

Electrochemistry

Peifeng Wu

Dec 2024

1 Introduction

An electrochemical reaction is a chemical reaction caused by an externally supplied current, such as oxidation-reduction reactions. Linear sweep and cyclic voltammetry represent the most common types of potentiodynamic electrochemical measurement[1]. In the case of linear sweep voltammetry, the potential is swept linearly with time whereas in the case of cyclic voltammetry, after the pre-determined potential is reached, the working electrode's potential is swept in the opposite direction to return to the initial potential.

2 Chronoamperometry

2.1 Equations

I consider mass transport of chemical species to the electrode to be a one-dimensional diffusion process[2], which can be expressed as:

$$\frac{\partial c_s}{\partial t} = D_s \frac{\partial^2 c_s}{\partial x^2} \quad (1)$$

where x is the distance from electrode surface, t is time, $c_s(x, t)$ is the concentration of chemical species and D_s is the diffusion constant. Assume initially only one chemical species of A exists and oxidation reaction occurs at the electrode surface



where k_1 , k_2 are rate constants that depend on the applied potential. Intuitively the current at the electrode surface is given by

$$I(t) = \left(\frac{\partial a}{\partial x} \right)_{x=0} \quad (3)$$

In the case of Chronoamperometry, the potential is stepped at $t = 0$ to ensure complete conversion of A to B at the electrode surface. Therefore I have the following set of

equations:

$$\frac{\partial a}{\partial t} = D_a \frac{\partial^2 a}{\partial x^2}, \quad \frac{\partial b}{\partial t} = D_b \frac{\partial^2 b}{\partial x^2} \quad (4)$$

$$D_a \frac{\partial a}{\partial x} = -D_b \frac{\partial b}{\partial x} \quad \text{at } x = 0 \quad (5)$$

$$a(x, 0) = a^*, \quad b(x, 0) = 0 \quad (6)$$

$$a(x, t) \rightarrow a^*, \quad b(x, t) \rightarrow 0 \quad \text{as } t \rightarrow \infty \quad (7)$$

$$a(0, t) = 0 \quad (8)$$

If I assume $D_a = D_b$ and nondimensionalise the model, I obtain

$$\frac{\partial a}{\partial t} = \frac{\partial^2 a}{\partial x^2} \quad (9)$$

$$a(x, 0) = 1 \quad (10)$$

$$a(x, t) \rightarrow 1 \quad \text{as } x \rightarrow \infty \quad (11)$$

$$a(0, t) = 0 \quad (12)$$

$$a + b = 1 \quad (13)$$

b can be easily computed once a is solved

2.2 Exact Solutions

The analytic solution of a can be obtained via similarity solution, setting

$$a = f(\eta), \quad \eta = \frac{x}{\sqrt{t}} \quad (14)$$

substitute this into the set of equations above, I obtain:

$$f'' + \frac{\eta}{2} f' = 0 \quad (15)$$

$$f(\eta) \rightarrow 1 \quad \text{as } \eta \rightarrow \infty \quad (16)$$

$$f(0) = 0 \quad (17)$$

therefore

$$a(x, t) = f(\eta) = \frac{2}{\sqrt{\pi}} \int_0^{\frac{\eta}{2}} e^{-s^2} ds = \frac{2}{\sqrt{\pi}} \int_0^{\frac{x}{2\sqrt{t}}} e^{-s^2} ds \quad (18)$$

Alternatively I could use the method of Laplace transform. Let \tilde{a} denote the Laplace transform of a . If I apply Laplace transform on equation (9) I have:

$$\frac{\partial^2 \tilde{a}}{\partial x^2}(x, s) - s\tilde{a}(x, s) = -1 \quad (19)$$

therefore

$$\tilde{a}(x, s) = A(s)e^{\sqrt{s}x} + B(s)e^{-\sqrt{s}x} + \frac{1}{s} \quad (20)$$

