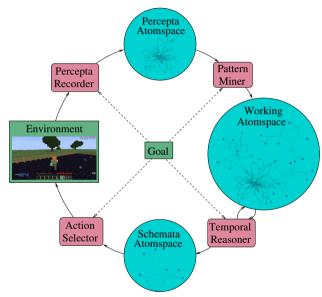
Rational OpenCog Controlled Agent

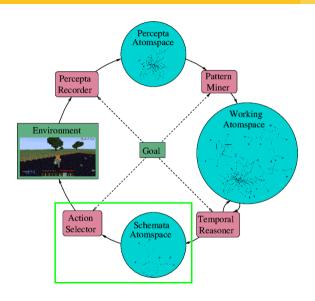
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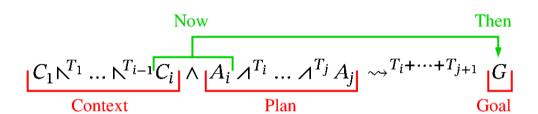


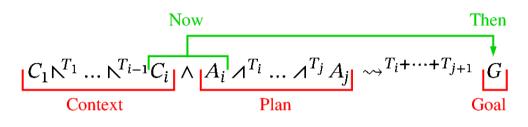


Cognitive Schematic

• Context \wedge Action \rightsquigarrow^T Goal

$$C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \wedge A_i \wedge^{T_i} \dots \wedge^{T_j} A_j \rightsquigarrow^{T_i + \dots + T_{j+1}} G$$





$$[C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i](t) = True \mid False$$

Now Then
$$C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \wedge A_i \wedge^{T_i} \dots \wedge^{T_j} A_j \rightsquigarrow^{T_i + \dots + T_{j+1}} G$$
Context Plan Goal

$$\begin{bmatrix} C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \end{bmatrix} (t) = \text{True} \mid \text{False} \\ \mapsto \mathcal{D}ist(Bool)$$

Now Then
$$C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \wedge A_i \wedge^{T_i} \dots \wedge^{T_j} A_j \rightsquigarrow^{T_i + \dots + T_{j+1}} G$$
Context Plan Goal

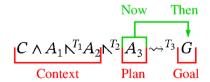
$$\begin{bmatrix} C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \end{bmatrix} (t) = True \mid False \\ \mapsto \mathcal{D}ist(Bool) \\ \mapsto \mathcal{D}ist(\mathcal{D}ist(Bool))$$



$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_1 + T_2 + T_3} G$$
Now Then
$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_2 + T_3} G$$
Context Plan Goal

$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_1+T_2+T_3} G$$

$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_2+T_3} G$$





Actions

- get(key)
- go(house)
- collect(diamond)

Percepts

- outside(house)
- inside(house)
- hold(key)
- next(door)
- reward(1)
- reward(0)

outside(house) \land get(key) \land ¹ go(house) \land ¹ collect(diamond) \rightsquigarrow ³ reward(1)

outside(house) \land get(key) \land ¹ go(house) \land ¹ collect(diamond) \leadsto ³ reward(1)

hold(key) \land go(house) \nearrow ¹ collect(diamond) \rightsquigarrow ² reward(1)

```
outside(house) \land get(key) \land<sup>1</sup> go(house) \land<sup>1</sup> collect(diamond) \leadsto<sup>3</sup> reward(1)
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 $hold(key) \land go(house) \land^1 collect(diamond) \leadsto^2 reward(1)$

inside(house) \land collect(diamond) \leadsto^1 reward(1)

Learning schemata

Balancing exploitation and exploration



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