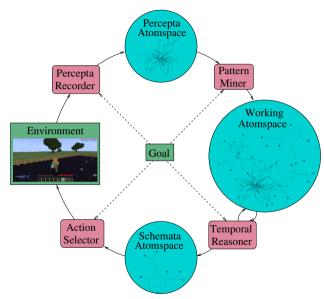
Rational OpenCog Controlled Agent

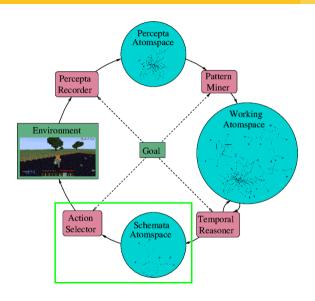
Nil Geisweiller, Hedra Yusuf

Artificial General Intelligence 2023 (AGI-23)





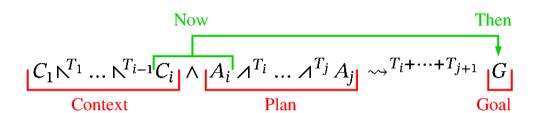


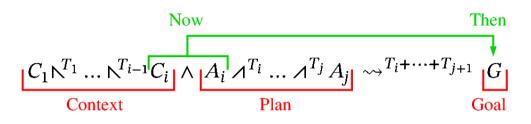


Cognitive Schematic

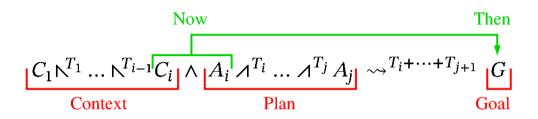
• Context \wedge Action \rightsquigarrow^T Goal

$$C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \wedge A_i \wedge^{T_i} \dots \wedge^{T_j} A_j \rightsquigarrow^{T_i + \dots + T_{j+1}} G$$

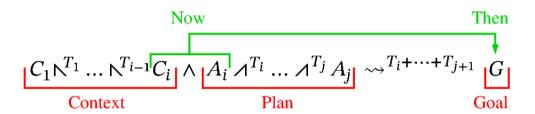




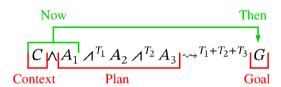
$$[C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i](t) = True \mid False$$



$$\begin{bmatrix} C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \end{bmatrix} (t) = \text{True} \mid \text{False} \\ \mapsto \mathcal{D}ist(Bool)$$



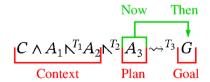
$$\begin{bmatrix} C_1 \wedge^{T_1} \dots \wedge^{T_{i-1}} C_i \end{bmatrix} (t) = True \mid False \\ \mapsto \mathcal{D}ist(Bool) \\ \mapsto \mathcal{D}ist(\mathcal{D}ist(Bool))$$



$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_1+T_2+T_3} G$$
Now Then
$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_2+T_3} G$$
Context Plan Goal

$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_1+T_2+T_3} G$$

$$C \wedge A_1 \wedge^{T_1} A_2 \wedge^{T_2} A_3 \rightsquigarrow^{T_2+T_3} G$$





Actions

- get(key)
- go(house)
- collect(diamond)

Percepts

- outside(house)
- inside(house)
- hold(key)
- next(door)
- reward(1)
- reward(0)



 $outside(house) \land get(key) \mathbin{{\scriptstyle \nearrow}}^1 go(house) \mathbin{{\scriptstyle \nearrow}}^1 collect(diamond) \mathbin{{\scriptstyle \longleftrightarrow}}^3 reward(1)$



outside(house) \land get(key) \land^1 go(house) \land^1 collect(diamond) \rightsquigarrow^3 reward(1)



outside(house) \land get(key) \nearrow^1 go(house) \nearrow^1 collect(diamond) \rightsquigarrow^3 reward(1) hold(key) \land go(house) \nearrow^1 collect(diamond) \rightsquigarrow^2 reward(1)



outside(house) \land get(key) \nearrow^1 go(house) \nearrow^1 collect(diamond) \rightsquigarrow^3 reward(1) hold(key) \land go(house) \nearrow^1 collect(diamond) \rightsquigarrow^2 reward(1)





