

Exploring CLIP's Dense Knowledge for Weakly Supervised Semantic Segmentation

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- Problem / objective
 - Weakly Supervised Semantic Segmentation (WSSS) via CLIP
- Contribution / Key idea
 - Text Semantic Enrichment module (TSE)
 - Visual Calibration module
 - Static Visual Calibration (SVC)
 - Learnable Visual Calibration (LVC)

- **Weakly Supervised Semantic Segmentation (WSSS)**

- ❑ **Definition**

- Generate pixel-level predictions using weak annotations like points, scribbles, bounding boxes, or **image-level labels**

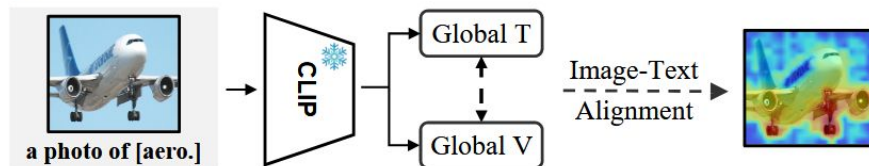
- ❑ **WSSS 3-stage Pipeline**

1. Generate Class Activation Maps (CAMs) by training a classification network
2. Refine CAMs into pseudo labels (PL)
3. Use these labels to **train** a segmentation model

- ❑ **Motivation**

- Current methods treating '**WSSS via CLIP**' primarily focus on CLIP's global **image-text alignment**, as shown in Fig. 1 (a). CLIP's dense knowledge with **patch-text alignment** still remains under-explored in WSSS.

(a) Previous methods



• Motivation

❑ Two key challenges:

1. Semantic sparsity in **textual prompts**

: The template 'a photo of [CLASS]' only indicates object presence but lacks knowledge for localization.

2. Fine-grained insufficiency in **visual features**

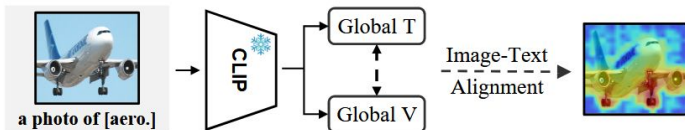
: CLIP prioritizes global representation due to its image-text pairing nature.

❑ Our proposed solution:

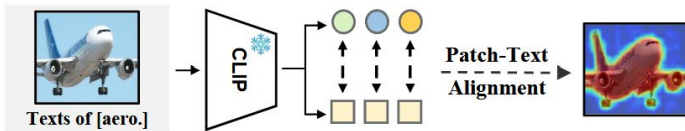
1. Text Semantic Enrichment (TSE) module

2. Visual Calibration (VC) module

(a) Previous methods



(b) The proposed method ExCEL



T
V Text and vision token

 Dense texts and patches
 ❄️ Frozen

Figure 1. Our motivation. (a) Previous methods leverage CLIP to generate CAMs with global image-text alignment, leaving CLIP's dense knowledge unexplored. (b) The proposed ExCEL explores CLIP's dense knowledge via a novel patch-text alignment paradigm, which generates better CAMs with less training cost.

