MA1512 TUTORIAL 1

Key Concepts – Chapter 1 Differential Equations

Theory

- General solutions to DE containing arbitrary constants.
- Substituting specific values into constants of general solutions produces a particular solution.
- The general solution of an n^{th} order DE will contain n arbitrary constants.

Solving 1st order DEs

Technique 1:

Question 1

Separable Equations

$$y' = M(x)N(y)$$

$$\Rightarrow \int \frac{1}{N(y)} dy = \int M(x) dx$$

<u>Technique 2 (1st Type)</u>: Change of Variable

Form:
$$y' = f(ax + by + c)$$

If $b \neq 0$, the equation will be reduced to a separable form.

Strategy: Substitution

Let
$$u = ax + by + \{c\}$$
, $u' = \frac{d}{dx}(ax + by + c) = a + by'$

Simplifying the equation into a separable form:

$$y' = f(ax + by + c)$$
$$(u' - a)/b = f(u)$$
$$u' = bf(u) + a$$

Technique 2 (2nd Type): Change of Variable

Form:
$$y' = f(\frac{y}{y})$$

Strategy: Substitution

Let
$$u = \frac{y}{x}$$
, $y' = u'x + ux' = u'x + u$

simplifying the equation into a separable form:

$$y' = f\left(\frac{y}{x}\right)$$
$$u'x + u = f(u)$$
$$\frac{1}{f(u) - u}du = \frac{1}{x}dx$$

Typical Applications

| Context | Differential Equation | Solution |
|---|-----------------------------------|---|
| Hot object left in environment <i>T</i> is the temperature of object. | $\frac{dT}{dt} = -k(T - T_{env})$ | $T = T_{env} + Ae^{-kt}$ |
| Radioactive Decay <i>x</i> is the amount of substance. | $\frac{dx}{dt} = -kx$ | $x = Ae^{-kt}, k = \frac{\ln 2}{t_{1/2}}$ |

Key Concepts – Chapter 1 Differential Equations

1st order DE (continued)

Technique 3: Integrating Factor

$$y' + P(x)y = Q(x)$$

Derivation:

Step 1 Define **Integrating Factor**:

$$R(x) = e^{\int^x P(s) ds}$$

$$R'(x) = \frac{d}{dx} e^{\int^x P(s) ds} = e^{\int^x P(s) ds} * \left(\int^x P(s) ds\right)'$$

$$= R(x)P(x)$$

Step 2 Multiply the DE by R(x):

$$R(x)\frac{dy}{dx} + R(x)P(x)y = R(x)Q(x)$$
$$R(x)y' + R'(x)y = R(x)Q(x)$$

Step 3 Recognize the LHS as (Ry)' according to product rule, then:

$$LHS = (Ry)', RHS = RQ$$

 $(Rv)' = RO$

Step 4 Integrate both sides simultaneously:

$$Ry = \int RQ$$

Integrating Factor Method Solution Steps:

$$y' + P(x)y = Q(x)$$

Step 1 Find Integrating Factor:

$$R(x) = e^{\int^x P(s) \, ds}$$

Step 2 Transform the DE to

$$(Ry)' = RQ$$

Step 3 Integrate both sides simultaneously:

$$Ry = \int RQ + C \quad (CEIR)$$

$$y = \frac{1}{R} \left(\int RQ \, dx + C \right)$$

REMARK

- 1. This method applies to all **linear** 1^{st} order DE
- 2. Remember to fit the DE into the standard form before finding the value of P(x) and Q(x).

Technique 4: Bernoulli Equation

$$y' + p(x)y = q(x)y^n$$

Derivation:

Step 1 Divided by y^n :

$$y^{-n}y' + p(x)y^{1-n} = q(x)$$

Step 2 Substitution: Let $z = y^{1-n}$,

$$z' = (1 - n)y^{-n}y'$$
, i.e. $y^{-n}y' = (1 - n)^{-1}z'$
 $y^{-n}y' + p(x)y^{1-n} = q(x)$

$$(1-n)^{-1}z' + p(x)z = q(x)$$

Simplifying:

$$z' + (1-n)p(x)z = (1-n)q(x).$$

Step 3 Solve the first order linear differential equation using the integrating factor method.

Bernoulli's Equation Solution Steps:

$$y' + p(x)y = q(x)y^n$$

Step 1 Find out n

Step 2 Set $z = y^{1-n}$

Step 3 Directly transform to

$$z' + (1-n)p(x)z = (1-n)q(x).$$

Step 4 Solve the DE using the integrating factor method

REMARK

- 1. In this case, $n \neq 0$, 1. (Why?)
- 2. Remember to fit the DE into the standard form before finding the value of n, p(x) and q(x).

