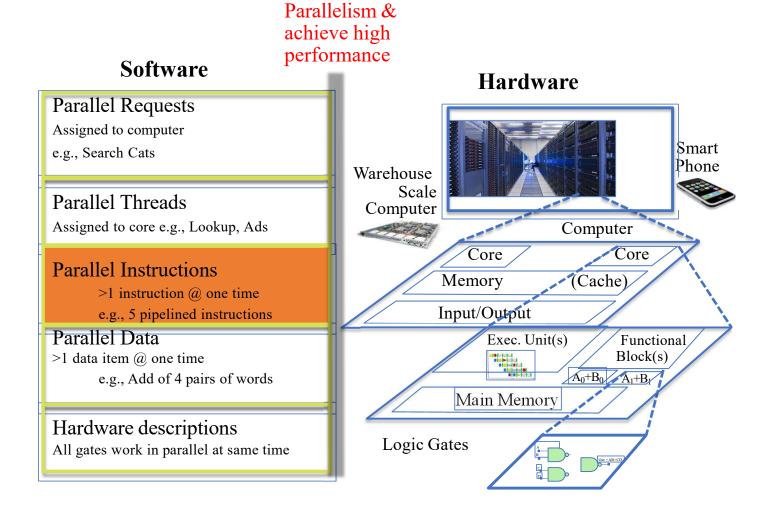
Computer Architecture 1

Computer Organization and Design
THE HARDWARE/SOFTWAREINTERFACE

[Adapted from Computer Organization and Design, RISC-V Edition, Patterson & Hennessy, © 2018, MK] [Adapted from Great ideas in Computer Architecture (CS 61C) lecture slides, Garcia and Nikolíc, © 2020, UC Berkeley]

New-School Machine Structures

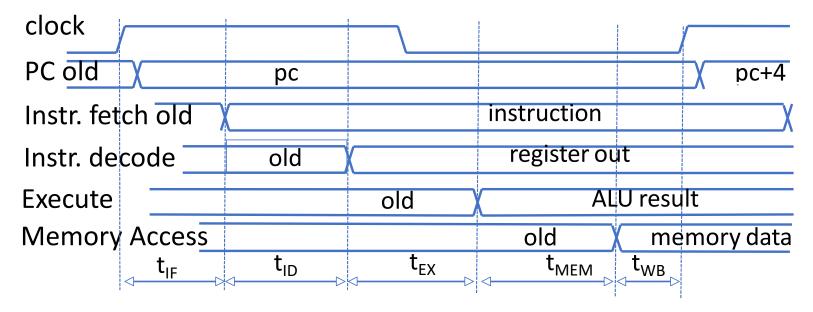


Harness

6 Great Ideas in Computer Architecture

- Abstraction (Layers of Representation/Interpretation)
- Moore's Law
- 3. Principle of Locality/Memory Hierarchy
- 4. Parallelism
- Performance Measurement & Improvement
- 6. Dependability via Redundancy

Instruction Timing



IF	ID	EX	MEM	WB	Total
I-MEM	Reg Read	ALU	D-MEM	Reg W	
200 ps	100 ps	200 ps	200 ps	100 ps	800 ps

Instruction Timing

Instr	IF = 200ps	ID = 100ps	ALU = 200ps	MEM=200ps	WB = 100ps	Total
add	Х	Х	x		Х	600ps
beq	Х	Х	X			500ps
jal	Х	Х	X		X	600ps
lw	Х	Х	x	x	X	800ps
sw	Х	Х	Х	Х		700ps

Maximum clock frequency

$$f_{max} = 1/800 ps = 1.25 GHz$$

Performance Measures

- "Our" Single-cycle RISC-V CPU executes instructions at 1.25 GHz
 - 1 instruction every 800 ps
- Can we improve its performance?
 - What do we mean with this statement?
 - Not so obvious:
 - Quicker response time, so one job finishes faster?
 - More jobs per unit time (e.g. web server returning pages, spoken words recognized)?
 - Longer battery life?

Transportation Analogy





	Sports Car	Bus
Passenger Capacity	2	50
Travel Speed	200 mph	50 mph
Gas Mileage	5 mpg	2 mpg

50 Mile trip (assume they return instantaneously)

	Sports Car	Bus
Travel Time	15 min	60 min
Time for 100 passengers	750 min (50 2-person trips)	120 min (two 50-person trips)
Gallons per passenger	5 gallons	0.5 gallons

Computer Analogy

Transportation	Computer
Trip Time	Program execution time: e.g. time to update display
Time for 100 passengers	Throughput: e.g. number of server requests handled per hour
Gallons per passenger	Energy per task*: e.g. how many movies you can watch per battery charge or energy bill for datacenter

* Note:

Power is not a good measure, since low-power CPU might run for a long time to complete one task consuming more energy than faster computer running at higher power for a shorter time

Processor Performance Iron Law

"Iron Law" of Processor Performance

```
Time = Instructions * Cycles * Time Program Program Cycle
```



CPI = Cycles Per Instruction

RISC-V

Defining (Speed) Performance

- Normally interested in reducing
 - Response time (aka execution time) the time between the start and the completion of a task
 - Important to individual users
 - Thus, to maximize performance, need to minimize execution time

If X is n times faster than Y, then

- Throughput the total amount of work done in a given time
 - Important to data center managers
- Decreasing response time almost always improves throughput

Performance Factors

- Want to distinguish elapsed time and the time spent on our task
- CPU execution time (CPU time) time the CPU spends working on a task
 - Does not include time waiting for I/O or running other programs

```
CPU execution time for a program = # CPU clock cycles time for a program or

CPU execution time for a program clock cycles for a program clock rate
```

□ Can improve performance by reducing either the length of the clock cycle or the number of clock cycles required for a program

Review: Machine Clock Rate

 Clock rate (MHz, GHz) is inverse of clock cycle time (clock period)

10 nsec clock cycle => 100 MHz clock rate

5 nsec clock cycle => 200 MHz clock rate

2 nsec clock cycle => 500 MHz clock rate

1 nsec clock cycle => 1 GHz clock rate

500 psec clock cycle => 2 GHz clock rate

250 psec clock cycle => 4 GHz clock rate

200 psec clock cycle => 5 GHz clock rate

Clock Cycles per Instruction

- Not all instructions take the same amount of time to execute
 - One way to think about execution time is that it equals the number of instructions executed multiplied by the average time per instruction

- Clock cycles per instruction (CPI) the average number of clock cycles each instruction takes to execute
 - A way to compare two different implementations of the same ISA

	CPI for this instruction class			
	A B C			
CPI	1	2	3	

Effective CPI

 Computing the overall effective CPI is done by looking at the different types of instructions and their individual cycle counts and averaging

Overall effective CPI =
$$\sum_{i=1}^{n} (CPI_i \times IC_i)$$

- Where IC_i is the count (percentage) of the number of instructions of class i executed
- CPI_i is the (average) number of clock cycles per instruction for that instruction class
- n is the number of instruction classes
- □ The overall effective CPI varies by instruction mix a measure of the dynamic frequency of instructions across one or many programs

THE Performance Equation

• Our basic performance equation is then

- □ These equations separate the three key factors that affect performance
 - Can measure the CPU execution time by running the program
 - The clock rate is usually given
 - Can measure overall instruction count by using profilers/ simulators without knowing all of the implementation details
 - CPI varies by instruction type and ISA implementation for which we must know the implementation details

A Simple Example

Ор	Freq	CPI _i	Freq x	CPI _i			
ALU	50%	1		.5	.5	.5	.25
Load	20%	5		1.0	.4	1.0	1.0
Store	10%	3		.3	.3	.3	.3
Branch	20%	2		.4	.4	.2	.4
			$\Sigma =$	2.2	1.6	2.0	1.95

 How much faster would the machine be if a better data cache reduced the average load time to 2 cycles?

