

# Chapter 6: Synchronous Sequential Circuits

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# Synchronous sequential circuit

- Combinational logic circuits: The outputs are determined fully by the present values of inputs
- Flip-flop: The output depends on the state of the flip-flop rather than the value of its inputs at any given time; the inputs cause changes in the state
- Sequential circuit: The outputs depend on the past behavior of the circuit, as well as on the present values of inputs
- Synchronous sequential circuit: clock signal is used to control the operation of a sequential circuit
- The alternative, in which no clock signal is used, is called an asynchronous sequential circuit

# Synchronous sequential circuit

- A sequential circuit is a circuit with memory, which forms the internal state of the circuit.
- Unlike a combinational circuit, in which the output is a function of input only, the output of a sequential circuit is a function of the input and the internal state. The synchronous design methodology is the most commonly used practice in designing a sequential circuit. In this methodology, all storage elements are controlled (i.e., synchronized) by a global clock signal and the data is sampled and stored at the rising or falling edge of the clock signal

# Review of Verilog assignment and procedure

# Continuous Assignments

## review

- Continuously assigns right side of expression to left side.
- Limited to basic Boolean and ? operators. For example a 2:1 mux:
  - ? operator  
**assign D = (A==1) ? B : C; // if A then D = B else D = C;**
  - Boolean operators  
**assign D = (B & A) | (C & ~A); // if A then D = B else D = C;**

# Procedural Assignments

- Executes a procedure allowing for more powerful constructs such as if-then-else and case statement.
- For example 2:1 mux:
  - if-else  
if (A) D = B else D = C;
  - case  
case(A)  
1'b1 : D = B;  
1'b0 : D = C;  
endcase

This is obviously much easier to implement and read than Boolean expressions!!

# Always Block

- An always block is an example of a procedure.
- The procedure executes a set of assignments when a defined set of inputs **change**.


# 2:1 mux Always Block

```
Module mux_2_1(a, b, out, sel);  
    input a, b, sel;  
    output out;
```

```
    reg out;  
    always @(a or b or sel)  
    begin  
        if (sel) out = a;  
        else out = b;  
    end
```

```
endmodule
```

```
    wire out;  
    assign out =(sel==1)?a:b;
```



Declare Module and IO as before.

All data types in always blocks must be declared as a 'reg' type.

This is required even if the data type is for combinational logic.

The always block 'executes' whenever signals named in the sensitivity list change.

Literally: always execute at a or b or sel.

Sensitivity list should include conditional (sel) and right side (a, b) assignment variables.



# As Easier Way to Implement the Sensitivity List

- Recent versions of Verilog provides a means to implement the sensitivity list without explicitly listing each potential variable.
- Instead of listing variables as in the previous example

always @ (a or b or sel)

Simply use

always @\*

The \* operator will automatically identify all sensitive variables.

# Blocking vs Non-Blocking Assignments

- Blocking (=) and non-blocking (<=) assignments are provided to control the execution order within an always block.
- Blocking assignments **literally block** the execution of the next statement until the current statement is executed.
  - **Consequently, blocking assignments result in ordered statement execution.**

For example:

```
assume a = b = 0 initially;  
a = 1;    //executed first  
b = a;    //executed second  
then a = 1, b = 1 after ordered execution
```

# Blocking vs Non-Blocking Cont

- Non-blocking assignments **literally do not block** the execution of the next statements. The right side of all statements are determined first, then the left sides are assigned together.
  - **Consequently, non-blocking assignments result in simultaneous or parallel statement execution.**

For example:

assume  $a = b = 0$  initially;

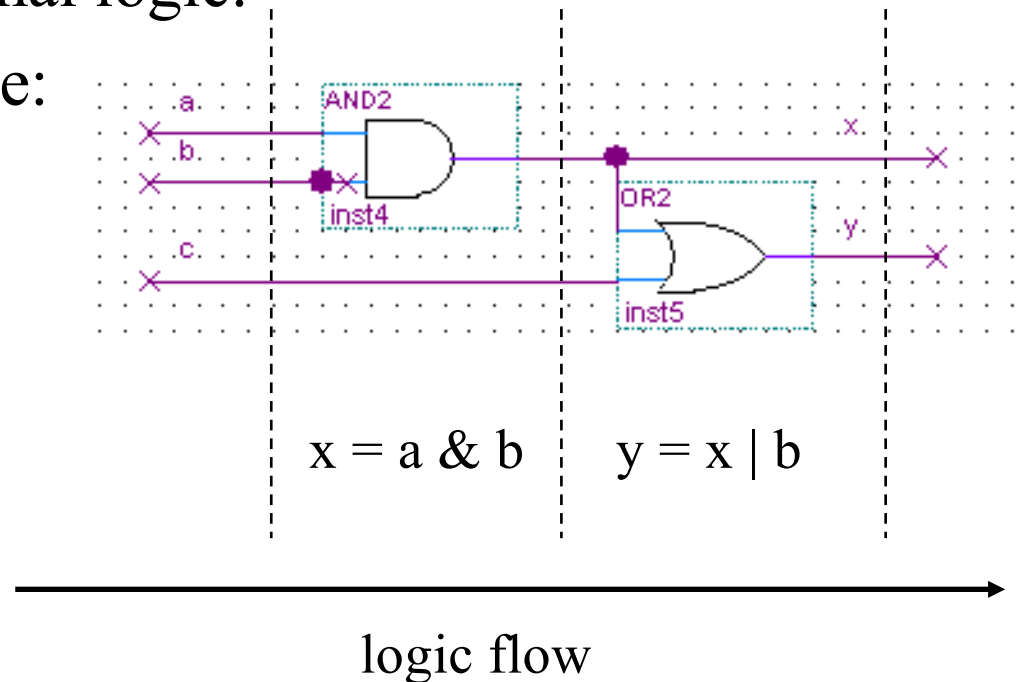
$\left. \begin{array}{l} a \leq 1; \\ b \leq a; \end{array} \right\}$  Execute together (in parallel)

