

Probabilistic Logic Networks for Temporal and Procedural Reasoning

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SingularityNET

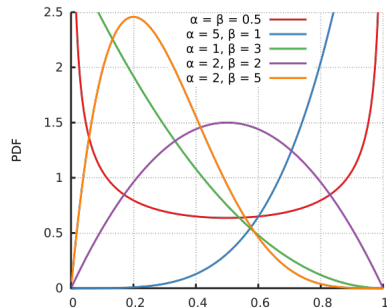


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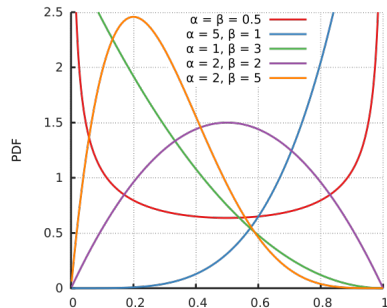
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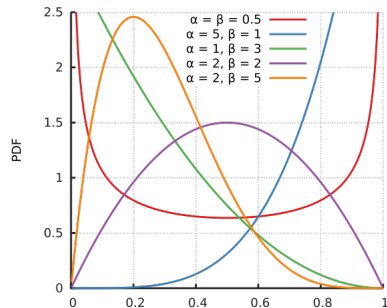
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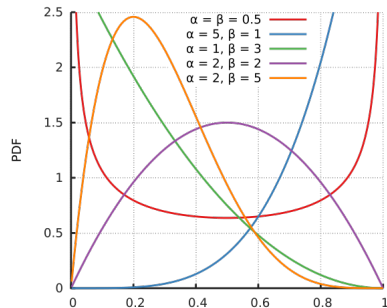
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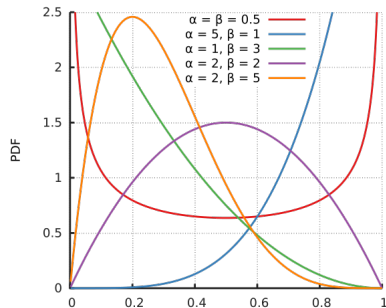
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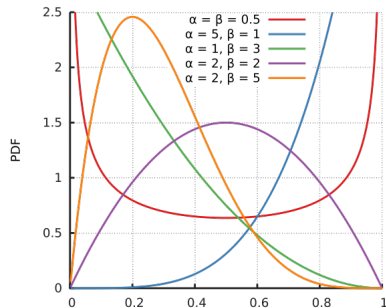
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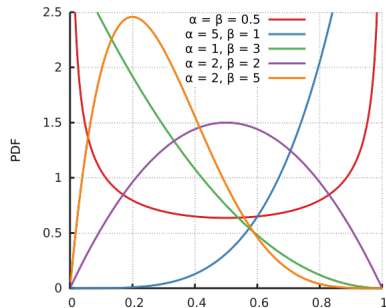
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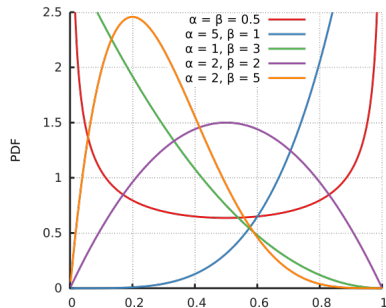
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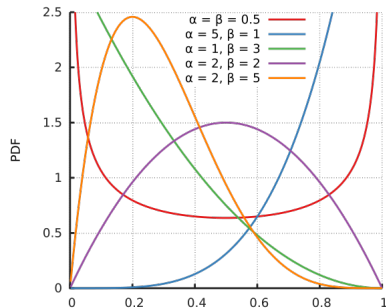
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- Implication Direct Introduction (IDI)

$$\frac{P(a_1) \stackrel{\text{m}}{=} TV_1^P \quad Q(a_1) \stackrel{\text{m}}{=} TV_1^Q \quad \dots \quad P(a_n) \stackrel{\text{m}}{=} TV_n^P \quad Q(a_n) \stackrel{\text{m}}{=} TV_n^Q}{P \rightarrow Q \stackrel{\text{m}}{=} \phi_{IDI}(TV_1^P, \dots, TV_n^Q)} \text{ (IDI)}$$

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- Deduction (D)

$$\frac{P \rightarrow Q \stackrel{\text{m}}{=} TV^{PQ} \quad Q \rightarrow R \stackrel{\text{m}}{=} TV^{QR} \quad P \stackrel{\text{m}}{=} TV^P \quad Q \stackrel{\text{m}}{=} TV^Q \quad R \stackrel{\text{m}}{=} TV^R}{P \rightarrow R \stackrel{\text{m}}{=} \phi_D(TV^{PQ}, \dots, TV^R)} \quad (\text{D})$$

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Temporal Inference Rules:

- Temporal Deduction (TD):

$$\frac{P \rightsquigarrow^{T_1} Q \stackrel{\text{m}}{=} TV^{PQ} \quad Q \rightsquigarrow^{T_2} R \stackrel{\text{m}}{=} TV^{QR} \quad P \stackrel{\text{m}}{=} TV^P \quad Q \stackrel{\text{m}}{=} TV^Q \quad R \stackrel{\text{m}}{=} TV^R}{P \rightsquigarrow^{T_1+T_2} R \stackrel{\text{m}}{=} \phi_{TD}(TV^{PQ}, \dots, TV^R)} \text{ (TD)}$$

$$\frac{P \rightsquigarrow^{T_1} Q \models TV^{PQ} \quad Q \rightsquigarrow^{T_2} R \models TV^{QR} \quad P \models TV^P \quad Q \models TV^Q \quad R \models TV^R}{P \rightsquigarrow^{T_1+T_2} R \models \phi_{TD}(TV^{PQ}, \dots, TV^R)} \text{ (TD)}$$

$$\equiv$$

$$\frac{\frac{P \rightsquigarrow^{T_1} Q \models TV^{PQ}}{P \rightarrow \tilde{Q}^{T_1} \models TV^{PQ}} \text{ (PI)} \quad \frac{\frac{Q \rightsquigarrow^{T_2} R \models TV^{QR}}{Q \rightarrow \tilde{R}^{T_2} \models TV^{QR}} \text{ (PI)} \quad \frac{Q \models TV^Q}{\tilde{Q}^{T_1} \models TV^Q} \text{ (S)} \quad \frac{R \models TV^R}{\tilde{R}^{T_1+T_2} \models TV^R} \text{ (S)}}{\frac{P \rightarrow \tilde{R}^{T_1+T_2} \models \phi_D(TV^{PQ}, \dots, TV^R)}{P \rightsquigarrow^{T_1+T_2} R \models \phi_D(TV^{PQ}, \dots, TV^R)} \text{ (IP)}} \text{ (D)}$$

$$\Downarrow$$

$$\phi_D = \phi_{TD}$$