# Adaptive Equi-Energy Sampler : Convergence and Illustration

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- Goal : sample a target distribution  $\pi$  known up to a multiplicative constant
- Example : motif sampling in biology
- Problem : for multimodal distributions, some algorithms remain trapped in one of the modes

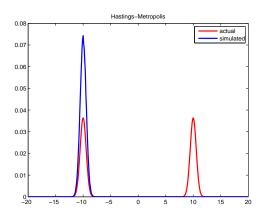


Figure: Random walk Metropolis-Hastings for a mixture of Gaussian distributions

- The algorithm
  - Why interact?
  - The adaptive equi-energy sampler
  - Illustration on a toy example
- Motif sampling : an example taken from real life
  - The model
  - Results
- On the convergence of AEES
  - Intuition
  - Condition required
  - General results



# Metropolis-Hastings algorithm:

- Sample  $X_0$  under any initial distribution  $\mu$
- Knowing the current state  $X_n$ , sample  $Y_{n+1}$  under  $Q(X_n, .)$
- Compute the acceptation-rejection probability :

$$\alpha(X_n, Y_{n+1}) = \min\left(1, \frac{\pi(Y_{n+1})q(Y_{n+1}, X_n)}{\pi(X_n)q(X_n, Y_{n+1})}\right)$$

• Set  $X_{n+1} = Y_{n+1}$  with probability  $\alpha(X_n, Y_{n+1})$  and  $X_{n+1} = X_n$  with probability  $1 - \alpha(X_n, Y_{n+1})$ .

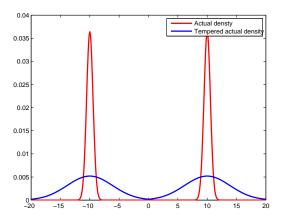


Figure: Actual density and a tempered version (T = 50)

- It seems easier to sample a tempered version  $\pi^{1/T}$ , T>1 of the target distribution.
- Idea: Sample a tempered version of the target distribution as an auxiliary process and allow the process of interest to "jump" on one of the auxiliary states after and acceptation/rejection step.
- Problem : The acceptation probability could be really low.

# Equi-Energy Sampler:

- Sample  $X_0$  under any initial distribution  $\mu$ .
- We know n values  $Y_1, \ldots, Y_n$  of an auxiliary process. Knowing the current state  $X_n$ :
  - with probability  $1 \epsilon$ , sample  $X_{n+1}$  with a symmetric random walk Metropolis-Hastings algorithm
  - with probability  $\epsilon$ , choose an auxiliar value  $Y_i$  such that  $\pi(Y_i)$  is "close" to  $\pi(X_n)$ , and set  $X_{n+1} = Y_i$  or  $X_{n+1} = X_n$  after an acceptation/rejection step

Fix a number of rings S. Consider a sequence of real number  $\xi_0 = 0 < \xi_1 < \dots < \xi_S = +\infty$ .

Two energies  $\pi(x)$  and  $\pi(y)$  are said to be close if there exists l, 1 < l < S such that  $\xi_{l-1} < \pi(x), \pi(y) < \xi_l$ .

On the choice of the  $\xi_i$ :

- Original equi-energy sampler: fixed by user
- Problem : crucial choice
- Adaptive equi-energy sampler : quantiles estimators
  - empirical quantiles
  - stochastic approximation estimator

# Empirical quantiles associated to a distribution heta :

- Cumulative distribution function :  $F_{\theta}(x) = \int \mathbf{1}_{\{\pi(y) < x\}} \theta(dy)$ .
- Quantile function :  $F_{\theta}^{-1}(p) = \inf\{x \geq 0, F_{\theta}(x) \geq p\}.$
- For any  $\{p_l, 1 \leq l \leq S\}$  (for example  $p_l = \frac{l}{S}$ ), the ring bouldaries are defined by  $\hat{\xi}_{\theta,l} = F_{\theta}^{-1}(p_l)$ .
- Rings :  $A_{\theta,I} = ]\hat{\xi}_{\theta,I-1}; \hat{\xi}_{\theta,I}]$ .

