



# Nicolas G. Morales

✉ ngmorales97@att.net  
☎ (937) 776-0843

🌐 ngmor.github.io  
🌐 github.com/ngmor

🌐 linkedin.com/in/nicolasgmorales  
📍 Chicago, IL

## EDUCATION

<b>Northwestern University</b> , Evanston, IL	December 2023
Master of Science in Robotics	
<b>Purdue University</b> , West Lafayette, IN	May 2019
Bachelor of Science in Mechanical Engineering, Purdue Honors College	Cumulative GPA: 4.00 / 4.00
Minors: Electrical and Computer Engineering, Spanish	
<b>University of Canterbury</b> , Christchurch, New Zealand	February 2018 – June 2018
Certificate of Proficiency with a focus on electrical and mechanical engineering	

## WORK EXPERIENCE

<b>DMC, Inc:</b> Systems Engineer II ( <i>Chicago, IL</i> )	August 2019 – August 2022
<u>Selected Specific Projects</u>	
<ul style="list-style-type: none"><li>• Onsite technical project lead for new battery production line projects at leading electric car company</li><li>• Co-project manager for automated safe loading system project at high-speed transportation research and development company</li><li>• Primary developer of data collection and storage application for cartridge production data at healthcare diagnostics company</li></ul>	
<u>General Responsibilities</u>	
<ul style="list-style-type: none"><li>• Developed customized automation and SCADA solutions for machine/process control and data collection in multiple industries</li><li>• Interfaced with clients to coordinate efforts, better meet customer needs, and communicate project status regularly</li><li>• Troubleshoot automation systems developed by DMC, clients, and 3rd parties to prevent disruption of production facilities</li><li>• Estimated project costs, wrote proposals, and successfully sold projects up to \$300K to new and existing clients</li></ul>	
<b>Northrop Grumman (Orbital ATK):</b> Mechanical Engineering Intern ( <i>Dayton, OH</i> )	Summer 2016; Winter 2017; Summer 2018
<ul style="list-style-type: none"><li>• Employed several CAD packages to design and additively manufacture novel structures for research and development efforts</li><li>• Modified open source FFF machine hardware and electronics to improve performance and work with new materials</li></ul>	
<b>Herrick Laboratories:</b> Undergraduate Research Assistant ( <i>West Lafayette, IN</i> )	June 2017 – May 2019
<ul style="list-style-type: none"><li>• Published a paper on the effects of interlayer wait time on the mechanical strength of additively manufactured parts</li><li>• Designed, laid out, and manufactured PCBs to assist with research efforts across the research group</li></ul>	

## ENGINEERING PROJECTS

<b>Attack of the Franka 7-DoF Robotic Arm Control:</b>	November 2022 – December 2022
<ul style="list-style-type: none"><li>• Created a ROS2 system which controlled a Franka Emika Panda arm to knock over “enemy” targets while protecting “allies”</li><li>• Architected an API to allow non-blocking usage of the ROS2 MoveIt Motion Planning Framework in Python</li><li>• Designed a computer vision node that employed a RealSense D435i, OpenCV, and AprilTags to detect the workspace and targets</li></ul>	
<b>Gesture Controlled Robotic Arm (IMUnipulator):</b>	November 2022 – December 2022
<ul style="list-style-type: none"><li>• Programmed an nRF52-based microcontroller in C to move a 2-DoF robotic arm based on input signals from a 9-DoF IMU</li><li>• Wrote drivers for I2C communication, PWM, servos, capacitive touch sensors, and more to interact with required devices</li></ul>	
<b>SimpleStrings Assistive Guitar Device:</b>	January 2019 – May 2019
<ul style="list-style-type: none"><li>• Worked with a team of engineers to develop an Arduino-based programmable assistive chord playing device for music therapy</li><li>• Designed, laid out, and assembled custom PCB/device electronics to receive inputs and control 24 actuation motors</li></ul>	
<b>Down-Counter/PWM Generator:</b>	February 2018 – June 2018
<ul style="list-style-type: none"><li>• Applied VHDL and Vivado to implement a programmable 16-bit down-counter and PWM waveform generator on an FPGA</li></ul>	
<b>Autonomous Robots:</b>	August 2015 – May 2016
<ul style="list-style-type: none"><li>• Acted as software design lead for writing wavefront planner pathfinding software in RobotC for a lunar transport vehicle</li></ul>	

## LEADERSHIP EXPERIENCE

<b>Purdue Lunabotics:</b> Excavation/Deposition Team Lead	September 2015 – May 2017
<ul style="list-style-type: none"><li>• Directed a subteam tasked with designing, prototyping, and testing excavation/deposition systems intended to mine lunar soil</li></ul>	
<b>Honors College Mentor Program:</b> Mentor	August 2016 – October 2016
<ul style="list-style-type: none"><li>• Led a weekly recitation discussion session in a first-year honors seminar course to aid in the college transition for freshmen</li></ul>	

## SKILLS

**Software:** Python, C, C++, Robot Operating System (ROS2/ROS), SQL, Version Control (Git, SVN), VBScript, MATLAB

**Automation:** Beckhoff TwinCAT, Ignition, Siemens TIA Portal, Rockwell Studio 5000, WinCC 7

**Design:** Inventor, NX, SolidWorks, CATIA, Creo, KiCad, Simplify3D, Cura

**Language:** Spanish (9.5 years education)

## HONORS AND AWARDS

Purdue 2015 Stamps Leadership Scholar	March 2015 – May 2019
Pi Tau Sigma Mechanical Engineering Honors Society, Beta Chapter	September 2016 – May 2019