then  $a = 1, b = 0$  after parallel execution

Result is different from ordered exec!!! Does not preserve logic flow

# To Block or Not to Block ?

- Ordered execution mimics the inherent logic flow of combinational logic.
- Hence blocking assignments generally work better for combinational logic.
- For example:



# To Block or Not to Block ? cont

Module blocking(a,b,c,x,y);

input a,b,c;

output x,y;

reg x,y;

always @\*

begin

x = a & b;

y = x | c;

end

endmodule

Blocking behavior	a	b	c	x	y
Initial values	1	1	0	1	1
a changes → always block execs	0	1	0	1	1
x = a & b; //make assignment	0	1	0	0	1
y = x   c; //make assignment	0	1	0	0	0

Module nonblocking(a,b,c,x,y);

input a,b,c;

output x,y;

reg x,y;

always @\*

begin

x <= a & b;

y <= x | c;

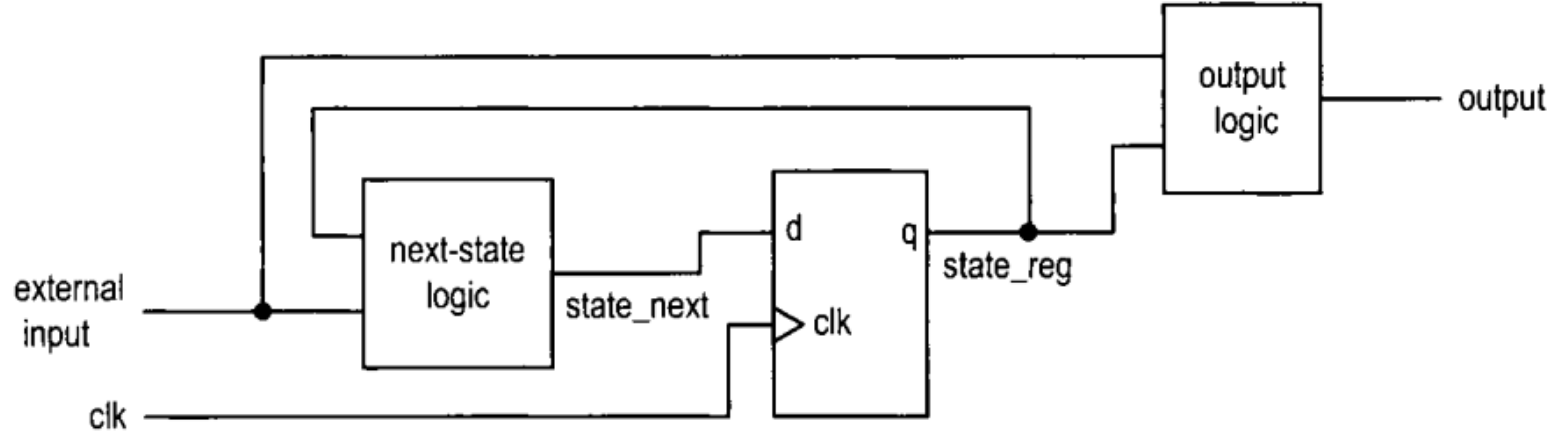
end

endmodule

Non-blocking behavior	a	b	c	x	y
Initial values	1	1	0	1	1
a changes → always block execs	0	1	0	1	1
x = a & b;	0	1	0	1	1
y = x   c; //x not passed from here	0	1	0	1	1
make x, y assignments	0	1	0	0	1

non-blocking behavior does not preserve logic flow!!

# Synchronous sequential circuit



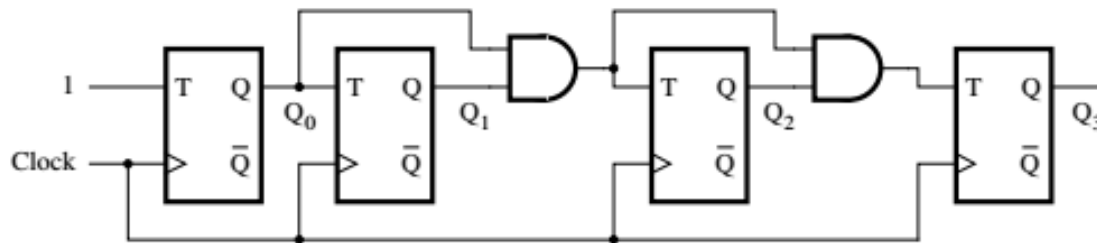
**Figure 4.2** Block diagram of a synchronous system.