CPU time new = $1.6 \times IC \times CC$ so 2.2/1.6 means 37.5% faster

- How does this compare with using branch prediction to shave a cycle off the branch time?
- CPU time new = 2.0 x IC x CC so 2.2/2.0 means 10% faster
 What if two ALU instructions could be executed at once?

CPU time new = $1.95 \times IC \times CC$ so 2.2/1.95 means 12.8% faster

Instructions per Program

Determined by

- Task
- Algorithm, e.g. O(N²) vs O(N)
- Programming language
- Compiler
- Instruction Set Architecture (ISA)

(Average) Clock Cycles per Instruction (CPI)

Determined by

- ISA
- Processor implementation (or microarchitecture)
- E.g. for "our" single-cycle RISC-V design, CPI = 1
- Complex instructions (e.g. strcpy), CPI >> 1
- Superscalar processors, CPI < 1 (next lectures)

Time per Cycle (1/Frequency)

Determined by

- Processor microarchitecture (determines critical path through logic gates)
- Technology (e.g. 5nm versus 28nm)
- Power budget (lower voltages reduce transistor speed)

Speed Tradeoff Example

For some task (e.g. image compression) ...

	Processor A	Processor B
# Instructions	1 Million	1.5 Million
Average CPI	2.5	1
Clock rate f	2.5 GHz	2 GHz
Execution time	1 ms	0.75 ms

Processor B is faster for this task, despite executing more instructions and having a slower clock rate!

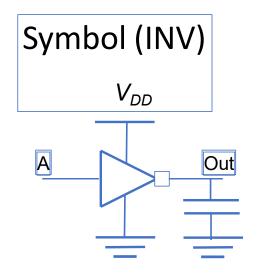
Determinates of CPU Performance

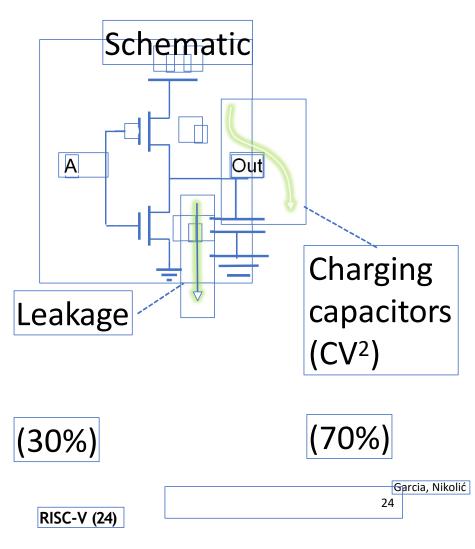
CPU time = Instruction_count x CPI x clock_cycle

	Instruction_ count	CPI	clock_cycle
Algorithm	X	X	
Programming language	Х	X	
Compiler	Х	Х	
ISA	Х	Х	х
Processor organization		х	x
Technology			х

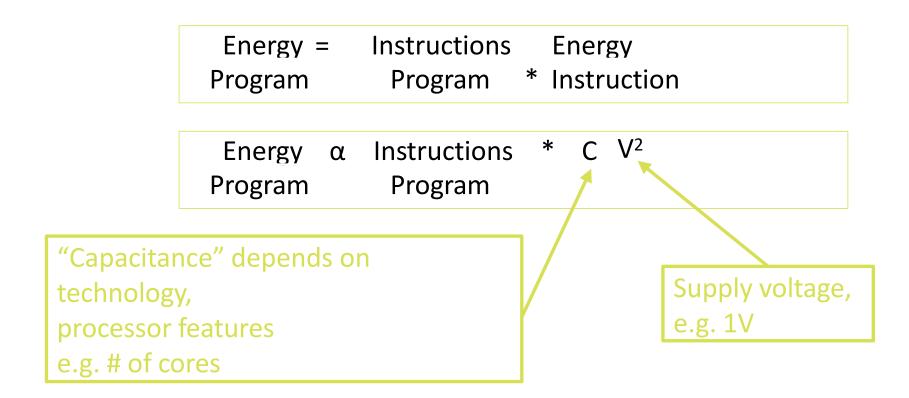
Energy Efficiency

Where Does Energy Go in CMOS?





Energy per Task



Want to reduce capacitance and voltage to reduce energy/task

Energy Tradeoff Example

"Next-generation" processor

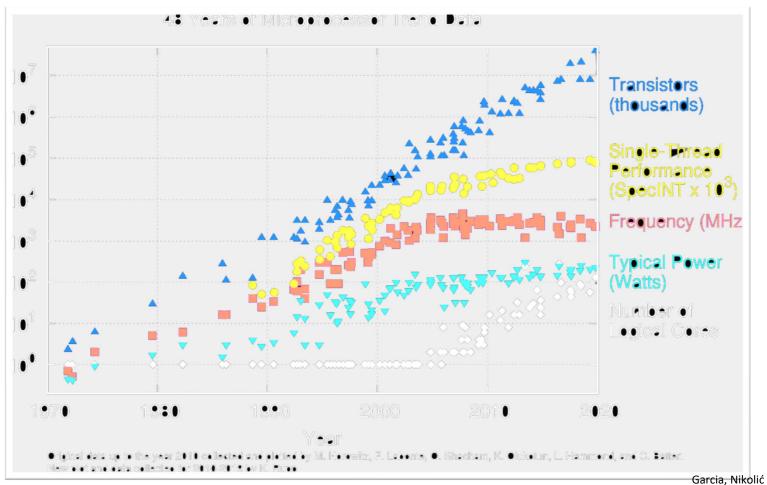
□ C (Moore's Law): -15 %

Supply voltage, V_{sup}: -15 %

Energy consumption: $0 - (1-0.85^3) = -39 \%$

- Significantly improved energy efficiency thanks to
 - Moore's Law AND
 - Reduced supply voltage

