

# Data Types

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## 1 Scalar Types

- Built-in Types
- User-Defined Ordinal Types

## 2 Composite Types

- Array Types
- String Types
- Record Types
- Union Types
- Set Types
- Pointer and Reference Types
- Recursive Type

## 3 Type Checking

- A data type is
  - a homogeneous collection of values and
  - a set of operations which manipulate these values
- Uses of type system:
  - Conceptual organization
  - Error detection
  - Implementation

A type system consists of:

- The set of predefined types
- The mechanisms to define a new type
- The mechanisms for the control of types:
  - Type equivalence
  - Type compatibility
  - Type inference
- The specification which type constraints are statically or dynamically checked

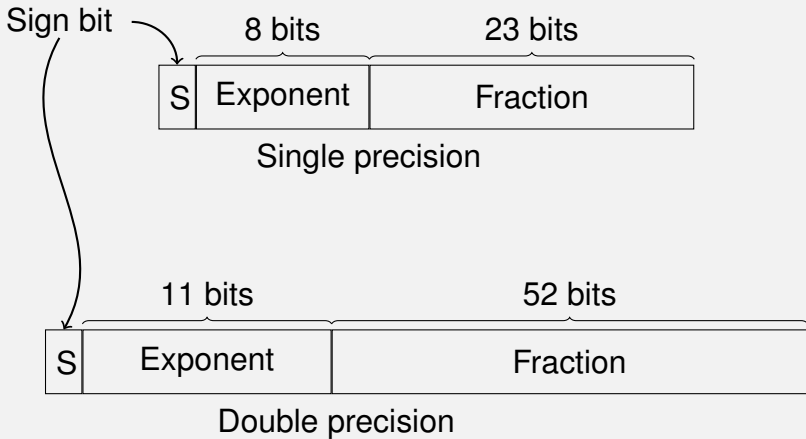
Scalar Types are

- **atomic**
- used to compose another types
- sometimes supported directly by hardware
- booleans, characters, integers, floating-point, fixed-point, complex, void, enumerations, intervals,...

► Skip Scalar Types

- Languages may support several sizes of integer
  - Java's signed integer sizes: byte, short, int, long
- Some languages include unsigned integers
- Supported directly by hardware: a string of bits
- To represent negative numbers: **two's complement**

- Model real numbers, but only as approximations
- Languages for scientific use support at least two floating-point types (e.g., float and double)
- Precision and range
- IEEE Floating-Point Standard 754





- For business applications (money)
  - Essential to COBOL
  - C# offers a decimal data type
- Store a fixed number of decimal digits
- *Advantage*: accuracy
- *Disadvantage*: limited range, wastes memory

- Simplest of all
- Range of values: two elements, one for “true” and one for “false”
- Could be implemented as bits, but often as bytes

- Stored as numeric codings
- Most commonly used coding: ASCII
- An alternative, 16-bit coding: Unicode
  - Includes characters from most natural languages
  - Originally used in Java
  - C# and JavaScript also support Unicode

- An ordinal type is one in which the range of possible values can be easily associated with the set of positive integers
- Examples of primitive ordinal types in Java
  - integer
  - char
  - boolean

- All possible values, which are named constants, are provided in the definition
- C# example  
*enum days {Mon, Tue, Wed, Thu, Fri, Sat, Sun};*  
*days myDay = Mon, yourDay = Tue;*
- Design issues:
  - Is an enumeration constant allowed to appear in more than one type definition?
  - Are enumeration values coerced to integer?
  - Are any other types coerced to an enumeration type?

- **Readability**

- no need to code a color as a number

- **Reliability**

- operations (don't allow colors to be added)
  - No enumeration variable can be assigned a value outside its defined range
  - Better support for enumeration than C++:  
enumeration type variables are not coerced into integer types
- Implemented as integers

- an ordered contiguous subsequence of an ordinal type  
*type pos = 0 .. MAXINT;*
- Subrange types behave as their parent types; can be used as *for* variables and array indices  
*type sv = array[1 .. 50] of string;*
- Subrange types are the parent types with code inserted (by the compiler) to restrict assignments to subrange variables

- An object in composite type contains many components which can be accessed individually
- component's type may be the same (homogeneous) or different (heterogeneous)
- the number of components may be fixed or changed
- there may be operations on structured-type object or its components
- there may be component insertion/removal operations
- there may be creation/destruction operations