***State register:*** a collection of D FFs controlled by the same clock signal

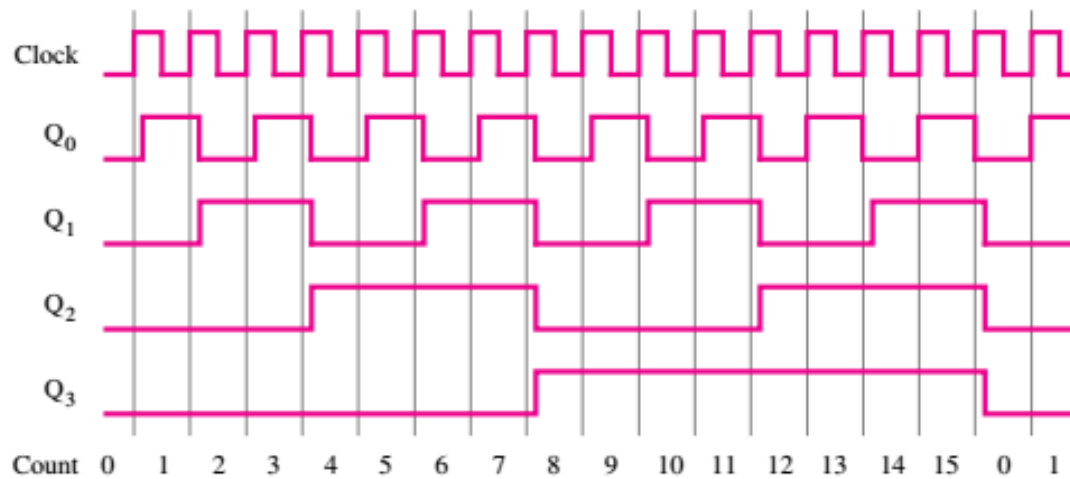
**Next-state logic:** combinational logic that uses the external input and internal state (i.e., the output of register) to determine the new value of the register

**Output logic:** combinational logic that generates the output signal

# Design of synchronous counter



(a) Circuit



(b) Timing diagram

**Figure 5.21** A four-bit synchronous up-counter.

# Design of synchronous counter

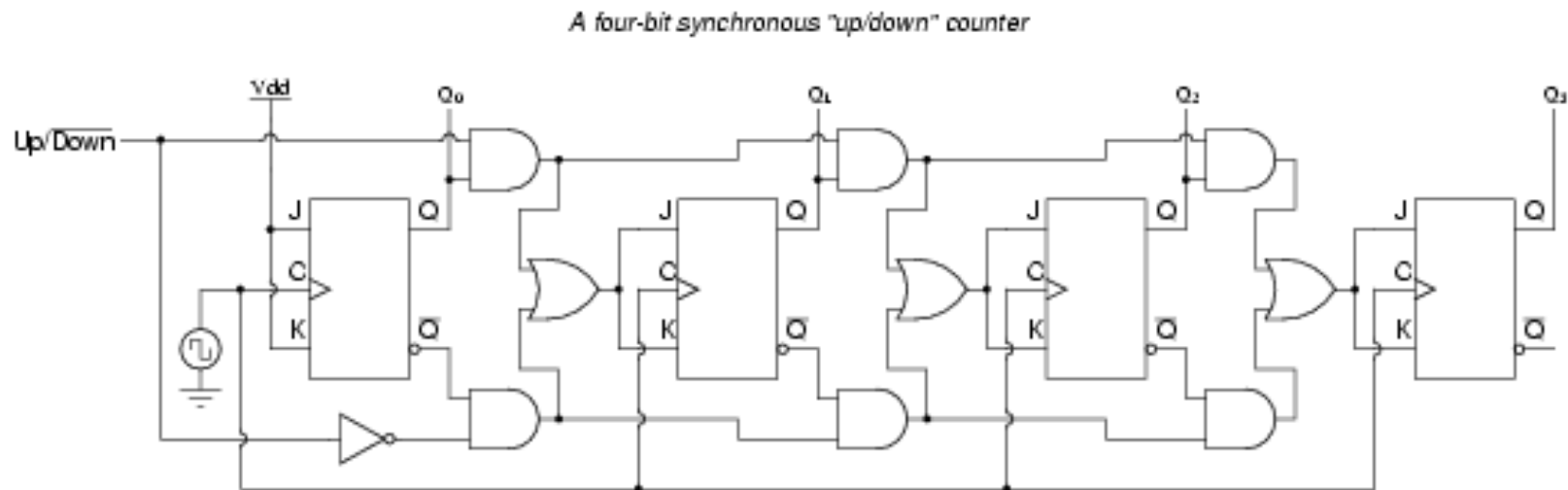
- Sample code

```
module Counter
  #(parameter N= 8)
    ( input wire clk, reset,
      output wire      [N-1:0] q );
    // signal declaration
    reg [N-1:0] r_reg;
    wire [N-1:0] r_next;
    // body, register
    always @(posedge clk, posedge reset)
      if (reset)
        r_reg <= 0;
      else
        r_reg<=r_next; // <= is non-blocking statement
    // next state logic
    assign r_next = r_reg + 1;
    // output logic
    assign q=r_reg;
endmodule
```



