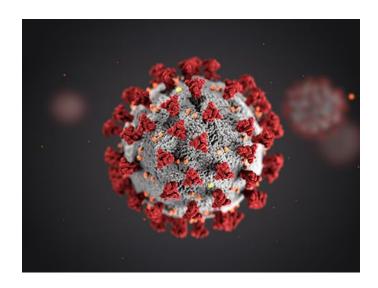


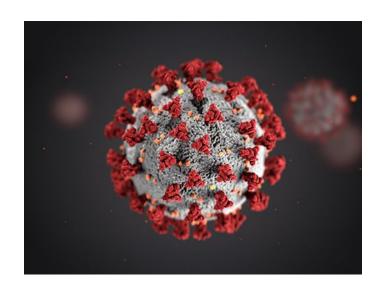
# Modeling Contagion

Nicolò Gozzi, ISI Foundation

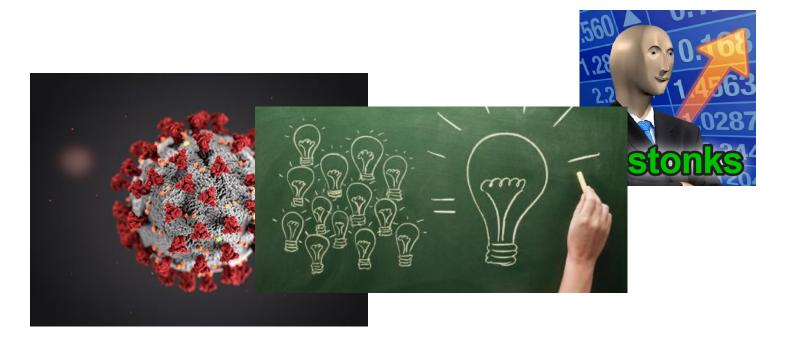


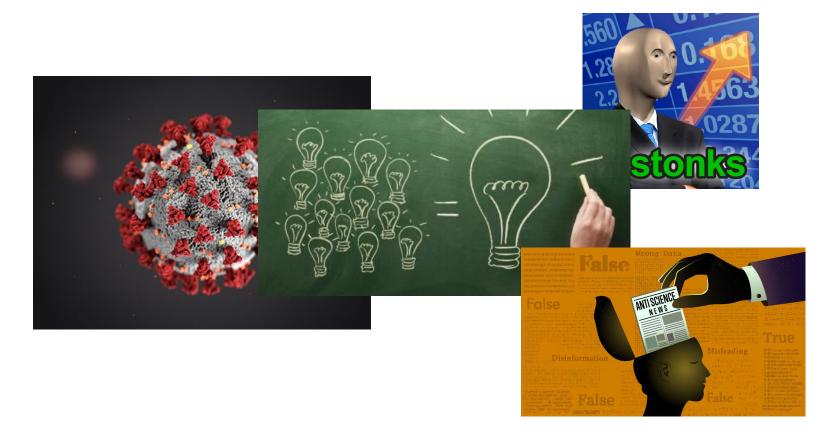




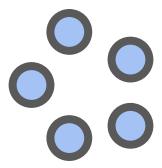






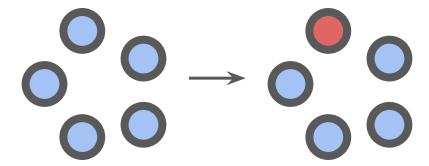


1) Individuals (susceptibles)



1) Individuals (susceptibles)

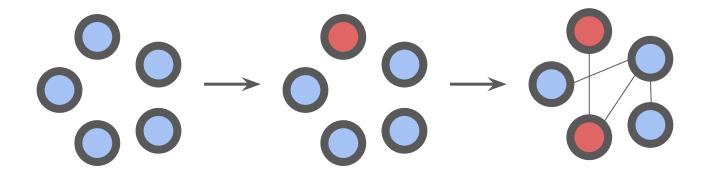
2) Something that *spreads* 



1) Individuals (susceptibles)

2) Something that *spreads* 

3) Interactions



#### Why are complexity scientists interested in Epidemics?

Epidemics are a perfect example of complex systems:

- Phase transitions, tipping points
- Emerging phenomena
- Feedback between spread and behavior
- Simple processes, complex outcomes

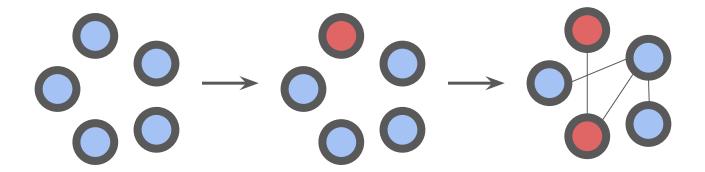


#### Why (Computational) Social Scientists should care about Epidemics?

1) Individuals (susceptibles)

2) Something that *spreads* 

3) Interactions

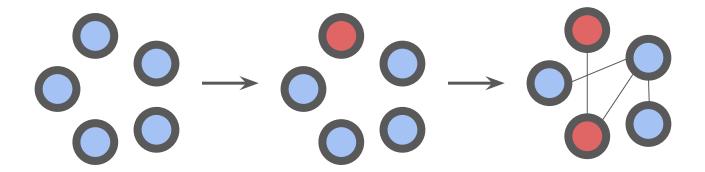


#### Why (Computational) Social Scientists should care about Epidemics?

1) Individuals (susceptibles)

