NPRE 449: HOMEWORK 3

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Question 1

To begin, the Navier-Stokes equations are:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0 \tag{1a}$$

$$\frac{\partial \rho \vec{v}}{\partial t} + \nabla \cdot \rho \vec{v} \, \vec{v} = -\nabla P + \nabla \cdot \vec{\tau} + \rho \vec{g} \tag{1b}$$

$$\frac{\partial \rho u}{\partial t} + \nabla \cdot \rho \vec{v} u = -\nabla \cdot q'' - P \nabla \cdot \vec{v} + \vec{\tau} : \nabla \vec{v} + q'''$$
(1c)

First, we expand the mass equation into Cartesian coordinates. This is rather rudimentary as the mass equation is a scalar equation, and there is only the divergence of a vector to be done:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{v} = 0$$

$$\frac{\partial \rho}{\partial t} + \left[\frac{\partial \rho v_x}{\partial x} + \frac{\partial \rho v_y}{\partial y} + \frac{\partial \rho v_z}{\partial z} \right] = 0$$
(2)

And so, for the mass equation:

Next, the momentum equation. To do this we will break into x, y, and z equations, as the momentum equation is a vector equation. The equations x, y, and z will all have the same form just with different subscripts. The expansion will be done with x. So as to not have a multi-line equation, each term will be defined for specifically x. To do this various steps are undertaken. Firstly, the divergence of \vec{v} \vec{v} can be seen as, in the x direction, $\nabla(v_x\vec{v})$. Next, the pressure is simply just the derivative of pressure in the x direction. Then, the divergence of the stress tensor is functionally similair to the divergence of the vector-vector multiplication, $\nabla \hat{\tau}_x$. Finally, the gravity form is simply the x-component of g.

$$\nabla \cdot \rho \vec{v} \, \vec{v} = \frac{\partial \rho v_x v_x}{\partial x} + \frac{\partial \rho v_x v_y}{\partial y} + \frac{\partial \rho v_x v_z}{\partial z}$$

$$\nabla P = \frac{\partial P_x}{\partial x}$$

$$\nabla \cdot \dot{\vec{\tau}} = \frac{\partial \dot{\vec{\tau}}_{xx}}{\partial x} + \frac{\partial \dot{\vec{\tau}}_{xy}}{\partial y} + \frac{\partial \dot{\vec{\tau}}_{xz}}{\partial z}$$

$$\rho \vec{g} = \rho g_x$$

$$(4)$$

Substituting these into our seperated momentum equations, we get the momentum equation expanded into x, y, and z:

$$\left| \frac{\partial \rho v_x}{\partial t} + \left[\frac{\partial \rho v_x v_x}{\partial x} + \frac{\partial \rho v_x v_y}{\partial y} + \frac{\partial \rho v_x v_z}{\partial z} \right] \right| = -\frac{\partial P_x}{\partial x} + \left[\frac{\partial \overset{\leftarrow}{\tau}_{xx}}{\partial x} + \frac{\partial \overset{\leftarrow}{\tau}_{xy}}{\partial y} + \frac{\partial \overset{\leftarrow}{\tau}_{xz}}{\partial z} \right] + \rho g_x \right|$$
(5a)

$$\frac{\partial \rho v_y}{\partial t} + \left[\frac{\partial \rho v_y v_x}{\partial x} + \frac{\partial \rho v_y v_y}{\partial y} + \frac{\partial \rho v_y v_z}{\partial z} \right] = -\frac{\partial P_y}{\partial y} + \left[\frac{\partial \overset{\leftarrow}{\tau}_{yx}}{\partial x} + \frac{\partial \overset{\leftarrow}{\tau}_{yy}}{\partial y} + \frac{\partial \overset{\leftarrow}{\tau}_{yz}}{\partial z} \right] + \rho g_y$$
 (5b)

$$\left| \frac{\partial \rho v_z}{\partial t} + \left[\frac{\partial \rho v_z v_x}{\partial x} + \frac{\partial \rho v_z v_y}{\partial y} + \frac{\partial \rho v_z v_z}{\partial z} \right] = -\frac{\partial P_z}{\partial z} + \left[\frac{\partial \overrightarrow{\tau}_{zx}}{\partial x} + \frac{\partial \overrightarrow{\tau}_{zy}}{\partial y} + \frac{\partial \overrightarrow{\tau}_{zz}}{\partial z} \right] + \rho g_z \right|$$
(5c)