# Up/ down counter

- Design 8-bit synchronous up/down counter

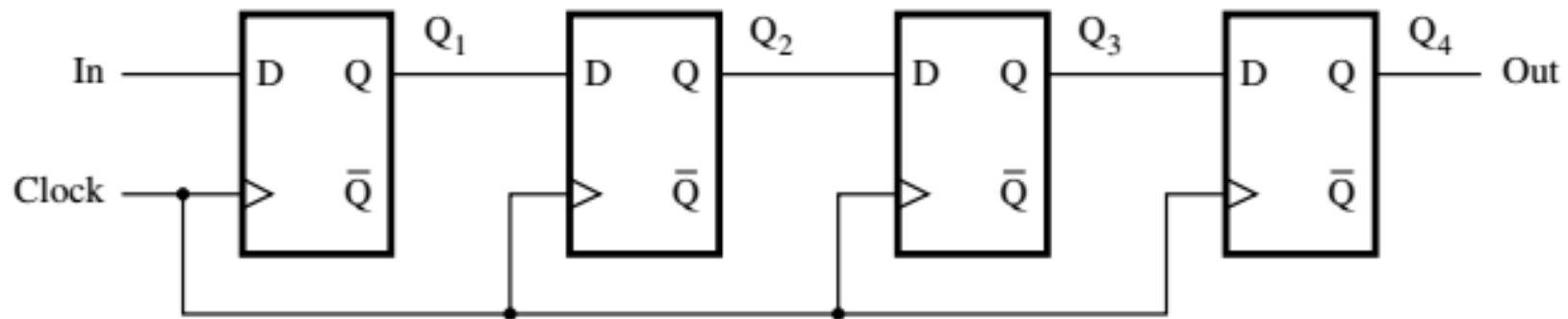


# 8-bit up/down counter

```
module CounterUD  
  (input wire clk,reset,ud,  
   output wire [7:0] q );  
  // signal declaration  
  reg [7:0] r_reg;  
  wire [7:0] r_next;  
  // body, register  
  always @(posedge clk, posedge reset)  
    if (reset)  
      r_reg<=0;  
    else  
      r_reg<=r_next;  
  // next state logic  
  assign r_next = (ud==1)?r_reg + 1:r_reg - 1;  
  // output logic  
  assign q=r_reg;  
endmodule
```

# Register

- A register is a collection of D FFs that are controlled by the same clock and reset signals
- Serial In – Serial Out (SISO) shift register. The block diagram of 4-bit SISO shift register is shown in the following figure.



# Register

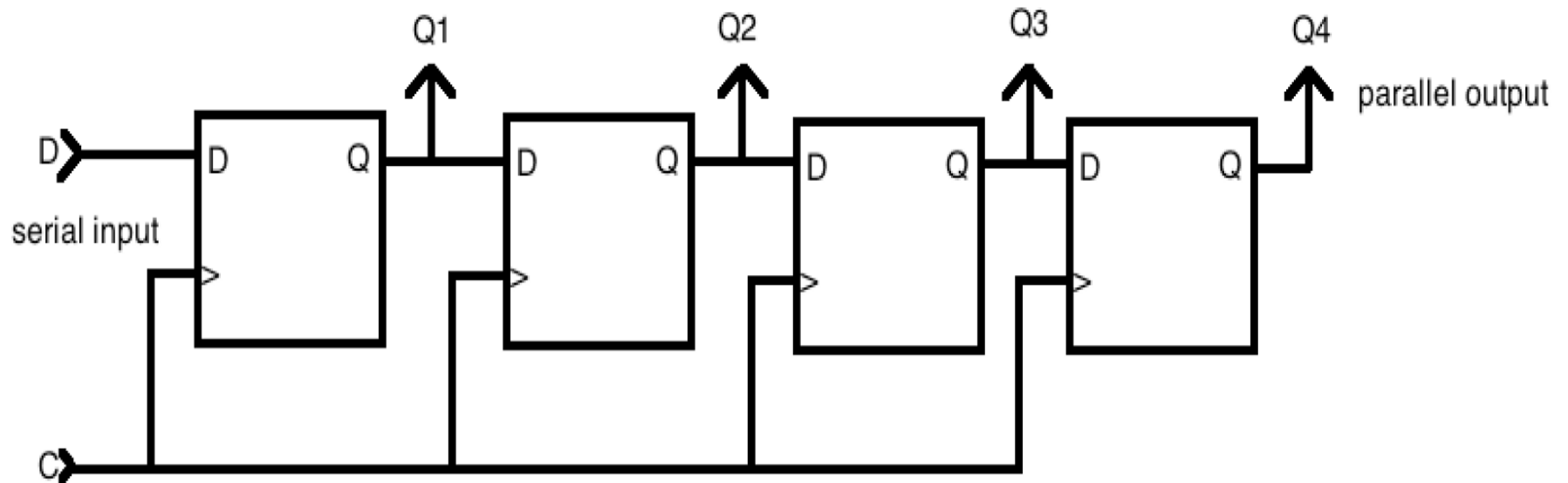
- Sample code

```
module Shift_SISO

#(parameter N= 4) // 500,000,000 for 0.1Hz
  ( input wire clk,reset,s_in,
    output wire      s_out
  );
    // signal declaration

    reg [N-1:0] r_reg;
    wire [N-1:0] r_next;
    // body, register
    always @(posedge clk, posedge reset)
    r_reg<=r_next;
    // next state logic
    assign r_next = {s_in,r_reg[N-1: 1]};
    // output logic
    assign s_out= r_reg[0];
endmodule
```

