



## **Contents**



## Highlights

**Advanced Features** 

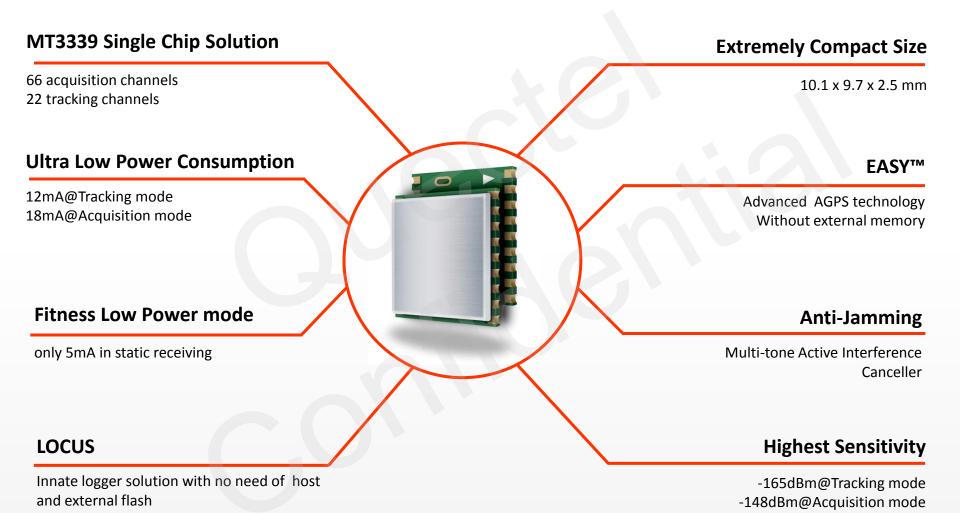
Quectel L70 Vs. Competitor's Product

**Support Package** 



## **Highlights**





## **Mechanical Dimensions**





Length: 10.1 mm

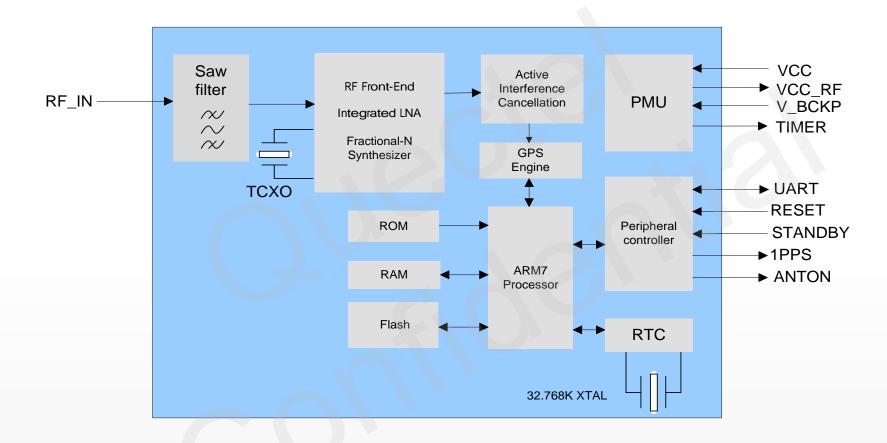
Width: 9.7 mm

Height: 2.5 mm

Weight: 0.6 g

## **Hardware Architecture**





### **Firmware**



- Protocol
  - NMEA 0183 standard V3.01
  - MTK Private Protocol: PMTK
- Configurable Operating Modes
  - UART: Adjustable 4800~115200bps (default: 9600bps)
  - Update rate: 1Hz (default), up to 10Hz
  - Selectable output NMEA messages
  - Configurable Periodic Standby Mode
  - Selectable navigation mode

## **Target Applications**



- Portable Devices
- Vehicle Management
- > Asset Tracking
- Security System
- Connected PND
- GIS Application
- > Industrial PDA





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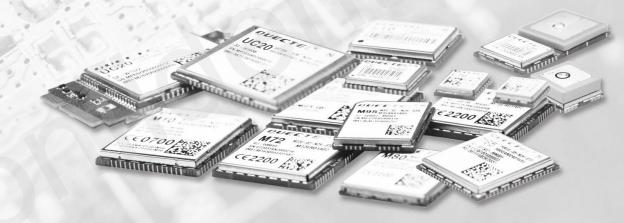


