Temporal Reasoning with OpenCog

Nil Geisweiller

SingularityNET & OpenCog Foundations







Why Temporal Reasoning?

- Lag between cause and effect
- Learn and operate in the world
- Meta-reasoning: Think about think about



PLN Recall

$$extsf{P}, extsf{Q}, \ldots$$
: $extsf{Atom}^n o \{ extsf{True}, extsf{False}\}$ (possibly fuzzy)

And
$$<$$
TV $>$
 P
 Q

Not $<$ TV $>$
 P
 $=$
Implication $<$ TV $>$
 P
 $=$
 Q

$$\mathcal{P}(P,Q) \approx TV.$$
strength

$$\mathcal{P}(P) \approx 1 - TV.$$
strength

$$\mathcal{P}(Q|P) \approx TV.$$
strength

PLN rules: Implication Direct Introduction

```
Evaluation
  Εi
Evaluation
  Εi
Implication <TV>
```

$$TV.strength = \frac{\sum_{x} f_{\land}(P(x).strength, Q(x).strength)}{\sum_{x} P(x).strength}$$

PLN rules: Deduction

```
P Q
Implication Q R |-
Implication <TV> P R
```

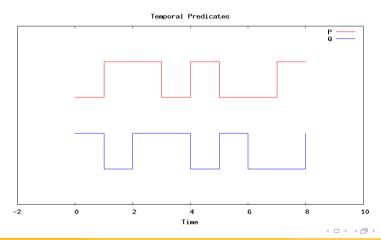
Implication

$$TV.strength = \mathcal{P}(R|Q,P) \times \mathcal{P}(Q|P) + \mathcal{P}(R|\neg Q,P) \times \mathcal{P}(\neg Q|P)$$



Temporal Predicate

$$\mathbb{P}, \mathbb{Q}, \ldots$$
: $\textit{Atom}^n \times \textit{Time} \rightarrow \{\textit{True}, \textit{False}\}$ (possibly fuzzy)

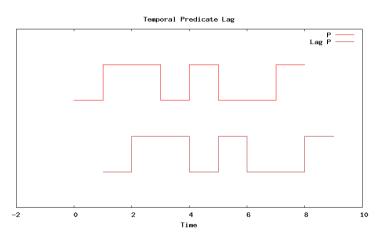


LagLink and LeadLink

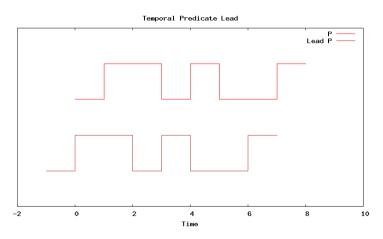
Lag: brings past into present

Lead: brings future into present

Lag: example



Lead: example



SequentialAnd

```
BackSequentialAnd <TV>
ForeSequentialAnd <TV>
                          \equiv
```

```
Lag
P
T
Q
And <TV>
P
Lead
Q
-
```

And <TV>

```
BackPredictiveImplication <TV>
ForePredictiveImplication <TV>
                          \equiv
```

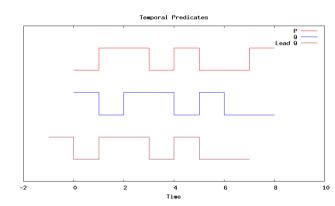
```
Implication <TV>
  Lag
Implication <TV>
  Р
  Lead
```

```
BackPredictiveImplication <TV>
   T
   P
   Q
```

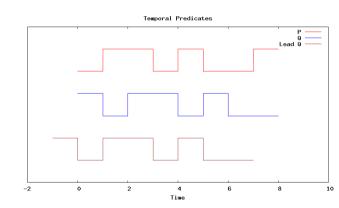
```
ForePredictiveImplication <TV> \frac{T}{P} \equiv 0
```

```
Implication <TV>
  Lag
Implication <TV>
  Р
  ForeSequentialAnd
```

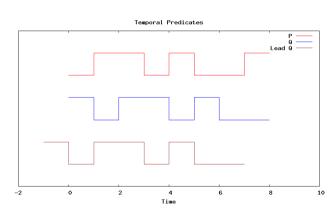
```
Implication \langle s=0.25 \rangle
P
Q
```



```
Implication \langle s=0.25 \rangle P Q Implication \langle s=0.75 \rangle P Lead Q 1
```



```
Implication \langle s=0.25 \rangle
Implication \langle s=0.75 \rangle
   Lead
PredictiveImplication \langle s=0.75 \rangle
```