# Serial input – parallel output shift register

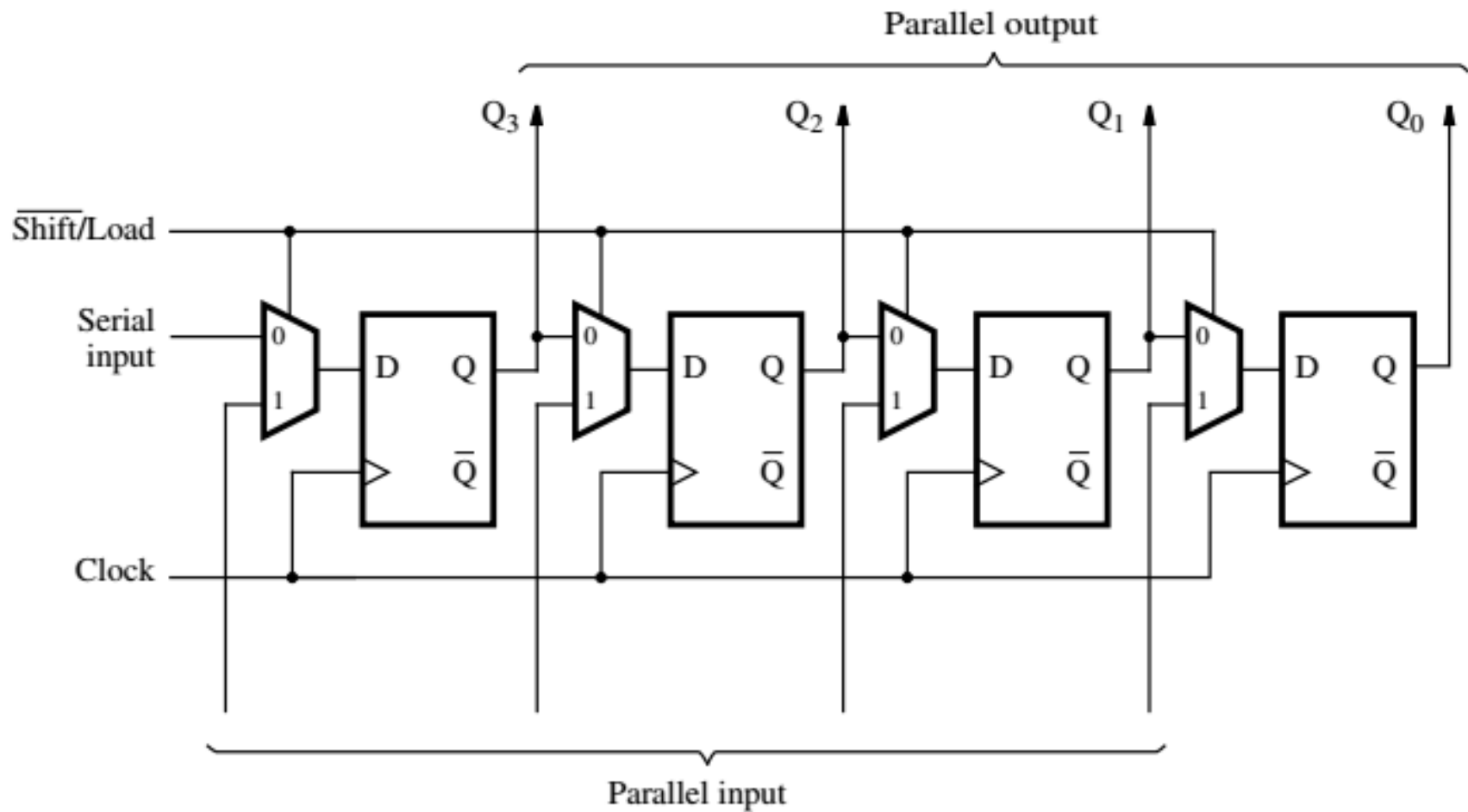


# Register

- Sample code

```
module Shift_SIPO
(
    input wire clk,s_in,
    output wire      [7:0] q_out );
// signal declaration
reg [7:0] r_reg;
wire [7:0] r_next;
// body, register
always@(negedge clk)
    r_reg<=r_next;
// next state logic
assign r_next = {s_in,r_reg[7:1]};
// output logic
assign q_out= r_reg;
```

