

# Optimal Mini-Batch and Step Sizes for SAGA

Nidham Gazagnadou<sup>1,a</sup>

joint work with Robert M. Gower<sup>1</sup> & Joseph Salmon<sup>2</sup>

---

<sup>1</sup>Télécom Paris, Institut Polytechnique de Paris, Paris, France

<sup>2</sup>IMAG, Université de Montpellier, CNRS, Montpellier, France



---

<sup>a</sup>This work was supported by grants from Région Ile-de-France

# Goals of this Work

- Finite Sum Minimization problem

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$

# Goals of this Work

- **Finite Sum Minimization problem**

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$

- **Stochastic Gradient Descent (SGD) and practitioners**
  - SGD and variance-reduced variants widely used to solve  $(\mathcal{P})$  ...

# Goals of this Work

- **Finite Sum Minimization problem**

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$

- **Stochastic Gradient Descent (SGD) and practitioners**
  - SGD and variance-reduced variants widely used to solve  $(\mathcal{P})$  ...
  - ... yet, **painful hyper-parameters tuning**

# Goals of this Work

- Finite Sum Minimization problem

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$

- Stochastic Gradient Descent (SGD) and practitioners
  - SGD and variance-reduced variants widely used to solve  $(\mathcal{P})$  ...
  - ... yet, **painful hyper-parameters tuning**
- This presentation
  - Provide theoretical optimal step and mini-batch sizes for SAGA algorithm

## Expected Smoothness Constant

---

# Supervised Learning Optimization Problem

- **Empirical Risk Minimization (ERM)**

Find optimal parameter/model  $w^*$  s.t.

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$


# Supervised Learning Optimization Problem

- **Empirical Risk Minimization (ERM)**

Find optimal parameter/model  $w^*$  s.t.

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$

Loss function  
of the  $i$ -th  
data sample






# Supervised Learning Optimization Problem

- **Empirical Risk Minimization (ERM)**

Find optimal parameter/model  $w^*$  s.t.

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$


Loss function  
of the  $i$ -th  
data sample


with

- $f$  is  $L$ -smooth and  $\mu$ -strongly convex
- $f_i$  is  $L_i$ -smooth,  $\forall i \in [n] := \{1, \dots, n\}$

# Supervised Learning Optimization Problem

- **Empirical Risk Minimization (ERM)**

Find optimal parameter/model  $w^*$  s.t.

$$w^* = \arg \min_{w \in \mathbb{R}^d} \left[ f(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) \right] \quad (\mathcal{P})$$


Loss function  
of the  $i$ -th  
data sample

with

- $f$  is  $L$ -smooth and  $\mu$ -strongly convex
- $f_i$  is  $L_i$ -smooth,  $\forall i \in [n] := \{1, \dots, n\}$

- **Includes problems such as**

- Ridge regression:  $f_i(w) = \frac{1}{2}(a_i^\top w - y_i)^2 + \frac{\lambda}{2} \|w\|_2^2$
- Regularized logistic regression:  $f_i(w) = \log(1 + e^{-y_i a_i^\top w}) + \frac{\lambda}{2} \|w\|_2^2$

where

- $a_i \in \mathbb{R}^d$ : feature vector (input)
- $y_i \in \mathbb{R}$  or  $\{-1, 1\}$ : label (output)
- $\lambda > 0$ : ridge/Tikhonov's regularization parameter

# Solving the ERM Problem

Given a precision  $\epsilon > 0$

# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**

- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**

- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

- **SAGA (or SVRG/SARAH)**

Let  $L_{\max} := \max_{i \in [n]} L_i$

- Step update:  $w^{k+1} = w^k - \frac{1}{3(n\mu + L_{\max})} \left[ \nabla f_i(w^k) - J_{:i}^k + \frac{1}{n} J^k \mathbf{1} \right]$
- Iteration complexity:  $\mathcal{O}\left(\left(\frac{L_{\max}}{\mu} + n\right) \log(1/\epsilon)\right)$

# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**


- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

- **SAGA (or SVRG/SARAH)**

Let  $L_{\max} := \max_{i \in [n]} L_i$

- Step update:  $w^{k+1} = w^k - \frac{1}{3(n\mu + L_{\max})} \left[ \nabla f_i(w^k) - J_{:i}^k + \frac{1}{n} J^k \mathbf{1} \right]$
- Iteration complexity:  $\mathcal{O}\left(\left(\frac{L_{\max}}{\mu} + n\right) \log(1/\epsilon)\right)$

Previous gradients  
stored in the  
Jacobian estimate



# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**

- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

- **SAGA (or SVRG/SARAH)**


Let  $L_{\max} := \max_{i \in [n]} L_i$

- Step update:  $w^{k+1} = w^k - \frac{1}{3(n\mu + L_{\max})} \left[ \nabla f_i(w^k) - J_{:i}^k + \frac{1}{n} J^k \mathbf{1} \right]$
- Iteration complexity:  $\mathcal{O}\left(\left(\frac{L_{\max}}{\mu} + n\right) \log(1/\epsilon)\right)$

- Distance between  $L$  and  $L_{\max}$

$$L \leq L_{\max} \leq nL$$

Previous gradients  
stored in the  
Jacobian estimate



# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**

- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

- **SAGA (or SVRG/SARAH)**

Let  $L_{\max} := \max_{i \in [n]} L_i$

- Step update:  $w^{k+1} = w^k - \frac{1}{3(n\mu + L_{\max})} \left[ \nabla f_i(w^k) - J_{:i}^k + \frac{1}{n} J^k \mathbf{1} \right]$
- Iteration complexity:  $\mathcal{O}\left(\left(\frac{L_{\max}}{\mu} + n\right) \log(1/\epsilon)\right)$

- Distance between  $L$  and  $L_{\max}$

$$L \leq L_{\max} \leq nL$$

Previous gradients  
stored in the  
Jacobian estimate

When  $n$  is big  
possibly  $L \ll L_{\max}$



# Solving the ERM Problem

Given a precision  $\epsilon > 0$

- **Gradient Descent (GD)**

- Step update:  $w^{k+1} = w^k - \frac{1}{L} \nabla f(w^k)$
- Iteration complexity:  $\mathcal{O}\left(\frac{L}{\mu} \log(1/\epsilon)\right)$

- **SAGA (or SVRG/SARAH)**

Let  $L_{\max} := \max_{i \in [n]} L_i$

- Step update:  $w^{k+1} = w^k - \frac{1}{3(n\mu + L_{\max})} \left[ \nabla f_i(w^k) - J_{:i}^k + \frac{1}{n} J^k \mathbf{1} \right]$
- Iteration complexity:  $\mathcal{O}\left(\left(\frac{L_{\max}}{\mu} + n\right) \log(1/\epsilon)\right)$

- Distance between  $L$  and  $L_{\max}$

$$L \leq L_{\max} \leq nL$$

→ Can we benefit from mini-batching to find an interpolating smoothness s.t.  $L \stackrel{?}{\leq} \mathcal{L} \stackrel{?}{\leq} L_{\max}$  ?

Previous gradients  
stored in the  
Jacobian estimate

When  $n$  is big  
possibly  $L \ll L_{\max}$

## Key Constant: Expected Smoothness

### Definition (Subsample/batch function)

Let  $B \subseteq [n]$  a mini-batch of size  $|B| = b$

$$f_B(w) := \frac{1}{b} \sum_{i \in B} f_i(w)$$

and denote  $L_B$  be the smallest constant s.t.  $f_B$  is  $L_B$ -smooth.

# Key Constant: Expected Smoothness

## Definition (Subsample/batch function)

Let  $B \subseteq [n]$  a mini-batch of size  $|B| = b$

$$f_B(w) := \frac{1}{b} \sum_{i \in B} f_i(w)$$

and denote  $L_B$  be the smallest constant s.t.  $f_B$  is  $L_B$ -smooth.

Recovering known smoothness constants

- $B = [n] \implies L_B = L$
- $B = \{i\} \implies L_B = L_i$

# Key Constant: Expected Smoothness

## Definition (Subsample/batch function)

Let  $B \subseteq [n]$  a mini-batch of size  $|B| = b$

$$f_B(w) := \frac{1}{b} \sum_{i \in B} f_i(w)$$

and denote  $L_B$  be the smallest constant s.t.  $f_B$  is  $L_B$ -smooth.