Finally, for the energy equation. This is fortunately a scalar equation, and is thus not needed to be separated into different equations. First, $\nabla \cdot \rho \vec{v}u$ is simply the divergence of a vector, in which each component is multiplied by ρ and u. Next, $\nabla \cdot q''$ is again just the divergence of the q'' vector. Further, $P\nabla \cdot \vec{v}$ is again just the divergence of a vector multiplied by the pressure.

$$\nabla \cdot \rho \vec{v} u = \frac{\partial \rho v_x u}{\partial x} + \frac{\partial \rho v_y u}{\partial y} + \frac{\partial \rho v_z u}{\partial z}$$

$$\nabla \cdot q'' = \frac{\partial q''_x}{\partial x} + \frac{\partial q''_y}{\partial y} + \frac{\partial q''_z}{\partial z}$$

$$P\nabla \cdot \vec{v} = P \left[\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right]$$
(6)

Then to explain the $\dot{\tau}: \nabla \vec{v}$. First, the $\nabla \vec{v}$. This is actually written as $\nabla^T \vec{v}$:

$$\nabla^T \vec{v} = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} [v_x \ v_y \ v_z] = \begin{bmatrix} \frac{\partial v_x}{\partial x} & \frac{\partial v_x}{\partial y} & \frac{\partial v_x}{\partial z} \\ \frac{\partial v_y}{\partial x} & \frac{\partial v_y}{\partial z} & \frac{\partial v_y}{\partial z} \\ \frac{\partial v_z}{\partial x} & \frac{\partial v_z}{\partial y} & \frac{\partial v_z}{\partial z} \end{bmatrix}$$
(7)

Thus the double dot product has the true form of:

$$\vec{\tau} : \nabla \vec{v} = \begin{bmatrix} \tau_{ii} & \tau_{ij} & \tau_{ik} \\ \tau_{ji} & \tau_{jj} & \tau_{kk} \\ \tau_{ki} & \tau_{kj} & \tau_{kk} \end{bmatrix} : \begin{bmatrix} \frac{\partial v_x}{\partial x} & \frac{\partial v_x}{\partial y} & \frac{\partial v_x}{\partial z} \\ \frac{\partial v_y}{\partial x} & \frac{\partial v_y}{\partial y} & \frac{\partial v_y}{\partial z} \\ \frac{\partial v_z}{\partial x} & \frac{\partial v_z}{\partial y} & \frac{\partial v_z}{\partial z} \end{bmatrix}$$
(8)

Next, the double dot product of two tensors is very similair to a vector dot product. Each component in the tensor will be multiplied by its corresponding component in the other tensor, then all of the products will be summed.

$$\vec{\tau}: \nabla \vec{v} = \tau_{ii} \frac{\partial v_x}{\partial x} + \tau_{ij} \frac{\partial v_x}{\partial y} + \tau_{ik} \frac{\partial v_x}{\partial z} + \tau_{ji} \frac{\partial v_y}{\partial x} + \tau_{jj} \frac{\partial v_y}{\partial y} + \tau_{jk} \frac{\partial v_y}{\partial z} + \tau_{ki} \frac{\partial v_z}{\partial x} + \tau_{kj} \frac{\partial v_z}{\partial y} + \tau_{kk} \frac{\partial v_z}{\partial z}$$
(9)