# Serial input – parallel output shift register

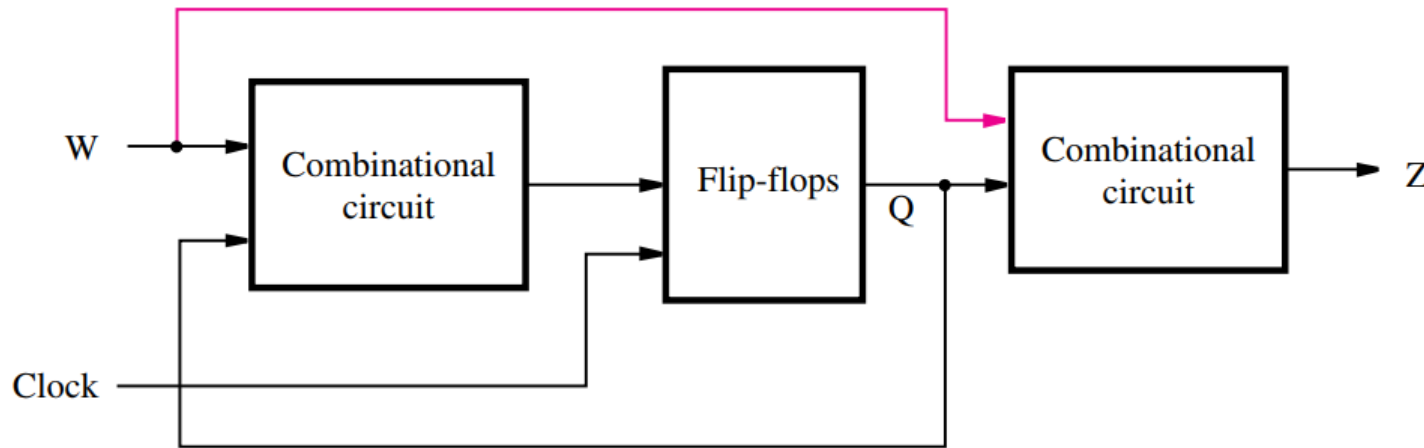






# Synchronous sequential circuit

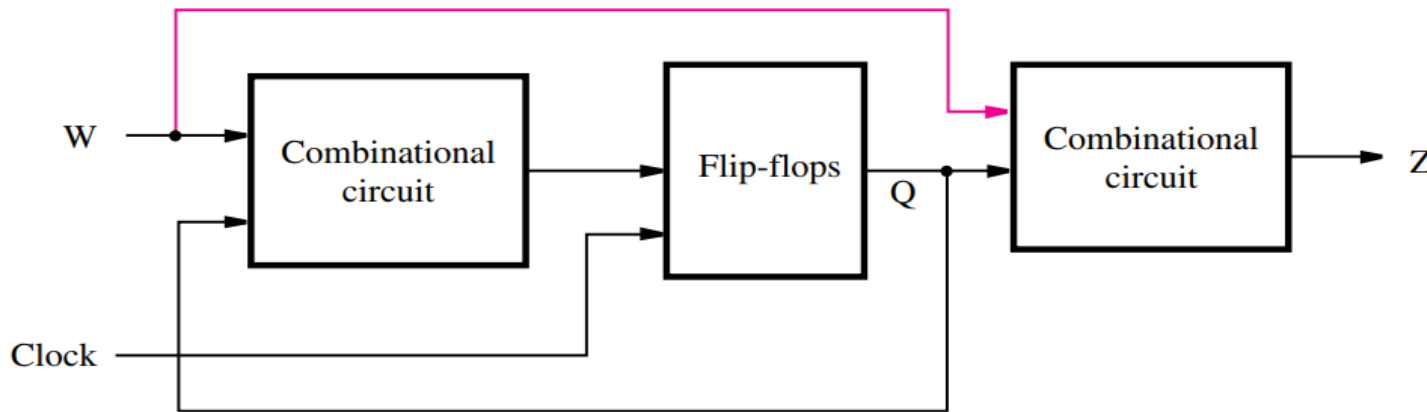
## Finite state machine (FSM)



**Figure 6.1** The general form of a sequential circuit.

- Synchronous sequential circuits are realized using combinational logic and one or more flip-flops.
- The circuit has a set of primary inputs,  $W$ , and produces a set of outputs,  $Z$ . The stored values in the flip-flops are referred to as the state,  $Q$ , of the circuit
- Under control of the clock signal, the flip-flops change their state as determined by the combinational logic that feeds the inputs of these flip-flops. the circuit moves from one state to another

