

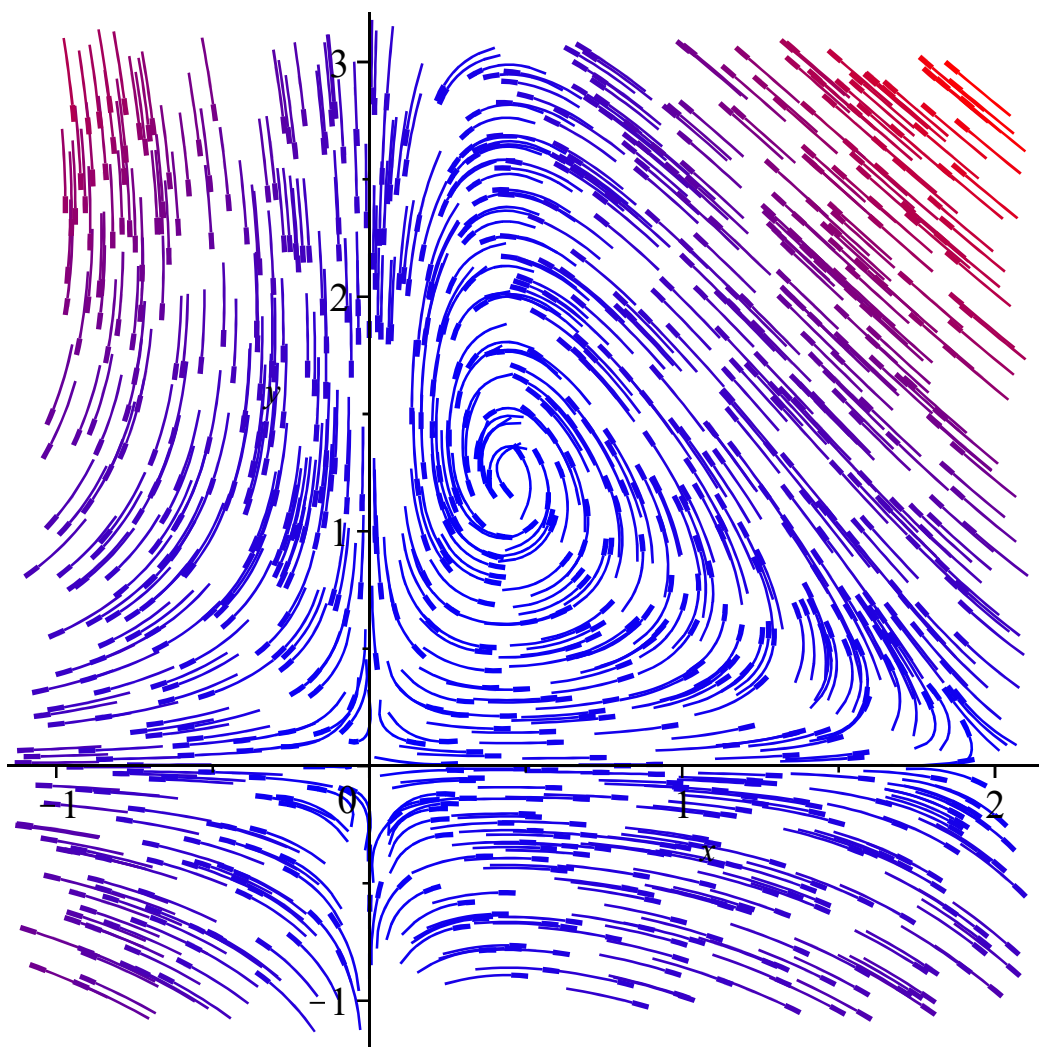
$$\begin{aligned} &> d1 := \text{diff}(x(t), t) = 8 \cdot x(t) - 5 \cdot x(t) \cdot y(t) - 4 \cdot x(t) \cdot x(t) \\ &\quad d1 := \frac{d}{dt} x(t) = 8 x(t) - 5 x(t) y(t) - 4 x(t)^2 \end{aligned} \quad (1)$$

$$\begin{aligned} &> d2 := \text{diff}(y(t), t) = -3 \cdot y(t) + 7 \cdot x(t) \cdot y(t) \\ &\quad d2 := \frac{d}{dt} y(t) = -3 y(t) + 7 x(t) y(t) \end{aligned} \quad (2)$$

$$\begin{aligned} &> \text{solve}(\{ \text{rhs}(d1) = 0, \text{rhs}(d2) = 0 \}, \{ x(t), y(t) \}) \\ &\quad \{ x(t) = 0, y(t) = 0 \}, \{ x(t) = 2, y(t) = 0 \}, \left\{ x(t) = \frac{3}{7}, y(t) = \frac{44}{35} \right\} \end{aligned} \quad (3)$$