● Overview

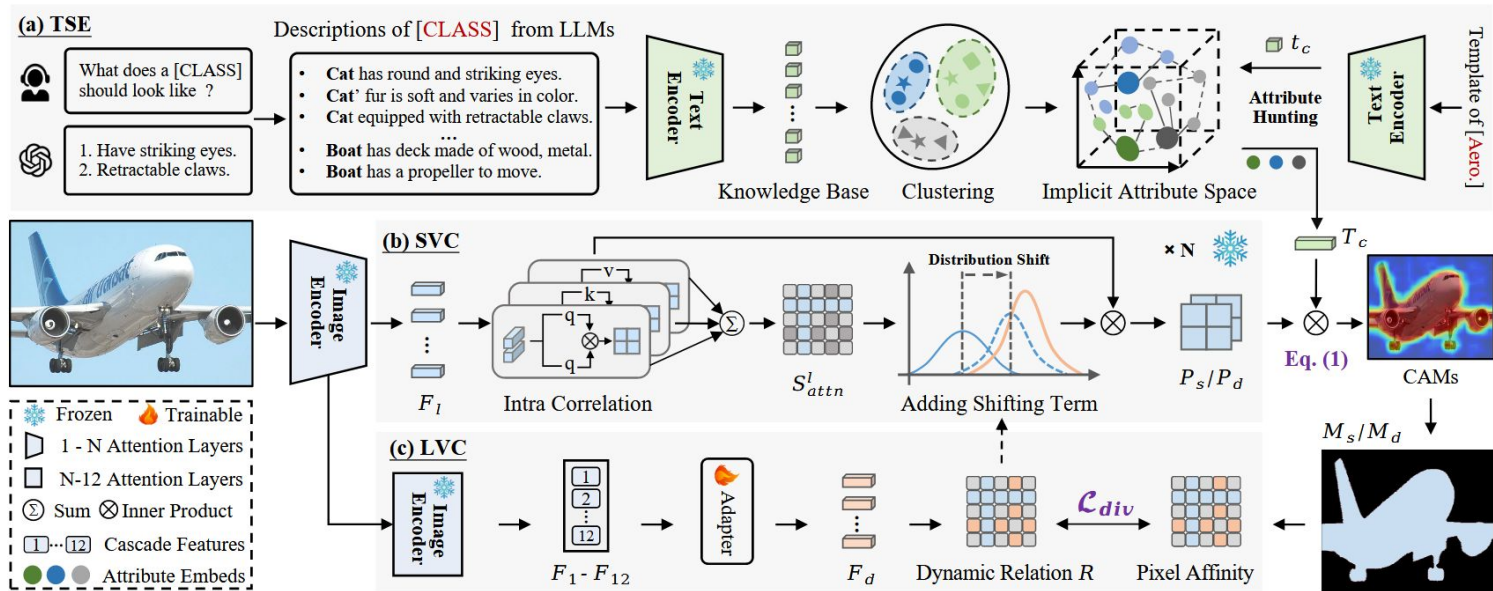


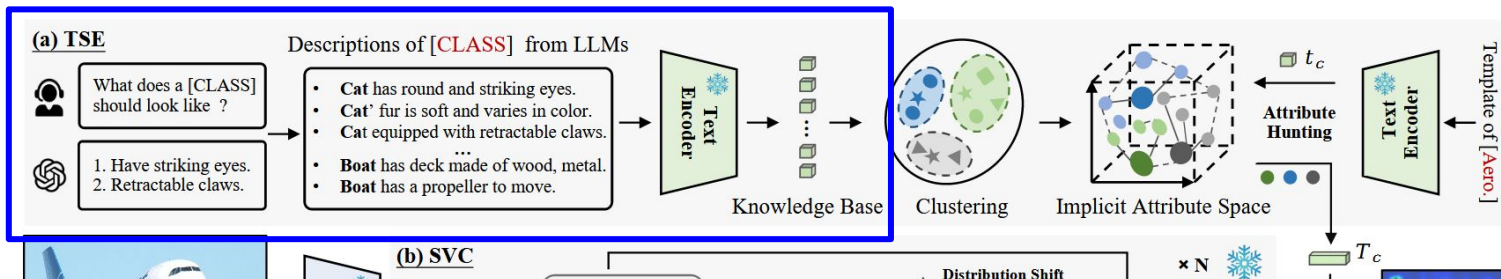
Figure 2. ExCEL Architecture. We explore CLIP’s dense knowledge with Text Semantic Enrichment (TSE) and Visual Calibration (VC). (a) TSE uses LLMs to build a knowledge base and clusters it into an implicit attribute space. The final text representation T_c is enhanced by hunting for relevant attributes. For vision modality, (b) we introduce Static Visual Calibration (SVC) to calibrate visual features using the Inter-correlation operation across N intermediate layers. It generates static CAMs with T_c and calibrated features P_s . (c) Learnable Visual Calibration (LVC) designs a learnable adapter to add a dynamic shift R to SVC. It generates optimized features P_d based on static CAMs guidance, creating dynamic CAMs from P_d and T_c . Dynamic CAMs are refined for segmentation supervision. Details are in Sec. 3.1.