Substituting boundary conditions:

$$a(0, t) = 0 \Rightarrow \tilde{a}(0, s) = 0 \Rightarrow A(s) + B(s) + \frac{1}{s} = 0 \quad (21)$$

$$\lim_{x \rightarrow \infty} a(x, t) = 1 \Rightarrow \lim_{x \rightarrow \infty} \tilde{a}(x, s) = \frac{1}{s} \Rightarrow A(s) = 0, B(s) = -\frac{1}{s} \quad (22)$$

$$a(x, 0) = 1 \Rightarrow \lim_{s \rightarrow 0} \tilde{a}(x, s) = \lim_{s \rightarrow 0} \frac{1}{s}(1 - e^{-\sqrt{s}x}) = \frac{1}{s} \quad (23)$$

Therefore $\tilde{a}(x, s)$ is given by:

$$\tilde{a}(x, s) = \frac{1}{s}(1 - e^{-\sqrt{s}x}) \quad (24)$$

Apply inverse Laplace transform I obtain:

$$a(x, t) = \frac{2}{\sqrt{\pi}} \int_0^{\frac{x}{2\sqrt{t}}} e^{-s^2} ds \quad (25)$$

which is same as equation (18).

2.3 Numerical Solution

The numerical solution of a and b can be solved by the method of finite differences. Plots of a and b are given in Figure 1 and Figure 2 respectively.

3 Linear Sweep Voltammetry

3.1 Equations

Now I consider the case that the applied potential varies linearly with time. In such case, after the nondimensionalisation procedure, at the point of $x = 0$ I have