> with(DEtools) :

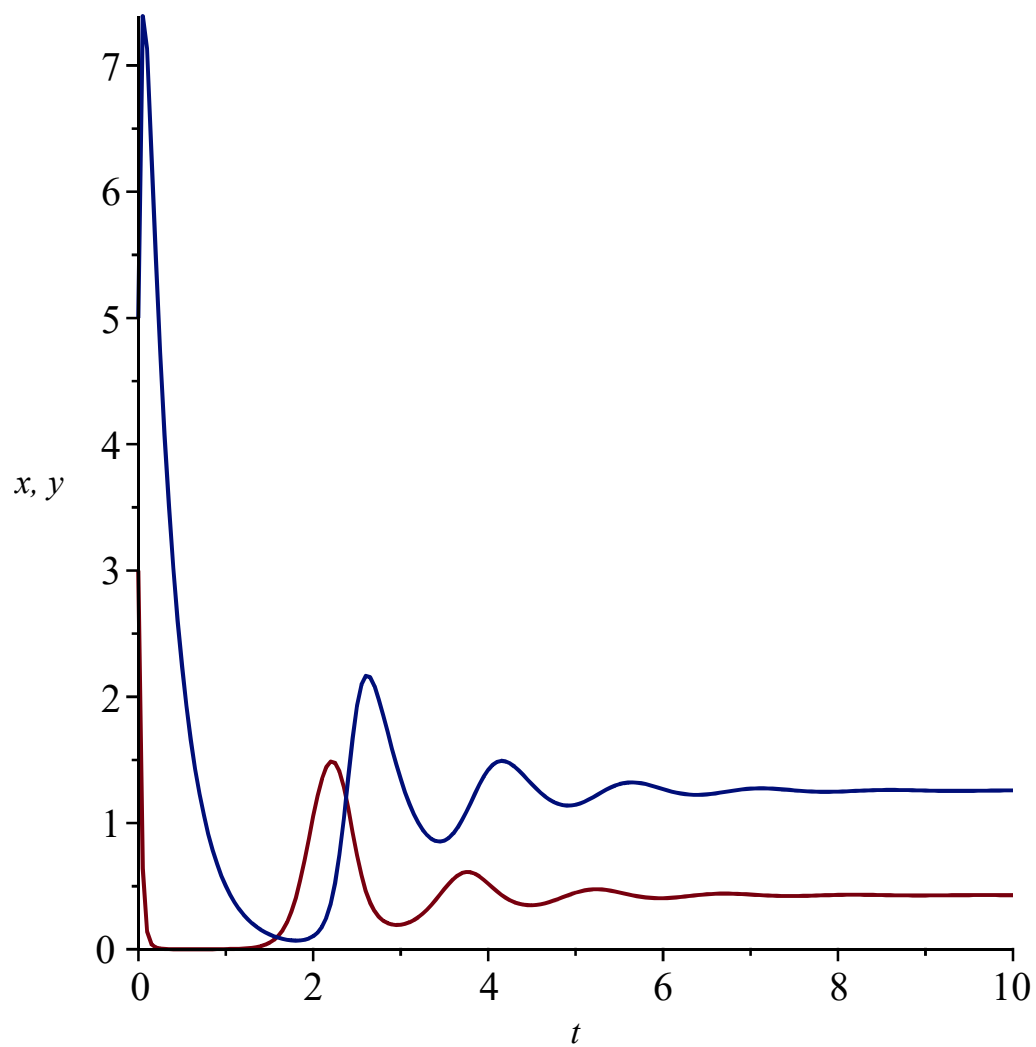
> DEplot([d1, d2], [x(t), y(t)], t = -10..10, x = -1..2, y = -1..3, arrows = curve, dirfield = 1000, color = magnitude)



$$\begin{aligned} &> \text{syst1} := \text{dsolve}(\{ d1, d2, x(0) = 3, y(0) = 5 \}, \{ x(t), y(t) \}, \text{numeric}, \text{method} = \text{rkf45}) \\ &\quad \text{syst1} := \text{proc}(x\_rkf45) \dots \text{end proc} \end{aligned} \quad (4)$$