• Text Semantic Enrichment

❑ Knowledge Base Construction

- Global text template E_c : 'a clean origami of [CLASS]'
- Instructions for GPT: "List n descriptions with key properties to describe the [CLASS] in terms of appearance, color, shape, size, or material, etc. These descriptions will help visually distinguish the [CLASS] from other classes in the dataset. Each description should follow the format: 'a clean origami [CLASS]. it + descriptive contexts.'"
- GPT generate n detailed descriptions for each class, which are subsequently encoded into a dataset-wide knowledge base with CLIP's text encoder.
- **Knowledge base:** $\mathcal{T} = \{\Phi(e_i)\}_{i=1}^{n \times C}$

Knowledge Base Construction



• Text Semantic Enrichment

❑ Implicit Attribute Hunting

- Cluster this knowledge into generalized attributes and treat text prompting as an implicit attribute-hunting process
- Each cluster centroid is viewed as the implicit attribute that represents a group of descriptions sharing similar properties

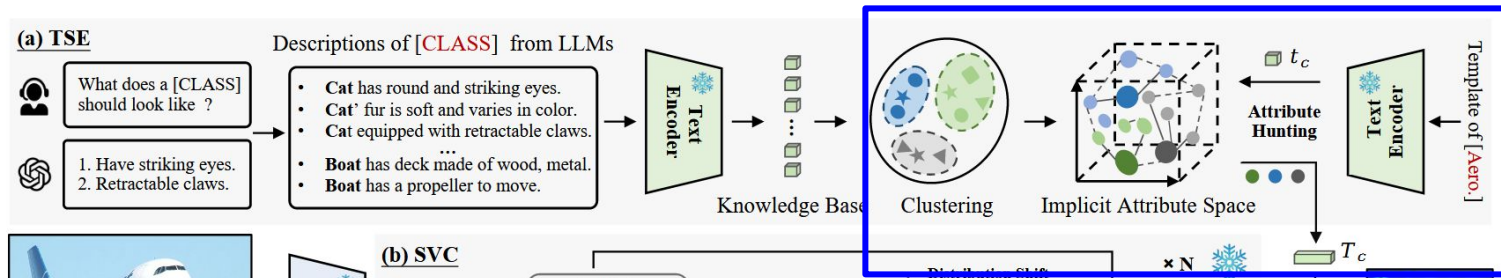
- Attribute feature space: $A = \text{Kmeans}(\mathcal{T}, B) = \{a_i\}_{i=1}^B$, (2)

- Global text template, Global text embedding: $E_c, t_c \in \mathbb{R}^{D \times 1}$

- Top-K Attribute neighbors: $A_c = \{a_j : j \in \arg\max_{\text{TOPK}} \{t_c^T a_j\}_{j=1}^B\}$. (3)

- **Final text representation:**

$$T_c = t_c + \lambda \sum_{j=1}^K \text{softmax}(t_c^T A_c) a_j, \quad (4)$$



● Visual Calibrations

❑ Static Visual Calibration

- Input image, features from l-th layer of CLIP: $X \in \mathbb{R}^{3 \times \mathcal{H} \times \mathcal{W}}$, $F_l \in \mathbb{R}^{D_s \times hw}$

- Original attention map: $SA(q, k) = \text{softmax} \left(q^T k / \sqrt{D_s} \right)$, (5)

- Limitation: The original q-k attention produces overly uniform attention maps, homogenizing diverse tokens from v to capture broad semantics for global image representation, due to the inherent image-text alignment of CLIP.