$$\frac{\partial a}{\partial x} = k_1 a - k_2(1 - a) \quad (26)$$

where

$$k_1 = k_0 e^{(1-\alpha)(E(t)-E_0)} \quad (27)$$

$$k_2 = k_0 e^{-\alpha(E(t)-E_0)} \quad (28)$$

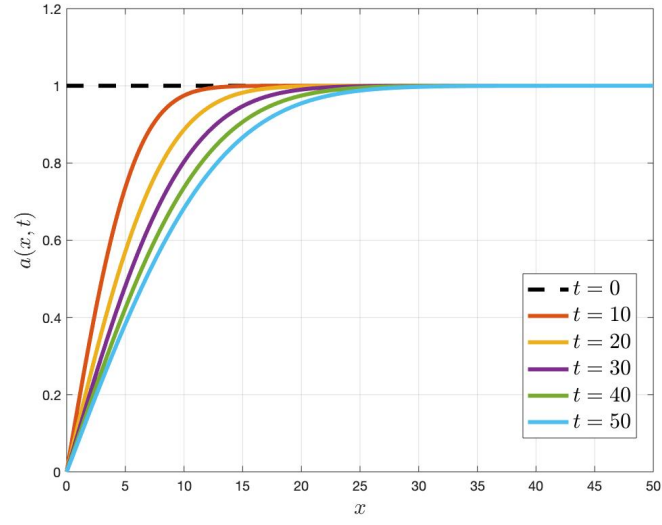


Figure 1: Plot of a at different times in chronoamperometry

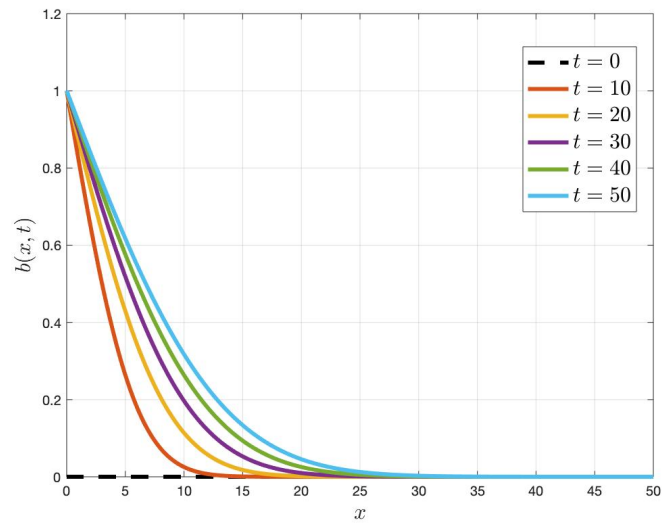


Figure 2: Plot of b at different times in chronoamperometry

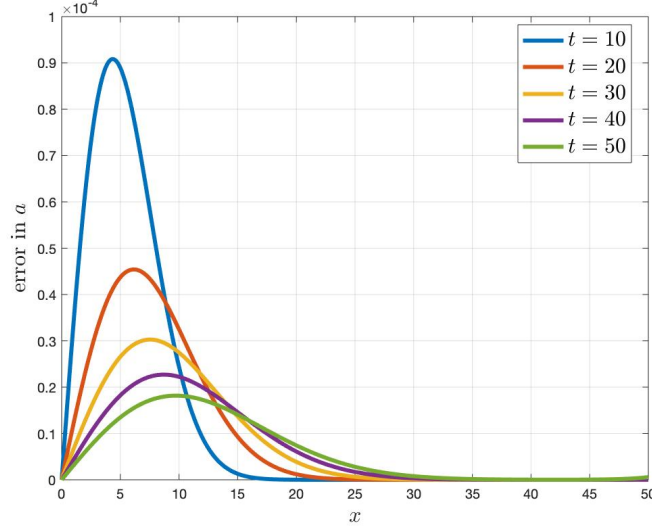


Figure 3: Absolute error between analytic and numerical results of a in chronoamperometry

$E(t)$ is the applied potential, E_0 is the formal potential which depends on the chemical species, k_0 is the heterogeneous rate constant and α is the charge transfer constant. In the case of linear sweep voltammetry

$$E(t) = E^* + t \quad (29)$$

where E^* denotes the initial potential. If a cyclic voltammetry is applied, where $E(t)$ is given by:

$$E(t) = \begin{cases} E^* + t & 0 \leq t \leq t^* \\ E^* + 2t^* - t & t^* \leq t \leq 2t^* \end{cases} \quad (30)$$

I expect the current to show cyclic behaviour as Figure 5 shows.

3.2 Integral Equation

I posit that the following equation holds:

$$\frac{\sqrt{\pi}}{1 + e^{-(E(t)-E_0)}} = \int_0^t \frac{I(\tau)}{\sqrt{t-\tau}} d\tau \quad (31)$$

This is the integral equation and I shall prove its validity. In the case of linear sweep voltammetry, $I(0) = 0$. Integrating the right hand side of the equation by parts:

$$\int_0^t \frac{I(\tau)}{\sqrt{t-\tau}} d\tau = \int_0^t 2\sqrt{t-\tau} I'(\tau) d\tau \quad (32)$$

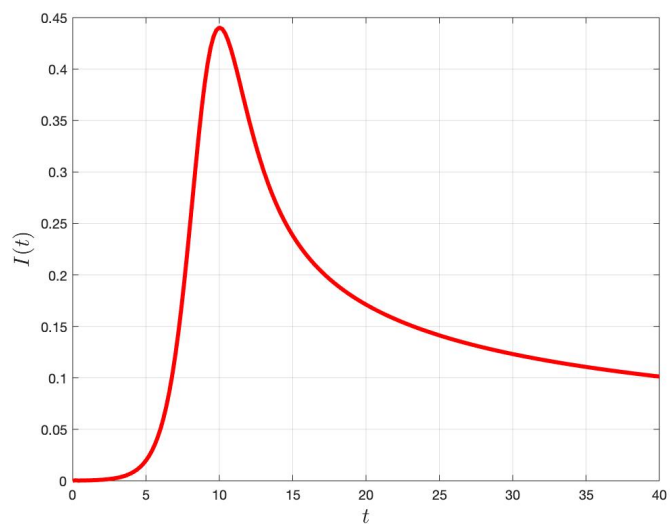


Figure 4: Current with respect to time when a linear sweep voltammetry is applied, $(E^*, E_0, k_0, \alpha) = (-10, -1, 35, 0.5)$

