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Section:

Laboratory Exercise 1

DISCRETE-TIME SIGNALS: TIME-DOMAIN REPRESENTATION

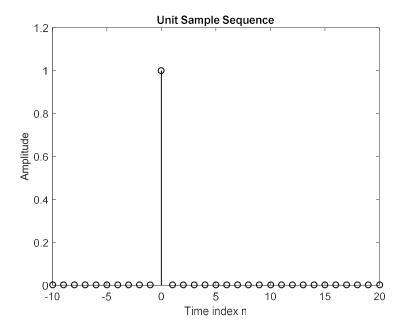
1.1 GENERATION OF SEQUENCES

Project 1.1 Unit sample and unit step sequences

A copy of Program P1 1 is given below.

```
% Generation of a Unit Sample Sequence
clc; clear all; close all;
% Generate a vector from -10 to 20
n = -10:20;
% Generate the unit sample sequence
u = [zeros(1,10) 1 zeros(1,20)];
% Plot the unit sample sequence
stem(n,u,'k','LineWidth', 1);
xlabel('Time index n');ylabel('Amplitude');
title('Unit Sample Sequence');
axis([-10 20 0 1.2]);
```

Q1.1 The unit sample sequence u[n] generated by running Program P1_1 is shown below:



Q1.2 The purpose of clf command is used to *clear current figure window*.

The purpose of axis command is used to set axis limits and appearance.

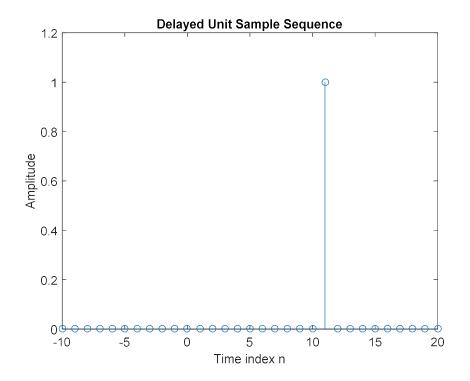
The purpose of title command is used to *add title to axes or legend*.

The purpose of xlabel command is used to *label x-axis*.

The purpose of ylabel command is used to *label y-axis*.

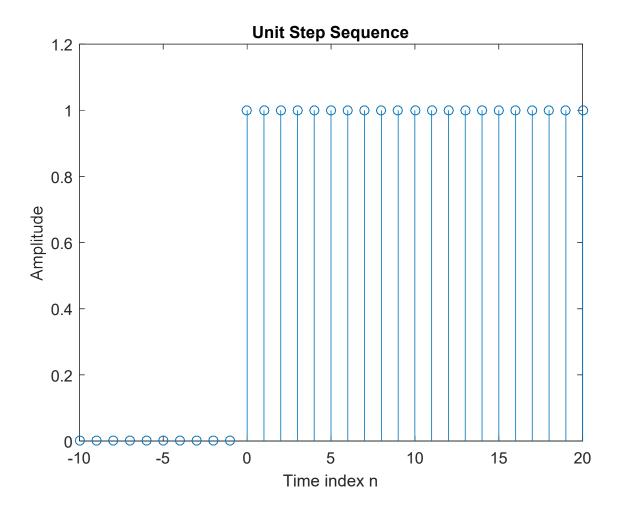
Q1.3 The modified Program P1_1 to generate a delayed unit sample sequence ud[n] with a *delay* of 11 samples is given below along with the sequence generated by running this program.

```
% Generation of a Unit Sample Sequence
clc; clear all; close all;
% Generate a vector from -10 to 20
n = -10:20;
% Generate the delayed unit sample sequence
u = [zeros(1,21) 1 zeros(1,9)];
% Plot the unit sample sequence
stem(n,u);
xlabel('Time index n');ylabel('Amplitude');
title('Delayed Unit Sample Sequence');
axis([-10 20 0 1.2]);
```



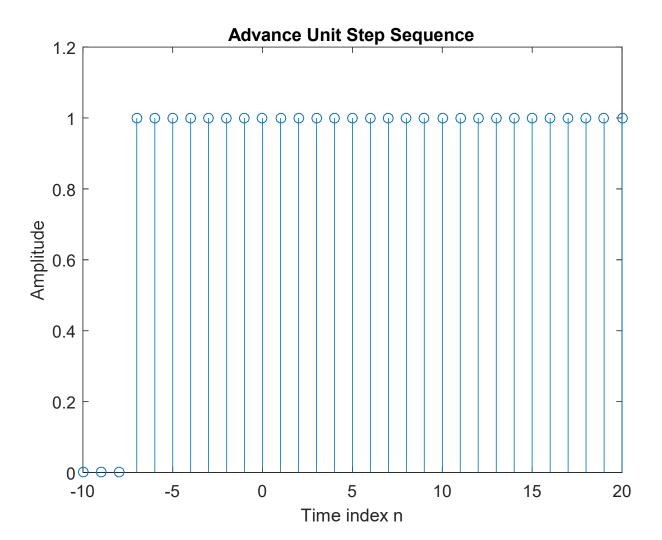
Q1.4 The modified Program P1_1 to generate *a unit step sequence* s[n] is given below along with the sequence generated by running this program.

```
% Generation of a Unit Sample Sequence
clc; clear all; close all;
% Generate a vector from -10 to 20
n = -10:20;
% Generate the unit sample sequence
u = [zeros(1,10) ones(1,21)];
% Plot the unit sample sequence
stem(n,u);
xlabel('Time index n');ylabel('Amplitude');
title('Unit Step Sequence');
axis([-10 20 0 1.2]);
```