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## **Receiver Performance**



- ➤ EASY™, advanced AGPS technology without the need of external memory
- Extremely low power consumption, 12mA
- ➤ AlwaysLocate<sup>™</sup>, an intelligent controller of periodic mode
- > LOCUS, innate logger solution with no need of host and external flash
- ➤ High sensitivity, -165dBm@Tracking, -148dBm@ Acquisition
- ➤ 66 acquisition channels, 22 tracking channels
- >FLP(Fitness Low Power) mode, only 5mA in static receiving
- ➤ Balloon mode, for high altitude up to 80km
- Support DGPS, QZSS, SBAS(WASS/EGNOS/MSAS/GAGAN)
- ➤ Anti-Jamming, Multi-tone Active Interference Canceller
- > PPS VS. NMEA can be used in time service
- ➤ Support SDK command developed by Quectel

# **Specifications**

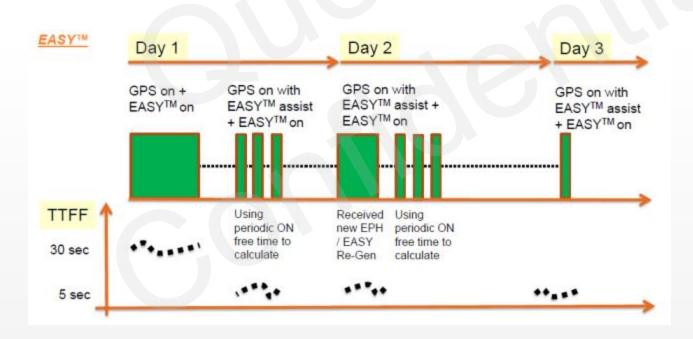


L1 Band Receiver (1575.42MHz)	Channel	22 (tracking) / 66 (acquisition)	Environmental	Operating Temperature	-40°C to 85°C
	C/A code			Storage Temperature	-45°C to 125°C
	SBA	WAAS, EGNOS MSAS,GAGAN	Dynamic Performance	Maximum Altitude	Max.18000m
				Maximum Velocity	Max.515m/s
Horizontal Position Accuracy	Autonomous	<2.5m CEP	Performance	Maximum Acceleration	4G
	Without aid	<0.1m/s	Dimensions	10.1 x 9.7 x 2.5mm	
Velocity Accuracy			Weight	Approx. 0.6g	
Acceleration Accuracy	Without aid	0.1m/s²	Serial Interface	UART: Adjustable 4800~115200 bps Default: 9600bps	
Timing Accuracy	1PPS	10ns	Update Rate	1Hz by default, up to10Hz	
Reacquisition Time		<1s	I/O Voltage	2.7V ~ 2.9V	
TTFF@-130dBm with EASY™	Cold Start	<15s	Protocols NMEA 0183 PMTK		
	Warm Start	<5s	Power Supply	2.8V ~ 4.3V	
	Hot Start	<1s	Power Acquisition	18mA	
TTFF@-130dBm without EASY™	Cold Start	<35s	Power Tracking	12mA	
				1.4mA@AlwaysLocate™	
	Warm Start	<30s		7uA@Backup Mode	
	Hot Start	<1s	Power Saving	200uA@Standby Mode	
Sensitivity	Acquisition	-148dBm		5mA@FLP Mode Periodic Mode	
	Tracking	-165dBm	Antenna Type	Active or Passive	
	Re-acquisition	-160dBm	Antenna Power	External or Internal VCC_RF	

## Self-AGPS EASY Technology(1)



- ➤ EASY™ is the abbreviation for Embedded Assist System for quick positioning. With EASY™ technology, the GPS engine can calculate and predict automatically single ephemeris (up to 3 days) when the power is on, and then save the predict information into the memory. So the GPS engine can use the information for positioning later if there are not enough information received from the satellites.
- > This function will be helpful for positioning and TTFF improvement under indoor or urban conditions.



