Temporal and Procedural Reasoning with OpenCog

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SingularityNET & OpenCog Foundations







Why Temporal Reasoning?

- Lag between cause and effect
- Learn and operate in the world
- Meta-reasoning: Think about think about



PLN Recall

$$\texttt{P},\,\texttt{Q},\,\ldots \colon \textit{Atom}^{\textit{n}} \to \{\textit{True},\textit{False}\} \ {}_{\texttt{(possibly fuzzy)}}$$

And <TV>

$$\begin{array}{ccc} P & & \equiv & \\ Q & & & \equiv \\ \\ \text{Not } & & \equiv \\ \\ P & & & \equiv \\ \\ Q & & \equiv \\ \end{array}$$

$$\mathcal{P}(P,Q) \approx TV.$$
strength

$$\mathcal{P}(P) \approx 1 - TV.$$
strength

$$\mathcal{P}(\textit{Q}|\textit{P}) \approx \textit{TV.strength}$$

PLN rules: Implication Direct Introduction

```
Evaluation
  Εi
Evaluation
  Εi
Implication <TV>
```

$$TV.strength = \frac{\sum_{x} f_{\land}(P(x).strength, Q(x).strength)}{\sum_{x} P(x).strength}$$

PLN rules: Deduction

```
P
Q
Implication
Q
R
|-
Implication <TV>
P
R
```

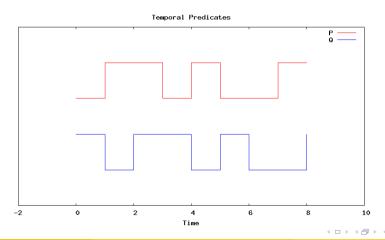
Implication

$$TV.strength = \mathcal{P}(R|Q,P) \times \mathcal{P}(Q|P) + \mathcal{P}(R|\neg Q,P) \times \mathcal{P}(\neg Q|P)$$



Temporal Predicate

$$extstyle extstyle ext$$



LagLink and LeadLink

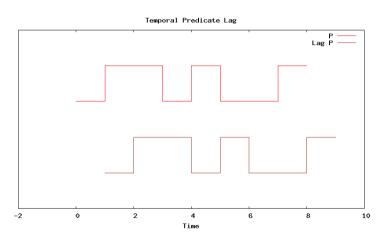
Lag: brings past into present

LagLink LambdaLink

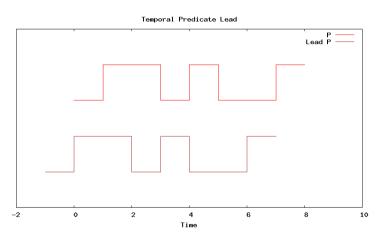
P x, tT $\equiv P(x, t-T)$

Lead: brings future into present

Lag: example



Lead: example



SequentialAnd

```
BackSequentialAnd <TV>
ForeSequentialAnd <TV>
                          \equiv
```

And <TV>
Lag
P
T
Q

And <TV>

P Lead

```
BackPredictiveImplication <TV>
ForePredictiveImplication <TV>
                          \equiv
```

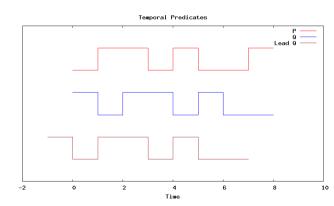
```
Implication <TV>
  Lag
Implication <TV>
  Р
  Lead
```

```
BackPredictiveImplication <TV>
   T
   P
   Q
```

```
Implication <TV>
Lag
P
T
```

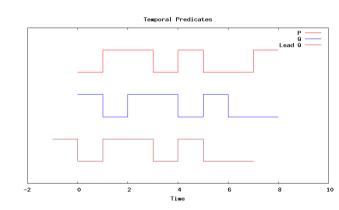
```
Implication <TV>
  P
  ForeSequentialAnd
  T
  P
  O
```

```
Implication \langle s=0.25 \rangle P Q
```

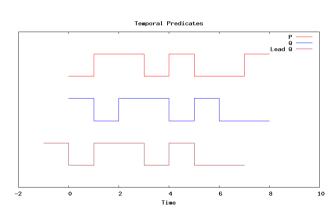


```
Implication <s=0.25>
  P
  Q

Implication <s=0.75>
  P
  Lead
  Q
  1
```



```
Implication \langle s=0.25 \rangle
Implication \langle s=0.75 \rangle
   Lead
PredictiveImplication \langle s=0.75 \rangle
```



• Implication P

 \equiv

P o Q

• Implication

```
\stackrel{	ext{P}}{\circ} \equiv P 	o Q
```

```
\begin{array}{ccc} T & & & & & \\ P & & & & & \\ Q & & & & \end{array}
```

$$P \leadsto^T Q$$

• Implication

 \equiv

$$\equiv$$

$$\equiv$$

$$\overrightarrow{P}^7$$

 $P \leadsto^T Q$

 $P \rightarrow Q$



14/22

```
• Implication
```

0

≡

• PredictiveImplication

D

 \equiv

 $P \rightsquigarrow^T Q$

Q

• Lag

Р

Т

≡

 \overrightarrow{P}^T

Lead

.