Performance/Power Trends



End of Scaling

- In recent years, industry has not been able to reduce supply voltage much, as reducing it further would mean increasing "leakage power" where transistor switches don't fully turn off (more like dimmer switch than on-off switch)
- Also, size of transistors and hence capacitance, not shrinking as much as before between transistor generations
 - Need to go to 3D
- Power becomes a growing concern the "power wall"

Energy "Iron Law"

```
Performance = Power * Energy Efficiency (Tasks/Second) (Joules/Second) (Tasks/Joule)
```

- Energy efficiency (e.g., instructions/Joule) is key metric in all computing devices
- For power-constrained systems (e.g., 20MW datacenter), need better energy efficiency to get more performance at same power
- For energy-constrained systems (e.g., 1W phone), need better energy efficiency to prolong battery life

Introduction to Pipelining

Gotta Do Laundry

- Avi, Bora, Caroline, Dan each have one load of clothes to wash, dry, fold, and put away
 - Washer takes 30 minutes
 - Dryer takes 30 minutes
 - "Folder" takes 30 minutes
 - "Stasher" takes 30 minutes to put clothes into drawers



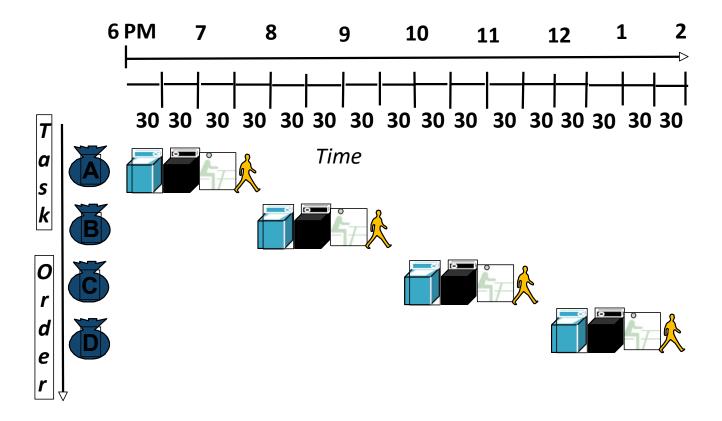








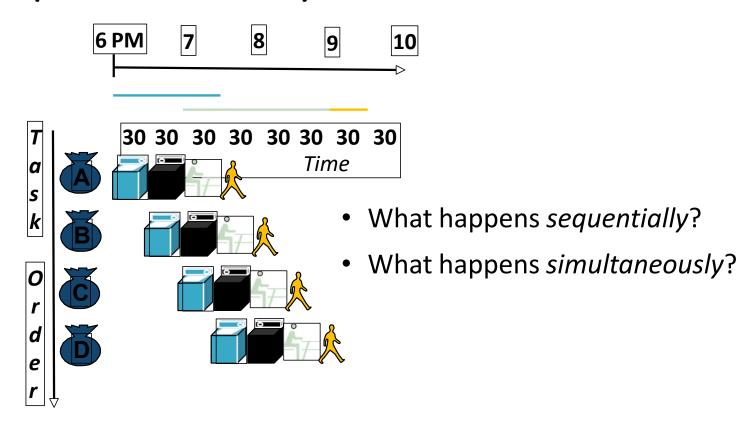
Sequential Laundry



Sequential laundry takes 8 hours for 4 loads!

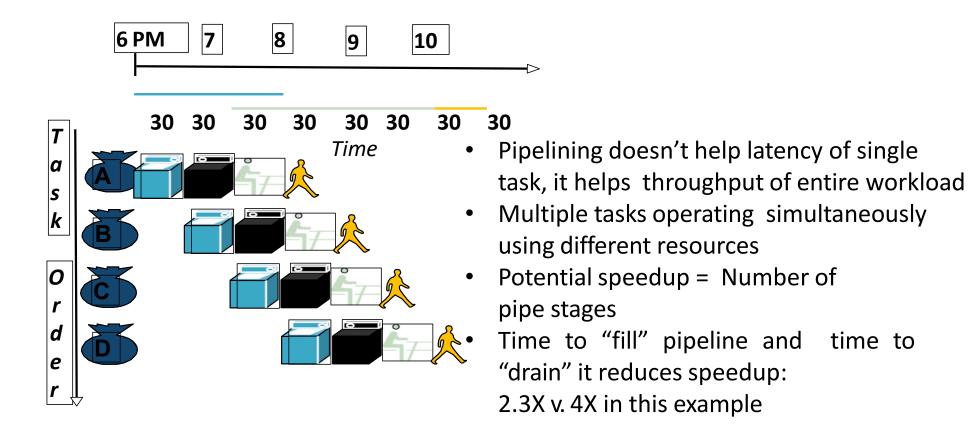
32

Pipelined Laundry

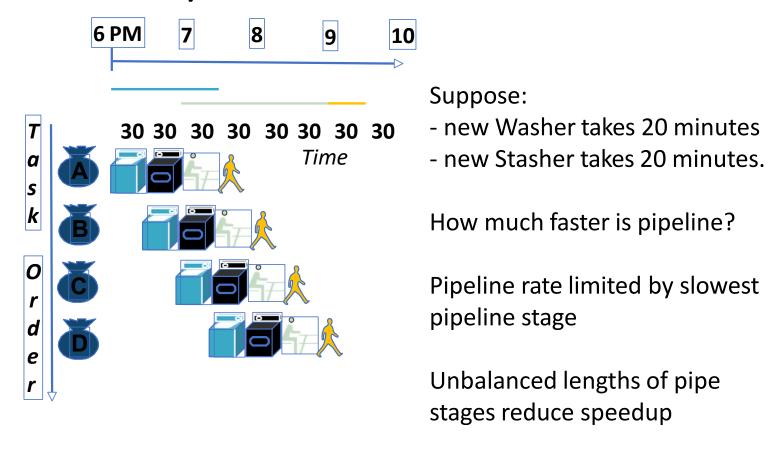


Pipelined laundry takes 3.5 hours for 4 loads!

