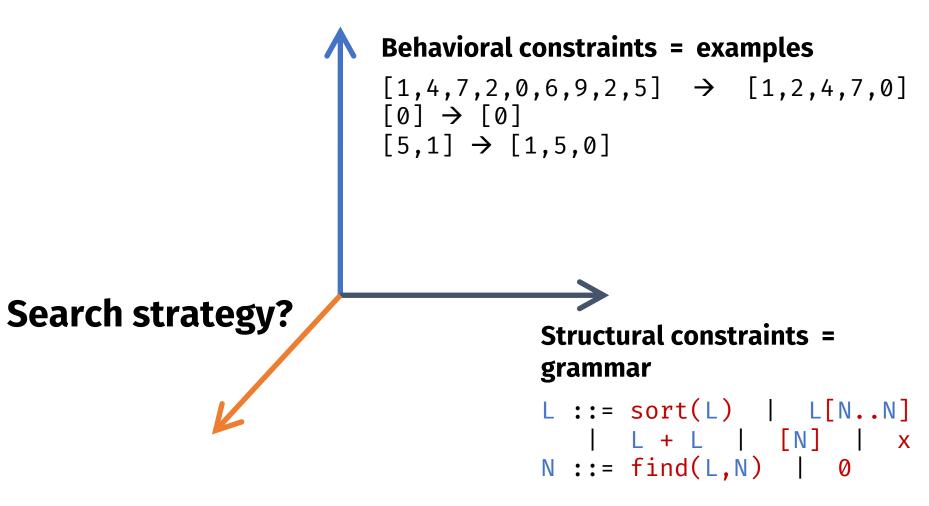
# **#5: Top-down Propagation**

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EECS 700: Introduction to Program Synthesis



### The problem statement



#### **Enumerative search**

=

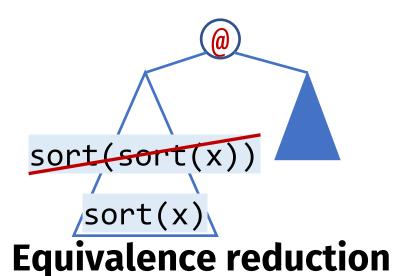
Explicit / Exhaustive Search

Idea: Enumerate programs from the grammar one by one and test them on the examples

```
L ::= sort(L)
                                L[N..N]
                                 \lceil N \rceil
   bottom-up
                                                          top-down
                         N ::= find(L,N)
Χ
   0
        x[0..0] x + x
sort(x)
                                                       L[N..N] L + L
                          [0]
                                           x sort(L)
                                                                       [N]
find(x,0)
               sort(x[0..0])
                                                    sort(sort(L))
                                                                    sort([N])
sort(sort(x))
                                           sort(x)
               sort([0])
                                           sort(L[N..N]) sort(L + L)
sort(x + x)
                                                   (sort L)[N..N]
x[0..find(x,0)]
                                           \times[N..N]
```

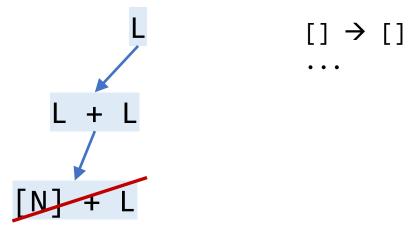
## When can we discard a subprogram?

redundant



(also: symmetry breaking)

infeasible



**Top-down propagation** 

### Top-down search: reminder

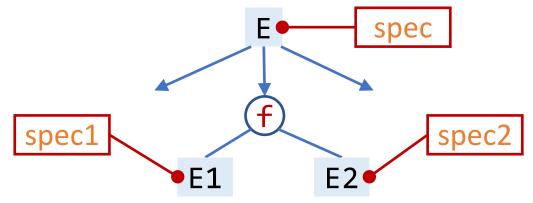
generates a lot of incomplete terms only discards complete terms

```
iter 0: L
          L[N..N]
                need to reject hopeless programs early!

[0.. f:
iter 2: L[N..N]
                                                                 N ::= find(L,N)
iter 3: x[N..N]
iter 4: x[0..N]
                                                                 [[1,4,0,6] \rightarrow [1,4]]
iter 6: x[0...find(L,N)] x[find(L,N)..N]
iter 7: x[0..find(x,N)] x[0..find(L[N..N],N)]
iter 8: x[0...find(x,0)] \sim x[0...find(x,find(L,N))]
iter 9:
```

## **Top-down propagation**

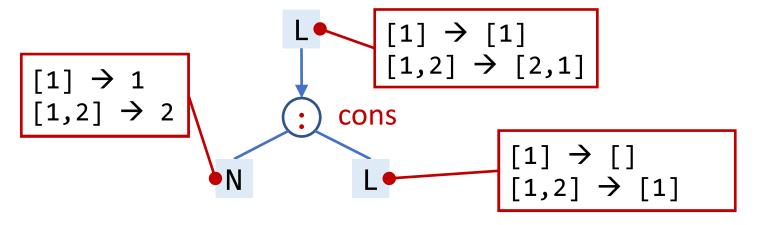
• Idea: once we pick the production, infer specs for subprograms