Q1.5 The modified Program P1_1 to generate a unit step sequence sd[n] with *an advance of 7 samples* is given below along with the sequence generated by running this program.

```
clc; clear all; close all;
n = -10:20;
% Generate the unit sample sequence
u = [zeros(1,3) ones(1,28)];
% Plot the unit sample sequence
stem(n,u);
xlabel('Time index n'); ylabel('Amplitude');
title('Advance Unit Step Sequence');
axis([-10 20 0 1.2]);
```



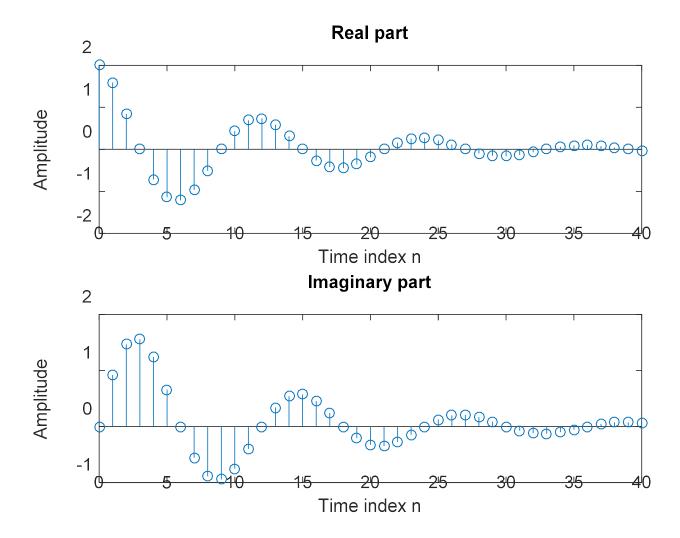
Project 1.2 Exponential signals

A copy of Programs P1 2 and P1 3 are given below.

```
% Generation of a complex exponential
sequence
clc; clear all; close all;
c = -(1/12)+(pi/6)*i;
K = 2;
n = 0:40;
x = K*exp(c*n);
subplot(2,1,1);
stem(n,real(x));
xlabel('Time index n');ylabel('Amplitude');
title('Real part');
subplot(2,1,2);
stem(n,imag(x));
xlabel('Time index n');ylabel('Amplitude');
title('Imaginary part');
```

```
% Generation of a real exponential sequence
clc; clear all; close all;
n = 0:35; a = 1.2; K = 0.2;
x = K*a.^n;
stem(n,x);
xlabel('Time index n'); ylabel('Amplitude');
```

Q1.6 The complex-valued exponential sequence generated by running Program P1_2 is shown below:



Q1.7 The parameter controlling the rate of growth or decay of this sequence is *the real* part of parameter "C".

The parameter controlling the amplitude of this sequence is *parameter "K"*.

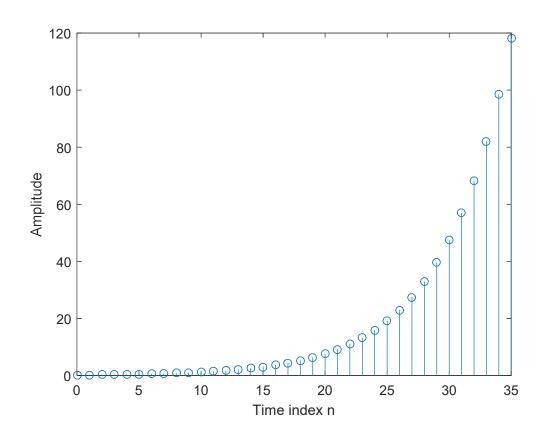
Q1.8 The result of changing the parameter c to (1/12)+(pi/6)*i is:

Since the exponential function now has $e^{\frac{1}{12}} \approx 1.087 > 1$, it means that the exponential is increasing, so the signal now has an extended envelope of n (divergence). In contrast to the case $c = -\frac{1}{12} + \frac{\pi}{6}j$ with $e^{-\frac{1}{12}} \approx 0.92 < 1$, we have the envelope narrowing to n (convergence).

Q1.9 The purpose of the operator real is used to get the real part of a vector.

The purpose of the operator imag is used to get the imaginary of a vector.