## Self-AGPS EASY Technology(2)



### > TTFF Comparison

Test Condition		TTFF without EASY™	TTFF with EASY™
Under GPS signal Generator,	Cold Start	<35s	<15s
conductive power level -130dBm	Warm Start	<30s	<5 s

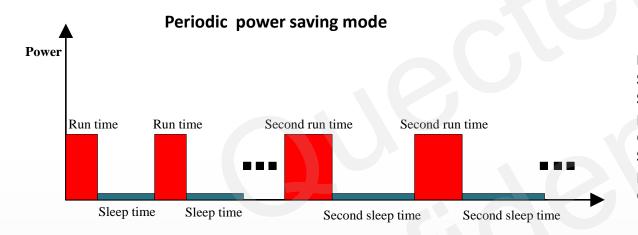
With EASY™ technology, L70 accelerates TTFF obviously.

## **Periodic Standby Mode**



Periodic standby mode can control power on/off time of GPS periodically to reduce average power consumption, and on/off time can be configured by using PMTK command. For details, see the figure below. Periodic standby mode can be entered by sending the following PMTK command.

\$PMTK255, Type, Run time, Sleep time, Second run time, Second sleep time



Run time: tracking period (ms)
Sleep time: standby period (ms)

**Second run time:** extended acquisition period (ms) when GPS acquisition fails

during the Run time

**Second sleep time:** extended standby period (ms) when GPS acquisition fails

during the Run time

### Notes:

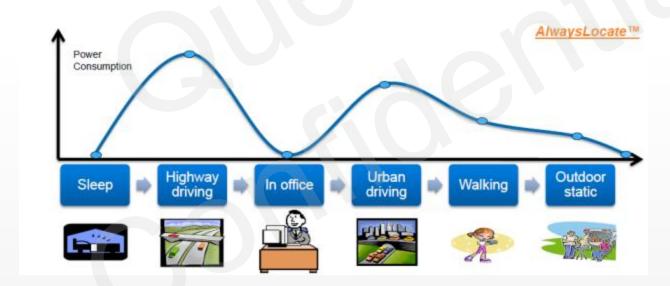
- 1. Normally, the GPS module will enter the periodic mode after successfully fixing position. But if acquisition fails, the GPS module still can enter this mode.
- 2. If GPS acquisition fails during the Run time, in order to ensure the success of reacquisition, it is better to set the longer Second run time.

Example: PMTK225, 2, 3000, 12000, 18000, 72000\*15 for periodic mode with 3s in tracking mode and 12s sleep in standby mode. The average current is about 2.5mA.

# AlwaysLocate<sup>TM</sup> Technology



- ➤ AlwaysLocate<sup>™</sup> is an intelligent controller of periodic mode.
- ➤L70 can adaptively adjust the on/off time to achieve balance between positioning accuracy and power consumption according to the environmental and motion conditions. So the average power consumption is lower in AlwaysLocate<sup>™</sup> power saving mode than that in periodic power saving mode. Typical average power is 1.4mA.

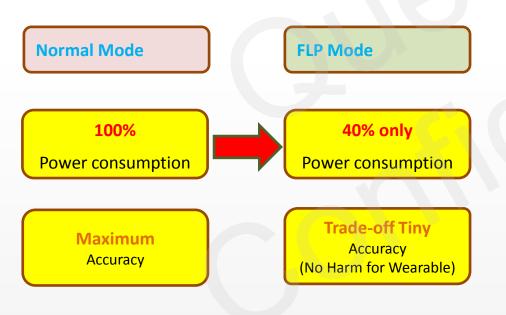


## **Fitness Low Power Mode**



Fitness low power (FLP) is an optimized solution for wearable, fitness and tracking device. It provides a FLP mode for Quectel GPS modules to reduce power consumption with tiny accuracy trading-off. The FLP mode can be easily set by using a specific message.

In FLP mode, the module has good route consistence in walking and running scenarios, and can switch dynamic duty operation automatically. It will come back to normal mode in difficult environment to keep good accuracy as well, thus realizing maximum performance with the lowest power consumption.