- If spec1 =  $\bot$  or spec2 =  $\bot$  discard f(E1,E2)!
- For now: spec = examples

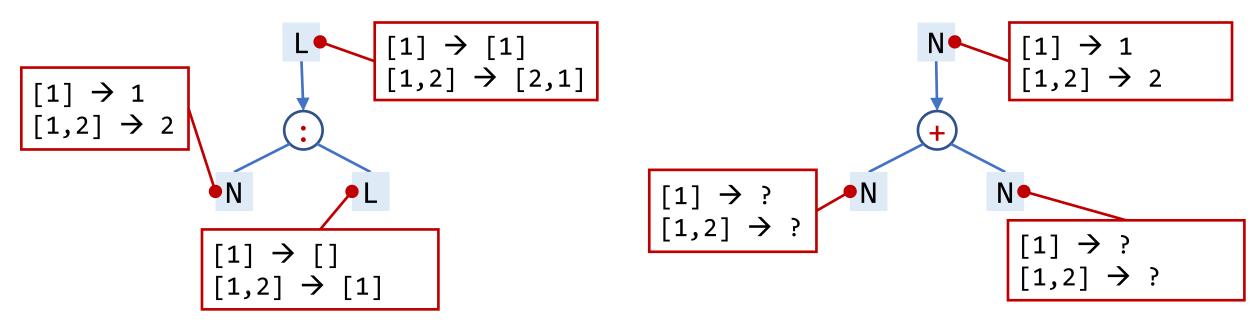
# When is TDP possible?

Depends on f!



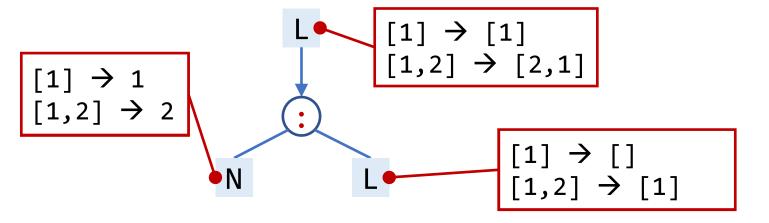
# When is TDP possible?

Depends on f!



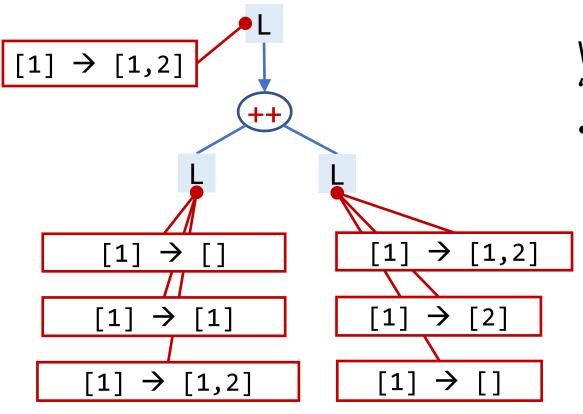
### When is TDP possible?

Depends on f!



- Works when the function is injective!
- Q: when would we infer ⊥? A: If at least one of the outputs is []!

# Something in between?



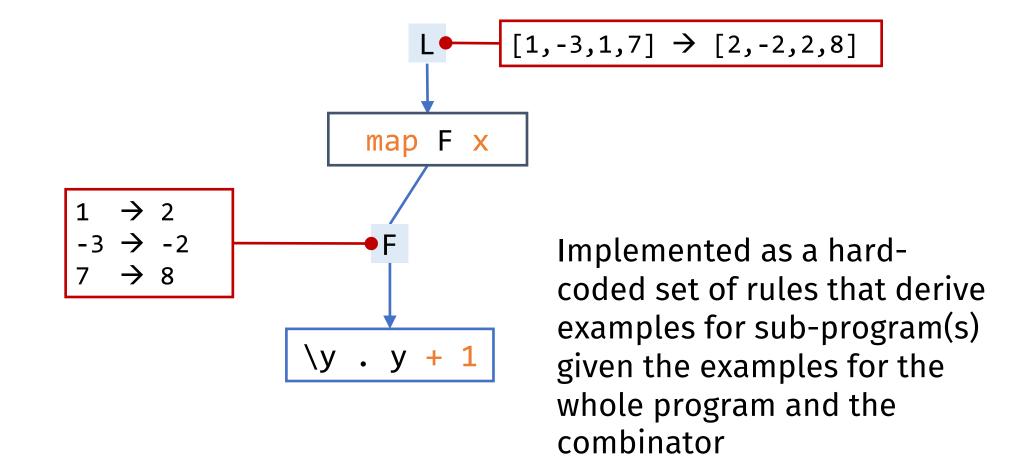
Works when the function has a "small inverse"