- Q1.10 The purpose of the command subplot is used to create axes in tiled positions.
- Q1.11 The real-valued exponential sequence generated by running Program P1_3 is shown below:



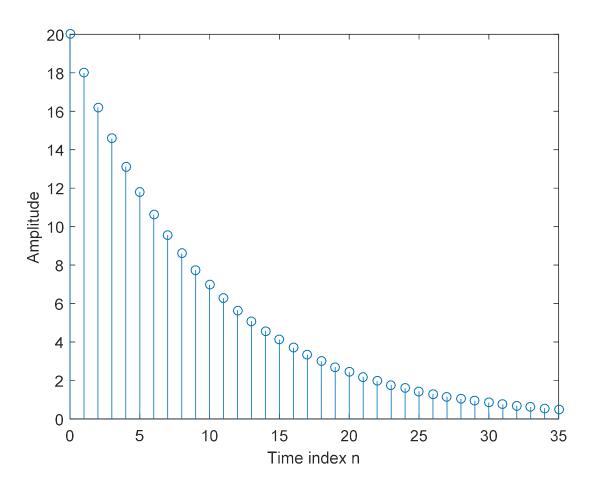
Q1.12 The parameter controlling the rate of growth or decay of this sequence is parameter "a".

The parameter controlling the amplitude of this sequence is *parameter "K"*.

Q1.13 The difference between the arithmetic operators $^{\land}$ and $.^{\land}$ is:

 \Rightarrow If we have a matrix A, then A^2 returns the square of that matrix (the matrix product A^*A) while $A.^2$ returns a matrix in which each element is the square of the corresponding element in A.

Q1.14 The sequence generated by running Program P1_3 with the parameter a changed to 0.9 and the parameter K changed to 20 is shown below:



Q1.15 The length of this sequence is 36.

It is controlled by the following MATLAB command line: n=0:35;

It can be changed to generate sequences with different lengths as follows (give an example command line and the corresponding length): n = 0:199; and now the length is 200.

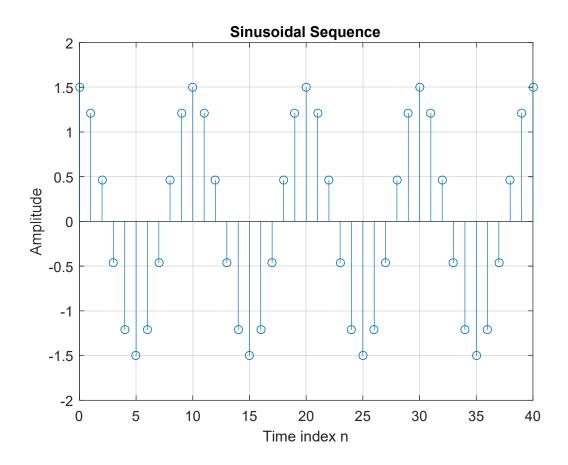
- Q1.16 The energies of the real-valued exponential sequences x[n] generated in Q1.11 and Q1.14 and computed using the command sum are:
 - We have: $s=sum(x.^2)$ so, the energies of the exponential sequences x[n] generated in Q1.11 is 4.5673e+04 and 2.1042e+03 for that of Q.14.

Project 1.3 Sinusoidal sequences

A copy of Program P1 4 is given below.

```
% Generation of a sinusoidal sequence
clc; clear all; close all;
n = 0:40;
f = 0.1;
phase = 0;
A = 1.5;
arg = 2*pi*f*n - phase;
x = A*cos(arg);
stem(n,x);
                % Plot the generated sequence
axis([0 40 -2 2]);
grid;
title('Sinusoidal Sequence');
xlabel('Time index n');
ylabel('Amplitude');
axis;
```

Q1.17 The sinusoidal sequence generated by running Program P1_4 is displayed below.



Q1.18 The frequency of this sequence is $f = 0.1 \, Hz$.

It is controlled by the following MATLAB command line: f=0.1;

A sequence with new frequency 1Hz can be generated by the following command line: f=1;

The parameter controlling the phase of this sequence is phase.

The parameter controlling the amplitude of this sequence is A.

The period of this sequence is $T = \frac{2\pi}{\omega} = \frac{1}{f} = \frac{1}{0.1} = 10$.

Q1.19 The length of this sequence is 41 samples.

It is controlled by the following MATLAB command line: n=0:40;

A sequence with new length 77 can be generated by the following command line: n=0:76;

Q1.20 The average power of the generated sinusoidal sequence is:

With period T = 10, we have average power of this sequence

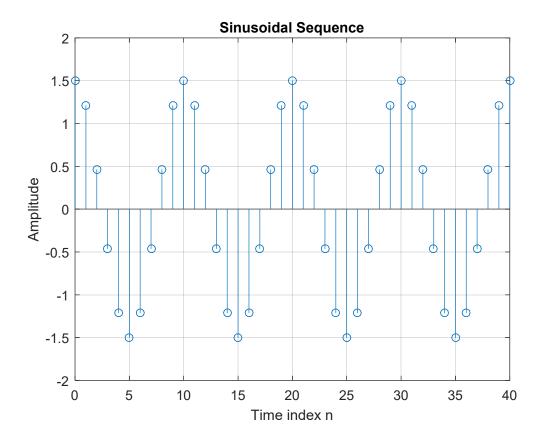
$$sum(x(1:10).*x(1:10))/10=1.125$$
 (power unit)

- Q1.21 The purpose of axis command is used to *set axis limits and appearance*.