Recovering known smoothness constants

- $B = [n] \implies L_B = L$
- $B = \{i\} \implies L_B = L_i$

## Assumption (Expected Smoothness)

Let  $S \subseteq [n]$  be a random set of  $b$  points sampled without replacement.  
There exist  $\mathcal{L}(b) > 0$  s.t.

$$\mathbb{E} \left[ \|\nabla f_S(w) - \nabla f_S(w^*)\|_2^2 \right] \leq 2\mathcal{L}(b) (f(w) - f(w^*))$$

## Key Constant: Expected Smoothness (cont'd)

### Definition ( $b$ -sampling without replacement)

$S$  (a random set-valued mapping) is a  $b$ -sampling without replacement if

$$\mathbb{P}[S = B] = \frac{1}{\binom{n}{b}} \quad \forall B \subset [n] : |B| = b$$

## Key Constant: Expected Smoothness (cont'd)

### Definition ( $b$ -sampling without replacement)

$S$  (a random set-valued mapping) is a  $b$ -sampling without replacement if

$$\mathbb{P}[S = B] = \frac{1}{\binom{n}{b}} \quad \forall B \subset [n] : |B| = b$$

### Lemma (Expected smoothness formula)

For  $b$ -sampling without replacement,

$$\mathcal{L}(b) := \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\}$$

Consequence of  $f_B$  being  $L_B$ -smooth and convex for a  $B \subseteq [n]$

## Key Constant: Expected Smoothness (cont'd)

### Definition ( $b$ -sampling without replacement)

$S$  (a random set-valued mapping) is a  $b$ -sampling without replacement if

$$\mathbb{P}[S = B] = \frac{1}{\binom{n}{b}} \quad \forall B \subset [n] : |B| = b$$

### Lemma (Expected smoothness formula)

For  $b$ -sampling without replacement,

$$\mathcal{L}(b) := \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\}$$

Consequence of  $f_B$  being  $L_B$ -smooth and convex for a  $B \subseteq [n]$

**Problem: calculating  $\mathcal{L}(b)$  is intractable for large  $n$**

## Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ —sampling without replacement

$$\mathcal{L}(b) = \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\}$$



# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(1) = \frac{1}{\binom{n-1}{0}} \max_{i=1,\dots,n} \left\{ \sum_{B \subseteq [n]: |B|=1 \wedge i \in B} L_B \right\}$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(1) = \frac{1}{\binom{n-1}{0}} \max_{i=1,\dots,n} \left\{ \sum_{B \in \{\{1\}, \dots, \{n\}\} : i \in B} L \right\}$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(1) = \max_{i=1,\dots,n} L_i$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(1) = \max_{i=1,\dots,n} L_i$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(n) = \frac{1}{\binom{n-1}{n-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n]: |B|=n \wedge i \in B} L \right\}$$

- If  $b = 1$

- Recovered algorithm: SAGA
- $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

- If  $b = n$

- Recovered algorithm: Gradient Descent

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(n) = \max_{i=1,\dots,n} \left\{ \sum_{B=[n]} L_B \right\}$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

- If  $b = n$ 
  - Recovered algorithm: Gradient Descent
  - $B = [n]$

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(n) = \max_{i=1,\dots,n} L$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

- If  $b = n$ 
  - Recovered algorithm: Gradient Descent
  - $B = [n]$

# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(n) = L$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

- If  $b = n$ 
  - Recovered algorithm: Gradient Descent
  - $B = [n]$

$$\mathcal{L}(n) = L$$



# Extreme Values of the Expected Smoothness

Let  $S$  be a  $b$ -sampling without replacement

$$\mathcal{L}(n) = L$$

- If  $b = 1$ 
  - Recovered algorithm: SAGA
  - $B \in \{\{1\}, \dots, \{n\}\}$

$$\mathcal{L}(1) = L_{\max}$$

- If  $b = n$ 
  - Recovered algorithm: Gradient Descent
  - $B = [n]$

$$\mathcal{L}(n) = L$$

→  $\mathcal{L}(b)$  interpolates between  $L_{\max}$  and  $L$

## **Optimal Mini-Batch and Step Sizes for SAGA**

---

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

- Sample a mini-batch  $B \subset [n]$  s.t.  $|B| = b$

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

- Sample a mini-batch  $B \subset [n]$  s.t.  $|B| = b$
- Compute a gradient estimate

$$g(w^k) = \frac{1}{b} \sum_{i \in B} \nabla f_i(w^k) - \frac{1}{b} \sum_{i \in B} \mathbf{J}_{:,i}^k + \frac{1}{n} \mathbf{J}^k \mathbf{1}$$

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

- Sample a mini-batch  $B \subset [n]$  s.t.  $|B| = b$
- Compute a gradient estimate

$$g(w^k) = \frac{1}{b} \sum_{i \in B} \nabla f_i(w^k) - \frac{1}{b} \sum_{i \in B} \mathbf{J}_{:,i}^k + \frac{1}{n} \mathbf{J}^k \mathbf{1}$$

- Take a step

$$w^{k+1} = w^k - \gamma g(w^k)$$

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

- Sample a mini-batch  $B \subset [n]$  s.t.  $|B| = b$
- Compute a gradient estimate

$$g(w^k) = \frac{1}{b} \sum_{i \in B} \nabla f_i(w^k) - \frac{1}{b} \sum_{i \in B} J_{:,i}^k + \frac{1}{n} J^k \mathbf{1}$$

- Take a step

$$w^{k+1} = w^k - \gamma g(w^k)$$

- Update the **Jacobian estimate**  $J^k$

$$J_{:,i}^k = \nabla f_i(w^k), \quad \forall i \in B$$

# Mini-Batch SAGA

- The algorithm

For  $k = 0, 1, 2, \dots$

- Sample a mini-batch  $B \subset [n]$  s.t.  $|B| = b$
- Compute a gradient estimate

$$g(w^k) = \frac{1}{b} \sum_{i \in B} \nabla f_i(w^k) - \frac{1}{b} \sum_{i \in B} J_{:,i}^k + \frac{1}{n} J^k \mathbf{1}$$

- Take a step

$$w^{k+1} = w^k - \gamma g(w^k)$$

- Update the Jacobian estimate  $J^k$

$$J_{:,i}^k = \nabla f_i(w^k), \quad \forall i \in B$$

- What is the optimal mini-batch size?

→ Find the “best”  $b$  value



# Mini-Batch SAGA Iteration Complexity

## Theorem (Convergence of mini-batch SAGA<sup>1</sup>)

Consider the iterates  $w^k$  of the mini-batch SAGA algorithm. Let the step size be

$$\gamma(b) = \frac{1}{4} \frac{1}{\max \left\{ \mathcal{L}(b), \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b} \right\}}$$

Given an  $\epsilon > 0$ , if  $k \geq K_{\text{iter}}(b)$  where

$$k \geq K_{\text{iter}}(b) := \left\{ \frac{4\mathcal{L}(b)}{\mu}, \frac{n}{b} + \frac{n-b}{n-1} \frac{4L_{\max}}{b\mu} \right\} \log \left( \frac{1}{\epsilon} \right) \implies \mathbb{E} \left[ \|w^k - w^*\|^2 \right] \leq \epsilon C .$$

with  $C > 0$  a constant<sup>a</sup>.

$$^a C := \|w^0 - w^*\|^2 + \frac{\gamma}{2L_{\max}} \sum_{i \in [n]} \|J_{:,i}^0 - \nabla f(w^*)\|^2$$

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, "Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching"

Given a precision  $\epsilon > 0$ ,

- **Optimal mini-batch size**


$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, “Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching”

Given a precision  $\epsilon > 0$ ,

#gradients  
per iteration



- **Optimal mini-batch size**

$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, “Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching”

# Methodology

Given a precision  $\epsilon > 0$ ,

- **Optimal mini-batch size**

#gradients  
per iteration

#iterations  $k$  to achieve  
 $\mathbb{E} [\|w^k - w^*\|^2] \leq \epsilon C$


$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, “Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching”

# Methodology

Given a precision  $\epsilon > 0$ ,

#gradients  
per iteration

#iterations  $k$  to achieve  
 $\mathbb{E} [\|w^k - w^*\|^2] \leq \epsilon C$

- **Optimal mini-batch size**

$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

- **Total complexity<sup>1</sup>**

$$K_{\text{total}}(b) = \max \left\{ \frac{4b\mathcal{L}(b)}{\mu}, n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu} \right\} \log \left( \frac{1}{\epsilon} \right)$$

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, "Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching"

# Methodology

Given a precision  $\epsilon > 0$ ,

#gradients  
per iteration

#iterations  $k$  to achieve  
 $\mathbb{E} [\|w^k - w^*\|^2] \leq \epsilon C$

- **Optimal mini-batch size**

$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

- **Total complexity<sup>1</sup>**

$$K_{\text{total}}(b) = \max \left\{ \frac{4b\mathcal{L}(b)}{\mu}, n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu} \right\} \log \left( \frac{1}{\epsilon} \right)$$

- **Importance of expected smoothness**

- $\mathcal{L}(b)$  embodies the complexity
- Gives larger step sizes  $\gamma$

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, "Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching"

# Methodology

Given a precision  $\epsilon > 0$ ,

#gradients  
per iteration

#iterations  $k$  to achieve  
 $\mathbb{E} [\|w^k - w^*\|^2] \leq \epsilon C$

- **Optimal mini-batch size**

$$\text{find } b^* \in \arg \min_{b \in [n]} K_{\text{total}}(b) = b \times K_{\text{iter}}(b)$$

- **Total complexity<sup>1</sup>**

$$K_{\text{total}}(b) = \max \left\{ \frac{4b\mathcal{L}(b)}{\mu}, n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu} \right\} \log \left( \frac{1}{\epsilon} \right)$$