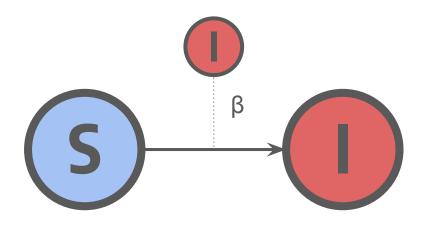
2) Something that *spreads* 

3) Interactions



# Compartmental Models

#### A more detailed example (SI model)

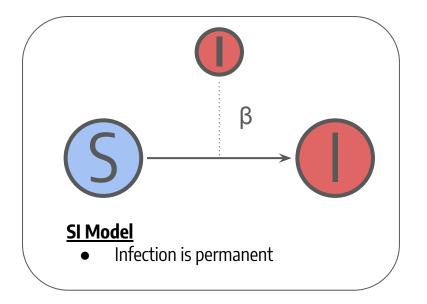


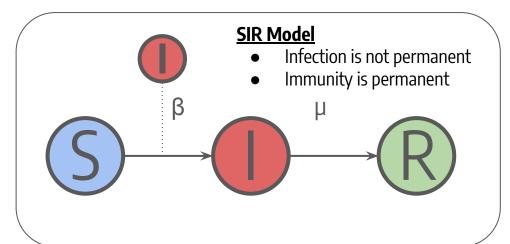
- Susceptible individuals interact with infectious
- With a certain probability β, the interaction leads to new infection

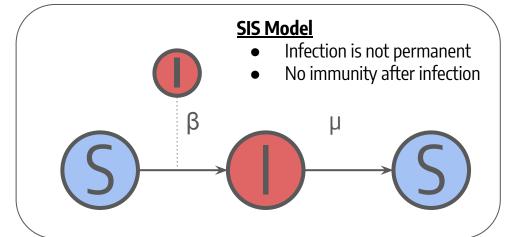
#### Compartmental models

- The framework we have just seen is a compartmental model
- In compartmental models, individuals are divided into compartments (groups) according to their (health) status
- Individuals transition among compartments at given rates
- Transitions can be divided into two main categories:
  - infection processes (they are mediated by infectious agents)
  - spontaneous processes (e.g., recovery)

#### SI, SIR, SIS







#### Compartmental Models as ODEs

- Compartmental models are convenient because they can be easily turned into systems of differential equations (ODE)
- The ODE system describe the evolution in time of number of people in different compartments
- Consider the SIR model:

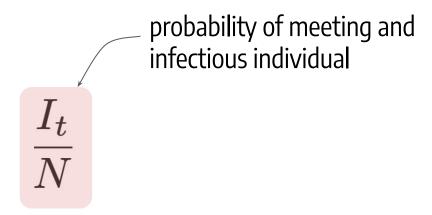
$$\frac{dS_t}{dt} = -\beta C \frac{I_t}{N} S_t$$

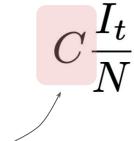
$$\frac{dI_t}{dt} = \beta C \frac{I_t}{N} S_t - \mu I_t$$

$$\frac{dR_t}{dt} = \mu I_t$$

Note: we are assuming that S, I, R are continuous quantities (i.e., we can have 0.5 individuals infected)

What are the factors influencing the force of infection?





The number of contacts an individual has

The infection probability of a single contact  $\beta C \frac{I_t}{\lambda}$ 

$$\beta C \frac{I_t}{N}$$

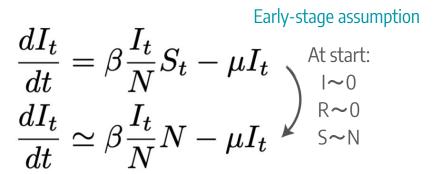
- Main Limitation: Homogeneous Mixing Assumption
- Individuals bump into each other like gas particles (or marbles in a box)
- The force of infection is proportional to the density of infected individuals (mass-action law)

#### Understanding the infection term

$$\beta C \frac{I_t}{N}$$

Disclaimer: in the following we will omit C and when we write "\beta" we implicitly means "\beta \cdot C"

$$\frac{dI_t}{dt} = \beta \frac{I_t}{N} S_t - \mu I_t$$



$$rac{dI_t}{dt} = eta rac{I_t}{N} S_t - \mu I_t$$
 At start:  $| \sim 0 
angle$  At start:  $| \sim 0 
an$ 

$$rac{dI_t}{dt}=etarac{I_t}{N}S_t-\mu I_t$$
 At start:  $lpha = rac{dI_t}{dt}\simeq etarac{I_t}{N}N-\mu I_t$  At start:  $lpha = 0$  R  $\sim 0$  S  $\sim N$  At start:  $lpha = 0$  R  $\sim 0$  S  $\sim N$ 

