# Chapter 7 Network Topology Inference

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<pre>library(igraph) library(igraphdata) library(sand)</pre>			

#### Introduction 1

Setting: given a set of measurements of interest:

- vertex attributes:  $\mathbf{x}=(x_1,x_2,\ldots,x_n)^T$  binary edge indicators:  $\mathbf{y}=y_{ij}=1$  if  $\{i,j\}\in E_G$ , and 0 otherwise
- or some combinatitions of both  ${\bf x}$  and  ${\bf y}$
- a collection  $\mathcal{G}$  of potential network graphs G

Goal: find  $G' \in \mathcal{G}$  that best captures the underlying graph.

## 2 Link Prediction

Assuming known attributes of all vertices and status of some of the edges/non-edges, the goal is to infer the rest of the egdes/non-edges.

Let G = (V, E) be random graph, with  $|V_G| = n$ , and random binary adjacency matrix  $\mathbf{Y}$ , consisting of observed  $\mathbf{y}^{obs}$  and missing elements  $\mathbf{y}^{miss}$ , and various vertex attributes  $\mathbf{X} = \mathbf{x} = (x_1, x_2, \dots, x_n)^T$ .

Assume that the missing information on edge status is missing at random, the problem of link prediction becomes:

$$\mathbb{P}(\mathbf{Y}^{miss} \mid \mathbf{Y}^{obs} = \mathbf{y}^{obs}, \mathbf{X} = \mathbf{x})$$

The 2 main approaches:

- 1. Predicting  $Y_{ii}^{miss}$  individually, via cross-validation for assessing model goodness-of-fit;
- 2. Scoring methods: for each pair of vertices i, j, a score s(i, j) is computed:
  - compare s(i, j) against a fixed threshold s\*, analogous to logistic regression
  - order the scores and take the top n\* highest scores

Example of scoring methods: small-world principle, where

$$s(i,j) = -dist_{G^{obs}}(i,j)$$

Higher scores indicate shorter distances, and thus the vertex pairs more likely to share an edge.

Example of scoring methods: based on comparison of the observed neighborhoods

$$s(i,j) = \#\Big(N(i)^{obs} \cap N(j)^{obs}\Big)$$

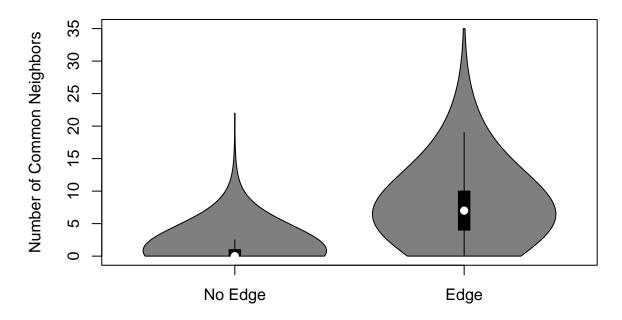
To illustrate the scoring by common neighbors, via the fblog dataset:

```
nv <- vcount(fblog)
ncn <- numeric()
A <- get.adjacency(fblog)

# computing number of common neighbors
for (i in (1:(nv-1))) {
    ni <- neighborhood(fblog, 1, i)
    nj <- neighborhood(fblog, 1, (i+1):nv)
    nbhd.ij <- mapply(intersect, ni, nj, SIMPLIFY = FALSE)
    temp <- unlist(lapply(nbhd.ij, length)) - 2*A[i, (i+1):nv]
    ncn <- c(ncn, temp)
}</pre>
```

```
library(vioplot)
par(mar=c(2,4,0.2,0.2))
Avec <- A[lower.tri(A)]
vioplot(ncn[Avec == 0], ncn[Avec == 1], names = c('No Edge', 'Edge'))</pre>
```

```
## [1] 0 35
```



**Interpretation**: the plot suggests that the number of common neighbors can be a good indicator: the higher the number the more likely there is an edge in common. The finding is supported by the AUC value below:

```
library(ROCR)
pred <- prediction(ncn, Avec)
perf <- performance(pred, 'auc')
slot(perf, 'y.values')

## [[1]]
## [1] 0.9275179</pre>
```

# 3 Association Network Inference

Assuming known attributes of all vertices and no knowledge of edge status anywhere, the goal is to infer the status of the egdes/non-edges in the network.