For the adaptive EES :  $\theta_n = n^{-1} \sum_{k=1}^n \delta_{Y_k}$ .

- Selection function :  $g_{\theta}(x,y) = \sum_{l=1}^{S} h_{\theta,l}(x) h_{\theta,l}(y)$ ,
- with :  $h_{\theta,I}(x) = \left(1 \frac{d(\pi(x), A_{\theta,I})}{r}\right)_+$ .
- Kernel for the EE move :  $K_{\theta}(x, A) = \int_{A} \alpha_{\theta}(x, y) \frac{g_{\theta}(x, y)\theta(dy)}{\int g_{\theta}(x, z)\theta(dz)} + \mathbf{1}_{A}(x) \int \{1 \alpha_{\theta}(x, y)\} \frac{g_{\theta}(x, y)\theta(dy)}{\int g_{\theta}(x, z)\theta(dz)}$
- with :  $\alpha_{\theta}(x,y) = 1 \wedge \left( \frac{\pi(y)}{\pi(x)} \frac{\pi^{1-\beta}(x) \int g_{\theta}(x,z)\theta(dz)}{\pi^{1-\beta}(y) \int g_{\theta}(y,z)\theta(dz)} \right)$ .
- Kernel for the AEE sampler :

$$P_{\theta}(x,.) = (1 - \epsilon)P(x,.) + \epsilon K_{\theta}(x,.).$$

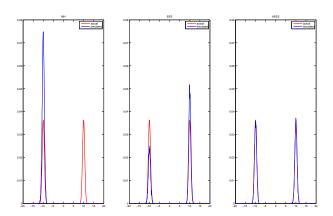


Figure: Equi-Energy Samplers for a mixture of Gaussian distributions

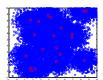


Figure: EES for a mixture of Gaussian distributions, T=60



Figure: T=7

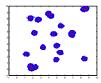


Figure: T=1

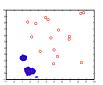


Figure: Metropolis-Hastings

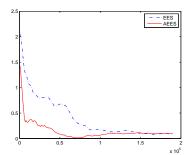


Figure: L1 error for EES and AEES

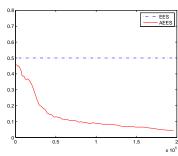
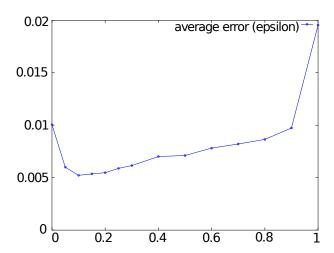


Figure: extreme case

## Many parameters to choose:

- proposal distribution (could be adaptive)
- number of energy rings
- temperature of the processes
- proportion of equi-energy moves



#### Notations:

- L : length of the DNA sequence
- S: DNA sequence.  $S = (s_1, s_2, ..., s_L)$  with  $s_i \in \{1, 2, 3, 4\}$  (1 corresponding to A, 2 to C, 3 to G and 4 to T)
- w : length of a motif
- A : array giving the position of the motifs.  $A = (a_1, \ldots, a_L)$ , where  $a_i$  is equal to  $j \in \{0, \ldots, w\}$  if the ith element of the sequence is the jth element of a motif
- ullet  $p_0$ : probability for a sub-sequence of length w to be a motif

## Distribution:

- $\bullet$  Background sequence : Markov chain associated with the transition matrix denoted by  $\theta_0$
- Motif: multinomial distribution of parameter  $\theta = (\theta_1, \dots, \theta_w)$

Knowing  $a_1, \ldots, a_{k-1}, s_1, \ldots, s_{k-1}, \theta$  and  $p_0$ , we have :

