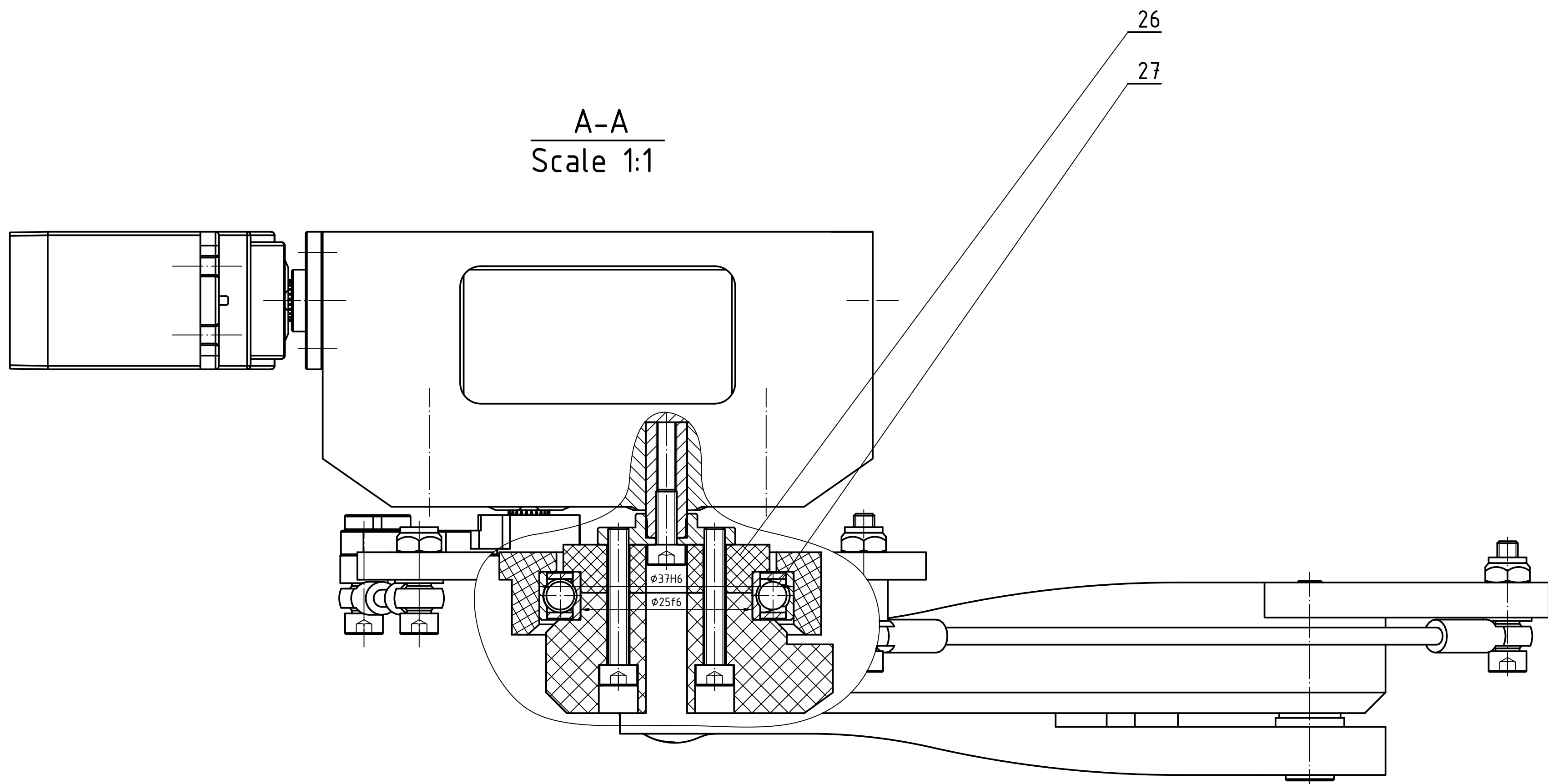
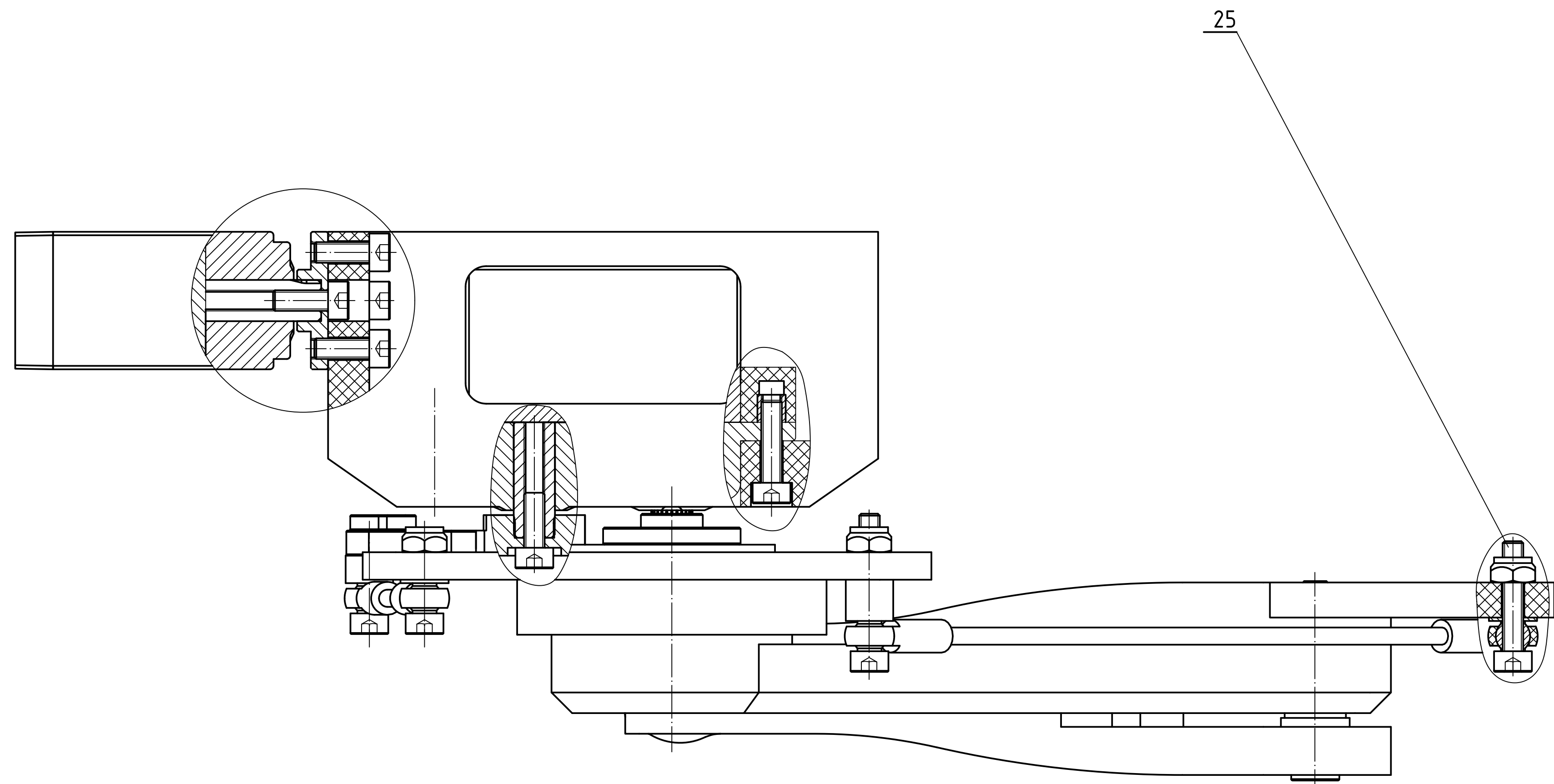