 The purpose of grid command is used to *display or hide axes grid lines*.
- Q1.22 The modified Program P1_4 to generate a sinusoidal sequence of frequency 0.9 is given below along with the sequence generated by running it.

```
% Generation of a sinusoidal sequence
clc; clear all; close all;
n = 0:40;
f = 0.9;
phase = 0;
A = 1.5;
arg = 2*pi*f*n - phase;
x = A*cos(arg);
stem(n,x); % Plot the generated sequence
axis([0 40 -2 2]);
grid;
```

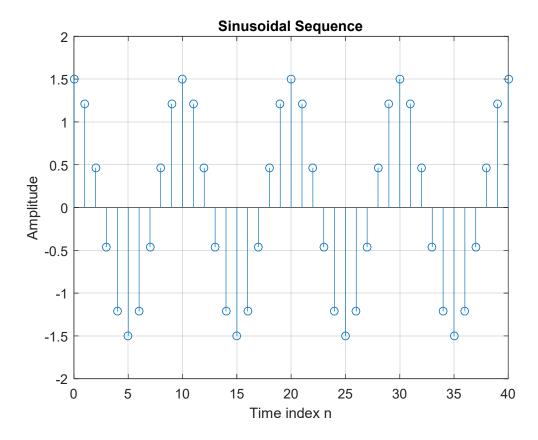
```
title('Sinusoidal Sequence');
xlabel('Time index n');
ylabel('Amplitude');
axis;
```



+ A comparison of this new sequence with the one generated in *Question Q1.17* shows that

The two signals have similar shape and both have properties of cosine functions. As we know, the sine function is a periodic function with period $T=2\pi$ and is even function $\cos\left(\omega\right)=\cos\left(-\omega\right)$ (*). So $0.9.2\pi-2\pi=-0.1.2\pi$, following (*) we get this conclusion.

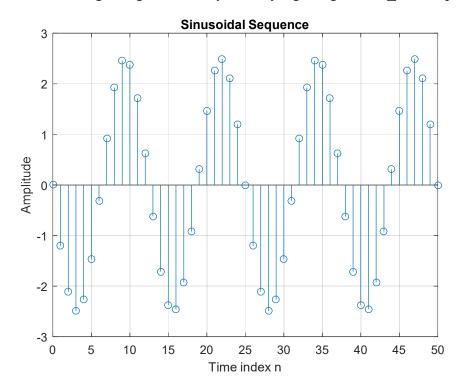
+ A sinusoidal sequence of *frequency 1.1* generated by modifying Program P1_4 is shown below.



+ A comparison of this new sequence with the one generated in *Question Q1.17* shows that:

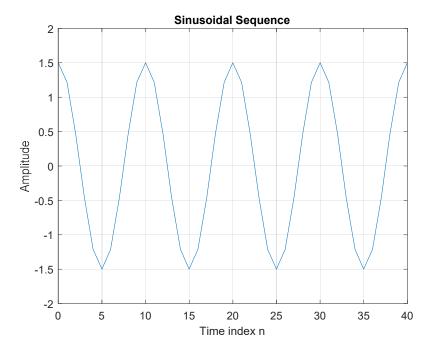
The two signals have similar shape and both have properties of cosine functions one morw time. As mentioned previously, So $1,1.2\pi-2\pi=0,1.2\pi$, following (*) we get this conclusion again.

Q1.23 The sinusoidal sequence of length 50, frequency 0.08, amplitude 2.5, and phase shift of 90 degrees generated by modifying Program P1 4 is displayed below.



The period of this sequence is
$$T = \frac{k2\pi}{\omega} = \frac{k}{f} = \frac{k}{0.08} = 12.5k = 25, 50, \dots$$

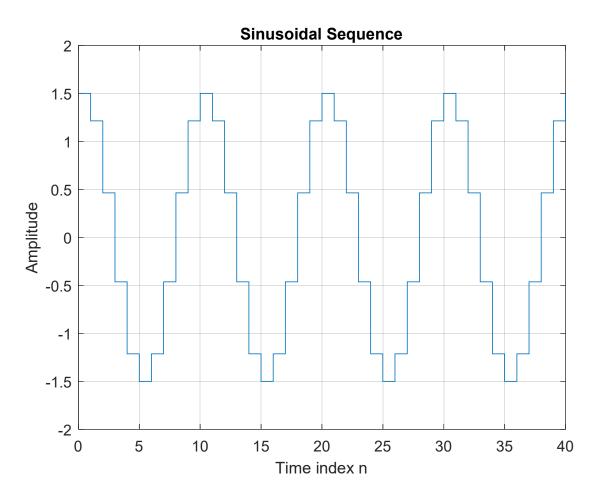
Q1.24 By replacing the stem command in Program P1_4 with the plot command, the plot obtained is as shown below:



→ The difference between the new plot and the one generated in Question Q1.17 is:

The main point of difference between the two is that plot displays the continuous values for the curve by connecting the points with straight line segments, which approximates the graph of a continuous-time cosine signal. On the other hand, stem displays the discrete values of the points on the curve.