- **Importance of expected smoothness**

- $\mathcal{L}(b)$  embodies the complexity
- Gives larger step sizes  $\gamma$

→ **Need to estimate  $\mathcal{L}(b)$**

---

<sup>1</sup>Gower et al (2018), arXiv:1805.02632, "Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching"

# First Proven Upper-Bound

## Lemma (Simple bound)

*If  $S$  is a  $b$ -sampling without replacement,*

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{simple}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \bar{L}$$

where  $\bar{L} := \frac{1}{n} \sum_{i=1}^n L_i$



# First Proven Upper-Bound

## Lemma (Simple bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{simple}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{n-1}{n-1} \bar{L}$$

where  $\bar{L} := \frac{1}{n} \sum_{i=1}^n L_i$

- $\mathcal{L}_{\text{simple}}(b)$  interpolates between  $L_{\max}$  and  $\bar{L} \geq L \dots$

# First Proven Upper-Bound

## Lemma (Simple bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{simple}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{n-1}{n-1} \bar{L}$$

where  $\bar{L} := \frac{1}{n} \sum_{i=1}^n L_i$

- $\mathcal{L}_{\text{simple}}(b)$  interpolates between  $L_{\max}$  and  $\bar{L} \geq L \dots$
- ... but  $\mathcal{L}(b)$  interpolates between  $L_{\max}$  and  $L$

## Lemma (Simple bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{simple}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{n-1}{n-1} \bar{L}$$

where  $\bar{L} := \frac{1}{n} \sum_{i=1}^n L_i$

- $\mathcal{L}_{\text{simple}}(b)$  interpolates between  $L_{\max}$  and  $\bar{L} \geq L \dots$
- ... but  $\mathcal{L}(b)$  interpolates between  $L_{\max}$  and  $L$

**Problem:  $\bar{L}$  and  $L$  can be far from each other**

# Exploiting Matrix Concentration Inequalities

## Lemma (Bernstein bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{Bernstein}}(b) := \frac{1}{b} \left( \frac{n-b}{n-1} + \frac{4}{3} \log(d) \right) L_{\max} + 2 \frac{b-1}{b} \frac{n}{n-1} L$$

# Exploiting Matrix Concentration Inequalities

## Lemma (Bernstein bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{Bernstein}}(b) := \frac{1}{b} \left( \frac{n-b}{n-1} + \frac{4}{3} \log(d) \right) L_{\max} + 2 \frac{b-1}{b} \frac{n}{n-1} L$$

- **Proof idea**

$$\begin{aligned} \mathcal{L}(b) &= \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\} \\ &\leq [\dots] + \max_{i=1, \dots, n} \mathbb{E} \left[ \lambda_{\max} \left( \sum_k \mathbf{M}_k^i \right) \right] \end{aligned}$$

where  $(\mathbf{M}_k^i)_k$  is a sequence of random matrices

# Exploiting Matrix Concentration Inequalities

## Lemma (Bernstein bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{Bernstein}}(b) := \frac{1}{b} \left( \frac{n-b}{n-1} + \frac{4}{3} \log(d) \right) L_{\max} + 2 \frac{b-1}{b} \frac{n}{n-1} L$$

- **Proof idea**

$$\begin{aligned} \mathcal{L}(b) &= \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\} \\ &\leq [\dots] + \max_{i=1, \dots, n} \mathbb{E} \left[ \lambda_{\max} \left( \sum_k \mathbf{M}_k^i \right) \right] \end{aligned}$$

where  $(\mathbf{M}_k^i)_k$  is a sequence of random matrices

- **Technical detail**

Adapt Matrix Bernstein Inequality to sampling without replacement<sup>2</sup>

---

<sup>2</sup>Gross & Nesme (2010), Tropp (2011, 2015)

# Exploiting Matrix Concentration Inequalities

## Lemma (Bernstein bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{Bernstein}}(b) := \frac{1}{b} \left( \frac{n-b}{n-1} + \frac{4}{3} \log(d) \right) L_{\max} + 2 \frac{b-1}{b} \frac{n}{n-1} L$$

- **Proof idea**

$$\begin{aligned} \mathcal{L}(b) &= \frac{1}{\binom{n-1}{b-1}} \max_{i=1, \dots, n} \left\{ \sum_{B \subseteq [n] : |B|=b \wedge i \in B} L_B \right\} \\ &\leq [\dots] + \max_{i=1, \dots, n} \mathbb{E} \left[ \lambda_{\max} \left( \sum_k \mathbf{M}_k^i \right) \right] \end{aligned}$$

where  $(\mathbf{M}_k^i)_k$  is a sequence of random matrices

- **Technical detail**

Adapt Matrix Bernstein Inequality to sampling without replacement<sup>2</sup>

**Problem:**  $\mathcal{L}_{\text{Bernstein}}(b)$  approximation interpolates between  
 $\approx \log(d) L_{\max}$  and  $2L$

<sup>2</sup>Gross & Nesme (2010), Tropp (2011, 2015)

# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{b-1}{n-1} L$$



# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{n-1}{n-1} L$$

$L$  instead of  $\bar{L}$  in  
the simple bound

# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{b-1}{n-1} L$$

- Nicely interpolation between  $L_{\max}$  and  $L \dots$

$L$  instead of  $\bar{L}$  in  
the simple bound

# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{b-1}{n-1} L$$

- Nicely interpolation between  $L_{\max}$  and  $L$  ...
- ... Yet, not a proven bound:  $\mathcal{L}(b) \stackrel{?}{\leq} \mathcal{L}_{\text{practical}}(b)$

$L$  instead of  $\bar{L}$  in  
the simple bound

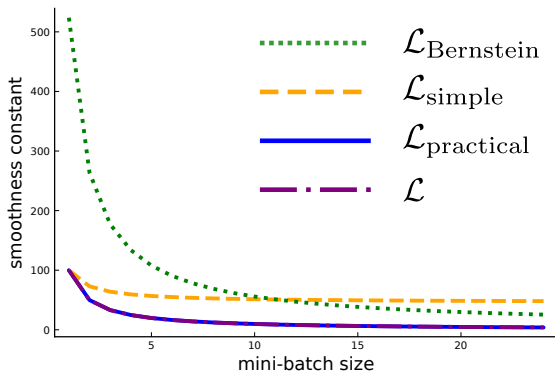
# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{b-1}{n-1} L$$

- Nicely interpolation between  $L_{\max}$  and  $L$  ...
- ... Yet, not a proven bound:  $\mathcal{L}(b) \stackrel{?}{\leq} \mathcal{L}_{\text{practical}}(b)$

$L$  instead of  $\bar{L}$  in  
the simple bound

Upper bounds and  $\mathcal{L}(b)$   
computed on artificial data  
( $n = d = 24$ )



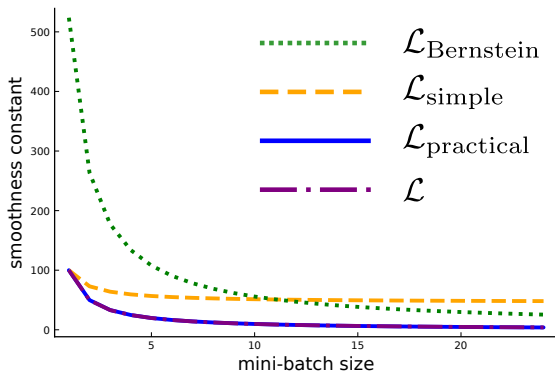
# The “Practical” Estimate

$$\mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{b-1}{n-1} L$$

- Nicely interpolation between  $L_{\max}$  and  $L$  ...
- ... Yet, not a proven bound:  $\mathcal{L}(b) \stackrel{?}{\leq} \mathcal{L}_{\text{practical}}(b)$

$L$  instead of  $\bar{L}$  in  
the simple bound

Upper bounds and  $\mathcal{L}(b)$   
computed on artificial data  
( $n = d = 24$ )



→ Numerically  $\mathcal{L}_{\text{practical}}(b) \approx \mathcal{L}(b)$

# Optimal Mini-Batch from the “Practical” Estimate

Given a precision  $\epsilon > 0$ ,

- **Total complexity bound**

Since  $\mathcal{L}(b) \leq \mathcal{L}_{\text{practical}}(b)$ ,

$$K_{\text{total}}(b) \leq \max \left\{ n \frac{b-1}{n-1} \frac{4L}{\mu} + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}, n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu} \right\} \log \left( \frac{1}{\epsilon} \right)$$

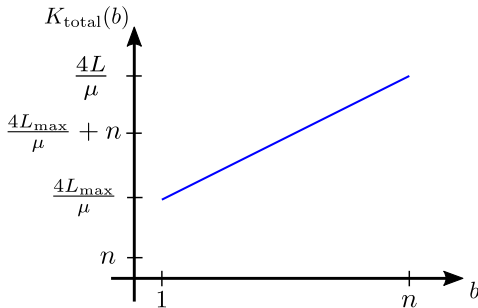
# Optimal Mini-Batch from the “Practical” Estimate