Sequential Laundry

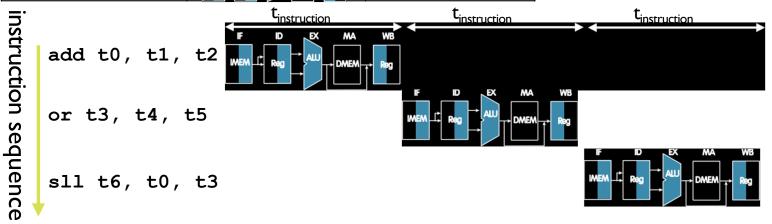


Sequential Laundry



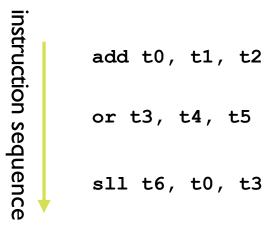
'Sequential' RISC-V Datapath

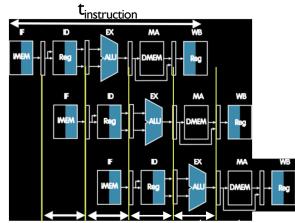
Phase	Pictogram	t _{step} Serial
Instruction Fetch	IMEM	200 ps
Reg Read	Reg	100 ps
ALU		200 ps
Memory	DMEM	200 ps
Register Write	Reg	100 ps
t _{instruction}	IMEM_I. Reg ALLI DMEM Reg	800 ps



Pipelined RISC-V Datapath

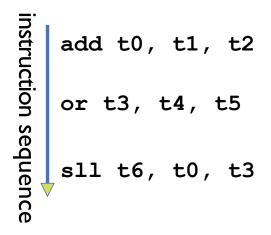
Phase	Pictogram	t _{step} Serial	t _{cycle} Pipelined
Instruction Fetch	IMEM	200 ps	200 ps
Reg Read	Reg	100 ps	200 ps
ALU	AU	200 ps	200 ps
Memory	DMEM	200 ps	200 ps
Register Write	Peg	100 ps	200 ps
t _{instruction}	IMEM_C Reg ALU DMEM Reg	800 ps	1000 ps

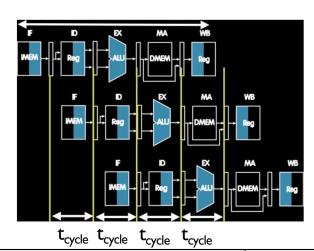




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Pipelined RISC-V Datapath

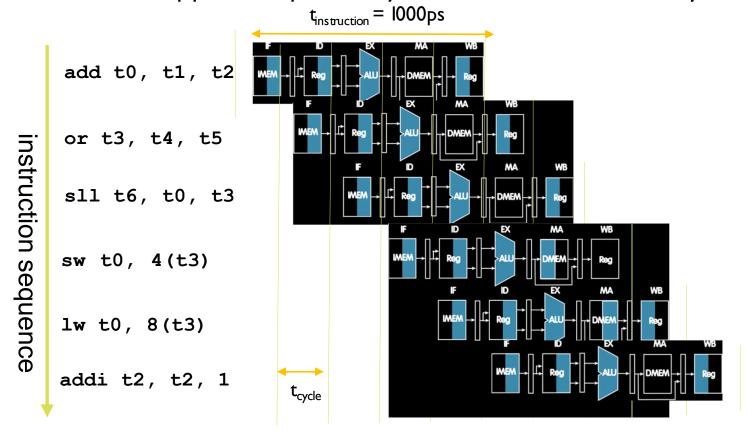




	Single Cycle	Pipelined
Timing	t _{step} = 100 200 ps	t _{cycle} = 200 ps
	Register access only 100 ps	All cycles same length
Instruction time, t _{instruction}	= t _{cycle} = 800 ps	1000 ps
CPI (Cycles Per Instruction)	~1 (ideal)	~1 (ideal), <1 (actual)
Clock rate, f _s	1/800 ps = 1.25 GHz	1/200 ps = 5 GHz
Relative speed	1 x	4 x

Sequential vs. Simultaneous

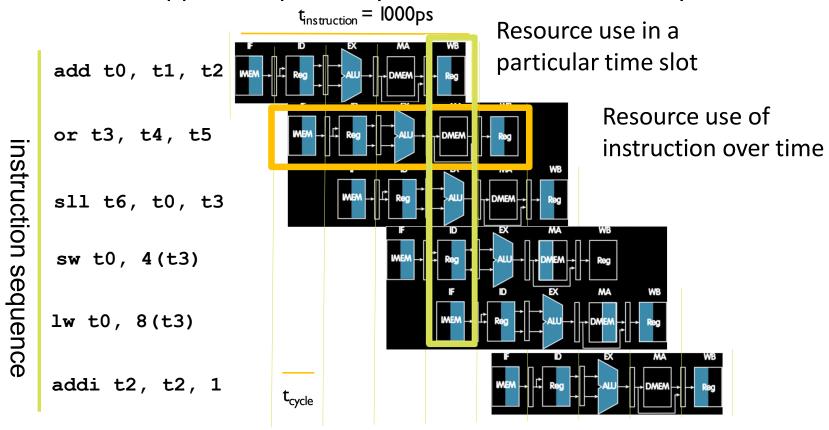
What happens sequentially and what simultaneously?



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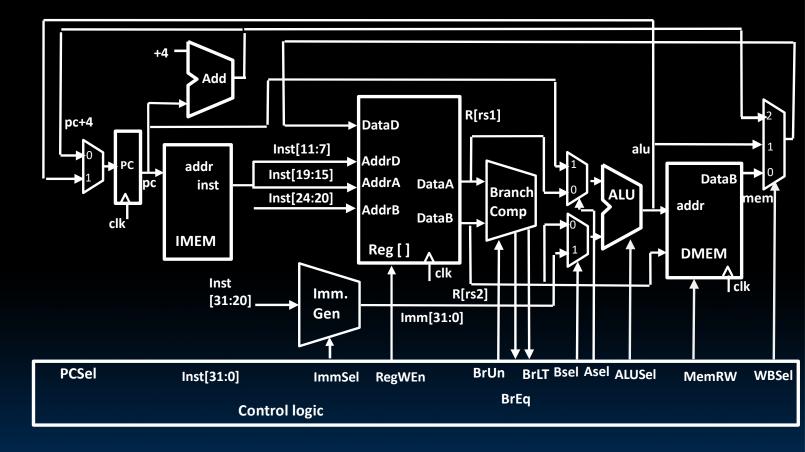
Sequential vs. Simultaneous

What happens sequentially and what simultaneously?



