (de)serialized
    { ... };
]
```

```
class ns_myDerived : myBase
{ ... };
```

Third example:

```
[ typedef int transientInt; ]
class ns_myClass
{
    int a; // will be (de)serialized
    [
        int b; // transient field
        char s[256]; // transient field
    ]
    extern float d; // transient field
    char *t; // will be (de)serialized
    transientInt *n; // transient field
    [
        virtual void method(char buf[1024]); // does not create a char[1024] (de)serializer
    ]
};
```

In this example, **class** `ns_myClass` has three transient fields: `b`, `s`, and `n` which will not be (de)serialized in SOAP. Field `n` is transient because the type is declared within a transient block. Pointers, references, and arrays of transient types are transient. The single class method is encapsulated within `[and]` to prevent gSOAP from creating (de)serializers for the `char[1024]` type. gSOAP will generate (de)serializers for all types that are not declared within a `[and]` transient block.

19.4 Volatile Data Types

While transient data types are supposed to be hidden from gSOAP, volatile data types are visible to gSOAP but their declaration and implementation is assumed to be hidden. That is, volatile data types are assumed to be part of an existing non-modifiable software package, such as a built-in library. It would not make sense to redefine the data types in a gSOAP header file. When you need to (de)serialize such data types, you must declare them in a gSOAP header file and use the **volatile** qualifier.

Consider for example **struct** `tm`, declared in `time.h`. The structure may actually vary between platforms, but the `tm` structure includes at least the following fields:

```
volatile struct tm
{
    int tm_sec; /* seconds (0 - 60) */
    int tm_min; /* minutes (0 - 59) */
    int tm_hour; /* hours (0 - 23) */
    int tm_mday; /* day of month (1 - 31) */
    int tm_mon; /* month of year (0 - 11) */
    int tm_year; /* year - 1900 */
    int tm_wday; /* day of week (Sunday = 0) */
};
```

```

    int tm_yday; /* day of year (0 - 365) */
    int tm_isdst; /* is summer time in effect? */
    char *tm_zone; /* abbreviation of timezone name */
    long tm_gmtoff; /* offset from UTC in seconds */
};

```

Note that we qualified the structure **volatile** in the gSOAP header file to inform the gSOAP compiler that it should not attempt to redeclare it. We can now readily serialize and deserialize the `tm` structure. The following program fragment serializes the local time stored in a `tm` structure to stdout:

```

time_t T = time(NULL);
struct tm *t = localtime(&T);
struct soap *soap = soap_new();
soap_set_omode(soap, SOAP_XML_GRAPH); // good habit to use this
soap_begin_send(soap);
soap_put_tm(soap, t, "myLocalTime", NULL);
soap_end_send(soap);
soap_end(soap);
soap_done(soap);
free(soap);

```

It is also possible to serialize the `tm` fields as XML attributes using the `@` qualifier, see Section 11.5.7.

If you must produce a schema file, say `time.xsd`, that defines an XML schema and namespace for the `tm` struct, you can add a **typedef** declaration to the header file:

```

typedef struct tm time__struct_tm;

```

We used the **typedef** name `time__struct_tm` rather than `time__tm`, because a schema name clash will occur with the latter since taking off the `time` prefix will result in the same name being used.

Classes should be declared **volatile** to prevent modification of these classes by gSOAP. gSOAP adds serialization methods to classes to support polymorphism. However, this is a problem when you can't modify class declarations because they are part of a non-modifiable software package. The solution is to declare these classes **volatile**, similar to the `tm` structure example illustrated above. You can also use a **typedef** to associate a schema with a class.

19.5 How to Declare User-Defined Serializers and Deserializers

Users can declare their own (de)serializers for specific data types instead of relying on the gSOAP-generated (de)serializers. To declare a external (de)serializer, declare a type with **extern typedef**. gSOAP will not generate the (de)serializers for the type name that is declared. For example:

```

extern typedef char *MyData;
struct Sample
{
    MyData s; // use user-defined (de)serializer for this field
    char *t; // use gSOAP (de)serializer for this field
};

```

The user is required to supply the following routines for each **extern typedef**'ed name \underline{T} :

```
void soap_serialize_ $\underline{T}$ (struct soap *soap, const  $\underline{T}$  *a)
void soap_default_ $\underline{T}$ (struct soap *soap,  $\underline{T}$  *a)
void soap_out_ $\underline{T}$ (struct soap *soap, const char *tag, int id, const  $\underline{T}$  *a, const char *type)
 $\underline{T}$  *soap_in_ $\underline{T}$ (struct soap *soap, const char *tag,  $\underline{T}$  *a, const char *type)
```

The function prototypes can be found in soapH.h.

For example, the (de)serialization of MyData can be done with the following code:

```
void soap_serialize_MyData(struct soap *soap, MyData *const*a)
{ } // no need to mark this node (for multi-ref and cycle detection)
void soap_default_MyData(&soap, MyData **a)
{ *a = NULL }
void soap_out_MyData(struct soap *soap, const char *tag, int id, MyData *const*a, const char
*type)
{
    soap_element_begin_out(soap, tag, id, type); // print XML beginning tag
    soap_send(soap, *a); // just print the string (no XML conversion)
    soap_element_end_out(soap, tag); // print XML ending tag
}
MyData **soap_in_MyData(struct soap *soap, const char *tag, MyData **a, const char *type)
{
    if (soap_element_begin_in(soap, tag))
        return NULL;
    if (!a)
        a = (MyData**)soap_malloc(soap, sizeof(MyData*));
    if (soap->null)
        *a = NULL; // xsi:nil element
    if (*soap->type && soap_match_tag(soap, soap->type, type))
    {
        soap->error = SOAP_TYPE;
        return NULL; // type mismatch
    }
    if (*soap->href)
        a = (MyData**)soap_id_forward(soap, soap->href, a, SOAP_MyData, sizeof(MyData*))
    else if (soap->body)
    {
        char *s = soap_value(soap); // fill buffer
        *a = (char*)soap_malloc(soap, strlen(s)+1);
        strcpy(*a, s);
    }
    if (soap->body && soap_element_end_in(soap, tag))
        return NULL;
    return a;
}
```

More information on custom (de)serialization will be provided in this document or in a separate document in the future. The writing of the (de)serializer code requires the use of the low-level gSOAP API.

19.6 How to Serialize Data Without Generating XSD Type Attributes

gSOAP serializes data in XML with `xsi:type` attributes when the types are declared with namespace prefixes to indicate the schema type of the data contained in the elements. SOAP 1.1 and 1.2 requires `xsi:type` attributes in the presence of polymorphic data or when the type of the data cannot be deduced from the SOAP payload. The namespace prefixes are associated with the type names of **typedefs** (Section 11.2) for primitive data types, **struct**/class names, and **enum** names.

To prevent the output of these `xsi:type` attributes in the XML serialization, you can simply use type declarations that do not include these namespace prefixes. That is, don't use the **typedefs** for primitive types and use unqualified type names with **structs**, **classes**, and **enums**.

However, there are two issues. Firstly, if you want to use a primitive schema type that has no C/C++ counterpart, you must declare it as a **typedef** name with a leading underscore, as in:

```
typedef char *_xsd_date;
```

This will produce the necessary `xsd:date` information in the WSDL output by the gSOAP compiler. But the XML serialization of this type at run time won't include the `xsi:type` attribute. Secondly, to include the proper schema definitions in the WSDL produced by the gSOAP compiler, you should use qualified **struct**, **class**, and **enum** names with a leading underscore, as in:

```
struct _ns_myStruct  
{ ... };
```

This ensures that `myStruct` is associated with a schema, and therefore included in the appropriate schema in the generated WSDL. The leading underscore prevents the XML serialization of `xsi:type` attributes for this type in the SOAP/XML payload.

19.7 Function Callbacks for Customized I/O and HTTP Handling

gSOAP provides five callback functions for customized I/O and HTTP handling:

Callback (function pointer)

int (*soap.fopen)(struct soap *soap, const char *endpoint, const char *host, int port)

Called from a client proxy to open a connection to a Web Service located at `endpoint`. Input parameters `host` and `port` are micro-parsed from `endpoint`. Should return a valid file descriptor, or `SOAP_INVALID_SOCKET` and `soap->error` set to an error code. Built-in gSOAP function: `tcp_connect`

int (*soap.fget)(struct soap *soap)

Called by the main server loop upon an HTTP GET request. The `SOAP_GET_METHOD` error is returned by the default `fget` routine. This callback can be used to respond to HTTP GET methods with content, see Section 19.10. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `http_get`

int (*soap.fform)(struct soap *soap)

Called by the main server loop when a user-defined `fparsehdr` callback returned `SOAP_FORM` to signal that the HTTP body must be processed by this form handler callback. The HTTP POST form data **MUST** be read, otherwise keep-alive messages will end up out of sync. Should return `SOAP_OK` or a gSOAP error code. Built-in gSOAP function: `none`.

int (*soap.fpost)(struct soap *soap, const char *endpoint, const char *host, int port, const char *path, const char *action, size_t count)

Called from a client proxy to generate the HTTP header to connect to `endpoint`. Input parameters `host`, `port`, and `path` are micro-parsed from `endpoint`, `action` is the SOAP action, and `count` is the length of the SOAP message or 0 when `SOAP_ENC_XML` is set or when `SOAP_IO_LENGTH` is reset. Use function `soap_send(struct soap *soap, char *s)` to write the header contents. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `http_post`.

int (*soap.fposthdr)(struct soap *soap, const char *key, const char *val)

Called by `http_post` and `http_response` (through the callbacks). Emits HTTP key: val header entries. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `http_post_header`.

int (*soap.fresponse)(struct soap *soap, int soap_error_code, size_t count)

Called from a service to generate the response HTTP header. Input parameter `soap_error_code` is a gSOAP error code (see Section 10.2 and `count` is the length of the SOAP message or 0 when `SOAP_ENC_XML` is set or when `SOAP_IO_LENGTH` is reset. Use function `soap_send(struct soap *soap, char *s)` to write the header contents. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `http_response`

int (*soap.fparse)(struct soap *soap)

Called by client proxy and service to parse an HTTP header (if present). When user-defined, this routine must at least skip the header. Use function `int soap_getline(struct soap *soap, char *buf, int len)` to read HTTP header lines into a buffer `buf` of length `len` (returns empty line at end of HTTP header). Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `http_parse`

int (*soap.fparsehdr)(struct soap *soap, const char *key, const char *val)

Called by `http_parse` (through the `fparse` callback). Handles HTTP key: val header entries to set gSOAP's internals. Should return `SOAP_OK`, `SOAP_STOP` (see `fstop`) or a gSOAP error code. Built-in gSOAP function: `http_parse_header`

int (*soap.fclose)(struct soap *soap)

Called by client proxy **multiple times**, to close a socket connection before a new socket connection is established and at the end of communications when the `SOAP_IO_KEEPAIVE` flag is not set and `soap.keep_alive` \neq 0 (indicating that the other party supports keep alive). Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `tcp_disconnect`

int (*soap.fsend)(struct soap *soap, const char *s, size_t n)

Called for all send operations to emit contents of `s` of length `n`. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `fsend`

size_t (*soap.frecv)(struct soap *soap, char *s, size_t n)

Called for all receive operations to fill buffer `s` of maximum length `n`. Should return the number of bytes read or 0 in case of an error, e.g. EOF. Built-in gSOAP function: `frecv`

int (*soap.fignore)(struct soap *soap, const char *tag)

Called when an unknown XML element was encountered on the input. The `tag` parameter is the offending XML element tag name. Should return `SOAP_OK`, or a gSOAP error code such as `SOAP_TAG_MISMATCH` to throw an exception. Built-in gSOAP function: `none`.

int (*soap.fconnect)(struct soap *soap, const char *endpoint, const char *host, int port)

When non-NULL, this callback is called for all client-to-server connect operations instead of the built-in socket connect code. Therefore, it can be used to override the built-in connection establishment. Parameter `endpoint` contains the server endpoint URL, `host` the domain name or IP, and `port` the port number. Should return `SOAP_OK`, or a gSOAP error code. Built-in gSOAP function: `none`

int (*soap.faccept)(struct soap *soap, struct sockaddr *a, int *n)

Called by `soap_accept`. This is a wrapper routine for `accept`. Should return a valid socket descriptor or `SOAP_INVALID_SOCKET` and set `soap->error` to an error code. Built-in gSOAP function: `tcp_accept`

In addition, a **void***user field in the **struct** soap data structure is available to pass user-defined data to the callbacks.

The following example uses I/O function callbacks for customized serialization of data into a buffer and deserialization back into a datastructure:

```

char buf[10000]; // XML buffer
int len1 = 0; // #chars written
int len2 = 0; // #chars read
// mysend: put XML in buf[]
int mysend(struct soap *soap, const char *s, size_t n)
{
    if (len1 + n > sizeof(buf))
        return SOAP_EOF;
    strcpy(buf + len1, s);
    len1 += n;
    return SOAP_OK;
}
// myrecv: get XML from buf[]
size_t myrecv(struct soap *soap, char *s, size_t n)
{
    if (len2 + n > len1)
        n = len1 - len2;
    strncpy(s, buf + len2, n);
    len2 += n;
    return n;
}
main()
{
    struct soap soap;
    struct ns__person p;
    soap_init(&soap);
    len1 = len2 = 0; // reset buffer pointers
    p.name = "John Doe";
    p.age = 25;
    soap.fsend = mysend; // assign callback
    soap.frecv = myrecv; // assign callback
    soap_begin(&soap);
    soap_set_omode(&soap, SOAP_XML_GRAPH);
    soap_serialize_ns__person(&soap, &p);
    soap_put_ns__person(&soap, &p, "ns:person", NULL);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
        exit(1);
    }
    soap_end(&soap);
    soap_begin(&soap);
    soap_get_ns__person(&soap, &p, "ns:person", NULL);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
    }
}

```

```

        exit(1);
    }
    soap_end(&soap);
    soap_init(&soap); // disable callbacks
}

```

The `soap_done` function can be called to reset the callback to the default internal gSOAP I/O and HTTP handlers.

The following example illustrates customized I/O and (HTTP) header handling. The SOAP request is saved to a file. The client proxy then reads the file contents as the service response. To perform this trick, the service response has exactly the same structure as the request. This is declared by the **struct** `ns__test` output parameter part of the remote method declaration. This struct resembles the service request (see the generated `soapStub.h` file created from the header file).

The header file is:

```

//gsoap ns service name: callback
//gsoap ns service namespace: urn:callback
struct ns__person
{
    char *name;
    int age;
};
int ns__test(struct ns__person in, struct ns__test &out);

```

The client program is:

```

#include "soapH.h"
...
int myopen(struct soap *soap, const char *endpoint, const char *host, int port)
{
    if (strncmp(endpoint, "file:", 5))
    {
        printf("File name expected\n");
        return SOAP_EOF;
    }
    if ((soap->sendfd = soap->recvfd = open(host, O_RDWR|O_CREAT, S_IWUSR|S_IRUSR)) < 0)
        return SOAP_EOF;
    return SOAP_OK;
}
void myclose(struct soap *soap)
{
    if (soap->sendfd > 2) // still open?
        close(soap->sendfd); // then close it
    soap->recvfd = 0; // set back to stdin
    soap->sendfd = 1; // set back to stdout
}
int mypost(struct soap *soap, const char *endpoint, const char *host, const char *path, const char *action, size_t count)
{

```

```

    return soap_send(soap, "Custom-generated file\n"); // writes to soap->sendfd
}
int myparse(struct soap *soap)
{
    char buf[256];
    if (lseek(soap->recvfd, 0, SEEK_SET) < 0 || soap_getline(soap, buf, 256)) // go to begin and
skip custom header
        return SOAP_EOF;
    return SOAP_OK;
}
main()
{
    struct soap soap;
    struct ns__test r;
    struct ns__person p;
    soap_init(&soap); // reset
    p.name = "John Doe";
    p.age = 99;
    soap.fopen = myopen; // use custom open
    soap.fpost = mypost; // use custom post
    soap.fparse = myparse; // use custom response parser
    soap.fclose = myclose; // use custom close
    soap_call_ns__test(&soap, "file://test.xml", "", p, r);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
        exit(1);
    }
    soap_end(&soap);
    soap_init(&soap); // reset to default callbacks
}

```

SOAP 1.1 and 1.2 specify that XML elements may be ignored when present in a SOAP payload on the receiving side. gSOAP ignores XML elements that are unknown, unless the XML attribute `mustUnderstand="true"` is present in the XML element. It may be undesirable for elements to be ignored when the outcome of the omission is uncertain. The `soap.ignore` callback can be set to a function that returns `SOAP_OK` in case the element can be safely ignored, or `SOAP_MUSTUNDERSTAND` to throw an exception, or to perform some application-specific action. For example, to throw an exception as soon as an unknown element is encountered on the input, use:

```

int myignore(struct soap *soap, const char *tag)
{
    return SOAP_MUSTUNDERSTAND; // never skip elements (secure)
}
...
soap.ignore = myignore;
soap_call_ns__method(&soap, ...); // or soap_serve(&soap);

```

To selectively throw an exception as soon as an unknown element is encountered but element `ns:xyz` can be safely ignored, use:

```

int myignore(struct soap *soap, const char *tag)
{
    if (soap_match_tag(soap, tag, "ns:xyz") != SOAP_OK)
        return SOAP_MUSTUNDERSTAND;
    return SOAP_OK;
}

...
soap->ignore = myignore;
soap_call_ns_method(&soap, ...); // or soap_serve(&soap)
...
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "some-URI"}, // the namespace of element ns:xyz
    {NULL, NULL}
}

```

Function `soap_match_tag` compares two tags. The third parameter may be a pattern where `*` is a wildcard and `-` is a single character wildcard. So for example `soap_match_tag(tag, "ns:*")` will match any element in namespace `ns` or when no namespace prefix is present in the XML message.

The callback can also be used to keep track of unknown elements in an internal data structure such as a list:

```

struct Unknown
{
    char *tag;
    struct Unknown *next;
};

int myignore(struct soap *soap, const char *tag)
{
    char *s = (char*)soap_malloc(soap, strlen(tag)+1);
    struct Unknown *u = (struct Unknown*)soap_malloc(soap, sizeof(struct Unknown));
    if (s && u)
    {
        strcpy(s, tag);
        u->tag = s;
        u->next = u;
        u->next = u;
    }
}

...
struct soap *soap;
struct Unknown *ulist = NULL;
soap_init(&soap);
soap->ignore = myignore;
soap_call_ns_method(&soap, ...); // or soap_serve(&soap)
// print the list of unknown elements
soap_end(&soap); // clean up

```

19.8 HTTP 1.0 and 1.1

gSOAP uses HTTP 1.1 by default. You can revert to HTTP 1.0 as follows:

```
struct soap soap;
soap_init(&soap);
...
soap.http_version = "1.0";
```

19.9 HTTP 307 Temporary Redirect Support

The client-side handling of HTTP 307 code "Temporary Redirect" and any of the redirect codes 301, 302, and 303 are not automated in gSOAP. Client application developers may want to consider adding a few lines of code to support redirects. It was decided not to automatically support redirects for the following reasons:

- Redirecting a secure HTTPS address to a non-secure HTTP address via 307 creates a security vulnerability.
- Cyclic redirects must be detected (e.g. allowing only a limited number of redirect levels).
- Redirecting HTTP POST will result in re-serialization and re-post of the entire SOAP request. The SOAP request message must be re-posted in its entirety when re-issuing the SOAP operation to a new address.

To implement client-side 307 redirect, add the following lines of code:

```
char *endpoint = NULL; // use default endpoint given in WSDL (or add another one here)
int n = 10; // max redirect count
while (n--)
{
    if (soap_call_ns1__myMethod(soap, endpoint, ...))
    {
        if ((soap->error >= 301 && soap->error <= 303) || soap->error == 307)
            endpoint = soap->endpoint; // endpoint from HTTP 301, 302, 303, 307 Location header
        else
        {
            ... report and handle error
            break;
        }
    }
    else
        break;
}
```

19.10 HTTP GET Support

A gSOAP server normally only grants HTTP (and HTTPS) POST requests. To support HTTP (HTTPS) GET, you need to set the `soap.fget` callback. The callback is required to produce a response to the request in textual form, such as a Web page or a SOAP/XML response.

The following example produces a Web page upon a HTTP GET request (e.g. from a browser):

```
struct soap *soap = soap_new();
soap->fget = http_get();
...
soap_serve(soap);
...
int http_get(struct soap *soap)
{
    soap_response(soap, SOAP_HTML); // HTTP response header with text/html
    soap_send(soap, "iHTMLiMy Web server is operational.i/HTMLi");
    soap_end_send(soap);
    return SOAP_OK;
}
```

The example below produces a WSDL file upon a HTTP GET with path ?wsdl:

```
int http_get(struct soap *soap)
{
    char *s = strchr(soap->path, '?');
    if (!s || strcmp(s, "?wsdl"))
        return SOAP_GET_METHOD;
    fd = fopen("myservice.wsdl", "rb"); // open WSDL file to copy
    if (!fd)
        return 404; // return HTTP not found error
    soap->http_content = "text/xml"; // HTTP header with text/xml content
    soap_response(soap, SOAP_FILE);
    for (;;)
    {
        r = fread(soap->tmpbuf, 1, sizeof(soap->tmpbuf), fd);
        if (!r)
            break;
        if (soap_send_raw(soap, soap->tmpbuf, r))
            break; // can't send, but little we can do about that
    }
    fclose(fd);
    soap_end_send(soap);
    return SOAP_OK;
}
```

Using one-way SOAP/XML message, you can also return a SOAP/XML response:

```
int http_get(struct soap *soap)
{
    if ((soap->omode & SOAP_IO) != SOAP_IO_CHUNK)
        soap_set_omode(soap, SOAP_IO_STORE); // if not chunking we MUST buffer entire content
    to determine content length
    soap_response(soap, SOAP_OK);
    return soap_send_ns1_mySendMethodResponse(soap, "", NULL, ... params ...);
}
```


where `ns1_._mySendMethodResponse` is a one-way message declared in a gSOAP header file as:

```
int ns1_._mySendMethodResponse(... params ..., void);
```

The generated `soapClient.cpp` includes the sending-side stub function.

19.11 HTTP Keep-Alive

gSOAP supports keep-alive socket connections. To activate keep-alive support, set the `SOAP_IO_KEEPAIVE` flag for both input and output modes, see Section 9.12. For example

```
struct soap soap;  
soap.init2(&soap, SOAP_IO_KEEPAIVE, SOAP_IO_KEEPAIVE);
```

When a client or a service communicates with another client or service that supports keep alive, the attribute `soap.keep_alive` will be set to 1, otherwise it is reset to 0 (indicating that the other party will close the connection). The connection maybe terminated on either end before the communication completed, for example when the server keep-alive connection has timed out. This generates a "Broken Pipe" signal on Unix/Linux platforms. This signal can be caught with a signal handler:

```
signal(SIGPIPE, sigpipe_handle);
```

where, for example:

```
void sigpipe_handle(int x) { }
```

Alternatively, broken pipes can be kept silent by setting:

```
soap.socket.flags = MSG_NOSIGNAL;
```

This setting will not generate a sigpipe but read/write operations return `SOAP_EOF` instead. Note that Win32 systems do not support signals and lack the `MSG_NOSIGNAL` flag. The sigpipe handling and flags are not very portable.

A connection will be kept open only if the request contains an HTTP 1.0 header with "Connection: Keep-Alive" or an HTTP 1.1 header that does not contain "Connection: close". This means that a gSOAP client method call should use "http://" in the endpoint URL of the request to the stand-alone service to ensure HTTP headers are used.

If the client does not close the connection, the server will wait forever when no `recv.timeout` is specified. In addition, other clients will be denied service as long as a client keeps the connection to the server open. To prevent this from happening, the service should be multi-threaded such that each thread handles the client connection:

```
int main(int argc, char **argv)  
{  
    struct soap soap, *tsoap;
```

```

pthread_t tid;
int m, s;
soap_init2(&soap, SOAP_IO_KEEPAIVE, SOAP_IO_KEEPAIVE);
soap.max_keep_alive = 100; // optional: at most 100 calls per keep-alive session
soap.accept_timeout = 600; // optional: let server time out after ten minutes of inactivity
m = soap_bind(&soap, NULL, 18000, BACKLOG); // use port 18000 on the current machine
if (m < 0)
{
    soap_print_fault(&soap, stderr);
    exit(1);
}
fprintf(stderr, "Socket connection successful %d\n", m);
for (count = 0; count >= 0; count++)
{
    soap.socket_flags = MSG_NOSIGNAL; // use this
    soap.accept_flags = SO_NOSIGPIPE; // or this to prevent sigpipe
    s = soap_accept(&soap);
    if (s < 0)
    {
        if (soap.errnum)
            soap_print_fault(&soap, stderr);
        else
            fprintf(stderr, "Server timed out\n"); // Assume timeout is long enough for threads to
complete serving requests
        break;
    }
    fprintf(stderr, "Accepts socket %d connection from IP %d.%d.%d.%d\n", s, (int)(soap.ip>>24)&0xFF,
(int)(soap.ip>>16)&0xFF, (int)(soap.ip>>8)&0xFF, (int)soap.ip&0xFF);
    tsoap = soap_copy(&soap);
    pthread_create(&tid, NULL, (void*)(*)(void*))process_request, (void*)tsoap);
}
return 0;
}
void *process_request(void *soap)
{
    pthread_detach(pthread_self());
    ((struct soap*)soap)->recv_timeout = 300; // Timeout after 5 minutes stall on recv
    ((struct soap*)soap)->send_timeout = 60; // Timeout after 1 minute stall on send
    soap_serve((struct soap*)soap);
    soap_destroy((struct soap*)soap);
    soap_end((struct soap*)soap);
    soap_done((struct soap*)soap);
    free(soap);
    return NULL;
}

```

To prevent a malicious client from keeping a thread waiting forever by keeping the connection open, timeouts are set in the `process_request` routine. See Section 19.17 for more details on timeout settings.

A gSOAP client call will automatically attempt to re-establish a connection to a server when the server has terminated the connection for any reason. This way, a sequence of calls can be made

to the server while keeping the connection open. Client stubs will poll the server to check if the connection is still open. When the connection was terminated by the server, the client will automatically reconnect.

A client should reset `SOAP_IO_KEEPAIVE` just before the last call to a server to close the connection after this last call. This will close the socket after the call and also informs the server to gracefully close the connection.

19.12 HTTP Chunked Transfer Encoding

gSOAP supports HTTP chunked transfer encoding. Un-chunking of inbound messages takes place automatically. Outbound messages are never chunked, except when the `SOAP_IO_CHUNK` flag is set for the output mode. Most Web services, however, will not accept chunked inbound messages.

19.13 HTTP Buffered Sends

The entire outbound message can be stored to determine the HTTP content length rather than the two-phase encoding used by gSOAP which requires a separate pass over the data to determine the length of the outbound message. Setting the flag `SOAP_IO_STORE` for the output mode will buffer the entire message. This can speed up the transmission of messages, depending on the content, but may require significant storage space to hold the verbose XML message.

Zlib compressed transfers require buffering. The `SOAP_IO_STORE` flag is set when the `SOAP_ENC_ZLIB` flag is set to send compressed messages. The use of chunking significantly reduces memory usage and may speed up the transmission of compressed SOAP/XML messages. This is accomplished by setting the `SOAP_IO_CHUNK` flag with `SOAP_ENC_ZLIB` for the output mode.

19.14 HTTP Authentication

HTTP authentication (basic) is enabled at the client-side by setting the `soap.userid` and `soap.passwd` strings to a username and password, respectively. A server may request user authentication and denies access (HTTP 401 error) when the client tries to connect without HTTP authentication (or with the wrong authentication information).

Here is an example client code fragment to set the HTTP authentication username and password:

```
struct soap soap;
soap_init(&soap);
soap.userid = "guest";
soap.passwd = "visit";
...
```

A client SOAP request will have the following HTTP header:

```
POST /XXX HTTP/1.0
Host: YY
User-Agent: gSOAP/2.2
Content-Type: text/xml; charset=utf-8
```

```

Content-Length:  nnn
Authorization:  Basic Z3Vlc3Q6Z3Vlc3Q=
...

```

A client **MUST** set the `soap.userid` and `soap.passwd` strings for each call that requires client authentication. The strings are reset after each successful or unsuccessful call.

When present, the value of the `WWW-Authenticate` HTTP header with the authentication realm can be obtained from the `soap.authrealm` string. This is useful for clients to respond intelligently to authentication requests.

A stand-alone gSOAP Web Service can enforce HTTP authentication upon clients, by checking the `soap.userid` and `soap.passwd` strings. These strings are set when a client request contains HTTP authentication headers. The strings **SHOULD** be checked in each service method (that requires authentication to execute).

Here is an example service method implementation that enforced client authentication:

```

int ns_...method(struct soap *soap, ...)
{
    if (!soap->.userid || !soap->.passwd || strcmp(soap->.userid, "guest") || strcmp(soap->.passwd,
"visit"))    return 401; ...
}

```

When the authentication fails, the service response with a SOAP Fault message and a HTTP error code "401 Unauthorized". The HTTP error codes are described in Section 10.2.

19.15 HTTP Proxy Authentication

HTTP proxy authentication (basic) is enabled at the client-side by setting the `soap.proxy_userid` and `soap.proxy_passwd` strings to a username and password, respectively. For example, a proxy server may request user authentication. Otherwise, access is denied by the proxy (HTTP 407 error). Example client code fragment to set proxy server, username, and password:

```

struct soap soap;
soap_init(&soap);
soap.proxy_host = "xx.xx.xx.xx"; // IP
soap.proxy_port = 8080;
soap.proxy_userid = "guest";
soap.proxy_passwd = "guest";
...

```

A client SOAP request will have the following HTTP header:

```

POST /XXX HTTP/1.0
Host: YYY
User-Agent:  gSOAP/2.2
Content-Type:  text/xml; charset=utf-8
Content-Length:  nnn
Proxy-Authorization:  Basic Z3Vlc3Q6Z3Vlc3Q=
...

```

19.16 Speed Improvement Tips

Here are some tips you can use to speed up gSOAP. gSOAP's default settings are chosen to maximize portability and compatibility. The settings can be tweaked to optimize the performance as follows:

- Increase the buffer size SOAP_BUFLEN by changing the SOAP_BUFLEN macro in stdsoap2.h. Use buffer size $2^{18} = 262144$ for example.
- Use HTTP keep-alive at the client-side, see 19.11, when the client needs to make a series of calls to the same server. Server-side keep-alive support can greatly improve performance of both client and server. But be aware that clients and services under Unix/Linux require signal handlers to catch dropped connections.
- Use HTTP chunked transfers, see 19.12.
- Do NOT use gzip compression, even when transferring data over a modem connection. Modems already compress data transfers.

19.17 Timeout Management for Non-Blocking Operations

Socket connect, accept, send, and receive timeout values can be set to manage socket communication timeouts. The soap.connect.timeout, soap.accept.timeout, soap.send.timeout, and soap.recv.timeout attributes of the current gSOAP runtime environment soap can be set to the appropriate user-defined socket send, receive, and accept timeout values. A positive value measures the timeout in seconds. A negative timeout value measures the timeout in microseconds (10^{-6} sec).

The soap.connect.timeout specifies the timeout value for soap_call_ns_method calls.

The soap.accept.timeout specifies the timeout value for soap_accept(&soap) calls.

The soap.send.timeout and soap.recv.timeout specify the timeout values for non-blocking socket I/O operations.

Example:

```
struct soap soap;
soap_init(&soap);
soap.send_timeout = 10;
soap.recv_timeout = 10;
```

This will result in a timeout if no data can be send in 10 seconds and no data is received within 10 seconds after initiating a send or receive operation over the socket. A value of zero disables timeout, for example:

```
soap.send_timeout = 0;
soap.recv_timeout = 0;
```

When a timeout occurs in send/receive operations, a SOAP_EOF exception will be raised (“end of file or no input”). Negative timeout values measure timeouts in microseconds, for example:

```

#define uSec *-1
#define mSec *-1000
soap.accept_timeout = 10 uSec;
soap.send_timeout = 20 mSec;
soap.recv_timeout = 20 mSec;

```

The macros improve readability.

Caution: Many Linux versions do not support non-blocking `connect()`. Therefore, setting `soap.connect_timeout` for non-blocking `soap_call_ns_*` method calls may not work under Linux.

19.18 Socket Options and Flags

gSOAP's socket communications can be controlled with socket options and flags. The gSOAP run-time environment **struct** `soap` flags are: **int** `soap.socket.flags` to control socket `send()` and `recv()` calls, **int** `soap.connect.flags` to set client connection socket options, **int** `soap.bind.flags` to set server-side port bind socket options, **int** `soap.accept.flags` to set server-side request message accept socket options. See the manual pages of `send` and `recv` for `soap.socket.flags` values and see the manual pages of `setsockopt` for `soap.connect.flags`, `soap.bind.flags`, and `soap.accept.flags` (`SOL_SOCKET`) values. These `SO_*` socket option flags (see `setsockopt` manual pages) can be bit-wise or-ed to set multiple socket options at once. The client-side flag `soap.connect.flags=SO_LINGER` is supported with values `l_onoff=1` and `l_linger=0`.

For example, to disable sigpipe signals on Unix/Linux platforms use: `soap.socket.flags=MSG_NOSIGNAL` and/or `soap.connect.flags=SO_NOSIGPIPE` (i.e. client-side connect) depending on your platform.

Use `soap.bind.flags=SO_REUSEADDR` to enable server-side port reuse and local port sharing (but be aware of the security issues when the port is not blocked by a firewall and open to the Internet).

19.19 Secure SOAP Web Services with HTTPS/SSL

When a Web Service is installed as CGI, it uses standard I/O that is encrypted/decrypted by the Web server that runs the CGI application. Therefore, HTTPS/SSL support must be configured for the Web server (not CGI-based Web Service application itself).

To enable OpenSSL, first install OpenSSL and use option `-DWITH_OPENSSL` to compile the sources with your C or C++ compiler, for example:

```

g++ -DWITH_OPENSSL -o myprog myprog.cpp stdsoap2.cpp soapC.cpp soapServer.cpp -lssl -lcrypto

```

SSL support for stand-alone gSOAP Web services is enabled by calling `soap_ssl_accept` after `soap_accept`. In addition, a key file, a CA file (or path to certificates), DH file (if RSA is not used), and password need to be supplied. Instructions on how to do this can be found in the OpenSSL documentation <http://www.openssl.org>. See also Section 19.22.

Let's take a look at an example SSL secure multi-threaded stand-alone SOAP Web Service:

```

int main()
{
    int m, s;
    pthread_t tid;
    struct soap soap, *tsoap;
    if (CRYPTO_thread_setup())
    {
        fprintf(stderr, "Cannot setup thread mutex\n");
        exit(1);
    }
    soap_init(&soap);
    if (soap_ssl_server_context(&soap,
        SOAP_SSL_DEFAULT,
        "server.pem", /* keyfile: required when server must authenticate to clients (see SSL docs on
how to obtain this file) */
        "password", /* password to read the key file */
        "cacert.pem", /* optional cacert file to store trusted certificates */
        NULL, /* optional capath to directory with trusted certificates */
        "dh512.pem", /* DH file, if NULL use RSA */
        NULL, /* if randfile!=NULL: use a file with random data to seed randomness */
        NULL /* optional server identification to enable SSL session cache (must be a unique name)
*/ ))
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    m = soap_bind(&soap, NULL, 18000, 100); // use port 18000
    if (m < 0)
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    fprintf(stderr, "Socket connection successful: master socket = %d\n", m);
    for (;;)
    {
        s = soap_accept(&soap);
        fprintf(stderr, "Socket connection successful: slave socket = %d\n", s);
        if (s < 0)
        {
            soap_print_fault(&soap, stderr);
            break;
        }
        tsoap = soap_copy(&soap); /* should call soap_ssl_accept on a copy */
        if (!tsoap)
            break;
        if (soap_ssl_accept(tsoap))
        {
            soap_print_fault(tsoap, stderr);
            soap_done(tsoap);
            free(tsoap);
            continue; /* when soap_ssl_accept fails, we should just go on */
        }
    }
}

```