Given a precision  $\epsilon > 0$ ,

- **Total complexity bound**

Since  $\mathcal{L}(b) \leq \mathcal{L}_{\text{practical}}(b)$ ,

$$K_{\text{total}}(b) \leq \max \left\{ \underbrace{n \frac{b-1}{n-1} \frac{4L}{\mu} + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}}_{\text{linearly increasing}}, n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu} \right\} \log \left( \frac{1}{\epsilon} \right)$$



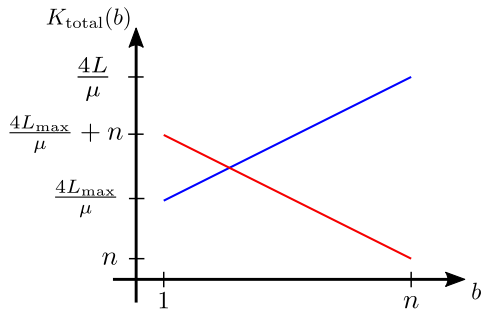
# Optimal Mini-Batch from the “Practical” Estimate

Given a precision  $\epsilon > 0$ ,

- **Total complexity bound**

Since  $\mathcal{L}(b) \leq \mathcal{L}_{\text{practical}}(b)$ ,

$$K_{\text{total}}(b) \leq \max \left\{ \underbrace{n \frac{b-1}{n-1} \frac{4L}{\mu} + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}}_{\text{linearly increasing}}, \underbrace{n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}}_{\text{linearly decreasing}} \right\} \log \left( \frac{1}{\epsilon} \right)$$





# Optimal Mini-Batch from the “Practical” Estimate

Given a precision  $\epsilon > 0$ ,

- **Total complexity bound**

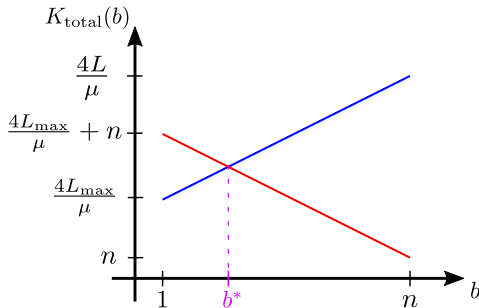
Since  $\mathcal{L}(b) \leq \mathcal{L}_{\text{practical}}(b)$ ,

$$K_{\text{total}}(b) \leq \max \left\{ \underbrace{n \frac{b-1}{n-1} \frac{4L}{\mu} + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}}_{\text{linearly increasing}}, \underbrace{n + \frac{n-b}{n-1} \frac{4L_{\max}}{\mu}}_{\text{linearly decreasing}} \right\} \log \left( \frac{1}{\epsilon} \right)$$

## Optimal mini-batch size

$\Rightarrow$

$$b_{\text{practical}} = \left\lfloor 1 + \frac{\mu(n-1)}{4L} \right\rfloor$$



## Mini-Batch SAGA Step Sizes

- Link between the step size and the expected smoothness

$$\gamma(b) = \frac{1}{4} \frac{1}{\max \left\{ \mathcal{L}(b), \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b} \right\}}$$

## Mini-Batch SAGA Step Sizes

- Link between the step size and the expected smoothness

$$\gamma(b) = \frac{1}{4} \frac{1}{\max \left\{ \mathcal{L}(b), \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b} \right\}}$$

- The smaller  $\mathcal{L}(b)$  (the smoother  $f_B$ ), the larger  $\gamma(b)$

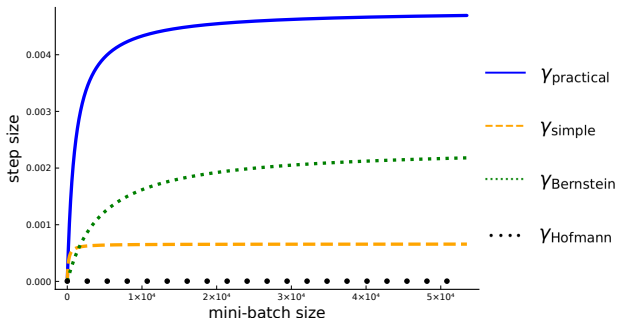
# Mini-Batch SAGA Step Sizes

- Link between the step size and the expected smoothness

$$\gamma(b) = \frac{1}{4} \frac{1}{\max \left\{ \mathcal{L}(b), \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b} \right\}}$$

- The smaller  $\mathcal{L}(b)$  (the smoother  $f_B$ ), the larger  $\gamma(b)$
- Plugging  $\mathcal{L}_{\text{practical}}(b)$ ,  $\mathcal{L}_{\text{simple}}(b)$  or  $\mathcal{L}_{\text{Bernstein}}(b)$  into  $\gamma(b)$

Step size increasing with  
mini-batch size  
on *slice* data set  
( $n = 53,500, d = 384$ )



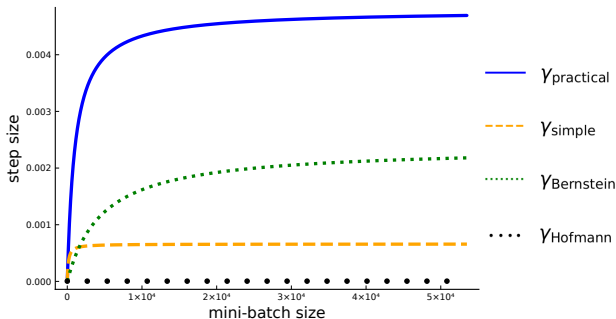
# Mini-Batch SAGA Step Sizes

- Link between the step size and the expected smoothness

$$\gamma(b) = \frac{1}{4} \frac{1}{\max \left\{ \mathcal{L}(b), \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b} \right\}}$$

- The smaller  $\mathcal{L}(b)$  (the smoother  $f_B$ ), the larger  $\gamma(b)$
- Plugging  $\mathcal{L}_{\text{practical}}(b)$ ,  $\mathcal{L}_{\text{simple}}(b)$  or  $\mathcal{L}_{\text{Bernstein}}(b)$  into  $\gamma(b)$

Step size increasing with  
mini-batch size  
on *slice* data set  
( $n = 53,500, d = 384$ )

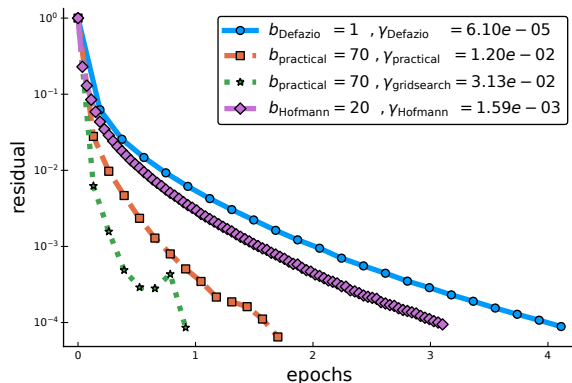


→ Straightforward and larger step size for large  $b$

# Numerical Experiments

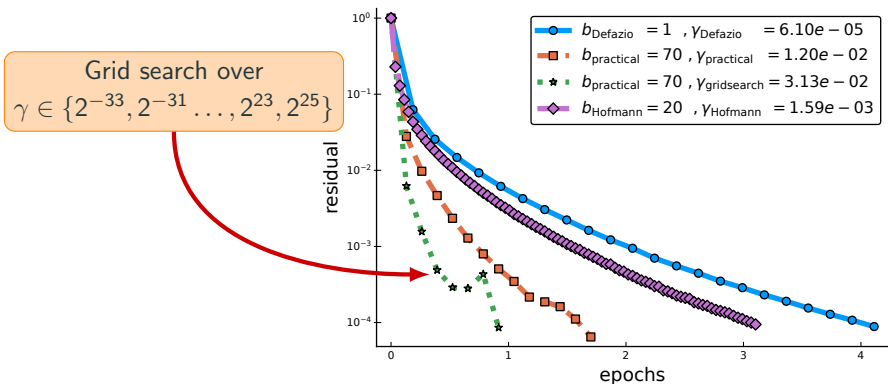
---

# Convergence Results on Real Data



Comparison of SAGA settings for the  $\text{slice}^3$  data set  
( $n = 53,500, d = 384$ )

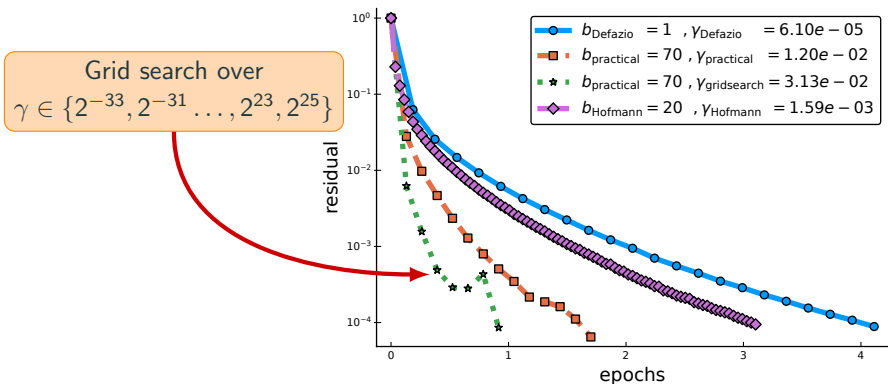
# Convergence Results on Real Data



Comparison of SAGA settings for the *slice*<sup>3</sup> data set  
( $n = 53,500, d = 384$ )