> with(plots) :

> odeplot(syst1, [[t, x(t)], [t, y(t)]], t = 0..10)

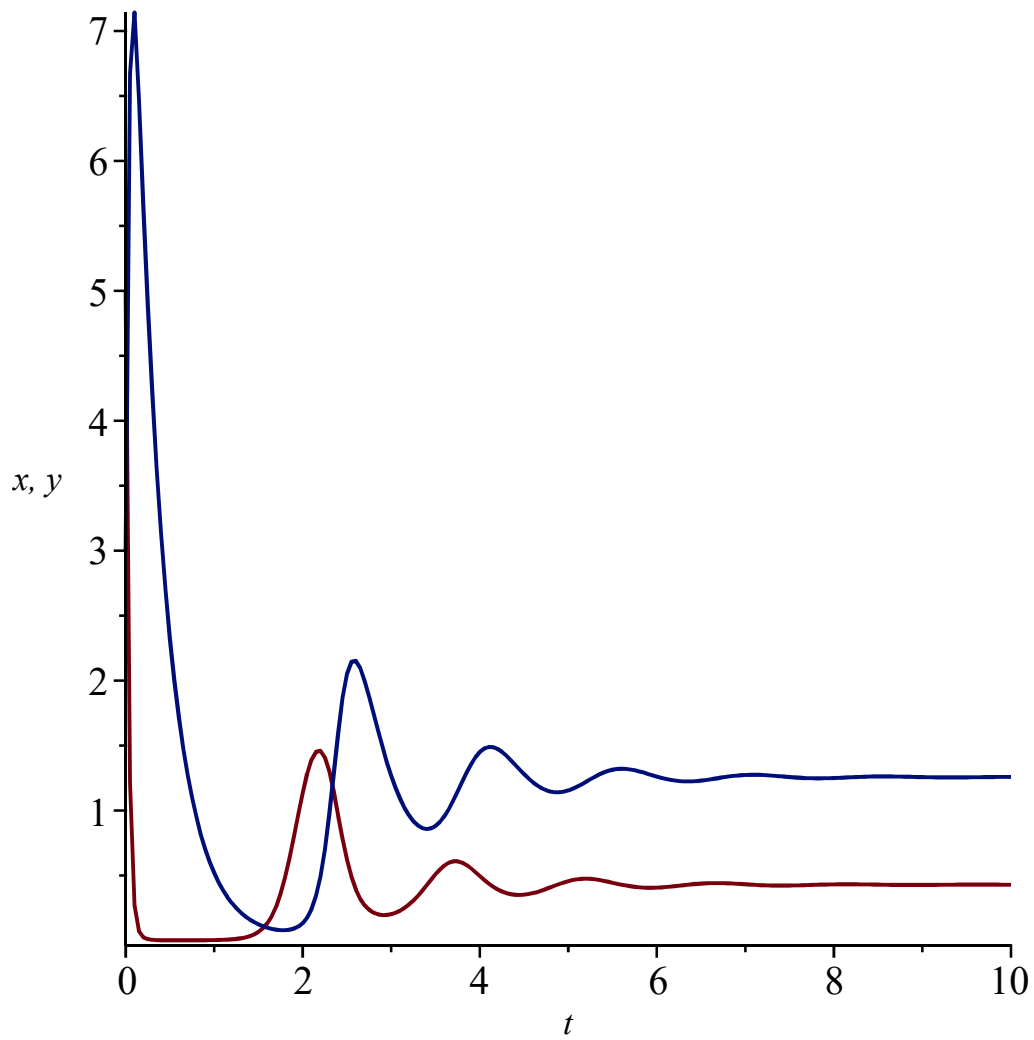


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> syst2 := dsolve( {d1, d2, x(0)=5, y(0)=3}, {x(t), y(t)}, numeric, method=rkf45)
               syst2 := proc(x_rkf45) ... end proc
> odeplot(syst2, [[t, x(t)], [t, y(t)]], t=0..10)

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(5)



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> DEplot3d( {d1, d2}, {x(t), y(t)}, t=0..10, x=-1..5, y=-1..5, [[x(0)=1, y(0)=1.5], [x(0)=2, y(0)=3]], scene=[t, x(t), y(t)], stepsize=0.01, title='predator prey', linecolor=t)
```

*predator prey*