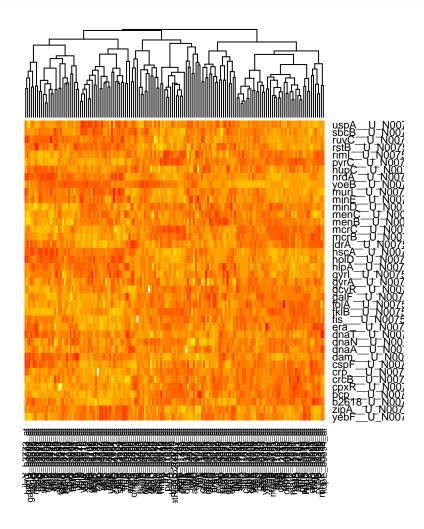
Let G = (V, E) be random graph, with  $|V_G| = n$ , and each vertex v has an m-dim vector  $\mathbf{x}$  of observed attributes, giving a collection  $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$ .

Let sim(i, j) be a measure of similarity between vertices i and j, of choice. 2 common choices are:

- 1. Correlation:  $sim(i,j) = corr(x_i, x_j) = \rho_{ij}$
- 2. Partial Correlation:  $sim(i, j) = \rho_{ij|S_m}$

For illustration, we will use the Ecoli.data dataset:

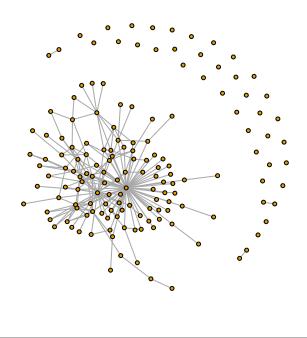
```
par(mar=c(0,0,0,0))
data(Ecoli.data)
heatmap(scale(Ecoli.expr), Rowv = NA)
```



```
g.regDB <- graph.adjacency(regDB.adj, 'undirected')
summary(g.regDB)

## IGRAPH 40cb7b3 UN-- 153 209 --
## + attr: name (v/c)

par(mar=c(0,0,0,0))
plot(g.regDB, vertex.size = 3, vertex.label = NA)</pre>
```



#### 3.1 Correlation Networks

Pearson correlation between  $X_i$  and  $X_j$ :

$$sim(i,j) = corr(x_i, x_j) = \rho_{ij} = \frac{\sigma_{ij}}{\sqrt{\sigma_{ii}\sigma_{jj}}}$$

which gives the decision criterion: G = (V, E), where

$$E = \left\{ \{i, j\} \in V^{(2)} : \rho_{ij} \neq 0 \right\}$$

Thus, given an observed network graph G, the *empirical formula* is used.

```
mycorr <- cor(Ecoli.expr)</pre>
```

Alternatively, we can work with the transformations of the correlation values, such as Fisher's transformation:

$$z_{ij} = \tanh^{-1}(\hat{\rho}_{ij}) = \frac{1}{2} \ln \left[ \frac{1 + \hat{\rho}_{ij}}{1 - \hat{\rho}_{ij}} \right]$$

If  $(X_i, X_j)$  are bivariate normal, then under  $H_o: \rho_{ij} = 0: \hat{\rho}_{ij} \sim \mathcal{N}(0, \frac{1}{n-3})$ .

```
z <- .5 * log((1+mycorr) / (1-mycorr))
z.vec <- z[upper.tri(z)]
n <- dim(Ecoli.expr)[1]
corr.pvals <- 2 * pnorm(abs(z.vec), 0, sqrt(1/(n-3)), lower.tail = FALSE)
print(paste('Number of correlation values, given 152 vertices:', length(corr.pvals)))</pre>
```

## [1] "Number of correlation values, given 152 vertices: 11628"

Recall that we are testing for correlation between multiple variables, we need to adjust the p-values.

```
corr.pvals.adj <- p.adjust(corr.pvals, 'BH')
n <- length(corr.pvals.adj[corr.pvals.adj < .05])
print(paste('Number of Rejections <=> Edges predicted:', n))
```

## [1] "Number of Rejections <=> Edges predicted: 5227"

#### 3.2 Partial Correlation Networks

Whereas correlation  $\rho_{ij}$  is computed using attributes of all vertices including i and j, the partial correlation of attributes  $X_i$  and  $X_j$  is computed with respect to attributes  $X_{k_1}, \ldots, X_{k_m} : k_1, \ldots, k_m \in V \setminus \{i, j\}$ .