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KEY CONCEPTS - CHAPTER 1 DIFFERENTIAL EQUATIONS

Consider the following 2nd order linear ordinary differential equation with Constant Real Coefficients:

$$y'' + ay' + by = r(x)$$

• If $r(x) \equiv 0$, this is known as a **homogeneous DE**. Then, the general solution is given by:

$$y = C_1 y_1 + C_2 y_2$$

where y_1 and y_2 are linearly independent solutions to the DE.

• If $r(x) \not\equiv 0$, the DE becomes **non-homogeneous**. Thus, the general solution is given by:

$$y = y_h + y_p = (C_1 y_1 + C_2 y_2) + y_p$$

where y_h is the general solution to the homogeneous DE and y_p is the particular solution satisfying the non-homogeneous DE.

• Homogenous 2nd Order Linear ODEs with Constant Real Coefficients:

What is the underlying principle for the characteristic equation?

$$ay'' + by' + cy = 0$$
, $a, b, c \in \mathbb{R}$

Step 1 Find out the characteristic equation $a\lambda^2 + b\lambda + c = 0$. Then solve for λ .

Step 2 Choose case based on λ .

| Case A: λ_1 , λ_2 real and distinct | <u>Case B</u> : λ real, repeated | $\underline{\text{Case C}}: \lambda_{1,2} = \alpha \pm \beta i$ |
|---|---|---|
| G.S.: $y = C_1 e^{\lambda_1 x} + C_2 e^{\lambda_2 x}$ | G.S.: $y = C_1 e^{\lambda x} + C_2 x e^{\lambda x}$ | G.S.: $y = C_1 e^{\alpha x} \cos \beta x + C_2 e^{\alpha x} \sin \beta x$ |

To solve non-homogeneous problems:

• Method of Variation of Parameters: y'' + ay' + by = r(x), $r(x) \neq 0$

Step 1 Find the general solution to homogeneous DE y'' + ay' + by = 0 given by

$$y_h = C_1 y_1 + C_2 y_2.$$

Step 2 Find Wronskian $W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_1' y_2.$

Step 3 Use the formula to find u and v.

$$u = -\int \frac{y_2 r}{W(y_1, y_2)} dx \qquad v = \int \frac{y_1 r}{W(y_1, y_2)} dx \qquad y_p = u y_1 + v y_2$$

Step 4 The general solution is given by $y = (C_1y_1 + C_2y_2) + (uy_1 + vy_2) = y_h + y_p$.

• Method of Undetermined Coefficients: y'' + ay' + by = r(x), $r(x) \not\equiv 0$

Step 1 Find the general solution y_h to homogeneous DE y'' + ay' + by = 0.

Step 2 Choose case based on r(x).

| Case A: $r(x)$ is a polynomial | $\underline{\text{Case B}}: r(x) = P(x)e^{kx}$ | $\frac{\text{Case } C}{\text{or } r(x) \equiv P(x)e^{\alpha x} \sin \beta x}$ $\text{or } r(x) \equiv P(x)e^{\alpha x} \cos \beta x$ |
|---|---|---|
| Guess y_p to be a polynomial with unknown constant coefficients with the same degree as $r(x)$. • Otherwise, choose next higher powers. | polynomial, and deg $(u(x)) = 0$ B. If the value of k is the same a guess u to be a polynomial, and | is either simple root λ_1 or λ_2 , then it deg $(u(x)) = \deg(P(x)) + 1$. the repeated root λ , then guess u to |

Step 3 The general solution is given by $y = y_h + y_p$.

CHAPTER 2 - APPLICATIONS OF ODES

The Harmonic Oscillator

Type 1 Simple Harmonic Oscillator

 $m\ddot{x} + kx = 0$, where m, k > 0

m is the mass and k is the spring constant.

General Solution:

$$x(t) = C\cos\omega t + D\sin\omega t$$

= $A\cos(\omega t - \delta)$

Angular frequency: ω ; Amplitude: A;

Phase Angle: δ

Period =
$$\frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$
; Frequency, $f = \frac{1}{T}$;

Type 2 Forced Harmonic Oscillator

$$m\ddot{x} + kx = F(t) = F_0 \cos \alpha t$$

General Solution:

$$x(t) = A\cos(\omega t - \delta) + \frac{F_0/m}{\omega^2 - \alpha^2}\cos\alpha t$$

