

# Neural Networks and Biological Modeling

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## QUESTION SET 6

### Exercise 1: Synaptic Plasticity: the BCM rule

A neuron receives 20 inputs that are organized in two groups of 10 inputs. The two groups fire in alternation: when group 1 is active, group 2 is silent; when group 2 is active, group 1 is silent. The input switches between the two groups every second (see figure 1(a)). All initial weights are  $w_{ij} = 1$ , but weights can change according to the BCM rule (eq. 1 with  $\vartheta = 20Hz$ ). The firing rate of the postsynaptic neuron  $\nu_i^{post}$  is given by eq. 2. The shape of  $\Phi$  is shown in figure 1(b).

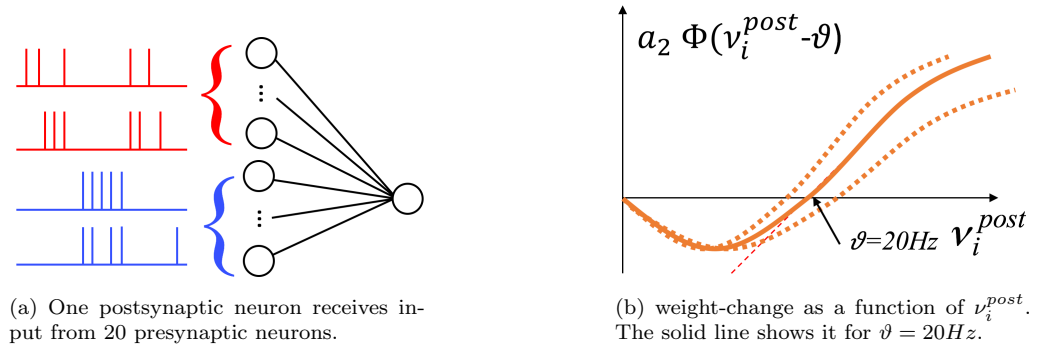


Figure 1: Network and weight-change

$$\frac{d}{dt}w_{ij} = a_2^{corr}\Phi(\nu_i^{post} - \vartheta)\nu_j^{pre} \quad (1)$$

$$\nu_i^{post} = g(I_i) = \sum_j^N w_{ij}\nu_j^{pre} \quad (2)$$

- Assume that group 1 fires at 3Hz, then group 2 at 1 Hz, then again group 1 etc. How do the weights of both groups evolve?
- Assume that group 1 fires at 3Hz, then group 2 at 2.5 Hz, then again group 1 etc. How do the weights of both groups evolve?
- The inputs are as in part b, but now you are free to choose theta. Suppose that the synapse can measure the time-average postsynaptic rate  $\bar{\nu}$ . What would you propose as model of  $\vartheta$  so that the weight-pattern becomes non-trivial?

## Exercise 2: Hopfield networks and Hebbian learning

Here we explore how we may obtain a Hopfield network with  $M$  stored prototypes through Hebbian plasticity instead of fixing the weights explicitly.

This is achieved by presenting the patterns to a fully connected network and apply a plasticity rule:

$$\frac{d}{dt}w_{ij} = a_2^{\text{corr}}(\nu_i^{\text{post}}(t) - \vartheta)(\nu_j^{\text{pre}}(t) - \vartheta), \quad (3)$$

where  $a_2$  and  $\vartheta$  are parameters of the plasticity model;  $\nu_i^{\text{post}}(t)$  and  $\nu_j^{\text{pre}}(t)$  are the activities of neurons  $i$  and  $j$  at time  $t$ .

We present a pattern  $\mu$  to the network in the following way: Each pixel  $j$  of pattern  $\mu$ ,  $p_j^\mu \in \{-1, +1\}$ , stimulates exactly one neuron  $j$  in the network. That neuron's firing rate  $\nu_j$  depends on the pattern:  $\nu_j = 0 \text{ Hz}$  if  $p_j^\mu = -1$ ;  $\nu_j = 20 \text{ Hz}$  if  $p_j^\mu = +1$ .