Or, in shorter notation (where i, j, k are x, y, z):

$$\vec{\tau} : \nabla \vec{v} = \sum_{n}^{i,j,k} \sum_{m}^{i,j,k} \tau_{nm} \frac{\partial v_n}{\partial m}$$
(10)

Finally, we can plug these all back into our energy equation, yielding the energy equation expanded into Cartesian. Both the short-hand and long form are presented. Short form:

$$\frac{\partial \rho u}{\partial t} + \left[\frac{\partial \rho v_x u}{\partial x} + \frac{\partial \rho v_y u}{\partial y} + \frac{\partial \rho v_z u}{\partial z} \right] = -\left[\frac{\partial q_x''}{\partial x} + \frac{\partial q_y''}{\partial y} + \frac{\partial q_z''}{\partial z} \right] - P\left[\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right] + \sum_{n=1}^{i,j,k} \sum_{m=1}^{i,j,k} \tau_{nm} \frac{\partial v_n}{\partial m} + q''' \quad (11)$$

Long form:

$$\frac{\partial \rho u}{\partial t} + \left[\frac{\partial \rho v_x u}{\partial x} + \frac{\partial \rho v_y u}{\partial y} + \frac{\partial \rho v_z u}{\partial z} \right] = -\left[\frac{\partial q_x''}{\partial x} + \frac{\partial q_y''}{\partial y} + \frac{\partial q_z''}{\partial z} \right]
- P\left[\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right] + q''' + \left[\tau_{ii} \frac{\partial v_x}{\partial x} + \tau_{ij} \frac{\partial v_x}{\partial y} + \tau_{ik} \frac{\partial v_x}{\partial z} \right]
+ \tau_{ji} \frac{\partial v_y}{\partial x} + \tau_{jj} \frac{\partial v_y}{\partial y} + \tau_{jk} \frac{\partial v_y}{\partial z} + \tau_{ki} \frac{\partial v_z}{\partial x} + \tau_{kj} \frac{\partial v_z}{\partial y} + \tau_{kk} \frac{\partial v_z}{\partial z} \right]$$
(12)

Question 2

From our assumptions, the mass and momentum equations simplify, in cylindrical coordinates, to:

$$\nabla \cdot \vec{v} = 0 \tag{13a}$$

$$0 = -\frac{\partial P}{\partial r} + \rho g_r \tag{13b}$$

$$0 = -\frac{1}{r}\frac{\partial P}{\partial \theta} + \rho g_{\theta} \tag{13c}$$

$$0 = -\frac{\partial P}{\partial z} + \mu \left[\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial v_z}{\partial r} \right]$$
 (13d)

Finally the energy equation simplifies as follows, because specific internal energy u is simply c_pT :

$$\nabla \cdot \rho \vec{v} u = -\nabla \cdot \vec{q}^{"} \tag{14a}$$

$$\rho c_p \left[\frac{1}{r} \frac{\partial}{\partial r} (r v_r T) + \frac{1}{r} \frac{\partial v_\theta T}{\partial \theta} + \frac{\partial v_z T}{\partial z} \right] = k \left[\frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial T}{\partial r} + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2} \right]$$
(14b)

$$v_z \frac{\partial T}{\partial z} = \frac{k}{\rho c_p} \frac{1}{r} \frac{\partial}{\partial r} r \frac{\partial T}{\partial r}$$
(14c)

Finally we can solve these equations for axial velocity and temperature.