- Collection of homogeneous data elements
- Each element is identified by its position relative to the first element and referenced using subscript expression

*array\_name (index expression list) → an element*

- What type are legal for subscripts?
  - Pascal, Ada: any ordinal type (integer, boolean, char, enumeration)
  - Others: subrange of integers
- Are subscripting expressions range checked?
  - Most contemporary languages do not specify range checking but Java, ML, C#
  - Unusual case: Perl

► Skip Array Type

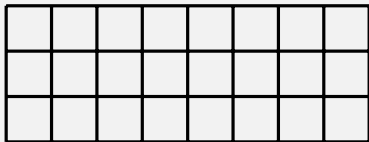
- Static  
*static int x[10];*
- Fixed Stack-dynamic  
*int x[10]; //inside a function*
- Stack-dynamic  
*cin »n;*  
*int x[n];*
- Fixed Heap-dynamic  
*int[] x = new int[10];*
- Heap-dynamic  
*cin »n;*  
*int[] x = new int[n];*

- Some language allow initialization at the time of storage allocation
  - C, C++, Java, C# example  
*int list [] = {4, 5, 7, 83}*
  - Character strings in C and C++  
*char name [] = "freddie";*
  - Arrays of strings in C and C++  
*char \*names [] = {"Bob", "Jake", "Joe"};*
  - Java initialization of String objects  
*String[] names = {"Bob", "Jake", "Joe"};*

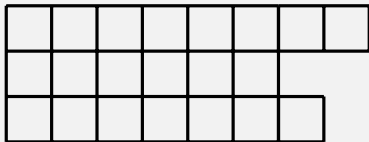
# Rectangular and Jagged Arrays

- C, C++, Java, C#: jagged arrays  
*myArray[3][7]*
- Fortran, Ada, C#: rectangular array  
*myArray[3,7]*

rectangular



jagged



- A slice is some substructure of an array; nothing more than a referencing mechanism
- Slices are only useful in languages that have array operations
- E.g. Python

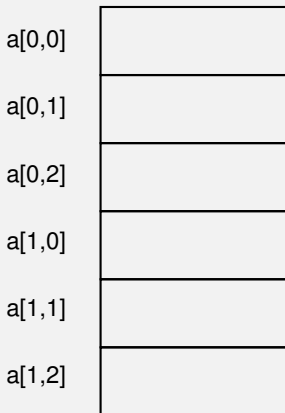
*vector = [2, 4, 6, 8, 10, 12, 14, 16]*

*mat = [[1, 2, 3],[4, 5, 6],[7, 8, 9]]*

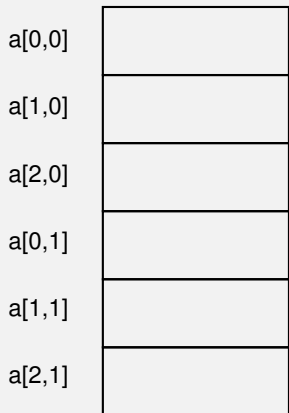
*vector[3:6], mat[1], mat[0][0:2]*

- Access function maps subscript expressions to an address in the array
- Single-dimensioned: list of adjacent memory cells
- Access function for single-dimensioned arrays:  
 **$\text{address}(\text{list}[k]) = \text{address}(\text{list}[\text{lower\_bound}]) + ((k - \text{lower\_bound}) * \text{element\_size})$**

# Accessing Two-dimensional Arrays



Row-major order  
used in most languages



Column-major order  
used in Fortran

Row-major order:

**Location** ( $a[i,j]$ ) =  $\alpha + (((i - \text{row\_lb}) * n) + (j - \text{col\_lb})) * E$

where  $\alpha$  is address of  $a[\text{row\_lb}, \text{col\_lb}]$  and  $E$  is element size

	1	2	...	j-1	j	...	n
1							
2							
$\vdots$							
i-1							
i					⊗		
$\vdots$							
m							



Array
Element type
Index type
Index lower bound
Index upper bound
Address

Single dimensional array

Multidimensional array
Element type
Index type
Number of dimensions
Index range 1
⋮
Index range n
Address

Multi-dimensional array

- An *associative array* is an unordered collection of data elements that are indexed by an equal number of values called *keys*

For example,

```
dt = [("name", "John"); ("age", "28"); ("address", "1 John st.")]
```

```
dt["name"] ⇒ "John"
```

```
dt["address"] ⇒ "1 John st."
```