During that presentation, the network learns the pattern by adjusting its weights according to the plasticity rule given in equation 3. We assume initial weights  $w_{ij} = 0$ . For this exercise, we use a constant threshold  $\vartheta = 10 \text{ Hz}$ .

**2.1** We now have the network learn  $M$  patterns. Each one is presented once for 0.5 seconds. Show that, for an appropriate choice of  $a_2$ , the final weights are given by

$$w_{ij} = \sum_{\mu} p_i^\mu p_j^\mu. \quad (4)$$

*Hint:* Begin by calculating the weight change induced by presenting a single pattern for 0.5s.

**2.2** How does this learning rule map to the general formulation

$$\frac{d}{dt}w_{ij} = a_0 + a_1^{\text{pre}}\nu_j^{\text{pre}} + a_1^{\text{post}}\nu_i^{\text{post}} + a_2^{\text{corr}}\nu_j^{\text{pre}}\nu_i^{\text{post}} + \dots? \quad (5)$$

**2.3** Would you describe this learning procedure as reinforcement or unsupervised learning?

## Exercise 3: Hopfield network with probabilistic update

So far we have studied Hopfield networks with deterministic activity dynamics. That is, for the same input potential  $h$  a neuron always takes the same state:

$$S_i(t+1) = \text{sign}(h_i(t)) \quad (6)$$

In this exercise we model stochastic neurons by replacing that equation with a probabilistic state update:

$$P\{S_i(t+1) = 1|h_i(t)\} = g(h_i(t)) \quad (7)$$

Let's say we have stored  $M$  patterns  $p^\mu$  in a network of  $N$  neurons. We then set the network to an initial state  $S(t_0)$  that has significant overlap with the third pattern and no overlap with other patterns:  $m^{\mu \neq 3}(t_0) = 0$ . For the deterministic update (eq. 6) we know (either from the textbook or from the proof done last week) we would retrieve pattern  $p^3$  in a single update:  $m^3(t_0+1) = g(m^3(t_0)) = 1$ .

We now study how that result changes in the presence of noisy neurons (eq. 7). Look at figure 2 to get an intuition about the stochastic update.

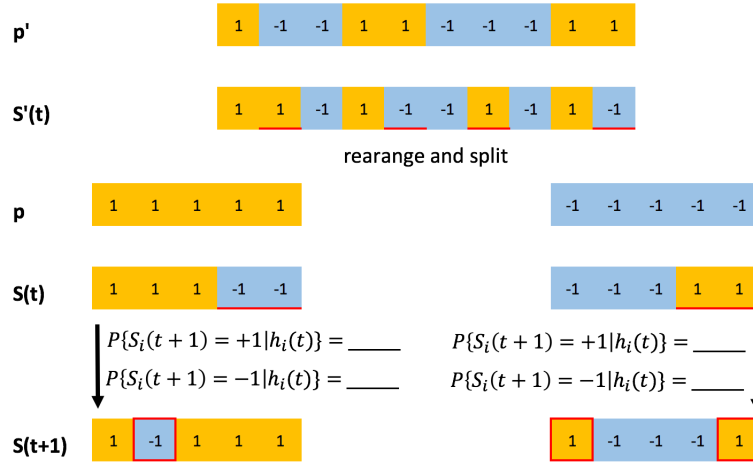


Figure 2: For the analysis of the overlap  $m^3(t+1)$  it helps to rearrange pattern  $p$  and state  $S$  such that we can identify four sub-populations in the last row. We first split the neurons  $S_i(t)$  into those that *should* be active and those that *should not* be active. All neurons in the same sub-population share the same probabilistic activity dynamics. In the last row, we see four groups of neurons which we label  $\{p_i/S_i(t+1)\}$ : {on/on}, {on/off}, {off/on}, {off/off}.