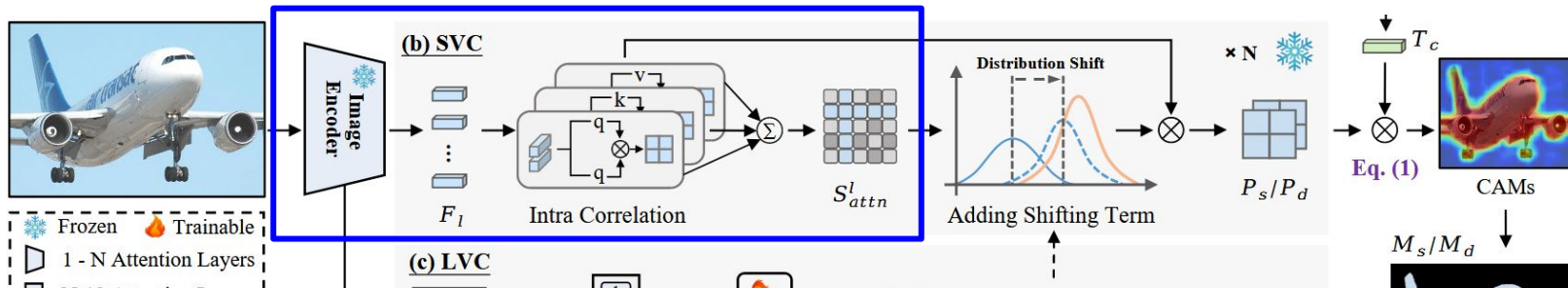
- Ours: **Intra-correlation** calculates the **attention within each space of $\{q, k, v\}$ across intermediate layers**, instead of generating q-k correlation

- Attention map from l-th SVC layer: $S_{attn}^l = \sum w_i SA(O_i^l, O_i^l)$, $O_i^l \in \{q^l, k^l, v^l\}$, (6) $S_{attn}^l \in \mathbb{R}^{hw \times hw}$ $l \in \{12-N, \dots, 12\}$

- Calibrated features from the last layer of SVC: $P_s \in \mathbb{R}^{D \times h \times w}$

- **Static CAM** is generated by calibrated visual features from the last layer P_s and text embedding T_c : CAM_s

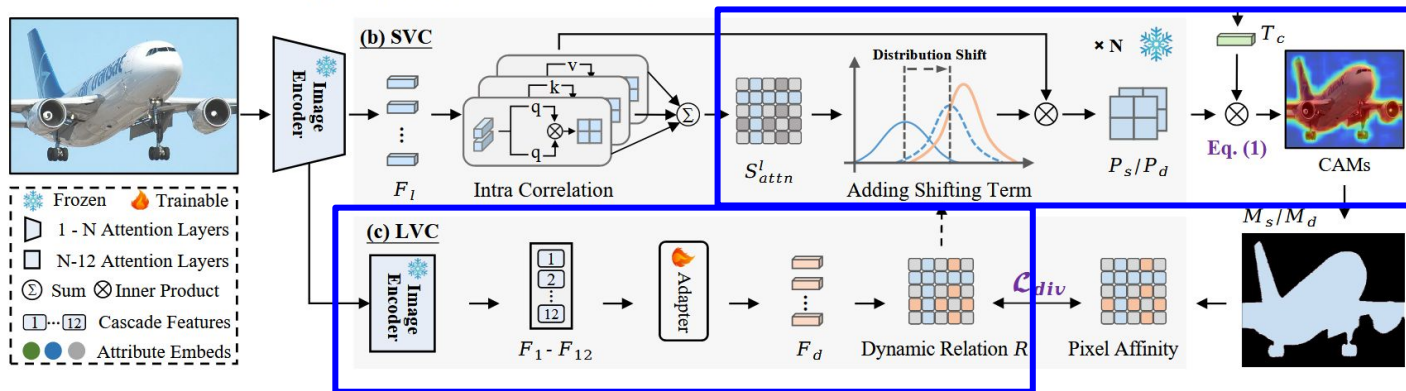
$$CAM = \text{Norm}(\cos(P, T)), \quad (1)$$