- User defined keys must be stored
- Similar to Map in Scala
- Design issues: What is the form of references to elements

- Values are sequences of characters
- Design issues:
  - Is it a primitive type or just a special kind of array?
  - Should the length of strings be static or dynamic?
- Typical operations
  - Assignment
  - Comparison (=, >, etc.)
  - Concatenation
  - Substring reference
  - Pattern matching (regular expression)

► Skip String Type

- **Static:** String length is fixed at compiling time
  - Python, Java String class
  - compile-time descriptor
- **Limited Dynamic:** String length may be changed but less than a limit
  - C, C++
  - run-time descriptor
- **Dynamic:** String length may be changed without any limit
  - Perl, JavaScript
  - run-time descriptor; linked list

Ada supports all three string length options

Static string
String length
Address

Compile-time descriptor  
for static length strings

Limited dynamic string
Maximum length
Current length
Address

Run-time descriptor  
for limited dynamic length  
strings

- A record:
  - heterogeneous aggregate of data elements
  - individual elements are identified by names
- Popular in most languages, OO languages use objects as records
- Design issues:
  - What is the syntactic form of references to the field?
  - Are elliptical references allowed

► Skip Record Type

Record structures are indicated in an orthogonal way

```
type Emp_Name_Type is record
```

```
    First: String (1..20);
```

```
    Mid: String (1..10);
```

```
    Last: String (1..20);
```

```
end record;
```

```
type Emp_Rec_Type is record
```

```
    Emp_Name: Emp_Name_Type;
```

```
    Hourly_Rate: Float;
```

```
end record;
```

```
Emp_Rec: Emp_Rec_Type;
```

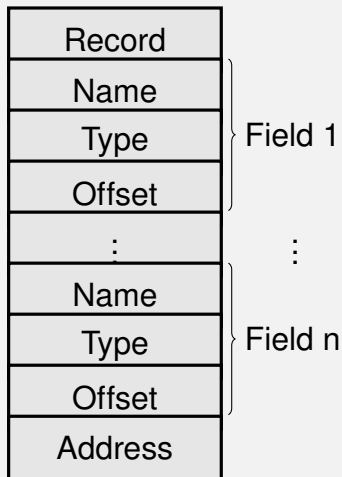
- Notation:
  - Dot-notation: *Emp\_Rec.Emp\_Name.Mid*
  - Keyword-based:  
*Mid OF Emp\_Name OF Emp\_Rec*
- Format:
  - **Fully qualified references:** include all record names
  - **Elliptical references:** may leave out some record names as long as reference is unambiguous  
*Mid, Mid OF Emp\_Name, Mid OF Emp\_Rec*



- Assignment is very common if the types are identical
- Ada allows record comparison
- Ada records can be initialized with aggregate literals
- COBOL provides MOVE CORRESPONDING  
Copies fields which have the same name

- Straight forward and safe design
- Comparison of arrays and records

Arrays	Records
homogenous	heterogeneous
elements are processed in the same way	elements are processed in different way
dynamic subscripting	static subscripting



## b-byte aligned

A b-byte aligned object has an address that is a multiple of b bytes.

## Example

- 1 A **char** (one byte) will be 1-byte aligned.
- 2 A **short** (two bytes) will be 2-byte aligned.
- 3 A **int** (four bytes) will be 4-byte aligned.
- 4 A **long** (four bytes) will be 4-byte aligned.
- 5 A **float** (four bytes) will be 4-byte aligned.

## Padding

when a structure member is

- followed by a member with a larger alignment requirement, or
- at the end of the structure to make the structure size be multiple of the biggest member size.

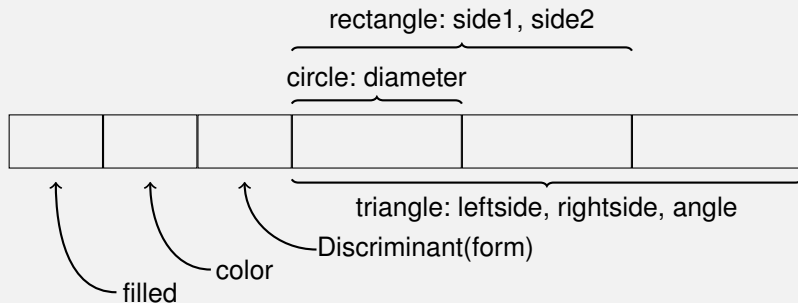
```
struct MyStruct {  
    char data1;  
    int data2;  
    char data3;  
    short data4;  
    char data5;  
};
```

What is the size of the above struct?