$$\frac{dI_t}{dt} \simeq (\beta - \mu)I_t$$

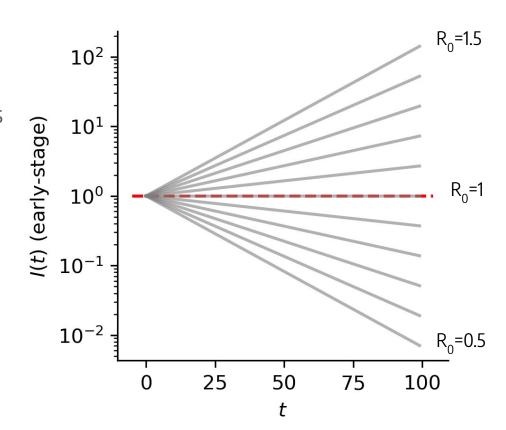
$$\frac{dI_t}{dt} = \beta \frac{I_t}{N} S_t - \mu I_t$$
 At start: 
$$\frac{dI_t}{dt} \simeq \beta \frac{I_t}{N} N - \mu I_t$$
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 At start: 
$$\frac{dI_t}{dt} \simeq \beta I_t - \mu I_t$$
 At start: 
$$\frac{dI_t}{dt} \simeq \mu (\beta - \mu) I_t$$
 Define: 
$$\frac{dI_t}{dt} \simeq \mu (R_0 - 1) I_t$$
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 Define: 
$$\frac{dI_t}{dt} \simeq \beta I_t - \mu I_t$$
 
$$\frac{dI_t}{dt} \simeq \mu (R_0 - 1) I_t$$

$$I(t) = I_0 e^{\mu(R_0 - 1)}$$

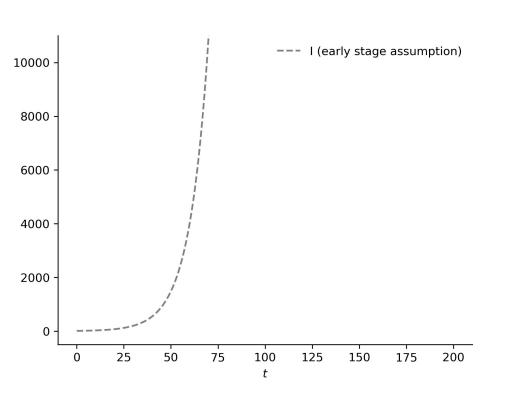
#### Interpreting R<sub>0</sub>

- R<sub>0</sub> is the number of secondary infections generated by a infected case in a fully susceptible population of infinite size
- In practice, if R<sub>0</sub> > 1 the epidemics will grow, if R<sub>0</sub> < 1 it will decrease</li>
- Think of it as the number of offsprings needed to maintain the size of a population



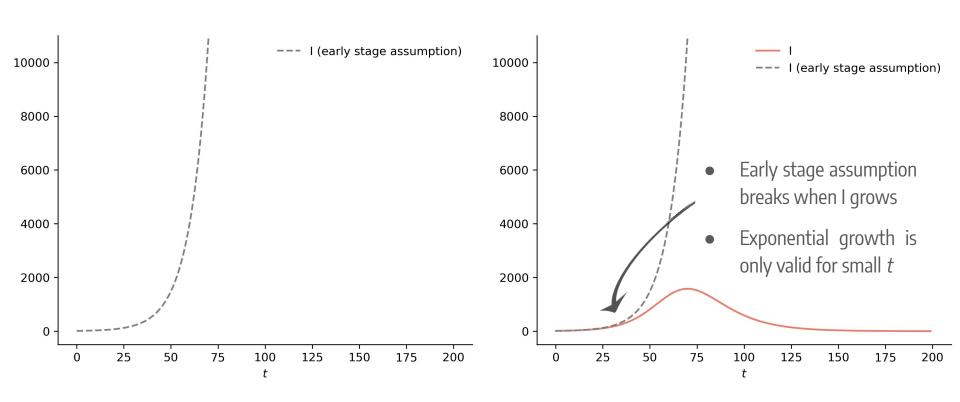
## $I(t) = I_0 e^{\mu(R_0 - 1)}$

#### Testing the early stage assumption

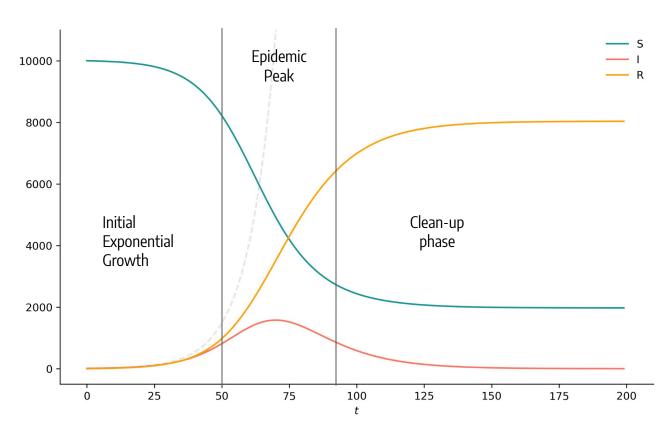


If we plot the solution for I(t) this is what we got, the number of infected grows indefinitely...

#### Testing the early stage assumption



#### **Epidemic Phases**

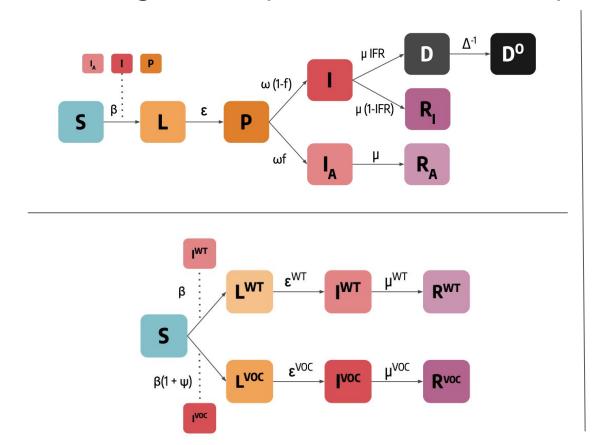


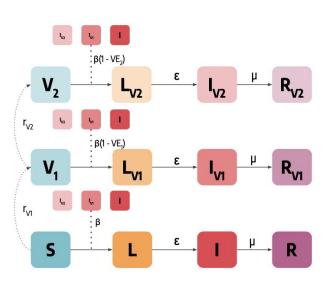
#### Extending the Compartments

The compartmental structure can be changed and adapted according to the phenomenon we are studying:

Compartments for Vaccinated, Asymptomatic, Pre-Symptomatic, Hospitalized, ...