First, we will solve for the pressure profile. We know that \vec{g} is equal to $\langle -g\sin(\theta), -g\cos(\theta), 0 \rangle$. Thus:

$$P = -\rho gr \sin \theta + C(\theta, z) \tag{15a}$$

$$P = -\rho gr \sin \theta + C(r, z) \tag{15b}$$

And because the result from both radial and azimuthal solving yields the same functional form, we know that C must only be a function of z. Further, we know that pressure must be a linear function of z, as its derivative with respect to z must not be a function of z. Thus, we can solve for the velocity profile.

$$\frac{P_0 r}{\mu} = \frac{\partial}{\partial r} r \frac{\partial v_z}{\partial r} \tag{16a}$$

$$\frac{P_0 r}{2\mu} + \frac{C_1}{r} = \frac{\partial v_z}{\partial r} \tag{16b}$$

$$v_z(r) = \frac{P_0 r^2}{4\mu} + C_1 \ln r + C_2 \tag{16c}$$

Next for our boundary conditions:

(1) No-Slip Condition: $v_z(R_o) = 0$

2 Symmetry: $\frac{\partial v_z(0)}{\partial r} = 0$, or Finiteness at the centerline

Thus, C_1 must be 0 by \bigcirc , and then investigating \bigcirc , C_2 must be:

$$v_z(R_0) = \frac{P_0 R_0^2}{4\mu} + C = 0 \tag{17a}$$

$$C = -\frac{P_0 R_0^2}{4\mu} \tag{17b}$$

Thus our axial velocity, recognizing that $P_0 = \frac{-\Delta P}{l}$, is:

$$v_z(r) = \frac{\Delta P R^2}{4\mu l} - \frac{\Delta P r^2}{4\mu l} = \frac{\Delta P}{4\mu l} (R^2 - r^2) = \langle v_z \rangle (1 - \frac{r^2}{R^2})$$
 (18)

Such that $\langle v_z \rangle = \frac{\Delta P R^2}{4\mu l}$.

Now, for the temperature. Importantly, $\frac{\partial T}{\partial z}$ is a constant because of the definition of fully developed temperature flow. .

$$v_z(r)\frac{\partial T}{\partial z} = \frac{k}{\rho c_p r} \frac{\partial}{\partial r} r \frac{\partial T}{\partial r}$$
(19a)

$$\frac{\langle v_z \rangle \rho c_p}{k} \frac{\partial T}{\partial z} (r - \frac{r^3}{R^2}) = \frac{\partial}{\partial r} r \frac{\partial T}{\partial r}$$
(19b)

$$\frac{\langle v_z \rangle \rho c_p}{k} \frac{\partial T}{\partial z} \left(\frac{r}{2} - \frac{r^3}{4R^2}\right) + \frac{C_1}{r} = \frac{\partial T}{\partial r}$$
(19c)

$$T(r,z) = \frac{\langle v_z \rangle \rho c_p}{k} \frac{\partial T}{\partial z} \left[\frac{r^2}{4} - \frac{r^4}{16R^2} \right] + C_1 \ln(r) + C_2$$
 (19d)

And then again for simplicity, I define $\frac{\langle v_z \rangle}{k} \frac{\rho}{\partial z} \frac{\partial T}{\partial z}$ as equal to ξ :

$$T(r,z) = \xi \left[\frac{r^2}{4} - \frac{r^4}{16R^2} \right] + C_1 \ln(r) + C_2$$
 (20)

Now for our boundary conditions:

- (1) Symmetry: $\frac{\partial T(0)}{\partial r}$, or Finiteness at the center line
- $(2) T(R,z) = T_s(z)$

Investigating \bigcirc , C_1 must be 0. Then from \bigcirc :

$$T(R,z) = \xi \left[\frac{R^2}{4} - \frac{R^2}{16} \right] + C_2$$
 (21a)

$$T_s(z) - \xi \left[\frac{3R^2}{16} \right] = C_2 \tag{21b}$$

Thus, our temperature distribution is:

$$T(r,z) = \xi \left[\frac{r^2}{4} - \frac{r^4}{16R^2} \right] + T_s(z) - \xi \frac{3R^2}{16}$$
 (22)

Then to find the normalized temperature, $\frac{T_s(z) - T(r,z)}{T_s(z) - T_{cl}(z)};$

$$T_s(z) - T(r, z) = \xi \left[\frac{r^4}{16R^2} - \frac{r^2}{4} + \frac{3R^2}{16} \right]$$
 (23a)

$$T_s(z) - T_{cl}(z) = \xi \left[\frac{3R^2}{16} \right]$$
 (23b)