- If  $a_{k-1} \in \{1, \dots, w-1\}$ ,  $a_k = a_{k-1} + 1$ , otherwise,  $a_k$  follows a Bernouilli distribution of parameter  $p_0$
- If  $a_k = 0$ ,  $s_k$  follows the distribution  $\theta_0(s_{k-1},.)$ , otherwise,  $s_k$  follows the distribution  $\theta_{a_k}(.)$

Conditionnal distribution of A given S:

$$P(A|S) \propto \frac{\Gamma(N_{1} + a)\Gamma(N_{0} + b)}{\Gamma(N_{1} + N_{0} + a + b)} \prod_{i=1}^{w} \frac{\prod_{j=1}^{4} \Gamma(c_{i,j} + \beta_{i,j})}{\Gamma(\sum_{j=1}^{4} c_{i,j} + \beta_{i,j})}$$
$$\prod_{k=2}^{L} (\delta_{a_{k-1}+1}(a_{k}))^{\mathbf{1}_{a_{k-1}} \in \{1, \dots, w-1\}} \prod_{k=2}^{L} \theta_{0}^{1-\bar{A}_{k}}(s_{k-1}, s_{k}) \xi_{a_{1}}(s_{1})$$

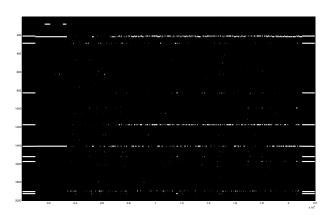


Figure: Location of the motifs retrieved by AEES at each iteration

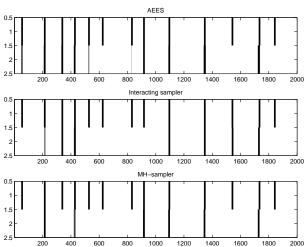


Figure: Average location of the motifs - comparison of 3 algorithms

- If g=1 and  $\theta=\pi^{1-\beta}$ ,  $K_{\theta}$  is a Metropolis-hastings kernel with  $\pi$  as stationary distribution.
- If  $\theta_n$  converges toward  $\pi^{1-\beta}$ , we expect  $P_{\theta_n}$  to converge toward  $P_{\pi^{1-\beta}}$  and  $(X_n)$  to converge toward  $\pi$ , invariant distribution of  $P_{\pi^{1-\beta}}$

## A few notations:

- V-norm of a function  $f:|f|_{V}=\sup_{x\in \mathbf{X}}\frac{|f(x)|}{V(x)}$
- V-norm of a signed measure  $\mu: \|\mu\|_V = \sup_{f,|f|_V \le 1} |\mu(f)|$
- We define the V-variation between  $P_{\theta}$  and  $P_{\theta'}$  by  $D_V(\theta, \theta') = \sup_{x \in \mathbf{X}} \left( \frac{\|P_{\theta}(x,.) P_{\theta'}(x,.)\|_V}{V(x)} \right)$
- Set  $\mathcal{L}_V : \mathcal{L}_V = \{f : \mathbf{X} \to \mathbb{R}, ||f||_V < +\infty\}$
- Target density :  $\pi$
- ullet Temperature of the auxiliary process  $T=rac{1}{1-eta}$

The adaptive EE sampler generates a bivariate process  $(X_n, \theta_n)$   $(\mathcal{F}_n)$ -adapted for the filtration  $(\mathcal{F}_n) = \sigma(Y_1, \ldots, Y_n, X_1, \ldots, X_n)$ , and such that :

$$\mathbb{E}\left[f(X_{n+1})|\mathcal{F}_n\right] = P_{\theta_n}f(X_n)$$

#### Condition on $\pi$ :

- (a)  $\pi$  is the density of a probability distribution on the measurable Polish space  $(\mathbf{X}, \mathcal{X})$  and  $\sup_{\mathbf{X}} \pi < \infty$ .
- (b)  $\pi$  is continuous on X.