#### Extending the Compartments - More Complex Disease



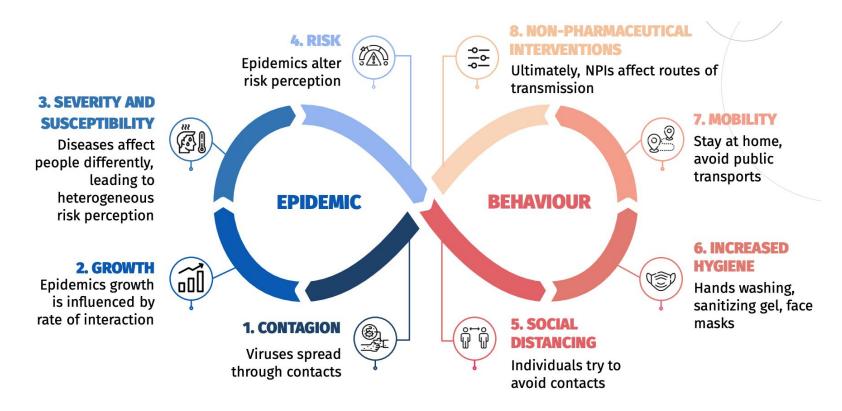


#### Extending the Compartments

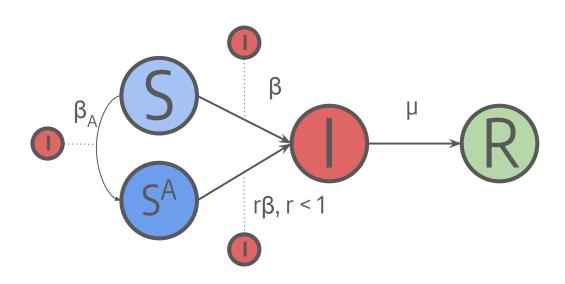
The compartmental structure can be changed and adapted according to the phenomenon we are studying:

- Compartments for Vaccinated, Asymptomatic, Pre-Symptomatic, Hospitalized, ...
- Compartments may represent also "behavioral" classes:
  - o Individuals may be more or less suceptible to the "virus" (behavioral preventive measures, level of information, gullibility, etc)

#### Epidemic-Behavior Feedback Loop

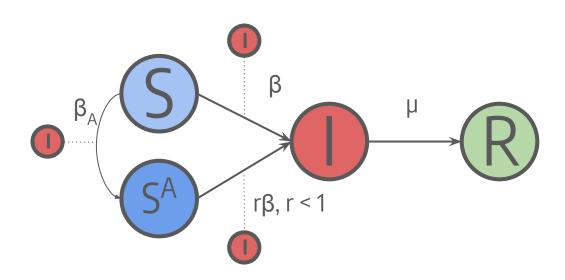


#### Extending the Compartments - Behavioral Information



- Compartments can also represent "behavioral" classes
- For example, some individuals may be less susceptible due to behavior change / awareness

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**ODE System** 

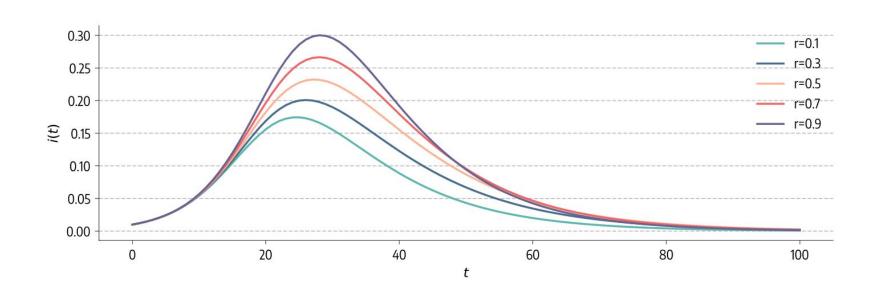
$$\frac{dS_t}{dt} = -\beta \frac{I_t}{N} S_t - \beta_A \frac{I_t}{N} S_t$$

$$\frac{dS_t^A}{dt} = -r\beta \frac{I_t}{N} S_t^A + \beta_A \frac{I_t}{N} S_t$$

$$\frac{dI_t}{dt} = \beta \frac{I_t}{N} S_t + r\beta \frac{I_t}{N} S_t^A - \mu I_t$$

$$\frac{dR_t}{dt} = \mu I_t$$

#### Extending the Compartments - Behavioral Information



#### A note on Machine Learning Models

- What we considered so far are Mechanistic Models
- In a Mechanistic model, we explicitly encode the *physics* of the problem
- In a Statistical model, we learn the mechanisms behind the system from the data
- Main pro of mechanistic model: easy to run counterfactuals ("what if tomorrow  $R_o$  is 2x?")

