EMERGENCY
MEETING

```
if x ≤ 2m {
    punish();
} else {
    keep looking();
}
```

ultrasonic   ultrasonic
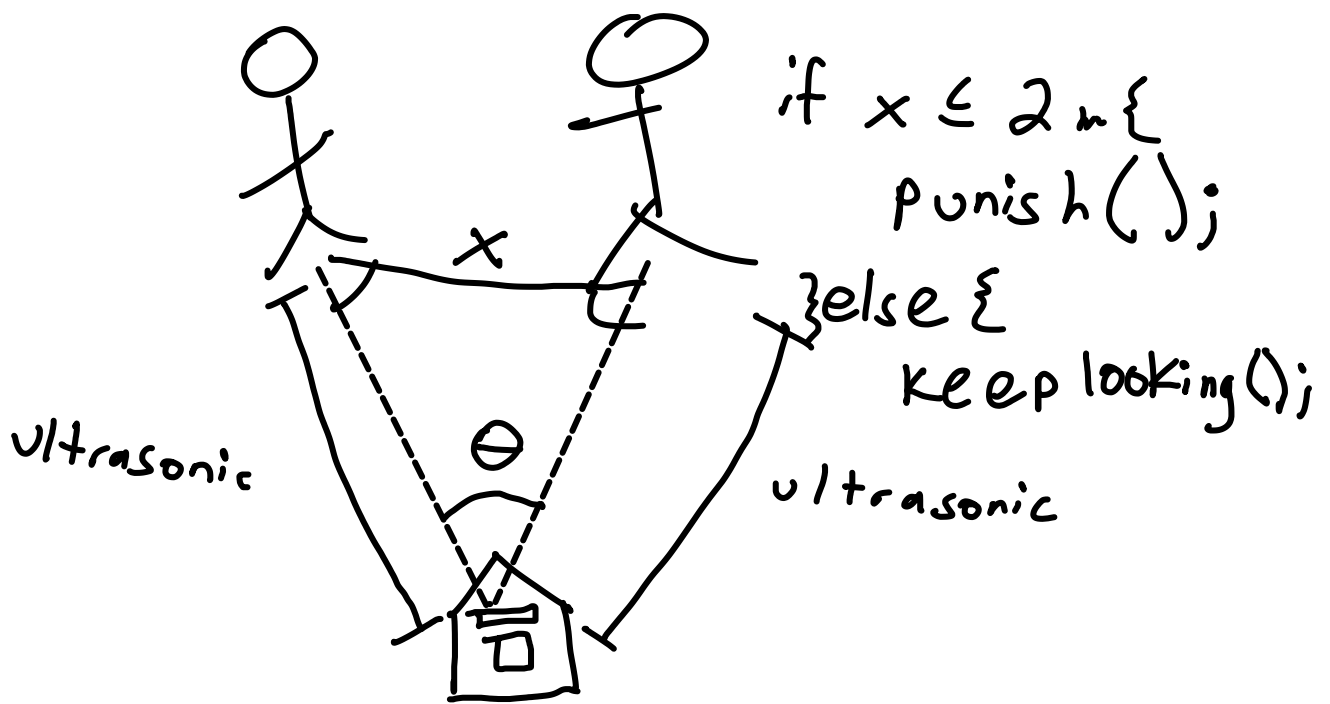
- Robot - in progress
    - RGB
    - drive system - done
    - ultrasonic sensor
    - camera - basically done
    - distance sensor at base for crash prevention
Image processing
    Goal: detect a person
        - center camera at person
            - log servo position
        - using own training set

Robot

- Phone
- Ultrasonic sensor
- ESP32

Rtsp

- running trained model
- MQTT

↓
training