7/13

outside(house) \land get(key) \land^1 go(house) \land^1 collect(diamond) \leadsto^3 reward(1)

hold(key) \land go(house) \land ¹ collect(diamond) \leadsto ² reward(1)

inside(house) ∧ collect(diamond) → 1 reward(1)



outside(house) \land get(key) \nearrow^1 go(house) \nearrow^1 collect(diamond) \rightsquigarrow^3 reward(1)

hold(key) \land go(house) \land ¹ collect(diamond) \leadsto ² reward(1)

inside(house) ∧ collect(diamond) → 1 reward(1)



The Paradox of Choice

Many applicable schemata

$$\begin{array}{cccc} C_1 \wedge A_1 \rightsquigarrow^{T_1} G & \stackrel{\text{\tiny m}}{=} & TV_1 \\ & \vdots & & & \\ C_{9999} \wedge A_{9999} \rightsquigarrow^{T_{9999}} G & \stackrel{\text{\tiny m}}{=} & TV_{9999} \end{array}$$

The Paradox of Choice

Many applicable schemata

$$\begin{array}{cccc} C_1 \wedge A_1 \rightsquigarrow^{T_1} G & \stackrel{\mathbb{m}}{=} & TV_1 \\ \vdots & & & \\ C_{9999} \wedge A_{9999} \rightsquigarrow^{T_{9999}} G & \stackrel{\mathbb{m}}{=} & TV_{9999} \end{array}$$

Some contradicting each other

$$C_1 \wedge A \rightsquigarrow^{T_1} G \stackrel{\text{m}}{=} <0.9 \ 0.5>$$

 $C_2 \wedge A \rightsquigarrow^{T_1} G \stackrel{\text{m}}{=} <0.1 \ 0.5>$

8/13

The Paradox of Choice

Many applicable schemata

$$\begin{array}{cccc} C_1 \wedge A_1 \rightsquigarrow^{T_1} G & \stackrel{\mathbb{m}}{=} & TV_1 \\ \vdots & & & \\ C_{9999} \wedge A_{9999} \rightsquigarrow^{T_{9999}} G & \stackrel{\mathbb{m}}{=} & TV_{9999} \end{array}$$

Some contradicting each other

$$C_1 \wedge A \rightsquigarrow^{T_1} G \stackrel{\text{m}}{=} <0.9 \ 0.5>$$

 $C_2 \wedge A \rightsquigarrow^{T_1} G \stackrel{\text{m}}{=} <0.1 \ 0.5>$

With different risk/reward profiles

$$C_1 \wedge A_1 \leadsto^{T_1} G \stackrel{\underline{m}}{=} <0.9 \ 0.1>$$

 $C_2 \wedge A_2 \leadsto^{T_2} G \stackrel{\underline{m}}{=} <0.6 \ 0.9>$



Balancing exploitation and exploration

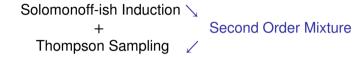
Solomonoff-ish Induction
+
Thompson Sampling

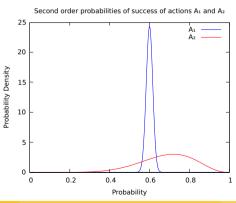


Balancing exploitation and exploration

Solomonoff-ish Induction \
+ Second Order Mixture
Thompson Sampling

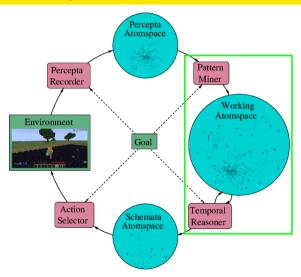
Balancing exploitation and exploration







Learning Schemata



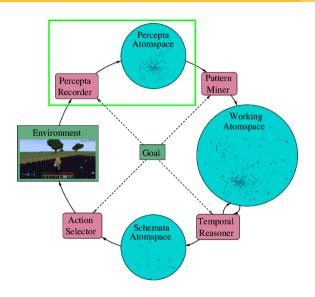
Pattern Mining
+
Temporal Reasoning

Pattern Mining Schemata



Reasoning Schemata





Events
Timestamped
Recorded