Visual Calibrations

Learnable Visual Calibration

- Limitation: Although ExCEL generates comparable CAMs without training, its performance is still limited by the fixed features in CLIP.
- Ours: We design a **lightweight adapter**, which only incorporates a distribution shift to calibrate the fixed features, to dynamically calibrate the visual features with diverse details.
- Frozen features from 1-12th layer of CLIP: $F_l \in \mathbb{R}^{D_s \times h \times w}$
- Dynamic feature: $F_d \in \mathbb{R}^{D_d \times h \times w}$ $F_d = \text{Conv}(\text{Concate}[\delta_l(F_l)]_{l=1}^{12})$, (7)
- Dynamic token relations: $r \in \mathbb{R}^{h \times w \times h \times w}$ $r = \alpha(\cos(F_d, F_d) - \beta \overline{\cos(F_d, F_d)})$, (8)
- Dynamic relations: $R \in \mathbb{R}^{h \times w \times h \times w}$ $R_{ij} = \begin{cases} r_{ij}, & \text{if } r_{ij} \geq 0 \\ -inf, & \text{else} \end{cases}$. (9)
- Optimized attention map: $L_{attn}^l \in \mathbb{R}^{h \times w \times h \times w}$ $L_{attn}^l = S_{attn}^l + \text{softmax}(R)$. (10)
- Dynamically calibrated features from the last layer of LVC: $P_d \in \mathbb{R}^{D \times h \times w}$
- **Dynamic CAM**: $\text{CAM} = \text{Norm}(\cos(P, T))$, (1)



• Training Objectives

❑ Diversity Loss

- Objective: To supervise the learning of F_d in LVC module
- Token correlations of F_d : $\hat{\mathcal{R}} \in \mathbb{R}^{hw \times hw}$ $\hat{\mathcal{R}} = \text{sigmoid}(\cos(F_d, F_d))$
- Static pseudo-labels: M_s
- **Diversity loss:**
$$\mathcal{L}_{\text{div}} = \frac{1}{N^+} \sum_{u^+ \in \hat{\mathcal{R}}^+} (1 - u^+) + \frac{1}{N^-} \sum_{u^- \in \hat{\mathcal{R}}^-} u^-, \quad (11)$$

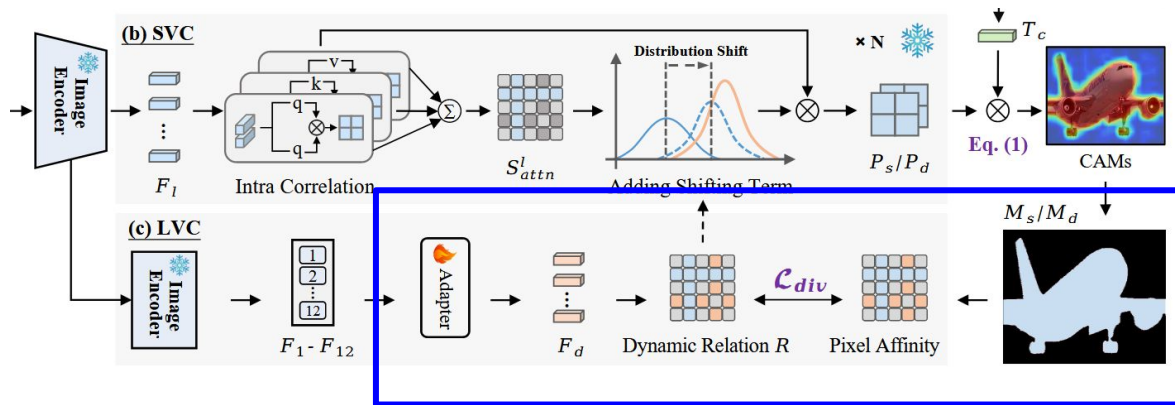
❑ Cross-Entropy Loss

- Objective: To supervise lightweight transformer-based segmentation head from WeCLIP [1]
- Dynamic pseudo-labels: M_d
- **Cross-entropy loss:** \mathcal{L}_{seg}

❑ Final Loss

- Adapter + Segmentation Head 학습

$$\mathcal{L}_{\text{ExCEL}} = \mathcal{L}_{\text{seg}} + \gamma \mathcal{L}_{\text{div}}, \quad (12)$$



Experiments

Table 1. Segmentation comparisons on VOC and COCO. Net. is the backbone for segmentation. Sup. is the supervision type. \mathcal{I} : image-level labels. \mathcal{SA} : saliency maps. \mathcal{L} : language.

