

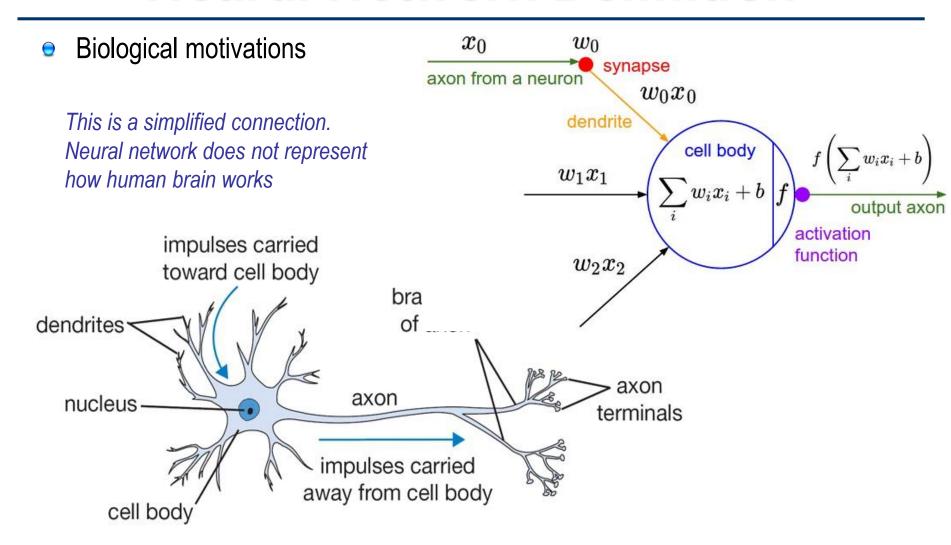
DLSG Week 3: Neural Network

Thuong Nguyen Canh

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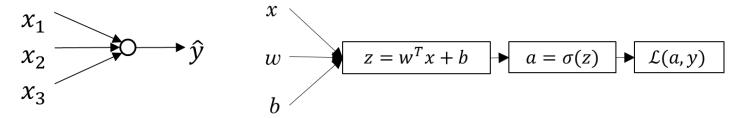
Neural Network Definition



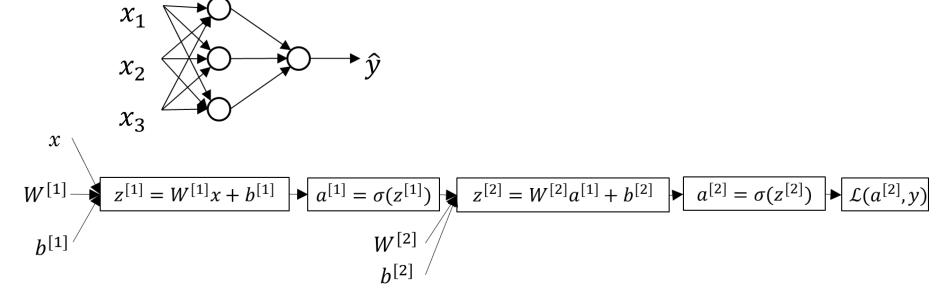


Neural Network Definition (3)

