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EDUCATION **University of Massachusetts Amherst,** Amherst, MA
Ph.D. in Computer Science Sep 2023 - Present

- Advisors: [Prof. Evangelos Kalogerakis](#), [Prof. Chuang Gan](#)
- GPA: 3.97/4.00

Ho Chi Minh City University of Technology,
B.E in Computer Engineering

Ho Chi Minh City, Vietnam
Aug 2017 - Aug 2021

- Graduated with the *Highest honor*.
- GPA: 9.62/10.00

SELECTED PUBLICATIONS **Conferences**

- **Tuan Duc Ngo**, Jiahui Huang, Seoung Wug Oh, Kevin Blackburn-Matzen, Evangelos Kalogerakis, Chuang Gan, Joon-Young Lee, “DAGE: Dual-Stream Architecture for Efficient and Fine-Grained Geometry Estimation”, *preprint*.
- **Tuan Duc Ngo**, Ashkan Mirzaei, Guocheng Qian, Hanwen Liang, Chuang Gan, Evangelos Kalogerakis, Peter Wonka, Chaoyang Wang, “[DELTA_{v2}: Accelerating Dense 3D Tracking](#)”, *preprint*.
- Chaoyang Wang*, Peiye Zhuang*, **Tuan Duc Ngo***, Willi Menapace, Aliaksandr Siarohin, Michael Vasilkovsky, Ivan Skorokhodov, Sergey Tulyakov, Peter Wonka, Hsin-Ying Lee, “[4Real-Video Learning Generalizable Photo-Realistic 4D Video Diffusion](#)”, in *Computer Vision and Pattern Recognition Conference (CVPR)*, 2025. **Highlight**
- **Tuan Duc Ngo**, Peiye Zhuang, Chuang Gan, Evangelos Kalogerakis, Sergey Tulyakov, Hsin-ying Lee, Chaoyang Wang, “[DELTA: Dense Efficient Long-range 3D Tracking for any video](#)”, in *International Conference on Learning Representations (ICLR)*, 2025.
- Phuc Nguyen*, **Tuan Duc Ngo***, Chuang Gan, Evangelos Kalogerakis, Anh Tran, Cuong Pham, Khoi Nguyen, “[Open3DIS: Open-vocabulary 3D Instance Segmentation with 2D Mask Guidance](#)”, in *Computer Vision and Pattern Recognition Conference (CVPR)*, 2024.
- **Tuan Duc Ngo**, Binh-Son Hua, Khoi Nguyen, “[GaPro: Box-Supervised 3D Point Cloud Instance Segmentation Using Gaussian Processes as Pseudo Labelers](#)”, in *International Conference on Computer Vision (ICCV)*, 2023.
- **Tuan Duc Ngo**, Binh-Son Hua, Khoi Nguyen, “[ISBNet: a 3D Point Cloud Instance Segmentation Network with Instance-aware Sampling and Box-aware Dynamic Convolution](#)”, in *Computer Vision and Pattern Recognition Conference (CVPR)*, 2023.
- **Tuan Duc Ngo** and Khoi Nguyen, “[Geodesic-Former: a Geodesic-Guided Few-shot 3D Point Cloud Instance Segmenter](#)”, in *European Conference on Computer Vision (ECCV)*, 2022.

RESEARCH EXPERIENCE **Adobe Inc.** San Jose, CA
Research Intern (Video team) May 2025 - Nov 2025

- Mentors: [Gabriel Huang](#), [Dr. Joon-Young Lee](#), [Dr. Seoung Wug Oh](#).
- Main research topics: 3D/4D reconstruction.
- Project: “Efficient and fine-grained visual geometry”
 - A dual-stream architecture for efficient and fine-grained pointmap/depth and camera pose estimation from video (under review).

Snap Inc.

Research Intern (Creative Vision team)

Santa Monica, CA

May 2024 - May 2025

- Mentors: [Dr. Chaoyang Wang](#), [Dr. Hsin-Ying Lee](#), [Dr. Peiye Zhuang](#).
- Main research topics: 3D Point Tracking, 4D reconstruction.
- Project: “Dense 3D Tracking”
 - Capturing dense, long-range, 3D point trajectories from casual videos in a feed-forward manner (ICLR 2025).
 - Accelerate dense, long-range 3D tracking with a coarse-to-fine approach (under review).

UMass Amherst

Research Assistant

Amherst, MA

Sept 2023 - present

- Main research topics: 3D Generative Model, 3D Animation and 3D Motion Synthesis.
- Project: “Open-Vocabulary 3D Segmentation”
 - Addressing 3D Instance Segmentation with Open-Vocabulary queries by leveraging 2D and 3D priors.
- Project: “Text-to-3D-motion”
 - Generating diverse 3D human motions from textual description.
- Project: “Articulated 3D Object Reconstruction”

VinAI Research

AI Research Resident

Ha Noi, Vietnam

Aug 2021 - July 2023

- Mentors: [Dr. Khoi Nguyen](#), [Prof. Binh-Son Hua](#).
- Main research topics: 3D Point Cloud Instance Segmentation, 3D Object Detection, and 3D Scene Completion.
- Project: “Camera-based 3D Occupancy Prediction”
 - Enhancing bird’s-eye-view 3D object detectors for 3D occupancy prediction task.
- Project: “3D Point Cloud Instance Segmentation”
 - Introduce an efficient and robust sampling strategy and propose leveraging the bounding box as a geometric cue for the 3D point cloud instance segmentation task (CVPR 2023).
- Project: “Weakly Supervised 3D Point Cloud Instance Segmentation”
 - Introduce using Gaussian Process to generate high-quality pseudo instance masks from the axis-aligned GT bounding boxes for the 3D point cloud instance segmentation task (ICCV 2023).
- Project: “Few-shot 3D Point Cloud Instance Segmentation”
 - Propose a new task of 3D understanding, Few-shot 3D point cloud instance segmentation, and address it with a transformer-based 3D instance segmenter leveraging geodesic distance as a strong geometric cue (ECCV 2022).

AI Engineer (Applied Rotation Program)

Jul 2022 - Oct 2022

- Project: “Bird-eye-view semantic segmentation from multi-view fisheye images”
 - Participate in the Surrounding-View-Monitoring team to design and develop a new “Bird-eye-view semantic segmentation” feature, including data preparation, modeling, and deploying.
 - Awarded as the best Applied Rotation Program project.

TECHNICAL TALKS	<ul style="list-style-type: none"> • DELTA: Dense Efficient Long-range 3D Tracking for any video, at <i>New England Computer Vision (NECV) Workshop 2024</i> • ISBNet: a 3D Point Cloud Instance Segmentation Network with Instance-aware Sampling and Box-aware Dynamic Convolution, at <i>ScanNet Indoor Scene Understanding Challenge CVPR 2023 Workshop</i>, slide, video, poster Jun, 2023 • Geodesic-Former: a Geodesic-Guided Few-shot 3D Point Cloud Instance Segmenter, at <i>VinAI 2022 Winter Workshop</i>, slide, video, poster Nov, 2022
ACADEMIC SERVICES	<ul style="list-style-type: none"> • Reviewer of CVPR (2024, 2025, 2026), ICCV (2025), ECCV (2024), NeurIPS (2025), ICLR (2026), AAAI (2025, 2026), IEEE Transactions on Image Processing.
HONORS AND AWARDS	<ul style="list-style-type: none"> • 2023 CICS Scholarship, UMass Amherst. 2023 • Class of 2021 Valedictorian of HCMUT (graduated with the highest GPA) 2021 • Scholarships for outstanding academic achievements, HCMUT 2017 - 2021