# Moore and Mealy type of FSM

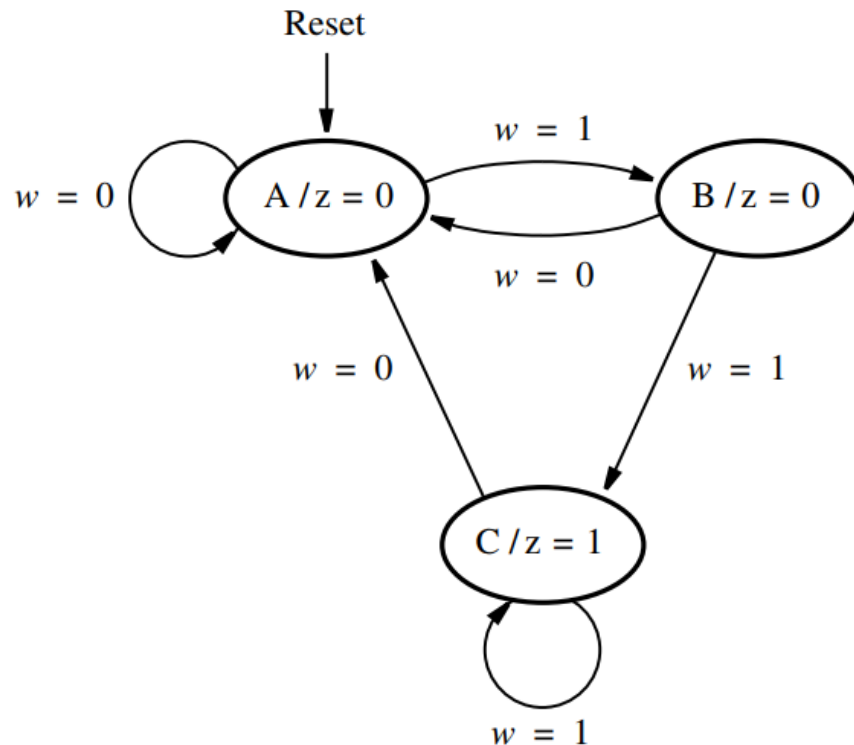


**Figure 6.1** The general form of a sequential circuit.

- Mealy type: The outputs are a function of the present state of the flip-flops and of the primary inputs
- Moore type: The outputs always depend on the present state, they do not necessarily have to depend directly on the primary inputs
- that sequential circuits whose outputs depend only on the state of the circuit are of **Moore** type, while those whose outputs depend on both the state and the primary inputs are of **Mealy** type
- Sequential circuits are also called <sup>24</sup> finite state machines (FSMs)

# State Machine

- The first step in designing a finite state machine is to determine how many states are needed and which transitions are possible from one state to another



**Figure 6.3** State diagram of a simple sequential circuit.

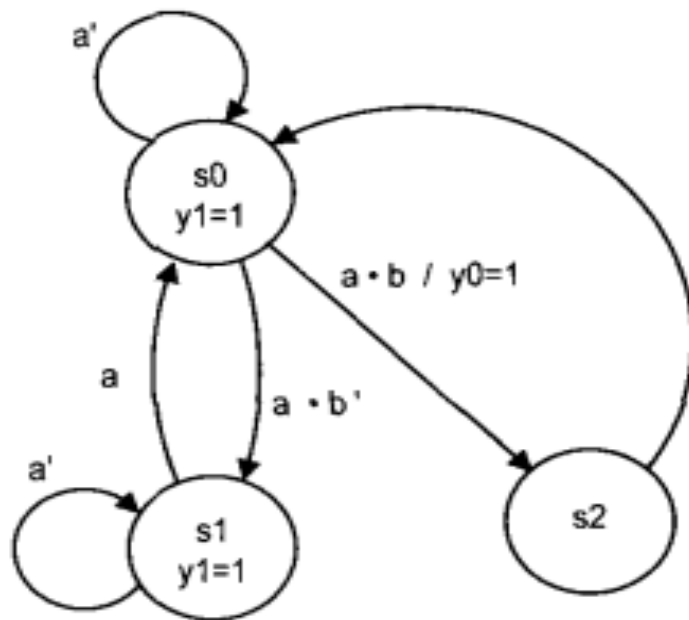
Present state	Next state		Output $z$
	$w = 0$	$w = 1$	
A	A	B	0
B	A	C	0
C	A	C	1

**Figure 6.4** State table corresponding to Figure 6.3.

# State Machine

```
module simple (Clock, Resetn, w, z);  
input Clock, Resetn, w; output z;  
reg [2:1] y, Y;  
parameter [2:1] A = 2'b00, B = 2'b01, C = 2'b10;  
// Define the next state combinational circuit  
always @(w, y)  
case (y)  
A: if (w) Y = B;  
else Y = A;  
B: if (w) Y = C;  
else Y = A;  
C: if (w) Y = C;  
else Y = A;  
default: Y = 2'bxx;  
endcase  
// Define the sequential block  
always @(negedge Resetn, posedge Clock)  
if (Resetn == 0) y <= A;  
else y <= Y;  
// Define output  
assign z = (y == C);  
Endmodule
```