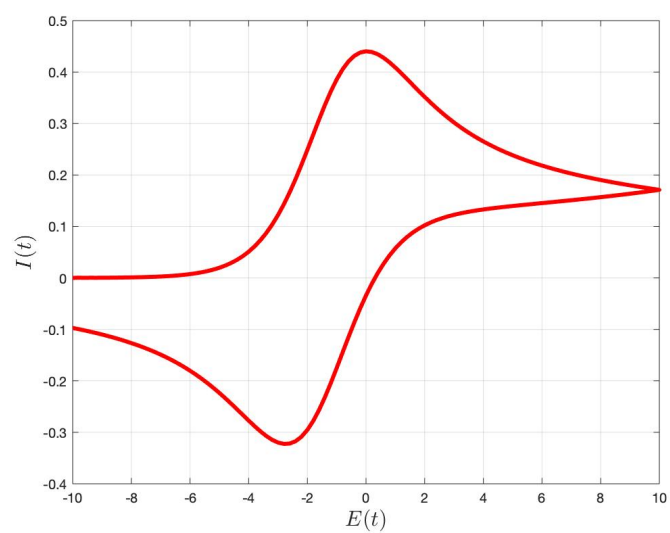


Figure 5: Current with respect to time when a cyclic voltammetry is applied, $(E^*, E_0, k_0, \alpha) = (-10, -1, 35, 0.5)$

Taking Laplace transform of equation (32) and apply the convolution theorem I have:

$$L[2\sqrt{t} * I'(t)] = 2L[\sqrt{t}]L[I'(t)] = \tilde{I}(s)\sqrt{\frac{\pi}{s}} \quad (33)$$

where $\tilde{I}(s)$ denotes the Laplace transform of $I(t)$ and $*$ denotes convolution. The Laplace transform of the current is given by:

$$I(t) = \left(\frac{\partial a}{\partial x} \right)_{x=0} \Rightarrow \tilde{I}(s) = \left(\frac{\partial \tilde{a}}{\partial x} \right)_{x=0} \quad (34)$$

The general form of $\tilde{a}(x, s)$ is given by equation (20), apply the far field boundary condition:

$$\lim_{x \rightarrow \infty} a(x, t) = 1 \Rightarrow \lim_{x \rightarrow \infty} \tilde{a}(x, s) = \frac{1}{s} \Rightarrow A(s) = 0 \quad (35)$$

Hence $\tilde{I}(s)$ is given by:

$$\tilde{I}(s) = \left(\frac{\partial \tilde{a}}{\partial x} \right)_{x=0} = - \left(\sqrt{s} B(s) e^{-\sqrt{s}x} + \frac{1}{s} \right)_{x=0} \quad (36)$$

Therefore

$$B(s) = -\frac{\tilde{I}(s)}{\sqrt{s}} \quad (37)$$

Combining equation (31) and equation (37) gives:

$$\tilde{a}(0, s) = -\frac{\tilde{I}(s)}{\sqrt{s}} + \frac{1}{s} \quad (38)$$

Apply inverse Laplace transform to equation (38) and use the relation given by equation (33) I obtain:

$$L^{-1}[\tilde{a}(0, s)] = -\frac{1}{\sqrt{\pi}} \int_0^t \frac{I(\tau)}{\sqrt{t-\tau}} d\tau + 1 \quad (39)$$

Moreover, equation (26) can be rearranged to show that:

$$a(0, t) = \frac{1}{e^{E(t)-E_0} + 1} \quad (40)$$

Equating equation (39) and equation (40) I obtain the integral equation.

3.3 Numerical Solution of Integral Equation

Remember that the integral equation is given by:

$$\frac{\sqrt{\pi}}{1 + e^{-(E(t)-E_0)}} = \int_0^t \frac{I(\tau)}{\sqrt{t-\tau}} d\tau \quad (41)$$

where $E(t)$ is a known function and $I(0) = 0$. Integrate the right hand side of the equation gives:

$$\int_0^t \frac{I(\tau)}{\sqrt{t-\tau}} d\tau = \int_0^t 2\sqrt{t-\tau} I'(\tau) d\tau \quad (42)$$

I notice that the right hand side of equation (42) is a Volterra integral equation of the first kind:

$$f(t) = \int_0^t K(t, \tau) \phi(\tau) d\tau \quad (43)$$

where

$$f(t) = \frac{\sqrt{\pi}}{1 + e^{-(E(t)-E_0)}}, \quad K(t, \tau) = 2\sqrt{t-\tau}, \quad \phi(\tau) = I'(\tau) \quad (44)$$