Assume initial conditions x(0) = 0 and $\dot{x}(0) = 0$, we get particular solution:

$$x(t) = \frac{\left(\frac{F_0}{m}\right)}{\omega^2 - \alpha^2} [\cos \alpha t - \cos \omega t]$$

$$= \left[\frac{\left(\frac{2F_0}{m}\right)}{\alpha^2 - \omega^2} \sin \left(\frac{\alpha - \omega}{2}t\right)\right] \sin \left(\frac{\alpha + \omega}{2}t\right)$$

$$= A(t) \sin \left(\frac{\alpha + \omega}{2}t\right)$$

Resonance: $\alpha = \omega$

Particular Solution:

$$x(t) = \frac{F_0 t}{2m\omega} \sin(\omega t)$$

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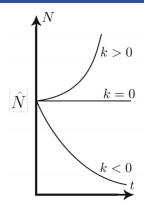
KEY CONCEPTS - CHAPTER 3 MATHEMATICAL MODELLING

Malthus Model of Population:

$$\frac{dN}{dt} = (B - D)N = kN$$

• Solution: $N(t) = \widehat{N}e^{kt}$, where \widehat{N} is the initial population

Question How do different values of *k* affect the prediction of population growth using the Malthus Model?



Logistic Growth Model:

Assumption: $D \sim N$, D = sN

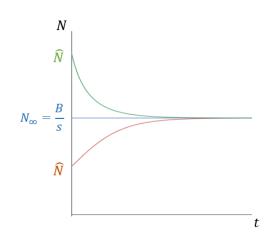
$$\frac{dN}{dt} = (B - D)N = (B - sN)N = -sN^2 + BN$$

- A logistic growth model has (1) increasing initial growth; (2) slower growth as saturation steps in; (3) growth stops upon maturation.
- Solution:

$$N = \frac{N_{\infty}}{1 + \left(\frac{N_{\infty}}{\widehat{N}} - 1\right)e^{-Bt}}$$

where $N_{\infty} = \frac{B}{s}$ (carrying capacity/logistic population) and $N(0) = \widehat{N}$.

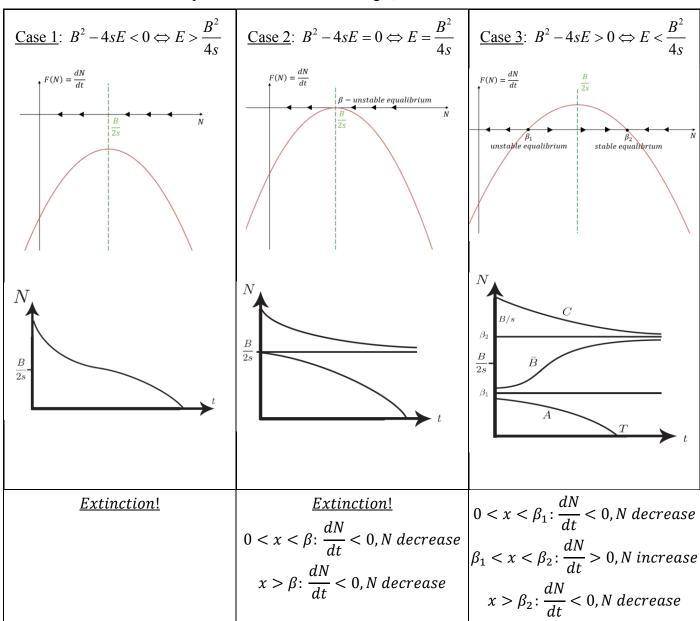
• The graph of N against t is shown below, with different initial starting values of N_0 .



Harvesting Model:

$$\frac{dN}{dt} = BN - sN^2 - E$$

To find equilibrium solutions, we consider $BN - sN^2 - E = 0$. The discriminant $B^2 - 4sE$ is of concern, as it will tell us the number of equilibrium solutions we will get, as well as the behaviour of N with time t.



Key Concepts – Chapter 4 Laplace Transform

• Laplace transform L(f) is a mapping L which maps a function f(t) to a function F(s), where F(s) is given by

$$L(f(t)) = F(s) = \int_0^\infty e^{-st} f(t) dt$$

• The Laplace transform and inverse Laplace's transform has the **linearity** property (α and β are constants):

$$L(\alpha f + \beta g) = \alpha L(f) + \beta L(g)$$
 $L^{-1}(\alpha f + \beta g) = \alpha L^{-1}(f) + \beta L^{-1}(g)$

- Solving **Initial** Value Problems
 - **Step 1** Perform Laplace transform on the DE (in terms of t) and transform it into an **algebraic** subsidiary equation.
 - **Step 2** Substitute in the appropriate initial values from the problem and make L(f) the subject of the formula (in terms of s).
 - Step 3 Perform inverse Laplace transform on the resultant equation to obtain the solution (in terms of *t*) for the differential equation.
- The standard Laplace transforms and its inverses are presented in the table below.