**3.1** Derive the overlap  $m^3(t_0+1)$  (eq. 8) under the state dynamics of eq. 7. Assume that there's only overlap with pattern  $p^3$ , and that for each pixel of the pattern 3, the probability to be on is  $P\{p_i^3 = 1\} = 0.5$

$$m^3(t_0+1) = g(m^3(t_0)) - g(-m^3(t_0)) \quad (8)$$

*Hints:*

1. Use a result we derived earlier:  $h_i(t_0) = p_i^3 m^3(t_0)$ .
2. For each of the four groups (see figure 2) find the probabilities for  $P\{S_i(t+1)|h_i(t_0)\}$
3. Recall the definition of the overlap  $m$ :  $m^3(t_0+1) = \frac{1}{N} \sum_{i=1}^N p_i^3 S_i(t_0+1)$
4. For large  $N$  we can use the expected number of neurons in each of the four sub populations to express (the expected) overlap  $m^3(t_0+1)$ .

### 3.2

- (a) In equation 7, what properties should the transfer function  $g$  have?
- (b) Use  $g(h) = \frac{1}{2}(\tanh(h) + 1)$  in equation 8. Simplify it, plot the function graph and discuss it.

## Exercise 4: Hopfield, asynchronous update and the energy picture

Consider a Hopfield network of  $N$  neurons with an **asynchronous** update regime. That is, only *one* randomly selected neuron  $k$  is updated at each step according to equation 9:

$$\begin{cases} S_k(t+1) = g(h_k(t)) = \text{sign}\left(\sum_j^N w_{kj}S_j(t)\right) & \text{for exactly one randomly chosen neuron } k \\ S_i(t+1) = S_i(t) & \text{for all other neurons, } i \neq k \end{cases} \quad (9)$$

For each state  $S$  of a Hopfield network, we can compute a scalar value, known as the **energy**  $E$  of the network:

$$E := - \sum_i^N \sum_j^N w_{ij} S_i S_j. \quad (10)$$

The evolution of the network state and the change of energy are related in an interesting way:

When a network is updated asynchronously then the energy function  $E(S(t))$  does either decrease or stays at a (local) minimum.

We will now proof this property:

In the trivial case of  $S_k(t+1) = S_k(t) \forall k$  the network has reached a stable state and therefore the energy function is stable too:  $\Delta E = E(t+1) - E(t) = 0$ .

Now consider the case of one neuron  $k$  changing its state and proof, in steps 4.1 to 4.3, that the energy decreases:

**4.1** The energy  $E(t)$  in eq. 10 is summed over all pre- and post- synaptic neurons  $i$  and  $j$ . Rewrite that sum such that the contribution of neuron  $k$  to the total energy  $E$  appears explicitly.

*Hint:* To simplify the resulting expression, remember that in a Hopfield network, the weight are symmetric:  $w_{ij} = w_{ji}$  and there are no self recurrent connections:  $w_{kk} = 0$

**4.2** Write the change in energy  $\Delta E = E(t+1) - E(t)$  when exactly one neuron  $k$  does changes its state.

**4.3** Proof that  $\Delta E < 0$  when exactly one neuron  $k$  does changes its state under the dynamics of eq. 9

## Exercise 5: Binary codes and spikes

A Hopfield model is specified by a binary variable  $S_i \in \{-1, +1\}$ , the weights (eq. 11) and the update dynamics (eq. 12).

$$w_{ij} = c \sum_{\mu=1}^M p_i^{\mu} p_j^{\mu} \quad \text{with } c = \frac{1}{N} \quad (11)$$

$$S_i(t+1) = \text{sign} \left( \sum_{j=1}^N w_{ij} S_j(t) \right) \quad (12)$$

For an interpretation in terms of spikes it is, however, more appealing to work with a binary variable  $\sigma_i$  which is zero or 1.

**5.1** Rewrite the Hopfield model in terms of  $\sigma_i \in \{0, 1\}$ ,  $S_i = 2\sigma_i - 1$ .

**5.2** Assume that the patterns have the property  $\sum_{i=1}^N p_i^{\mu} = 0 \quad \forall \mu$ . Discuss that condition and use it to simplify the update dynamics found in the previous question.