By trapezium rule the Volterra equation can be approximated by:

$$\int_0^t K(t, \tau) \phi(\tau) d\tau \approx \frac{\Delta t}{2} [K(t, 0)\phi(0) + 2K(t, \tau_1)\phi(\tau_1) + 2K(t, \tau_2)\phi(\tau_2) + \dots + K(t, \tau_n)\phi(\tau_n)] \quad (45)$$

where

$$0 < \tau_1 < \tau_2 < \dots < \tau_n = t, \quad \Delta t = \tau_{i+1} - \tau_i \quad (46)$$

Therefore I have a system of equations given by:

$$f(\tau_1) = \frac{\Delta \tau}{2} [K(\tau_1, 0)\phi(0) + K(\tau_1, \tau_1)\phi(\tau_1)] \quad (47)$$

$$f(\tau_2) = \frac{\Delta \tau}{2} [K(\tau_2, 0)\phi(0) + 2K(\tau_2, \tau_1)\phi(\tau_1) + K(\tau_2, \tau_2)\phi(\tau_2)] \quad (48)$$

$$\dots \quad (49)$$

$$f(\tau_n) = \frac{\Delta \tau_n}{2} [K(\tau_n, 0)\phi(0) + 2K(\tau_n, \tau_1)\phi(\tau_1) + 2K(\tau_n, \tau_2)\phi(\tau_2) + \dots + K(\tau_n, \tau_n)\phi(\tau_n)] \quad (50)$$

Since $K(\tau_i, \tau_i) = 0$, denoting $K(\tau_i, \tau_j)$ by $K_{i,j}$, then the above system can be written as:

$$\begin{pmatrix} f(\tau_1) \\ f(\tau_2) \\ f(\tau_3) \\ \vdots \\ f(\tau_n) \end{pmatrix} = \frac{\Delta \tau}{2} \begin{pmatrix} K_{1,0} & & & & \\ K_{2,0} & K_{2,1} & & & \\ K_{3,0} & K_{3,1} & K_{3,2} & & \\ \vdots & \vdots & \vdots & \ddots & \\ K_{n,0} & K_{n,1} & K_{n,2} & \dots & K_{n,n-1} \end{pmatrix} \begin{pmatrix} \phi(0) \\ \phi(1) \\ \phi(2) \\ \vdots \\ \phi(\tau_{n-1}) \end{pmatrix} \quad (51)$$

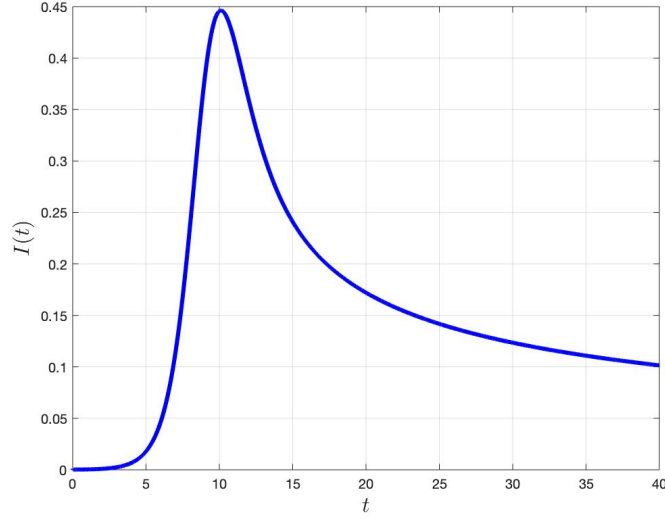


Figure 6: Plot of current with respect to time when a Linear Sweep Voltammetry is applied, solved by using the integral equation. $(E^*, E_0, k_0, \alpha) = (-10, -1, 35, 0.5)$

which can be solved via forward substitution to obtain $\phi(0), \phi(1), \dots, \phi(\tau_{n-1})$. Given $I'(0), I'(1), \dots, I'(\tau_{n-1})$, I can use trapezium rule to compute I by this way:

$$I(0) = 0 \quad (52)$$

$$I(\tau_1) = \frac{\Delta\tau}{2}[I'(0) + I'(\tau_1)] \quad (53)$$

$$\vdots \quad (54)$$

$$I(\tau_n) = \frac{\Delta\tau}{2}[I'(0) + 2I'(\tau_1) + \dots + I'(\tau_n)] \quad (55)$$

From Figure 6 I can see that numerical solution by integral equation match nicely with the numerical solution computed by finite difference method in Figure 5.