# FSM

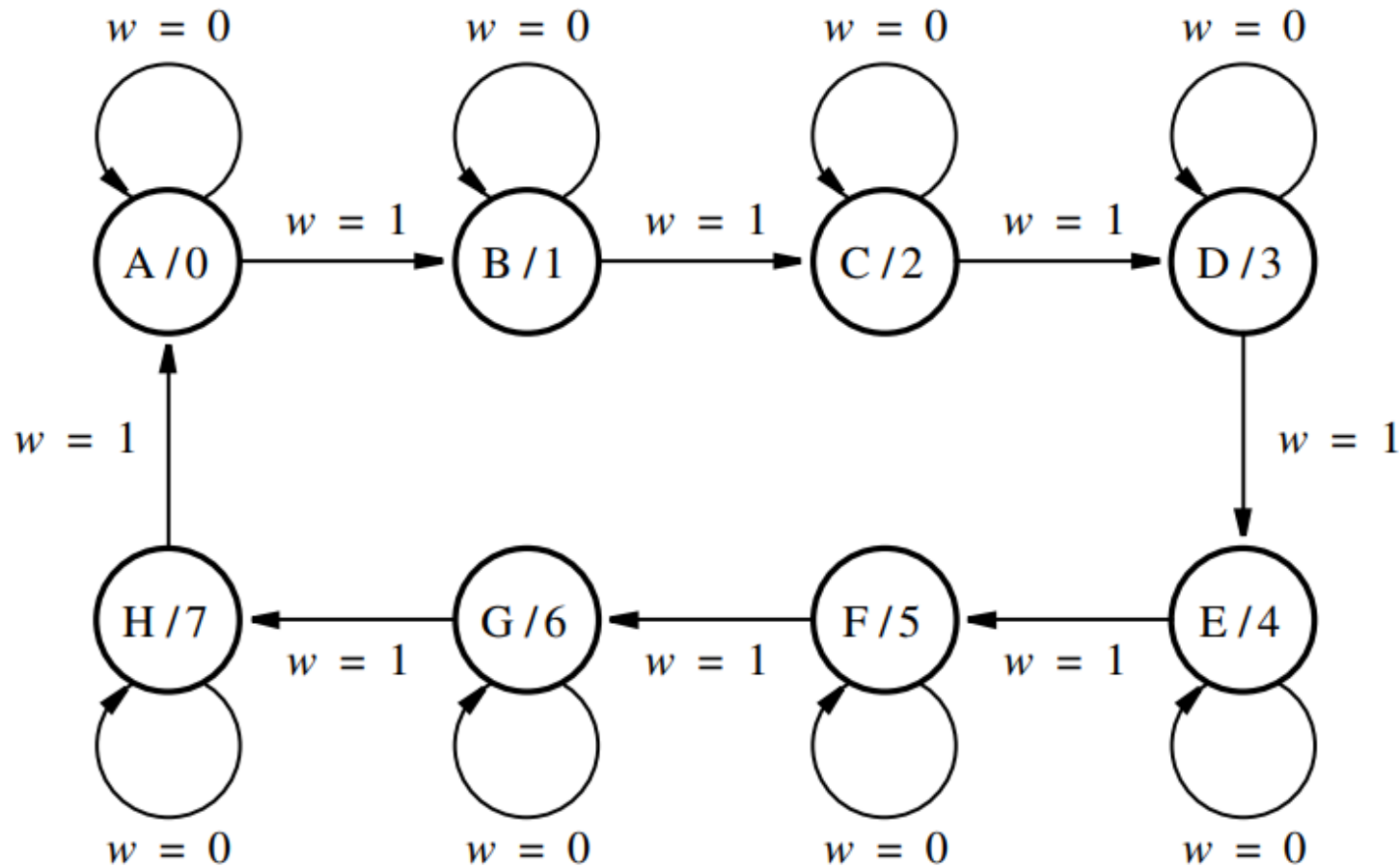


# FSM

```
module fsm-eg-mult-seg
(
input wire clk, reset,
input wire a, b,
output wire y0, y1 );
//symbolic state declaration
localparam [1:0] S0 = 2'b00; S1 = 2'b01,
S2=2'b10;
// signal declaration
reg [1 : 0] state_reg,state_next ;
    // state register
always @(posedge clk,posedge reset)
if(reset)
state_reg<=S0;
else
state_reg<=state_next;
//next_state logic
always @*
case (state_reg)
```

```
    S0: if(a)
        if(b)
            state_next=S2;
        else
            state_next=S1;
    else
        state_next=S0;
    S1: if(a)
        state_next=S0;
    else
        state_next=S1;
    S2: state_next=S0;
default: state_next=S0;
endcase
//Moore outputlogic
assign y1=(state_reg==S0)||(state_reg==S1);
//Mealy outputlogic
assign y0=(state_reg==S0)&a&b;
endmodule
```

# Design of Counter Using Sequential Circuit



**Figure 6.60** State diagram for the counter.

# Design of Counter Using Sequential Circuit

Present state	Next state		Output
	$w = 0$	$w = 1$	
A	A	B	0
B	B	C	1
C	C	D	2
D	D	E	3
E	E	F	4
F	F	G	5
G	G	H	6
H	H	A	7

**Figure 6.61** State table for the counter.

	Present state $y_2 y_1 y_0$	Next state		Count $z_2 z_1 z_0$
		$w = 0$	$w = 1$	
		$Y_2 Y_1 Y_0$	$Y_2 Y_1 Y_0$	
A	000	000	001	000
B	001	001	010	001
C	010	010	011	010
D	011	011	100	011
E	100	100	101	100
F	101	101	110	101
G	110	110	111	110
H	111	111	000	111

**Figure 6.62** State-assigned table for the counter.



# Design of Counter Using Sequential Circuit

- Sample code

# Homework #1

- Design the up/down counter. The input clock is 50Mhz. The circuit count up or down, with the frequency is selected by two switches ( $f, 2*f, 4*f, 8*f$ , where  $f$  is less than  $f_{clk}$ ). The block diagram is shown as follows