## Condition on the proposal distribution P:

- (a) P is a  $\phi$ -irreducible transition kernel which is Feller on  $(\mathbf{X}, \mathcal{X})$  and such that  $\pi P = \pi$ .
- (b) (drift) There exist  $\lambda \in (0,1)$ ,  $b<+\infty$  and  $\tau \in (0,1-\beta)$  such that  $PW \leq \lambda W + b$  with

$$W(x) = \left(\frac{\pi(x)}{\sup_{\mathbf{X}} \pi}\right)^{-\tau} \quad . \tag{1}$$

(c) (small) For all  $p \in (0, \sup_{\mathbf{X}} \pi)$ , the sets  $\{\pi \geq p\}$  are 1-small for P.

## Condition on the auxiliary process

- (a)  $\theta_{\star}(W) < +\infty$ , and for all continuous function f in  $\mathcal{L}_{W}$ ,  $\theta_{n}(f) \to \theta_{\star}(f)$  a.s.
- (b)  $\sup_{n} \mathbb{E}\left[W\left(Y_{n}\right)\right] < \infty$ .

where  $\theta_{\star}$  is the density proportionnal to  $\pi^{1/T}$ .

With these conditions, we prove the "convergence" of our adaptation (only for a 2-level algorithm for the moment):

- (a) For any  $l \in \{1, \dots, S-1\}$ ,  $\lim_n \left| \xi_{\theta_n, l} \xi_{\theta_*, l} \right| = 0$ , w.p.1
- (b) There exists  $\Gamma>0$  such that for any  $k\in\{1,\ldots,K-1\}$ , for any  $l\in\{1,\ldots,S-1\}$ , and any  $\gamma<\Gamma$ ,

$$\limsup_{n} n^{\gamma} |\xi_{\theta_{n+1},I} - \xi_{\theta_{n},I}| < \infty , \mathbb{P} - a.s.$$

## We also prove that:

- For all  $n \in \mathbb{N}$ , the kernel  $P_{\theta_n}$  admits a finite stationnary distribution  $\pi_{\theta_n}$
- For all  $n \in \mathbb{N}$ , there exist some random variables  $C_{\theta_n}$  and  $\rho_{\theta_n}$  such that for all  $x \in \mathbf{X}$ :

$$||P_{\theta_n}^k(x,.) - \pi_{\theta_n}||_V \le C_{\theta_n} \rho_{\theta_n}^k V(x)$$

Finally, this allow to control the V-variation between  $P_{\theta}$  and  $P_{\theta'}$ : on the set  $\bigcap_i \{\theta_i \in \Theta_m\}$ , where

Conclusion

$$\Theta_m = \left\{ \theta \in \Theta : \frac{1}{m} \leq \inf_{x} \int g_{\theta}(x, y) \theta(\mathrm{d}y) \right\} ,$$

there exists a constant  $C_m$  such that

$$\begin{split} &D_{V}(\theta_{k},\theta_{k-1}) \\ &\leq C_{m} \left( \sup_{l} \left| \xi_{\theta_{k},l} - \xi_{\theta_{k-1},l} \right| + \|\theta_{k} - \theta_{k-1}\|_{\text{TV}} \right) (\|\theta_{k}\|_{V} + \|\theta_{k-1}\|_{V}) \\ &+ C_{m} \|\theta_{k} - \theta_{k-1}\|_{V} \; . \end{split}$$

Convergence of the stationnary distributions :

$$\left| \pi_{\theta_{n}(x)}(f) - \pi_{\theta_{\star}(w)}(f) \right| \leq \left| \pi_{\theta_{n}(w)}(f) - P_{\theta_{n}(w)}^{k} f(x) \right|$$

$$+ \left| P_{\theta_{n}(w)}^{k} f(x) - P_{\theta_{\star}(w)}^{k} f(x) \right|$$

$$+ \left| P_{\theta_{\star}(w)}^{k} f(x) - \pi_{\theta_{\star}}(f) \right|$$

#### Control:

- Terms 1 and 3 : controlled with  $\|P_{\theta}^{k}(x,.) \pi_{\theta}\|_{V} \leq C_{\theta} \rho_{\theta}^{k} V(x)$  P-ps
- Term 2 : weak convergence of the kernels  $P_{\theta_n}$  toward  $P_{\theta_{\star}}$ , and equi-continuity of these kernels



