

## \* Displaying Coordinates of the Image

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Task 1.ipynb U X
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[1] import cv2

def click_event(event, x, y, flags, params):
    if event == cv2.EVENT_LBUTTONDOWN:
        print(x, ' ', y)
        font = cv2.FONT_HERSHEY_SIMPLEX
        cv2.putText(img, str(x)+' '+str(y), (x,y), font, 1, (255,0,0),2)
        cv2.imshow('image', img)
    if event == cv2.EVENT_RBUTTONDOWN:
        print(x, ' ', y)
        font = cv2.FONT_HERSHEY_SIMPLEX
        b = img[y,x,0]
        g = img[y,x,1]
        r = img[y,x,2]
        cv2.putText(img, str(b)+' '+str(g)+' '+str(r), (x,y), font, 1, (255,255,0),2)
        cv2.imshow('image', img)

[2]

if __name__ == "__main__":
    img = cv2.imread('img.jpg',1)
    cv2.imshow('image', img)
    cv2.setMouseCallback('image', click_event)
    cv2.waitKey()
    cv2.destroyAllWindows()

[3]

... 386 105
190 103
135 317
198 431
379 437
40 39
88 191
177 149
```

## \* High Dynamic Range of Images

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Task 2.ipynb U X
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▶ ▾
[1] import cv2 as cv
import numpy as np

[2] img_fn = ["img0.jfif", "img1.jfif", "img2.jfif", "img3.jfif"]
img_list = [cv.imread(fn) for fn in img_fn]
exposure_times = np.array([15.0, 2.5, 0.25, 0.0333], dtype=np.float32)

[3] merge_debevec = cv.createMergeDebevec()
hdr_debevec = merge_debevec.process(img_list, times=exposure_times.copy())
merge_robertson = cv.createMergeRobertson()
hdr_robertson = merge_robertson.process(img_list, times=exposure_times.copy())

[4] tonemap1 = cv.createTonemap(gamma = 2.2)
res_debevec = tonemap1.process(hdr_debevec.copy())
res_robertson = tonemap1.process(hdr_robertson.copy())

[5] res_debevec_8bits = np.clip(res_debevec*255,0,255).astype('uint8')
res_robertson_8bits = np.clip(res_robertson*255,0,255).astype('uint8')

[6] cv.imwrite('ldr_debevec2.jpg', res_debevec_8bits)
cv.imwrite('ldr_robertson2.jpg', res_robertson_8bits)

... True
```

\* CNN