Let  $S_m = \{k_1, \ldots, k_m\}$ , the partial correlation of  $X_i$  and  $X_j$  is:

$$\rho_{ij|S_m} = \frac{\sigma_{ij|S_m}}{\sqrt{\sigma_{ii}|S_m}\sigma_{jj|S_m}}$$

where  $\sigma_{ii|S_m}$ ,  $\sigma_{jj|S_m}$ ,  $\sigma_{ij|S_m}$ ,  $\sigma_{ji|S_m}$  are the diagonal and off-diagnol elements of the  $2 \times 2$  covariance matrix. Remark: if m = 0, the partial correlation reduces to the Pearson correlation.

Using partial correlation, for a given m, we can have a decision criterion for an edge set of G as

$$E = \left\{ \{i, j\} \in V^{(2)} : \rho_{ij|S_m} \neq 0, \forall S_m \in V_{\setminus \{i, j\}}^{(m)} \right\}$$

where  $V_{\{i,j\}}^{(m)}$  is the collection of all unordered subset of m distinct vertices from  $V \setminus \{i,j\}$ . The problem of determining the presence of an edge becomes:

$$H_0: \exists S_m \in V_{\backslash \{i,j\}}^{(m)}, \rho_{ij|S_m} = 0$$
  
$$H_1: \forall S_m \in V_{\backslash \{i,j\}}^{(m)}, \rho_{ij|S_m} \neq 0$$

Similar to above, by Fisher's transformation:

$$z_{ij|S_m} = \tanh^{-1}(\hat{\rho}_{ij|S_m}) = \frac{1}{2} \ln \left[ \frac{1 + \hat{\rho}_{ij|S_m}}{1 - \hat{\rho}_{ij|S_m}} \right]$$

```
pcorr.pvals <- matrix(0, dim(mycorr)[1], dim(mycorr)[2])
for (i in seq(1,153)) {
   for (j in seq(1,153)) {
      rowi <- mycorr[i, -c(i,j)]
      rowj <- mycorr[j, -c(i,j)]
      tmp <- (mycorr[i,j] - rowi*rowj) / sqrt((1-rowi^2) * (1-rowj^2))
      tmp.zvals <- .5 * log((1+tmp)/(1-tmp))
      tmp.s.zvals <- sqrt(n-4) * tmp.zvals
      tmp.pvals <- 2 * pnorm(abs(tmp.s.zvals), 0, 1, lower.tail = FALSE)
      pcorr.pvals[i, j] <- max(tmp.pvals)
   }
}</pre>
```

Adjusting for multiple testing:

```
pcorr.pvals.vec <- pcorr.pvals[lower.tri(pcorr.pvals)]
pcorr.pvals.adj <- p.adjust(pcorr.pvals.vec, 'BH')
pcorr.edges <- (pcorr.pvals.adj < .05)
n <- length(pcorr.pvals.adj[pcorr.edges])
print(paste('Number of Rejections <=> Edges predicted:', n))
```

## [1] "Number of Rejections <=> Edges predicted: 2615"

```
pcorr.A <- matrix(0, 153, 153)
pcorr.A[lower.tri(pcorr.A)] <- as.numeric(pcorr.edges)
g.pcorr <- graph.adjacency(pcorr.A, 'undirected')</pre>
```

To compare networks, in R: graph.intersection()