#### **Average Current for FLP Mode and Normal Mode of L70**

Scenario	In FLP Mode (mA)	In Normal Mode (mA)
Static	5.0	12
Walking	5.4	12
Running	5.5	12
Driving	8.5	12

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**Quectel L70 Vs. Competitor's Product** 

**Support Package** 



# L70 vs. Ucompany NEX-6Q(1)



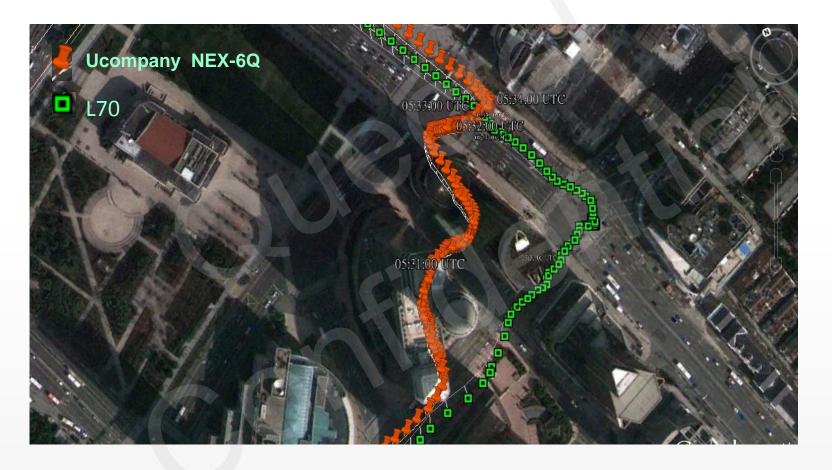
## > Specification Comparison

Product Features		L70	Ucompany NEX-6Q
Power supply		2.8V~4.3V	2.7V~3.6V
Power Consumption	Acquisition Mode	18mA@3.3V	117m\\\@2 0\/ typical
	Tracking Mode	12mA@3.3V	117mW@3.0V typical
Sensitivity	Acquisition	-148dBm	-148dBm
	Tracking	-165dBm	-162dBm
	Re-acquisition	-160dBm	-160dBm
TTFF @ -130dBm	Hot Start	<1s	1s
	Warm Start	<5s (EASY™)	26s
	Cold Start	<15s (EASY™)	26s
Position Accuracy		2.5m CEP	2.5m CEP
Timing Accuracy 1PPS		10ns	30ns
Data Update Rate		Up to 10Hz	Up to 5Hz

# L70 vs. Ucompany NEX-6Q(2)



### > Tracking Comparison



When driving across overpass and making a turn, L70 module can still capture the accurate tracking data. But Ucompany module has a small drift.

## L7Q(30 vs. Ucompany NEX-6)



### > Tracking Comparison



When driving under the overpass, L70 module shows its excellent performance. But Ucompany's module has a bigger drift.

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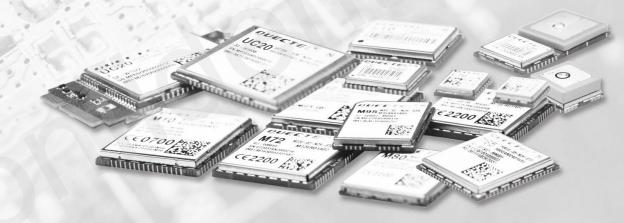


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## **Support Package(1)**



### **Evaluation Board**

- > Interfaces
  - GPS serial port
  - Antenna interface
  - Adapter interface

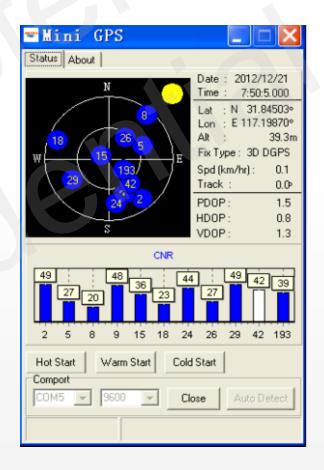
- Accessories
  - Serial port cable
  - DC 5V/2A power adapter
  - GPS antenna



## **Support Package(2)**



- Documents
  - Hardware Design
  - GPS Protocol
  - Part&Decal in PADS and Protel Format
  - Evaluation Board User Guide
  - Circuit Reference Design
- PC tool
  - MiniGPS-GPS testing tool





Q&A...

Thank you