# Convergence Results on Real Data

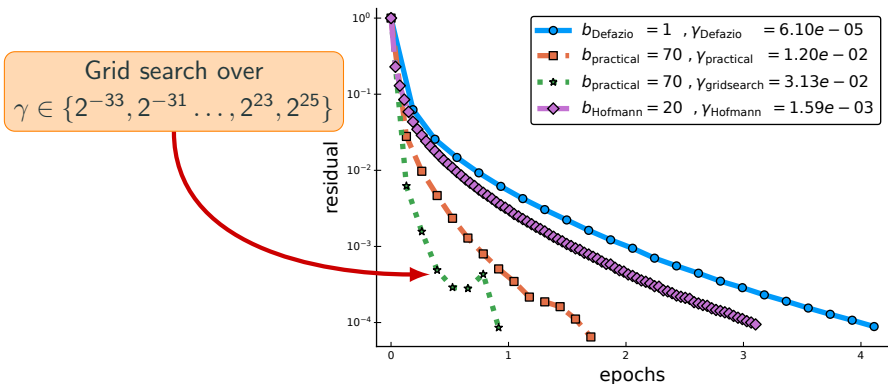


Comparison of SAGA settings for the *slice*<sup>3</sup> data set  
( $n = 53,500, d = 384$ )

→ **Larger mini-batch and step sizes: faster convergence**

<sup>3</sup>UCI Machine Learning Repository

# Convergence Results on Real Data



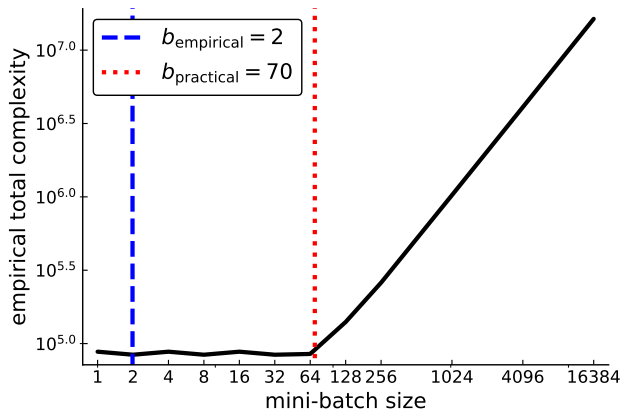
Comparison of SAGA settings for the *slice*<sup>3</sup> data set  
( $n = 53,500, d = 384$ )

→ **Larger mini-batch and step sizes: faster convergence**

→ **Competing against grid-search!**

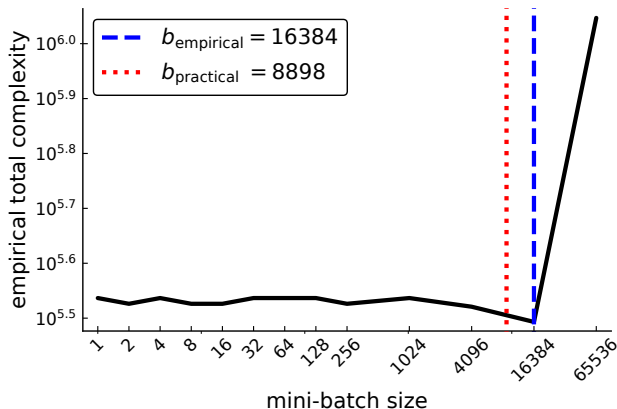
<sup>3</sup>UCI Machine Learning Repository

# Optimality of Our Mini-Batch Size



Complexity explosion for the *slice* data set ( $n = 53,500, d = 384$ )

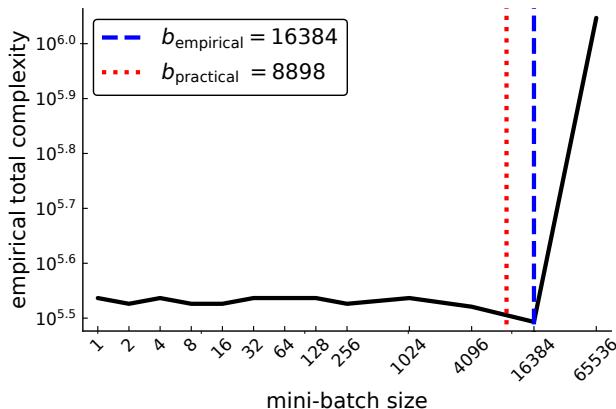
## Optimality of Our Mini-Batch Size (cont'd)



Complexity explosion for the *real-sim*<sup>4</sup> data set ( $n = 72,309$ ,  $d = 20,958$ )

<sup>4</sup>LIBSVM Data

# Optimality of Our Mini-Batch Size (cont'd)



Complexity explosion for the *real-sim*<sup>4</sup> data set ( $n = 72,309$ ,  $d = 20,958$ )

→ Regime change observed & predicting the largest mini-batch size before complexity explosion

<sup>4</sup>LIBSVM Data

## Conclusion

---

## What was done for SAGA

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

# Summary of Our Contributions

## What was done for SAGA

- Estimates of the expected smoothness

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”



# Summary of Our Contributions

## What was done for SAGA

- Estimates of the expected smoothness

Turned out that  
 $\mathcal{L}_{\text{practical}}(b)$   
is an actual  
upper-bound!<sup>4</sup>

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

# Summary of Our Contributions

## What was done for SAGA

- Estimates of the expected smoothness
- Simple formula for the step size  $\gamma(b)$

Turned out that  
 $\mathcal{L}_{\text{practical}}(b)$   
is an actual  
upper-bound!<sup>4</sup>

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

# Summary of Our Contributions

Turned out that  
 $\mathcal{L}_{\text{practical}}(b)$   
is an actual  
upper-bound!<sup>4</sup>

## What was done for SAGA

- Estimates of the expected smoothness
- Simple formula for the step size  $\gamma(b)$
- Optimal mini-batch size  $b_{\text{practical}}$

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

# Summary of Our Contributions

Turned out that  $\mathcal{L}_{\text{practical}}(b)$  is an actual upper-bound!<sup>4</sup>

## What was done for SAGA

- Estimates of the expected smoothness
- Simple formula for the step size  $\gamma(b)$
- Optimal mini-batch size  $b_{\text{practical}}$
- Convincing numerics verifying the optimality of our parameters on real data sets<sup>5</sup>

Julia code available at

<https://github.com/gowerrobert/StochOpt.jl/>

## What has been done since then

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

# Summary of Our Contributions

Turned out that  
 $\mathcal{L}_{\text{practical}}(b)$   
is an actual  
upper-bound!<sup>4</sup>

## What was done for SAGA

- Estimates of the expected smoothness
- Simple formula for the step size  $\gamma(b)$
- Optimal mini-batch size  $b_{\text{practical}}$
- Convincing numerics verifying the optimality of our parameters on real data sets<sup>5</sup>

Julia code available at

<https://github.com/gowerrobert/StochOpt.jl/>

## What has been done since then

- Extended study to variants of SVRG<sup>6</sup>

---

<sup>4</sup>Gower et. al (2019), ICML, “SGD: General Analysis and Improved Rates”

<sup>5</sup>LIBSVM and UCI repositories

<sup>6</sup>Sebbouh et. al (2019), arXiv:1908.02725, “Towards closing the gap between the theory and practice of SVRG”

## References (1/2)

- Defazio, Bach and Lacoste-Julien (2014), NIPS  
**“SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives”**
- Gower, Richtárik and Bach (2018), preprint online arXiv:1805.02632  
**“Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching”**
- Gower, Loizou, Qian, Sailanbayev, Shulgin, Richtárik (2019), ICML  
**“SGD: General Analysis and Improved Rates”**
- Sebbouh, Gazagnadou, Jelassi, Bach, Gower (2019), preprint online arXiv:1908.02725  
**“Towards closing the gap between the theory and practice of SVRG”**
- Robbins and Monro (1951), Annals of Mathematical Statistics  
**“A stochastic approximation method”**
- Schmidt, Le Roux and Bach (2017), Mathematical Programming  
**“Minimizing finite sums with the stochastic average gradient”**
- Johnson and Zhang (2013), NIPS  
**“Accelerating Stochastic Gradient Descent using Predictive Variance Reduction”**