Method	Sup.	Net.	VOC		COCO
			Val	Test	Val
Multi-stage WSSS methods.					
L2G [14] CVPR'2022	$\mathcal{I} + \mathcal{SA}$	RN101	72.1	71.7	44.2
RCA [49] CVPR'2023	$\mathcal{I} + \mathcal{SA}$	RN38	72.2	72.8	36.8
OCR [7] CVPR'2023	\mathcal{I}	RN38	72.7	72.0	42.5
BECO [26] CVPR'2023	\mathcal{I}	RN101	73.7	73.5	45.1
MCTformer+ [38] TPAMI'2024	\mathcal{I}	RN38	74.0	73.6	45.2
CTI [41] CVPR'2024	\mathcal{I}	RN101	74.1	73.2	45.4
CLIMS [36] CVPR'2022	$\mathcal{I} + \mathcal{L}$	RN101	70.4	70.0	-
CLIP-ES [20] CVPR'2023	$\mathcal{I} + \mathcal{L}$	RN101	72.2	72.8	45.4
PSDPM [45] CVPR'2024	$\mathcal{I} + \mathcal{L}$	RN101	74.1	74.9	47.2
CPAL [31] CVPR'2024	$\mathcal{I} + \mathcal{L}$	RN101	74.5	74.7	46.8
Single-stage WSSS methods.					
AFA [28] CVPR'2022	\mathcal{I}	MiT-B1	66.0	66.3	38.9
ViT-PCM [27] ECCV'2022	\mathcal{I}	ViT-B	70.3	70.9	-
ToCo [29] CVPR'2023	\mathcal{I}	ViT-B	71.1	72.2	42.3
DuPL [35] CVPR'2024	\mathcal{I}	ViT-B	73.3	72.8	44.6
SeCo [39] CVPR'2024	\mathcal{I}	ViT-B	74.0	73.8	46.7
DIAL [13] ECCV'2024	$\mathcal{I} + \mathcal{L}$	ViT-B	74.5	74.9	44.4
WeCLIP [43] CVPR'2024	$\mathcal{I} + \mathcal{L}$	ViT-B	76.4	77.2	47.1
ExCEL(w/o CRF)	$\mathcal{I} + \mathcal{L}$	ViT-B	77.2	77.3	49.3
ExCEL (Ours)	$\mathcal{I} + \mathcal{L}$	ViT-B	78.4	78.5	50.3

Table 2. CAM seed comparisons on VOC train set. \mathcal{M} : multi-stage methods. \mathcal{S} : single-stage methods. †: our reproduction following official codes. ExCEL*: ExCEL in a training-free manner.

