

Introduction to High Performance Computing

MPI (2)

Misc point-to-point

If not known

- data type, type of message
- sender
- size of data to be received

Probe for a message before receiving it

```
MPI_Probe(source, tag, comm, &status)
MPI_Iprobe(source, tag, comm, &flag, &status)
```

- Look into receive stack (blocking or non blocking) whether an appropriate message arrived.
- Allows inspection (status) first.
- Does not receive message!

Example - probing

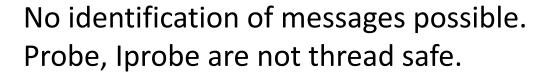
```
// Receive any messages with tag 34
MPI Probe (MPI ANY SOURCE, 34, comm, & status);
// Inspect sender
if(status.MPI SOURCE == 0) {
   ... // small control message
} else {
  // large data - alloc appropriate memory
  MPI Get count (&status, MPI DOUBLE, &number);
  buffer = (double *)malloc(number*sizeof(double));
  MPI Recv (buffer, number, MPI DOUBLE,
           status.MPI SOURCE, tag, comm, &status);
```

status.MPI_SOURCE (status.MPI_TAG) allows classification of messages MPI_Get_count helps to get number of words required to store message

Probing – thread safety

Threaded application (hybrid with OpenMP)— one MPI Stack

- Thread 0 probes for a message
- •Thread 1 probes for a message
- Thread 0 receives message
- Thread 1?



Be careful!

Mprobe and Improbe

```
MPI_Mprobe(source, tag, comm, &message, &status)
MPI_Improbe(source, tag, comm, &flag, &message, &status)
```

- Look into receive stack (blocking or non blocking) whether an appropriate message arrived.
- Allows inspection (status) first.
- Does not receive message!
- Returns a message handle to identify a message in multi threaded context
- Receive data with matching receive operations:

```
MPI_Mrecv (&buf, count, datatype, &message, &status)
MPI_Imrecv (&buf, count, datatype, &message, &request)
```

No interference from another thread possible -> thread safe

How to exchange a structure?

```
struct Particlestruct {
double c[3]; // coordinates
double v[3]; // velocities
int hydro; // water molecules in complex
double m; // mass
char name; // name (type) of particles
} particle[10];
for(i=0;i<10;i++) {
   MPI Send(particle[i].c,3,MPI DOUBLE,rec,tag,comm);
   MPI Send(particle[i].v,3,MPI DOUBLE,rec,tag,comm);
   MPI Send(particle[i].hydro,1,MPI INT,rec,tag,comm);
   MPI Send(particle[i].m,1,MPI DOUBLE,rec,tag,comm);
   MPI_Send(particle[i].name,1,MPI_CHAR,rec,tag,comm);
```

Questions:

How is a structure organized in memory?

```
struct Particlestruct {
  double c[3]; // coordinates
  double v[3]; // velocities
  int hydro; // water molecules in complex
  double m; // mass
  char name; // name (type) of particles
  } particle[10];
```

c 3x8 Byte v 3x8 Byte 8 Byte 8 Byte 8 Byte

consecutive?

Questions:

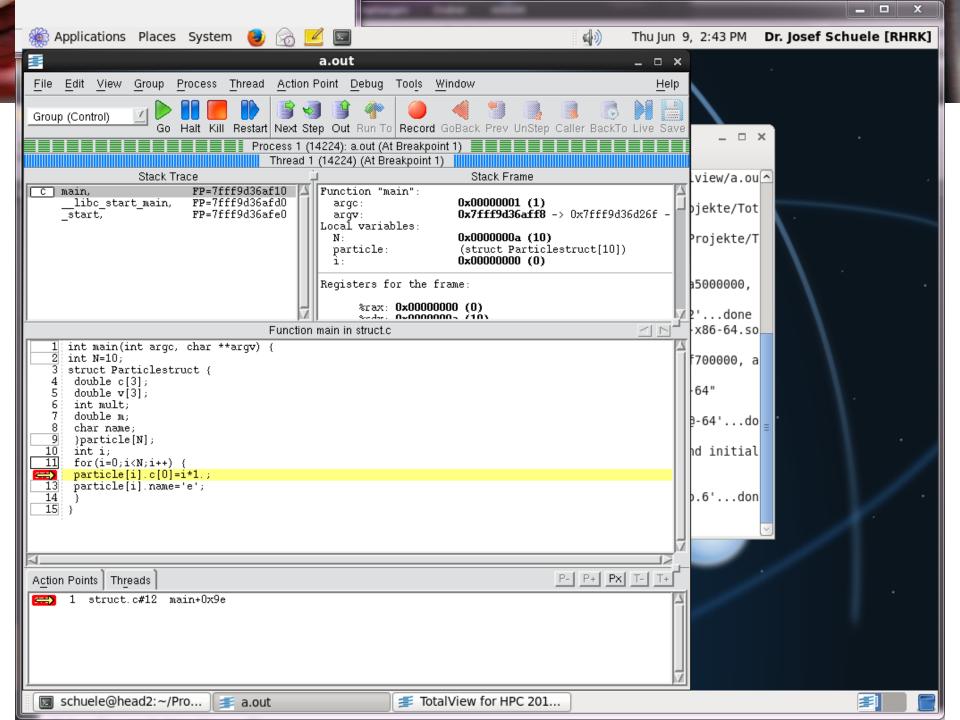
- How is a structure organized in memory?
- How many bytes are occupied by this structure?