Pipelining Datapath

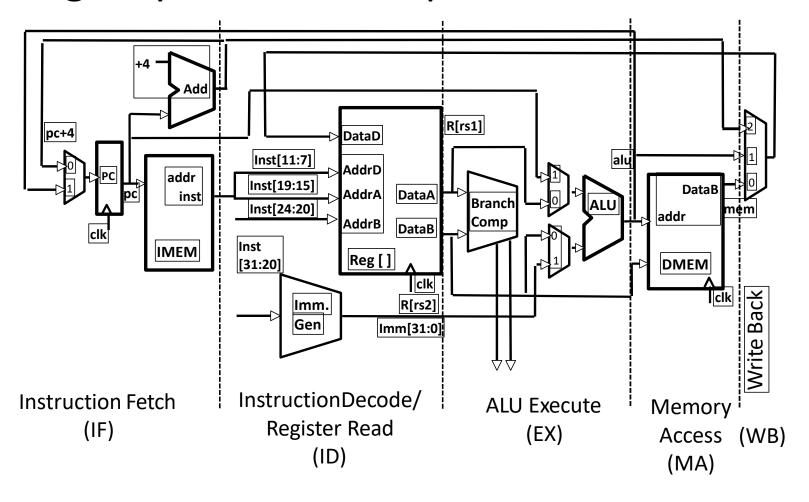
Single-Cycle







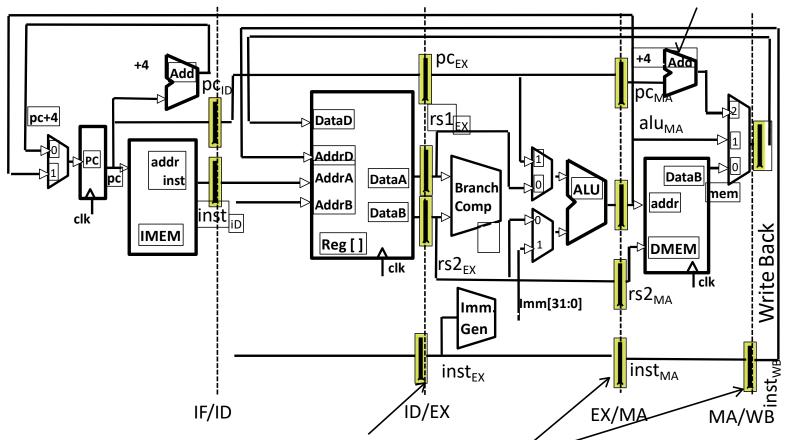
Single-Cycle RV32I Datapath



RISC-V (36)

Pipelined RV32I Datapath

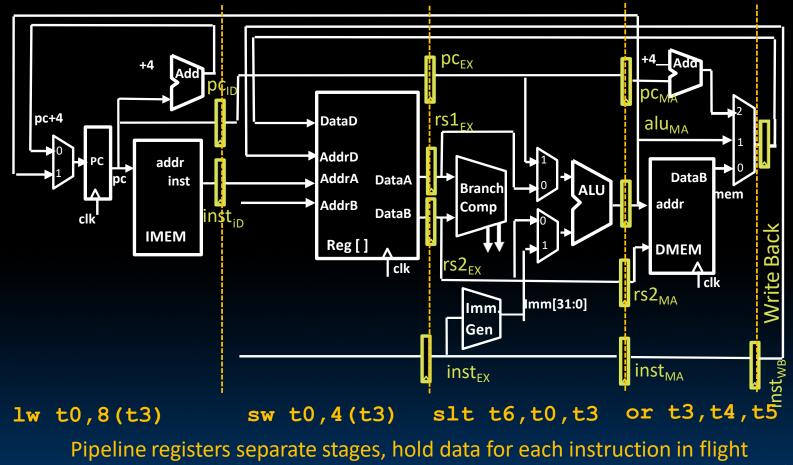
Recalculate PC+4 in M stage to avoid sending both PC and PC+4 down pipeline



Must pipeline instruction along with data, so control operates correctly in each stage

RISC-V (37)

Pipelined RV321 Datapath



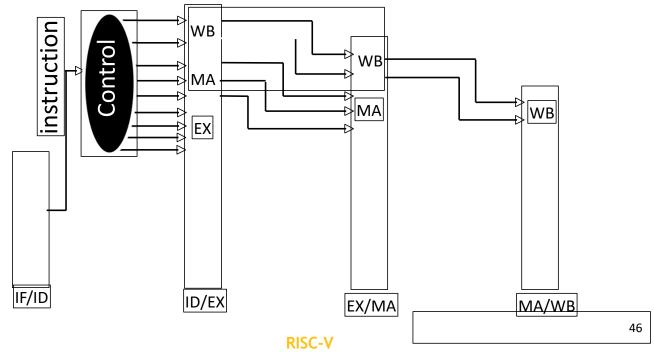
Pipeline registers separate stages, hold data for each instruction in flight





Pipelined Control

- Control signals derived from instruction
 - As in single-cycle implementation
 - Information is stored in pipeline registers for use by later stages



Pipeline Hazards

Hazards Ahead!











Pipelining Hazards

A *hazard* is a situation that prevents starting the next instruction in the next clock cycle

1) Structural hazard

A required resource is busy (e.g. needed in multiple stages)

2) Data hazard

- Data dependency between instructions
- Need to wait for previous instruction to complete its data read/write

3) Control hazard

Flow of execution depends on previous instruction

Structural Hazard

- Problem: Two or more instructions in the pipeline compete for access to a single physical resource
- Solution 1: Instructions take it in turns to use resource, some instructions have to stall
- Solution 2: Add more hardware to machine
- Can always solve a structural hazard by adding more hardware

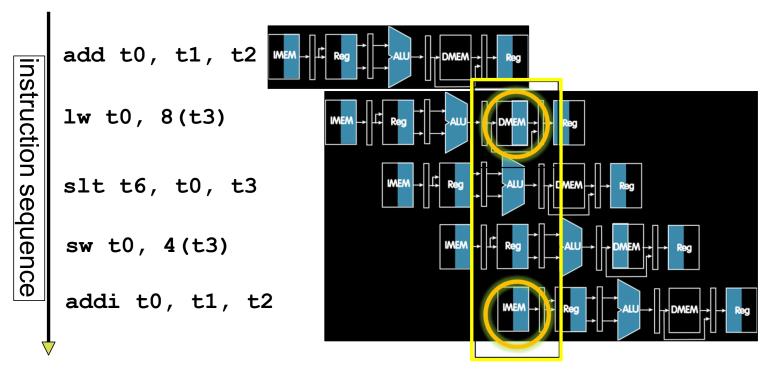
50

Regfile Structural Hazards

- Each instruction:
 - Can read up to two operands in decode stage
 - Can write one value in writeback stage
- Avoid structural hazard by having separate "ports"
 - Two independent read ports and one independent write port
- Three accesses per cycle can happen simultaneously

Structural Hazard: Memory Access

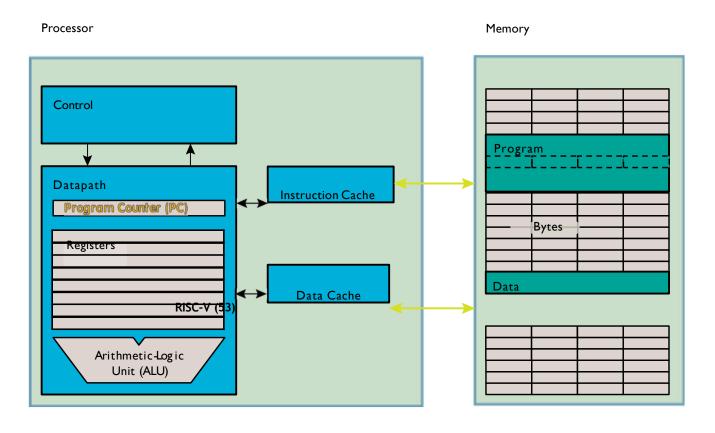
- Instruction and data memory used simultaneously
 - ✓ Use two separate memories