### Technical Aspects

#### Simulation

- We can derive analytically some interesting characteristics of the system (such as R<sub>0</sub>)
- But when the system becomes more complicated simulation become essential
- Simulation: writing a computer program that simulates the system

#### **Deterministic and Stochastic Simulations**

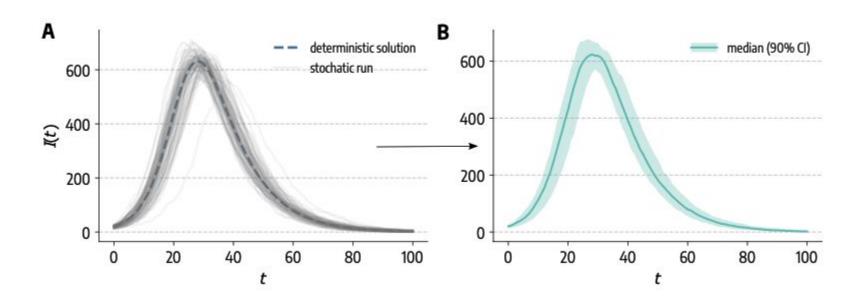
#### **Deterministic Simulations**

- Numerical integration of the system of ODEs
- Pros:
  - Easy to implement, can leverage all methods for ODE system integration
  - Faster
  - For a given set of parameters and initial conditions 1 run is enough
- Cons:
  - No uncertainty
  - Number of individuals is approximated as a continuous quantity

#### **Stochastic Simulations**

- Simulate transitions among compartments via probabilistic sampling
- Pros:
  - Allow to include uncertainty (important especially for scenarios, forecast, early stage)
- Cons:
  - Multiple runs needed
  - Slower

#### **Deterministic and Stochastic Simulations**



#### Deterministic Simulation - Python Implementation (i)

In order to be represented in a programming language, equations must be discretized in time, according to the well-known Euler method:

$$\frac{dy}{dt} \simeq \frac{y(t + \Delta t) - y(t)}{\Delta t}$$

For the SIR Model:

$$\frac{S(t + \Delta t) - S(t)}{\Delta t} = -\beta \frac{I(t)}{N} S(t)$$

$$\frac{I(t + \Delta t) - I(t)}{\Delta t} = \beta \frac{I(t)}{N} S(t) - \mu I(t)$$

$$\frac{R(t + \Delta t) - R(t)}{\Delta t} = \mu I(t)$$

#### Deterministic Simulation - Python Implementation (ii)

Last expressions provide us with a convenient recursive formula to get the number of individuals in different compartments in the next step:

$$S(t + \Delta t) = S(t) - \beta \frac{I(t)}{N} S(t) \Delta t$$

$$I(t + \Delta t) = I(t) + (\beta \frac{I(t)}{N} S(t) - \mu I(t)) \Delta t$$

$$R(t + \Delta t) = R(t) + \mu I(t) \Delta t$$

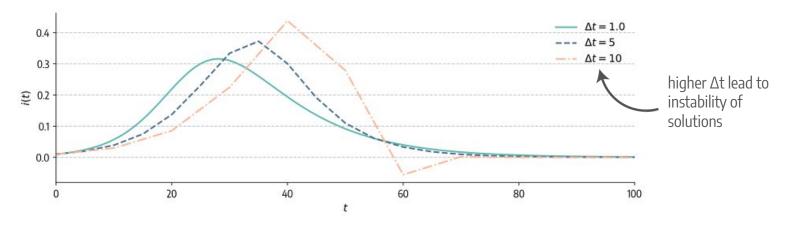
Setting initial conditions S(0),I(0),R(0), one can iteratively apply these equations to find  $S(1),I(1),R(1),\ldots S(T),I(T)$ , R(T)

# Deterministic Simulation - Python Implementation (iii)

```
SIR deterministic(beta: float,
                  mu : float.
                  N : int,
                  dt : float = 1.0,
                  I0_frac : float = 0.01,
                  T : int = 100):
This function numerically integrates the system of ODEs defining the SIR model
Parameters
- beta (float): transmission rate
- mu (float): recovery rate
- N (int): population size
- dt (float, optional): integration step. Default is 1.0.
- IO_frac (float, optional): initial fraction of infected. Default is 0.01 (1%).
- T (int, optional): simulation length in steps. Default is 100.
Returns
- evolution of S, I, R compartments
I0 = int(N * I0 frac)
S, I, R, t = [N - I0], [I0], [0], [0]
for i in range(T):
    new_infected = (S[-1] * beta * I[-1] / N) * dt
    new recovered = (I[-1] * mu) * dt
    S.append(S[-1] - new_infected)
    I.append(I[-1] + new infected - new recovered)
    R.append(R[-1] + new_recovered)
    t.append(t[-1] + dt)
return np.array(S), np.array(I), np.array(R), np.array(t)
```

#### Deterministic Simulation - Python Implementation (iv)

The choose of  $\Delta t$  can influence the results:



- As a rule of thumb, smaller  $\Delta t$  lead to more accurate results but slower simulations
- More sophisticated techniques can be used to overcome the issue of the stability of the solutions, such as the Runge-Kutta or Jacobi methods

#### Stochastic Simulation - Python Implementation (i)

Stochastic simulations provide a framework for a more realistic representation of the dynamics of the system under study. Indeed, transitions among compartments are intrinsically probabilistic events:

- At each time step, the number of individuals transitioning among compartments (during  $\Delta t$ ) is sampled from a probability distribution
- After the sampling step, the number of individuals in different compartments is updated to reflect the transitions.
- This process is repeated iteratively to get the time evolution of different compartments.

A common approach to represent the discrete and stochastic nature of transitions among compartments is through chain binomial processes.