```

    }
    pthread_create(&tid, NULL, &process_request, (void*)tsoap);
}
soap_done(&soap); /* deallocates SSL context */
CRYPTO_thread_cleanup();
return 0;
}
void *process_request(void *soap)
{
    pthread_detach(pthread_self());
    soap_serve((struct soap*)soap);
    soap_destroy((struct soap*)soap);
    soap_end((struct soap*)soap);
    soap_done((struct soap*)soap);
    free(soap);
    return NULL;
}

```

The `soap_ssl_server_context` function initializes the server-side SSL context. The `server.pem` key file is the server's private key. The `cacert.pem` is used to authenticate clients and contains the client certificates. Alternatively a directory name can be specified. This directory is assumed to contain the certificates. The `dh512.pem` file specifies that DH will be used for key agreement instead of RSA. The `randfile` entry can be used to seed the PRNG. The last entry enable server-side session caching. A unique server name is required.

The `CRYPTO_thread_setup()` and `CRYPTO_thread_cleanup()` routines can be found in `openssl/crypto/threads/th-lock.c`. These routines are required to setup locks for multi-threaded applications that use SSL. We give a Windows and POSIX threads implementation of these here:

```

#include <unistd.h> /* defines _POSIX_THREADS if pthreads are available */
#ifdef _POSIX_THREADS
# include <pthread.h>
#else
# if defined(WIN32)
#  define MUTEX_TYPE HANDLE
#  define MUTEX_SETUP(x) (x) = CreateMutex(NULL, FALSE, NULL)
#  define MUTEX_CLEANUP(x) CloseHandle(x)
#  define MUTEX_LOCK(x) WaitForSingleObject((x), INFINITE)
#  define MUTEX_UNLOCK(x) ReleaseMutex(x)
#  define THREAD_ID GetCurrentThreadId()
# elif defined(_POSIX_THREADS)
#  define MUTEX_TYPE pthread_mutex_t
#  define MUTEX_SETUP(x) pthread_mutex_init(&(x), NULL)
#  define MUTEX_CLEANUP(x) pthread_mutex_destroy(&(x))
#  define MUTEX_LOCK(x) pthread_mutex_lock(&(x))
#  define MUTEX_UNLOCK(x) pthread_mutex_unlock(&(x))
#  define THREAD_ID pthread_self()
# else
#  error "You must define mutex operations appropriate for your platform"
#  error "See OpenSSL /threads/th-lock.c on how to implement mutex on your platform"
# endif

```



```

struct CRYPTO_dynlock_value { MUTEX_TYPE mutex; };
static MUTEX_TYPE *mutex_buf;
static struct CRYPTO_dynlock_value *dyn_create_function(const char *file, int line)
{
    struct CRYPTO_dynlock_value *value;
    value = (struct CRYPTO_dynlock_value*)malloc(sizeof(struct CRYPTO_dynlock_value));
    if (value)
        MUTEX_SETUP(value->mutex);
    return value;
}
static void dyn_lock_function(int mode, struct CRYPTO_dynlock_value *l, const char *file, int
line)
{
    if (mode & CRYPTO_LOCK)
        MUTEX_LOCK(l->mutex);
    else
        MUTEX_UNLOCK(l->mutex);
}
static void dyn_destroy_function(struct CRYPTO_dynlock_value *l, const char *file, int line)
{
    MUTEX_CLEANUP(l->mutex);
    free(l);
}
void locking_function(int mode, int n, const char *file, int line)
{
    if (mode & CRYPTO_LOCK)
        MUTEX_LOCK(mutex_buf[n]);
    else
        MUTEX_UNLOCK(mutex_buf[n]);
}
unsigned long id_function()
{
    return (unsigned long)THREAD_ID;
}
int CRYPTO_thread_setup()
{
    int i;
    mutex_buf = (MUTEX_TYPE*)malloc(CRYPTO_num_locks() * sizeof(pthread_mutex_t));
    if (!mutex_buf)
        return SOAP_EOM;
    for (i = 0; i < CRYPTO_num_locks(); i++)
        MUTEX_SETUP(mutex_buf[i]);
    CRYPTO_set_id_callback(id_function);
    CRYPTO_set_locking_callback(locking_function);
    CRYPTO_set_dynlock_create_callback(dyn_create_function);
    CRYPTO_set_dynlock_lock_callback(dyn_lock_function);
    CRYPTO_set_dynlock_destroy_callback(dyn_destroy_function);
    return SOAP_OK;
}
void CRYPTO_thread_cleanup()
{

```

```

    int i;
    if (!mutex_buf)
        return;
    CRYPTO_set_id_callback(NULL);
    CRYPTO_set_locking_callback(NULL);
    CRYPTO_set_dynlock_create_callback(NULL);
    CRYPTO_set_dynlock_lock_callback(NULL);
    CRYPTO_set_dynlock_destroy_callback(NULL);
    for (i = 0; i < CRYPTO_num_locks(); i++)
        MUTEX_CLEANUP(mutex_buf[i]);
    free(mutex_buf);
    mutex_buf = NULL;
}

```

For Unix and Linux, make sure you have signal handlers set in your service and/or client applications to catch broken connections (SIGPIPE):

```
signal(SIGPIPE, sigpipe_handle);
```

where, for example:

```
void sigpipe_handle(int x) { }
```

By default, clients are not required to authenticate. To support client authentication use the following:

```

if (soap_ssl_server_context(&soap,
    SOAP_SSL_REQUIRE_CLIENT_AUTHENTICATION,
    "server.pem",
    "password",
    "cacert.pem",
    NULL,
    "dh512.pem",
    NULL,
    NULL
))
{
    soap_print_fault(&soap, stderr);
    exit(1);
}

```

This requires each client to authenticate with its certificate.

The `cacert` file and `capath` are optional. Either one can be specified when clients must run on non-trusted systems. We want to avoid storing trusted certificates in the default location on the file system when that is not secure. Therefore, a flat `cacert.pem` file or directory can be specified to store trusted certificates.

The gSOAP distribution includes a `cacerts.pem` file with the certificates of all certificate authorities such as Verisign. You can use this file to verify the authentication of servers that provide certificates issued by these CAs.

The cacert.pem, client.pem, and server.pem files in the gSOAP distribution are examples of self-signed certificates.

Caution: it is important that the WITH_OPENSSL macro MUST be consistently defined to compile the sources, such as stdsoap2.cpp, soapC.cpp, soapClient.cpp, soapServer.cpp, and all application sources that include stdsoap2.h or soapH.h. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP environment.

19.20 Secure SOAP Clients with HTTPS/SSL

You need to install the OpenSSL library on your platform to enable secure SOAP clients to utilize HTTPS/SSL. After installation, compile all the sources of your application with option -DWITH_OPENSSL. For example on Linux:

```
g++ -DWITH_OPENSSL myclient.cpp stdsoap.cpp soapC.cpp soapClient.cpp -lssl -lcrypto
```

or Unix:

```
g++ -DWITH_OPENSSL myclient.cpp stdsoap.cpp soapC.cpp soapClient.cpp -lnet -lsocket -lnsl  
-lssl -lcrypto
```

or you can add the following line to soapdefs.h:

```
#define WITH_OPENSSL
```

and compile with option -DWITH_SOAPDEFS_H to include soapdefs.h in your project. A client program simply uses the prefix https: instead of http: in the endpoint URL of a remote method call to a Web Service to use encrypted transfers (if the service supports HTTPS). You need to specify the client-side key file and password of the keyfile:

```
if (soap_ssl_client_context(&soap,  
    SOAP_SSL_DEFAULT,  
    "client.pem", /* keyfile: required only when client must authenticate to server (see SSL docs on  
how to obtain this file) */  
    "password", /* password to read the key file */  
    "cacert.pem", /* optional cacert file to store trusted certificates (needed to verify server) */  
    NULL, /* optional capath to direcoty with trusted certificates */  
    NULL /* if randfile!=NULL: use a file with random data to seed randomness */  
))  
{  
    soap_print_fault(&soap, stderr);  
    exit(1);  
}  
soap_call_ns_mymethod(&soap, "https://domain/path/secure.cgi", "", ...);
```

By default, server authentication is enabled. To disable server authentication for testing purposes, use the following:

```

if (soap_ssl_client_context(&soap,
    SOAP_SSL_NO_AUTHENTICATION,
    NULL,
    NULL,
    NULL,
    NULL,
    NULL
))
{
    soap_print_fault(&soap, stderr);
    exit(1);
}

```

This also assumes that the server does not require clients to authenticate (the keyfile is absent).

The `cacert` file and `capath` are optional. Either one can be specified when clients must run on non-trusted systems. We want to avoid storing trusted certificates in the default location on the file system when that is not secure. Therefore, a flat `cacert.pem` file or directory can be specified to store trusted certificates.

Make sure you have signal handlers set in your application to catch broken connections (SIGPIPE):

```
signal(SIGPIPE, sigpipe_handle);
```

where, for example:

```
void sigpipe_handle(int x) { }
```

Caution: it is important that the `WITH_OPENSSL` macro MUST be consistently defined to compile the sources, such as `stdsoap2.cpp`, `soapC.cpp`, `soapClient.cpp`, `soapServer.cpp`, and all application sources that include `stdsoap2.h` or `soapH.h`. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP environment. **Caution:** concurrent client calls MUST be made using separate soap structs copied with `soap_copy` from an originating struct initialized with `soap_ssl_client_context`. In addition, the thread initialization code discussed in Section 19.19 MUST be used to properly setup OpenSSL in a multi-threaded client application.

19.21 SSL Authentication Callback

gSOAP provides a callback function for authentication initialization:

Callback (function pointer)

int (*soap.fsslauth)(**struct** soap *soap)

Initialize the authentication information for clients and services, such as the certificate chain, password, read the key and/or DH file, generate an RSA key, and initialization of the RNG. Should return a gSOAP error code or `SOAP_OK`. Built-in gSOAP function: `ssl_auth_init`

19.22 SSL Certificates

The gSOAP distribution includes a `cacerts.pem` file with the certificates of all certificate authorities (such as Verisign). You can use this file to verify the authentication of servers that provide certificates issued by these CAs. Just set the `cafile` parameter to the location of this file on your file system. Therefore, when you obtain a certificate signed by a trusted CA such as Verisign, you can simply use the `cacerts.pem` file to develop client applications that can verify the authenticity of your server.

The other `.pem` files in the gSOAP distribution are examples of self-signed certificates for testing purposes (`cacert.pem`, `client.pem`, `server.pem`).

You can also create your own self-signed certificates. There is more than one way to generate the necessary files for clients and servers. See <http://www.openssl.org> for information on OpenSSL and <http://sial.org/howto/openssl/ca/> on how to setup and manage a local CA and <http://sial.org/howto/openssl/self-signed/> on how to setup self-signed test certificates.

It is also possible to convert IIS-generated certificates to PEM format, see <http://www.icewarp.com/Knowledgebase/6> for a discussion and examples.

Here is the simplest way to setup self-signed certificates. First you need to create a private Certificate Authority (CA). The CA is used in SSL to verify the authenticity of a given certificate. The CA acts as a trusted third party who has authenticated the user of the signed certificate as being who they say. The certificate is signed by the CA, and if the client trusts the CA, it will trust your certificate. For use within your organization, a private CA will probably serve your needs. However, if you intend use your certificates for a public service, you should probably obtain a certificate from a known CA (e.g. VeriSign). In addition to identification, your certificate is also used for encryption.

Creating certificates should be done through a CA to obtain signed certificates. But you can create your own certificates for testing purposes as follows.

- Go to the OpenSSL bin directory (`/usr/local/ssl` by default and `/System/Library/OpenSSL` on Mac OS X)
- There should be a file called `openssl.cnf`
- Create a new directory in your home account, e.g. `$HOME/CA`, and copy the `openssl.cnf` file to this directory
- Modify `openssl.cnf` by changing the 'dir' value to `HOME/CA`
- Copy the `README.txt`, `root.sh`, and `cert.sh` scripts from the gSOAP distribution package located in the `samples/ssl` directory to `HOME/CA`
- Follow the `README.txt` instructions

You now have a self-signed CA root certificate `cacert.pem` and a `server.pem` (or `client.pem`) certificate in PEM format. The `cacert.pem` certificate is used in the `cafile` parameter of the `soap_ssl_client_context` (or `soap_ssl_server_context`) at the client (or server) side to verify the authenticity of the peer. You can also provide a `capath` parameter to these trusted certificates. The `server.pem` (or `client.pem`) must

be provided with the `soap_ssl_server_context` at the server side (or `soap_ssl_client_context` at the client side) together with the password you entered when generating the certificate using `cert.sh` to access the file. These certificates must be present to grant authentication requests by peers. In addition, the `server.pem` (and `client.pem`) include the host name of the machine on which the application runs (e.g. `localhost`), so you need to generate new certificates when migrating a server (or client).

Finally you need to generate Diffie-Hellmann parameters for the server if you don't want to use RSA. Do the following at the prompt:

```
openssl dhparam -outform PEM -out dh.pem 512
```

File `dh512.pem` is the output file and 512 is the number of bits used.

19.23 SSL Hardware Acceleration

You can specify a hardware engine to enable hardware support for cryptographic acceleration. This can be done once in a server or client with the following statements:

```
static const char *engine = "cswift"; /* engine name */
int main()
{
    ...
    ENGINE *e;
    if (!(e = ENGINE_by_id(engine)))
        fprintf(stderr, "Error finding engine %s\n", engine);
    else if (!ENGINE_set_default(e, ENGINE_METHOD_ALL))
        fprintf(stderr, "Error using engine %s\n", engine);
    ...
}
```

The following table lists the names of the hardware and software engines:

Name	Description
openssl	The default software engine for cryptographic operations
openbsd_dev_crypto	OpenBSD supports kernel level cryptography
cswift	CryptoSwift acceleration hardware
chil	nCipher CHIL acceleration hardware
atalla	Compaq Atalla acceleration hardware
nuron	Nuron acceleration hardware
ubsec	Broadcom uBSec acceleration hardware
aep	Aep acceleration hardware
sureware	SureWare acceleration hardware

19.24 SSL on Windows

Set the full path to `libssl.lib` and `libcrypto.lib` under the MSVC++ "Projects" menu, then choose "Link": "Object/Modules". The path to `libssl32.dll` and `libeay32.dll` need to be specified in the `PATH` environment variable when running gSOAP applications.

Alternatively, you can use the `WinInet` interface available in the `mod_gsoap` directory of the gSOAP package. API instructions are included in the source.

19.25 Zlib Compression

To enable deflate and gzip compression with Zlib, install Zlib from <http://www.zlib.org> if not already installed on your system. Compile `stdsoap2.cpp` (or `stdsoap2.c`) and **all** your sources that include `stdsoap2.h` or `soapH.h` with compiler option `-DWITH_GZIP` and link your code with the Zlib library, e.g. `-lz` on Unix/Linux platforms.

The gzip compression is orthogonal to all transport encodings such as HTTP, SSL, DIME, and can be used with other transport layers. You can even save and load compressed XML data to/from files.

gSOAP supports two compression formats: deflate and gzip. The gzip format is used by default. The gzip format has several benefits over deflate. Firstly, gSOAP can automatically detect gzip compressed inbound messages, even without HTTP headers, by checking for the presence of a gzip header in the message content. Secondly, gzip includes a CRC32 checksum to ensure messages have been correctly received. Thirdly, gzip compressed content can be decompressed with other compression software, so you can decompress XML data saved by gSOAP in gzip format.

Gzip compression is enabled by compiling the sources with `-DWITH_GZIP`. To transmit gzip compressed SOAP/XML data, set the output mode flags to `SOAP_ENC_ZLIB`. For example:

```
soap_init(&soap);
...
soap_set_omode(&soap, SOAP_ENC_ZLIB); // enable Zlib's gzip
if (soap_call_ns_myMethod(&soap, ...))
...
soap_clr_omode(&soap, SOAP_ENC_ZLIB); // disable Zlib's gzip
...
```

This will send a compressed SOAP/XML request to a service, provided that Zlib is installed and linked with the application and the `-DWITH_GZIP` option was used to compile the sources. Receiving compressed SOAP/XML over HTTP either in gzip or deflate formats is automatic. The `SOAP_ENC_ZLIB` flag does not have to be set at the server side to accept compressed messages. Reading and receiving gzip compressed SOAP/XML without HTTP headers (e.g. with other transport protocols) is also automatic.

To control the level of compression for outbound messages, you can set the `soap.z_level` to a value between 1 and 9, where 1 is the best speed and 9 is the best compression (default is 6). For example

```
soap_init(&soap);
...
soap_set_omode(&soap, SOAP_ENC_ZLIB);
soap.z_level = 9; // best compression
...
```

To verify and monitor compression rates, you can use the values `soap.z_ratio_in` and `soap.z_ratio_out`. These two float values lie between 0.0 and 1.0 and express the ratio of the compressed message length over uncompressed message length.

```
soap_call_ns_myMethod(&soap, ...);
...
```

```
printf(" Compression ratio: %f%% (in) %f%% (out)\n", 100*soap.z_ratio_out, 100*soap.z_ratio_in);
...
```

Note: lower ratios mean higher compression rates.

Compressed transfers require buffering the entire output message to determine HTTP message length. This means that the SOAP_IO_STORE flag is automatically set when the SOAP_ENC_ZLIB flag is set to send compressed messages. The use of HTTP chunking significantly reduces memory usage and may speed up the transmission of compressed SOAP/XML messages. This is accomplished by setting the SOAP_IO_CHUNK flag with SOAP_ENC_ZLIB for the output mode. However, some Web servers do not accept HTTP chunked request messages (even when they return HTTP chunked messages!). Stand-alone gSOAP services always accept chunked request messages.

To restrict the compression to the deflate format only, compile the sources with `-DWITH_ZLIB`. This limits compression and decompression to the deflate format. Only plain and deflated messages can be exchanged, gzip is not supported with this option. Receiving gzip compressed content is automatic, even in the absence of HTTP headers. Receiving deflate compressed content is not automatic in the absence of HTTP headers and requires the flag `SOAP_ENC_ZLIB` to be set for the input mode to decompress deflated data.

Caution: it is important that the `WITH_GZIP` and `WITH_ZLIB` macros **MUST** be consistently defined to compile the sources, such as `stdsoap2.cpp`, `soapC.cpp`, `soapClient.cpp`, `soapServer.cpp`, and all application sources that include `stdsoap2.h` or `soapH.h`. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP environment.

19.26 Client-Side Cookie Support

Client-side cookie support is optional. To enable cookie support, compile all sources with option `-DWITH_COOKIES`, for example:

```
g++ -DWITH_COOKIES -o myclient stdsoap2.cpp soapC.cpp soapClient.cpp
```

or add the following line to `stdsoap.h`:

```
#define WITH_COOKIES
```

Client-side cookie support is fully automatic. So just (re)compile `stdsoap2.cpp` with `-DWITH_COOKIES` to enable cookie-based session control in your client.

A database of cookies is kept and returned to the appropriate servers. Cookies are not automatically saved to a file by a client. An example cookie file manager is included as an extras in the distribution. You should explicitly remove all cookies before terminating a gSOAP environment by calling `soap_free_cookies(soap)` or by calling `soap_done(soap)`.

To avoid "cookie storms" caused by malicious servers that return an unreasonable amount of cookies, gSOAP clients/servers are restricted to a database size that the user can limit (32 cookies by default), for example:

```
struct soap soap;
soap_init(&soap);
soap.cookie_max = 10;
```


The cookie database is a linked list pointed to by `soap.cookies` where each node is declared as:

```
struct soap_cookie
{
    char *name;
    char *value;
    char *domain;
    char *path;
    long expire; /* client-side: local time to expire; server-side: seconds to expire */
    unsigned int version;
    short secure;
    short session; /* server-side */
    short env; /* server-side: 1 = got cookie from client */
    short modified; /* server-side: 1 = client cookie was modified */
    struct soap_cookie *next;
};
```

Since the cookie database is linked to a `soap` struct, each thread has a local cookie database in a multi-threaded implementation.

19.27 Server-Side Cookie Support

Server-side cookie support is optional. To enable cookie support, compile all sources with option `-DWITH_COOKIES`, for example:

```
g++ -DWITH_COOKIES -o myserver ...
```

gSOAP provides the following cookie API for server-side cookie session control:

Function

struct soap_cookie *soap_set_cookie(struct soap *soap, const char *name, const char *value, const char *domain, const char *path);

Add a cookie to the database with name *name* and value *value*. *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns pointer to a cookie node in the linked list, or NULL otherwise.

struct soap_cookie *soap_cookie(struct soap *soap, const char *name, const char *domain, const char *path);

Find a cookie in the database with name *name* and value *value*. *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns pointer to a cookie node in the linked list, or NULL otherwise.

char *soap_cookie_value(struct soap *soap, const char *name, const char *domain, const char *path);

Get value of a cookie in the database with name *name*. *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns the string pointer to the value, or NULL otherwise.

long soap_cookie_expire(struct soap *soap, const char *name, const char *domain, const char *path);

Get expiration value of the cookie in the database with name *name* (in seconds). *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. Returns the expiration value, or -1 if cookie does not exist.

int soap_set_cookie_expire(struct soap *soap, const char *name, long expire, const char *domain, const char *path);

Set expiration value *expire* of the cookie in the database with name *name* (in seconds). *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns SOAP_OK, or SOAP_EOF otherwise.

int soap_set_cookie_session(struct soap *soap, const char *name, const char *domain, const char *path);

Set cookie in the database with name *name* to be a session cookie. This means that the cookie will be returned to the client. (Only cookies that are modified are returned to the client). *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns SOAP_OK, or SOAP_EOF otherwise.

int soap_clr_cookie_session(struct soap *soap, const char *name, const char *domain, const char *path);

Clear cookie in the database with name *name* to be a session cookie. *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*. If successful, returns SOAP_OK, or SOAP_EOF otherwise.

void soap_clr_cookie(struct soap *soap, const char *name, const char *domain, const char *path);

Remove cookie from the database with name *name*. *domain* and *path* may be NULL to use the current domain and path given by *soap_cookie_domain* and *soap_cookie_path*.

int soap_getenv_cookies(struct soap *soap);

Initializes cookie database by reading the 'HTTP_COOKIE' environment variable. This provides a means for a CGI application to read cookies send by a client. If successful, returns SOAP_OK, or SOAP_EOF otherwise.

void soap_free_cookies(struct soap *soap);

Release cookie database.

The following global variables are used to define the current domain and path:

Attribute	value
const char * <i>cookie_domain</i>	MUST be set to the domain (host) of the service
const char * <i>cookie_path</i>	MAY be set to the default path to the service
int <i>cookie_max</i>	maximum cookie database size (default=32)

The `cookie_path` value is used to filter cookies intended for this service according to the path prefix rules outlined in RFC2109.

The following example server adopts cookies for session control:

```
int main()
{
    struct soap soap;
    int m, s;
    soap_init(&soap);
    soap.cookie_domain = "...";
    soap.cookie_path = "/"; // the path which is used to filter/set cookies with this destination
    if (argc < 2)
    {
        soap_getenv_cookies(&soap); // CGI app: grab cookies from 'HTTP_COOKIE' env var
        soap_serve(&soap);
    }
    else
    {
        m = soap_bind(&soap, NULL, atoi(argv[1]), 100);
        if (m < 0)
            exit(1);
        for (int i = 1; ; i++)
        {
            s = soap_accept(&soap);
            if (s < 0)
                exit(1);
            soap_serve(&soap);
            soap_end(&soap); // clean up
            soap_free_cookies(&soap); // remove all old cookies from database so no interference occurs
            // with the arrival of new cookies
        }
    }
    return 0;
}

int ck_demo(struct soap *soap, ...)
{
    int n;
    const char *s;
    s = soap_cookie_value(soap, "demo", NULL, NULL); // cookie returned by client?
    if (!s)
        s = "init-value"; // no: set initial cookie value
    else
        ... // modify 's' to reflect session control
    soap_set_cookie(soap, "demo", s, NULL, NULL);
    soap_set_cookie_expire(soap, "demo", 5, NULL, NULL); // cookie may expire at client-side in 5
    // seconds
    return SOAP_OK;
}
```

19.28 Connecting Clients Through Proxy Servers

When a client needs to connect to a Web Service through a proxy server, set the `soap.proxy_host` string and `soap.proxy_port` integer attributes of the current `soap` runtime environment to the proxy's host name and port, respectively. For example:

```
struct soap soap;
soap_init(&soap);
soap.proxy_host = "proxyhostname";
soap.proxy_port = 8080;
if (soap_call_ns_method(&soap, "http://host:port/path", "action", ...))
    soap_print_fault(&soap, stderr);
else
    ...
```

The attributes `soap.proxy_host` and `soap.proxy_port` keep their values through the remote method calls, so they only need to be set once.

19.29 FastCGI Support

To enable FastCGI support, install FastCGI and compile *all* sources (including your application sources that use `stdsoap2.h`) with option `-DWITH_FASTCGI` or add

```
#define WITH_FASTCGI
```

to `stdsoap2.h`.

19.30 How to Create gSOAP Applications With a Small Memory Footprint

To compile gSOAP applications intended for small memory devices, you may want to remove all non-essential features that consume precious code and data space. To do this, compile the gSOAP sources with `-DWITH_LEAN` (i.e. `#define WITH_LEAN`) to remove many non-essential features. The features that will be disabled are:

- No I/O timeouts. Note that many socket operations already obey some form of timeout handling, such as a connect timeout for example.
- No HTTP keep alive
- No HTTP cookies
- No HTTP authentication
- No HTTP chunked output (but input is OK)
- No HTTP compressed output (but input is OK when compiled with `WITH_GZIP`)
- No send/recv timeouts

- No socket flags (no `soap.socket_flag`, `soap.connect_flag`, `soap.bind_flag`, `soap.accept_flag`)
- No canonical XML output
- No logging
- Limited TCP/IP and HTTP error diagnostic messages
- No support for `time_t` serialization
- No support for LONG64/ULONG64 serialization (use **`typedef long xsd_long`**)

Use `-DWITH_LEANER` to make the executable even smaller by removing DIME and MIME attachment handling, `wchar_t*` serialization, and support for XML DOM operations. Note that DIME/MIME attachments are not essential to achieve SOAP/XML interoperability. DIME attachments are a convenient way to exchange non-text-based (i.e. binary) content, but are not required for basic SOAP/XML interoperability. Attachment requirements are predictable. That is, applications won't suddenly decide to use DIME or MIME instead of XML to exchange content.

It is safe to try to compile your application with `-DWITH_LEAN`, provided that your application does not rely on I/O timeouts. When no linkage error occurs in the compilation process, it is safe to assume that your application will run just fine.

19.31 How to Eliminate BSD Socket Library Linkage

The `stdsoap2.c` and `stdsoap2.cpp` gSOAP runtime libraries should be linked with a BSD socket library in the project build, e.g. `winsock` for Win32. To eliminate the need to link a socket library, you can compile `stdsoap2.c` (for C) and `stdsoap2.cpp` (for C++) with the `-DWITH_NOIO` macro set (i.e. `#define WITH_NOIO`). This eliminates the dependency on the BSD socket API, IO streams, FILE type, and `errno`.

As a consequence, you **MUST** define callbacks to replace the missing socket stack. To do so, add to your code the following definitions:

```
struct soap soap;
soap_init(&soap);
/* fsend is used to transmit data in blocks */
soap.fsend = my_send;
/* frecv is used to receive data in blocks */
soap.frecv = my_recv;
/* fopen is used to connect */
soap.fopen = my_tcp_connect;
/* fclose is used to disconnect */
soap.fclose = my_tcp_disconnect;
/* fclosesocket is used only to close the master socket in a server upon soap_done() */
soap.fclosesocket = my_tcp_closesocket;
/* fshutdownsocket is used after completing a send operation to send TCP FIN */
soap.fshutdownsocket = my_tcp_shutdownsocket;
/* setting fpoll is optional, leave it NULL to omit polling the server */
soap.fpoll = my_poll;
```

```
/* faccept is used only by a server application */
soap.faccept = my_accept;
```

These functions are supposed to provide a (minimal) transport stack. See Section 19.7 for more details on the use of these callbacks. All callback function pointers should be non-NULL, except `fpoll`.

You cannot use `soap_print_fault` and `soap_print_fault_location` to print error diagnostics. Instead, the value of `soap.error`, which contains the gSOAP error code, can be used to determine the cause of a fault.

19.32 How to Combine Multiple Client and Server Implementations into one Executable

The `wsdl2h` tool can be used to import multiple WSDLs and schemas at once. The service definitions are combined in one header file to be parsed by `soapcpp2`. It is important to assign namespace prefixes to namespace URIs using the `typemap.dat` file. Otherwise, `wsdl2h` will assign namespace prefixes `ns1`, `ns2`, and so on to the service operations and schema types. Thus, any change to a WSDL or schema may result in a new prefix assignment. For more details, please see Section 8.2.11.

For example, consider the XMethods delayed stock quote and exchange rate services. We can import both WSDLs at once with:

```
wsdl2h -s -o qx.h http://services.xmethods.net/soap/urn:xmethods-delayed-quotes.wsdlhttp://www.xmethods.net/sd/20
```

This generates the `qx.h` file for C++ (option `-s` for non-STL). The next step is to use the `soapcpp2` compiler on this file to generate client code (option `-C`):

```
soapcpp2 -C qx.h
```

The resulting header file can be viewed with Doxygen to pretty-print the service definitions in HTML.

You will notice that the `qx.h` file contains a very lengthy service name `"net_x002exmethods_x002eservices_x002est"`. Since this is undesirable for naming files, operations, and proxies, we manually change its name into `"StockQuote"` and re-run `soapcpp2`.

This gives us a couple of files we need to build the application in C++:

```
soapStub.h
soapH.h
soapC.cpp
soapClient.cpp
soapStockQuoteProxy.h
soapCurrencyExchangeBindingProxy.h
StockQuote.nsmap
```

The two `.cpp` files and `stdsoap2.cpp` are compiled and linked with the main application:

```

#include "soapStockQuoteProxy.h"
#include "soapCurrencyExchangeBindingProxy.h"
#include "StockQuote.nsmap"
main()
{
    StockQuote stock;
    CurrencyExchangeBinding exchange;
    float quote, rate;
    stock.ns1._getQuote("IBM", quote); // get quote for IBM
    if (stock.soap->error)
        exit(1);
    exchange.ns2._getRate("us", "uk", rate); // get US to UK rate
    if (exchange.soap->error)
        exit(1);
    cout << "IBM in UK pounds = " << rate*quote << endl;
}

```

This application prints the value of the IBM stock in UK pounds.

Note that the prefixes ns1 and ns2 can be changed using the `typemap.dat` file for `wsdl2h`, see Section 8.2.11.

Another approach to combine multiple client and service applications into one executable is by using C++ namespaces to logically separate the definitions or by creating C libraries for the client/server objects as explained in subsequent sections.

19.33 How to Build a Client or Server in a C++ Code Namespace

You can use a C++ code namespace of your choice in your header file to build a client or server in that code namespace. In this way, you can create multiple clients and servers that can be combined and linked together without conflicts, which is explained in more detail in the next section (which also shows an example combining two client libraries defined in two C++ code namespaces).

At most one namespace can be defined for the entire gSOAP header file. The code namespace **MUST** completely encapsulate the entire contents of the header file:

```

namespace myNamespaceName {
... gSOAP header file contents ...
}

```

When compiling this header file with the gSOAP compiler, all type definitions, the (de)serializers for these types, and the stub/skeleton codes will be placed in this namespace. The XML namespace mapping table (saved in a `.nsmap` file) will not be placed in the code namespace to allow it to be linked as a global object. You can use option `-n` to create local XML namespace tables, see Section 9.1 (but remember that you explicitly need to initialize the `soap.namespaces` to point to a table at run time). The generated files are prefixed with the code namespace name instead of the usual `soap` file name prefix to enable multiple client/server codes to be build in the same project directory (a code namespace automatically sets the `-p` compiler option, see Section 9.1 for options).

Because the SOAP Header and Fault serialization codes will also be placed in the namespace, they cannot be called from the `stdsoap2.cpp` run time library code and are therefore rendered unusable.

Therefore, these serializers are not compiled at all (enforced with `#define WITH_NOGLOBAL`). To add SOAP Header and Fault serializers, you MUST compile them separately as follows. First, create a new header file `env.h` with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```
soapcpp2 -penv env.h
```

The generated `envC.cpp` file holds the SOAP Header and Fault serializers and you can link this file with your client or server application.

19.34 How to Create Client/Server Libraries

The gSOAP compiler produces `soapClientLib.cpp` and `soapServerLib.cpp` codes that are specifically intended for building static or dynamic client/server libraries. These codes export the stubs and skeletons, but keep all marshaling code (i.e. parameter serializers and deserializers) local (i.e. as static functions) to avoid link symbol conflicts when combining multiple clients and/or servers into one executable. Note that it is far simpler to use the `wsdl2h` tool on multiple WSDL files to generate a header file that combines all service definitions. However, the approach presented in this section is useful when creating (dynamic) libraries for client and server objects, such as DLLs as described in Section 19.35.

To build multiple libraries in the same project directory, you can define a C++ code namespace in your header file (see Section 19.33) or you can use `soapcpp2` with option `-p` to rename the generated `soapClientLib.cpp` and `soapServerLib.cpp` (and associated) files. The `-p` option specifies the file name prefix to replace the `soap` prefix. The libraries don't have to be C++ codes. You can use option `-c` to generate C code. A clean separation of libraries can also be achieved with C++ code namespaces, see Section 19.33.

The library codes do not define SOAP Header and Fault serializers. You MUST add SOAP Header and Fault serializers to your application, which are compiled separately as follows. First, create a new header file `env.h` with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```
soapcpp2 -c -penv env.h
```

The generated `envC.cpp` file holds the SOAP Header and Fault serializers and you can create a (dynamic) library for it to link this code with your client or server application.

You MUST compile the `stdsoap2.cpp` library using `-DWITH_NONNAMESPACES`:

```
g++ -DWITH_NONNAMESPACES -c stdsoap2.cpp
```

This omits the reference to the global namespaces table, which is nowhere to be defined since we will use XML namespaces for each client/service separately. Therefore, you MUST explicitly set the namespaces value of the gSOAP environment in your code every time after initialization of the `soap` struct.

For example, suppose we have two clients defined in header files `client1.h` and `client2.h`. We first generate the `envH.h` file for the SOAP Header and Fault definitions:


```
soapcpp2 -c -penv env.h
```

Then we generate the code for client1 and client2:

```
soapcpp2 -c -n -pmyClient1 client1.h
soapcpp2 -c -n -pmyClient2 client2.h
```

This generates myClient1ClientLib.c and myClient2ClientLib.c (among many other files). These two files should be compiled and linked with your application. The source code of your application should include the generated envH.h, myClient1H.h, myClient2.h files and myClient1.nsmmap, myClient2.nsmmap files:

```
#include "envH.h" // include this file first!
#include "myClient1H.h" // include client 1 stubs
#include "myClient2H.h" // include client 2 stubs
...
#include "myClient1H.nsmmap" // include client 1 nsmmap
#include "myClient2H.nsmmap" // include client 2 nsmmap
...
soap_init(&soap);
soap_set_namespaces(&soap, myClient1_namespaces);
... make Client 1 invocations ...
...
soap_set_namespaces(&soap, myClient2_namespaces);
... make Client 2 invocations ...
```

It is important to use soapcpp2 option -n, see Section 9.1, to rename the namespace tables so we can include them all without running into redefinitions.

Note: Link conflicts may still occur in the unlikely situation that identical remote method names are defined in two or more client stubs or server skeletons when these methods share the same XML namespace prefix. You may have to use C++ code namespaces to avoid these link conflicts or rename the namespace prefixes used by the remote method defined in the header files.

19.34.1 C++ Example

As an example we will build a Delayed Stock Quote client library and a Currency Exchange Rate client library.

First, we create an empty header file env.h (which may contain optional SOAP Header and Fault definitions), and compile it as follows:

```
soapcpp2 -penv env.h
g++ -c envC.cpp
```

We also compile stdsoap2.cpp without namespaces:

```
g++ -c -DWITH_NONNAMESPACES stdsoap2.cpp
```

Note: when you forget to use `-DWITH_NONNAMESPACES` you will get an unresolved link error for the global namespaces table. You can define a dummy table to avoid having to recompile `stdsoap2.cpp`.

Second, we create the Delayed Stock Quote header file specification, which may be obtained using the WSDL importer. If you want to use C++ namespaces then you need to manually add the **namespace** declaration to the generated header file:

```
namespace quote {
//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-delayed-quotes
//gsoap ns service method-action: getQuote ""
int ns_ _getQuote(char *symbol, float &Result);
}
```

We then compile it as a library and we use option `-n` to rename the namespace table to avoid link conflicts later:

```
soapcpp2 -n quote.h
g++ -c quoteClientLib.cpp
```

If you don't want to use a C++ code namespace, you should compile `quote.h` "as is" with `soapcpp2` option `-pquote`:

```
soapcpp2 -n -pquote quote.h
g++ -c quoteClientLib.cpp
```

Third, we create the Currency Exchange Rate header file specification:

```
namespace rate {
//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-CurrencyExchange
//gsoap ns service method-action: getRate ""
int ns_ _getRate(char *country1, char *country2, float &Result);
}
```

Similar to the Quote example above, we compile it as a library and we use option `-n` to rename the namespace table to avoid link conflicts:

```
soapcpp2 -n rate.h
g++ -c rateServerProxy.cpp
```

Fourth, we consider linking the libraries to the main program. The main program can import the `quoteServiceProxy.h` and `rateServiceProxy.h` files to obtain client proxies to invoke the services. The

proxy implementations are defined in the quoteServiceProxy.cpp and rateServiceProxy.cpp files compiled above. The -n option also affects the generation of the quoteServiceProxy.cpp and rateServiceProxy.cpp C++ proxy codes to ensure that the gSOAP environment is properly initialized with the appropriate namespace table (so you don't have to initialize explicitly – this feature is only available with C++ proxy and server object classes).

```
#include "quoteServiceProxy.h" // get quote Service proxy
#include "rateServiceProxy.h" // get rate Service proxy
#include "quote.nsmmap" // get quote namespace bindings
#include "rate.nsmmap" // get rate namespace bindings
int main(int argc, char *argv[])
{
    if (argc <= 1)
    {
        std::cerr << "Usage: main ticker [currency]" << std::endl
        exit(0);
    }
    quote::Service quote;
    float q;
    if (quote.getQuote(argv[1], q)) // get quote
        soap_print_fault(quote.soap, stderr);
    else
    {
        if (argc > 2)
        {
            rate::Service rate;
            float r;
            if (rate.getRate("us", argv[2], r)) // get rate in US dollars
                soap_print_fault(rate.soap, stderr);
            else
                q *= r; // convert the quote
        }
        std::cout << argv[1] << ": " << q << std::endl;
    }
    return 0;
}
```

Compile and link this application with stdsoap2.o, envC.o, quoteServerProxy.o, and rateServerProxy.o.

To compile and link a server object is very similar. For example, assume that we need to implement a calculator service and we want to create a library for it.

```
namespace calc {
    //gsoap ns service name: Service
    //gsoap ns service style: rpc
    //gsoap ns service encoding: encoded
    //gsoap ns service location: http://www.cs.fsu.edu/ engelen/calc.cgi
    //gsoap ns schema namespace: urn:calc
    int ns_add(double a, double b, double &result);
    int ns_sub(double a, double b, double &result);
    int ns_mul(double a, double b, double &result);
}
```

```
int ns_div(double a, double b, double &result);
}
```

We compile this with:

```
soapcpp2 -n calc.h
g++ -c calcServiceObject.cpp
```

The effect of the `-n` option is that it creates local namespace tables, and a modified `calcServiceObject.h` server class definitions that properly initialize the gSOAP run time with the table.

```
#include "calcServiceObject.h" // get Service object
#include "calc.nsmap" // get calc namespace bindings
...
calc::Service calc;
calc.serve(); // calls request dispatcher to invoke one of the functions below
...
int calc::Service::add(double a, double b, double &result);
{ result = a + b; return SOAP_OK; }
int calc::Service::sub(double a, double b, double &result);
{ result = a - b; return SOAP_OK; }
int calc::Service::mul(double a, double b, double &result);
{ result = a * b; return SOAP_OK; }
int calc::Service::div(double a, double b, double &result);
{ result = a / b; return SOAP_OK; }
```

In fact, the `calc::Service` class is derived from the **struct** `soap`. So the environment is available as this, which can be passed to all gSOAP functions that require a `soap` struct context.

19.34.2 C Example

This is the same example as above, but the clients are build with pure C.

First, we create an empty header file (which may contain optional SOAP Header and Fault definitions), and compile it as follows:

```
soapcpp2 -c -penv env.h
gcc -c envC.c
```

We also compile `stdsoap2.c` without namespaces:

```
gcc -c -DWITH_NONNAMESPACES stdsoap2.c
```

Second, we create the Delayed Stock Quote header file specification, which may be obtained using the WSDL importer.

```

//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-delayed-quotes
//gsoap ns service method-action: getQuote ""
int ns_ _getQuote(char *symbol, float *Result);

```

We compile it as a library and we use options -n and -p to rename the namespace table to avoid link conflicts:

```

soapcpp2 -c -n -pquote quote.h
gcc -c quoteClientLib.c

```

Third, we create the Currency Exchange Rate header file specification:

```

//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-CurrencyExchange
//gsoap ns service method-action: getRate ""
int ns_ _getRate(char *country1, char *country2, float *Result);

```

We compile it as a library and we use options -n and -p to rename the namespace table to avoid link conflicts:

```

soapcpp2 -c -n -prate rate.h
gcc -c rateClientLib.c

```

The main program is:

```

#include "quoteStub.h" // get quote Service stub
#include "rateStub.h" // get rate Service stub
#include "quote.nsmmap" // get quote namespace bindings
#include "rate.nsmmap" // get rate namespace bindings
int main(int argc, char *argv[])
{
    if (argc <= 1)
    {
        fprintf(stderr, "Usage: main ticker [currency]\n");
        exit(0);
    }
    struct soap soap;
    float q;
    soap_init(&soap);
    soap_set_namespaces(&soap, quote_namespaces);
    if (soap_call_ns_ _getQuote(&soap, "http://services.xmethods.net/soap", "", argv[1], &q)) // get
quote
        soap_print_fault(&soap, stderr);

```

```

else
{
    if (argc > 2)
    {
        soap_set_namespaces(&soap, rate_namespaces);
        float r;
        if (soap_call_ns_getRate(&soap, "http://services.xmethods.net/soap", "", "us", argv[2],
&r)) // get rate in US dollars
            soap_print_fault(&soap, stderr);
        else
            q *= r; // convert the quote
    }
    printf("%s: %f \n", argv[1], q);
}
return 0;
}

```

Compile and link this application with `stdsoap2.o`, `envC.o`, `quoteClientLib.o`, and `rateClientLib.o`.

To compile and link a server library is very similar. Assuming that the server is named “calc” (as specified with options `-n` and `-p`), the application needs to include the `calcStub.h` file, link the `calcServerLib.o` file, and call `calc_serve(&soap)` function at run time.

19.35 How to Create DLLs

19.35.1 Create the Base `stdsoap2.dll`

First, create a new header file `env.h` with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```
soapcpp2 -penv env.h
```

The generated `envC.cpp` file holds the SOAP Header and Fault serializers, which need to be part of the base library functions.

The next step is to create `stdsoap2.dll` which consists of the file `stdsoap2.cpp` and `envC.cpp`. This DLL contains all common functions needed for all other clients and servers based on gSOAP. Compile `envC.cpp` and `stdsoap2.cpp` into `stdsoap2.dll` using the C++ compiler option `-DWITH_NONNAMESPACES` and the MSVC Pre-Processor definitions `SOAP_FMAC1=__declspec(dllexport)` and `SOAP_FMAC3=__declspec(dllexport)` (or you can compile with `-DWITH_SOAPDEFS_H` and put the macro definitions in `soapdefs.h`). This exports all functions which are preceded by the macro `SOAP_FMAC1` in the `soapcpp2.cpp` source file and macro `SOAP_FMAC3` in the `envC.cpp` source file.

19.35.2 Creating Client and Server DLLs

Compile the `soapClientLib.cpp` and `soapServerLib.cpp` sources as DLLs by using the MSVC Pre-Processor definitions `SOAP_FMAC5=__declspec(dllexport)` and `SOAP_CMAC=__declspec(dllexport)`, and by using the C++ compiler option `-DWITH_NONNAMESPACES`. This DLL links to `stdsoap2.dll`.

To create multiple DLLs in the same project directory, you **SHOULD** use option `-p` to rename the generated `soapClientLib.cpp` and `soapServerLib.cpp` (and associated) files. The `-p` option specifies the file name prefix to replace the `soap` prefix. A clean separation of libraries can also be achieved with C++ namespaces, see Section 19.33.

Unless you use the client proxy and server object classes (`soapXProxy.h` and `soapXObject.h` where `X` is the name of the service), all client and server applications **MUST** explicitly set the namespaces value of the gSOAP environment:

```
soap_init(&soap);
soap_set_namespaces(&soap, namespaces);
```

where the `namespaces[]` table should be defined in the client/server source. These tables are generated in the `.nsmap` files. You can rename the tables using option `-n`, see Section 9.1.

19.36 gSOAP Plug-ins

The gSOAP plug-in feature enables a convenient extension mechanism of gSOAP capabilities. When the plug-in registers with gSOAP, it has full access to the run-time settings and the gSOAP function callbacks. Upon registry, the plug-in's local data is associated with the gSOAP run-time. By overriding gSOAP's function callbacks with the plug-in's function callbacks, the plug-in can extend gSOAP's capabilities. The local plug-in data can be accessed through a lookup function, usually invoked within a callback function to access the plug-in data. The registry and lookup functions are:

```
int soap_register_plugin_arg(struct soap *soap, int (*fcreate)(struct soap *soap, struct soap_plugin
*p, void *arg), void *arg)
void* soap_lookup_plugin(struct soap*, const char*);
```

Other functions that deal with plug-ins are:

```
int soap_copy(struct soap *soap);
void soap_done(struct soap *soap);
```

The `soap_copy` function returns a new dynamically allocated gSOAP environment that is a copy of another, such that no data is shared between the copy and the original environment. The `soap_copy` function invokes the plug-in copy callbacks to copy the plug-ins' local data. The `soap_copy` function returns a gSOAP error code or `SOAP_OK`. The `soap_done` function de-registers all plugin-ins, so this function should be called to cleanly terminate a gSOAP run-time environment.

An example will be used to illustrate these functions. This example overrides the send and receive callbacks to copy all messages that are sent and received to the terminal (`stderr`).