Method	Type	Sup.	Net.	VOC Train
Training-free WSSS methods.				
CLIP-ES [20] CVPR'2023	\mathcal{M}	$\mathcal{I} + \mathcal{L}$	ViT-B	70.8
ExCEL* (Ours)	\mathcal{S}	$\mathcal{I} + \mathcal{L}$	ViT-B	74.6
Training-required WSSS methods.				
ReCAM [6] CVPR'2022	\mathcal{M}	\mathcal{I}	RN101	54.8
FPR [3] CVPR'2023	\mathcal{M}	\mathcal{I}	RN101	63.8
LPCAM [5] CVPR'2023	\mathcal{M}	\mathcal{I}	RN50	65.3
MCTformer+ [38] TPAMI'2024	\mathcal{M}	\mathcal{I}	RN38	68.8
SFC [44] AAAI'2024	\mathcal{M}	\mathcal{I}	RN101	64.7
CTI [41] CVPR'2024	\mathcal{M}	\mathcal{I}	RN101	69.5
AFA [28] CVPR'2022	\mathcal{S}	\mathcal{I}	MiT-B1	65.0
ViT-PCM [27] ECCV'2022	\mathcal{S}	\mathcal{I}	ViT-B	67.7
†ToCo [29] CVPR'2023	\mathcal{S}	\mathcal{I}	ViT-B	71.6
†DuPL [35] CVPR'2024	\mathcal{S}	\mathcal{I}	ViT-B	75.0
SeCo [39] CVPR'2024	\mathcal{S}	\mathcal{I}	ViT-B	74.8
CLIMS [36] CVPR'2022	\mathcal{M}	$\mathcal{I} + \mathcal{L}$	RN101	56.6
POLE [22] WACV'2023	\mathcal{M}	$\mathcal{I} + \mathcal{L}$	RN50	59.0
CPAL [31] CVPR'2024	\mathcal{M}	$\mathcal{I} + \mathcal{L}$	RN101	71.9
DIAL [13] ECCV'2024	\mathcal{S}	$\mathcal{I} + \mathcal{L}$	ViT-B	75.2
†WeCLIP [43] CVPR'2024	\mathcal{S}	$\mathcal{I} + \mathcal{L}$	ViT-B	75.4
ExCEL (Ours)	\mathcal{S}	$\mathcal{I} + \mathcal{L}$	ViT-B	78.0

- Experiments

Table 3. Ablation study of ExCEL on VOC val set.

Conditions	SVC	TSE	LVC	Precision	Recall	mIoU
Baseline (CLIP)				18.8	21.3	12.1
w/ SVC	✓			81.2	86.2	72.5
w/o LVC	✓	✓		80.7	89.8	74.7
w/o TSE	✓		✓	83.7	86.3	75.1
ExCEL	✓	✓	✓	85.0	88.4	77.2

Table 4. Ablation study of attribute number B on VOC val set.

Number of Attr	None	32	64	112	144	196
mIoU	75.1	75.8	76.2	77.2	77.0	76.5

Table 5. Ablation study of VC module on VOC train set.

Conditions	q-k	v	I.C.	M.C.	LVC	Precision	Recall	mIoU
Baseline (CLIP)	✓					18.0	21.8	11.2
MaskCLIP		✓				77.1	80.9	65.8
w/ I.C.			✓			79.1	84.7	69.7
SVC			✓	✓		82.2	88.2	74.6
ExCEL			✓	✓	✓	86.6	87.9	78.0

