# gaussian nb

October 16, 2020

## 0.0.1 Generative story

- Generative models have some theory about how data observed in the world was generated.
- We have been looking at one important generative model, naive Bayes
- Let's look at how naive Bayes models data observed in the world
- The model here is know as "Gaussian naive Bayes" because we assume the features are normally distributed (i.e. with Gaussians)

```
[15]: import random
      import numpy as np
      import pandas as pd
      # generative models can generate data. Let's generate one point
      def generatePoint(p, mu11, mu12, mu21, mu22, dogSD, catSD):
          Generate one point with two Gaussian features, conditioned on a class
          p = probability of class 1
          mu11 = Mean of feature 1, class 1
          mu12 = Mean of feature 1, class 2
          mu21 = Mean of feature 2, class 1
          mu22 = Mean of feature 2, class 2
          SD = 1 # assume standard deviation of 1
          label = None
          feature1 = None
          if (random.random() < p):</pre>
              label = "cat"
              height = np.random.normal(mu11, catSD, size=1)[0]
              weight = np.random.normal(mu12, catSD, size=1)[0]
          else:
              label = "dog"
              height = np.random.normal(mu21, dogSD, size=1)[0]
              weight = np.random.normal(mu22, dogSD, size=1)[0]
          return {"label": label, "height": height, "weight": weight}
```

```
[15]:
        label
                  height
                             weight
                6.375636 10.497257
           cat
                          13.320037
     1
                1.759638
     2
          cat
                8.259552 10.717193
     3
          dog 17.644864 40.487721
     4
          cat
                2.328081
                          10.072252
                          10.493530
     95
          cat
                5.937577
     96
               7.897894
                          52.422734
          dog
     97
                          50.535273
          dog 29.257206
     98
          cat
                3.501942
                           7.339525
     99
          dog
               17.212922 44.684520
     [100 rows x 3 columns]
```

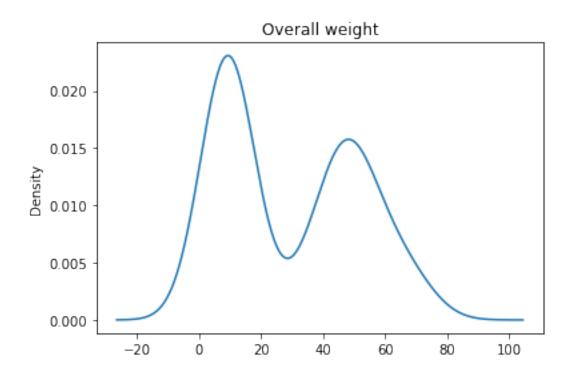
### 0.0.2 Question

What is happening in the method "generatePoint"? It generates the features from a Normal distribution conditioned on a label.

What happens if you vary p(Y=cat)? It increses the probability that a given point is labeled cat in the generated data.

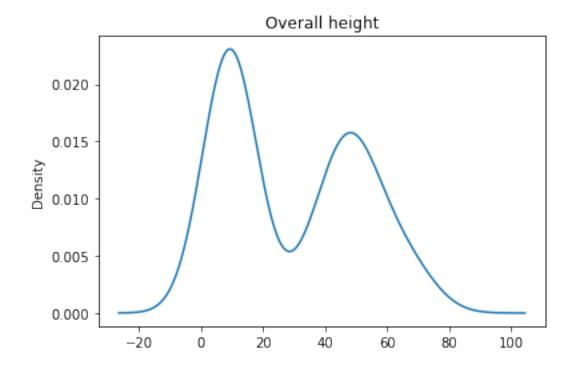
```
[16]: df["weight"].plot.kde(title="Overall weight")
```

[16]: <matplotlib.axes.\_subplots.AxesSubplot at 0x7fad3c02f700>



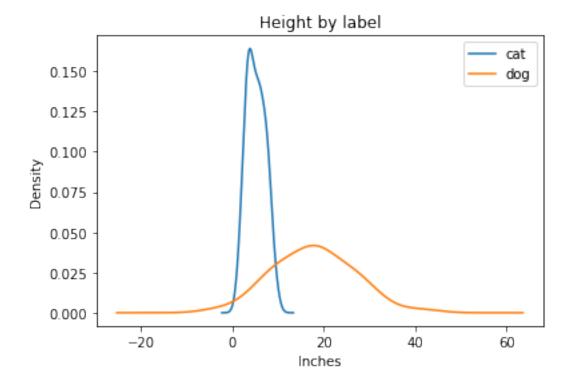
[22]: df["weight"].plot.kde(title="Overall height")