RISC-V (52)

Instruction and Data Caches

Fast, on-chip memory, separate for instructions and data



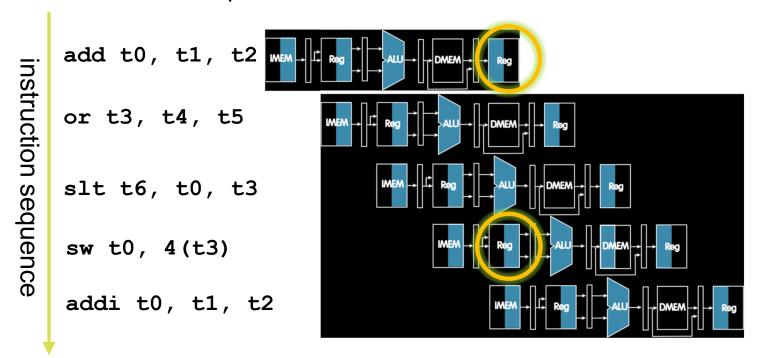
Structural Hazards – Summary

- Conflict for use of a resource
- In RISC-V pipeline with a single memory
 - Load/store requires data access
 - Without separate memories, instruction fetch would have to stall for that cycle
 - All other operations in pipeline would have to wait
- Pipelined datapaths require separate instruction/data memories
 - Or separate instruction/data caches
- RISC ISAs (including RISC-V) designed to avoid structural hazards
 - e.g. at most one memory access/instruction

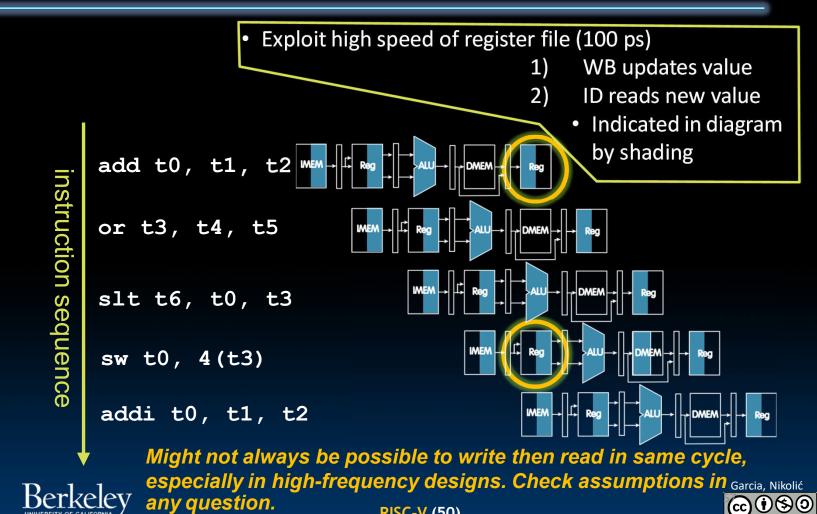
Data Hazards

Data Hazard: Register Access

- Separate ports, but what if write to same register as read?
- Does **sw** in the example fetch the old or new value?

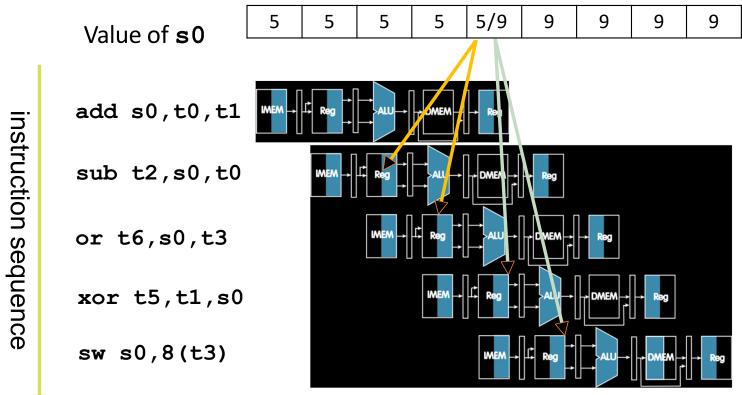






RISC-V (50)

Data Hazard: ALU Result



Without some fix, **sub** and **or** will calculate wrong result!

Solution 1: Stalling

Problem: Instruction depends on result from previous instruction

```
add s0, t0, t1
sub t2, s0, t3

add s0, t0, t1
"bubbles"

sub t2, s0, t3
```

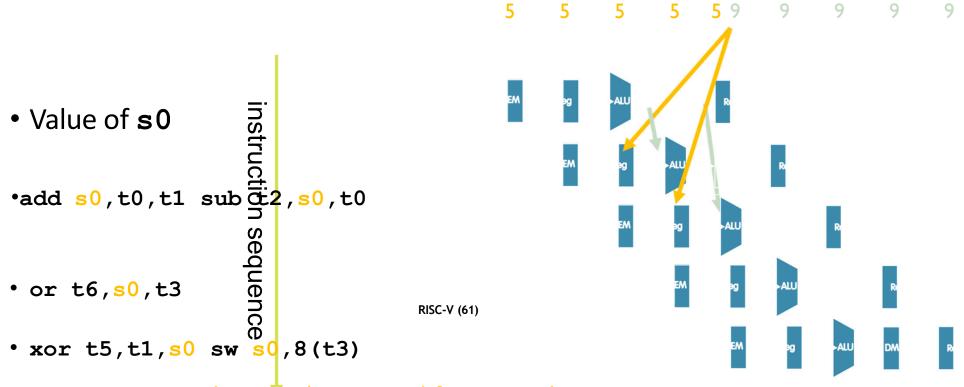
- Bubble:
 - Effectively nop: Affected pipeline stages do "nothing"

Stalls and Performance

- Stalls reduce performance
 - But stalls are required to get correct results
- Compiler can arrange code or insert nops (addi x0,
 x0, 0) to avoid hazards and stalls
 - Requires knowledge of the pipeline structure

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Solution 2: Forwarding



Forwarding: grab operand from pipeline stage,

rather than register file

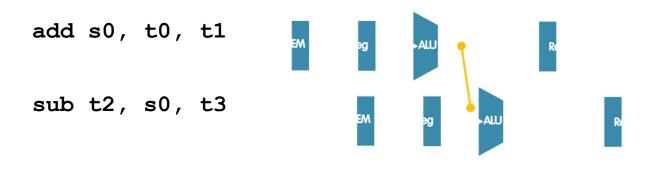


Forwarding (aka Bypassing)