#### Stochastic Simulation - Python Implementation (ii)

SIR model algorithm:

- 1. Initialize the number of individuals in different compartments:  $S_{t_0}$ ,  $I_{t_0}$ ,  $R_{t_0}$
- 2. For t in range(0, T):
  - Sample the number of newly infected individuals:  $infected_t = Bin(S_t, \beta \frac{I_t}{N} \Delta t)$
  - Find the number of newly recovered individuals:  $recovered_t = Bin(I_t, \mu \Delta t)$
  - Update next step compartments to reflect transitions:  $S_{t+1} = S_t infected_t$ ,  $I_{t+1} = I_t + infected_t recovered_t$ ,  $R_{t+1} = R_t + recovered_t$
- 3. Return the sequences of  $S_t$ ,  $I_t$ ,  $R_t$

# Stochastic Simulation - Python Implementation (iii

```
def SIR_stochastic(beta : float,
                  mu : float,
                  N : int,
                  dt : float = 1.0,
                  I0_frac : float = 0.01,
                  T : int = 100):
    This function runs a stochastic simulation of the SIR model
    Parameters
    - beta (float): transmission rate
    - mu (float): recovery rate
    - dt (float, optional): integration step. Default is 1.0.
    - IO frac (float, optional): initial fraction of infected. Default is 0.01 (1%).
    - T (int, optional): simulation length in steps. Default is 100.
    Returns
    - evolution of S, I, R compartments
    I0 = np.random.binomial(N, I0_frac)
   S, I, R, t = [N - I0], [I0], [0], [0]
    for i in range(T):
       new infected = np.random.binomial(S[-1], beta * I[-1] / N * dt)
       new_recovered = np.random.binomial(I[-1], mu * dt)
       S.append(S[-1] - new_infected)
       I.append(I[-1] + new_infected - new_recovered)
       R.append(R[-1] + new_recovered)
       t.append(t[-1] + dt)
    return np.array(S), np.array(I), np.array(R), np.array(t)
```

#### **Model Calibration**

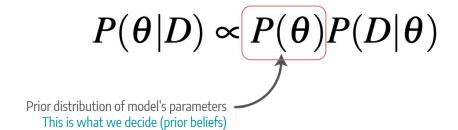
We have a model, we have data, so what? **→Model Calibration** 

- Estimating the parameters of the mathematical model from the data
- Epidemic models depend on a range of parameters ( $\beta$ ,  $\mu$ , ...):
  - The values of some of them can be informed considering the literature
  - The remaining free parameters need to be determined through a statistical procedure based on the data the model is trying to reproduce

- The main concept of Bayesian inference is the idea of updating beliefs with new evidence
- Within the Bayesian framework, the parameters of a model are considered as random variables characterized by probability distributions, rather than exact values
- These ideas are condensed in the famous Bayes theorem:

$$P(\theta|D) \propto P(\theta)P(D|\theta)$$

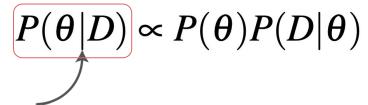
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- The main concept of Bayesian inference is the idea of updating beliefs with new evidence
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- These ideas are condensed in the famous Bayes theorem:



Posterior distribution of model's parameters This is what we want to get

- In practice, the Bayes theorem is rarely applied directly to get the expression of  $P(\theta|D)$
- Indeed, apart from trivial cases, it is hard to get an analytical expression for  $P(D|\theta)$
- This is where Approximate Bayesian Computation (ABC) techniques come into play
- The goal of ABC is to estimate the posterior distribution of the parameters without computing the likelihood function

#### A simple ABC technique: the Rejection Algorithm

This algorithm accepts proposed parameter values (also named *particles*) if a distance metric d between the real (D) and the model simulated (D\*) data is less than or equal to a predefined threshold  $\delta$ . In steps:

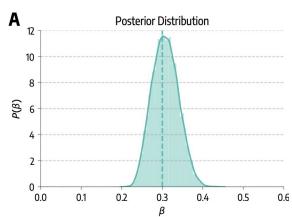
- 1. sample a parameter set  $\theta^*$  from the prior distribution  $P(\theta)$ ;
- 2. create an instance of the model using  $\theta^*$  and simulate to get  $D^*$ ;
- 3. if  $d(D,D^*) \leq \delta$  accept the proposed parameter set  $\theta^*$ , otherwise reject it.
- 4. repeat until N particles  $\theta^*$  are accepted.

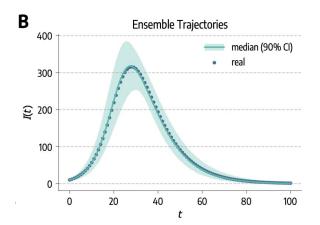
The N accepted samples are an approximation of the actual posterior distribution of model parameters

#### ABC Rejection Algorithm: Practical Example

We want to find the posterior distribution of  $\beta$  using a stochastic SIR model

- We set a uniform prior on the only free parameter  $\beta \sim U(0.01,0.6)$
- As distance metric, we use the weighted mean absolute percentage error on the number of infected at each time step t
- We set a threshold  $\delta$  = 0.25 and we run 10,000 iterations of the ABC-rejection algorithm
- Other parameters are set to μ = 0.1, total number of individuals N = 1000, initial fraction of infected 1%