First, we write a header file `plugin.h` to define the local plug-in data structure(s) and we define a global name to identify the plug-in:

```
#include "stdsoap2.h"
#define PLUGIN_ID "PLUGIN-1.0" // some name to identify plugin
struct plugin_data // local plugin data
```

```

{
    int (*fsend)(struct soap*, const char*, size_t); // to save and use send callback
    size_t (*frecv)(struct soap*, char*, size_t); // to save and use recv callback
};
int plugin(struct soap *soap, struct soap_plugin *plugin, void *arg);

```

Then, we write the plugin registry function and the callbacks:

```

#include "plugin.h"
static const char plugin_id[] = PLUGIN_ID; // the plugin id
static int plugin_init(struct soap *soap, struct plugin_data *data);
static int plugin_copy(struct soap *soap, struct soap_plugin *dst, struct soap_plugin *src);
static void plugin_delete(struct soap *soap, struct soap_plugin *p);
static int plugin_send(struct soap *soap, const char *buf, size_t len);
static size_t plugin_recv(struct soap *soap, char *buf, size_t len);
// the registry function:
int plugin(struct soap *soap, struct soap_plugin *p, void *arg)
{
    p->id = plugin_id;
    p->data = (void*)malloc(sizeof(struct plugin_data));
    p->fcopy = plugin_copy; /* optional: when set the plugin must copy its local data */
    p->fdelete = plugin_delete;
    if (p->data)
        if (plugin_init(soap, (struct plugin_data*)p->data))
        {
            free(p->data); // error: could not init
            return SOAP_EOM; // return error
        }
    return SOAP_OK;
}
static int plugin_init(struct soap *soap, struct plugin_data *data)
{
    data->fsend = soap->fsend; // save old recv callback
    data->frecv = soap->frecv; // save old send callback
    soap->fsend = plugin_send; // replace send callback with new
    soap->frecv = plugin_recv; // replace recv callback with new
    return SOAP_OK;
}
// copy plugin data, called by soap_copy() // This is important: we need a deep copy to avoid data
sharing by two run-time environments
static int plugin_copy(struct soap *soap, struct soap_plugin *dst, struct soap_plugin *src)
{
    if (!(dst->data = (struct plugin_data*)malloc(sizeof(struct plugin_data))))
        return SOAP_EOM;
    *dst->data = *src->data;
    return SOAP_OK;
}
// plugin deletion, called by soap_done()
static void plugin_delete(struct soap *soap, struct soap_plugin *p)
{
    free(p->data); // free allocated plugin data
}

```



```

// the new send callback
static int plugin_send(struct soap *soap, const char *buf, size_t len)
{
    struct plugin_data *data = (struct plugin_data*)soap_lookup_plugin(soap, plugin_id); // fetch
    plugin's local data
    fwrite(buf, len, 1, stderr); // write message to stderr
    return data->fsend(soap, buf, len); // pass data on to old send callback
}
// the new receive callback
static size_t plugin_rcv(struct soap *soap, char *buf, size_t len)
{
    struct plugin_data *data = (struct plugin_data*)soap_lookup_plugin(soap, plugin_id); // fetch
    plugin's local data
    size_t res = data->frecv(soap, buf, len); // get data from old rcv callback
    fwrite(buf, res, 1, stderr);
    return res;
}

```

The `fdelete` callback of `struct soap_plugin` MUST be set to register the plugin. It is the responsibility of the plug-in to handle registry (init), copy, and deletion of the plug-in data and callbacks.

A plugin is copied with the `soap_copy()` call. This function copies a soap struct and the chain of plugins. It is up to the plugin implementation to share the plugin data or not:

1. if the `fcopy()` callback is set by the plugin initialization, this callback will be called to allow the plugin to copy its local data upon a `soap_copy()` call. When `soap_done()` is called on the soap struct copy, the `fdelete()` callback is called for deallocation and cleanup of the local data.
2. if the `fcopy()` callback is not set, then the plugin data will be shared (i.e. the data pointer points to the same address). The `fdelete()` callback will not be called upon a `soap_done()` on a copy of the soap struct. The `fdelete()` callback will be called for the original soap struct with which the plugin was registered.

The example plug-in should be used as follows:

```

struct soap soap;
soap_init(&soap);
soap_register_plugin(&soap, plugin);
...
soap_done(&soap);

```

Note: `soap_register_plugin(...)` is an alias for `soap_register_plugin_arg(..., NULL)`. That is, it passes `NULL` as an argument to plug-in's registry callback.

A number of example plug-ins are included in the gSOAP package's plugin directory. Some of these plug-ins are discussed.

19.36.1 The Message Logging and Statistics Plug-in

The message logging and access statistics plug-in can be used to selectively log inbound and outbound messages to a file or stream. It also keeps access statistics to log the total number of bytes

sent and received.

To use the plug-in, compile and link your application with `logging.c` located in the `plugin` directory of the package. To enable the plug-in in your code, register the plug-in and set the streams as follows:

```
#include "logging.h"
...
if (soap_register_plugin(&soap, logging))
    soap_print_fault(&soap, stderr); // failed to register
...
struct logging_data *logdata;
logdata = (struct logging_data*)soap_lookup_plugin(&soap, logging_id);
if (!logdata)
    ... // if the plug-in registered OK, there is certainly data but can't hurt to check
logdata->inbound = stdout; // log to stdout
logdata->outbound = stdout; // log to stdout
... process messages ...
logdata->inbound = NULL; // don't log
logdata->outbound = NULL; // don't log
... process messages ...
size_t bytes_in = logdata->stat_rcv;
size_t bytes_out = logdata->stat_sent;
```

If you use `soap_copy` to copy the `soap` struct with the plug-in, the plug-in's data will be shared by the copy. Therefore, the statistics are not 100% guaranteed to be accurate for multi-threaded services since race conditions on the counters may occur. Mutex is not used to update the counters to avoid introducing expensive synchronization points. If 100% server-side accuracy is required, add mutex at the points indicated in the `logging.c` code.

19.36.2 The HTTP GET Plug-in

The HTTP GET plug-in allows your server to handle HTTP GET requests as well as SOAP-based POST request. HTTP GET requests can also be handled with the `fget` callback, see Section 19.7. However, the HTTP GET plug-in also keeps statistics on the number of successful POST and GET exchanges and failed operations (HTTP faults, SOAP Faults, etc.). It also keeps hit histograms accumulated for up to a year.

To use the plug-in, compile and link your application with `httpget.c` located in the `plugin` directory of the package. To enable the plug-in in your code, register the plug-in with your HTTP GET handler function as follows:

```
#include "httpget.h"
...
if (soap_register_plugin_arg(&soap, httpget, (void*)my_http_get_handler))
    soap_print_fault(&soap, stderr); // failed to register
...
struct http_get_data *httpgetdata;
httpgetdata = (struct http_get_data*)soap_lookup_plugin(&soap, http_get_id);
if (!httpgetdata)
    ... // if the plug-in registered OK, there is certainly data but can't hurt to check
```

```

... process messages ...
size_t get_ok = httpgetdata->stat_get;
size_t post_ok = httpgetdata->stat_post;
size_t errors = httpgetdata->stat_fail;
...
time_t now = time(NULL);
struct tm *T;
T = localtime(&now);
size_t hitsthismminute = httpgetdata->min[T->tm_min];
size_t hitsthishour = httpgetdata->hour[T->tm_hour];
size_t hitstoday = httpgetdata->day[T->tm_yday];

```

An HTTP GET handler can simply produce HTML content, or any other type of information:

```

int my_http_get_handler(struct soap)
{
    soap->http_content = "text/html";
    soap_response(soap, SOAP_FILE);
    soap_send(soap, "¡html¿Hello¡/html¿");
    soap_end_send(soap);
    return SOAP_OK; // return SOAP_OK or HTTP error code, e.g. 404
}

```

If you use `soap_copy` to copy the `soap` struct with the plug-in, the plug-in's data will be shared by the copy. Therefore, the statistics are not 100% guaranteed to be accurate for multi-threaded services since race conditions on the counters may occur. Mutex is not used to update the counters to avoid introducing expensive synchronization points. If 100% server-side accuracy is required, add mutex at the points indicated in the `httpget.c` code.

19.36.3 The HTTP MD5 Plug-in

The HTTP MD5 plug-in works in the background to automatically verify the content of messages using MD5 checksums. With the plug-in, messages can be transferred over (trusted but) unreliable connections. The plug-in can be used on the client side and server side.

To use the plug-in, compile and link your application with `httpmd5.c` and `md5evp.c` located in the plugin directory of the package. The `md5evp.c` implementation uses the EVP interface to compute MD5 checksums with OpenSSL (compiled with `-DWITH_OPENSSL`).

To enable the plug-in in your code, register the plug-in as follows:

```

#include "httpmd5.h"
...
if (soap_register_plugin(&soap, httpmd5))
    soap_print_fault(&soap, stderr); // failed to register

```

Once registered, MD5 checksums are produced for all outbound messages. Inbound messages with MD5 checksums in the HTTP header are automatically verified.

The plug-in requires you to set the `SOAP_IO_STORE` flag when sending SOAP with attachments:

```

#include "httpmd5.h"
...
struct soap soap;
soap_init1(&soap, SOAP_IO_STORE);
if (soap_register_plugin(&soap, httpmd5)
    soap_print_fault(&soap, stderr); // failed to register
... now safe to send SOAP with attachments ...

```

Unfortunately, this eliminates streaming.

19.36.4 The HTTP Digest Authentication Plug-in

The HTTP digest authentication plug-in enables a more secure authentication scheme compared to basic authentication. HTTP basic authentication sends unencrypted userids and passwords over the net, while digest authentication does not exchange passwords but exchanges checksums of passwords (and other data such as nonces to avoid replay attacks). For more details, please see RFC 2617.

The HTTP digest authentication can be used next to the built-in basic authentication, or basic authentication can be rejected to tighten security. The server must have a database with userid's and passwords (in plain text form). The client, when challenged by the server, checks the authentication realm provided by the server and sets the userid and passwords for digest authentication. The client application can temporarily store the userid and password for a sequence of message exchanges with the server, which is faster than repeated authorization challenges and authentication responses.

At the client side, the plug-in is registered and service invocations are checked for authorization challenges (HTTP error code 401). When the server challenges the client, the client should set the userid and password and retry the invocation. The client can determine the userid and password based on the authentication realm part of the server's challenge. The authentication information can be temporarily saved for multiple invocations.

Client-side example:

```

#include "httpda.h"
...
if soap_register_plugin(&soap, http_da))
    soap_print_fault(&soap, stderr); // failed to register
...
if (soap_call_ns_method(&soap, ...) != SOAP_OK)
{
    if (soap.error == 401) // challenge: HTTP authentication required
    {
        if (!strcmp(soap.authrealm, authrealm)) // determine authentication realm    {
            struct http_da_info info; // to store userid and passwd
            http_da_save(&soap, &info, authrealm, userid, passwd); // set userid and passwd for this
realm
            if (soap_call_ns_method(&soap, ...) == SOAP_OK) // retry
            { ...
                soap_end(&soap); // userid and passwd were deallocated
            }
        }
    }
}

```

```

http_da_restore(&soap, &info); // restore userid and passwd
if (!soap_call_ns_method(&soap, ...) == SOAP_OK) // another call
...
http_da_release(&soap, &info); // remove userid and passwd

```

This code supports both basic and digest authentication.

The server can challenge a client using HTTP code 401. With the plug-in, HTTP digest authentication challenges are send. Without the plug-in, basic authentication challenges are send.

Each server method can implement authentication as desired and may enforce digest authentication or may also accept basic authentication responses. To verify digest authentication responses, the server should compute and compare the checksums using the plug-in's `http_da_verify_post` function for HTTP POST requests (and `http_da_verify_get` for HTTP GET requests with the HTTP GET plugin) as follows:

```

#include "httpda.h"
...
if (soap_register_plugin(&soap, http_da))
    soap_print_fault(&soap, stderr); // failed to register
...
soap_serve(&soap);
...
int ns_method(struct soap *soap, ...)
{
    if (soap->userid && soap->passwd) // client used basic authentication { // may decide not
to handle, but if ok then go ahead and compare info:      if (!strcmp(soap->userid, userid) &&
!strcmp(soap->passwd, passwd))
        { ... handle request ...
          return SOAP_OK;
        }
    }
    else if (soap->authrealm && soap->userid) // Digest authentication
    {
        passwd = ... // database lookup on userid and authrealm to find passwd
        if (!strcmp(soap->authrealm, authrealm) && !strcmp(soap->userid, userid))
        {
            if (!http_da_verify_post(soap, passwd))
            { ... handle request ...
              return SOAP_OK;
            }
        }
    }
    soap->authrealm = authrealm; // set realm for challenge
    return 401; // Not authorized, challenge digest authentication
}

```