TECHNICAL REQUIREMENTS:

1. UNIT: MM
2. INSTALL ALL THREADED INSERTS USING SOLDERING IRON
3. START ASSEMBLING FROM THE HIP SERVO AND DISC TO THE SERVO HUB
4. CONNECT TWO SERVOS TO THE H-SHAPED CONNECTOR AS SHOWN SECTION B-B
5. FOR THE LEG LINKAGE, INSTALL TWO THRUST BEARINGS ON THE UPPER LEG BEFORE CONNECTING IT THE THE LOWER LEG



27	214-0322	6805 Ball Bearing	1		Misumi
26	L.B.L.2.3	Servo Disc Washer	1	PLA	Workshop
25	TM314-18	M3x18 Socket Head Screw	1	Inox 304	Ocvlmin
24	L.B.L.1.2	Servo Connector H-shaped	1	PLA	Workshop
23	L.B.L.2.8	Feet Silicon Casing	1	Silicone	Workshop
22	L.B.L.2.7	Feet Bone	1	PLA	Workshop
21	TM314-8	M3x8 Socket Head Screw	8	Inox 304	Ocvlmin
20	3TD3-4.1-4	M3x4.1x4. Threaded Insert	9	Brass	Ocvlmin
19	4TD4-6.4	M4x6x4. Threaded Insert	2	Brass	Ocvlmin
18	221000058378	628Z2 Ball Bearing	2		Misumi
17	TS416-25	M4x25 Socket Shoulder Screw	1	Inox 304	Ocvlmin
16	N3R4-4	M3x4 Plastic Spacer	1		Ocvlmin
15	VDTM3-7-0.5	M3x0.5 Flat Washer	2	Inox 304	Ocvlmin
14	TM314-12	M3x12 Socket Head Screw	10	Inox 304	Ocvlmin
13	UM3KL	M3 Torque Prevailing nut	3	Inox 304	Ocvlmin
12	N3R4-6	M3x6 Plastic Spacer	1		Ocvlmin
11	TM314-20	M3x20 Socket Head Screw	5	Inox 304	Ocvlmin
10	L.B.L.2.6	M3x120 Metal Link	1	Stainless steel	Workshop
9	5993K13	M3 RC Rod End	4		McMASTER-CARR
8	L.B.L.2.4	Cam Link	1	PLA	Workshop
7	L.B.L.1.1	Servo hub	1	PLA	Workshop
6	L.B.L.2.5	M3x35 Metal Link	1	Stainless steel	Workshop
5	3918565933	SPT5435LV RC Servo	3		SPT-SERVO
4	Y010	25T Metal Servo Disc	2	Aluminium	Nshopvn
3	CD04	25T Metal Servo Arm	1	Aluminium	Nshopvn
2	L.B.L.2.1	Upper leg	1	PLA	Workshop
1	L.B.L.2.2	Lower leg	1	PLA	Workshop
No.	Symbol	Name	Qty	Material	Notation
DESIGN OF QUADRUPED ROBOT					Capstone Project
Func.	Full name	Sign	Date	Quantity	Weight
Design	P.D.K.Nguyen		15/03	1	2.1
Instruct.	L.D.Hanh			Sheet: 2	Total sheet: 5
Approve	L.D.Hanh			Capstone Project	
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