[22]: <matplotlib.axes.\_subplots.AxesSubplot at 0x7fad3c56df10>



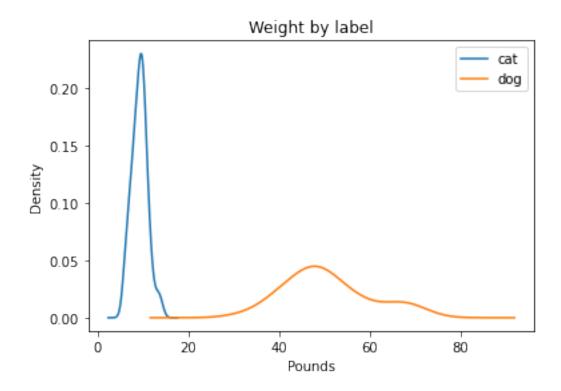
```
[21]: fig, ax = df.groupby("label")["height"].plot.kde(legend=True)
    ax.set_title('Height by label')
    ax.set(xlabel='Inches')
```

[21]: [Text(0.5, 0, 'Inches')]



```
[20]: fig, ax = df.groupby("label")["weight"].plot.kde(legend=True)
    ax.set_title('Weight by label')
    ax.set(xlabel='Pounds')
```

[20]: [Text(0.5, 0, 'Pounds')]



#### 0.0.3 Question

What do you observe in the plots called "Overall weight" and "Overall height"? Why do you think the plots have this shape? They are bimodal beacuse the data is drawn from two different distributions associated with 'cat' and 'dog'

What happens to these plots if you vary the parameters? They change in shape based on the mean and standard deviation.

### 0.0.4 Question

What do you observe in the plots called "Height by animal" and "Weight by animal"?

Why do you think the plots have this shape? [Type your answer here]

What happens to these plots if you vary the parameters? [Type your answer here]

### 0.0.5 Likelihood

Naive Bayes assumes that all features are generated independently. That means that the probability of drawing an observation like {animal=dog, weight=13, height=30} is p(animal=dog)\*p(weight=13|dog)\*p(height=30|dog).

```
[23]: from scipy.stats import norm
     def BernoulliProbOnePoint(p, x_i):
        return the probability of x_i, according to the Bernoulli distribution with_
      \hookrightarrow parameter p
        111
        if x_i == 1:
            return p
        else:
            return 1 - p
     def GaussianProbOneFeature(mu, sigma, observation):
        return norm(loc=mu, scale=sigma).pdf(observation)
[24]: def log_probability_of_one_point(point, theta):
        height = point["height"]
        weight = point["weight"]
        if point["label"] == "dog":
            pheight = GaussianProbOneFeature(mu=theta["dog_mu_height"],__
      pweight = GaussianProbOneFeature(mu=theta["dog_mu_weight"],__

→sigma=theta["dogSD"], observation=weight)
        else:
            pheight = GaussianProbOneFeature(mu=theta["cat_mu_height"],__
      pweight = GaussianProbOneFeature(mu=theta["cat_mu_weight"],__

→sigma=theta["catSD"], observation=weight)
        return np.log(p_point) + np.log(pheight) + np.log(pweight)
     def log_likelihood(points, theta):
```

### 0.0.6 Question

sum = 0

return sum\_

for point in points:

11 = log\_likelihood(points, theta)

What is happening in "log\_likelihood" function? [Type your answer here]

sum\_ += log\_probability\_of\_one\_point(point, theta=theta)

#### 0.0.7 Classification

In naive Bayes, we apply Bayes rule to classify points based on which class is most probable  $p(Y|X) \propto p(X|Y)p(Y)$ 

Use this expression and the function log\_probability\_of\_one\_point to classify a random point. Does the classification make sense? Some starter code is provided below

```
-16.330840316130097 real_label = dog
```

## 0.0.8 Learning

In reality, you would fit Gaussian naive Bayes using maximum likelihood estimation (MLE). There are closed-form expressions for the MLE of each parameter. You can look them up. But we can try to optimize with random seach. You would not want to do this in practice, but it's very helpful for understanding what is going on. Although random search is inefficient, it is easy to implement and requires no math! Try generating parameters at random in a variable called theta\_guess and then computing the likelihood. It might be helpful to only vary one parameter at a time. What do you observe about the values of theta\_guess and theta?