4 Sine Wave Voltammetry

In the case of Sine Wave Voltammetry:

$$E(t) = E_{dc}(t) + E_{ac}(t) \quad (56)$$

where

$$E_{dc}(t) = E^* + t, \quad E_{ac}(t) = \Delta E \sin(\omega t) \quad (57)$$

Here Δt and ω are controlled by the experiment. Similarly I could solve for $I(t)$ via finite difference method and an example is given in Figure 7.

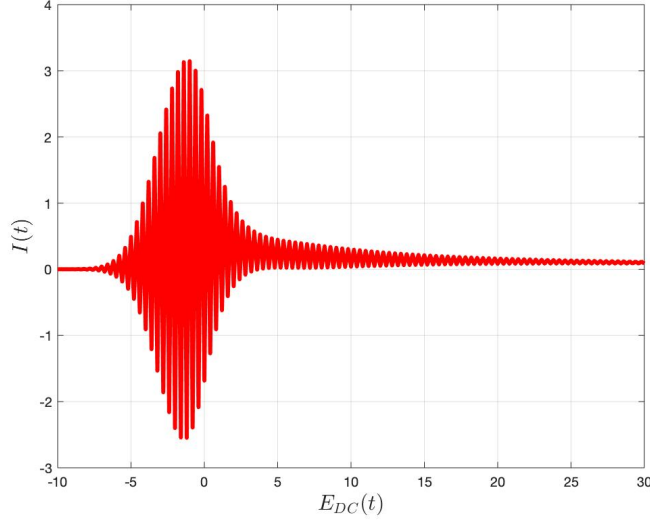


Figure 7: Plot of current with respect to time when a sine wave voltammetry is applied, $(E^*, E_0, k_0, \alpha, \Delta t, \omega) = (-10, -1, 35, 0.5, 2, 16)$

5 Inverse Problem

Suppose I are given experimental data $I(t_n)$ for $n = 1, 2, 3, \dots, N$, along with parameters $E^*, \Delta E, \omega$, and I would like to find the parameters E_0, k_0, α from the data that I have. Firstly I can set up an objective function given by:

$$J(E_0, k_0, \alpha) = \sum_{n=0}^N (I_{exp}(t_n) - I_{num}(t_n, E_0, k_0, \alpha)) \quad (58)$$

where $I_{exp}(t_n)$ denote the experimental data and $I_{exp}(t_n) - I_{num}(t_n, E_0, k_0, \alpha)$ denote the numerical result when some (t_n, E_0, k_0, α) is used. One way to solve for parameters (E_0, k_0, α) is by using the `fminsearch` function in MATLAB to find the values that fit the best. However I need to make sure that k_0 is positive and $\alpha \in (0, 1)$. I will try to apply this method to the case where $(E_0, k_0, \alpha) = (0, 0.1, 0.5)$ and see if it works. First I generate $I_{num}(t_n, E_0, k_0, \alpha)$ using these parameter values, then I generate a noisy current by adding noise such that:

$$I_{exp}(t_n) = I_{num}(t_n, E_0, k_0, \alpha) + r I_{max} \Delta N \quad (59)$$

where $I_{max} = \max_{0 \leq n \leq N} I_{num}(t_n, E_0, k_0, \alpha)$, ΔN is sampled from a standard normal distribution and r denotes the percentage error. Then I apply `fminsearch` to $I_{exp}(t_n)$ to obtain parameter values and check if they are closed to the actual values. In this

