Temporal Reasoning with OpenCog

Nil Geisweiller

SingularityNET & OpenCog Foundations





Why Temporal Reasoning?

- Lag between cause and effect
- Meta-reasoning: Think about think about think about think about think about ...



PLN Recall

$$P, Q, \ldots$$
: Atomⁿ $\rightarrow \{True, False\}$

And <TV>

$$\begin{array}{c} P \\ Q \\ \\ \text{Not} & < \text{TV} > \\ P \\ \\ \\ \text{Implication} & < \text{TV} > \\ \\ P \\ \\ \\ \\ \\ \\ \end{array} \equiv \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{array}$$

$$\mathcal{P}(P,Q) \approx TV.$$
strength

$$\mathcal{P}(P) \approx 1 - TV.strength$$

$$\mathcal{P}(Q|P) \approx TV.$$
strength

PLN rules: Implication Direct Evaluation

```
Evaluation
  Εi
Evaluation
  Εi
Implication <TV>
```

$$TV.strength = \frac{\sum_{x} f_{\land}(P(x).strength, Q(x).strength)}{\sum_{x} P(x).strength}$$

PLN rules: Deduction

```
P
Q
Implication
Q
R
|-
Implication <TV>
P
R
```

Implication

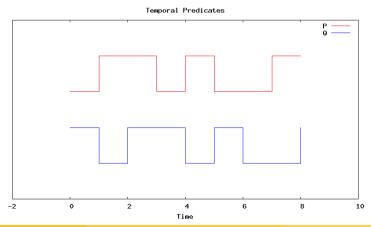
$$TV.strength = \mathcal{P}(R|Q,P) \times \mathcal{P}(Q|P) + \mathcal{P}(R|\neg Q,P) \times \mathcal{P}(\neg Q|P)$$



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Temporal Predicate

$P: Atom^n \times Time \rightarrow \{True, False\}$



LagLink and LeadLink

Lag: brings past into present

LagLink

P

x, t

T

≡

LambdaLink

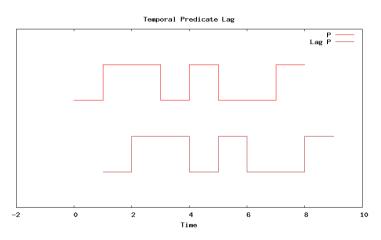
x, t

P(x, t-T)

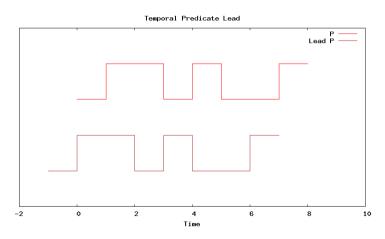
Lead: brings future into present

LeadLink P \equiv X, t P(x, t+T)

Lag: example



Lead: example



SequentialAnd

```
BackSequentialAnd <TV>
ForeSequentialAnd <TV>
                          \equiv
```

```
Lag
P
T
Q
And <TV>
P
Lead
Q
-
```

And <TV>

```
BackPredictiveImplication <TV>
ForePredictiveImplication <TV>
                          \equiv
```

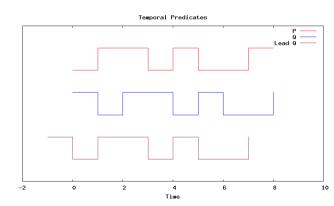
```
Implication <TV>
  Lag
Implication <TV>
  Р
  Lead
```

```
BackPredictiveImplication <TV>
   T
   P
   Q
```

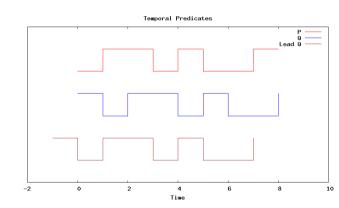
```
ForePredictiveImplication <TV> ^{\rm T}_{\rm P} \equiv 0
```

```
Implication <TV>
  Lag
Implication <TV>
  Ρ
  ForeSequentialAnd
```

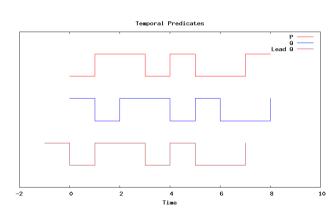
```
Implication \langle s=0.25 \rangle P Q
```



```
Implication \langle s=0.25 \rangle P Q Implication \langle s=0.75 \rangle P Lead Q 1
```



```
Implication \langle s=0.25 \rangle
Implication \langle s=0.75 \rangle
   Lead
PredictiveImplication \langle s=0.75 \rangle
```