## ABC Rejection Algorithm: Python Code

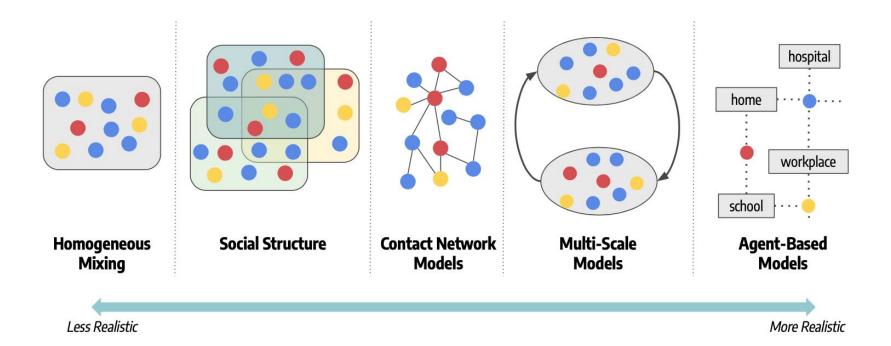
```
def ABC_rejection(Nsim : int,
                  th : float,
                  realI : List[float],
                  params : dict):
    This function runs a simple ABC rejection algorithm
    Parameters
    - Nsim (int): total number of simulations to run
    - th (float): acceptance/rejection threshold
    - realI (List[float]): list of actual number infected in time
    - params (dict): dictionary of model parameters
   Returns:
    - accepted parameters and sampled trajectories
    accepted_params, sampledI = [], []
    for n in range(Nsim):
        beta = np.random.uniform(0.01, 0.6)
        S, I, R, t = SIR stochastic(beta, **params)
        if wmape(realI, I) < th:</pre>
            accepted params.append(beta)
            sampledI.append(I)
    return np.array(accepted_params), np.array(sampledI)
```

#### Advanced ABC: The ABC-SMC Algorithm

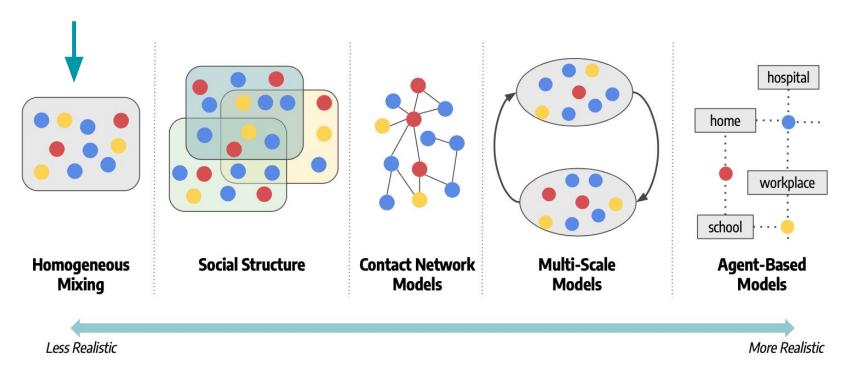
- The simple rejection algorithm is easy to implement but slow to converge
- Indeed, the information from previous iterations is not integrated into the next ones.
- The ABC-SMC algorithm solves this issue (SMC stands for Sequential Monte Carlo) by implementing iteratively the rejection algorithm
- In the initial step a high tolerance is used, this will lead to the exclusion of very unlikely parameters
- At next steps, the tolerance is lowered and the prior distribution will we constituted by the parameters accepted in the previous step (perturbed via a kernel function)

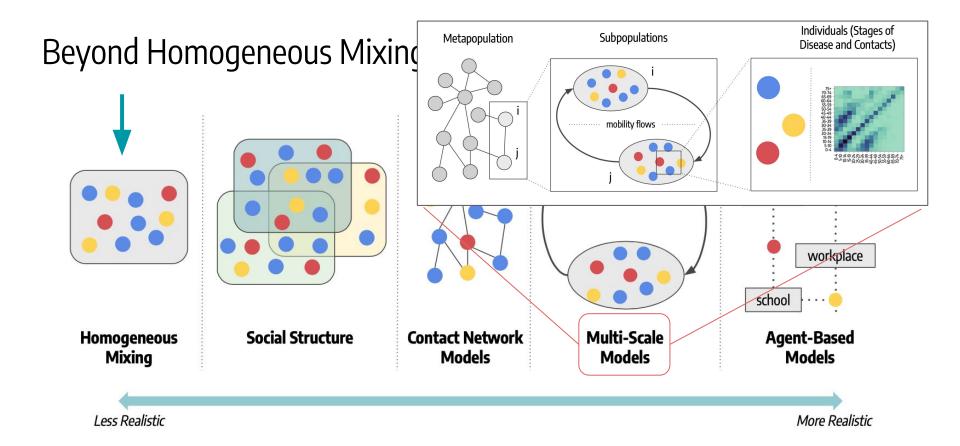
### Beyond Homogeneous Mixing

#### Beyond Homogeneous Mixing

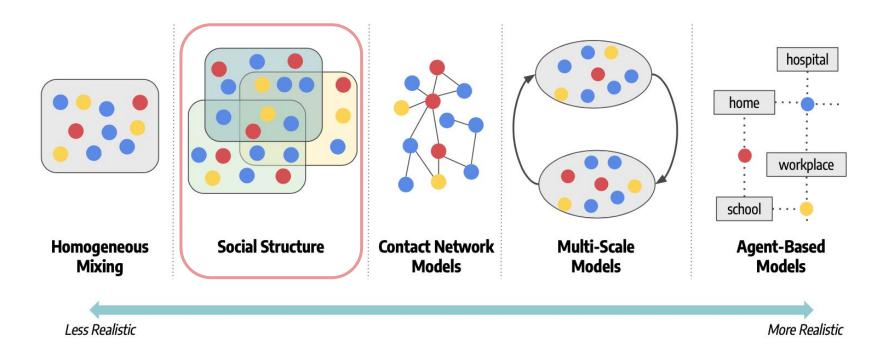


#### Beyond Homogeneous Mixing





#### Beyond Homogeneous Mixing



#### Adding a Social Structure to Compartmental Models

- Consider a society formed by two groups of individuals (A and B)
- The two groups mix at different rates (homophily)
- Contacts can be represented with a matrix:

$$C = \begin{pmatrix} C_{AA} & C_{AB} \\ C_{BA} & C_{BB} \end{pmatrix}$$

#### Adding a Social Structure to Compartmental Models

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- Contacts can be represented with a matrix:

$$C = \begin{pmatrix} C_{AA} & C_{AB} \\ C_{BA} & C_{BB} \end{pmatrix}$$

Number of contacts that an individual of group A has, on average, with an individual of group B (in a day)

#### Adding a Social Structure to Compartmental Models

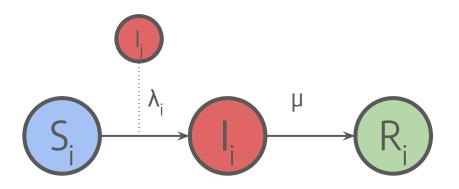
- Consider a society formed by two groups of individuals (A and B)
- The two groups mix at different rates (homophily)
- Contacts can be represented with a matrix:

$$C = \begin{pmatrix} C_{AA} & C_{AB} \\ C_{BA} & C_{BB} \end{pmatrix}$$

Number of contacts that an individual of group A has, on average, with an individual of group B (in a day)

Is C symmetric? (i.e., is  $C_{AB} = C_{BA}$ ?)

#### Extending the SIR model to a complex social structure



What is the expression of the Force of Infection  $(\lambda_i)$  now?

• We were starting from:

$$eta Crac{I}{N}$$

But now C is a matrix and we have K groups:

$$\lambda_i = \beta \sum_{j=1}^K C_{ij} \frac{I_j}{N_j}$$

#### Extending the SIR model to a complex social structure

The equation system will now have  $3 \times K$  equations (3 compartments, K groups):

$$\frac{dS_i}{dt} = -\beta \sum_{j=1}^K C_{ij} \frac{I_j}{N_j} S_i$$

$$\frac{dI_i}{dt} = \beta \sum_{j=1}^K C_{ij} \frac{I_j}{N_j} S_i - \mu I_i$$

$$\frac{dR_i}{I_i} = \mu I_i$$

#### Extending the SIR model to a complex social structure

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$$egin{aligned} rac{dS_i}{dt} &= -eta \sum_{j=1}^K C_{ij} rac{I_j}{N_j} S_i \ rac{dI_i}{dt} &= eta \sum_{j=1}^K C_{ij} rac{I_j}{N_j} S_i - \mu I_i \ rac{dR_i}{I_i} &= \mu I_i \end{aligned}$$

The  $R_0$  is now:

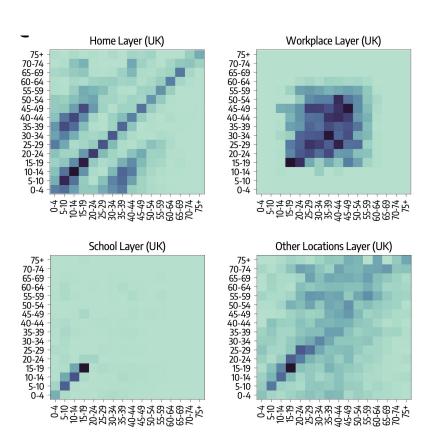
$$R_0 = \rho(\tilde{C}) \frac{\beta}{\mu}$$

Where  $\rho(\cdot)$  indicates the spectral radius (i.e., the largest eigenvalue) and "C tilde" is the contact matrix weighted by the number of individuals in different groups

#### Example: Age Structure

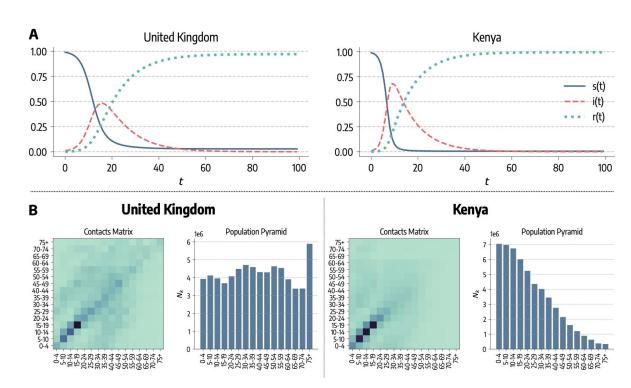
A common approach is to introduce a contact matrix describing contacts among different age groups:

- Contacts among age groups correlates with the setting of the contact
- Age is also generally an important risk factor (disease)



#### Example: Age Structure

- Age distribution and contacts significantly vary among context
- We run SIR model with same parameters but different demographics (UK and Kenya)



#### Conclusions

- Epidemics are social phenomena
- Three ingredients: individuals, something that spread, interactions
- Build on simple models
- Implementation is as important as theory (simulation, calibration)