Single neuron as a linear classifier

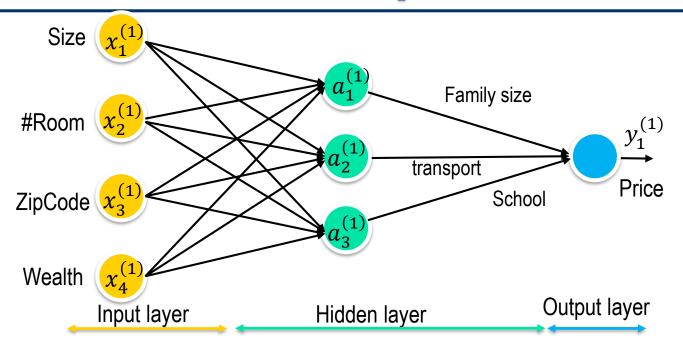


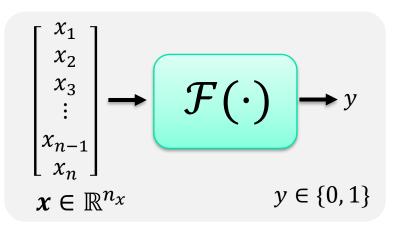
Multiple neurons as a classifier





Neural Network Representation



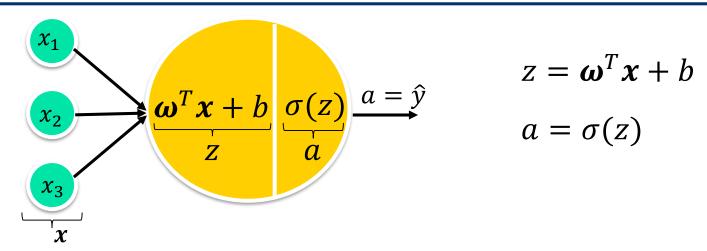


Training pairs $\{(x^{(1)}, y^{(1)}), ..., (x^{(m)}, y^{(m)})\}$

In matrix form



Neural Network Representation



$$\boldsymbol{W^{(1)}} = \begin{bmatrix} --- \boldsymbol{\omega}_1^{(1)^I} - --- \\ --- \boldsymbol{\omega}_4^{(1)^T} - --- \end{bmatrix}$$

$$z_{1}^{(1)} = \boldsymbol{\omega}_{1}^{(1)^{T}} \boldsymbol{x} + b_{1}^{(1)}, \quad a_{1}^{(1)} = \sigma(z_{1}^{(1)})$$

$$z_{2}^{(1)} = \boldsymbol{\omega}_{2}^{(1)^{T}} \boldsymbol{x} + b_{2}^{(1)}, \quad a_{2}^{(1)} = \sigma(z_{2}^{(1)})$$

$$z_{3}^{(1)} = \boldsymbol{\omega}_{3}^{(1)^{T}} \boldsymbol{x} + b_{3}^{(1)}, \quad a_{3}^{(1)} = \sigma(z_{3}^{(1)})$$

$$z_{4}^{(1)} = \boldsymbol{\omega}_{4}^{(1)^{T}} \boldsymbol{x} + b_{4}^{(1)}, \quad a_{4}^{(1)} = \sigma(z_{4}^{(1)})$$

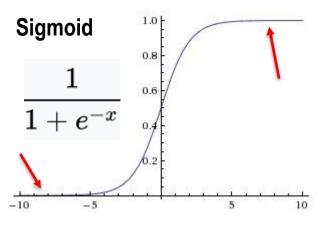
$$\boldsymbol{z}_{4}^{(1)} = \boldsymbol{w}_{4}^{(1)^{T}} \boldsymbol{x} + \boldsymbol{b}_{4}^{(1)}, \quad \boldsymbol{a}_{4}^{(1)} = \sigma(z_{4}^{(1)})$$

$$\boldsymbol{z}_{4}^{(1)} = \boldsymbol{w}_{4}^{T} \boldsymbol{x} + \boldsymbol{b}_{4}^{T}, \quad \boldsymbol{a}_{4}^{(1)} = \sigma(z_{4}^{(1)})$$

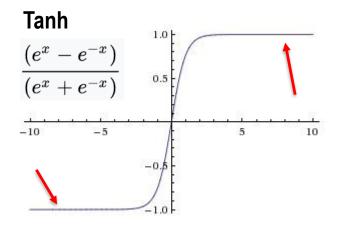


Activation Functions (1)

Activation function defines the output of given input



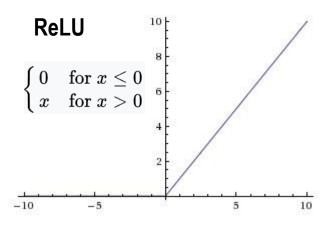
- Enforce output range to [0, 1]
- Saturation kills the gradients
- Outputs are not zero means



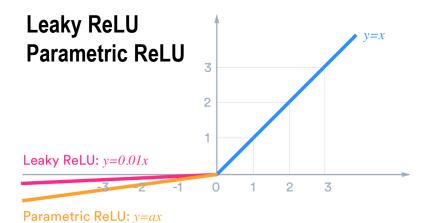
- Enforce output range to [-1, 1]
- Saturation kills the gradients