- A union is a type whose variables are allowed to store different type values at different times during execution

```
type Shape is (Circle, Triangle, Rectangle);  
type Colors is (Red, Green, Blue);  
type Figure (Form: Shape) is record  
    Filled: Boolean;  
    Color: Colors;  
    case Form is  
        when Circle => Diameter: Float;  
        when Triangle =>  
            Leftside, Rightside: Integer;  
            Angle: Float;  
        when Rectangle => Side1, Side2: Integer;  
    end case;  
end record;
```

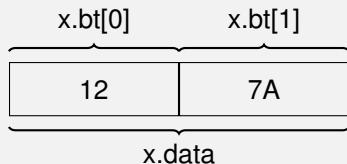
# Ada Union Type Illustrated



- Should type checking be required?
- Discriminated vs. Free Union
  - Fortran, C, and C++ provide union constructs in which there is no language support for type checking; the union in these languages is called **free union**
  - Type checking of unions require that each union include a type indicator called a **discriminant**
    - Supported by Ada
- Should unions be embedded in records?



```
union {  
    int data;  
    char bt[2];  
} x;  
x.data = 0x7A12;  
cout << x.bt[0] << endl; // 18  
cout << x.bt[1] << endl; // 122
```



- Potentially unsafe construct in some languages
  - Do not allow type checking
- Java and C# do not support unions
  - Reflective of growing concerns for safety in programming language

```
x: set of 1..10;  
y: set of char;
```

- represent the concept of set
- has operators: membership, union, intersection, different,...
- implemented by bit chain or hash table.

```
int *ptr;
```

- A *pointer* type variable has a range of values that consists of memory addresses and a special value, *nil*
- Provide the power of indirect addressing
- Provide a way to manage dynamic memory
  - A pointer can be used to access a location in the area where storage is dynamically created (usually called a *heap*)

► Skip Pointer Type

- Two fundamental operations: assignment and dereferencing
- Assignment is used to set a pointer variable's value to some useful address

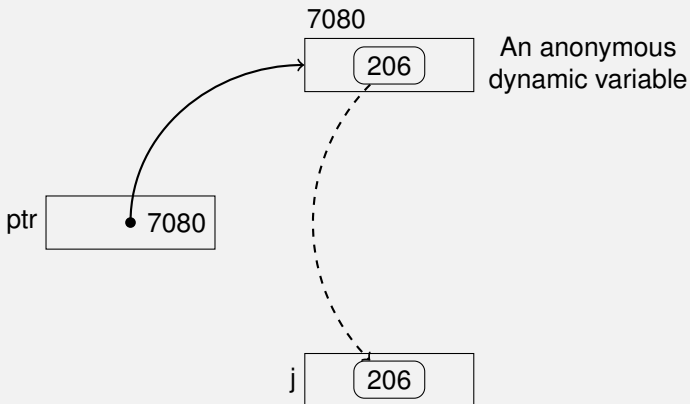
```
int *p,*q;
```

```
p = q
```

- Dereferencing yields the value stored at the location represented by the pointer's value
  - Dereferencing can be explicit or implicit
  - C++ uses an explicit operation via `*`

```
j = *ptr
```

sets `j` to the value located at `ptr`



The dereferencing operation  $j = *ptr$

- Dangling pointers (dangerous)
  - A pointer points to a heap-dynamic variable that has been de-allocated
- Lost heap-dynamic variable
  - An allocated heap-dynamic variable that is no longer accessible to the user program (often called *garbage*)

```
int *ptr;  
int count, init;  
...  
ptr = &init;  
count = *ptr;
```

- Extremely flexible but must be used with care
- Pointers can point at any variable regardless of when it was allocated
- Used for dynamic storage management and addressing



- Pointer arithmetic is possible

```
int list [10]; int *ptr; ptr = list;  
*(ptr + 1)  
*(ptr + index)  
ptr[index]
```

- Explicit dereferencing and address-of operators
- Domain type need not be fixed (void \*)
- void \* can point to any type and can be type checked (cannot be de-referenced)