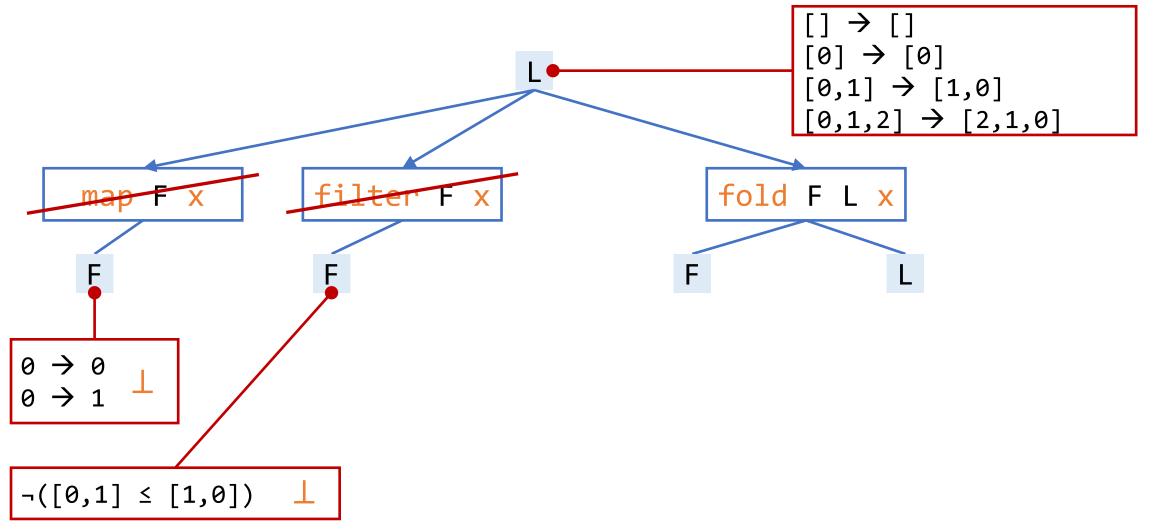
 or just the output examples have a small inverse

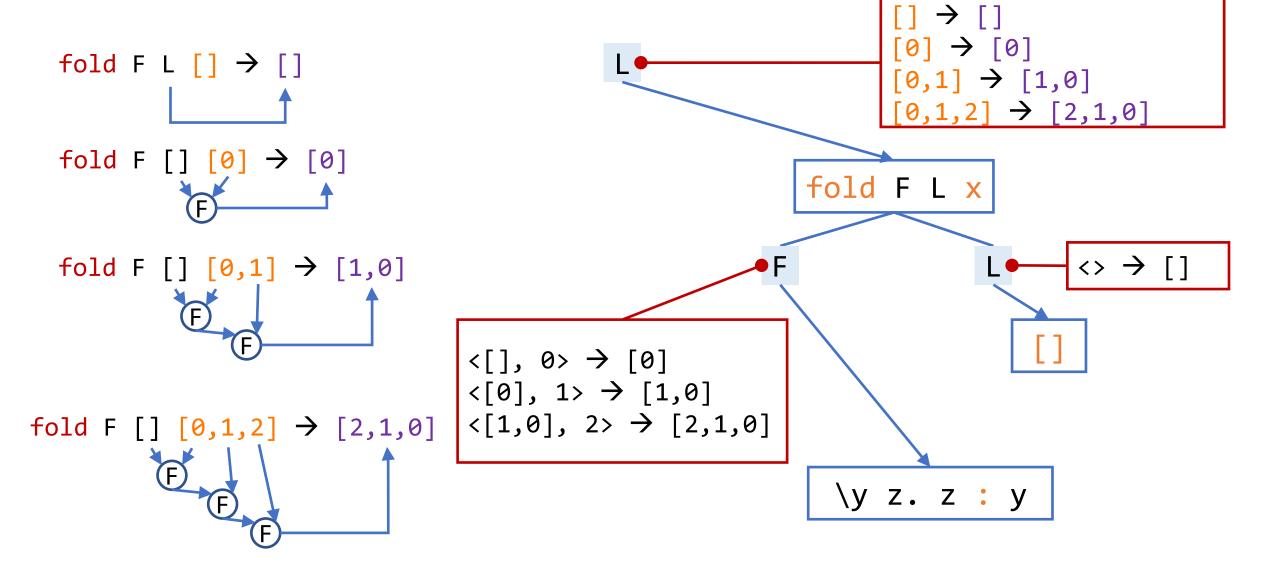
```
map (\y . y + 1) [1, -3, 1, 7] \rightarrow [2, -2, 2, 8]
• map f x
                        filter (\y . y > 0) [1, -3, 1, 7] \rightarrow [1, 1, 7]
• filter f x
                       fold (\y z . y + z) 0 [1, -3, 1, 7] \rightarrow 6

    fold f acc x

                        fold (\y z . y + z) \emptyset [] \rightarrow \emptyset
```







#### **Condition abduction**

- Smart way to synthesize conditionals
- Used in many tools (under different names):
  - FlashFill [Gulwani '11]
  - Escher [Albarghouthi et al. '13]
  - Leon [Kneuss et al. '13]
  - Synquid [Polikarpova et al. '16]
  - **EUSolver** [Alur et al. '17]
- In fact, an instance of TDP!

### **Condition abduction**