Q1.25 By replacing the stem command in Program P1_4 with the stairs command the plot obtained is as shown below:



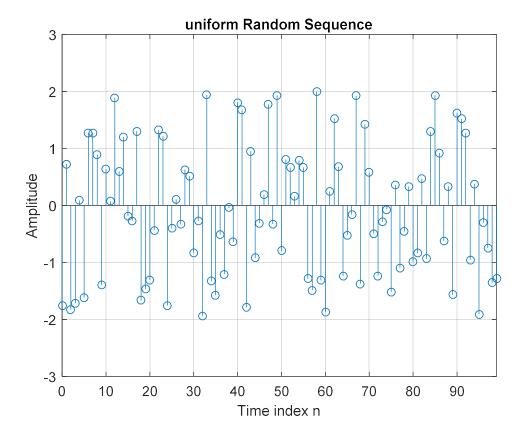
The difference between the new plot and those generated in *Questions Q1.17* and *Q1.24* is:

→ Unlike plot and stem command, stairs command draws a stairstep graph.

Project 1.4 Random signals

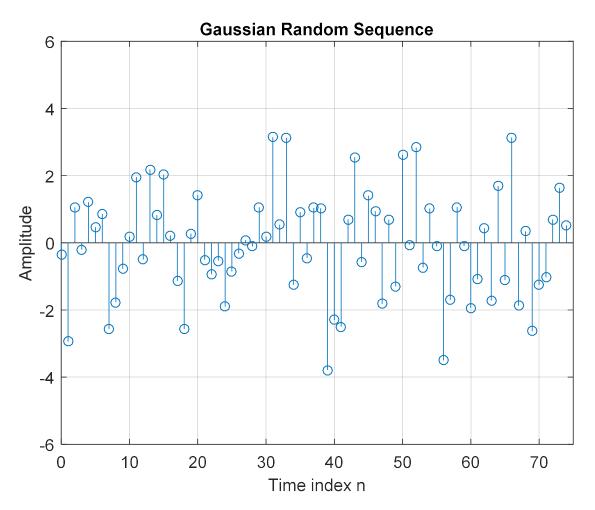
Q1.26 The MATLAB program to generate and display a random signal of length 100 with elements *uniformly distributed* in the interval [-2, 2] is given below along with the plot of the random sequence generated by running the program:

```
n=0:99;
x = 4*(rand(1,100)-0.5); %4*([0,1]-0.50=[2,2]
clf;
stem(n,x);
title('uniform Random Sequence');
xlabel('Time index n');
ylabel('Amplitude');
axis([0 99 -3 3]);
grid on
```



Q1.27 The MATLAB program to generate and display a *Gaussian random signal* of length 75 with elements normally distributed with zero mean and a variance of 3 is given below along with the plot of the random sequence generated by running the program:

```
clc; clear all; close all;
n=0:74;
mean=0;
dlc=sqrt(3);
x=dlc*randn(1,75)+mean; %p=aX+b
stem(n,x);
axis([0 75 -6 6]);
grid;
title('Gaussian Random Sequence');
xlabel('Time index n');
ylabel('Amplitude');
```

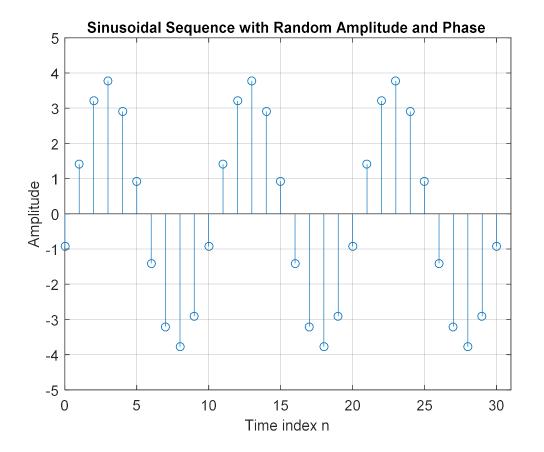


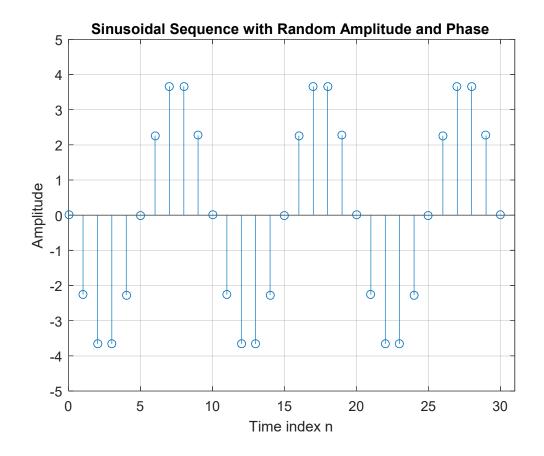
Q1.28 The MATLAB program to generate and display five sample sequences of a random sinusoidal signal of length 31 $\left\{x\left(n\right) = A\cos\left(\omega_{_{0}}n + \phi\right)\right\}$