## str(graph.intersection(g.regDB, g.pcorr, byname = FALSE))

```
## List of 10
## $ :List of 1
   ...$ acrR_b0464_at: 'igraph.vs' Named int(0)
    .. ..- attr(*, "names")= chr(0)
    .. ..- attr(*, "env")=<weakref>
##
   ....- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
##
## $ :List of 1
##
    ..$ ada_b2213_at: 'igraph.vs' Named int(0)
##
    ...- attr(*, "names")= chr(0)
    .. ..- attr(*, "env")=<weakref>
## ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
## $ :List of 1
   ..$ adiY_b4116_at: 'igraph.vs' Named int(0)
##
    \dots attr(*, "names")= chr(0)
    .. ..- attr(*, "env")=<weakref>
##
    ....- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$ alpA_b2624_at: 'igraph.vs' Named int(0)
    .. ..- attr(*, "names")= chr(0)
##
    .. ..- attr(*, "env")=<weakref>
##
##
    ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
## $ :List of 1
    ..$ appY_b0564_at: 'igraph.vs' Named int 120
##
##
    ....- attr(*, "names")= chr "rpoS_b2741_at"
## ....- attr(*, "env")=<weakref>
## ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
## $ :List of 1
##
    ..$ araC_b0064_at: 'igraph.vs' Named int(0)
## ....- attr(*, "names")= chr(0)
    .. ..- attr(*, "env")=<weakref>
##
    ....- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$ arcA_b4401_at: 'igraph.vs' Named int [1:2] 16 80
    ....- attr(*, "names")= chr [1:2] "betI_b0313_at" "lldR_b3604_at"
##
    .. ..- attr(*, "env")=<weakref>
##
    ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-01000000000"
## $ :List of 1
##
    ..$ argR_b3237_at: 'igraph.vs' Named int(0)
    .. ..- attr(*, "names")= chr(0)
##
    .. ..- attr(*, "env")=<weakref>
##
##
   ....- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
## $ :List of 1
##
    ..$ arsR_b3501_at: 'igraph.vs' Named int(0)
    .. ..- attr(*, "names")= chr(0)
##
    .. ..- attr(*, "env")=<weakref>
##
    ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
##
## $ :List of 1
   ...$ asnC b3743 at: 'igraph.vs' Named int(0)
    .. ..- attr(*, "names")= chr(0)
##
    .. ..- attr(*, "env")=<weakref>
##
## ...- attr(*, "graph")= chr "41adc79e-a150-11e9-8000-010000000000"
## - attr(*, "class")= chr "igraph"
```

### 3.3 Gaussian Graphical Model Networks

Given the use of partial correlation coefficients, when m = n - 2, and the attributes are assumed to have a multivariate Gaussian joint distribution (joint Normal), let the coefficients be  $\rho_{ij|V\setminus\{i,j\}}$ , then  $\rho_{ij|V\setminus\{i,j\}} = 0 \iff X_i$ and  $X_i$  are conditionally independent given all of other attributes. This gives the decision criterion:

$$E = \left\{ \{i, j\} \in V^{(2)} : \rho_{ij|V \setminus \{i, j\}} \neq 0 \right\}$$

Also,

$$\rho_{ij|V\setminus\{i,j\}} = \frac{\omega_{ij}}{\sqrt{\omega_{ii}\omega_{jj}}}$$

where  $\omega_{ij}$  is the (i,j) entry of  $\Omega = \Sigma^{-1}$ , the inverse of the covariance matrix  $\Sigma$  of the vertex attributes vector  $(X_1, \ldots, X_n)^T$ .

```
library(huge)
set.seed(42)
huge.out <- huge(Ecoli.expr)</pre>
## Conducting Meinshausen & Buhlmann graph estimation (mb)....done
huge.opt <- huge.select(huge.out, criterion = 'ric')</pre>
## Conducting rotation information criterion (ric) selection....done
## Computing the optimal graph....done
summary(huge.opt$refit)
##
      Length
                 Class
                             Mode
##
       23409 dsCMatrix
                               S4
huge.opt <- huge.select(huge.out, criterion = 'stars')</pre>
g.huge <- graph.adjacency(huge.opt$refit, 'undirected')</pre>
summary(g.huge)
## IGRAPH 4948c75 U--- 153 786 --
str(graph.intersection(g.pcorr, g.huge))
## List of 10
## $ :List of 1
    ..$: 'igraph.vs' int [1:5] 6 16 100 122 142
##
     .. ..- attr(*, "env")=<weakref>
    ....- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
##
##
    $:List of 1
    ..$: 'igraph.vs' int [1:9] 17 23 104 107 108 120 123 129 133
##
     .. ..- attr(*, "env")=<weakref>
##
     ... - attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$: 'igraph.vs' int [1:11] 13 14 22 59 60 87 89 98 132 145 ...
```