- Pointer points to a record in C/C++
  - Explicit: (\*p).name
  - Implicit: p -> name
- Management of heap use explicit allocation
  - C: function **malloc**
  - C++: **new** and **delete** operators

- What are the scope of and lifetime of a pointer variable?
- What is the lifetime of a heap-dynamic variable?
- Are pointers restricted as to the type of value to which they can point?
- Are pointers used for dynamic storage management, indirect addressing, or both?
- Should the language support pointer types, reference types, or both?

```
int A;  
int &rA = A;  
A = 1;  
cout << rA << endl;  
rA++;  
cout << A << endl
```

- Pointers refer to an address, references refer to object or value
- C++ includes a special kind of pointer type called a reference type that is used primarily for formal parameters
- Java extends C++'s reference variables and allows them to replace pointers entirely
- C# includes both the references of Java and the pointers of C++

# References vs. Pointers in C++

Reference Type	Pointer
<code>int A;</code> <code>int&amp; rA = A;</code>	<code>int A;</code> <code>int* pA = &amp;A;</code>
$rA \Rightarrow A$	$*pA \Rightarrow A$
N/A	<code>pA++</code>
cannot be reseated	<code>pA = &amp;B</code>
cannot be null	<code>pA = null</code>
cannot be uninitialized	<code>int* pA</code>

- Dangling pointers and garbage are big problems
- Pointers are like goto's—they widen the range of cells that can be accessed by a variable
- Essential in some kinds of programming applications, e.g. device drivers
- Using references provide some of the flexibility and capabilities of pointers, without the hazards

- Most computers use single values
- Intel microprocessors use segment and offset

- Tombstone: extra heap cell that is a pointer to the heap-dynamic variable
  - The actual pointer variable points only at tombstones
  - When heap-dynamic variable de-allocated, tombstone remains but set to nil
  - Costly in time and space
- Locks-and-keys: Pointer values are represented as (key, address) pairs
  - Heap-dynamic variables are represented as variable plus cell for integer lock value
  - When heap-dynamic variable allocated, lock value is created and placed in lock cell and key cell of pointer





A value of a *recursive type* can contain a (reference to) value of the same type.

```
type int_list = {int val;  
                  int_list next;}  
{3,{43,{-1,{6,null}}}}
```

```
type char_tree = {char val;  
                  char_tree left;  
                  char_tree right;}  
{A,{B,{C,null,null},{D,{E,null,null},null}},  
   {F,null,null}}
```

```
type char_btree =  
    Tree of char * char_btree * char_btree  
    | Null
```

```
Tree('A', Tree('B', Tree('C', Null, Null),  
                  Tree('D',  
                        Tree('E', Null, Null),  
                        Null)),  
      Tree('F', Null, Null))
```

```
type 'a btree = Tree of 'a * 'a btree * 'a btree  
    | Null
```

```
Tree(4, Tree(3, Null, Null), Tree(6, Null, Null))
```

```
x: array [1..10] of record
a: array [5..10] of integer;
  b: record
    c: real;
    d: array[1..3] of real;
  end;
  d: string[3];
end;
```

- A **basic type** is a type expression.  
boolean, char, integer, float, void, subrange.
- A **type name** is a type expression.
- A **type constructor** applied to type expressions is a type expression. Including:
  - Arrays:  $\text{array}(I, T)$  where  $I$ : index type,  $T$ : element type
  - Products:  $T_1 \times T_2$
  - Records:  $\text{record}((\text{name1} \times T_1) \times (\text{name2} \times T_2) \times \dots)$
  - Pointers:  $\text{pointer}(T)$
  - Functions:  $T_1 \rightarrow T_2$
- A **type variable** is a type expression.

- `int`  $\Rightarrow$  `int`
- `typedef int siso;`  $\Rightarrow$  `siso`
- `int t[10];`  $\Rightarrow$  `array(0..9,int)`
- `int foo(int a,float b)`  $\Rightarrow$  `(int  $\times$  float)  $\rightarrow$  int`
- `struct int a;int b`  $\Rightarrow$  `record((a  $\times$  int)  $\times$  (b  $\times$  int))`
- `int *p`  $\Rightarrow$  `pointer(int)`
- `template <class T> struct vd T a; T b[3];`  
 $\Rightarrow$  `record((a  $\times$  T)  $\times$  (b  $\times$  array(0..2,T)))`

## Definition

**Type checking** is the activity of ensuring that a program respects the rules imposed by the type system

- **Static type checking** is performed in **compiling** time. It is often applied for static type binding languages.
- **Dynamic type checking** is performed in **running** time. It is often applied for
  - dynamic type binding languages
  - dome features in static type binding language that cannot be type checked during compiling time.