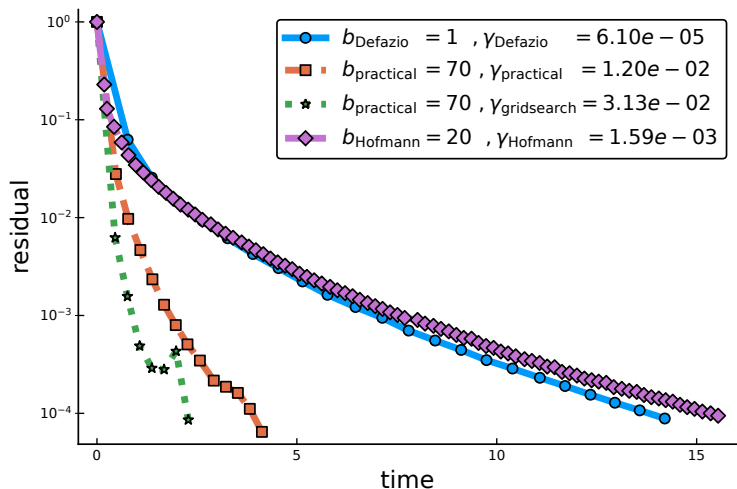
## References (2/2)

- Tropp (2015), Foundations and Trends® in Machine Learning  
**“An Introduction to Matrix Concentration Inequalities”**
- Tropp (2012), Foundations of Computational Mathematics  
**“User-Friendly Tail Bounds for Sums of Random Matrices”**
- Tropp (2011), Advances in Adaptive Data Analysis  
**“Improved analysis of the subsampled randomized Hadamard transform”**
- Bach (2013), COLT  
**“Sharp analysis of low-rank kernel matrix approximations”**
- Gross and Nesme (2010), preprint online arXiv:1001.2738  
**“Note on sampling without replacing from a finite collection of matrices”**
- Hoeffding (1963), Journal of the American Statistical Association  
**“Probability inequalities for sums of bounded random variables”**
- Chang and Lin (2011), ACM TIST  
**“LIBSVM : A library for support vector machines”**

**Questions ?**



# Time Plot Convergence Results on Real Data



Comparison of SAGA settings for the *slice*<sup>5</sup> data set  
( $n = 53,500, d = 384$ )

## Definition (Stochastic Lyapunov function)

$$\Psi^k := \|w^k - w^*\|_2^2 + \frac{\gamma}{2bL_{\max}} \|\mathbf{J}^k - \nabla \mathbf{F}(w^*)\|_F^2$$

- $\|\cdot\|_F$ : Frobenius norm
- $\nabla \mathbf{F}(w) = [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$ : Jacobian matrix
- $\{w^k, \mathbf{J}^k\}_{k \geq 0}$  are the points and Jacobian estimate

If  $\epsilon > 0$  denotes the desired precision, Theorem 3.6 ensures that, for a

$$\text{step size } \gamma = \min \left\{ \frac{1}{4\mathcal{L}}, \frac{1}{\frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{\mu}{4} \frac{n}{b}} \right\},$$

$$\mathbb{E} [\Psi^k] \leq \epsilon \Psi^0 .$$

---

<sup>7</sup>Gower et al (2018), arXiv:1805.02632, “Stochastic Quasi-Gradient Methods: Variance Reduction via Jacobian Sketching”

# Proof of the “Practical” Bound (1/2)

## Lemma (Practical bound)

If  $S$  is a  $b$ -sampling without replacement,

$$\mathcal{L}(b) \leq \mathcal{L}_{\text{practical}}(b) := \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{1}{n-1} L$$

**Proof:** See Proposition 3.8 in Gower et. al (2019), “SGD: General Analysis and Improved Rates”, Let  $S$  be a  $b$ -sampling without replacement with  $b \in [n]$ , and  $x, z \in \mathbb{R}^d$ . Let us denote

$$p_B := \mathbb{P}[S = B] = \frac{1}{\binom{n}{b}}, \quad p_i := \mathbb{P}[i \in S] = \frac{b}{n}, \quad p_{ij} := \mathbb{P}[i, j \in S] = \begin{cases} \frac{b(b-1)}{n(n-1)} & \text{if } i \neq j \\ \frac{n-b}{n} & \text{else} \end{cases},$$

for all  $B \subseteq [n]$  and all  $i, j \in [n]$ .

$$\begin{aligned} \|\nabla f_S(w) - \nabla f_S(z)\|_2^2 &= \frac{1}{n^2} \left\| \sum_{i \in S} \frac{1}{p_i} (\nabla f_i(w) - \nabla f_i(z)) \right\|_2^2 \\ &= \sum_{i, j \in S} \left\langle \frac{1}{np_i} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{np_j} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle \end{aligned}$$

Then, we take expectation over all possible mini-batches ( $B \subseteq [n] : |B| = b$ ).

$$\mathbb{E} \left[ \|\nabla f_S(w) - \nabla f_S(z)\|_2^2 \right] = \sum_B p_B \sum_{i, j \in B} \left\langle \frac{1}{np_i} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{np_j} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle$$

$$\stackrel{\text{double counting}}{=} \sum_{i, j=1}^n \sum_{B : i, j \in B} p_B \left\langle \frac{1}{np_i} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{np_j} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle$$

$$\sum_{B : i, j \in B} p_B = p_{ij} \sum_{i, j=1}^n \left\langle \frac{1}{np_i} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{np_j} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle p_{ij}$$

# Proof of the “Practical” Bound (2/2)

Now consider the two disjoint cases where  $i \neq j$  and  $i = j$ .

$$\begin{aligned}
 \mathbb{E} \left[ \|\nabla f_S(w) - \nabla f_S(z)\|_2^2 \right] &= \sum_{i,j=1}^n \frac{P_{ij}}{p_i p_j} \left\langle \frac{1}{n} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{n} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle \\
 &= \sum_{i,j: i \neq j} \frac{n(b-1)}{b(n-1)} \left\langle \frac{1}{n} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{n} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle + \sum_{i=1}^n \frac{1}{n^2} \frac{1}{p_i} \|\nabla f_i(w) - \nabla f_i(z)\|_2^2 \\
 &= \sum_{i,j=1}^n \frac{n(b-1)}{b(n-1)} \left\langle \frac{1}{n} (\nabla f_i(w) - \nabla f_i(z)), \frac{1}{n} (\nabla f_j(w) - \nabla f_j(z)) \right\rangle \\
 &\quad + \sum_{i=1}^n \frac{1}{n^2} \frac{1}{p_i} \left( 1 - \frac{n(b-1)}{b(n-1)} p_i \right) \|\nabla f_i(w) - \nabla f_i(z)\|_2^2 \\
 &\stackrel{f_i \text{ smooth} \& \text{ convex}}{\leq} \frac{n(b-1)}{b(n-1)} \|\nabla f(w) - \nabla f(z)\|_2^2 + 2 \sum_{i=1}^n \frac{L_i}{n^2 p_i} \left( 1 - \frac{n(b-1)}{b(n-1)} p_i \right) (f_i(w) - f_i(z) - \langle \nabla f_i(z), w - z \rangle) \\
 &\stackrel{f \text{ smooth} \& \text{ convex}}{\leq} 2 \left( \frac{n(b-1)}{b(n-1)} L + \max_{i=1, \dots, n} \frac{L_i}{n p_i} \left( 1 - \frac{n(b-1)}{b(n-1)} p_i \right) \right) (f(w) - f(z) - \langle \nabla f(z), w - z \rangle) \\
 &= 2 \left( \frac{n(b-1)}{b(n-1)} L + \max_{i=1, \dots, n} \frac{L_i}{b} \left( 1 - \frac{b-1}{n-1} \right) \right) (f(w) - f(z) - \langle \nabla f(z), w - z \rangle) \\
 &= 2 \underbrace{\left( \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b(n-1)} L \right)}_{\mathcal{L}_{\text{practical}}(b)} (f(w) - f(z) - \langle \nabla f(z), w - z \rangle)
 \end{aligned}$$

# From Sampling Without to With Replacement

## Lemma (Domination of the trace of the mgf of a sample without replacement)

*Consider two finite sequences, of same length,  $\{\mathbf{X}_k\}$  and  $\{\mathbf{M}_k\}$  of Hermitian random matrices of same size sampled respectively with and without replacement from a finite set  $\mathcal{X}$ . Let  $\theta \in \mathbb{R}$ , then*

$$\mathbb{E} \operatorname{tr} \exp \left( \theta \sum_k \mathbf{M}_k \right) \leq \mathbb{E} \operatorname{tr} \exp \left( \theta \sum_k \mathbf{X}_k \right) .$$

See Gross and Nesme (2010), arXiv:1001.2738,  
“Note on sampling without replacing from a finite collection of matrices”

# Proof Sketch of the Bernstein Bound (1/2)

(i) Write  $\mathcal{L}$  as an **expectation**

$$\begin{aligned}\mathcal{L} &= \max_{i=1,\dots,n} \mathbb{E} [L_{S^i \cup \{i\}}] \\ &= \max_{i=1,\dots,n} \mathbb{E} \left[ \lambda_{\max} \left( \frac{1}{b} \sum_{j \in S^i \cup \{i\}} a_j a_j^\top \right) \right] \\ &\leq \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b} \frac{1}{n-1} L \\ &\quad + \max_{i=1,\dots,n} \mathbb{E} \left[ \lambda_{\max} \left( \underbrace{\frac{1}{b} \sum_{j \in S^i} a_j a_j^\top - \frac{1}{b} \frac{b-1}{n-1} \sum_{j \in [n] \setminus \{i\}} a_j a_j^\top}_{\mathbf{N} = \sum_k \mathbf{M}_k} \right) \right]\end{aligned}$$