Use result when it is computed

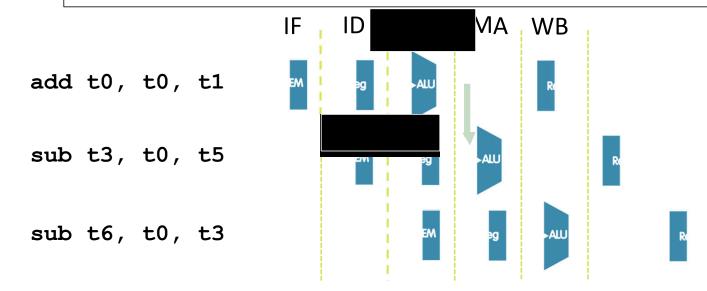
RISC-V (62)

- Don't wait for it to be stored in a register
- Requires extra connections in the datapath

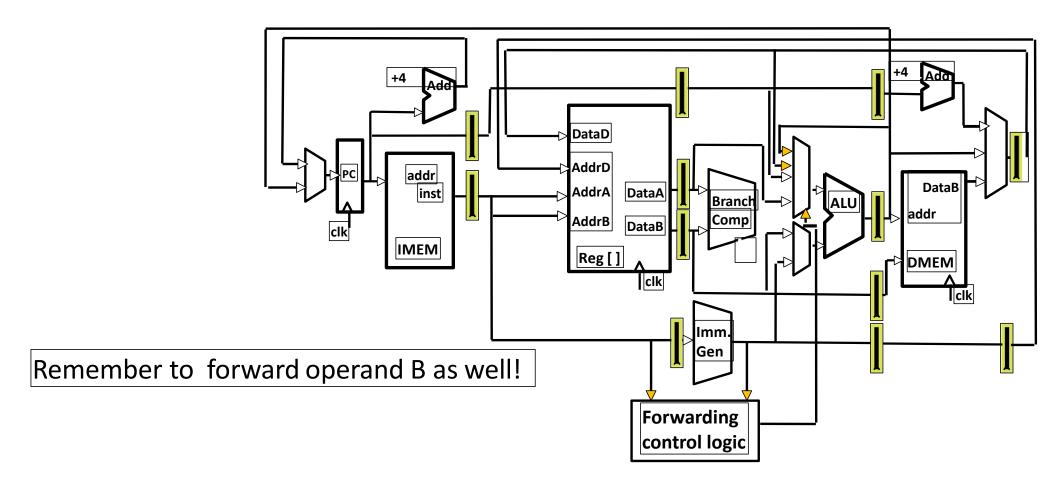


Data Needed for Forwarding (Example)

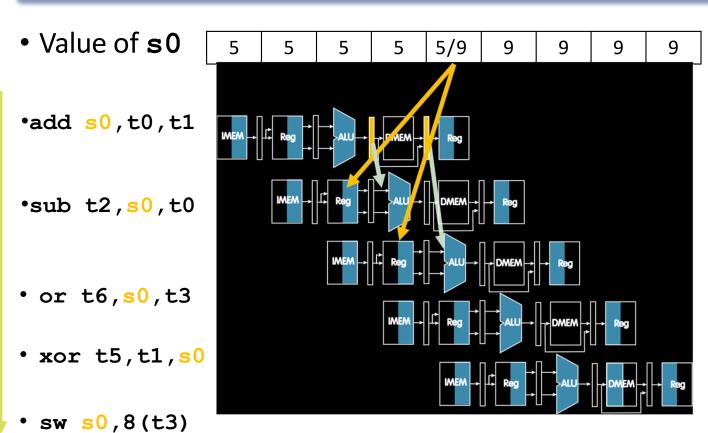
- Compare destination of older instructions in pipeline with sources of new instruction in decode stage.
- Must ignore writes to x0!



Pipelined RV32I Datapath





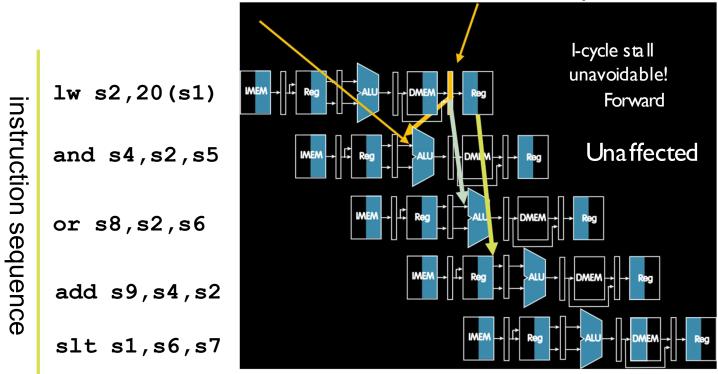


• Forwarding: grab operand from pipeline stage, rather than register file RISC-V (59)

Load Data Hazard

Needs to be here!

Data from memory is here



Load requires one-cycle pipeline stall

Stall Pipeline

instruction sequence

```
lw s2,20(s1)

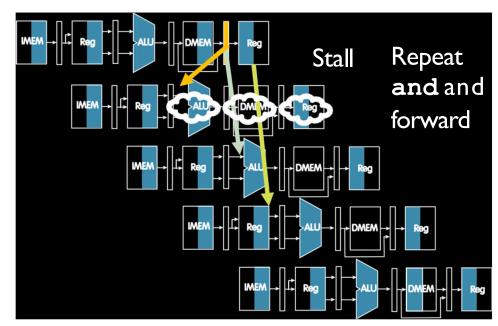
and s4, s2, s5

mp

or s8,s2,s6

add s9,s4,s2

slt s1,s6,s7
```



Load requires one-cycle pipeline stall

lw Data Hazard

- Slot after a load is called a load delay slot
 - If that instruction uses the result of the load, then the hardware will stall for one cycle
 - Equivalent to inserting an explicit nop in the slot
 - except the latter uses more code space
 - Performance loss
- Idea:
 - Put unrelated instruction into load delay slot
 - No performance loss!

Code Scheduling to Avoid Stalls

- Reorder code to avoid use of load result in the next instr!
- RISC-V code for A[3]=A[0]+A[1]; A[4]=A[0]+A[2]

Original Order: Alternative: t1, 0(t0)lw lw t1, 0(t0)t2, 4 (t0) lw 4 (t0) Stall! 9\cycles t4, 8(t0) add lw t3, t3, 12(t0) add SW t3, 12(t0)t4, 8 (t0) SW Stall! t5, t1, t4 t5, add t1, add t5, 16(t0)t5, 16(t0) SW SW

Control Hazards

Control Hazards

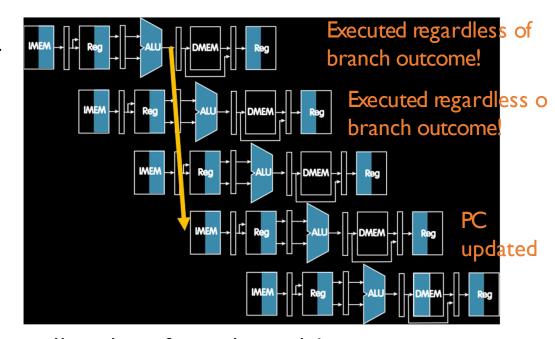
beq t0,t1,Label

sub t2,s0,t0

or t6,s0,t3

xor t5, t1, s0

sw s0,8(t3)



Two stall cycles after a branch!