• Implication P



• Implication

```
\stackrel{\mathrm{P}}{\circ} \equiv P 	o Q
```

```
T
P ≡
Q
```

$$P \leadsto^T Q$$

• Implication

• PredictiveImplication

Lag

$$extcolor{black}{ extcolor{black}{ ext$$

$$P \leadsto^T Q$$

$$\overrightarrow{P}^7$$

=

• Implication

Q

 \equiv

P o Q

• PredictiveImplication

Τ

Р

≡

 $P \rightsquigarrow^T Q$

• Lag

Т

 \equiv

 \overrightarrow{P}^T

Lead

Ι

Т

 \equiv

 \overleftarrow{P}^T

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Temporal Deduction

$$egin{array}{ccccc} P
ightarrow Q & Q
ightarrow R & P & Q & R \ P
ightarrow R & P
ightarrow$$

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Temporal Deduction

$$\frac{P \to Q \quad Q \to R \quad P \quad Q \quad R}{P \to R} \text{ (Deduction)}$$

$$\frac{P \leadsto^{T_1} Q \quad Q \leadsto^{T_2} R \quad P \quad Q \quad R}{P \leadsto^{T_1 + T_2} R} \text{ (Temporal Deduction?)}$$

Temporal Deduction → Deduction

$$\frac{P \overset{T_1}{\longrightarrow} Q}{P \overset{T_1}{\longrightarrow} Q^{-1}} \text{ (PI2I)} \qquad \frac{Q \overset{T_2}{\longrightarrow} R}{Q \overset{T_1}{\longrightarrow} R^{T_1 + T_2}} \text{ (TS)} \qquad Q \qquad \frac{Q}{\overset{T_1}{\bigcirc} T_1 + T_2} \text{ (TS)} \qquad \frac{R}{\overset{T_1 + T_2}{\nearrow} T_1 + T_2} \text{ (Deduction)} \qquad \frac{P \overset{T_1}{\longrightarrow} R^{T_1 + T_2}}{P \overset{T_1 + T_2}{\longrightarrow} R} \text{ (I2PI)}$$

$$TS: Temporal Shift}$$

- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication



Procedural Reasoning (notations)

• SequentialAnd

$$P \prec^{T} Q$$

 \equiv

Procedural Reasoning (notations)

```
• SequentialAnd

T
P
\mathbb{P}
\mathbb{Q}

• Lambda
T
AtTime
Execution
A
```



Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Cognitive Schematics

- Monoaction plan
- Diaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

$$\left((C \wedge \widehat{A_1}) \prec^{T_1} \widehat{A_2}\right) \leadsto^{T_1 + T_2} G$$

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Diaction plan

$$\left((C \wedge \widehat{A_1}) \prec^{T_1} \widehat{A_2} \right) \leadsto^{T_1 + T_2} G$$

Polyaction plan

$$\left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^{2} \mathit{OpenDoor}\right) \prec^{3} \mathit{StepOut}\right) \leadsto^{6} \mathit{Outside}$$



Temporal Deduction for Procedural Reasoning

$$\frac{P \wedge \widehat{A} \rightsquigarrow^{T_1} Q}{P \wedge \widehat{A} \rightarrow \overleftarrow{\Omega}^{T_1}} \text{ (Pl2I)} \qquad \frac{\widehat{B}}{\overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B} \rightsquigarrow^{T_2} R}{Q \wedge \widehat{B} \rightarrow \overleftarrow{B}^{T_2}} \text{ (Pl2I)} \qquad Q \wedge \widehat{B} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (Pl2I)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (Pl2I)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (D)}$$

- D: Deduction
- CI: Conjunction Introduction
- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication



Procedural Reasoning Example

$$\begin{array}{c} \left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \rightsquigarrow^3 \mathit{OpenDoorStep} \\ \\ \mathit{OpenDoorStep} \land \mathit{StepOut} \rightsquigarrow^1 \mathit{Outside} \\ \\ \vdash \\ \left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \prec^3 \mathit{StepOut}\right) \rightsquigarrow^6 \mathit{Outside} \end{array}$$

Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - ...

Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

Temporal Truth Value

Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - . . .
- Distributional Time
 - Temporal Interval

$$(((\mathit{Inside} \land \mathit{WalkToDoor}) \prec^{[1,2]} \widehat{\mathit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\mathit{StepOut}}) \leadsto^{[1.6,4]} \mathit{Outside}$$

Temporal Truth Value

Behavior Tree

$$(((Inside \land WalkToDoor) \prec (Locked ? SmashDoor : OpenDoor)) \prec StepOut) \leadsto Outside$$