# Proof Sketch of the Bernstein Bound (1/2)

(i) Write  $\mathcal{L}$  as an **expectation**

$$\begin{aligned}
 \mathcal{L} &= \max_{i=1,\dots,n} \mathbb{E} [L_{S^i \cup \{i\}}] \\
 &= \max_{i=1,\dots,n} \mathbb{E} \left[ \lambda_{\max} \left( \frac{1}{b} \sum_{j \in S^i \cup \{i\}} a_j a_j^\top \right) \right] \\
 &\leq \frac{1}{b} \frac{n-b}{n-1} L_{\max} + \frac{n-b-1}{b(n-1)} L \\
 &\quad + \max_{i=1,\dots,n} \mathbb{E} \left[ \lambda_{\max} \left( \underbrace{\frac{1}{b} \sum_{j \in S^i} a_j a_j^\top - \frac{1}{b} \frac{b-1}{n-1} \sum_{j \in [n] \setminus \{i\}} a_j a_j^\top}_{\mathbf{N} = \sum_k \mathbf{M}_k} \right) \right]
 \end{aligned}$$

Practical approximation

## Proof Sketch of the Bernstein Bound (2/2)

(ii) Write  $\mathbf{N}$  as a sum of random matrices and apply

### Theorem (Matrix Bernstein Inequality Without Replacement)

Let  $\mathcal{X}$  be a finite set of Hermitian matrices with dimension  $d$  s.t.

$$\lambda_{\max}(\mathbf{X}) \leq L \quad \forall \mathbf{X} \in \mathcal{X} .$$

Sample  $\{\mathbf{X}_k\}$  and  $\{\mathbf{M}_k\}$  uniformly at random from  $\mathcal{X}$  resp. with and without replacement s.t.

$$\mathbb{E} \mathbf{X}_k = \mathbf{0} \quad \forall k .$$

Let  $\mathbf{Y} := \sum_k \mathbf{X}_k$  and  $\mathbf{N} := \sum_k \mathbf{M}_k$  . Then

$$\mathbb{E} \lambda_{\max}(\mathbf{N}) \leq \sqrt{2v(\mathbf{Y}) \log d} + \frac{1}{3} L \log d .$$

where  $v(\mathbf{Y}) := \|\mathbb{E} \mathbf{Y}^2\| = \left\| \sum_k \mathbb{E} \mathbf{X}_k^2 \right\| = \lambda_{\max} \left( \sum_k \mathbb{E} \mathbf{X}_k^2 \right) .$

(Tropp, 2011, 2012, 2015; Gross and Nesme, 2010; Bach 2013)



# Stochastic Reformulation of the ERM

- **Sampling vector**

Let  $v \in \mathbb{R}^n$ , with distribution  $\mathcal{D}$  s.t.

$$\mathbb{E}_{\mathcal{D}} [v] = \mathbf{1}$$

where  $\mathbf{1}$  is the all-ones vector

# Stochastic Reformulation of the ERM

- **Sampling vector**

Let  $v \in \mathbb{R}^n$ , with distribution  $\mathcal{D}$  s.t.

$$\mathbb{E}_{\mathcal{D}}[v] = \mathbf{1}$$

where  $\mathbf{1}$  is the all-ones vector

- **Unbiased subsampled function**

$$f_v(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) v_i = \frac{1}{n} \langle F(w), v \rangle$$

where  $F(w) := (f_1(w), \dots, f_n(w))^{\top} \in \mathbb{R}^n$

# Stochastic Reformulation of the ERM

- **Sampling vector**

Let  $v \in \mathbb{R}^n$ , with distribution  $\mathcal{D}$  s.t.

$$\mathbb{E}_{\mathcal{D}}[v] = \mathbb{1}$$

where  $\mathbb{1}$  is the all-ones vector

- **Unbiased subsampled function**

$$f_v(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) v_i = \frac{1}{n} \langle F(w), v \rangle$$

where  $F(w) := (f_1(w), \dots, f_n(w))^{\top} \in \mathbb{R}^n$

$$\implies \mathbb{E}_{\mathcal{D}}[f_v(w)] = \frac{1}{n} \langle F(w), \mathbb{E}_{\mathcal{D}}[v] \rangle = f(w)$$

# Stochastic Reformulation of the ERM

- **Sampling vector**

Let  $v \in \mathbb{R}^n$ , with distribution  $\mathcal{D}$  s.t.

$$\mathbb{E}_{\mathcal{D}}[v] = \mathbb{1}$$

where  $\mathbb{1}$  is the all-ones vector

- **Unbiased subsampled function**

$$f_v(w) := \frac{1}{n} \sum_{i=1}^n f_i(w) v_i = \frac{1}{n} \langle F(w), v \rangle$$

where  $F(w) := (f_1(w), \dots, f_n(w))^{\top} \in \mathbb{R}^n$

$$\implies \mathbb{E}_{\mathcal{D}}[f_v(w)] = \frac{1}{n} \langle F(w), \mathbb{E}_{\mathcal{D}}[v] \rangle = f(w)$$

- **ERM reformulation**

$$\text{solving ERM} \iff \text{find } w^* \in \arg \min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) = \mathbb{E}_{\mathcal{D}}[f_v(w)]$$

# Arbitrary Sampling

## Examples of sampling vector

Let  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$  be the Jacobian

# Arbitrary Sampling

## Examples of sampling vector

Let  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$  be the Jacobian

- Let  $\mathbf{v} = \mathbb{1}$  (deterministic)

$$\nabla f_{\mathbf{v}}(w) = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{1} = \nabla f(w) \quad (\text{GD})$$

# Arbitrary Sampling

## Examples of sampling vector

Let  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$  be the Jacobian

- Let  $\mathbf{v} = \mathbb{1}$  (deterministic)

$$\nabla f_{\mathbf{v}}(w) = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{1} = \nabla f(w) \quad (\text{GD})$$

- Let  $\mathbf{v} = n\mathbf{e}_i$  (where  $\mathbf{e}_i$  is the  $i$ -th vector of basis) with probability  $1/n$  for all  $i \in [n]$

$$\nabla f_{\mathbf{v}}(w) = \frac{1}{n} \nabla \mathbf{F}(w) n\mathbf{e}_i = \nabla f_i(w) \quad (\text{SGD})$$

# Arbitrary Sampling

## Examples of sampling vector

Let  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$  be the Jacobian

- Let  $\mathbf{v} = \mathbb{1}$  (deterministic)

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{1} = \nabla f(w) \quad (\text{GD})$$

- Let  $\mathbf{v} = n\mathbf{e}_i$  (where  $\mathbf{e}_i$  is the  $i$ -th vector of basis) with probability  $1/n$  for all  $i \in [n]$

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) n\mathbf{e}_i = \nabla f_i(w) \quad (\text{SGD})$$

- Let  $\mathbf{v} = (n/b) \sum_{i \in B} \mathbf{e}_i$  with  $B$  drawn from  $[n]$  uniformly s.t.  $|B| = b$

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) \frac{n}{b} \sum_{i \in B} \mathbf{e}_i = \frac{1}{b} \sum_{i \in B} \nabla f_i(w)$$

( $b$ -SGD without replacement)



# Arbitrary Sampling

## Examples of sampling vector

Let  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$  be the Jacobian

- Let  $\mathbf{v} = \mathbb{1}$  (deterministic)

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{1} = \nabla f(w) \quad (\text{GD})$$

- Let  $\mathbf{v} = n\mathbf{e}_i$  (where  $\mathbf{e}_i$  is the  $i$ -th vector of basis) with probability  $1/n$  for all  $i \in [n]$

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) n\mathbf{e}_i = \nabla f_i(w) \quad (\text{SGD})$$

- Let  $\mathbf{v} = (n/b) \sum_{i \in B} \mathbf{e}_i$  with  $B$  drawn from  $[n]$  uniformly s.t.  $|B| = b$

$$\nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) \frac{n}{b} \sum_{i \in B} \mathbf{e}_i = \frac{1}{b} \sum_{i \in B} \nabla f_i(w) \quad (b\text{-SGD without replacement})$$

→ Arbitrary sampling covers many common methods

- Unbiased estimates

- **Unbiased estimates**

- Function:  $\mathbb{E}_{\mathcal{D}} [f_v(w)] = \frac{1}{n} \langle F(w), \mathbb{E}_{\mathcal{D}} [v] \rangle = f(w)$