## Definition

Type inference is the ability of a compiler to deduce type information of program unit.

## Example on Scala

```
def add(x:Int) = x + 1
```

Return type of function add is inferred to be Int

## Mechanism

- Assign type (built-in or variable type) to leaf nodes in AST.
- Generate type constraints in each internal node in AST.
- Resolve these type constraints



- an operand of one type can be substituted for one of the other type without coercion.
- Two approaches:
  - Equivalence by name: same type name

```
type Celsius = Float;  
type Fahrenheit = Float;
```

- Structural equivalence: same structure

```
type A = record           type B = record  
  field1 : integer;      field1 : integer;  
  field2 : real;         field2 : real;  
end                     end
```

```
function sequiv(Type s,Type t):boolean
begin
    if (s and t are the same basic type) then
        return true;
    else if (s = array(s1,s2) and t = array(t1,t2)) then
        return sequiv(s1,t1) and sequiv(s2,t2);
    else if (s = s1 × s2 and t = t1 × t2) then
        return sequiv(s1,t1) and sequiv(s2,t2);
    else if (s = pointer(s1) and t = pointer(t1)) then
        return sequiv(s1,t1);
    else if (s = s1 → s2 and t = t1 → t2) then
        return sequiv(s1,t1);
    else
        return false;
```

## Definition

Type T is compatible with type S if a value of type T is permitted in any context where a value of type S is admissible

Example, *int* and *float*

A type T is compatible with type S when:

- T is equivalence to S
- Values of T form a subset of values of S
- All operations on S are permitted on T
- Values of T correspond *in a canonical fashion* to values of S. (*int* and *float*)
- Values of T can transform to some values of S.

## Definition

Type conversion is conversing a value of this type to a value of another type

- Implicit conversion - coercion
- Explicit conversion - cast

## Definition

- *Monomorphic*: any language object has a unique type
- *Polymorphic*: the same object can have more than one type

Example,  $+$ :  $int \times int \rightarrow int$  or  $float \times float \rightarrow float$

## Kind of Polymorphism

- *Ad hoc polymorphism* - Overloading
- *Universal Polymorphism*
  - Parametric polymorphism ( $swap(T\& x, T\& y)$ )
  - Subtyping polymorphism (in OOP)

```
template<typename T>
void swap (T& x, T& y){
    T tmp = x;
    x = y;
    y = tmp;
}
int a = 5, b = 3;
swap(a,b);
cout << a << " " << b << endl;
```

## Example of Subtyping Polymorphism

```
class Polygon
    public:
        virtual float getArea() = 0;
class Rectangle : public Polygon
    public:
        float getArea()
            return height * width;
    private:
        float height, width;
class Triangle : public Polygon
    public:
        float getArea()
            float p = (a + b + c) / 2;
            return sqrt(p*(p-a)*(p-b)*(p-c));
    private:
        float a, b, c;

Shape *s;
s = (...) ? new Rectangle(3,4) : new Triangle(3,4,5);
s->getArea();
```

```
abstract class Stack[A]  
  def push(x: A): Stack[A] =  
    new NonEmptyStack[A](x, this)  
  def isEmpty: Boolean  
  def top: A  
  def pop: Stack[A]  
class EmptyStack[A] extends Stack[A]  
  def isEmpty = true  
  def top = error("EmptyStack.top")  
  def pop = error("EmptyStack.pop")  
class NonEmptyStack[A](elem: A, rest: Stack[A])  
  extends Stack[A]  
  def isEmpty = false  
  def top = elem  
  def pop = rest  
val x = new EmptyStack[Int]  
val y = x.push(1).push(2)  
println(y.pop.top)
```



```
def isPrefix[A](p: Stack[A], s: Stack[A]): Boolean = {  
    p.isEmpty ||  
    p.top == s.top && isPrefix[A](p.pop, s.pop)  
}
```

- Type system is mainly used to error detection
- Primitive type
- Structure type
- Type checking



Maurizio Gabbrielli and Simone Martini, Programming Languages: Principles and Paradigms, Chapter 8, Springer, 2010.