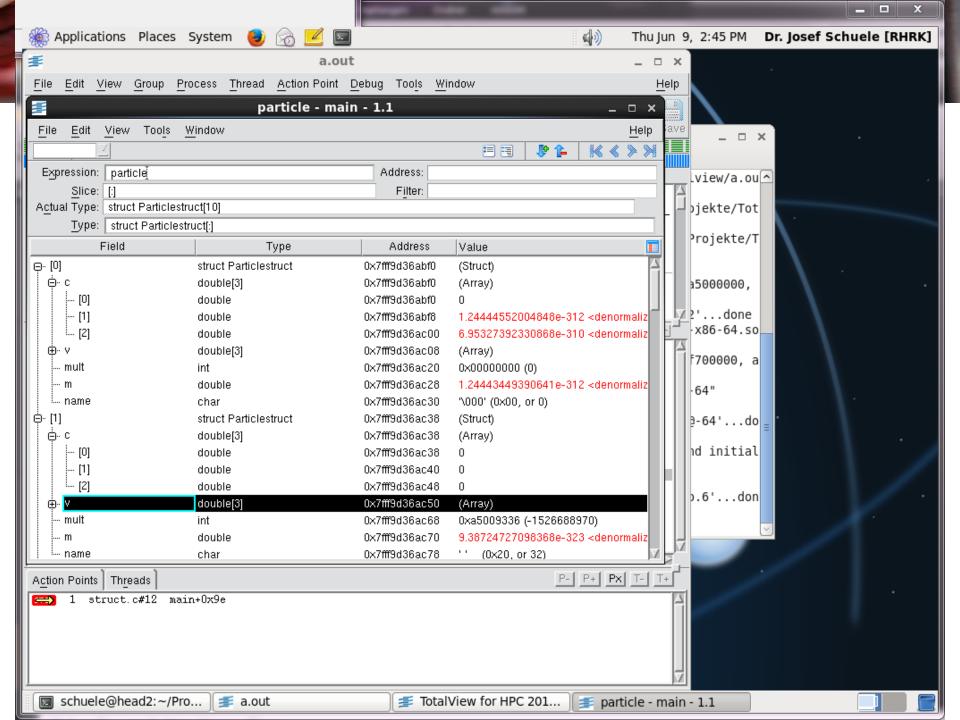
```
struct Particlestruct {
  double c[3]; // coordinates
  double v[3]; // velocities
  int hydro; // water molecules in complex
  double m; // mass
  char name; // name (type) of particles
  } particle[10];
```

```
c 3x8 Byte v 3x8 Byte 8 Byte 8 Byte 8 Byte
```

9x8=72 Byte (whereof 61 are used)

To control extends of structures – use debugger totalview.





Questions:

- How is a structure organized in memory?
- How many bytes are occupied by this structure?
- How much time is required to send (model time τ_c)

```
struct Particlestruct {
  double c[3]; // coordinates
  double v[3]; // velocities
  int hydro; // water molecules in complex
  double m; // mass
  char name; // name (type) of particles
  } particle[10];
```

```
for each communication: Tc(L) = Ts + L/BB
In total:
Tc = (5Ts + (24+24+4+1+8)/BB)*10
```

Questions:

- How is a structure organized in memory?
- How many bytes are occupied by this structure?
- How much time is required to send (model time τ_c)
- Why is the following better?

```
struct Particlestruct {
double c[3*10]; // coordinates
double v[3*10]; // velocities
double m[10]; // mass
 int hydro[10]; // water molecules
char name[10]; // name (type) of particles
} particle;
   MPI Send(particle.c,30,MPI DOUBLE,rec,tag,comm);
   MPI Send(particle.v,30,MPI DOUBLE,rec,tag,comm);
   MPI_Send(particle.m,10,MPI_DOUBLE,rec,tag,comm);
   MPI_Send(particle.hydro,10,MPI_INT,rec,tag,comm);
   MPI Send(particle.name, 10, MPI CHAR, rec, tag, comm);
```

```
MPI_Pack(inbuf, incnt, datatype, outbuf, outcnt, &pos, comm);
MPI_Unpack(inbuf,incnt,&pos,outbuf,outcnt,datatype,comm);
```

Pack/Unpack data into a buffer (inbuf). This buffer may be sent in one piece.

```
pos=0;
for(i=0;i<10;i++) {
    MPI_Pack(particle[i].c,3,MPI_DOUBLE,&buf,size_buf,&pos,comm);
    MPI_Pack (particle[i].v,3,MPI_DOUBLE,&buf,size_buf,&pos,comm);
    MPI_Pack (particle[i].m,1,MPI_DOUBLE,&buf,size_buf,&pos,comm);
    MPI_Pack(particl[i].hydro,1,MPI_INT,&buf,size_buf,&pos,comm);
    MPI_Pack (particle[i].name,1,MPI_CHAR,&buf,size_buf,&pos,comm);
}
MPI_Send(buf,size_buf,MPI_PACKED,rec,tag,comm);</pre>
```

cancel

Messages may be cancelled thus

- freeing buffers (resources) and
- allow to remove dangling send operations to broken threads.

MPI_Cancel(&request)

End of (most) information about point-to-point communication.



Einführung in das Hochleistungsrechnen Introduction to High Performance Computing

VIELEN DANK THANK YOU