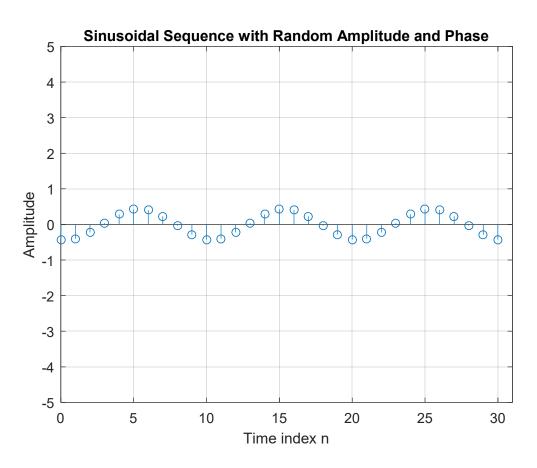
where the amplitude A and the phase ϕ are statistically independent random variables with uniform probability distribution in the range $0 \le A \le 4$ for the amplitude and in the range

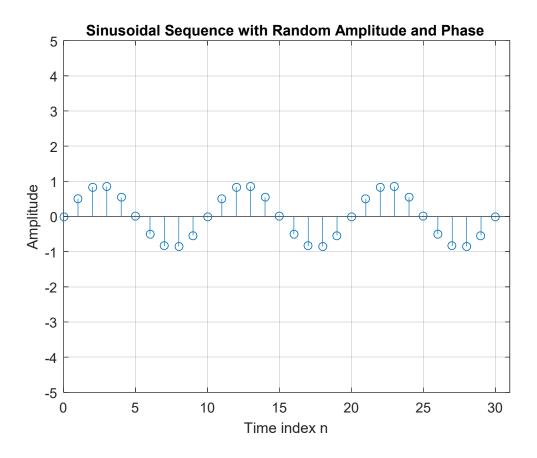
 $0 \le \phi \le 2\pi$ for the phase is given below. Also shown are five sample sequences generated by running this program five different times.

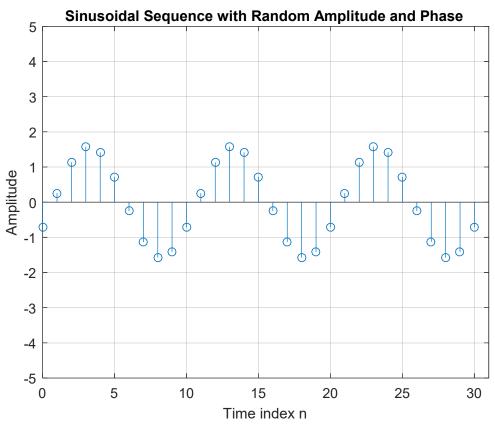
```
clc; clear all; close all;
n = 0:30;
f = 0.1;
Amax = 4;
phimax = 2*pi;
A = Amax*rand;
phi = phimax*rand;
arg = 2*pi*f*n + phi;
x = A*cos(arg);
stem(n,x);
axis([0 31 -5 5]);
grid;
title('Sinusoidal Sequence with Random Amplitude and
Phase');
xlabel('Time index n');
ylabel('Amplitude'); axis;
```











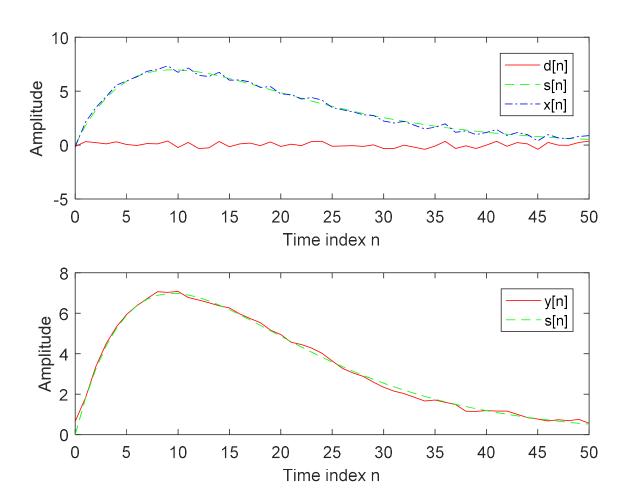
1.2 SIMPLE OPERATIONS ON SEQUENCES

Project 1.5 Signal Smoothing

A copy of Program P1 5 is given below.

```
% Signal Smoothing by Averaging
clc; clear all; close all;
R = 51;
d = 0.8*(rand(R,1) - 0.5); % Generate random
noise
m = 0:R-1;
s = 2*m.*(0.9.^m); % Generate uncorrupted
signal
x = s + d'; % Generate noise corrupted
signal
subplot(2,1,1);
plot(m,d','r-',m,s,'g--',m,x,'b-.');
xlabel('Time index n');
ylabel('Amplitude');
legend('d[n] ','s[n] ','x[n] ');
x1 = [0 \ 0 \ x]; x2 = [0 \ x \ 0]; x3 = [x \ 0 \ 0];
y = (x1 + x2 + x3)/3;
subplot(2,1,2);
plot(m, y(2:R+1), 'r-', m, s, 'q--');
legend( 'y[n] ','s[n] ');
xlabel('Time index n');
ylabel('Amplitude');
```

Q1.29 The signals generated by running Program P1 5 are displayed below:



Q1.30 The uncorrupted signal s[n] is a decreasing exponential function.