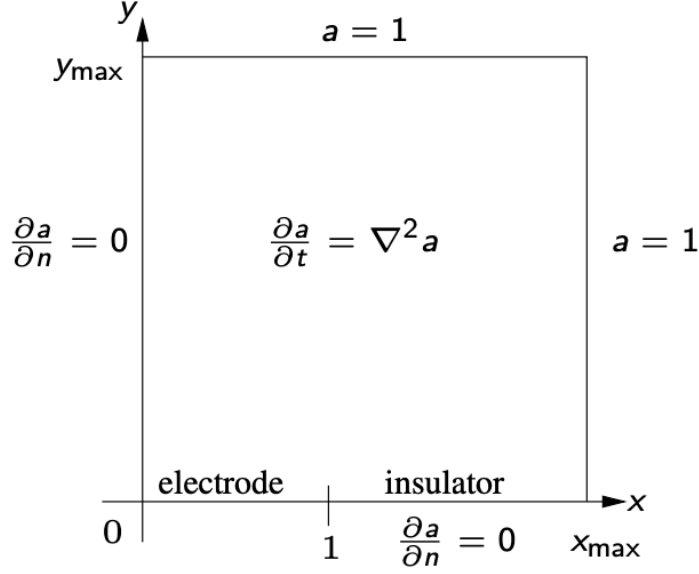


Figure 8: 2D problem

case I set $r = 0.05$ and apply 5 iterations of `fminsearch`, the result is given by the following table.

Error			
	error E_0	error α	error k_0
<i>Linear</i>	2.2758	0.11874	0.23088
<i>Cyclic</i>	0.10487	0.039065	0.015578
<i>Sine</i>	8.8764	0.037121	0.17398

Clearly the most accurate result is recovered when cyclic voltammetry is applied, followed by linear sweep voltammetry and lastly sine wave voltammetry. In general α and k_0 are recovered correctly whereas E_0 is recovered only when cyclic voltammetry is applied.

6 Extension

Now I consider a 2D problem of linear sweep voltammetry at a microband electrode assuming equal coefficient for A and B . Here the electrode is small so it is assumed that the effects from the electrode/insulator edge have an effect. The problem in a truncated domain is given by Figure 8. Here I can see that there exist two types of

boundary conditions: Dirichlet boundary condition and zero Neumann boundary condition. Inside the domain a satisfies the heat equation. Here I consider a rectangular domain of $\Omega = [0, 2] \times [0, 2]$, the uniform mesh points are defined by

$$x_i = i\Delta x, \quad y_j = j\Delta y$$

for $i, j = 0, 1, 2, \dots, N+1$ with meshsizes $\Delta x = \Delta y = 2/(N+1)$. Timestep is defined by $t_m = m\Delta t$ for $m = 0, 1, 2, \dots$. I use the approximation $A_{i,j}^m$ for $a(x_i, y_j, t_m)$. Consider the equation:

$$\frac{da}{dt} = \frac{d^2a}{dx^2} + \frac{d^2a}{dy^2} \quad (60)$$

By the Crank Nicolsan Method[3], equation (60) can be approximated by:

$$\frac{A_{i,j}^{m+1} - A_{i,j}^m}{\Delta t} = \theta \frac{A_{i+1,j}^{m+1} - 2A_{i,j}^{m+1} + A_{i-1,j}^{m+1}}{\Delta x^2} + (1-\theta) \frac{A_{i+1,j}^m - 2A_{i,j}^m + A_{i-1,j}^m}{\Delta x^2} \quad (61)$$

$$(62)$$

$$+ \theta \frac{A_{i,j+1}^{m+1} - 2A_{i,j}^{m+1} + A_{i,j-1}^{m+1}}{\Delta y^2} + (1-\theta) \frac{A_{i,j+1}^m - 2A_{i,j}^m + A_{i,j-1}^m}{\Delta y^2} \quad (63)$$

for $i, j = 1, 2, \dots, N$, $m = 1, 2, \dots$ and $\theta \in [0, 1]$. Using θ -method subject to the boundary conditions I obtain a linear system:

$$(I - \theta M)\mathbf{A}^{m+1} = (I + (1-\theta)M)\mathbf{A}^m + \mathbf{f} \quad (64)$$

where

$$\mathbf{A}^m = (A_{1,1}^m, A_{1,2}^m, \dots, A_{1,N}^m, A_{2,1}^m, \dots, A_{N,N}^m)^T \quad (65)$$

