

view_frames Result

Recorded at time: 1685719717.136

map

Broadcaster: /map_to_odom
Average rate: 38.543 Hz
Most recent transform: 1685719717.162 (-0.026 sec old)
Buffer length: 2.932 sec

odom

Broadcaster: /robot_pose_ekf
Average rate: 20.364 Hz
Most recent transform: 1685719717.100 (0.036 sec old)
Buffer length: 2.750 sec

base_footprint

Broadcaster: /base_footprint_to_base_link
Average rate: 33.389 Hz
Most recent transform: 1685719717.150 (-0.014 sec old)
Buffer length: 2.815 sec

base_link

Broadcaster: /base_link_to_imu
Average rate: 33.449 Hz
Most recent transform: 1685719717.158 (-0.022 sec old)
Buffer length: 2.900 sec

Broadcaster: /base_link_to_camera
Average rate: 33.401 Hz
Most recent transform: 1685719717.153 (-0.017 sec old)
Buffer length: 2.784 sec

Broadcaster: /base_link_to_laser
Average rate: 33.449 Hz
Most recent transform: 1685719717.157 (-0.020 sec old)
Buffer length: 2.601 sec

imu

camera_frame

laser