## Ergodicity:

$$|\mathbb{E}[f(X_n)] - \pi(f)| \leq \left| \mathbb{E}\left[f(X_n) - P_{\theta_{n-N}}^N f(X_{n-N})\right] \right| + \left| \mathbb{E}\left[P_{\theta_{n-N}}^N f(X_{n-N}) - \pi_{\theta_{n-N}}(f)\right] \right| + \left| \mathbb{E}\left[\pi_{\theta_{n-N}}(f) - \pi(f)\right] \right|$$

#### Control:

- Term 1 : sum of some  $D_V(\theta_{n+j}, \theta_{n+j-1})$
- Term 2 : controlled with  $\|P_{\theta}^k(x,.) \pi_{\theta}\|_{V} \leq C_{\theta} \rho_{\theta}^k V(x)$  P-ps
- Terme 3 : convergence of the stationnary distributions

Strong law of large numbers : The idea is to introduce the solution  $\hat{f}_{\theta}$  of the Poisson equation

$$\hat{f}_{\theta} - P_{\theta} \hat{f}_{\theta} = f - \pi_{\theta}(f)$$

to isolate a martingale term.

$$\frac{1}{n} \sum_{k=0}^{n-1} f(X_k) - L = T_{1,n} + T_{2,n} + T_{3,n} + T_{4,n} + T_{5,n}$$

$$T_{1,n} = \frac{1}{n} \int_{k=1}^{n-1} {\{\hat{f}_{\theta_{k-1}}(X_k) - P_{\theta_{k-1}}\hat{f}_{\theta_{k-1}}(X_{k-1})\}}$$

$$T_{3,n} = \frac{1}{n} \sum_{k=1}^{n-1} {\{P_{\theta_k}\hat{f}_{\theta_k}(X_k) - P_{\theta_{k-1}}\hat{f}_{\theta_{k-1}}(X_k)\}}$$

$$T_{4,n} = \frac{1}{n} P_{\theta_0}\hat{f}_{\theta_0}(X_0) - \frac{1}{n} P_{\theta_{n-1}}\hat{f}_{\theta_{n-1}}(X_{n-1})$$

$$T_{5,n} = \frac{1}{n} \sum_{k=0}^{n-2} {\{\pi_{\theta_{k-1}}(f) - L\}}$$

Term  $T_{2,n}$ :

$$T_{2,n} = \frac{1}{n} \sum_{k=1}^{n-1} \{ \hat{f}_{\theta_{k-1}}(X_k) - P_{\theta_{k-1}} \hat{f}_{\theta_{k-1}}(X_{k-1}) \}$$

 $T_{2,n}$  is a sum of martingale increments. We control it by showing that there exists  $\alpha > 1$  such that

$$\sum_{k=1}^{\infty} k^{-\alpha} \mathbb{E}\left[\left|\left\{\hat{f}_{\theta_{k-1}}(X_k) - P_{\theta_{k-1}}\hat{f}_{\theta_{k-1}}(X_{k-1})\right|^{\alpha} \middle| \mathcal{F}_{k-1}\right] < \infty \text{ as }$$

Term  $T_{3,n}$ :

$$T_{3,n} = \frac{1}{n} \sum_{k=1}^{n-1} \{ P_{\theta_k} \hat{f}_{\theta_k}(X_k) - P_{\theta_{k-1}} \hat{f}_{\theta_{k-1}}(X_k) \}$$

is caused by the adaptation. To control it, we show that  $n^{-1}\sum_{k=1}^n D_V(\theta_k,\theta_{k-1})V(X_k) \to 0$  almost surely.

## In practice:

- Far more efficient than Metropolis-Hastings (mix better)
- Does not require the user to choose the rings

#### But:

- A lot of parameters to choose
- Quite high computational cost

# To go further:

- Extend results of convergence for the empirical quantiles
- Central limit theorem?
- Adaptive proposal