.. ..- attr(\*, "env")=<weakref>

##

```
...- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$: 'igraph.vs' int [1:14] 26 35 37 47 65 69 73 84 92 103 ...
    .. ..- attr(*, "env")=<weakref>
    ...- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-01000000000"
##
## $ :List of 1
##
    ..$: 'igraph.vs' int [1:10] 12 31 34 60 82 97 111 134 146 148
    .. ..- attr(*, "env")=<weakref>
##
##
    ....- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
## $ :List of 1
    ..$: 'igraph.vs' int [1:11] 1 24 35 36 53 56 66 69 100 137 ...
##
    .. ..- attr(*, "env")=<weakref>
##
##
    ...- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
## $ :List of 1
    ..$: 'igraph.vs' int [1:8] 53 69 71 80 100 101 118 128
##
##
    .. ..- attr(*, "env")=<weakref>
    ....- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$: 'igraph.vs' int [1:15] 17 20 26 35 39 48 51 56 70 73 ...
    .. ..- attr(*, "env")=<weakref>
##
   ....- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
##
## $ :List of 1
    ..$: 'igraph.vs' int [1:8] 15 26 40 41 90 94 112 125
##
    .. ..- attr(*, "env")=<weakref>
##
## ...- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
## $ :List of 1
    ..$: 'igraph.vs' int [1:10] 36 39 51 74 82 89 126 134 139 148
## .. ..- attr(*, "env")=<weakref>
## ...- attr(*, "graph")= chr "494b37fc-a150-11e9-8000-010000000000"
## - attr(*, "class")= chr "igraph"
```

# 4 Tomographic Network Topology Inference

Assuming known attributes of a *subset* of vertices and *no* knowledge of edge status anywhere, the goal is to infer the status of the egdes/non-edges in the network.

## 4.1 Constraining the Problem: Tree Topologies

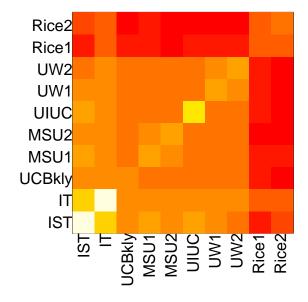
Let T = (V, E) be an undirected tree. Recall that a rooted tree is a tree with a specified root  $r \in V$ , leaves are vertices  $R \subset V$  of degree 1, then  $V \setminus \{\{r\} \cup R\}$  are internal vertices.

A binary tree is a rooted tree where, going from the root towards the leaves, each internal vertex has at most 2 children. For illustration, we will use the sandwichprobe dataset:

```
data(sandwichprobe)
delaydata[1:5,]
```

```
##
     DelayDiff SmallPktDest BigPktDest
## 1
            757
                            3
                                       10
                            6
## 2
            608
                                        2
                            8
                                        9
## 3
            242
                            1
                                        8
## 4
            84
## 5
          1000
```

```
par(mar=c(3,3,0.5,0.5))
meanmat <- with(delaydata, by(DelayDiff, list(SmallPktDest, BigPktDest), mean))
image(log(meanmat + t(meanmat)), xaxt = 'n', yaxt = 'n', col = heat.colors(16))
mtext(side = 1, text = host.locs, at = seq(0, 1, .11), las = 3)
mtext(side = 2, text = host.locs, at = seq(0, 1, .11), las = 1)</pre>
```



# 4.2 Tomographic Inference of Tree Topologies: An Illustration

In modeling tree topologies, there are 2 major classes of methods:

- 1. hierarchical clustering
- $2.\ likelihood\text{-}based\ methods$

Here, we will use the *hierarchical clustering* as an illustration, in R: hclust()

```
par(mar=c(0,0,0,0))
SSDelayDiff <- with(delaydata, by(DelayDiff^2, list(SmallPktDest, BigPktDest), sum))
x <- as.dist(1 / sqrt(SSDelayDiff))
myclust <- hclust(x, method = 'average')
plot(myclust, labels = host.locs, axes = FALSE, ylab = NULL, ann = FALSE)</pre>
```