- **Unbiased estimates**

- Function:  $\mathbb{E}_{\mathcal{D}} [f_v(w)] = \frac{1}{n} \langle F(w), \mathbb{E}_{\mathcal{D}} [v] \rangle = f(w)$
- Gradient:  $\mathbb{E}_{\mathcal{D}} [\nabla f_v(w)] = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{E}_{\mathcal{D}} [v] = \nabla f(w)$

where  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$

- **Unbiased estimates**

- Function:  $\mathbb{E}_{\mathcal{D}} [f_v(w)] = \frac{1}{n} \langle F(w), \mathbb{E}_{\mathcal{D}} [v] \rangle = f(w)$
- Gradient:  $\mathbb{E}_{\mathcal{D}} [\nabla f_v(w)] = \frac{1}{n} \nabla \mathbf{F}(w) \mathbb{E}_{\mathcal{D}} [v] = \nabla f(w)$

where  $\nabla \mathbf{F}(w) := [\nabla f_1(w), \dots, \nabla f_n(w)] \in \mathbb{R}^{d \times n}$

→ **Motivates using:**  $w^{k+1} = w^k - \gamma_k \nabla f_v(w^k)$

where  $\gamma_k$  is a step size sequence

# Reducing the Variance With Control Variates

- Controlled stochastic reformulation of the ERM

$$\text{find } w^* \in \arg \min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) = \mathbb{E}_{\mathcal{D}} \left[ f_v(w) \underbrace{- z_v(w) + \mathbb{E}_{\mathcal{D}} [z_v(w)]}_{\text{unbiased correction term}} \right]$$

with  $z_v(\cdot)$  a random function

# Reducing the Variance With Control Variates

- Controlled stochastic reformulation of the ERM

$$\text{find } w^* \in \arg \min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) = \mathbb{E}_{\mathcal{D}} [f_v(w) \underbrace{- z_v(w) + \mathbb{E}_{\mathcal{D}} [z_v(w)]}_{\text{unbiased correction term}}]$$

with  $z_v(\cdot)$  a random function

- Stochastic variance-reduced gradient estimator

$$g_v(w) := \nabla f_v(w) - \nabla z_v(w) + \mathbb{E}_{\mathcal{D}} [\nabla z_v(w)]$$

Iteration:  $w^{k+1} = w^k - \gamma g_v(w^k)$

# Reducing the Variance With Control Variates

- Controlled stochastic reformulation of the ERM

$$\text{find } w^* \in \arg \min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) = \mathbb{E}_{\mathcal{D}} [f_v(w) \underbrace{- z_v(w) + \mathbb{E}_{\mathcal{D}} [z_v(w)]}_{\text{unbiased correction term}}]$$

with  $z_v(\cdot)$  a random function

- Stochastic variance-reduced gradient estimator

$$g_v(w) := \nabla f_v(w) - \nabla z_v(w) + \mathbb{E}_{\mathcal{D}} [\nabla z_v(w)]$$

Iteration:  $w^{k+1} = w^k - \gamma g_v(w^k)$

→ Recovers stochastic variance-reduced methods



## Brief recap

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

- Unbiased gradient:  $\mathbb{E}[g_v(w^k)] = \nabla f(w^k)$

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

- Unbiased gradient:  $\mathbb{E} [g_v(w^k)] = \nabla f(w^k)$
- Decreasing variance:  $\mathbb{E} \left[ \|g_v(w^k) - \nabla f(w^k)\|_2^2 \right] \xrightarrow{w^k \rightarrow w^*} 0$

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

- Unbiased gradient:  $\mathbb{E} [g_v(w^k)] = \nabla f(w^k)$
- Decreasing variance:  $\mathbb{E} \left[ \|g_v(w^k) - \nabla f(w^k)\|_2^2 \right] \xrightarrow{w^k \rightarrow w^*} 0$

- Advantages

- No decreasing step sizes  $(\gamma_k)_k$  needed

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

- Unbiased gradient:  $\mathbb{E} [g_v(w^k)] = \nabla f(w^k)$
- Decreasing variance:  $\mathbb{E} \left[ \|g_v(w^k) - \nabla f(w^k)\|_2^2 \right] \xrightarrow{w^k \rightarrow w^*} 0$

- Advantages

- No decreasing step sizes  $(\gamma_k)_k$  needed
- $f_v(w)$  determines the smoothness of the controlled stochastic reformulation

### Assumption (Expected Smoothness)

$$\mathbb{E} \left[ \|\nabla f_v(w) - \nabla f_v(w^*)\|_2^2 \right] \leq 2\mathcal{L} (f_v(w) - \nabla f_v(w^*))$$

## Brief recap

- Iterative methods

$$w^{k+1} = w^k - \gamma g_v(w^k)$$

Such that

- Unbiased gradient:  $\mathbb{E} [g_v(w^k)] = \nabla f(w^k)$
- Decreasing variance:  $\mathbb{E} [\|g_v(w^k) - \nabla f(w^k)\|_2^2] \xrightarrow{w^k \rightarrow w^*} 0$

- Advantages

- No decreasing step sizes  $(\gamma_k)_k$  needed
- $f_v(w)$  determines the smoothness of the controlled stochastic reformulation

### Assumption (Expected Smoothness)

$$\mathbb{E} [\|\nabla f_v(w) - \nabla f_v(w^*)\|_2^2] \leq 2\mathcal{L} (f_v(w) - \nabla f_v(w^*))$$

- No “bounded gradient” assumption such as  $\mathbb{E} [\|\nabla f_v(w^k)\|_2^2] \leq cst$



## Example: Recovering SAGA Algorithm

- SAGA<sup>6</sup>

$$\left\{ \begin{array}{ll} f_v(w) = \frac{1}{n} \langle F(w), v \rangle & \implies \nabla f_v(w) = \frac{1}{n} \nabla F(w) v \\ z_v(w) = \frac{1}{n} \langle \underbrace{J^\top w}_\text{linear estimation of } F(w), v \rangle & \implies \nabla z_v(w) = \frac{1}{n} J v \end{array} \right.$$

with  $J$  an **estimate of the Jacobian** in  $R^{d \times n}$

---

<sup>6</sup>Defazio, Bach and Lacoste-Julien (2014), NIPS, "SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives"

## Example: Recovering SAGA Algorithm

- SAGA<sup>6</sup>

$$\begin{cases} f_v(w) = \frac{1}{n} \langle F(w), v \rangle & \implies \nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) v \\ z_v(w) = \frac{1}{n} \langle \underbrace{\mathbf{J}^\top w}_{\text{linear estimation of } F(w)}, v \rangle & \implies \nabla z_v(w) = \frac{1}{n} \mathbf{J} v \end{cases}$$

with  $\mathbf{J}$  an **estimate of the Jacobian** in  $\mathbb{R}^{d \times n}$

- If  $v = ne_i$ , where  $e_i$  is the  $i$ -th vector of basis

$$\begin{aligned} g_v(w) &:= \nabla f_v(w) - \nabla z_v(w) + \mathbb{E}_{\mathcal{D}} [\nabla z_v(w)] \\ &= \frac{1}{n} \nabla \mathbf{F}(w) ne_i - \frac{1}{n} \mathbf{J} ne_i + \mathbb{E} \left[ \frac{1}{n} \mathbf{J} v \right] \\ &= \nabla f_i(w) - \mathbf{J}_{:i} + \frac{1}{n} \mathbf{J} \mathbf{1} \end{aligned}$$

where  $\mathbf{1}$  is the all-ones vector and  $\mathbf{J}_{:i}$  the  $i$ -th column of  $\mathbf{J}$

---

<sup>6</sup>Defazio, Bach and Lacoste-Julien (2014), NIPS, "SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives"

## Example: Recovering SAGA Algorithm

- SAGA<sup>6</sup>

$$\begin{cases} f_v(w) = \frac{1}{n} \langle F(w), v \rangle & \implies \nabla f_v(w) = \frac{1}{n} \nabla \mathbf{F}(w) v \\ z_v(w) = \frac{1}{n} \langle \underbrace{\mathbf{J}^\top w}_{\text{linear estimation of } F(w)}, v \rangle & \implies \nabla z_v(w) = \frac{1}{n} \mathbf{J} v \end{cases}$$

with  $\mathbf{J}$  an **estimate of the Jacobian** in  $\mathbb{R}^{d \times n}$

- If  $v = ne_i$ , where  $e_i$  is the  $i$ -th vector of basis

$$\begin{aligned} g_v(w) &:= \nabla f_v(w) - \nabla z_v(w) + \mathbb{E}_{\mathcal{D}} [\nabla z_v(w)] \\ &= \frac{1}{n} \nabla \mathbf{F}(w) ne_i - \frac{1}{n} \mathbf{J} ne_i + \mathbb{E} \left[ \frac{1}{n} \mathbf{J} v \right] \\ &= \nabla f_i(w) - \mathbf{J}_{:i} + \frac{1}{n} \mathbf{J} \mathbf{1} \end{aligned}$$

where  $\mathbf{1}$  is the all-ones vector and  $\mathbf{J}_{:i}$  the  $i$ -th column of  $\mathbf{J}$

- **Variance term**

Convergence analysis:  $\mathbb{E}_{\mathcal{D}} \left[ \|g_v(w) - \nabla f(w)\|_2^2 \right]$  low for  $\mathbf{J} \approx \nabla \mathbf{F}(w)$

---

<sup>6</sup>Defazio, Bach and Lacoste-Julien (2014), NIPS, "SAGA: A Fast Incremental Gradient Method With Support for Non-Strongly Convex Composite Objectives"