I is the $N^2 \times N^2$ identity matrix and M is a $N^2 \times N^2$ matrix of the form:

$$M = \begin{pmatrix} B' & C & & & \\ C & B & C & & \\ & C & B & C & \\ & & \ddots & \ddots & \ddots \\ & & & C & B & C \\ & & & & C & B \end{pmatrix} \quad (66)$$

where C, B', B are $N \times N$ matrices of the form:

$$C = \begin{pmatrix} \mu_x & & & \\ & \mu_x & & \\ & & \ddots & \\ & & & \mu_x \end{pmatrix} \quad (67)$$

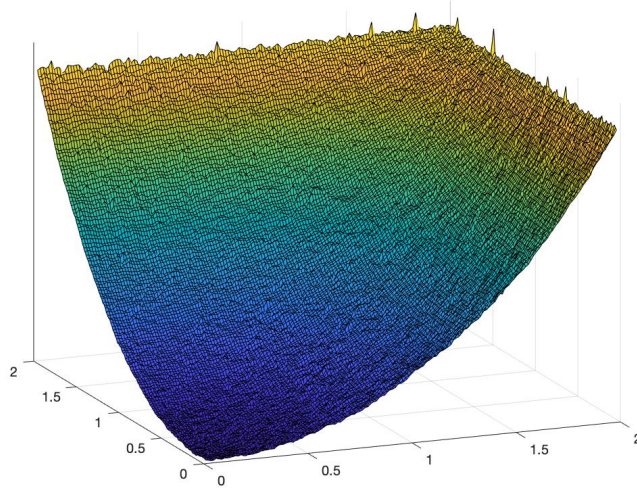


Figure 9: Numerical solution of a when $t = 10$

$$B' = \begin{pmatrix} -(\mu_x + \mu_y) & \mu_y & & & \\ \mu_y & -(\mu_x + 2\mu_y) & \mu_y & & \\ & \mu_y & -(\mu_x + 2\mu_y) & \mu_y & \\ & \ddots & \ddots & \ddots & \\ & & \mu_y & -(\mu_x + 2\mu_y) & \mu_y \\ & & & \mu_y & -(\mu_x + 2\mu_y) \end{pmatrix} \quad (68)$$

$$B = \begin{pmatrix} -(2\mu_x + \mu_y) & \mu_y & & & \\ \mu_y & -2(\mu_x + \mu_y) & \mu_y & & \\ & \mu_y & -2(\mu_x + \mu_y) & \mu_y & \\ & \ddots & \ddots & \ddots & \\ & & \mu_y & -2(\mu_x + \mu_y) & \mu_y \\ & & & \mu_y & -2(\mu_x + \mu_y) \end{pmatrix} \quad (69)$$

and \mathbf{f} is of the form:

$$\mathbf{f} = (0, 0, \dots, \mu_y, 0, 0, \dots, \mu_y, \dots, 0, 0, \dots, \mu_y, \mu_x, \mu_x, \dots, \mu_x + \mu_y)^T \quad (70)$$

where $\mu_x = \frac{\Delta t}{\Delta x^2}$ and $\mu_y = \frac{\Delta t}{\Delta y^2}$. Plugging in initial values for a and run iterations I obtain a numerical solution of a showed by Figure 9.

7 Conclusion

In this paper I introduced one-dimensional diffusion of chemical species to the electrode in the case of chronoamperometry. Then I extend it to the case when linear sweep voltammetry is applied and derive the integral equation which can be solved numerically by trapezium rule. I also introduce the inverse problem where I recover unknown parameter values from experimental data by using `fminsearch` in MATLAB. Lastly I extend linear sweep voltammetry in a two-dimensional domain and compute the solution numerically by using the method of finite differences.

References

- [1] Zoski C. Leddy J. Bard A., Faulkner L. *Electrochemical methods : fundamentals and applications*. Wiley, 2001.
- [2] Bond A.M. Gavaghan D.J. A complete numerical simulation of the techniques of alternating current linear sweep and cyclic voltammetry: analysis of a reversible process by conventional and fast fourier transform methods. *Journal of Electroanalytical Chemistry*, 480(1):133–149, 2000.
- [3] Nicolson P. Crank J. A practical method for numerical evaluation of solutions of partial differential equations of the heat-conduction type. *Advances in Computational Mathematics*, 6(3-4):207–226, 1996.