Observation

- If branch not taken, then instructions fetched sequentially after branch are correct
- If branch or jump taken, then need to flush incorrect instructions from pipeline by converting to NOPs

RISC-V 72

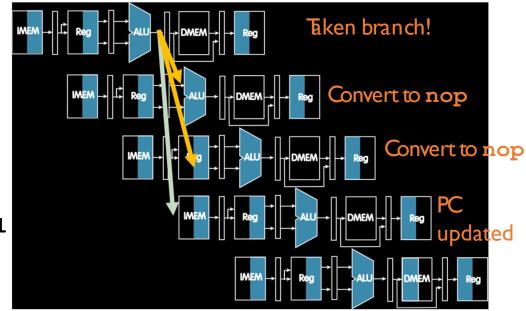
Kill Instructions after Branch if Taken

beq t0,t1,Label

sub t2,s0,t0

or t6,s0,t3

Label: xor t5,t1



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Reducing Branch Penalties

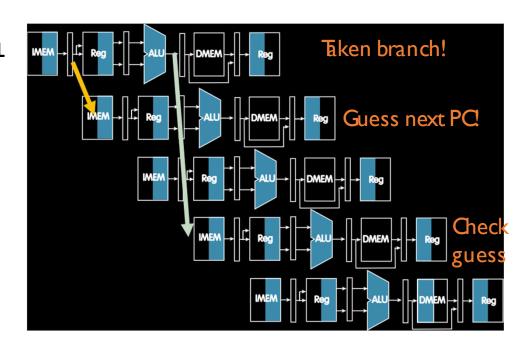
- Every taken branch in simple pipeline costs 2 dead cycles
- To improve performance, use "branch prediction" to guess which way branch will go earlier in pipeline
- Only flush pipeline if branch prediction was incorrect

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Branch Prediction

beq t0,t1,Label

Label :...



RISC-V 75

Superscalar Processors

Increasing Processor Performance

Clock rate

Limited by technology and power dissipation

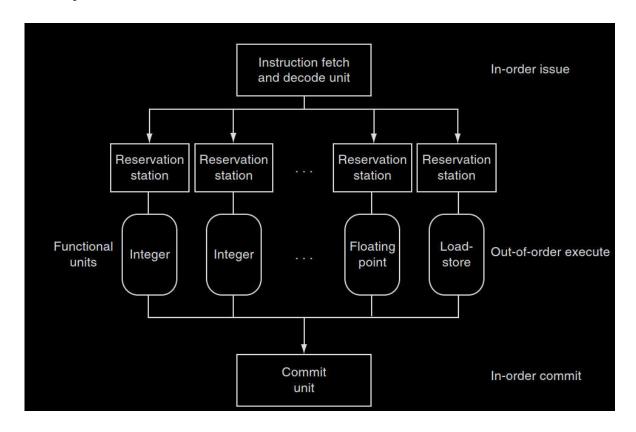
Pipelining

- "Overlap" instruction execution
- Deeper pipeline: 5 => 10 => 15 stages
 - Less work per stage → shorter clock cycle
 - But more potential for hazards (CPI > 1)
- 3. Multi-issue "superscalar" processor

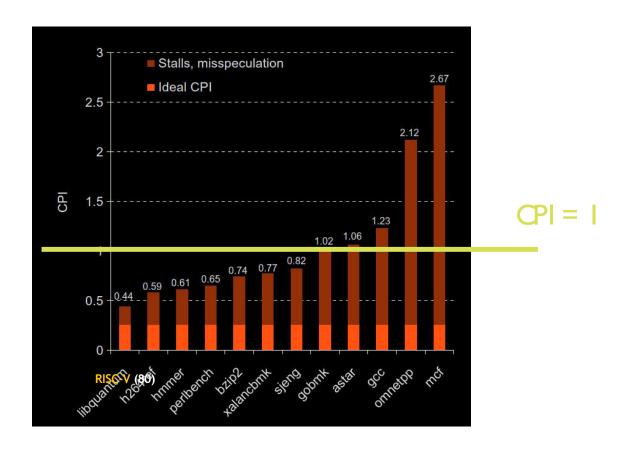
Superscalar Processor

- Multiple issue "superscalar"
 - □ Replicate pipeline stages ⇒ multiple pipelines
 - Start multiple instructions per clock cycle
 - CPI < 1, so use Instructions Per Cycle (IPC)
 - E.g., 4GHz 4-way multiple-issue
 - 16 BIPS, peak CPI = 0.25, peak IPC = 4
 - Dependencies reduce this in practice
- "Out-of-Order" execution
 - Reorder instructions dynamically in hardware to reduce impact of hazards
- CS152 discusses these techniques!

Superscalar Processor

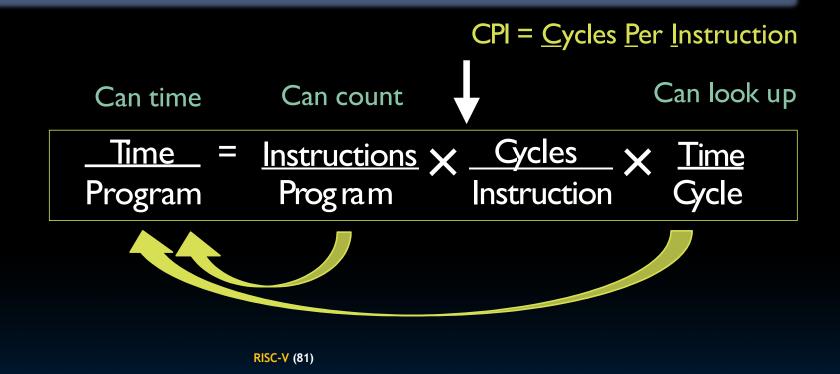


Benchmark: CPI of i7





"Iron Law" of Processor Performance





Pipelining and ISA Design

- RISC-V ISA designed for pipelining
 - All instructions are 32-bits
 - Easy to fetch and decode in one cycle
 - Versus x86: 1- to 15-byte instructions
 - Few and regular instruction formats
 - Decode and read registers in one step
 - Load/store addressing
 - Calculate address in 3rd stage, access memory in 4th stage
 - Alignment of memory operands
 - Memory access takes only one cycle

"And In conclusion..."

- We have built a processor!
 - Capable of executing all RISC-V instructions in one cycle each
- 5 Phases of execution
 - IF, ID, EX, MEM, WB
 - Not all instructions are active in all phases
- Controller specifies how to execute instructions
 - Implemented as ROM or logic
- Pipelining improves performance
 - But we must resolve hazards