Activation Functions (2)

Activation function defines the output of given input



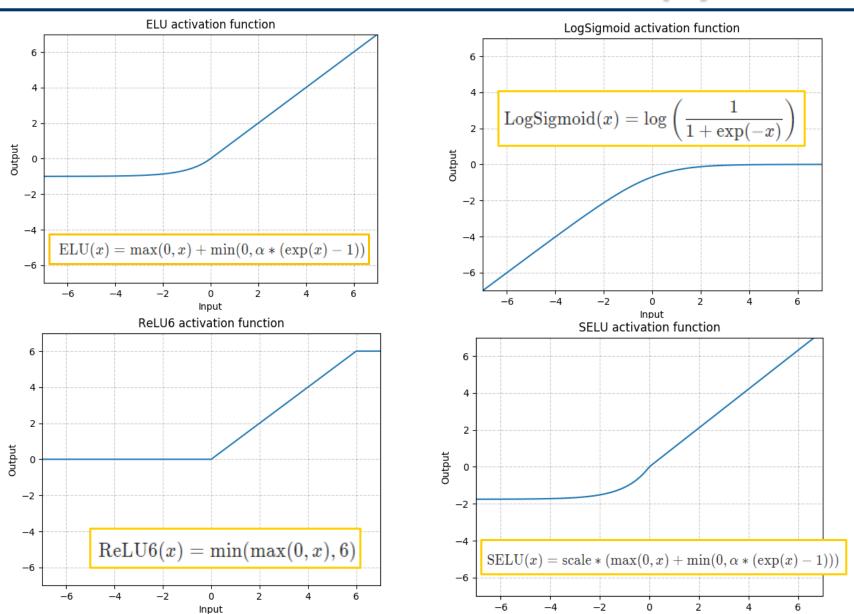
- Not saturate
- Computation efficient
- Faster convergence
- Dead ReLU



- Not saturated
- Computation efficient
- Faster convergence
- Will not "die"



Activation Function (3)



https://pytorch.org/docs/stable/ modules/torch/nn/modules/activation.html



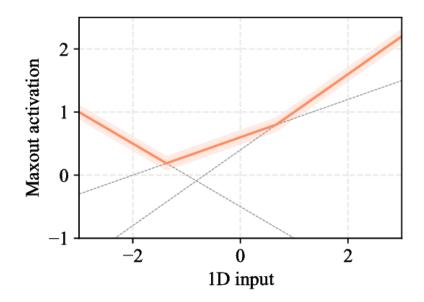
Input

Activation (4)

- Maxout "activation"
 - Generalized Relu & Leaky ReLU

$$\max(w_1^Tx+b_1,w_2^Tx+b_2)$$

- Not saturate
- Faster convergence
- Not die
- Double parameters



- Rule of thump
 - Use ReLU. Be careful with your learning rates
 - Try out Leaky ReLU / Maxout
 - Try out tanh but don't expect much
 - Never use sigmoid except for the desired output range.



Back Propagation

See the Lecture note from CS231n note



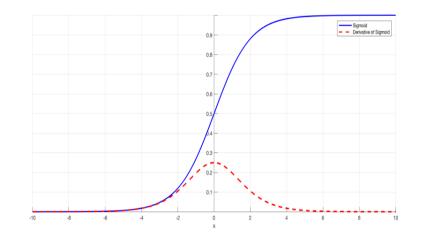
Random Initialization

- Gradient vanishing (deep network)
 - Certain activation change very slow
 - Gradient get smaller via back propagation
 - Too small gradients,
 - Network changing slowly
 - Slow to converge → cannot train more



- Very large gradient can jump to far away
- Objective function can be much bigger
- Undo all previous training effort







Random Initialization

- Zero initialization or very small random initialization
 - Network is more likely to stuck at local minimal
 - All neural would follow the same directions due to same weights
- Large random initialization
 - Gradient will converse slowly if using sigmoid
 - Potential of gradient exploding
- Random initialization with a scale (depend on size of parameters)