The additive noise d[n] is a random sequence uniformly distributed between -0.4 and + 0.4.

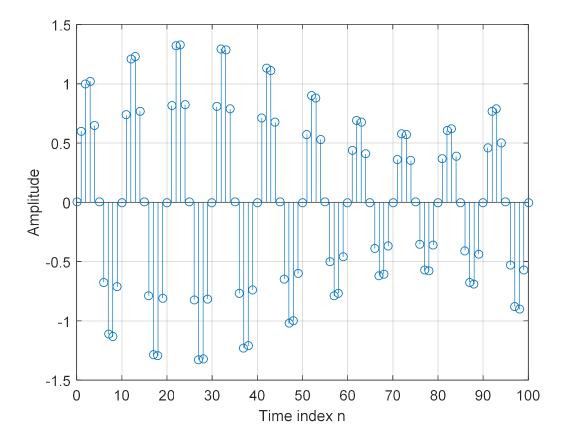
- Q1.31 The statement x = s + d CANNOT be used to generate the noise corrupted signal because d is a column vector, whereas s is a row vector; it is necessary to transpose one of these vectors before adding them.
- Q1.32 The relations between the signals x1, x2, and x3, and the signal x are all of those signals x1, x2, and x3 are another versions of x, with one is at the left and one is at the right. The signal x1 is a delayed version of x, the signal x2 is equal to x and x3 is a time advanced version of x.
- Q1.33 The purpose of the legend command is used to add legend to graph.

Project 1.6 Generation of Complex Signals

A copy of Program P1 6 is given below.

```
% Generation of amplitude modulated sequence
clc; clear all; close all;
n = 0:100;
m = 0.4; fH = 0.1; fL = 0.01;
xH = sin(2*pi*fH*n);
xL = sin(2*pi*fL*n);
y = (1+m*xL).*xH;
stem(n,y); grid;
xlabel('Time index n'); ylabel('Amplitude');
```

Q1.34 The amplitude modulated signals y[n] generated by running Program P1_6 for various values of the frequencies of the carrier signal xH[n] and the modulating signal xL[n], and various values of the modulation index m are shown below:

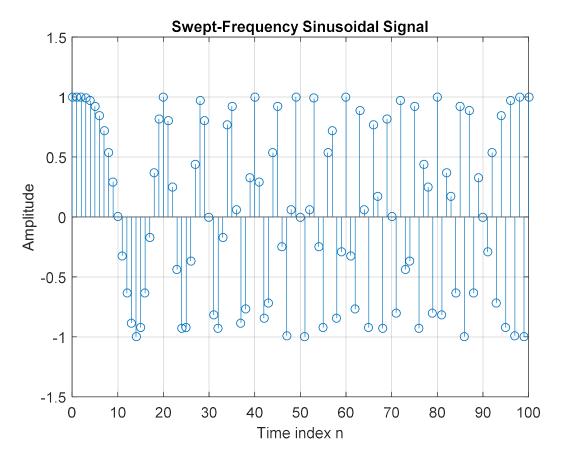


Q1.35 The difference between the arithmetic operators * and .* is: "*" multiplies two conformable matrices or vectors using matrix multiplication. ".*" takes the pointwise products of the elements of two matrices that have the same dimensions.

A copy of Program P1 7 is given below.

```
% Program P1 7
clc; clear all; close all;
n = 0:100;
a = pi/2/100;
b = 0;
arg = a*n.*n + b*n;
x = cos(arg);
stem(n, x);
axis([0,100,-1.5,1.5]);
title('Swept-Frequency Sinusoidal
Signal');
xlabel('Time index n');
ylabel('Amplitude');
grid;
axis;
```

Q1.36 The swept-frequency sinusoidal sequence x[n] generated by running Program P1_7 is displayed below.



Q1.37 The minimum and maximum frequencies of this signal are:

As the frequency of a sinusoidal signal is the derivative of its phase with respect to time,

so we have
$$\omega = (an^2 + bn)' = 2an + b = 2.\frac{\pi}{2.100}.n$$

+ The minimum frequencie is 0 when $n=0 \Rightarrow \omega=0$

+ The maximum frequencie is 0.5 when $n = 100 \Rightarrow \omega = 2.\frac{\pi}{2.100}.100 = \pi$

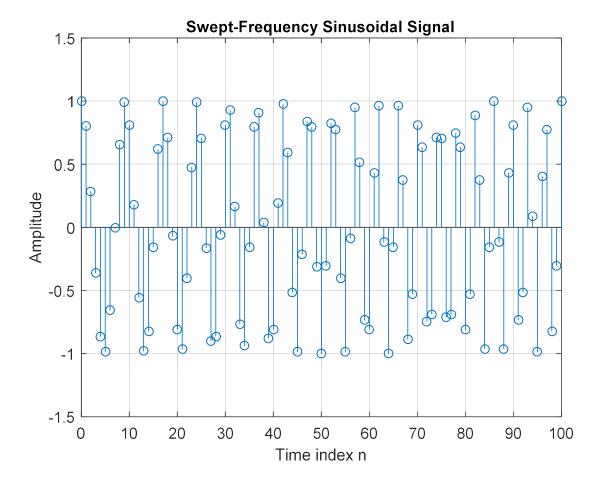
Q1.38 The Program 1_7 modified to generate a swept sinusoidal signal with a minimum frequency of 0.1 and a maximum frequency of 0.3 is given below:

We have the following system of equations:

$$\begin{cases} \omega_{\min(n=0)} &= 2.a.0 + b = 0, 1.2\pi \\ \omega_{\max(n=100)} &= 2.100.a + b = 0, 3.2\pi \end{cases} \Rightarrow \begin{cases} b = 0.2\pi \\ a = 2\pi.10^{-3} \end{cases}$$

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```
clc; clear all; close all;
n = 0:100;
a = 2*pi*10^(-3);
b = 0.2*pi;
arg = a*n.*n + b*n;
x = cos(arg);
stem(n, x);
axis([0,100,-1.5,1.5]);
title('Swept-Frequency Sinusoidal Signal');
xlabel('Time index n');
ylabel('Amplitude');
grid;
```



1.3 WORKSPACE INFORMATION

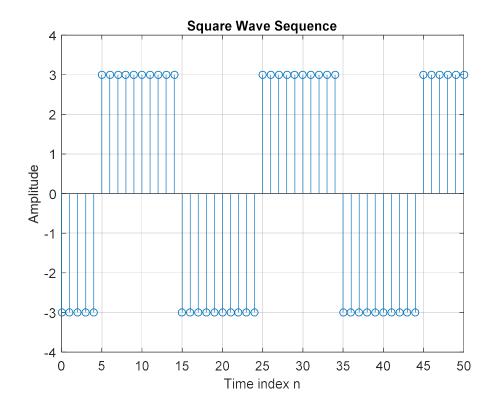
- Q1.39 The information displayed in the command window as a result of the who command is a list of variables in current workspace.
- Q1.40 The information displayed in the command window as a result of the whos command is a list of variables in workspace, with sizes and types.

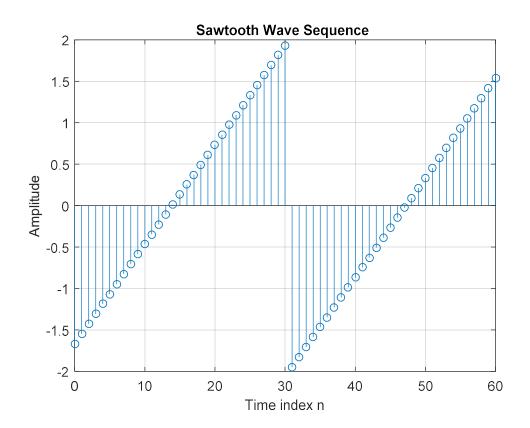
1.4 OTHER TYPES OF SIGNALS (Optional)

Project 1.8 Squarewave and Sawtooth Signals

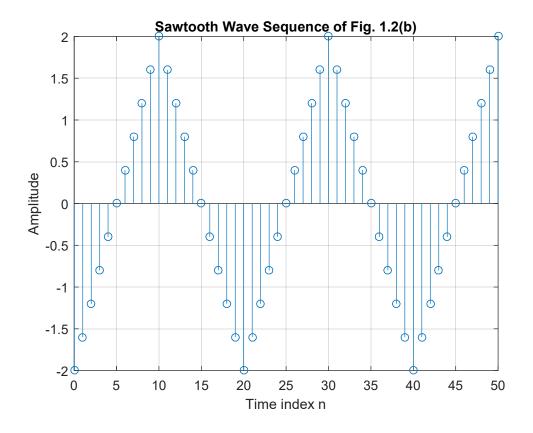
Q1.41 MATLAB programs to generate the square-wave and the sawtooth wave sequences of the type shown in Figures 1.1 and 1.2 are given below along with the sequences generated by running these programs:

```
clc; clear all; close all;
n = 0:50;
f = 0.05;
phase = -pi/2;
duty=50;
A = 3;
arg = 2*pi*f*n + phase;
x = A*square(arg,duty);stem(n,x); % Plot the
generated sequence
axis([0 50 -4 4]);
grid;
title('Square Wave Sequence');
xlabel('Time index n');
ylabel('Amplitude');
axis;
n = 0:60;
f = 0.03;
phase = pi/6;
clc; clear all; close all;
peak = 1;
A = 2.0;
arg = 2*pi*f*n + phase;
x = A*sawtooth(arg,peak);
stem(n,x); % Plot the generated sequence
axis([0 60 -2 2]);
grid;
title ('Sawtooth Wave Sequence ');
xlabel('Time index n');
ylabel('Amplitude');
```





```
clc; clear all; close all;
n = 0:50;
f = 0.05;
phase = 0;
peak = 0.5;
A = 2.0;
arg = 2*pi*f*n + phase;
x = A*sawtooth(arg,peak);
clf; % Clear old graph
stem(n,x); % Plot the generated sequence
axis([0 50 -2 2]);
grid;
title ('Sawtooth Wave Sequence of Fig. 1.2(b)');
xlabel('Time index n');
ylabel('Amplitude');
axis;
```



Date: 29/08/2023 Signature: Do Trung Hau