| $L(k) = \frac{k}{s}, k \in \mathbb{R}$ | $L^{-1}\left(\frac{k}{s}\right) = k, k \in \mathbb{R}$ | | | |
|--|---|--|--|--|
| $L(t^n) = \frac{n!}{s^{n+1}}$ | $L^{-1}\left(\frac{1}{s^n}\right) = \frac{t^{n-1}}{(n-1)!}$ | | | |
| $L(e^{at}) = \frac{1}{s-a}, s > a$ | $L^{-1}\left(\frac{1}{s-a}\right) = e^{at}$ | | | |
| $L(\cos at) = \frac{s}{s^2 + a^2}, s > 0$ | $L^{-1}\left(\frac{s}{s^2+a^2}\right) = \cos at$ | | | |
| $L(\sin at) = \frac{a}{s^2 + a^2}, s > 0$ | $L^{-1}\left(\frac{a}{s^2+a^2}\right) = \sin at$ | | | |
| $L(\cosh at) = \frac{s}{s^2 - a^2}, s > a $ | $L^{-1}\left(\frac{s}{s^2 - a^2}\right) = \cosh at$ | | | |
| $L(\sinh at) = \frac{a}{s^2 - a^2}, s > a $ | $L^{-1}\left(\frac{a}{s^2 - a^2}\right) = \sinh at$ | | | |
| $L(f(t-a)\cdot u(t-a)) = e^{-as}\cdot F(s)$ | $L^{-1}(e^{-as}F(s)) = f(t-a) \cdot u(t-a)$ | | | |
| $L(\delta(t-a)) = e^{-as}$ | $L^{-1}(e^{-as}) = \delta(t-a)$ | | | |
| L(y') = sL(y) - y(0) | | | | |
| $L(y'') = s^2 L(y)$ | -sy(0)-y'(0) | | | |
| $L\left(\int_0^t f(\tau) d\tau\right) = \frac{1}{s}L(f), s > 0$ | | | | |
| Frequency-Shifting (<i>s</i> -shifting): | Time-shifting (<i>t</i> -shifting): | | | |
| $L(e^{ct}f(t)) = F(s-c)$ | $L^{-1}(e^{-as}F(s)) = f(t-a) \cdot u(t-a)$ | | | |
| $L(e^{ct}t^n) = \frac{n!}{(s-c)^{n+1}}$ | $L^{-1}\left(\frac{1}{(s-c)^n}\right) = \frac{e^{ct}t^{n-1}}{(n-1)!}$ | | | |
| $L(e^{ct}\cos\omega t) = \frac{s-c}{(s-c)^2 + \omega^2}$ | $L^{-1}\left(\frac{s-c}{(s-c)^2+\omega^2}\right) = e^{ct}\cos\omega t$ | | | |
| $L(e^{ct}\sin\omega t) = \frac{\omega}{(s-c)^2 + \omega^2}$ | $L^{-1}\left(\frac{\omega}{(s-c)^2+\omega^2}\right) = e^{ct}\sin\omega t$ | | | |

Key Concepts – Chapter 5 Partial Differential Equations

Separation of Variables

- **Step 1** Assume that the solution is in the form $u(x, y) = X(x) \cdot Y(y)$.
- Step 2 Substitute the form above into the PDE.
- **Step 3** Perform separation of variables across equal signs, and equate it to a constant. (**Question** Why must we equate to a constant?)
- **Step 4** Separate the variables to obtain ODEs with their boundary conditions.
- **Step 5** Obtain solutions to both ODEs and combine them to give the solution u.

WAVE EQUATION

$$\begin{split} u_{tt} &= c^2 u_{xx}, & 0 \leq x \leq \pi, \ t > 0 \\ u(0,t) &= 0, \ u(\pi,t) = 0, \\ u(x,0) &= f(x), \ u_t(x,0) = 0. \end{split}$$

Then,
$$u(x,t) = \frac{1}{2} [f(x+ct) + f(x-ct)]$$
 is a solution, where f is an odd extension with period

solution, where f is an odd extension with period 2π .

HEAT EQUATION:

$$u_t = c^2 u_{xx},$$

 $u(0,t) = 0, \ u(L,t) = 0,$
 $u(x,0) = f(x).$

Then
$$u(x,t) = \sum_{n=1}^{\infty} b_n \sin\left(\frac{n\pi}{L}x\right) e^{-c^2\left(\frac{n\pi}{L}\right)^2 t}$$
 is a solution.