Experiments

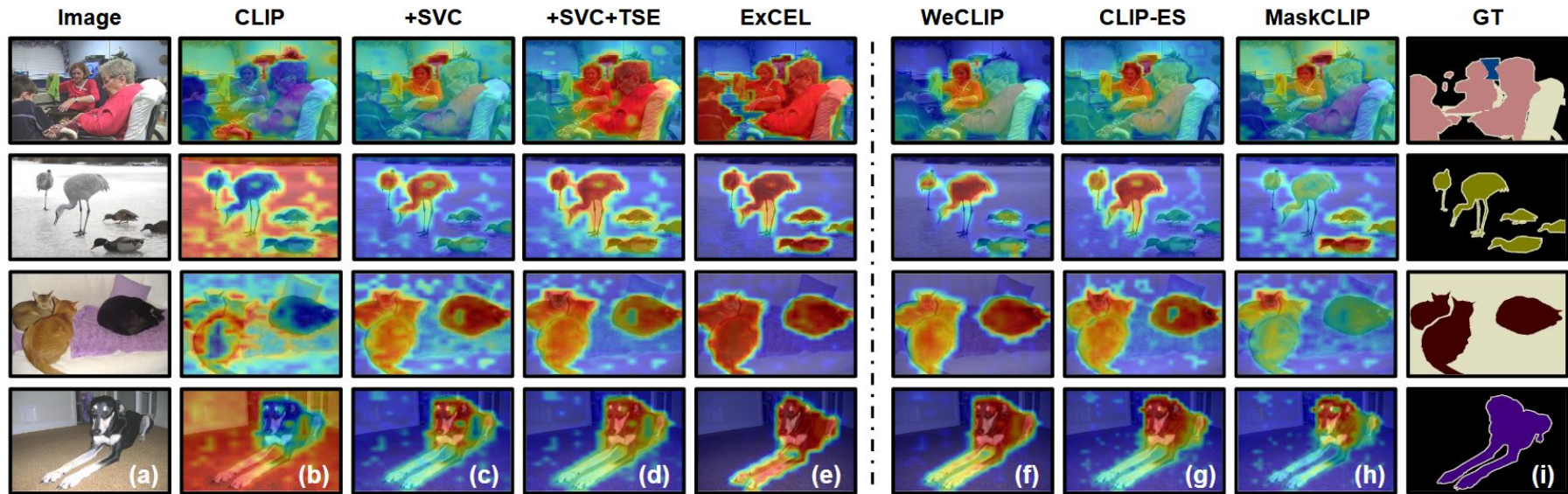


Figure 4. CAM visualizations on VOC train set. (a) Image. (b-e) Ablative visualizations of proposed modules. (e-h) Qualitative comparisons of (e) ExCEL and recent CLIP-based methods, i.e., (f) WeCLIP [43], (g) CLIP-ES [20] and (h) MaskCLIP [47]. (i) Ground truth.

- Experiments

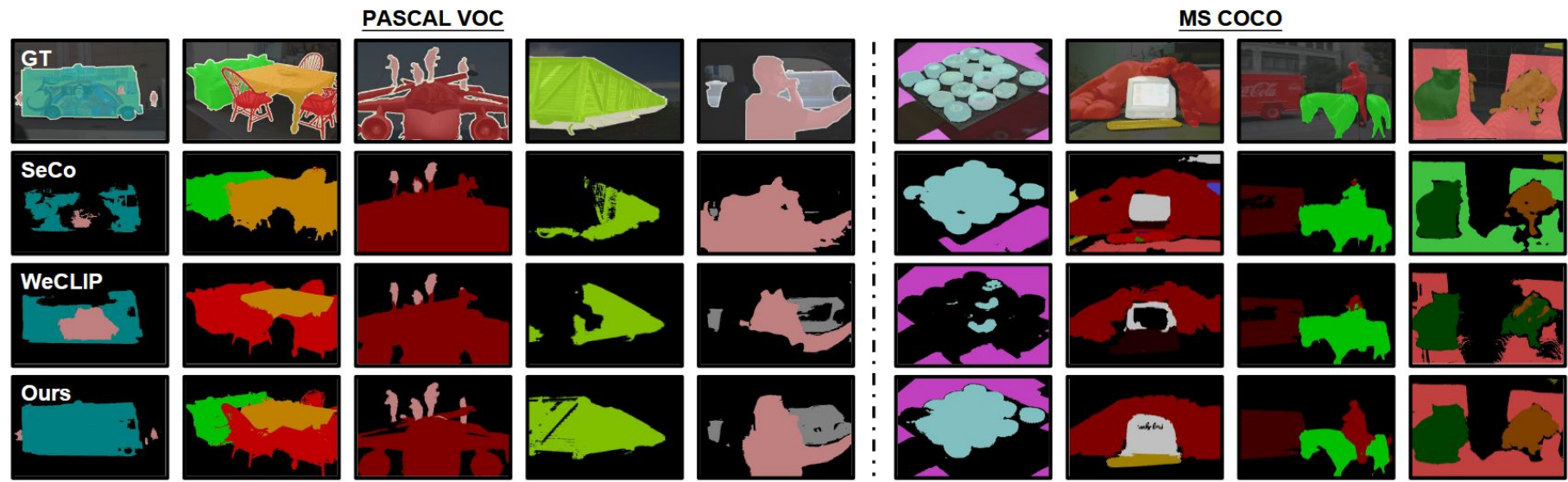


Figure 3. Segmentation visualizations of SeCo [39], WeCLIP [43] and ours on VOC and COCO. ExCEL segments objects more precisely.