Т

 \equiv

 \overleftarrow{P}^T

Temporal Deduction

$$egin{array}{c|cccc} P
ightarrow Q & Q
ightarrow R & P & Q & R \\ \hline P
ightarrow R & & & & & & & & & & \end{array}$$
 (Deduction)

Temporal Deduction

$$\frac{P \to Q \quad Q \to R \quad P \quad Q \quad R}{P \to R} \text{ (Deduction)}$$

$$\frac{P \leadsto^{T_1} Q \quad Q \leadsto^{T_2} R \quad P \quad Q \quad R}{P \leadsto^{T_1 + T_2} R} \text{ (Temporal Deduction?)}$$

Temporal Deduction → Deduction

$$\frac{P \overset{T_1}{\longrightarrow} Q}{P \overset{T_1}{\longrightarrow} Q^{-1}} \text{ (PI2I)} \qquad \frac{Q \overset{T_2}{\longrightarrow} R}{Q \overset{T_1}{\longrightarrow} R^{T_1}} \text{ (PI2I)} \qquad Q \overset{Q}{\longrightarrow} Q \text{ (TS)} \qquad \frac{R}{\overleftarrow{R}^{T_1 + T_2}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{R}^{T_1 + T_2}} \text{ (Deduction)} \qquad \frac{P \overset{T_1}{\longrightarrow} R}{P \overset{T_1 + T_2}{\longrightarrow} R} \text{ (I2PI)}$$

$$\uparrow TS: \text{ Temporal Shift}$$

- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication

Procedural Reasoning (notations)

• SequentialAnd

P

 \equiv

 $P \prec^{T} Q$

Procedural Reasoning (notations)

```
• SequentialAnd
                                                      P \prec^T Q
                                 \equiv
• Lambda
     AtTime
       Execution
          Α
```

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^{\mathcal{T}} G$$

Diaction plan

$$\left((\mathit{C} \wedge \widehat{\mathit{A}_{1}}) \prec^{\mathit{T}_{1}} \widehat{\mathit{A}_{2}}\right) \leadsto^{\mathit{T}_{1} + \mathit{T}_{2}} \mathit{G}$$

Cognitive Schematics

Monoaction plan

$$C \wedge \widehat{A} \leadsto^T G$$

Diaction plan

$$\left((C \wedge \widehat{A_1}) \prec^{T_1} \widehat{A_2} \right) \leadsto^{T_1 + T_2} G$$

Polyaction plan

$$\left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \prec^3 \mathit{StepOut}\right) \leadsto^6 \mathit{Outside}$$



Temporal Deduction for Procedural Reasoning

$$\frac{P \wedge \widehat{A} \rightsquigarrow^{T_1} Q}{P \wedge \widehat{A} \rightarrow \overleftarrow{O}^{T_1}} \text{ (Pl2l)} \qquad \frac{\widehat{B}}{\overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B} \rightsquigarrow^{T_2} R}{Q \wedge \widehat{B} \rightarrow \overleftarrow{B}^{T_2}} \text{ (Pl2l)} \qquad Q \wedge \widehat{B} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{O}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{Q \wedge \widehat{B}}{\overleftarrow{O}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{O}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (TS)} \qquad \frac{R}{\overleftarrow{B}^{T_1+T_2}} \text{ (TS)} \qquad \frac{P \wedge \widehat{A} \wedge \overleftarrow{B}^{T_1}}{\overleftarrow{O}^{T_1} \wedge \overleftarrow{B}^{T_1}} \text{ (Pl2l)} \qquad (D)$$

- D: Deduction
- CI: Conjunction Introduction
- TS: Temporal Shift
- PI2I: PredictiveImplication to Implication
- I2PI: Implication to PredictiveImplication



Procedural Reasoning Example

$$\begin{array}{c} \left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \rightsquigarrow^3 \mathit{OpenDoorStep} \\ \\ \mathit{OpenDoorStep} \land \mathit{StepOut} \rightsquigarrow^1 \mathit{Outside} \\ \\ \vdash \\ \left(\left(\left(\mathit{Inside} \land \mathit{WalkToDoor}\right) \prec^2 \mathit{OpenDoor}\right) \prec^3 \mathit{StepOut}\right) \rightsquigarrow^6 \mathit{Outside} \end{array}$$

- More rules
 - Temporal Abduction
 - ...

- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

Temporal Truth Value



- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

Temporal Truth Value

Behavior Tree

$$(((Inside \land WalkToDoor) \prec (Locked ? SmashDoor : OpenDoor)) \prec StepOut) \leadsto Outside$$



- More rules
 - Temporal Abduction
 - ...
- Distributional Time
 - Temporal Interval

$$(((\textit{Inside} \land \textit{WalkToDoor}) \prec^{[1,2]} \widehat{\textit{OpenDoor}}) \prec^{[1.5,3]} \widehat{\textit{StepOut}}) \leadsto^{[1.6,4]} \textit{Outside}$$

• Temporal Truth Value

$$(((Inside \land WalkToDoor) \prec OpenDoor) \prec StepOut) \leadsto Outside$$

Behavior Tree

• Dependent Truth Value (or Density Truth Value)



Conclusion

Demo Time

