

view\_frames Result

Recorded at time: 1686311513.416

map

Broadcaster: /mcl  
Average rate: 5.776 Hz  
Most recent transform: 1686311513.513 ( -0.097 sec old)  
Buffer length: 4.328 sec

odom

Broadcaster: /robot\_pose\_ekf  
Average rate: 18.636 Hz  
Most recent transform: 1686311513.367 ( 0.049 sec old)  
Buffer length: 4.883 sec

base\_footprint

Broadcaster: /base\_footprint\_to\_base\_link  
Average rate: 29.486 Hz  
Most recent transform: 1686311513.432 ( -0.015 sec old)  
Buffer length: 4.952 sec

base\_link

Broadcaster: /base\_link\_to\_camera  
Average rate: 30.134 Hz  
Most recent transform: 1686311513.429 ( -0.013 sec old)  
Buffer length: 4.911 sec

imu

Broadcaster: /base\_link\_to\_imu  
Average rate: 29.615 Hz  
Most recent transform: 1686311513.429 ( -0.013 sec old)  
Buffer length: 4.930 sec

Broadcaster: /base\_link\_to\_laser  
Average rate: 29.654 Hz  
Most recent transform: 1686311513.427 ( -0.011 sec old)  
Buffer length: 4.822 sec

camera\_frame

laser