Thus:

$$\frac{T_s(z) - T(r, z)}{T_s(z) - T_{cl}(z)} = \frac{\frac{r^4}{16R^2} - \frac{r^2}{4} + \frac{3R^2}{16}}{\frac{3R^2}{16}}$$
(24a)

$$\frac{T_s(z) - T(r, z)}{T_s(z) - T_{cl}(z)} = \frac{r^4}{3R^4} - \frac{4r^2}{3R^2} + 1$$
 (24b)

Finally, the normalized temperature and velocity distributions are:

plots/q2.png

Question 3

To begin, we can skip all of the beginning cruft. We already know our velocity profile:

$$v_z(r) = \frac{\Delta P}{4\mu \, l} (r^2 - R^2) \tag{25}$$

And taking the area average of this:

$$\langle v_z \rangle = \frac{1}{\pi R^2} \int_0^{2\pi} \int_0^R r v_z(r) dr d\theta$$
 (26a)

$$\langle v_z \rangle = \frac{1}{\pi R^2} \frac{\pi \Delta P}{2\mu l} \left(\frac{r^4}{4} - \frac{R^2 r^2}{2} \right) \Big|_0^R$$
 (26b)

$$\langle v_z \rangle = \frac{-R^2 \Delta P}{8ul} \tag{26c}$$

Thus, the velocity profile is equal to $2\langle v_z\rangle(1-\frac{r^2}{R^2})$.

Next, our energy equation is:

$$\rho c_p v_z(r) \frac{\partial T}{\partial z} = \frac{k}{r} \frac{\partial}{\partial r} r \frac{\partial T}{\partial z} + \mu \left(\frac{\partial v_z}{\partial r} \right)^2$$
(27a)

$$2\rho c_p \langle v_z \rangle (1 - \frac{r^2}{R^2}) \frac{\partial T}{\partial z} = 16\mu \langle v_z \rangle^2 \frac{r^2}{R^4}$$
 (27b)

Next, to integrate both sides through the volume:

$$\iiint_{V} 2r\rho c_{p} \langle v_{z} \rangle (1 - \frac{r^{2}}{R^{2}}) \frac{\partial T}{\partial z} dV = \iiint_{V} 16r\mu \langle v_{z} \rangle^{2} \frac{r^{2}}{R^{4}} dV$$
 (28a)

$$2\rho c_p \int_0^{2\pi} \int_0^R \int_0^l (r - \frac{r^3}{R^2}) \frac{\partial T}{\partial z} dz d\theta dr = 16\mu \langle v_z \rangle \int_0^{2\pi} \int_0^R \int_0^l \frac{r^3}{R^4} dz d\theta dr$$
 (28b)

$$4\pi\rho c_p \Delta T \left(\frac{r^2}{2} - \frac{r^4}{4R^2}\right) \Big|_0^R = 32\pi\mu \langle v_z \rangle \frac{r^4}{4R^4} \Big|_0^R (z) \Big|_0^l$$
 (28c)

$$\rho c_p \Delta T R^2 = 8\mu \langle v_z \rangle l \tag{28d}$$

$$l = \frac{\rho c_p \Delta T R^2}{8\mu \langle v_z \rangle} \tag{28e}$$

Finally, we can find the average velocity, $\langle v_z \rangle$, with the reynolds number of laminar flow.

$$Re = \frac{2\rho \langle v_z \rangle R}{\mu} \langle v_z \rangle = \frac{Re\mu}{2R\rho} \tag{29}$$

Finally, using a reynolds number of 2300, we can solve for the two lengths:

$$l = 56473.337m, D = 0.1m$$
(30)

$$l = 56.473m, D = 0.01m \tag{31}$$