• Implication P O

 \equiv

P o Q

• Implication

```
\stackrel{{
m P}}{\circ} \equiv P 	o Q
```

```
T
P
Q
```

$$P \rightsquigarrow^T Q$$

• Implication

• PredictiveImplication

• Lag

=

$$P \rightsquigarrow^T Q$$

$$\overrightarrow{P}^{ au}$$

• Implication

0

 \equiv

• PredictiveImplication

Τ

Р

≡

$$P \rightsquigarrow^T Q$$

Ç

Lag

Р

Τ

 \equiv

 \overrightarrow{P}^T

Lead

I

Т

 \equiv



Temporal Deduction

Temporal Deduction

$$\frac{P \to Q \quad Q \to R \quad P \quad Q \quad R}{P \to R} \text{ (Deduction)}$$

$$\frac{P \leadsto^{T_1} Q \quad Q \leadsto^{T_2} R \quad P \quad Q \quad R}{P \leadsto^{T_1 + T_2} R} \text{ (Temporal Deduction?)}$$

Temporal Deduction → Deduction

$$\frac{P \overset{T_1}{\longrightarrow} Q}{P \overset{T_1}{\longrightarrow} Q^{-1}} \text{ (PI2I)} \qquad \frac{Q \overset{T_2}{\longrightarrow} R}{Q \overset{T_1}{\longrightarrow} R^{T_1 + T_2}} \text{ (TS)} \qquad Q \qquad \frac{Q}{\overset{T_1}{\bigcirc} T_1 + T_2} \text{ (TS)} \qquad \frac{R}{\overset{T_1 + T_2}{\nearrow} T_1 + T_2} \text{ (Deduction)} \qquad \frac{P \overset{T_1}{\longrightarrow} R^{T_1 + T_2}}{P \overset{T_1 + T_2}{\longrightarrow} R} \text{ (I2PI)}$$

$$TS: Temporal Shift}$$

- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication



Procedural Reasoning (notations)

• SequentialAnd

P

Q

 \equiv

 $P \prec^{T} Q$

Procedural Reasoning (notations)

```
• SequentialAnd \begin{array}{c} T \\ P \\ Q \end{array} \equiv \begin{array}{c} P \prec^T Q \\ Q \end{array}
• Lambda \begin{array}{c} T \\ AtTime \\ Execution \\ A \end{array} \equiv \begin{array}{c} \widehat{A} \end{array}
```

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Cognitive Schematics

- Monoaction plan
- Diaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

$$\left((C \wedge \widehat{A_1}) \prec^{T_1} \widehat{A_2}\right) \leadsto^{T_1 + T_2} G$$

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Diaction plan

$$\left((C \wedge \widehat{A_1}) \prec^{T_1} \widehat{A_2} \right) \leadsto^{T_1 + T_2} G$$

Polyaction plan

$$\left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \prec^3 \mathit{StepOut}\right) \leadsto^6 \mathit{Outside}$$

18/22

Temporal Deduction for Procedural Reasoning

$$\frac{P \wedge \widehat{A} \rightsquigarrow^{T_1} Q}{P \wedge \widehat{A} \rightarrow \overleftarrow{\Omega}^{T_1}} \text{ (Pl2I)} \qquad \frac{\widehat{B}}{\overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B} \rightsquigarrow^{T_2} R}{Q \wedge \widehat{B} \rightarrow \overleftarrow{B}^{T_2}} \text{ (Pl2I)} \qquad Q \wedge \widehat{B} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (Pl2I)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (Pl2I)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{\Omega}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (D)}$$

- D: Deduction
- CI: Conjunction Introduction
- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication



Procedural Reasoning Example

$$\begin{array}{c} \left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \leadsto^3 \mathit{OpenDoorStep} \\ \\ \mathit{OpenDoorStep} \land \mathit{StepOut} \leadsto^1 \mathit{Outside} \\ \\ \vdash \\ \left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \prec^3 \mathit{StepOut}\right) \leadsto^6 \mathit{Outside} \end{array}$$

Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - ...



Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

Temporal Truth Value

Temporal and Procedural Reasoning: next steps

- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

Temporal Truth Value

Behavior Tree



Conclusion

Demo Time

